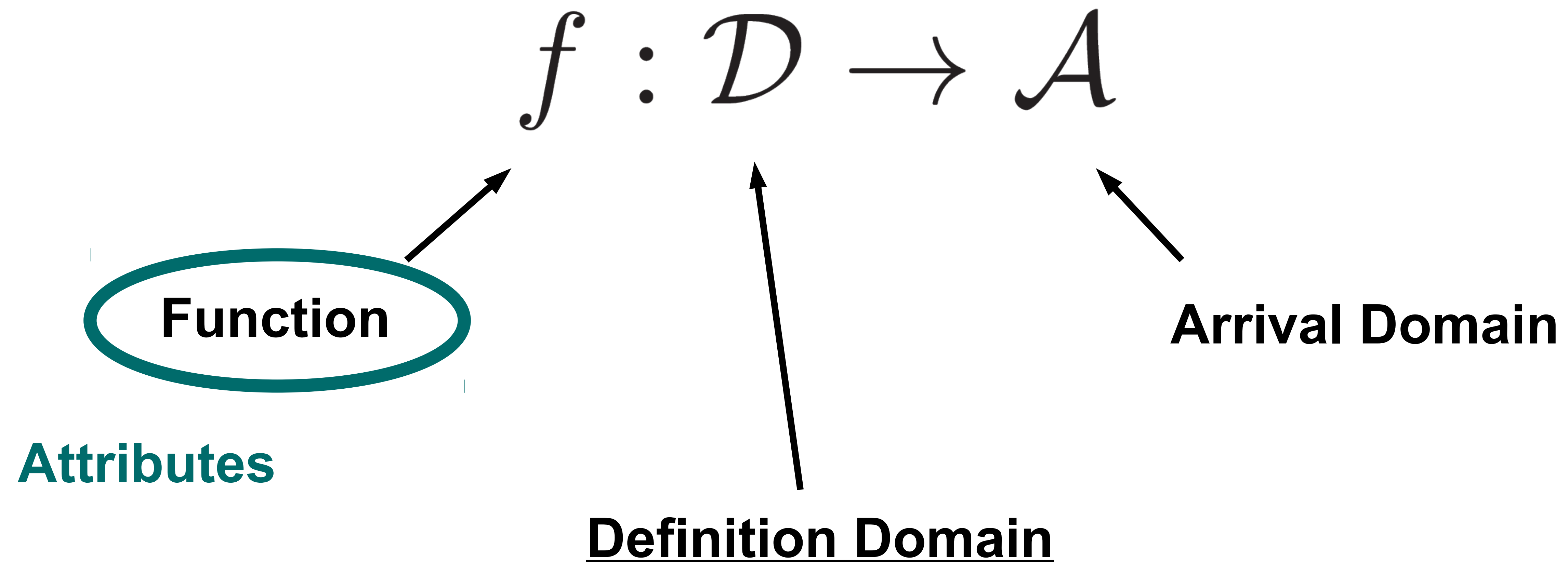


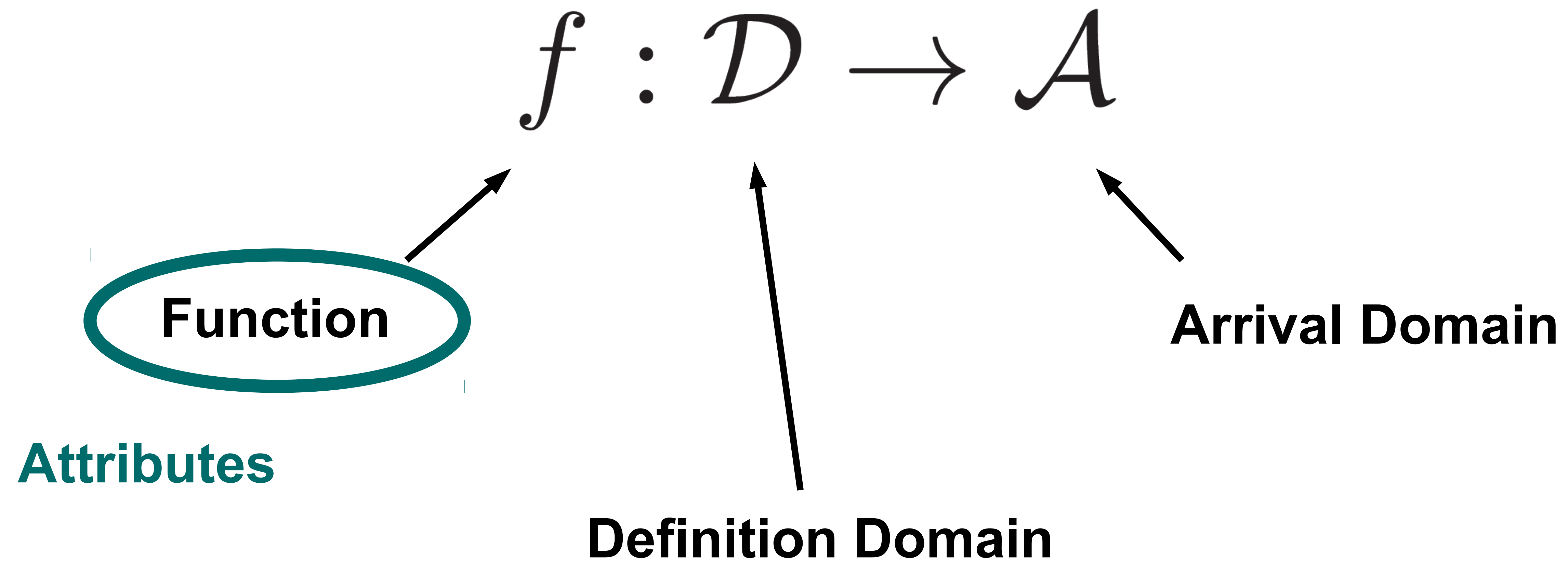
Scalar Field Visualization

Master M2S

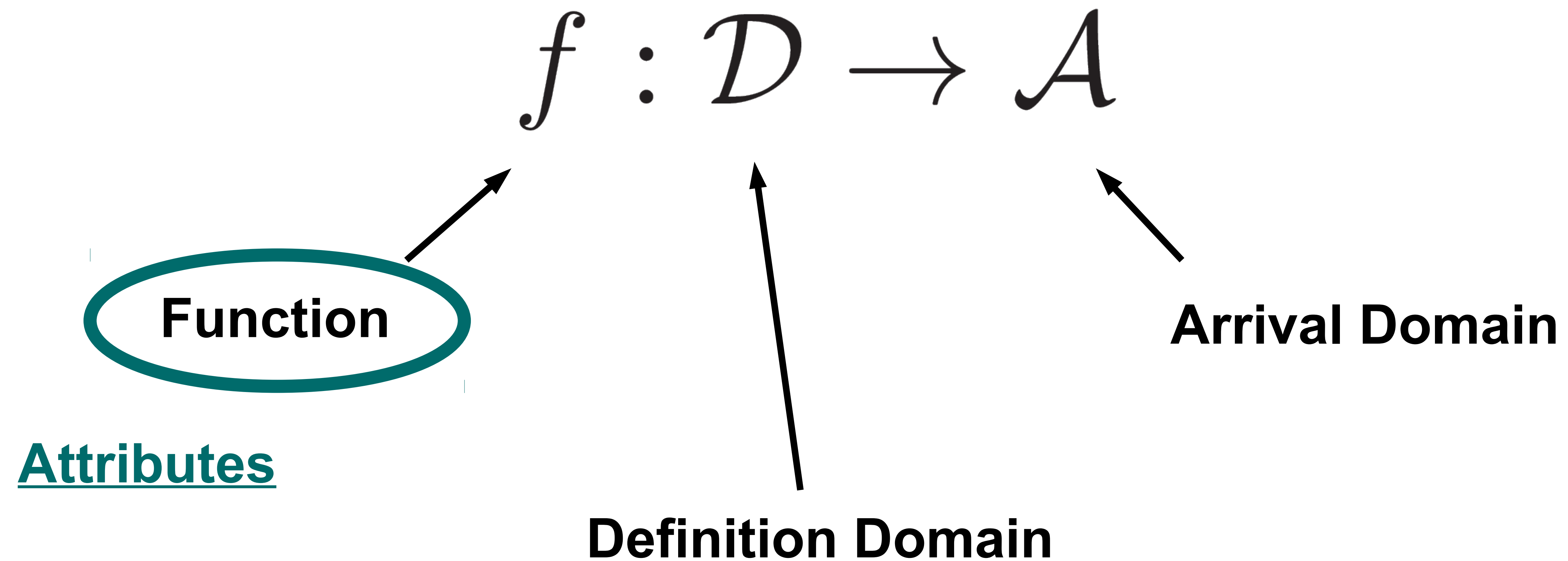
Previously



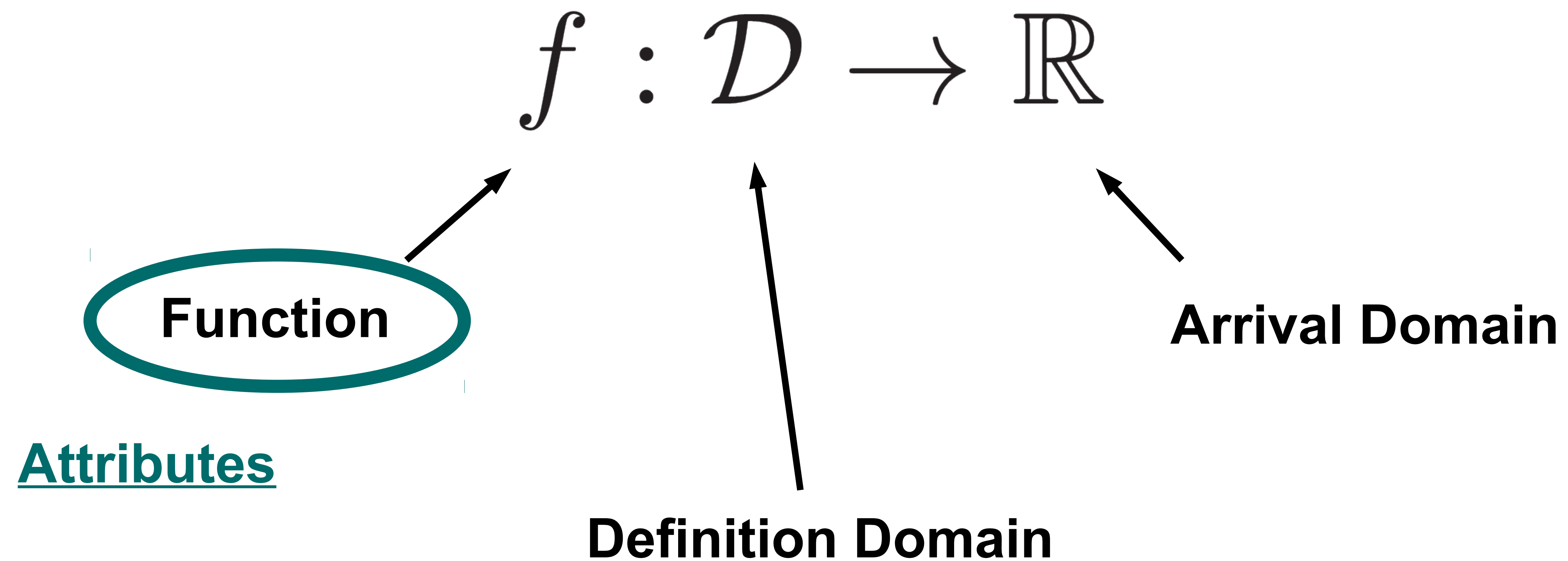
Previously



Previously



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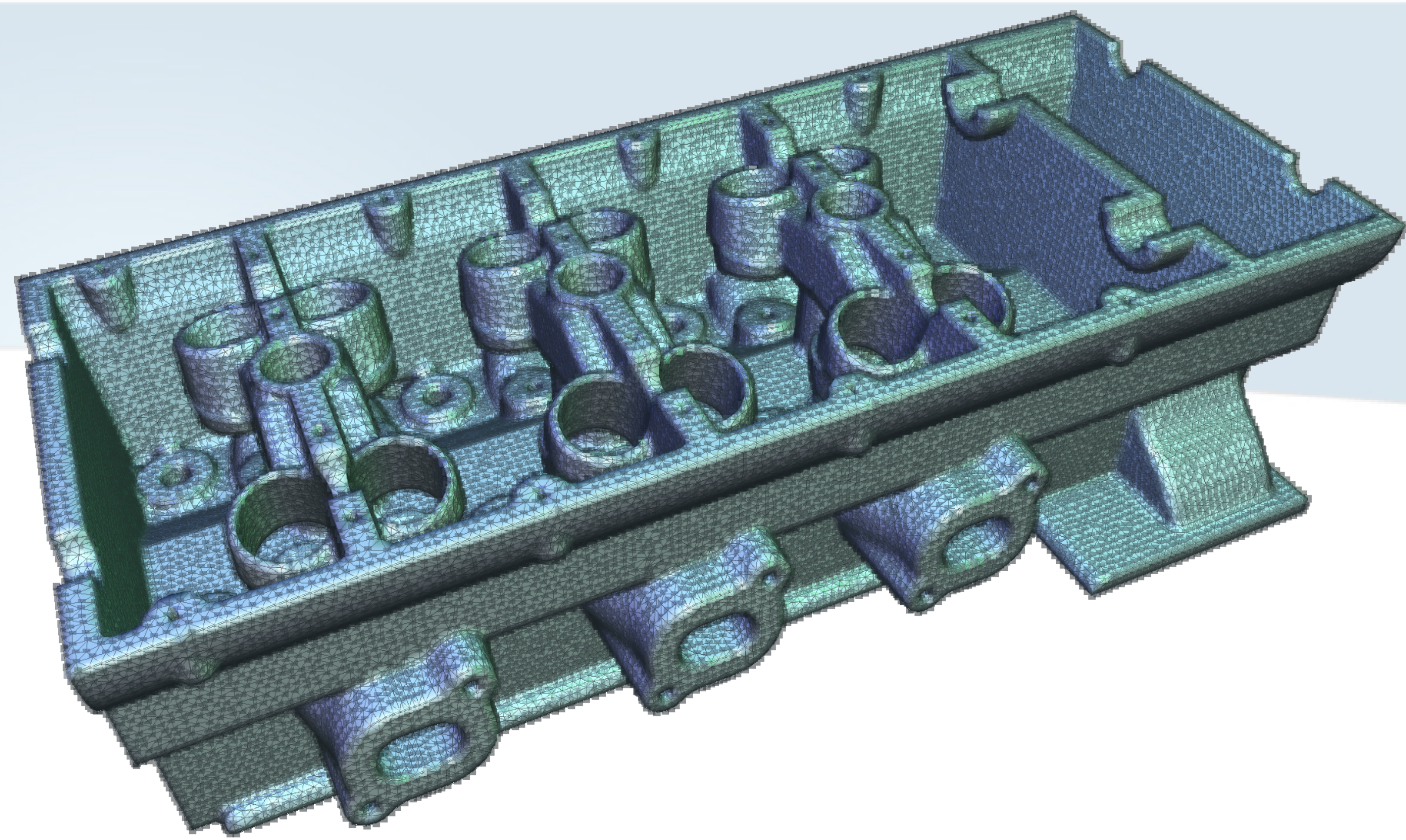
