Introduction

MPRI 2–6: Abstract Interpretation, application to verification and static analysis

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course 01b 14 September 2016

Motivating program verification

The cost of software failure

- Patriot MIM-104 failure, 25 February 1991 (death of 28 soldiers¹)
- Ariane 5 failure, 4 June 1996 (cost estimated at more than 370 000 000 US\$²)
- Toyota electronic throttle control system failure, 2005 (at least 89 death³)
- Heartbleed bug in OpenSSL, April 2014
- ...
- economic cost of software bugs is tremendous⁴

¹R. Skeel. "Roundoff Error and the Patriot Missile". SIAM News, volume 25, nr 4.

²M. Dowson. "The Ariane 5 Software Failure". Software Engineering Notes 22 (2): 84, March 1997.

³CBSNews. Toyota "Unintended Acceleration" Has Killed 89. 20 March 2014.

⁴NIST. Software errors cost U.S. economy \$59.5 billion annually. Tech. report, NIST Planning Report, 2002.

Zoom on: Ariane 5, Flight 501



Maiden flight of the Ariane 5 Launcher, 4 June 1996.

Zoom on: Ariane 5, Flight 501



40s after launch...

Zoom on: Ariane 5, Flight 501

Cause: software error⁵

 arithmetic overflow in unprotected data conversion from 64-bit float to 16-bit integer types⁶

```
P_M_DERIVE(T_ALG.E_BH) :=
   UC_16S_EN_16NS (TDB.T_ENTIER_16S
   ((1.0/C_M_LSB_BH) * G_M_INFO_DERIVE(T_ALG.E_BH)));
```

- software exception not caught
 - \Longrightarrow computer switched off
- all backup computers run the same software
 - ⇒ all computers switched off, no guidance
 - ⇒ rocket self-destructs

⁵J.-L. Lions et al., Ariane 501 Inquiry Board report.

⁶J.-J. Levy. Un petit bogue, un grand boum. Séminaire du Département d'informatique de l'ENS, 2010.

How can we avoid such failures?

Choose a safe programming language.

```
C (low level) / Ada, Java (high level)
```

Carefully design the software.
 many software development methods exist

• Test the software extensively.

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yet, Ariane 5 software is written in Ada
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- Carefully design the software.
 many software development methods exist
 yet, critical embedded software follow strict development processes
- Test the software extensively.
 yet, the erroneous code was well tested... on Ariane 4
 - ⇒ not sufficient!

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Choose a safe programming language.

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C (low level) / Ada, Java (high level)
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Test the software extensively.

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yet, the erroneous code was well tested... on Ariane 4
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⇒ not sufficient!

We should use **formal methods**.

provide rigorous, mathematical insurance

Proving program properties

```
assume X in [0,1000];
I := 0;
while I < X do
    I := I + 2;
assert I in [0,?]</pre>
```

Goal: find a bound property, sufficient to express the absence of overflow

⁷R. W. Floyd. "Assigning meanings to programs". In Proc. Amer. Math. Soc. Symposia in Applied Mathematics, vol. 19, pp. 19–31, 1967.

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```
assume X in [0,1000];
{X \in [0, 1000]}
I := 0;
{X \in [0, 1000], I = 0}
while T < X do
    {X \in [0, 1000], I \in [0, 998]}
     I := I + 2:
    {X \in [0, 1000], I \in [2, 1000]}
{X \in [0, 1000], I \in [0, 1000]}
assert I in [0,1000]
```



Robert Floyd⁷

invariant: property true of all the executions of the program

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Robert Floyd⁷

invariant: property true of all the executions of the program **issue**: if I = 997 at a loop iteration, I = 999 at the next

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```
assume X in [0,1000];
{X \in [0, 1000]}
I := 0;
{X \in [0, 1000], I = 0}
while T < X do
     \{X \in [0, 1000], I \in \{0, 2, \dots, 996, 998\}\}\
     I := I + 2;
     {X \in [0, 1000], I \in \{2, 4, \dots, 998, 1000\}}
{X \in [0, 1000], I \in \{0, 2, \dots, 998, 1000\}}
assert I in [0,1000]
```



Robert Floyd⁷

inductive invariant: invariant that can be proved to hold by induction on loop iterates

(if $I \in S$ at a loop iteration, then $I \in S$ at the next loop iteration)

⁷R. W. Floyd. "Assigning meanings to programs". In Proc. Amer. Math. Soc. Symposia in Applied Mathematics. vol. 19, pp. 19–31, 1967.

