# Automatic Detection of Vulnerable Variables for CTL Properties of Programs

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while(y > z){
y = y - x;
}
ERROR()
}
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#### Our analysis:

- reduce as possible the sets of variable(s) to control
- numeric constraints on these variables to ensure the error

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$$\{y, z\}$$
 + condition  $\{z \ge y\}$ 

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- A:  $\{y,z\}$  + condition  $\{z \ge y\}$   $\iff$  trivial condition (loop condition)
- B:  $\{x\}$  + condition  $\{x \ge 1\}$   $\iff$  non-trivial condition (semantics)

# Error as a CTL property

```
void main(int x, int y, int z){
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    }
    ERROR()
}
```

 $AF\{l_5 : \mathsf{true}\} \in CTL$ 

# Error as a CTL property

# **CTL** properties

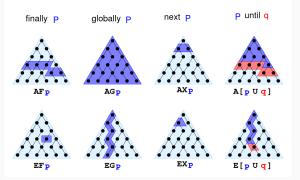
CTL: A branching time logic to express program (trace) properties

$$\phi ::= l \mid \neg \phi \mid \phi \land \phi \mid \phi \lor \phi$$
$$\mid AX\phi \mid AG\phi \mid AF\phi \mid A\{\phi \cup \phi\}$$
$$\mid EX\phi \mid EG\phi \mid EF\phi \mid E\{\phi \cup \phi\}$$

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## Abstract interpretation for CTL properties



#### Abstract Interpretation of CTL Properties

Caterina Urban, Samuel Ueltschi, and Peter Müller

Department of Computer Science ETH Zurich, Switzerland



Abstract. CTL is a temporal logic commonly used to express program properties. Most of the existing approaches for proving CTL properties only support certain classes of programs, limit their scope to a subset of CTL, or do not directly support certain existential CTL formulas. This paper presents an abstract interpretation framework for proving CTL properties that does not suffer from these limitations. Our approach automatically infers sufficient preconditions, and thus provides useful information even when a program satisfies a property only for some inputs. We systematically derive a program semantics that precisely captures CTL properties by abstraction of the operational trace semantics of a program. We then leverage existing abstract domains based on piecewisedefined functions to derive decidable abstractions that are suitable for static program analysis. To handle existential CTL properties, we augment these abstract domains with under-approximating operators. We implemented our approach in a prototype static analyzer. Our experimental evaluation demonstrates that the analysis is effective, even for CTL formulas with non-trivial nesting of universal and existential path quantifiers, and performs well on a wide variety of benchmarks.

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- Abstract sound semantics: decision tree representing piecewise defined function
- Provide efficient algorithms for a static analysis of C programs

```
void main(int x, int y, int z){
                    while(y > z){
3
                    ERROR()
5
6
                                                                           \begin{cases} 3 & y < z \\ 5 & x - y + z \ge 0 \\ 2*y - 2*z + 3 & x \ge 1 \\ \text{undefined} & \text{otherwise} \end{cases}
                                                represents
                                   \overline{3}
     x - y + z \ge 0
```

void main(int x, int y, int z) {
$$y = y - x;$$

$$Frame = x - y + z \ge 0$$

$$x - y + z \ge 0$$

$$2 * y - 2 * z + 3 x \ge 1$$

$$x - y + z \ge 0$$

$$x - y + z$$

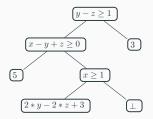
#### **Theorem**

Given a decision tree  $\mathcal{T}_\phi$  for a CTL property  $\phi$ , if  $s \in \mathsf{dom}(\mathcal{T}_\phi)$  then

$$s \models \phi$$
.

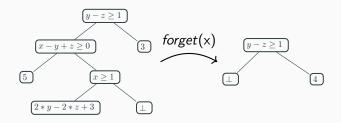
#### **Abstract semantics**

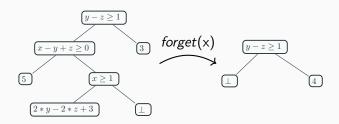
 $\it forget$ : given a decision tree and a variable  $\it X$  try to build a tree by removing all the constraints on  $\it X$ .