In practice

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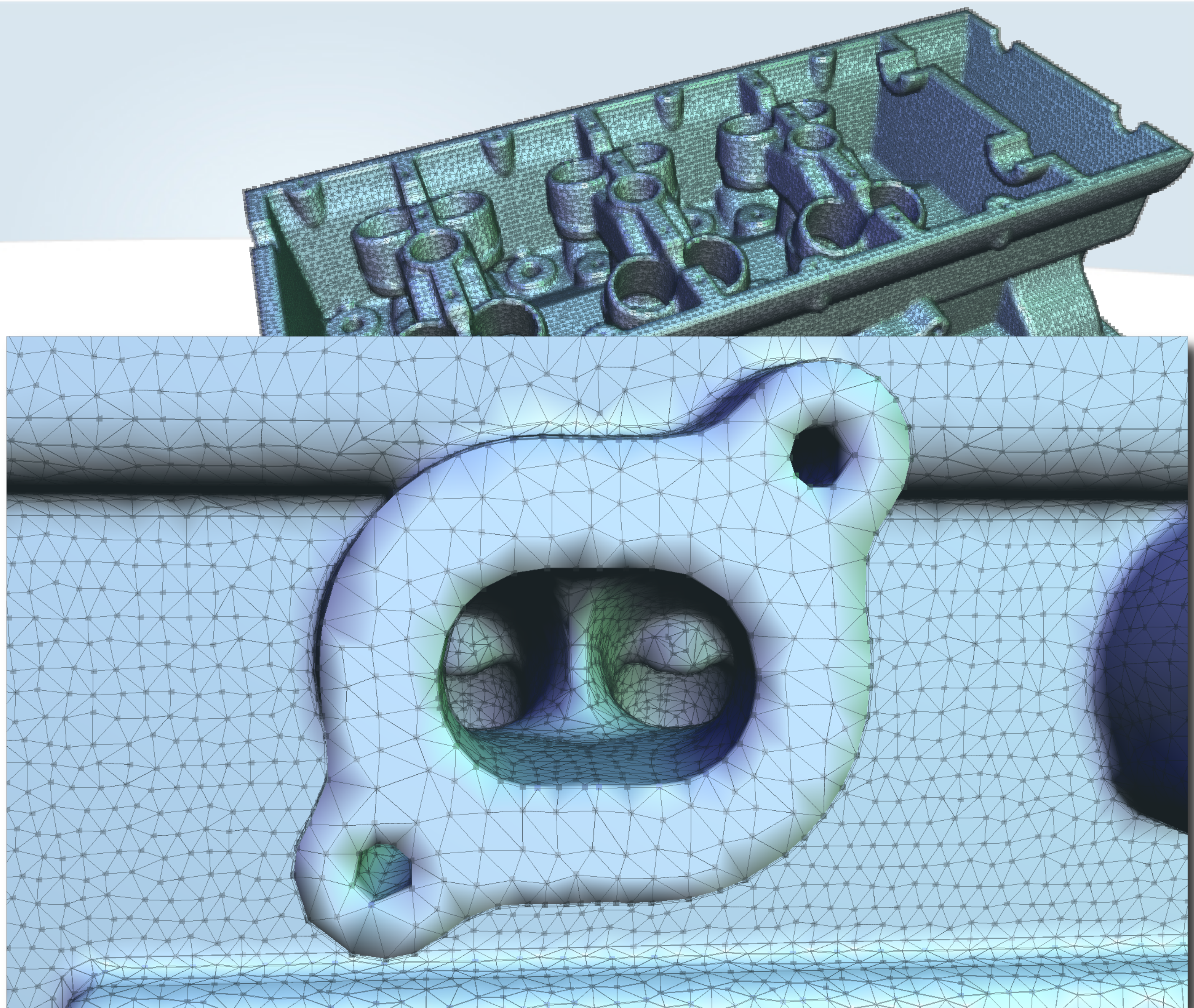
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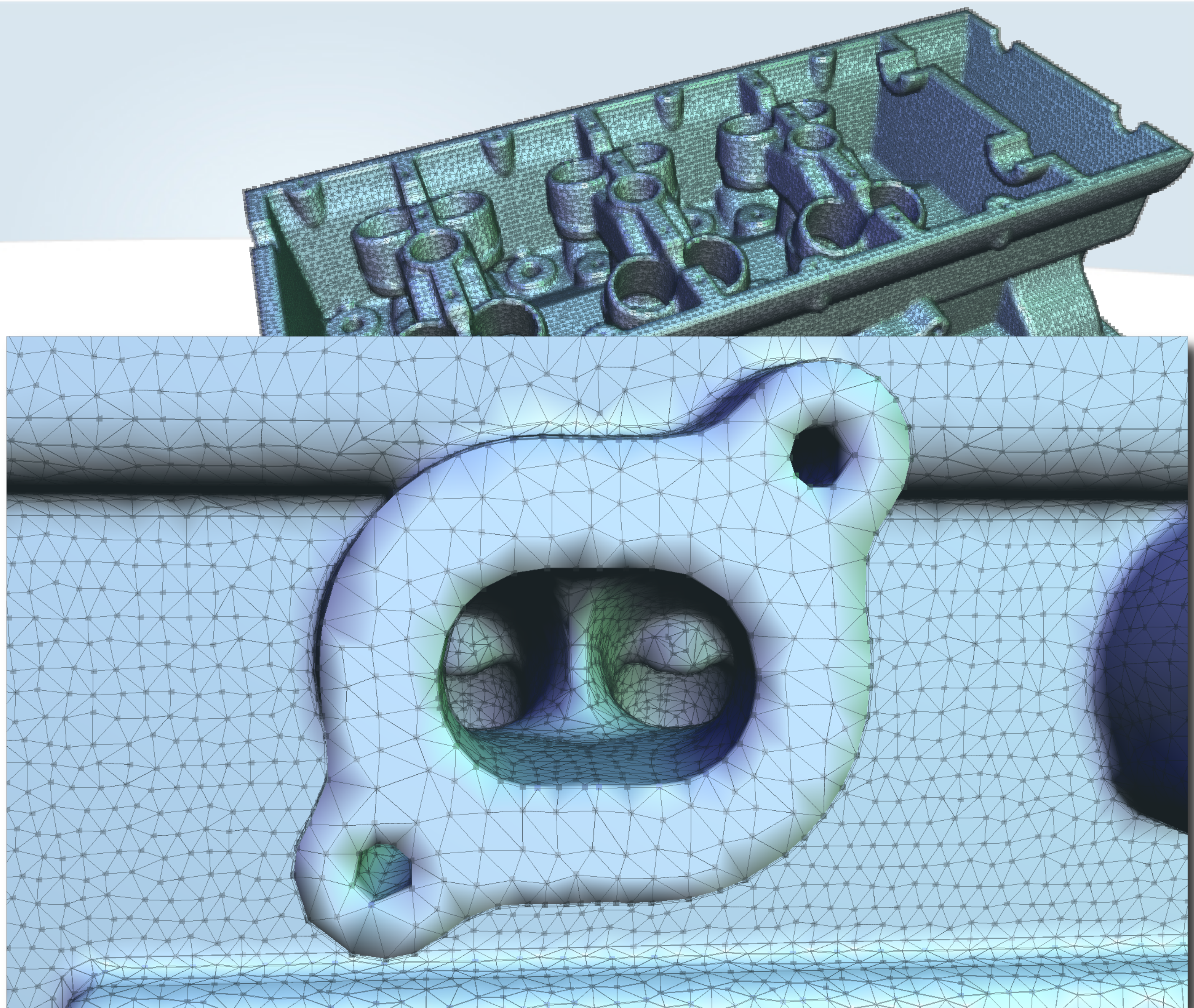
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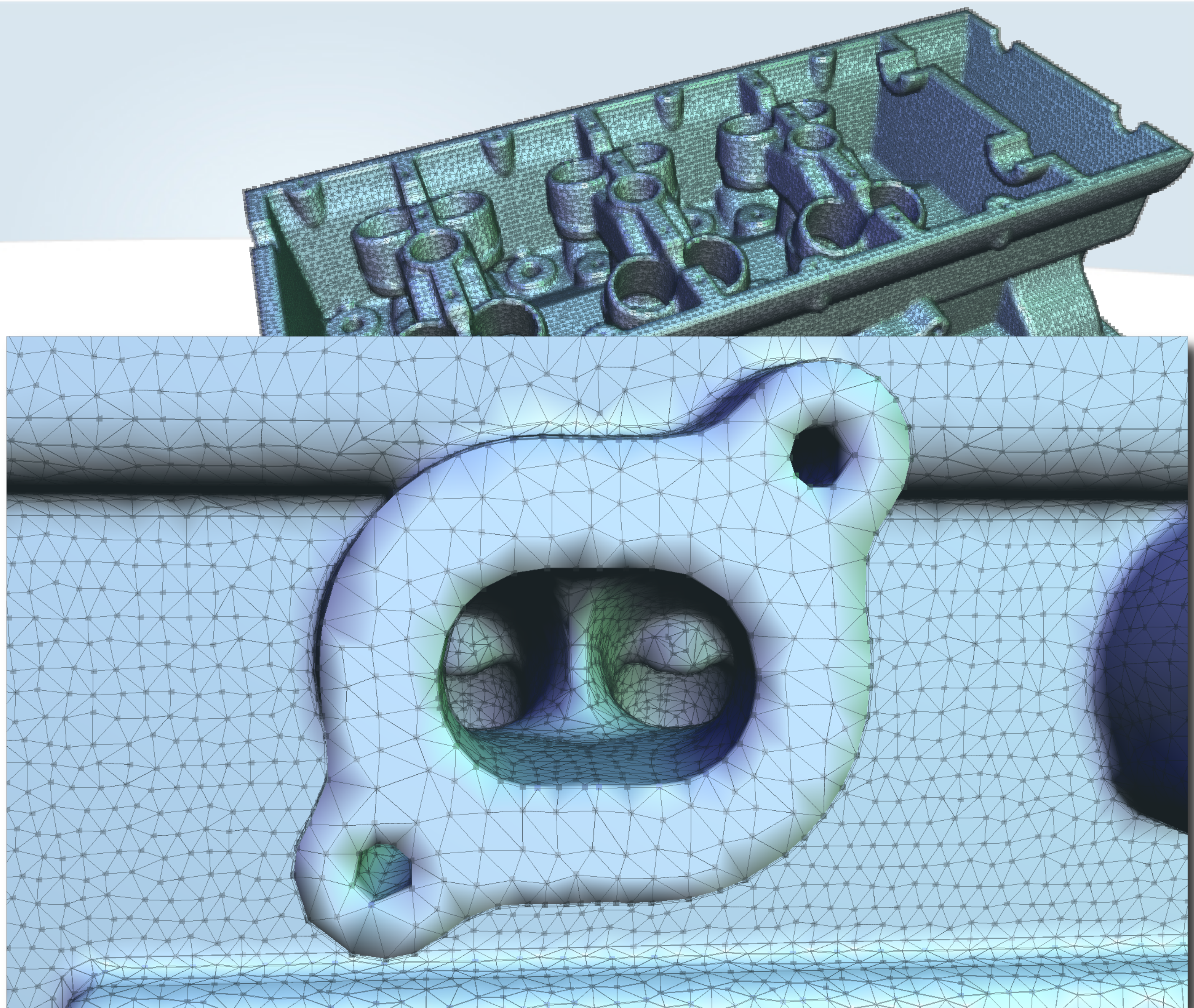
In practice