Logics and programs

$$\begin{split} \overline{\{P[e/X]\}\,\mathtt{X} := e\,\{P\}} &\quad \frac{\{P\}\,\mathtt{C}_1\,\{R\} \quad \{R\}\,\mathtt{C}_2\,\{Q\}}{\{P\}\,\mathtt{C}_1;\,\mathtt{C}_2\,\{Q\}} \\ &\quad \frac{\{P\,\&\,b\}\,\mathtt{C}\,\{P\}}{\{P\}\,\mathtt{while}\,\,\mathtt{b}\,\,\mathtt{do}\,\,\mathtt{C}\,\{P\,\&\,\neg b\}} \\ &\quad \dots \end{split}$$



Tony Hoare⁸

- sound logic to prove program properties, (rel.) complete
- proofs can be partially automated (at least proof checking)
 (e.g., using proof assistants: Coq, PVS, Isabelle, HOL, etc.)

 $^{^{8}}$ C. A. R. Hoare. "An Axiomatic Basis for Computer Programming". Commun. ACM 12(10): 576–580 (1969).

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Tony Hoare⁸

- sound logic to prove program properties, (rel.) complete
- proofs can be partially automated (at least proof checking)
 (e.g., using proof assistants: Coq, PVS, Isabelle, HOL, etc.)
- requires annotations and interaction with a prover even manual annotation is not practical for large programs

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A calculs of program properties

```
\begin{split} & \textit{wlp}(\mathtt{X} := \mathtt{e}, P) \overset{\mathrm{def}}{=} P[e/X] \\ & \textit{wlp}(\mathtt{C}_1; \mathtt{C}_2, P) \overset{\mathrm{def}}{=} \textit{wlp}(\mathtt{C}_1, \textit{wlp}(\mathtt{C}_2, P)) \\ & \textit{wlp}(\mathtt{while} \ \mathtt{e} \ \mathtt{do} \ \mathtt{C}, P) \overset{\mathrm{def}}{=} \\ & \textit{I} \land ((e \land \textit{I}) \implies \textit{wlp}(\mathtt{C}, \textit{I})) \land ((\neg e \land \textit{I}) \implies P) \end{split}
```



Edsger W. Dijkstra⁹

- predicate transformer semantics
 propagate predicates on states through the program
- weakest (liberal) precondition
 backwards, from property to prove to condition for program correctness
- calculs that can be mostly automated

⁹E. W. Dijkstra. "Guarded commands, nondeterminacy and formal derivation of programs". EWD472. Commun. ACM 18(8): 453-457 (1975).

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\begin{aligned} &\textit{wlp}(\mathtt{X} := \mathtt{e}, P) \overset{\mathrm{def}}{=} P[\mathtt{e}/X] \\ &\textit{wlp}(\mathtt{C}_1; \mathtt{C}_2, P) \overset{\mathrm{def}}{=} \textit{wlp}(\mathtt{C}_1, \textit{wlp}(\mathtt{C}_2, P)) \\ &\textit{wlp}(\mathtt{while} \ \mathtt{e} \ \mathtt{do} \ \mathtt{C}, P) \overset{\mathrm{def}}{=} \\ &\textit{I} \land ((\mathtt{e} \land \textit{I}) \implies \textit{wlp}(\mathtt{C}, \textit{I})) \land ((\lnot \mathtt{e} \land \textit{I}) \implies P) \end{aligned}
```



Edsger W. Dijkstra⁹

- predicate transformer semantics
 propagate predicates on states through the program
- weakest (liberal) precondition
 backwards, from property to prove to condition for program correctness
- calculs that can be mostly automated, except for:
 - user annotations for inductive loop invariants
 - function annotations (modular inference)
- academic success: complex (functional) but local properties
- industry success: for simple, local properties

⁹E. W. Dijkstra. "Guarded commands, nondeterminacy and formal derivation of programs". EWD472. Commun. ACM 18(8): 453-457 (1975).

Static analysis

Principle: a program A that

- takes as input another program P (programs are also data!)
- answers with "yes" if the program is safe, "no" if it is not safe
- always answers, hopefully quickly
- ⇒ proves automatically a program safe before it is run!



Alan Turing

Limit to automation: undecidability

It is well known that termination (a useful property) is undecidable. 10 In fact, all "interesting" properties are undecidable 11

 \implies A cannot exist.



¹⁰ A. M. Turing. "Computability and definability". The Journal of Symbolic Logic, vol. 2, pp. 153–163, (1937).

¹¹H. G. Rice. "Classes of Recursively Enumerable Sets and Their Decision Problems." Trans. Amer. Math. Soc. 74, 358-366, 1953.

Approximate static analysis

An approximate static analyzer A always answers in finite time

- either *yes*: the program *P* is definitely safe (soundness)
- either *no*: I don't know (incompleteness)

Sufficient to prove the safety of (some) programs.

Incompleteness: A fails on infinitely many programs. . .

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Sufficient to prove the safety of (some) programs.

Incompleteness: A fails on infinitely many programs. . .

Completeness: for any safe program P, we can design an analyzer \overline{A} that proves it!

- \implies We should adapt the analyzer A to
 - a class of programs to verify, and
 - a class of safety properties to check.



Patrick Cousot¹²



General theory of the approximation and comparison of program semantics:

- unifies many existing semantics
- allows the definition of new static analyses that are correct by construction

¹²P. Cousot. "Méthodes itératives de construction et d'approximation de points fixes d'opérateurs monotones sur un treillis, analyse sémantique des programmes." Thèse És Sciences Mathématiques, 1978.

Abstract interpretation: LIP6 Colloquium



Talk by Patrick Cousot at Paris 6, 29 September 2016, 18h00 https://www.lip6.fr/colloquium/

