

**PhD. Defense**

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**Weakly Relational Numerical  
Abstract Domains**

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**Domaines numériques abstraits faiblement relationnels**

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**Antoine Miné**

École Normale Supérieure, Paris

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# Introduction

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## Main Goal:

- discover properties on the **numerical** variables of a program,
- **statically**, at compile-time,
- **automatically**, without human interaction.

## Applications of Numerical Properties:

- Check for illegal arithmetic operations: overflow, division by zero.  
(Ariane 5 explosion on June the 4-th 1996  $\implies$  \$ 500 M loss)
- Check for out-of-bound array or pointer accesses.
- Optimisation, debugging information inference.
- Parameters to non-numerical analyses.  
(pointer analyses, parametric predicate abstractions, etc.)

# Overview

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- ◆ Formal framework, previous work, motivation for our work.
- ◆ New numerical abstract domains: weakly relational domains.
- ◆ Improving the precision using generic symbolic manipulation techniques.
- ◆ Dealing with floating-point semantics.
- ◆ Application within the *Astrée* analyser and experimental results.

# **(Simplified) Formal Framework**

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# Language Syntax

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For the sake of presentation:

- one data-type: **scalars** in  $\mathbb{I}$ , where  $\mathbb{I} \in \{\mathbb{Z}, \mathbb{Q}, \mathbb{R}\}$ ,
- no procedure,
- a **finite, fixed** set of variables:  $\mathcal{V}$ .

◆ **instructions**  $\mathcal{I} ::= X \leftarrow \mathcal{E}$       assignment to  $X \in \mathcal{V}$   
                  |  $\mathcal{E} \bowtie 0 ?$       test  $\bowtie \in \{=, \leq, \dots\}$

◆ **expressions**  $\mathcal{E} ::= [a, b]$       interval  $a \in \mathbb{I} \cup \{-\infty\}$ ,  $b \in \mathbb{I} \cup \{+\infty\}$ ,  
                  |  $X$       variable  $X \in \mathcal{V}$   
                  |  $-\mathcal{E}$       unary operator  
                  |  $\mathcal{E} \diamond \mathcal{E}$       binary operators  $\diamond \in \{+, \times, \dots\}$

**Note:**  $[a, b]$  models a **non-deterministic** choice within an interval.

# Semantics

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**Environments:** maps  $\rho \in (\mathcal{V} \rightarrow \mathbb{I})$ .

**Expression Semantics:**  $\llbracket \mathcal{E} \rrbracket: (\mathcal{V} \rightarrow \mathbb{I}) \rightarrow \mathcal{P}(\mathbb{I})$

$\mathcal{E}$  maps **environments** to **sets** of numerical values:

$$\begin{aligned}\llbracket [a, b] \rrbracket(\rho) &\stackrel{\text{def}}{=} \{ c \in \mathbb{I} \mid a \leq c \leq b \}, \\ \llbracket X \rrbracket(\rho) &\stackrel{\text{def}}{=} \{ \rho(X) \}, \\ \llbracket e_1 + e_2 \rrbracket(\rho) &\stackrel{\text{def}}{=} \{ v_1 + v_2 \mid v_1 \in \llbracket e_1 \rrbracket(\rho), v_2 \in \llbracket e_2 \rrbracket(\rho) \}, \\ &\text{etc.}\end{aligned}$$

**Instruction Semantics:**  $\llbracket \mathcal{I} \rrbracket: \mathcal{P}(\mathcal{V} \rightarrow \mathbb{I}) \rightarrow \mathcal{P}(\mathcal{V} \rightarrow \mathbb{I})$

A **transfer function** defines a **relation** between environments:

$$\begin{aligned}\{ X \leftarrow e \}(R) &\stackrel{\text{def}}{=} \{ \rho [ X \mapsto v ] \mid \rho \in R, v \in \llbracket e \rrbracket(\rho) \}, \\ \{ e \bowtie 0 ? \}(R) &\stackrel{\text{def}}{=} \{ \rho \in R \mid \exists v \in \llbracket e \rrbracket(\rho) \text{ such that } v \bowtie 0 \}.\end{aligned}$$

# Reachability Semantics

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Given a control-flow graph  $(L, e, I)$ :

$L$	program points
$e \in L$	entry point
$I \subseteq L \times \mathcal{I} \times L$	arcs

we seek to compute the **reachability semantics**, the smallest solution of:

$$\mathcal{X}_l = \begin{cases} (\mathcal{V} \rightarrow \mathbb{I}) & \text{if } l = e & \text{(initial state)} \\ \bigcup_{(l', i, l) \in I} \{i\}(\mathcal{X}_{l'}) & \text{if } l \neq e & \text{(transfer function)} \end{cases}$$

that gathers all possible environments at each program points.

**Problem:** This is **not computable** in general.

$\implies$  we will compute **sound over-approximations** of the  $\mathcal{X}_l \dots$

# Abstract Interpretation

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## Abstract Interpretation:

General theory of sound approximations of semantics [Cousot78].

## Numerical Abstract Domain:

- **computer-representable** set  $\mathcal{D}^\#$  of **abstract values**, together with:
- a **concretisation**:  $\gamma: \mathcal{D}^\# \rightarrow \mathcal{P}(\mathcal{V} \rightarrow \mathbb{I})$ ,
- a **partial order**:  $\sqsubseteq^\#, \perp^\#, \top^\#$ ,
- sound, effective **abstract transfer functions**  $\{\mathcal{I}\}^\#$ :  $(\{\mathcal{I}\} \circ \gamma)(\mathcal{X}^\#) \subseteq (\gamma \circ \{\mathcal{I}\}^\#)(\mathcal{X}^\#)$ ,  
a sound, effective **abstract union**  $\cup^\#$ :  $\gamma(\mathcal{X}^\#) \cup \gamma(\mathcal{Y}^\#) \subseteq \gamma(\mathcal{X}^\# \cup^\# \mathcal{Y}^\#)$ ,
- effective **extrapolation operators**  $\nabla, \Delta$  if  $\mathcal{D}^\#$  has infinite chains.