- Given a domain \mathcal{D}
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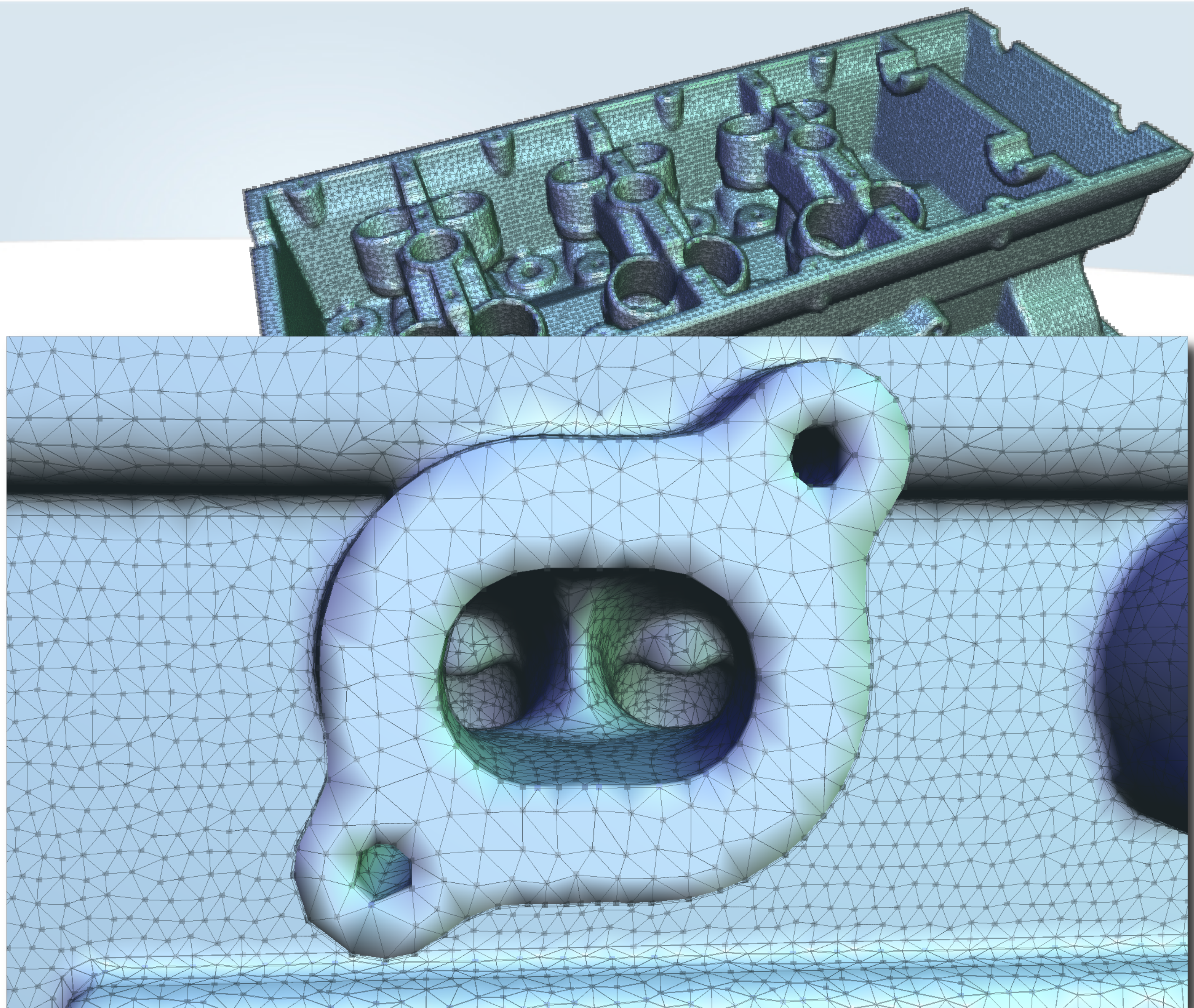
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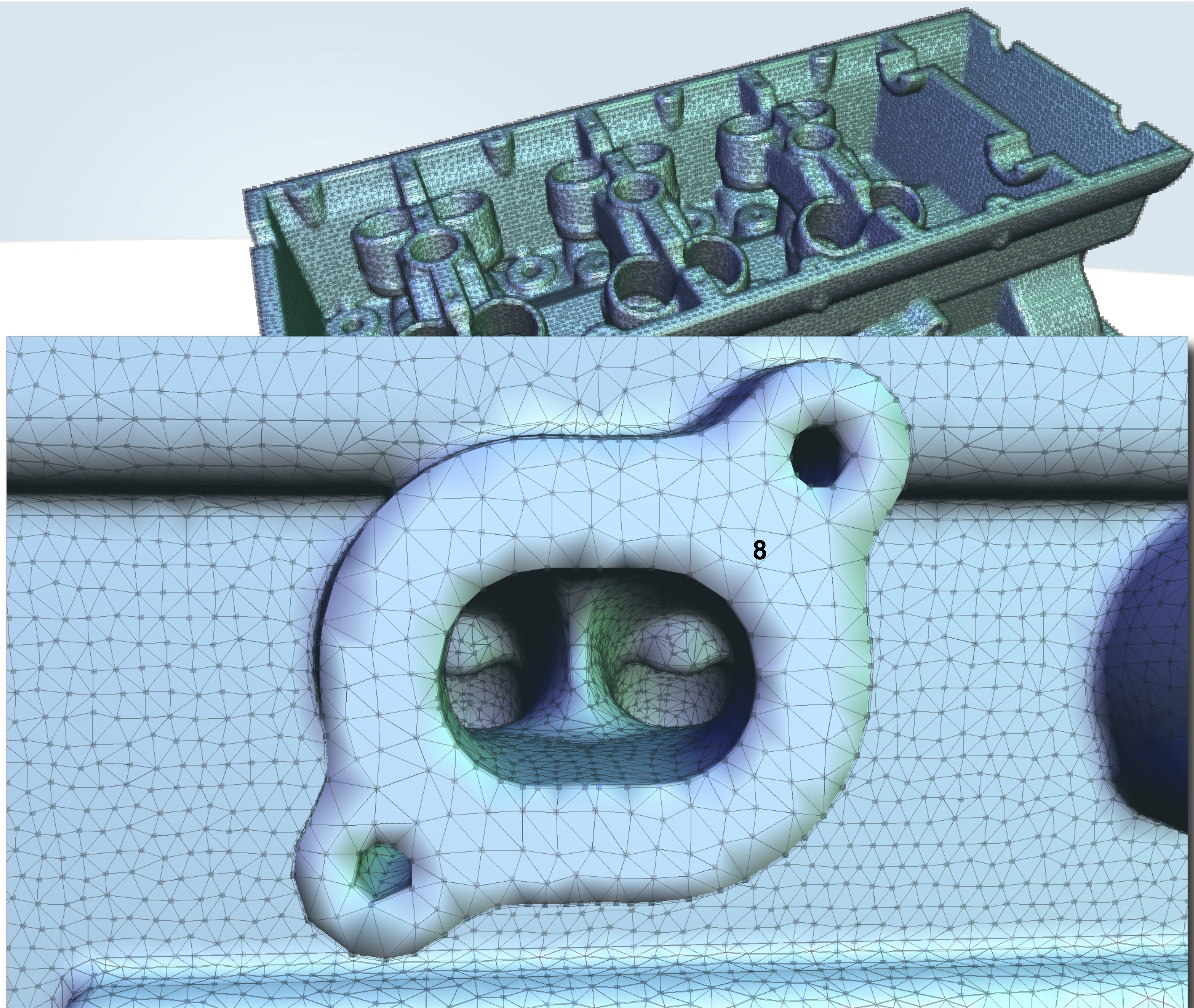
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- Given a domain \mathcal{D}
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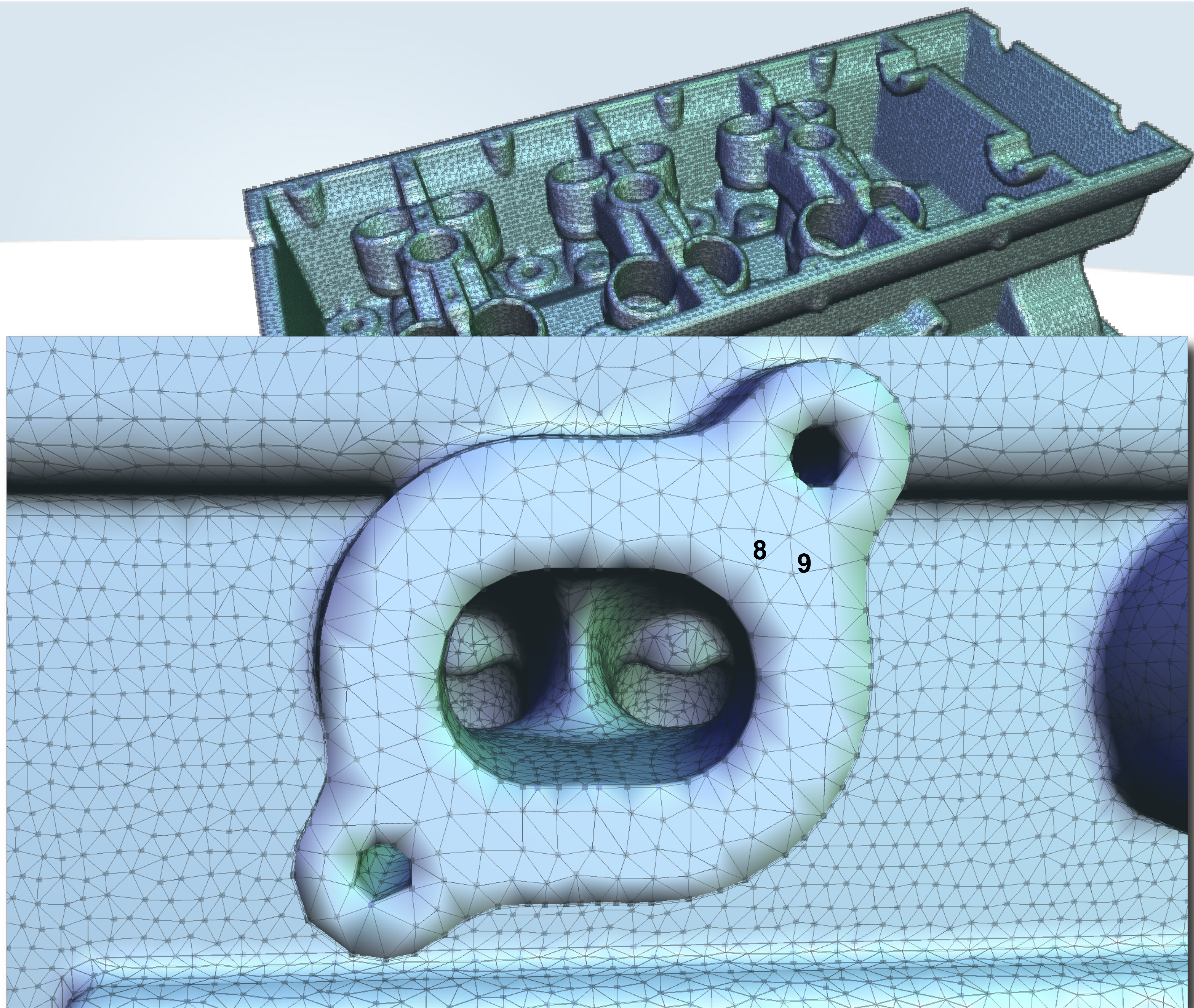