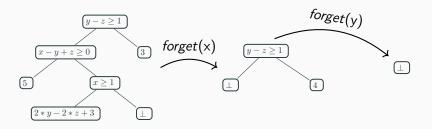


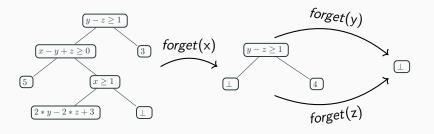
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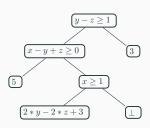


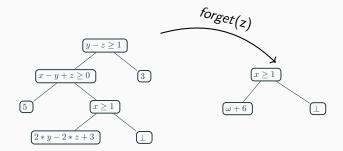


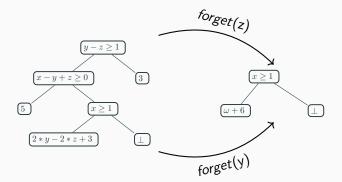


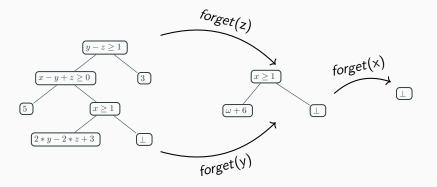


 $\{x\}$  is safe: maximal set of variable that can be removed  $\{y,z\}$  is vulnerable: Complement of maximal safe set  $\{y,z\}$  is a first **minimal** set to control to ensure the reachability of the error

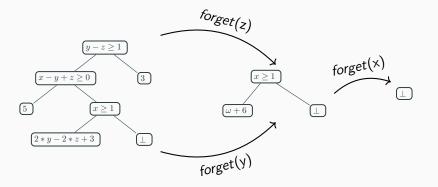








Note: removing contraints on  $\boldsymbol{y}$  removes the contraints on  $\boldsymbol{z}$  and vice-versa

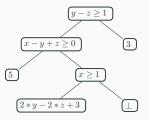


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 $\{y,z\}$  is safe

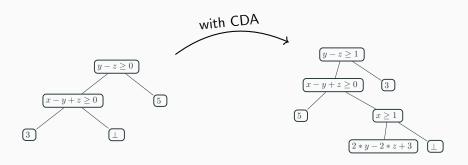
 $\{x\}$  is vulnerable

 $\{x\}$  is a **second** minimal set to control to ensure reachability of the error



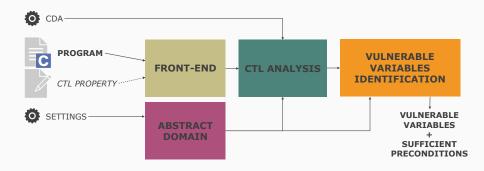
Result of the algorithm is a set of sets to control:  $\{\{x\}, \{y, z\}\}$ 

# **Abstract refinement process**



#### FuncTion-V

Static Analyzer coded in Ocaml Support a numerical subset of C programs.



# Experimentation

 $\label{eq:special-comp} Evaluated \ on \ 347 \ examples \ from: \ SV-Comp, \ Literature, \ LTL-Automizer..$ 

# **Experimentation**

Evaluated on 347 examples from: SV-Comp, Literature, LTL-Automizer.. Number of vulnerable variable sets:

		Vulnerable Sets	Number of Programs	Total Time	Average Time	Average I
	NO CDA	0	146	15 s	0.1 s	79
NO		1	$165 \ (+15)$	21 s	0.1 s	22
NO		2	30	10 s	0.33 s	24
		3	6	5 s	0.7 s	25
	CDA	0	154	23 s	0.15 s	77
_		1	160 (+14)	934 s	5 s	22
CL	.DA	2	79	432 s	15 s	25
		3	5	124 s	25 s	26

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Average minimum percentage of vulnerable variables:

	Termination	Robust Reachability	CTL
NO CDA	17%	26%	32%
CDA	16%	22%	28%

14/18

#### **Related Work**

Robust Reachability: error reachability independently of the values of uncontrolled variables

Implemented in:  $\operatorname{BINSEC-RSE}$ 

#### **Related Work**

Non-exploitability: absence of runtime errors independently of the values of controlled variables

Implemented in: MOPSA

# Comparison

#### FUNCTION-V:

- $(+): {f infer}$  set of variable that imply Robust reachability or Non-exploitability
- $(+): \mathsf{CTL}$  properties: combination of safety and liveness properties
- (+): Termination sensitive
- (-): Restricted to a subset of numerical C-programs while MOPSA and BINSEC-RSE are not!

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#### **Conclusion**

- Detection of variables that an attacker can control to ensure an undesirable properties
- Experimentation on various programs
- More detailed in the paper: semantics, dynamic programming algorithm, Conflict driven analysis