```
 \begin{array}{l} (\mathcal{S}_0) \\ \text{assume X in [0,1000];} \\ (\mathcal{S}_1) \\ \text{I := 0;} \\ (\mathcal{S}_2) \\ \text{while } (\mathcal{S}_3) \text{ I < X do} \\ (\mathcal{S}_4) \\ \text{I := I + 2;} \\ (\mathcal{S}_5) \\ (\mathcal{S}_6) \\ \text{program} \end{array}
```

```
(S_0)
                                          \mathcal{S}_i \in \mathcal{D} = \mathcal{P}(\{\mathtt{I},\mathtt{X}\} \to \mathbb{Z})
 assume X in [0,1000];
 (S_1)
                                           S_0 = \{(i, x) | i, x \in \mathbb{Z}\}
                                                                                         = T
 I := 0:
                                           S_1 = \{ (i, x) \in S_0 \mid x \in [0, 1000] \} = F_1(S_0)
 (S_2)
                                           S_2 = \{ (0, x) \mid \exists i, (i, x) \in S_1 \}
                                                                                   =F_2(\mathcal{S}_1)
 while (S_3) I < X do
                                          S_2 = S_2 \cup S_5
        (S_4)
                                          S_4 = \{ (i, x) \in S_3 \mid i < x \}
                                                                               =F_4(S_3)
        I := I + 2:
                                           S_5 = \{(i+2,x) | (i,x) \in S_4\} = F_5(S_4)
       (S_5)
                                           S_6 = \{ (i, x) \in S_3 \mid i > x \}
                                                                                         =F_6(S_3)
 (S_6)
                                        semantics
program
```

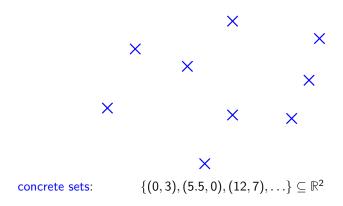
Concrete semantics $S_i \in \mathcal{D} = \mathcal{P}(\{\mathtt{I},\mathtt{X}\} \to \mathbb{Z})$:

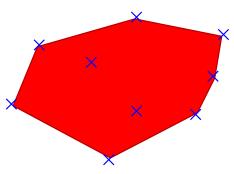
- strongest invariant (and an inductive invariant)
- not computable in general
- smallest solution of a system of equations