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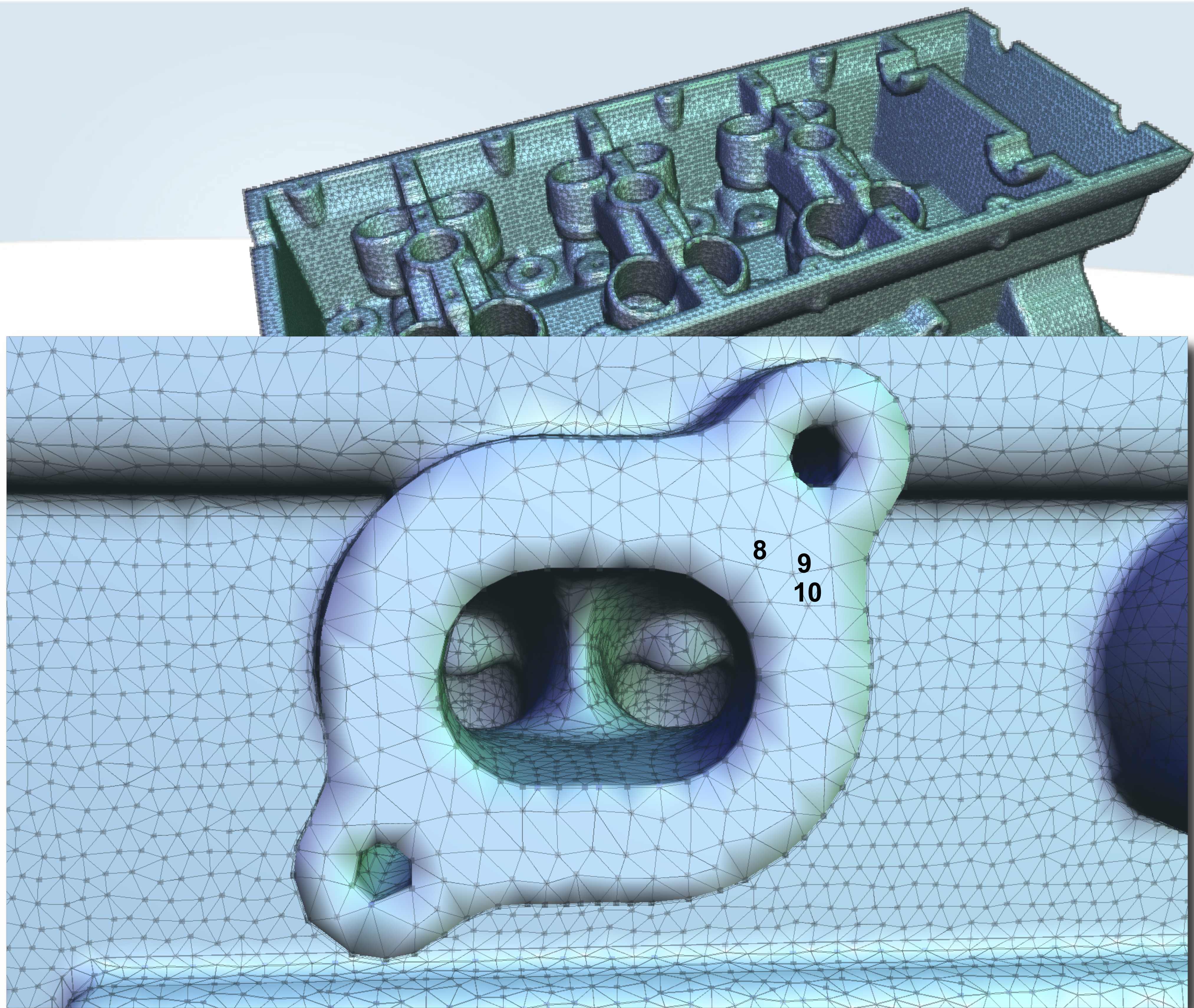
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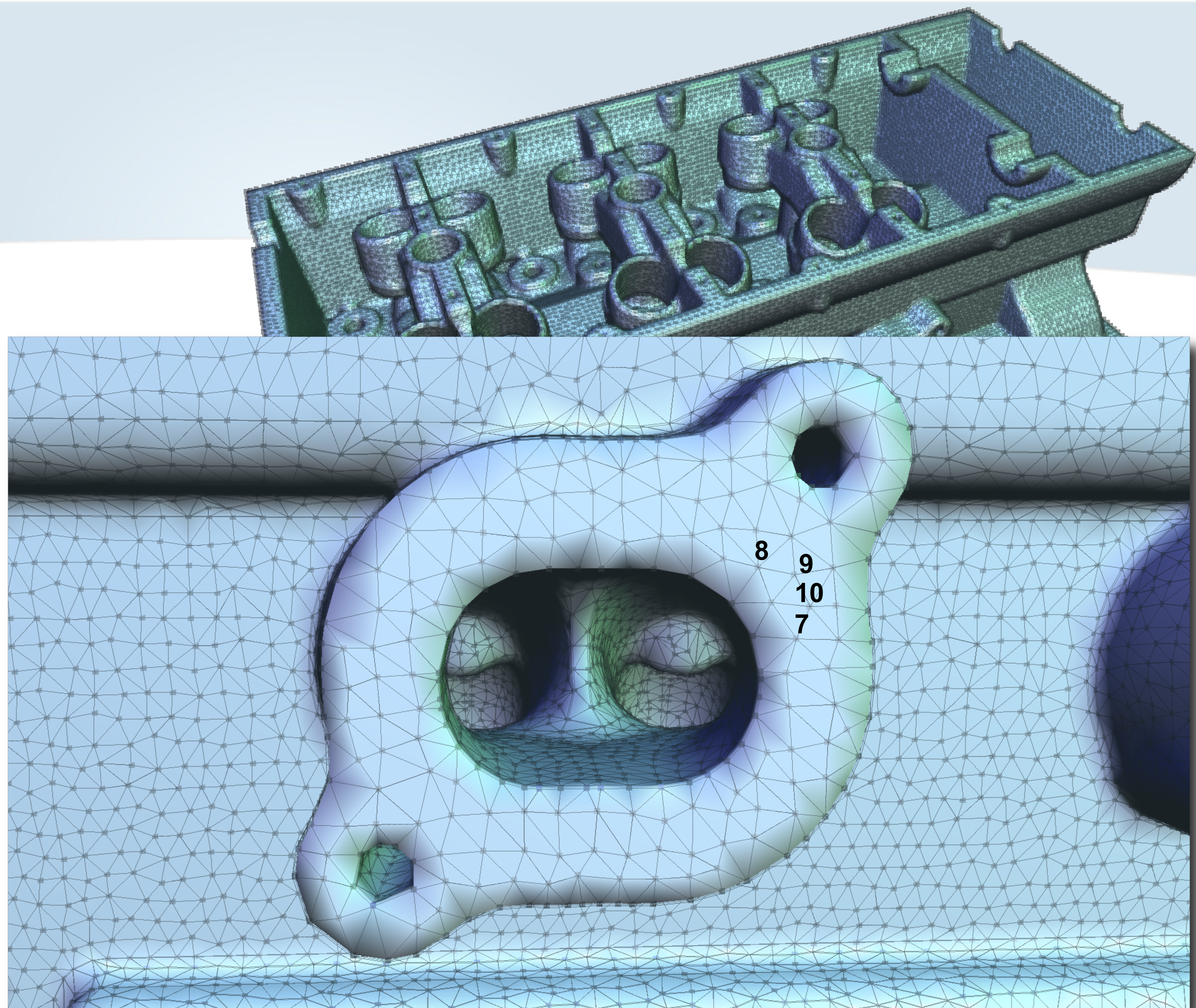
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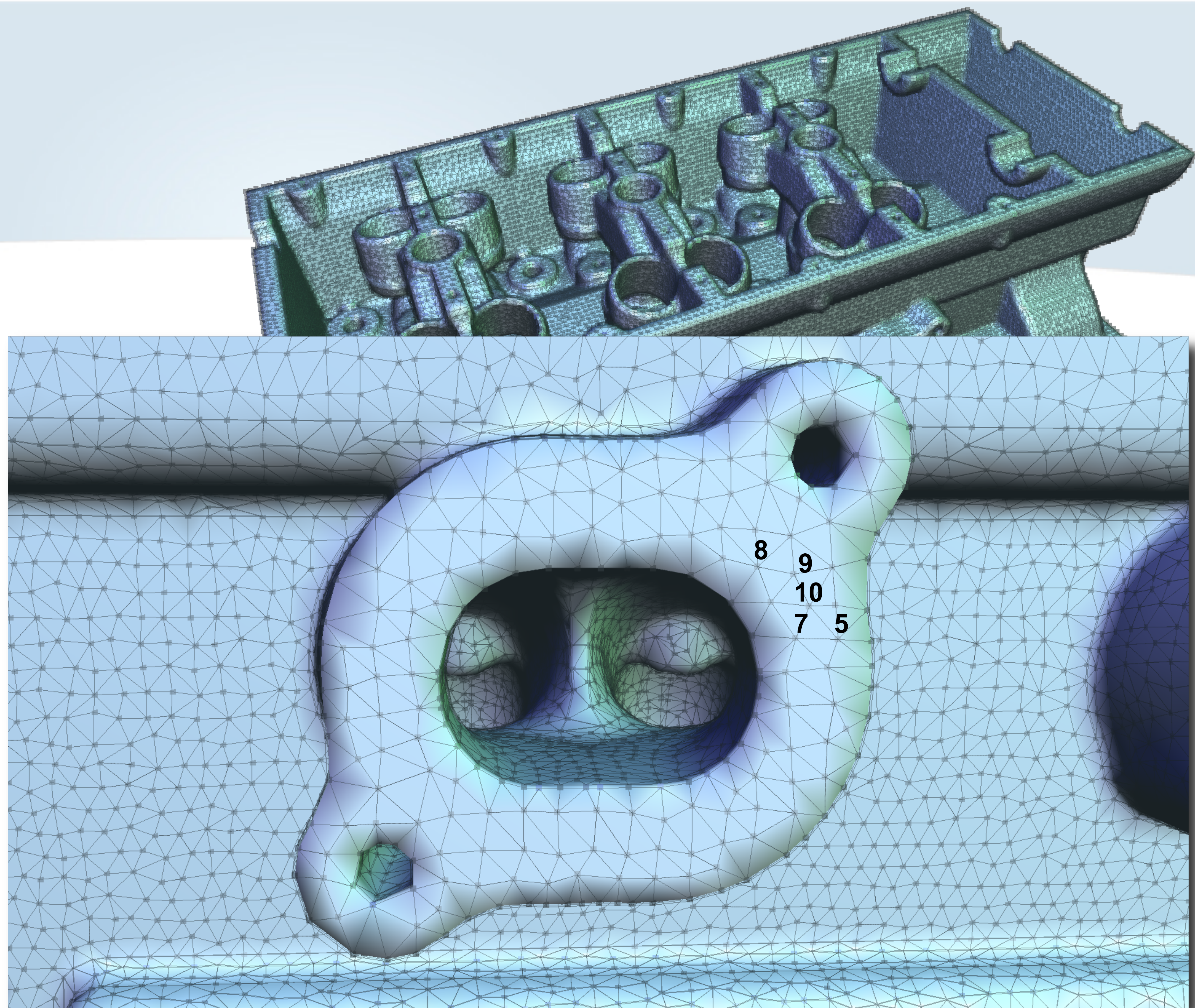
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Basic idea