$\implies$  we can perform a reachability analysis in  $L \rightarrow \mathcal{D}^\#$  soundly.

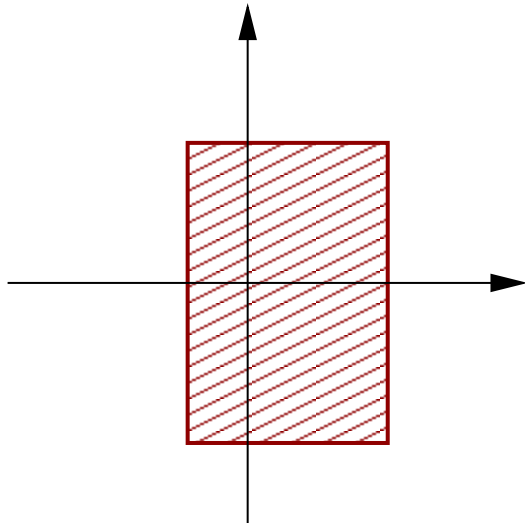
There does not exist an all-purpose abstract domain.

We need a fine control on both the **semantic** and **algorithmic** aspects!



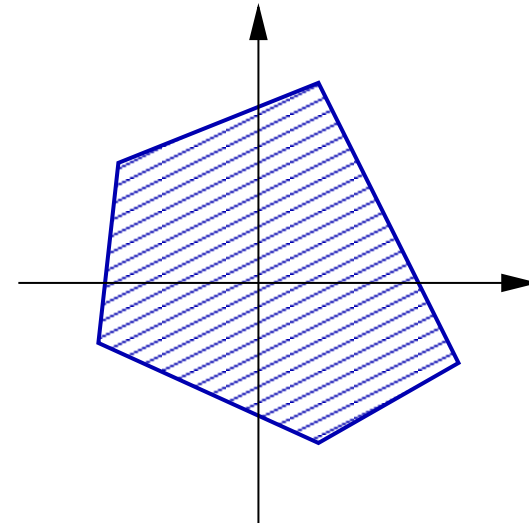
# Existing Numerical Abstract Domains

Before this work, the two most used numerical abstract domains were:



Intervals (1976)  
 $\bigwedge_i (X_i \in [a_i, b_i])$

**non relational**  
**linear** cost



Polyhedra (1978)  
 $\bigwedge_j (\sum_i \alpha_{ij} X_i \leq \beta_j)$

**relational**  
**unbounded** cost  
exponential in practice

There were other domains, but no domain “**in-between**” these two.

# The Need for Relational Domains

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## Example:

```
I := 10
V := 0
while • (I ≥ 0) {
  I := I - 1
  if (random()) { V := V + 1 }
} • // here I = -1 and 0 ≤ V ≤ 11
```

To prove that  $V \leq 11$  at •,  
we need to prove the **relational** loop invariant  $V + I \leq 10$  at •.

Other applications:

- analysis of programs with **symbolic** parameters,
- **modular** analysis of procedures, (out of context)
- inference of **non-uniform** non-numerical invariants. (e.g., pointer analysis)

# Weakly Relational Abstract Domains

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New abstract domains introduced in this PhD:

- zone abstract domain,
- octagon abstract domain,
- zone congruence abstract domain.

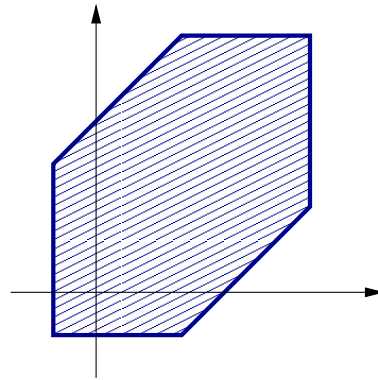
# The Zone Abstract Domain

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**Simplest** of our three domains, but **characteristic** in its construction.

**Zones** enrich intervals with invariants of the form:

$$\bigwedge_{ij} (V_i - V_j \leq c_{ij}) \quad c_{ij} \in \mathbb{I}$$



The zone abstract domain features:

- a precision between the interval and polyhedron domains; **relational** invariants,
- a **quadratic** memory cost and **cubic** worst-case time cost.

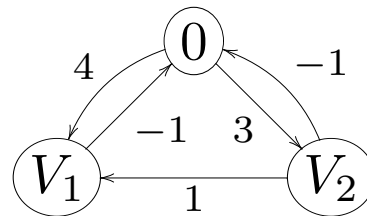
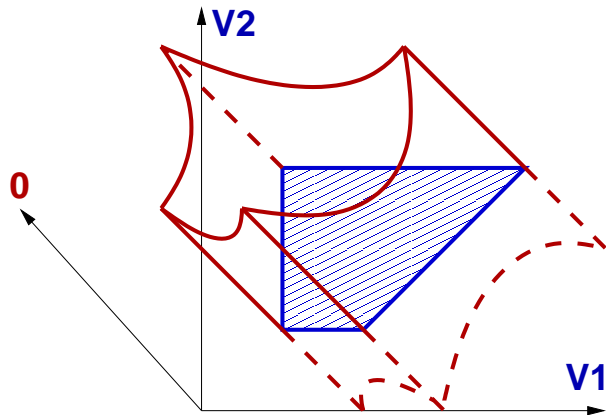
Zones are used in the model-checking of timed automata and Petri nets but they need many new abstract operators to suit Abstract Interpretation needs.