```
(S_0)
                                                                               \mathcal{S}_{i}^{\sharp} \in \mathcal{D}^{\sharp}
   assume X in [0,1000];
                                                                               \mathcal{S}_0^{\sharp} = \top^{\sharp}
   (S_1)
                                                                               S_1^{\sharp} = [\![ assume \ X \in [0, 1000] ]\!]^{\sharp} (S_0^{\sharp})
   I := 0:
   (S_2)
                                                                               \mathcal{S}_2^{\sharp} = \llbracket I \leftarrow 0 \rrbracket^{\sharp} (\mathcal{S}_1^{\sharp})
   while (S_3) I < X do
                                                                               S_2^{\sharp} = S_2^{\sharp} \cup^{\sharp} S_5^{\sharp}
              (S_4)
                                                                               \mathcal{S}_{A}^{\sharp} = \llbracket \text{ assume } I < X \rrbracket^{\sharp} (\mathcal{S}_{3}^{\sharp})
               I := I + 2;
                                                                               \mathcal{S}_{5}^{\sharp} = \llbracket I \leftarrow I + 2 \rrbracket^{\sharp} (\mathcal{S}_{4}^{\sharp})
             (S_5)
                                                                               S_6^{\sharp} = \llbracket \text{ assume } I > X \rrbracket^{\sharp} (S_2^{\sharp})
   (S_6)
                                                                          semantics
program
```

Abstract semantics $S_i^{\sharp} \in \mathcal{D}^{\sharp}$:

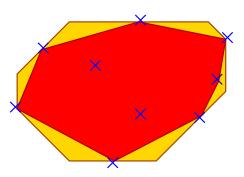
- \mathcal{D}^{\sharp} is a subset of properties of interest (approximation) with a machine representation
- $F^{\sharp}: \mathcal{D}^{\sharp} \to \mathcal{D}^{\sharp}$ over-approximates the effect of $F: \mathcal{D} \to \mathcal{D}$ in \mathcal{D}^{\sharp} (with effective algorithms)





concrete sets: $\{(0,3),(5.5,0),(12,7),\ldots\}\subseteq\mathbb{R}^2$

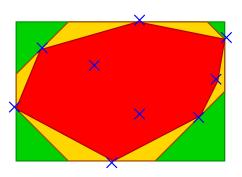
abstract polyhedra: $6X + 11Y \ge 33 \land \cdots$



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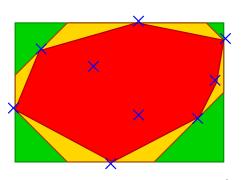
abstract octagons: $X + Y \ge 3 \land Y \ge 0 \land \cdots$



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abstract polyhedra: $6X + 11Y \ge 33 \land \cdots$

abstract octagons: $X + Y \ge 3 \land Y \ge 0 \land \cdots$ abstract intervals: $X \in [0, 12] \land Y \in [0, 8]$



concrete sets:

 $\{(0,3),(5.5,0),(12,7),\ldots\}\subseteq\mathbb{R}^2$

abstract polyhedra: $6X + 11Y \ge 33 \land \cdots$

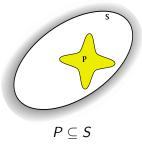
abstract octagons: $X + Y > 3 \land Y > 0 \land \cdots$

abstract intervals: $X \in [0, 12] \land Y \in [0, 8]$

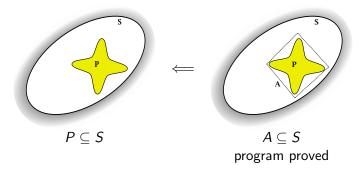
not computable exponential cost cubic cost linear cost

Trade-off between cost and expressiveness / precision

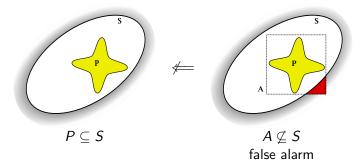
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Goal: prove that a program P satisfies its specification S



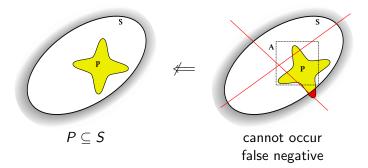
<u>Goal</u>: prove that a program *P* satisfies its specification *S* A polyhedral abstraction *A* can prove the correctness.



Goal: prove that a program P satisfies its specification S

A polyhedral abstraction A can prove the correctness.

An interval abstraction cannot prove the correctness ⇒ false alarm.



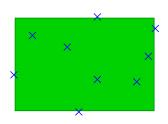
Goal: prove that a program P satisfies its specification S

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An interval abstraction cannot prove the correctness ⇒ false alarm.

The analysis is sound: no false negative reported!

Abstract elements and operators



abstract semantics F^{\sharp} in the interval domain \mathcal{D}_{i}^{\sharp}

- $I \in \mathcal{D}_i^{\sharp}$ is a pair of bounds $(\ell, h) \in \mathbb{Z}^2$ (for each variable) representing an interval $[\ell, h] \subseteq \mathbb{Z}$
- I:=I+2: $(\ell, h) \mapsto (\ell+2, h+2)$
- \cup^{\sharp} : $(\ell_1, h_1) \cup^{\sharp} (\ell_2, h_2) = (\min(\ell_1, \ell_2), \max(h_1, h_2))$