- Intuitive technique
 - Exploit additional dimensions for the embedding

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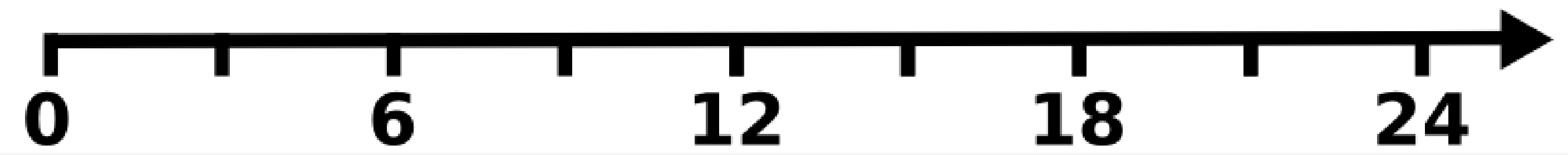
$$f : [0, 24] \rightarrow \mathbb{R}$$

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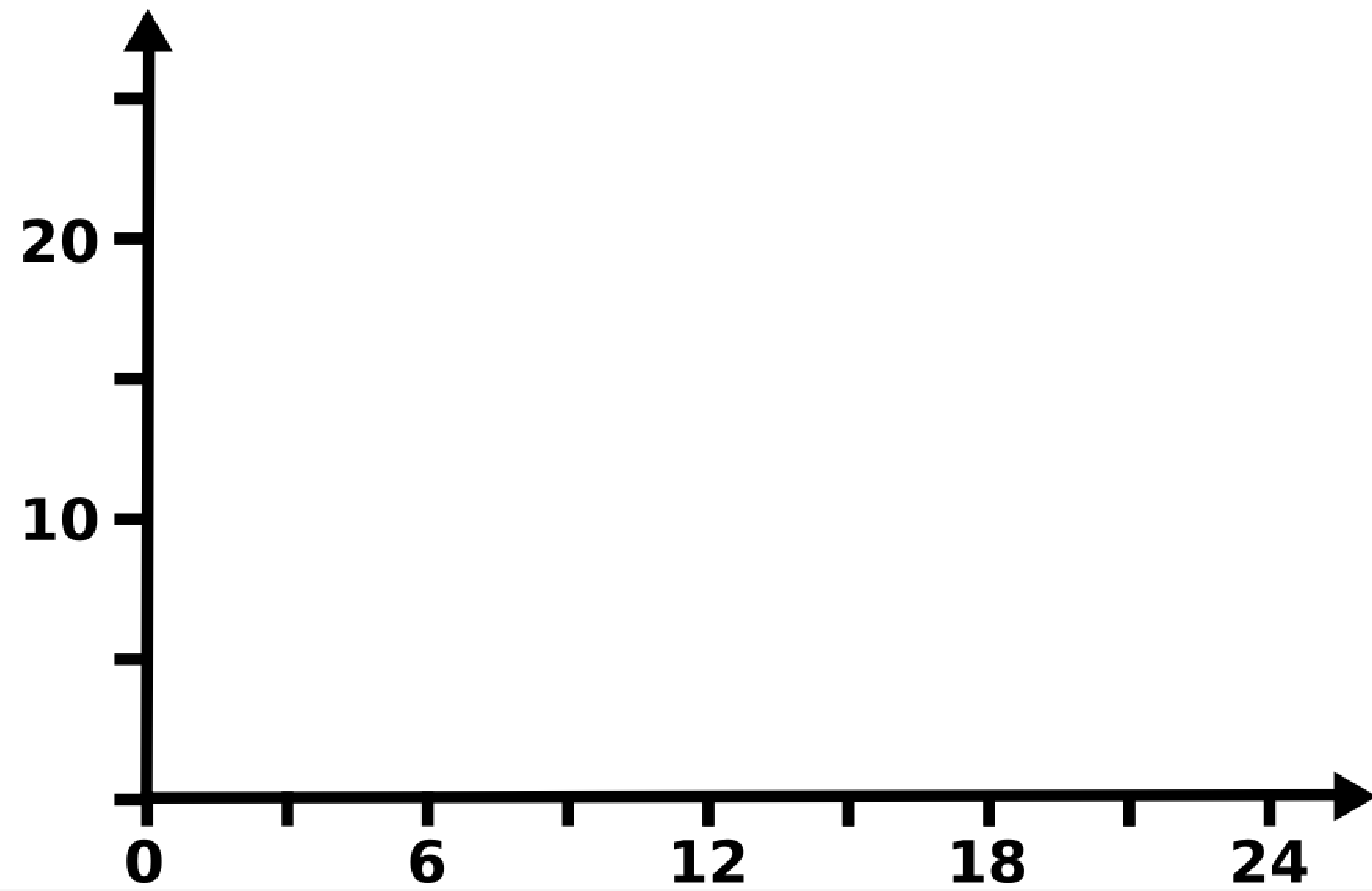
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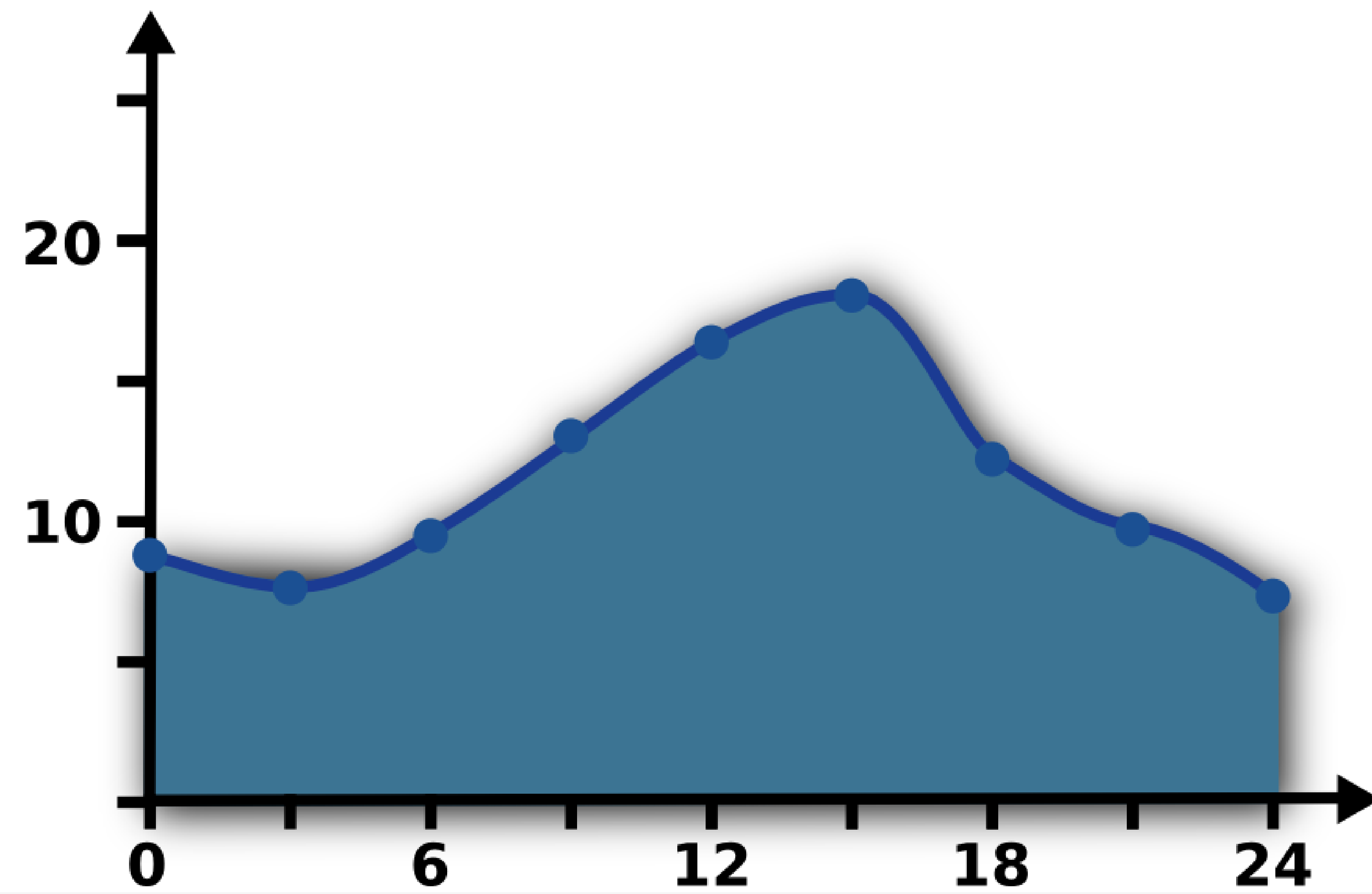