# Zone Representation

## Difference Bound Matrices: (DBMs)

- ◆ matrix of size  $(n + 1) \times (n + 1)$  with elements in  $\bar{\mathbb{I}} \stackrel{\text{def}}{=} \mathbb{I} \cup \{+\infty\}$ :
  - $\mathbf{m}_{ij} \neq +\infty$  is an upper bound for  $V_j - V_i$ ,
  - $\mathbf{m}_{ij} = +\infty$  means that  $V_j - V_i$  is unbounded,
  - $\mathbf{m}_{i0}, \mathbf{m}_{0j}$  encode unary constraints:  $-V_i \leq \mathbf{m}_{i0}, V_j \leq \mathbf{m}_{0j}$ ,
- ◆  $\gamma(\mathbf{m}) \stackrel{\text{def}}{=} \{ (v_1, \dots, v_n) \in \mathbb{I} \mid \forall i, j, v_j - v_i \leq \mathbf{m}_{ij}, v_0 = 0 \}$ ,
- ◆  $\mathbf{m}$  is the adjacency matrix of a **weighted directed graph**:  $V_i \xrightarrow{\mathbf{m}_{ij}} V_j$ .

### Example:



		$j$		
		0	$V_1$	$V_2$
$i$	0	$+\infty$	4	3
	$V_1$	-1	$+\infty$	$+\infty$
	$V_2$	-1	1	$+\infty$

# Order Structure

The total order on  $\mathbb{I}$  is extended to  $\bar{\mathbb{I}} \stackrel{\text{def}}{=} \mathbb{I} \cup \{+\infty\}$ .

The total order on  $\bar{\mathbb{I}}$  is extended to a partial order on  $\mathcal{D}^\#$ :

$$\begin{array}{llll} \mathbf{m} \sqsubseteq^\# \mathbf{n} & \stackrel{\text{def}}{\iff} & \forall i, j, \mathbf{m}_{ij} \leq \mathbf{n}_{ij} & \text{point-wise partial order} \\ [\mathbf{m} \sqcap^\# \mathbf{n}]_{ij} & \stackrel{\text{def}}{=} & \min(\mathbf{m}_{ij}, \mathbf{n}_{ij}) & \text{greatest lower bound} \\ [\mathbf{m} \sqcup^\# \mathbf{n}]_{ij} & \stackrel{\text{def}}{=} & \max(\mathbf{m}_{ij}, \mathbf{n}_{ij}) & \text{least upper bound} \\ [\top^\#]_{ij} & \stackrel{\text{def}}{=} & +\infty & \text{greatest element} \end{array}$$

## However:

- $\mathbf{m} \sqsubseteq^\# \mathbf{n} \implies \gamma(\mathbf{m}) \subseteq \gamma(\mathbf{n})$  but not the converse,
- $\mathbf{m} = \mathbf{n} \implies \gamma(\mathbf{m}) = \gamma(\mathbf{n})$  but not the converse:  $\gamma$  is not injective!

$\implies$  we introduce a **normal form**.

# Normal Form

**Idea:** Derive **implicit** constraints by summing weights on adjacent arcs:

e.g. 
$$\begin{cases} V_1 - V_2 \leq 3 \\ V_2 - V_3 \leq -1 \\ V_1 - V_3 \leq 4 \end{cases}$$

$$\begin{cases} V_1 - V_2 \leq 3 \\ V_2 - V_3 \leq -1 \\ V_1 - V_3 \leq 2 \end{cases}$$

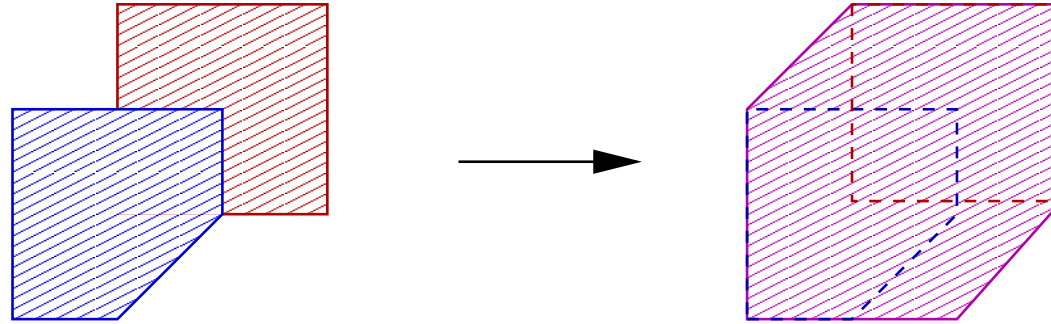
**Shortest-Path Closure  $\mathbf{m}^*$ :** Floyd–Warshall algorithm:

$$\begin{cases} \mathbf{m}_{ij}^* & \stackrel{\text{def}}{=} & \mathbf{m}_{ij}^{n+1} \\ \mathbf{m}_{ij}^0 & \stackrel{\text{def}}{=} & \mathbf{m}_{ij} \\ \mathbf{m}_{ij}^{k+1} & \stackrel{\text{def}}{=} & \min(\mathbf{m}_{ij}^k, \mathbf{m}_{ik}^k + \mathbf{m}_{kj}^k) \quad \text{if } 0 \leq k \leq n \end{cases}$$

- derives **all** implicit constraints in **cubic** time,
- gives a **normal form** when  $\gamma(\mathbf{m}) \neq \emptyset$ :  $\mathbf{m}^* = \inf_{\sqsubseteq^\#} \{ \mathbf{n} \mid \gamma(\mathbf{n}) = \gamma(\mathbf{m}) \}$ ,
- enables **emptiness testing**:  $\gamma(\mathbf{m}) = \emptyset \iff \exists i, \mathbf{m}_{ii}^* < 0$ ,
- enables **inclusion testing**:  $\gamma(\mathbf{m}) \subseteq \gamma(\mathbf{n}) \iff \mathbf{m}^* \sqsubseteq^\# \mathbf{n}^*$ , etc.

# Operator Example: Abstract Union

The union of two zones is not always a zone:



$\sqcup^\#$  is a sound counterpart for  $\cup$ :  $\gamma(\mathbf{m}) \cup \gamma(\mathbf{n}) \subseteq \gamma(\mathbf{m} \sqcup^\# \mathbf{n})$ .