- . . .

Resolution by iteration and extrapolation

 $\underline{ \text{Challenge:}} \text{ the equation system is recursive: } \vec{\mathcal{S}}^{\sharp} = \vec{F}^{\sharp}(\vec{\mathcal{S}}^{\sharp}).$

 $\underline{\text{Solution:}} \text{ resolution by iteration: } \vec{\mathcal{S}}^{\sharp \, 0} = \emptyset^{\sharp}, \ \vec{\mathcal{S}}^{\sharp \, i+1} = \vec{F}^{\sharp}(\vec{\mathcal{S}}^{\sharp \, i}).$

e.g., \mathcal{S}_3^{\sharp} : I \in \emptyset , I = 0, I \in [0,2], I \in [0,4], ..., I \in [0,1000]

Resolution by iteration and extrapolation

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Solution: resolution by iteration: $\vec{\mathcal{S}}^{\sharp \, 0} = \emptyset^{\sharp}, \ \vec{\mathcal{S}}^{\sharp \, i+1} = \vec{F}^{\sharp}(\vec{\mathcal{S}}^{\sharp \, i}).$ e.g., $\mathcal{S}_3^{\sharp} : \mathbf{I} \in \emptyset, \ \mathbf{I} = 0, \ \mathbf{I} \in [0,2], \ \mathbf{I} \in [0,4], \dots, \ \mathbf{I} \in [0,1000]$

Challenge: infinite or very long sequence of iterates in \mathcal{D}^{\sharp}

Solution: extrapolation operator ∇

e.g.,
$$[0,2] \ \forall \ [0,4] = [0,+\infty[$$

- remove unstable bounds and constraints
- ensures the convergence in finite time
- inductive reasoning (through generalisation)

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e.g.,
$$\mathcal{S}_3^{\sharp}:\,\mathtt{I}\in\emptyset,\,\mathtt{I}=0,\,\mathtt{I}\in[0,2],\,\mathtt{I}\in[0,4],\,\ldots,\,\mathtt{I}\in[0,1000]$$

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e.g.,
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- remove unstable bounds and constraints
- ensures the convergence in finite time
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 \Longrightarrow effective solving method \longrightarrow static analyzer!

Other uses of abstract interpretation

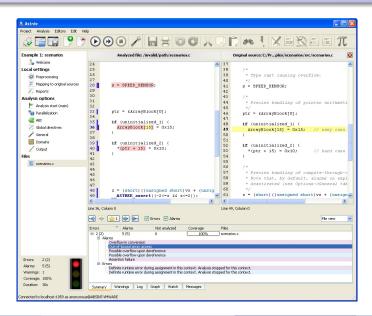
- Analysis of dynamic memory data-structures (shape analysis).
- Analysis of parallel, distributed, and multi-thread programs.
- Analysis of probabilistic programs.
- Analysis of biological systems.
- Security analysis (information flow).
- Termination analysis.
- Cost analysis.
- Analyses to enable compiler optimisations.

• . . .

A few examples of abstract interpretation tools

- Proprietary tools
 - PolySpace analyzer (MathWorks)
 run-time errors in Ada, C, C++
 - aiT (AbsInt) worst-case execution time for binary
 - Astrée (CNRS, ENS, INRIA, AbsInt)
 run-time errors in embedded C, with an emphasis on validation
 - Sparrow (Seoul National University)
 run-time errors in C
 - Julia (University of Verona) analysis of Java and Andorid
- Open-source tools
 - Frama-C (CEA LIST, INRIA, TrustInSoft)
 run-time errors in C software, also has a commercial version
 - Code Contracts Static Checker (Microsoft Research) static checking and inference of .NET contracts

The Astrée static analyzer



The Astrée static analyzer

Analyseur statique de programmes temps-réels embarqués

(static analyzer for real-time embedded software)

- developed at ENS
 - B. Blanchet, P. Cousot, R. Cousot, J. Feret, L. Mauborgne, D. Monniaux, A. Miné, X. Rival
- industrialized and made commercially available by AbsInt





www.absint.com

The Astrée static analyzer

Specialized:

- for the analysis of run-time errors
 (arithmetic overflows, array overflows, divisions by 0, etc.)
- on embedded critical C software (no dynamic memory allocation, no recursivity)
- in particular on control / command software (reactive programs, intensive floating-point computations)
- intended for validation

 (analysis does not miss any error and tries to minimise false alarms)

Approximately 40 abstract domains are used at the same time:

- numeric domains (intervals, octagons, ellipsoids, etc.)
- boolean domains
- domains expressing properties on the history of computations

Astrée applications



Airbus A340-300 (2003)



Airbus A380 (2004)



(model of) ESA ATV (2008)

- size: from 70 000 to 860 000 lines of C
- analysis time: from 45mn to \simeq 40h
- 0 alarm: proof of absence of run-time error