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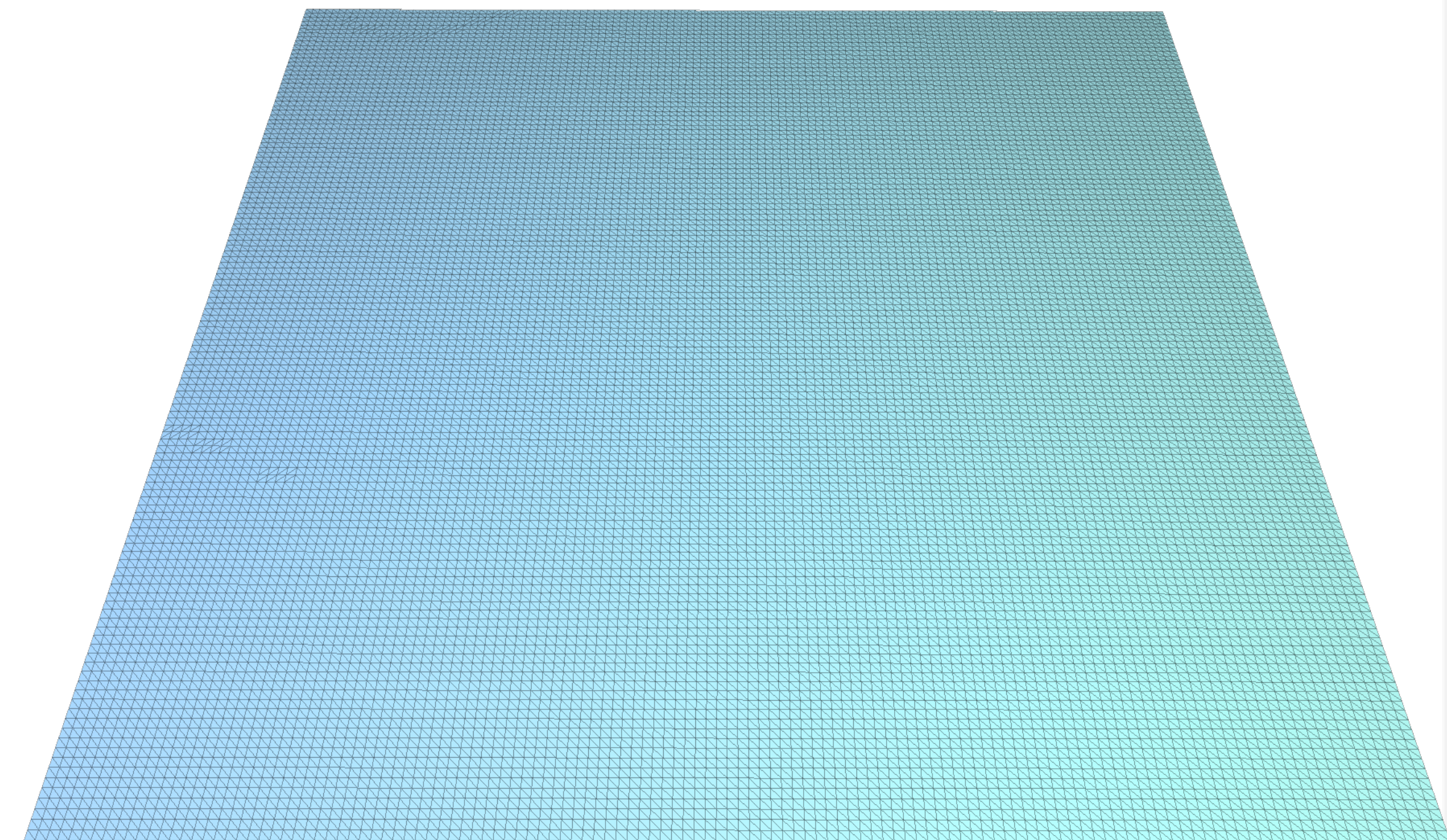
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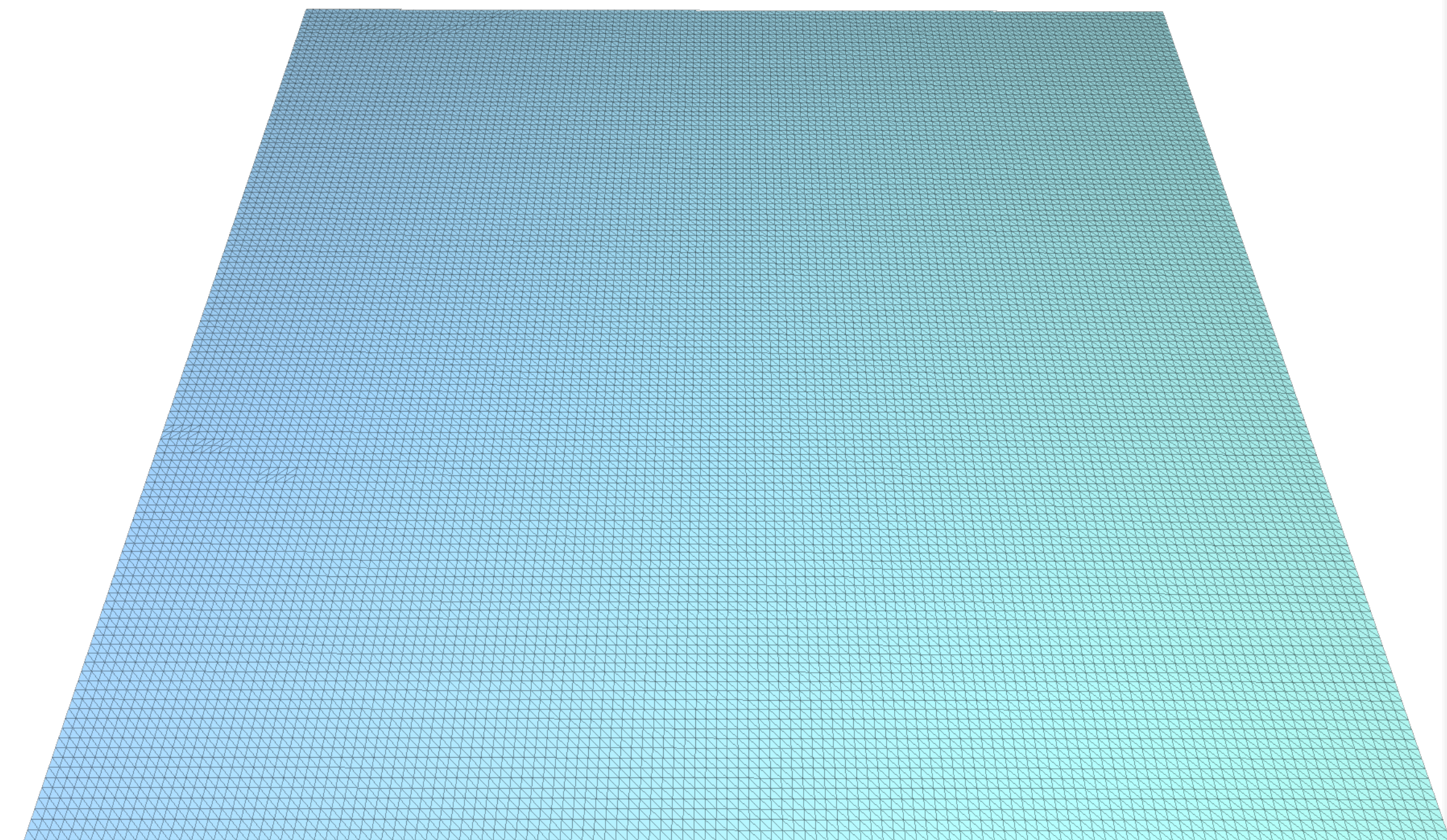
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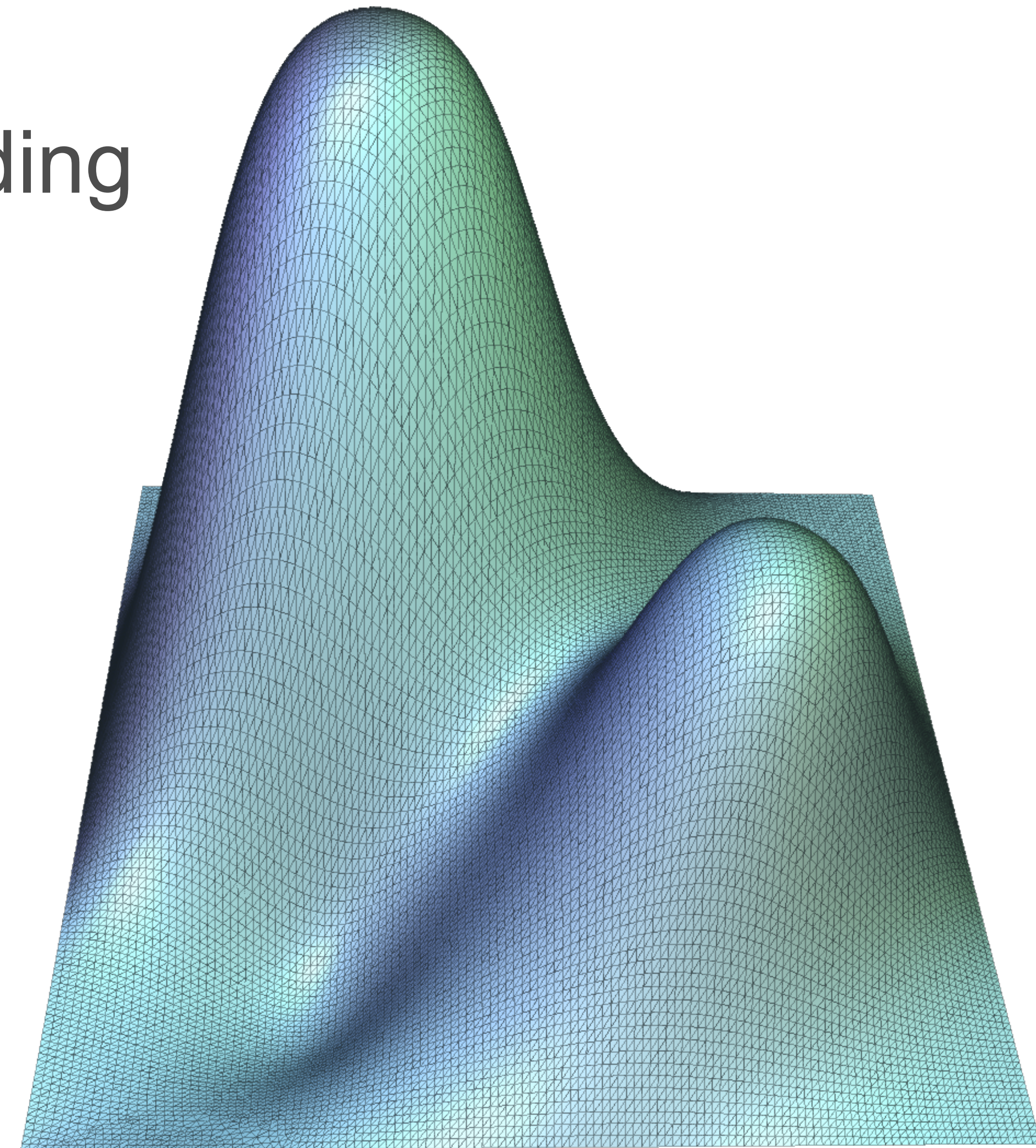
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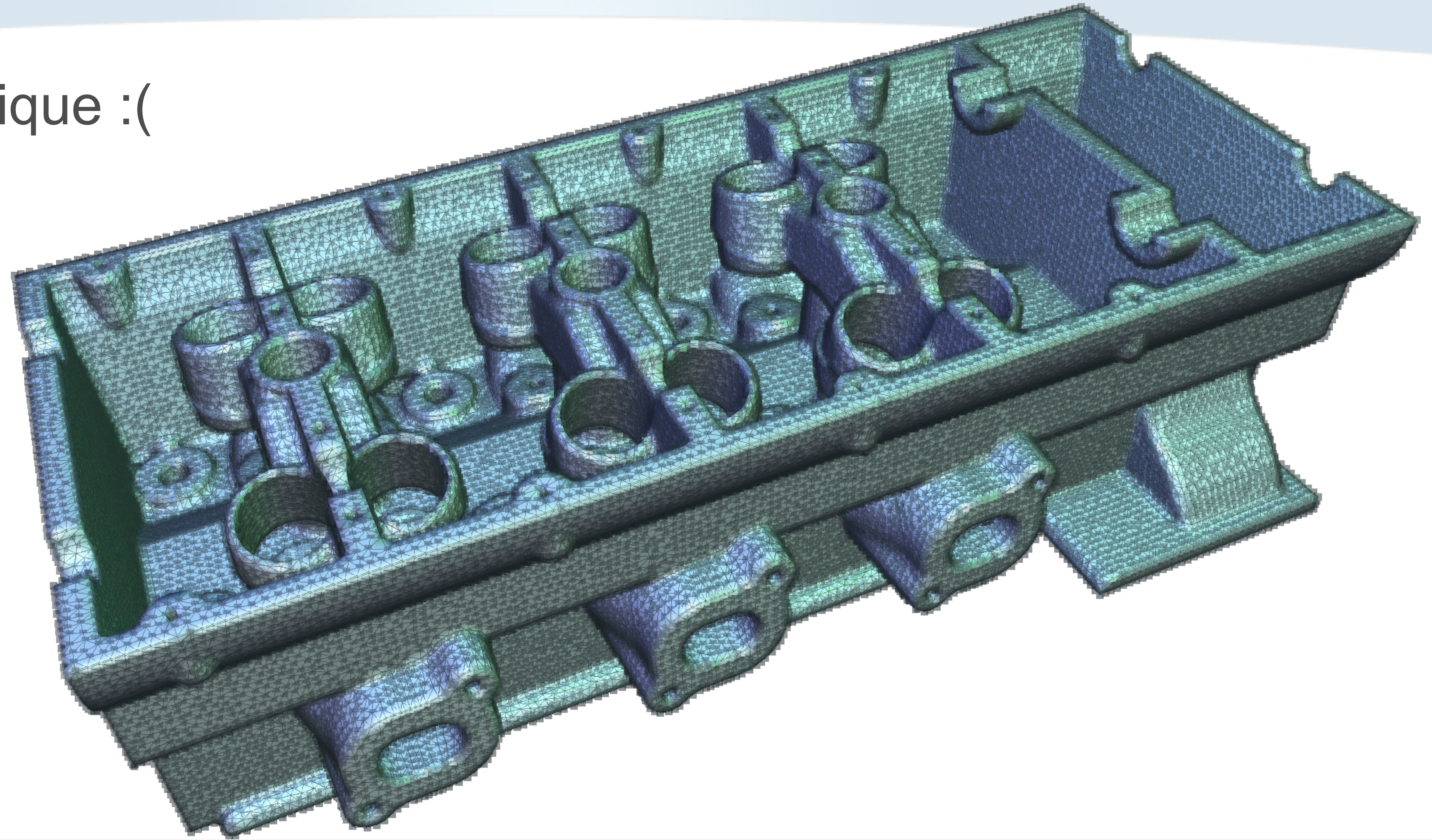
$$y = y$$