But it may not output the smallest zone encompassing two zones... because of implicit constraints.

**Solution:** Define  $\mathbf{m} \cup^\# \mathbf{n} \stackrel{\text{def}}{=} \mathbf{m}^* \sqcup^\# \mathbf{n}^*$ :

- always the best abstraction:  $\gamma(\mathbf{m} \cup^\# \mathbf{n}) = \inf_{\subseteq} \{ \gamma(\mathbf{o}) \mid \gamma(\mathbf{m}), \gamma(\mathbf{n}) \subseteq \gamma(\mathbf{o}) \}$
- $\mathbf{m} \cup^\# \mathbf{n}$  is already closed:  $(\mathbf{m} \cup^\# \mathbf{n})^* = \mathbf{m} \cup^\# \mathbf{n}$

**Note:** The intersection  $\sqcap^\#$  behaves differently (dually).



# Operator Example: Abstract Assignment

We propose **several** operators with varying cost versus precision trade-offs.

**Exact Assignments:** Only for  $X \leftarrow Y + [a, b]$ ,  $X \leftarrow X + [a, b]$ , or  $X \leftarrow [a, b]$ .

$$\text{e.g. } \left[ \{ V_{j_0} \leftarrow V_{i_0} + [a, b] \}^\#(\mathbf{m}) \right]_{ij} \stackrel{\text{def}}{=} \begin{cases} -a & \text{if } i = j_0 \text{ and } j = i_0, \\ b & \text{if } i = i_0 \text{ and } j = j_0, \\ +\infty & \text{otherwise if } i = j_0 \text{ or } j = j_0, \\ \mathbf{m}_{ij}^* & \text{otherwise.} \end{cases}$$

## Interval and Polyhedra Based Assignments

We can reuse existing transfer functions from other abstract domains using:

- **exact conversion** operators: intervals  $\rightarrow$  zones  $\rightarrow$  polyhedra,
- **best conversion** operators: polyhedra  $\rightarrow$  zones  $\rightarrow$  intervals. (using  $*$ )

- e.g.  $\left| \begin{array}{l} \bullet \text{ **best** abstract assignment for **linear expressions** using **polyhedra**,} \\ \bullet \text{ **fast** assignment of **arbitrary expressions** using **intervals**.} \end{array} \right.$

# Operator Example: Abstract Assignment

**Problem:** for many usual assignments, e.g.,  $X \leftarrow Y + Z$ :

- there is no exact abstraction,
- the polyhedron-based assignment is too costly, (exponential cost)
- the interval-based assignment is very imprecise. (not relational enough)

$\implies$  we introduce an operator with intermediate cost versus precision.

**Interval Linear Form Assignments:**  $V_j \leftarrow [a_0, b_0] + \sum_k ([a_k, b_k] \times V_k)$

**For each**  $i$ , derive new bounds on  $V_j - V_i$  by evaluating:

$$[a_0, b_0] + \sum_{k \neq i} ([a_k, b_k] \times \pi_k(\mathcal{X}^\#)) + ([a_i - 1, b_i - 1] \times \pi_i(\mathcal{X}^\#))$$

using the **interval** operators  $+$ ,  $\times$ , and the interval projections  $\pi_k$  of variables  $V_k$ .

$\implies$  we can **infer** relational invariants for a **linear cost**.

Not optimal because we do not use the relational information in the zone.

# Operator Example: Widening

The zone abstract domain has infinite strictly increasing chains!

We need a **widening**  $\nabla$  to compute fixpoints in finite time:

$$\left\{ \begin{array}{l} x_0^\# \stackrel{\text{def}}{=} y_0^\# \\ x_{i+1}^\# \stackrel{\text{def}}{=} x_i^\# \nabla y_{i+1}^\# \end{array} \right. \text{ should } \left\{ \begin{array}{l} \text{converge in } \mathbf{finite\ time} \\ \text{towards an over-approximation of } \bigcup_i \gamma(y_i^\#) \end{array} \right.$$

Example Widening: Point-wise standard interval widening:

$$(\mathbf{m} \nabla \mathbf{n})_{ij} \stackrel{\text{def}}{=} \begin{cases} \mathbf{m}_{ij} & \text{if } \mathbf{m}_{ij} \geq \mathbf{n}_{ij} \\ +\infty & \text{otherwise} \end{cases}$$

Unstable constraints are simply thrown away.

## Notes:

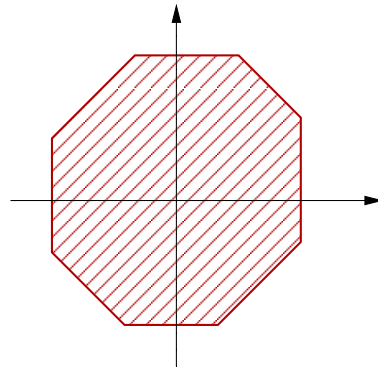
- Any interval widening can be extended point-wisely.
- $x_{i+1}^\# \stackrel{\text{def}}{=} (x_i^\# *) \nabla y_i^\#$  may diverge! Bad interaction between  $*$  and  $\nabla$ .

# The Octagon Abstract Domain

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**Octagons** extend zones to invariants of the form:

$$\bigwedge_{ij} (\pm V_i \pm V_j \leq c_{ij}) \quad \mathbb{I} \in \{\mathbb{Z}, \mathbb{Q}, \mathbb{R}\}$$



- It is strictly **more expressive** than the zone domain.
- It has the same asymptotic cost: **quadratic** in memory and **cubic** in time.
- It is sufficient to analyse our first example!

The main difficulty is to **adapt the normal form algorithm**.

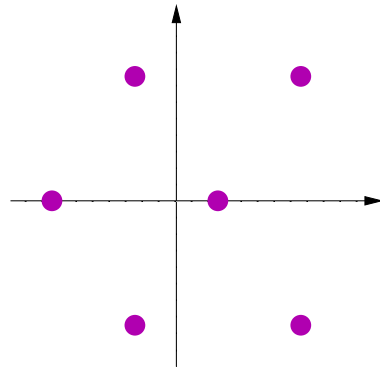
All our exactness, best abstraction results derive from the new normal form.

# The Zone Congruence Abstract Domain

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**Zone congruences** correspond to invariants of the form:

$$\bigwedge_{ij} (V_i \equiv V_j + b_{ij} [c_{ij}]) \quad \mathbb{I} \in \{\mathbb{Z}, \mathbb{Q}\}$$



The main difficulty is, again, to adapt the normal form algorithm.

We use a technique similar to Floyd–Warshall’s algorithm in dioid algebras.

# Symbolic Manipulation

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# Core Principles

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**Idea:** Replace expressions with nicer ones.

Suppose that  $\forall \rho \in \gamma(\mathcal{X}^\#)$ ,  $\llbracket e \rrbracket(\rho) \subseteq \llbracket e' \rrbracket(\rho)$ , then:

$$(\{V \leftarrow e\} \circ \gamma)(\mathcal{X}^\#) \subseteq (\gamma \circ \{V \leftarrow e'\}^\#)(\mathcal{X}^\#)$$

$\implies$  we can safely use  $\{V \leftarrow e'\}^\#(\mathcal{X}^\#)$  in place of  $\{V \leftarrow e\}^\#(\mathcal{X}^\#)$ .

The same holds for tests.

## Example Application:

If  $X \in [0, 1]$  in  $\mathcal{X}^\#$ : we replace  $\{V \leftarrow X \times Y\}^\#(\mathcal{X}^\#)$  with  $\{V \leftarrow [0, 1] \times Y\}^\#(\mathcal{X}^\#)$ .

Useful because our abstraction of non-linear assignments is imprecise.

**Note:** Interactions between numerical abstract values  $\mathcal{X}^\#$  and expression transformations.  
( $\neq$  performing a static program transformation before the analysis)

# Linearisation

**Goal:** Put arbitrary expressions to the form  $[a_0, b_0] + \sum_k ([a_k, b_k] \times V_k)$ .

Useful when we have interval linear form assignment operators. (zones, etc.)

## Interval Linear Form Manipulations: $\cdot, a, b, m, l$

Resemble a **vector space** structure.

- $$([a_0, b_0] + \sum_k [a_k, b_k] \times V_k) \cdot ([a'_0, b'_0] + \sum_k [a'_k, b'_k] \times V_k) \stackrel{\text{def}}{=} (([a_0, b_0] + [a'_0, b'_0]) + \sum_k ([a_k, b_k] + [a'_k, b'_k]) \times V_k)$$
- $$[a, b] \cdot ([a'_0, b'_0] + \sum_k [a'_k, b'_k] \times V_k) \stackrel{\text{def}}{=} ([a, b] \times [a'_0, b'_0]) + \sum_k ([a, b] \times [a'_k, b'_k]) \times V_k$$
- $$l([a_0, b_0] + \sum_k [a_k, b_k] \times V_k, \mathcal{X}^\#) \stackrel{\text{def}}{=} [a_0, b_0] + \sum_k ([a_k, b_k] \times \pi_k(\mathcal{X}^\#))$$

(on-the-fly intervalisation)



# Linearisation (continued)

Linearising an expression:  $\llbracket e \rrbracket$  defined by structural induction:

- $\llbracket V_i \rrbracket(\mathcal{X}^\#) \stackrel{\text{def}}{=} [1, 1] \times V_i$
- $\llbracket e_1 + e_2 \rrbracket(\mathcal{X}^\#) \stackrel{\text{def}}{=} \llbracket e_1 \rrbracket(\mathcal{X}^\#) + \llbracket e_2 \rrbracket(\mathcal{X}^\#)$
- $\llbracket e_1 \times e_2 \rrbracket(\mathcal{X}^\#) \stackrel{\text{def}}{=} [a, b] \times \llbracket e_2 \rrbracket(\mathcal{X}^\#)$  when  $\llbracket e_1 \rrbracket(\mathcal{X}^\#) = [a, b]$
- $\llbracket e_1 \times e_2 \rrbracket(\mathcal{X}^\#) \stackrel{\text{def}}{=} \iota(\llbracket e_1 \rrbracket(\mathcal{X}^\#), \mathcal{X}^\#) \times \llbracket e_2 \rrbracket(\mathcal{X}^\#)$  or  
 $\llbracket e_1 \times e_2 \rrbracket(\mathcal{X}^\#) \stackrel{\text{def}}{=} \iota(\llbracket e_2 \rrbracket(\mathcal{X}^\#), \mathcal{X}^\#) \times \llbracket e_1 \rrbracket(\mathcal{X}^\#)$

## Notes:

- ◆ **Non-linear multiplication:** we must **choose** whether to intervalise  $e_1$  or  $e_2$ .  
example: intervalise the expression with smallest bounds

$$X \in [0, 1], Y \in [-10, 10] \implies \llbracket X \times Y \rrbracket(\mathcal{X}^\#) = [0, 1] \times Y$$

- ◆ Linearisation provides **simplification for free:**  $\llbracket (X + Y) - X \rrbracket(\mathcal{X}^\#) = Y$ .

If  $X, Y \in [0, 1]$ , interval arithmetics gives  $\llbracket (X + Y) - X \rrbracket^\# = [-1, 2]$  but  $\llbracket Y \rrbracket^\# = [0, 1]$ .

# Symbolic Constant Propagation

Idea: Enhance simplification-by-linearisation using expression propagation.

Example:  $X \leftarrow Y + Z; U \leftarrow X - Z$

- $\{ U \leftarrow X - Z \}^\#$  is replaced with  $\{ U \leftarrow (Y + Z) - Z \}^\#$ ,
- which is linearised into  $\{ U \leftarrow Y \}^\#$ .