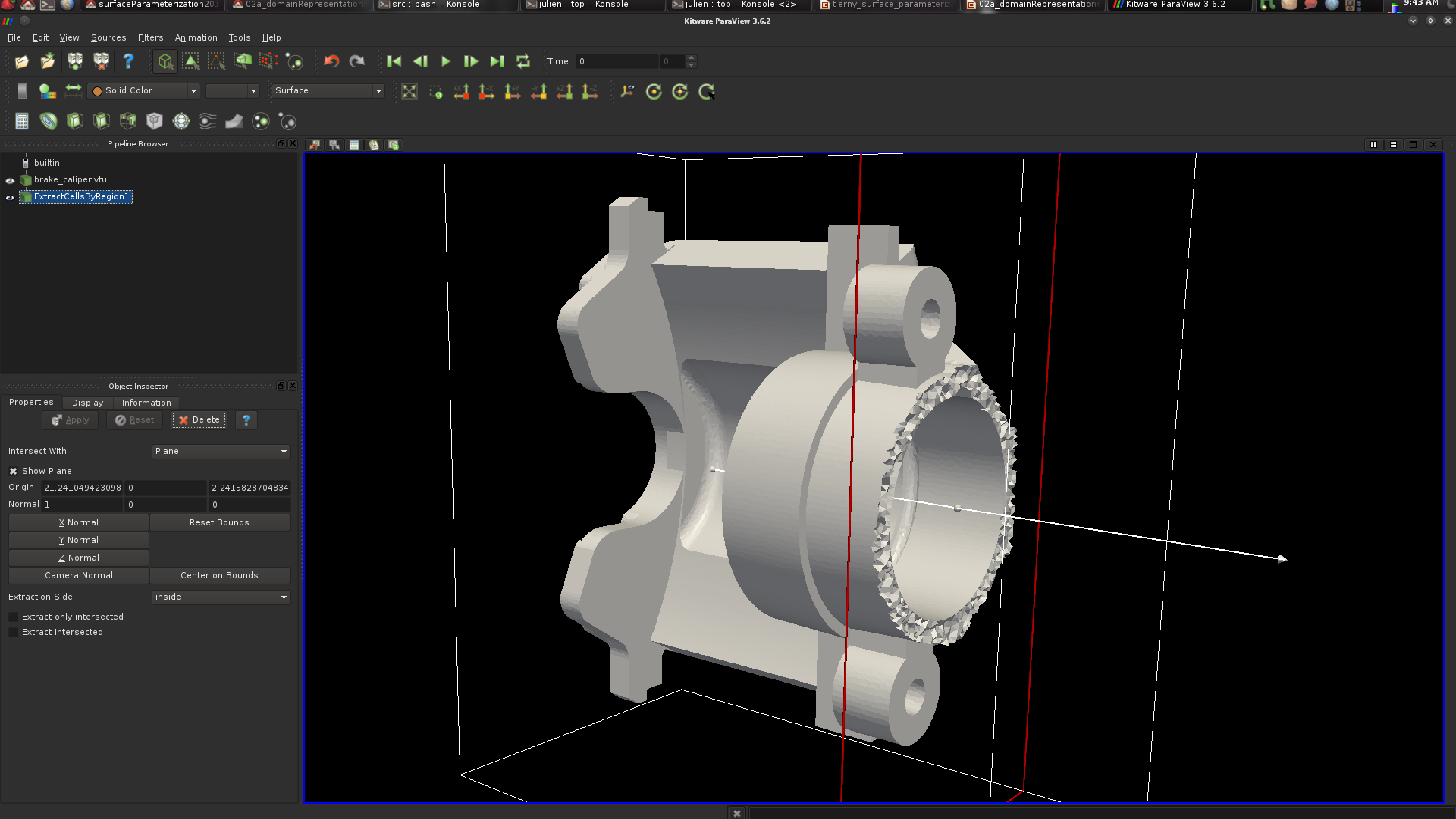
$$z = f(x, y)$$



Basic idea

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Additional information channels

- Domain with an embedding to \mathbb{R}^3
 - How can we encode scalar values?