Technique:  $\mathcal{X}^\# \in \mathcal{D}^\#$  is enriched with a map  $S^\# \in (\mathcal{V} \rightarrow \mathcal{E})$ .

◆ Abstract elements  $\langle \mathcal{X}^\#, S^\# \rangle$  now represent:

$$\gamma \langle \mathcal{X}^\#, S^\# \rangle \stackrel{\text{def}}{=} \{ \rho \in \gamma(\mathcal{X}^\#) \mid \forall i, \rho(V_i) \in \llbracket S^\#(V_i) \rrbracket(\rho) \}.$$

◆ Abstract assignments  $\{ X \leftarrow e \}^\# \langle \mathcal{X}^\#, S^\# \rangle$

- **propagate**  $S^\#$  into  $e$  to get  $e'$  and evaluate  $\mathcal{X}^{\#'} \stackrel{\text{def}}{=} \{ X \leftarrow e' \}^\#(\mathcal{X}^\#)$ ,
- kill information on  $X$  in  $S^\#$ , then add  $X = e$ .

Note: We must **choose** how far to propagate.

# **Floating-Point Number Abstractions**

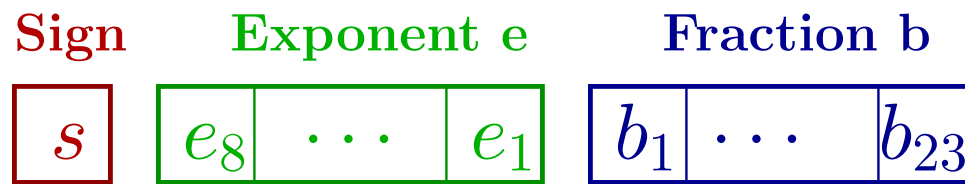
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# IEEE 754-1985 Floating-Point Numbers:

We consider the **IEEE 754-1985 norm** because:

- ◆ it is widely implemented in today's hardware (Intel, Motorola),
- ◆ it is supported by the C language (and many others).

**Example: 32-bit “single precision” float numbers  $\mathbb{F}$**



The set  $\mathbb{F}$  of floats is composed of:

- ◆ **normalised** numbers:  $(-1)^s \times 2^{e-127} \times 1.b_1 \dots b_{23}$  ( $1 \leq e \leq 254$ )
- ◆ **denormalised** numbers:  $(-1)^s \times 2^{-126} \times 0.b_1 \dots b_{23}$  ( $e = 0, b \neq 0$ )
- ◆ **signed zeros**:  $+0$  and  $-0$  (if  $e = 0, b = 0$ )
- ◆ **infinities and error codes**:  $+\infty, -\infty, NaN$  (if  $e = 255$ )

# IEEE 754-1985 Arithmetics

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## Floating-Point Expressions $\mathcal{E}_f$ :

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$\mathcal{E}_f ::=$	$[a, b]$	interval $a, b \in \mathbb{F}$
	$X$	variable $X \in \mathcal{V}$
	$\ominus \mathcal{E}_f$	unary operator
	$\mathcal{E}_f \odot \mathcal{E}_f$	binary operators $\odot \in \{\oplus, \otimes, \dots\}$

## Floating-Point Arithmetics:

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Differences between floating-point and  $\mathbb{Q}, \mathbb{R}$  arithmetics:

- ◆ **rounding** to a representable float occurs, several types of rounding: **towards**  $+\infty$ ,  $-\infty$ ,  $0$  or **to nearest**.
- ◆ **overflow**: large numbers, division by  $0$  generate  $+\infty$  or  $-\infty$ ,
- ◆ **underflow**: small numbers round to  $+0$  or  $-0$ ,
- ◆ **invalid operations**:  $0/0$ ,  $(+\infty) + (-\infty)$ , etc. generate *NaN*.

# Chosen Floating-Point Semantics

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Restrict to programs that use  $\mathbb{F}$  as “approximated reals”:

- ◆ Rounding and underflow are **benign**, but we must consider all rounding directions!
- ◆ **Overflow** and **invalid operations** result in a **run-time error  $\Omega$** .
- ◆ Error-free computations live in  $\mathbb{F}' \simeq \mathbb{F} \cap \mathbb{R}$ , assimilated to a finite subset of  $\mathbb{R}$ .

Partial Definition of  $\llbracket e \rrbracket_f$ : (with rounding towards  $+\infty$ )

- $\llbracket e_1 \oplus e_2 \rrbracket_f(\rho) \stackrel{\text{def}}{=} \{ R(v_1 + v_2) \mid v_1 \in \llbracket e_1 \rrbracket_f(\rho), v_2 \in \llbracket e_2 \rrbracket_f(\rho) \},$
- etc.
- $R(x) \stackrel{\text{def}}{=} \begin{cases} \Omega & \text{if } x = \Omega \text{ or } x > 2^{127}(2 - 2^{-23}) \\ \min \{y \in \mathbb{F}' \mid y \geq x\} & \text{otherwise} \end{cases}$
- etc.

# Difficulties in Adapting Relational Domains

- ◆ The interval domain is easy to adapt.  
We simply round lower bounds toward  $-\infty$  and upper bounds toward  $+\infty$ .
- ◆ Relational domains **cannot** manipulate floating-point expressions.  
Such domains require properties of  $\mathbb{Q}$ ,  $\mathbb{R}$  not true in floating-point arithmetics!

e.g.  $(X - Y \leq c) \wedge (Y - Z \leq d) \implies (X - Z \leq c + d)$  (Zone propagation)

$$(X \ominus Y \leq c) \wedge (Y \ominus Z \leq d) \not\implies (X \ominus Z \leq c \oplus d)$$
$$(10^{22} \oplus 1.000000019 \cdot 10^{38}) \oplus (10^{22} \ominus 1.000000019 \cdot 10^{38}) = 0$$

## Solution:

- $\llbracket e \rrbracket_f$  is abstracted as a **linear interval form** on  $\mathbb{Q}$ .
- Invariant semantics will be expressed **using**  $\mathbb{Q}$ ,  $+$ ,  $-$ , ... not  $\mathbb{F}'$ ,  $\oplus$ ,  $\ominus$ .  
 $\implies$  We keep the same abstract domains and operators as before.

# Floating-Point Linearisation

**Rounding Error on Linear Forms:** Its magnitude is the maximum of:

- ◆ a **relative error**  $\varepsilon$  of amplitude  $2^{-23}$ , expressed as a linear form:

$$\varepsilon([a, b] + \sum_i [a_i, b_i] \times V_i) \stackrel{\text{def}}{=} \max(|\mathbf{a}|, |\mathbf{b}|) \times [-2^{-23}, 2^{-23}] + \sum_i (\max(|\mathbf{a}_i|, |\mathbf{b}_i|) \times [-2^{-23}, 2^{-23}]) \times V_i$$

(normalised numbers)

- ◆ an **absolute error**  $\omega \stackrel{\text{def}}{=} [-2^{-159}, 2^{-159}]$  (denormalised numbers).

⇒ We sum these two causes of rounding.

## Linearisation $(\mathbf{e})_f$ :

- $(e_1 \oplus e_2)_f(\mathcal{X}^\#) \stackrel{\text{def}}{=} (e_1)_f(\mathcal{X}^\#) \cdot \varepsilon((\mathbf{e}_1)_f(\mathcal{X}^\#)) + (e_2)_f(\mathcal{X}^\#) \cdot \varepsilon((\mathbf{e}_2)_f(\mathcal{X}^\#)) + \omega$
- $([a, b] \otimes e_2)_f(\mathcal{X}^\#) \stackrel{\text{def}}{=} ([a, b] \cdot (e_2)_f(\mathcal{X}^\#)) \cdot \varepsilon((\mathbf{e}_2)_f(\mathcal{X}^\#)) + \omega$
- etc.



# Application of Floating-Point Linearisation

Abstract Assignment:  $V \leftarrow e$

We first evaluate  $e$  in the floating-point interval domain.

- ◆ If there is no run-time error  $\Omega$  detected, then

$$\forall \rho \in \gamma(\mathcal{X}^\#), \llbracket e \rrbracket_f(\rho) \subseteq \llbracket (e)_f(\mathcal{X}^\#) \rrbracket(\rho)$$

and we can **feed**  $\{V \leftarrow (e)_f(\mathcal{X}^\#)\}^\#$  to an abstract domain in  $\mathbb{Q}$ .

- ◆ If  $\Omega$  is detected, we can still fall back to the interval domain.

Example:  $Z \leftarrow X \ominus (0.25 \otimes X)$  is linearised as  
 $Z \leftarrow ([0.749 \dots, 0.750 \dots] \times X) + (2.35 \dots 10^{-38} \times [-1, 1])$

- Allows **simplification** even in the interval domain.

e.g., if  $X \in [-1, 1]$ , we get  $|Z| \leq 0.750 \dots$  instead of  $|Z| \leq 1.25 \dots$

- Allows **using a relational abstract domain**. (zone, etc.)

# Floating-Point Zones

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We are now **sound**, but not very efficient: abstract operations are expressed in  $\mathbb{Q}$ .  
 $\implies$  This requires costly arbitrary precision exact rational packages!

**Solution:** Perform all **abstract** computations in  $\mathbb{F}$ :

- ◆ **linearisation:** use **sound** floating-point interval arithmetics,
- ◆ **zone domain:** upper bounds computation are **rounded towards**  $+\infty$ .

We lose some precision.

We gain much speed.

**Note:** Sound algorithms in  $\mathbb{F}$  are much harder to provide for polyhedra!

# Floating-Point Abstractions

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To sum up, the following sound approximations are made:

- ① **linearisation**: rounding errors are treated as non-deterministic,
- ② **linearisation**: non-linear computations are “intervalised”,
- ③ **abstract domain**: limits the expressiveness,
- ④ **abstract operators**,
- ⑤ **implementation in  $\mathbb{F}$** : extra rounding errors.

Due to ① and ⑤, our best abstraction results no longer hold!

Despite unpredictable ⑤, abstract computations are stable in many cases:

- when concrete computations are naturally **contracting**, e.g.,  $X \leftarrow 0.5X + [-1, 1]$ ,
- when concrete computations have explicit **limiters**,
- specific **widenings** and **narrowings** can help.

# Real-Life Application Within Astrée

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# Presentation of Astrée

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## Astrée:

- ◆ Static analyser developed at the ENS.
- ◆ Checks for run-time errors in reactive C code. (integer and float overflows, etc.)
- ◆ Aimed at **proving** automatically the correctness: **0** alarm goal.

## Analysed Code Features:

A real-life example:

- primary flight control software for the Airbus A340 fly-by-wire system,
- **70,000** lines of C,
- **10,000** global variables, 5,000 of which are 32-bit **floating-point**,
- one **very large loop** executed  $3.6 \cdot 10^6$  times.

# Octagon Packing

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**Problem:** There are too many variables (10,000) even for the octagon domain!

**Solution:** Do not relate all variables together.

- ◆ Define static **packs** of a few variables only.
- ◆ One octagon per pack, **no inter-pack relationality**.

**Automatic Packing:** Using simple **syntactic criteria**.

# lines	# variables	# packs	pack size
370	100	20	3.6
9 500	1 400	200	3.1
70 000	14 000	2 470	3.5
226 000	47 500	7 429	3.5
400 000	82 000	12 964	3.3

⇒ **Linear** increase in cost: the method is **scalable**.

# Analysis Results

Astrée includes:

- floating-point octagons using floating-point linearisation,
- symbolic propagation in the interval domain,
- **other domains** working in  $\mathbb{R}$ , supplied with linearised floating-point expressions.

Analysis Comparison: AMD Opteron 248, mono-processor

# lines	without symbolic			without octagon			with everything		
	time	memory	alarms	time	memory	alarms	time	memory	alarms
370	1.8s	16 MB	0	1.7s	14 MB	0	3.1s	16 MB	0
9 500	90s	81 MB	8	75s	75 MB	8	160s	80 MB	8
70 000	2h 40mn	559 MB	391	3h 17mn	537 MB	58	1h 16mn	582 MB	0
226 000	11h 16mn	1.3 GB	141	7h 8mn	1.0 GB	165	8h 5mn	1.3 GB	1
<b>400 000</b>	<b>22h 8mn</b>	<b>2.2 GB</b>	<b>282</b>	<b>20h 31mn</b>	<b>1.7 GB</b>	<b>804</b>	<b>13h 52mn</b>	<b>2.2 GB</b>	<b>0</b>

⇒ **Our work is instrumental in proving the code correctness!**

# Conclusion

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# Work Summary

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## To sum up we proposed:

- ◆ **New relational abstract domains between intervals and polyhedra.**

Provides new **theoretical results**. (properties of closure)

Design and proofs of soundness, exactness, best precision of abstract operators.

- ◆ **Generic techniques for the local enhancement of domains:**

Linearisation, symbolic constant propagation.

Avoid the need for more expressive domains.

- ◆ **Adaptation to floating-point arithmetics.**

**First** relational domains to relate floating-point variable values.

- ◆ **Integration within the *Astrée* analyser.**

Motivated new researches. (abstract operators, packing, etc.)

Provided **experimental** results on **real-life** examples.

# Abstract Domains Comparison

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Domain	Invariants	Cost	Floating-Point
Intervals	$X \in [a, b]$	$\mathcal{O}(n)$	yes
<b>Zones</b>	$X - Y \leq c$	$\mathcal{O}(n^2, n^3)$	<b>yes</b>
<b>Octagons</b>	$\pm X \pm Y \leq c$	$\mathcal{O}(n^2, n^3)$	<b>yes</b>
<b>Zone congruence</b>	$X \equiv Y + a [b]$	$\mathcal{O}(n^2, n^3)$	no
<b>Symbolic</b>	$X = \mathcal{E}$	$\mathcal{O}(n)$	yes
Polyhedra	$\sum_i \alpha_i X_i \leq \beta$	$\mathcal{O}(e^n)$	<b>no</b>

The ability to easily implement floating-point versions is crucial.

# Future Work

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- ◆ Extend the **spectrum choice for cost vs. precision trade-offs**:
  - Define new abstract domains.  
(e.g., between octagons and polyhedra; Octahedra, TVPI)
  - Define alternate abstract operators. (fine-grain control, widenings)
  - Local refinement techniques, non-homogeneous precision (extend packing)
  - Theoretical results on linearisation and symbolic propagation techniques.  
(precision guarantees)
- ◆ Consider new numerical properties, **adapted to**:
  - Complex numerical algorithms. (finite elements methods)
  - Non-numerical properties parametrised by a numerical domain.  
(e.g., non-uniform pointer analysis)
  - Parametric predicate abstractions.  
(complex functional properties, e.g., sorting algorithms)

**Thank you for your attention!**

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# Appendices

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# Octagon Analysis Example (1)

## Absolute Value Computation:

```
X ← [-100, 100]
① Y ← X
② if Y ≤ 0 { ③ Y ← -Y ④ } else { ⑤ }
⑥ if Y ≤ 69 { ⑦ ... }
```

The octagon domain can prove that, at ⑦,  $-69 \leq X \leq 69$ .

```
①  $-100 \leq X \leq 100$ 
②  $-100 \leq X \leq 100 \wedge -100 \leq Y \leq 100 \wedge X - Y = 0 \wedge -200 \leq X + Y \leq 200$ 
③  $-100 \leq X \leq 0 \wedge -100 \leq Y \leq 0 \wedge X - Y = 0 \wedge -200 \leq X + Y \leq 0$ 
④  $-100 \leq X \leq 0 \wedge 0 \leq Y \leq 100 \wedge -200 \leq X - Y \leq 0 \wedge X + Y = 0$ 
⑤  $0 \leq X \leq 100 \wedge 0 \leq Y \leq 100 \wedge X - Y = 0 \wedge 0 \leq X + Y \leq 200$ 
⑥  $-100 \leq X \leq 100 \wedge 0 \leq Y \leq 100 \wedge -200 \leq X - Y \leq 0 \wedge 0 \leq X + Y \leq 200$ 
⑦  $-69 \leq X \leq 69 \wedge 0 \leq Y \leq 69 \wedge -138 \leq X - Y \leq 0 \wedge 0 \leq X + Y \leq 138$ 
```

# Octagon Analysis Example (2)

## Rate Limiter:

```
Y ← 0
while ① random() {
  X ← [-128, 128]
  D ← [0, 16]
  S ← Y
  ② R ← X - S
  Y ← X
  if R ≤ -D { ③ Y ← S - D ④ } else
  if D ≤ R { ⑤ Y ← S + D ⑥ }
  ⑦ }
```

The octagon domain can prove that  $|Y| \leq M$  is **stable** at ① for any  $M \geq 144$ .

In fact, we have  $Y \in [-128, 128]$ ...

**Note:** The interval domain **cannot** prove any bound to be stable.

# Interaction Between Closure and Widening

```

X ← 0
Y ← [-1, 1]
while random() {
  if X = Y {
    if random() { Y ← X + [-1, 1] }
    else      { X ← Y + [-1, 1] }
  }
}
    
```

Non-Terminating Analysis: Using  $\mathbf{m}_{i+1} \stackrel{\text{def}}{=} (\mathbf{m}_i^*) \nabla \mathbf{n}_i$