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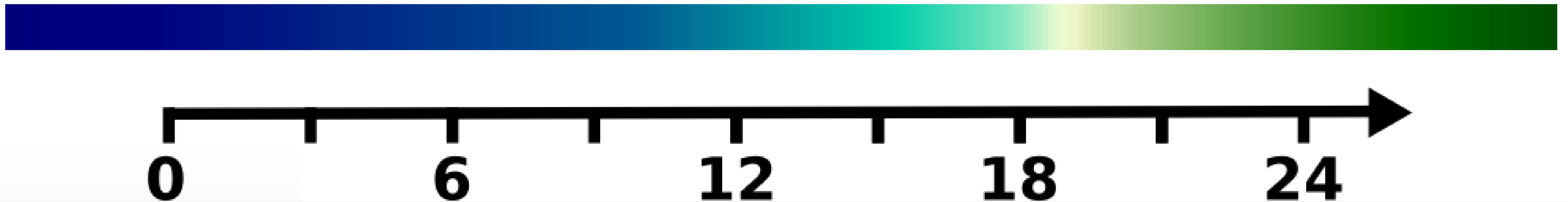
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 - Map it to the real line (\mathcal{A})

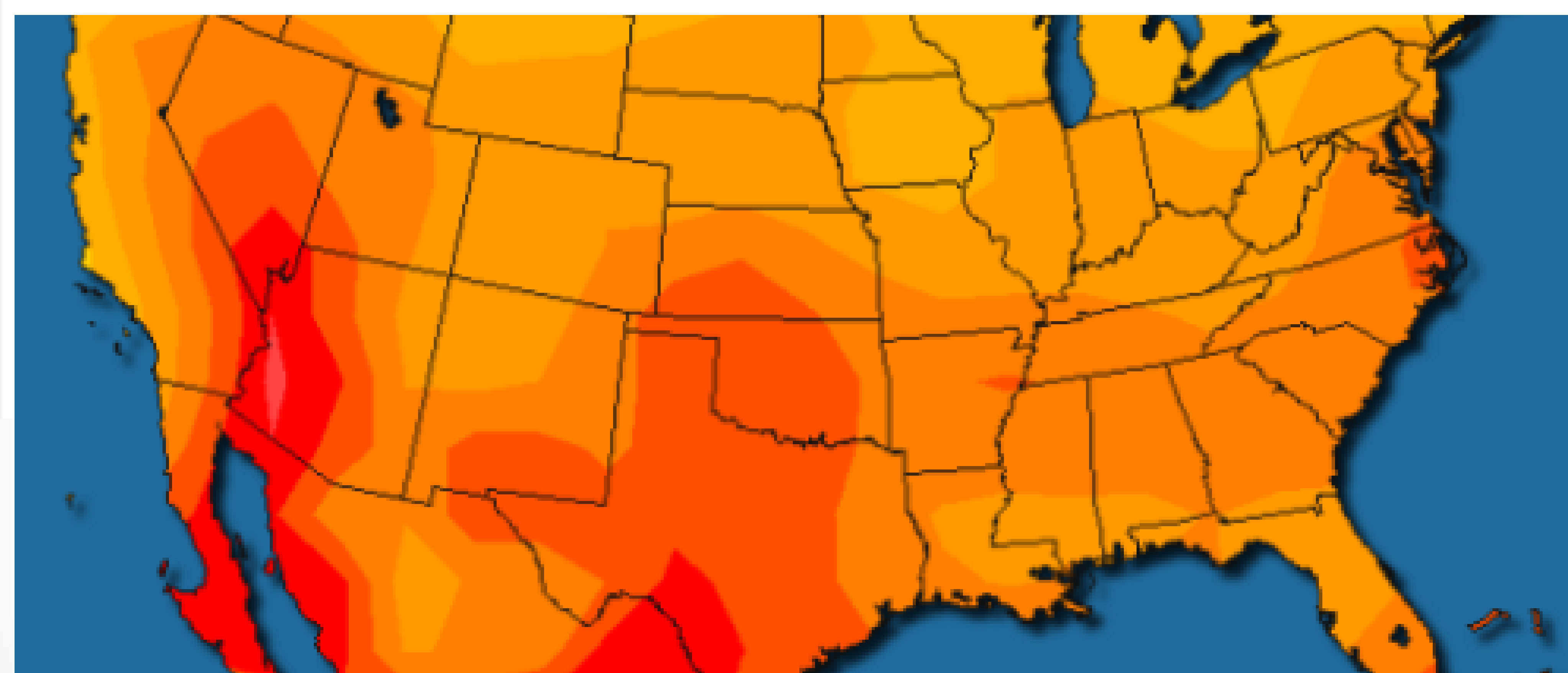


Additional information channels

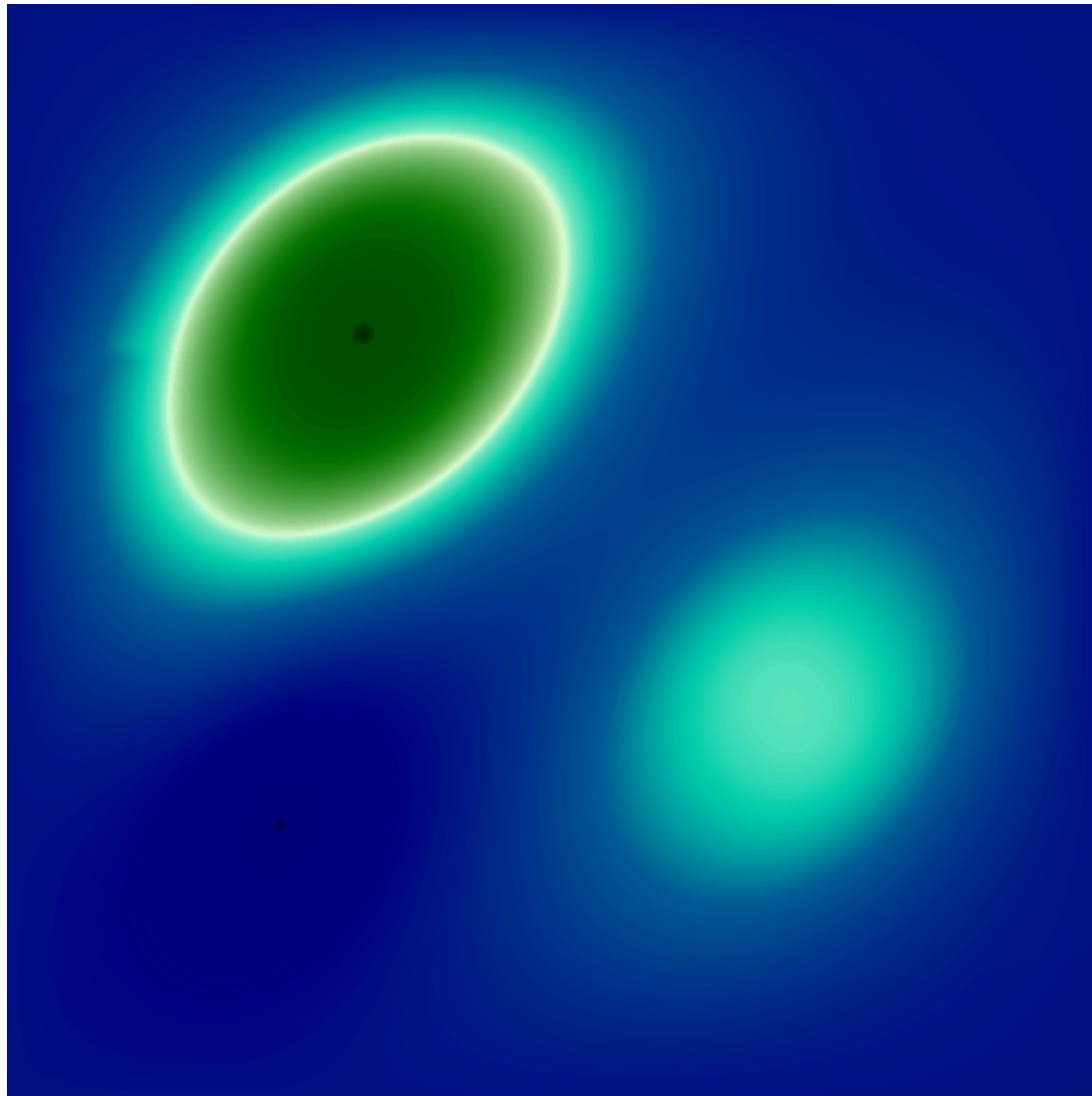
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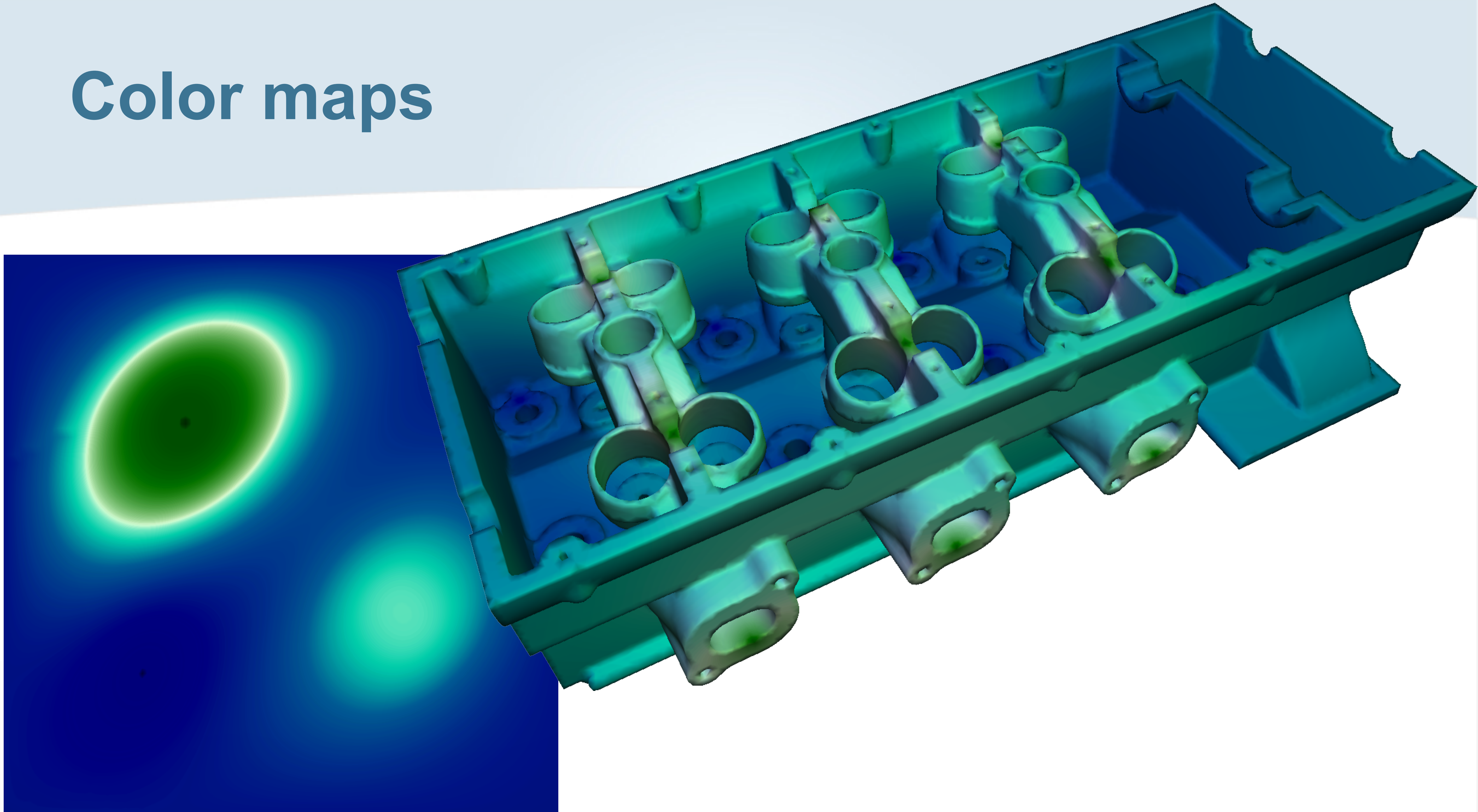
Color maps



Color maps



Color maps

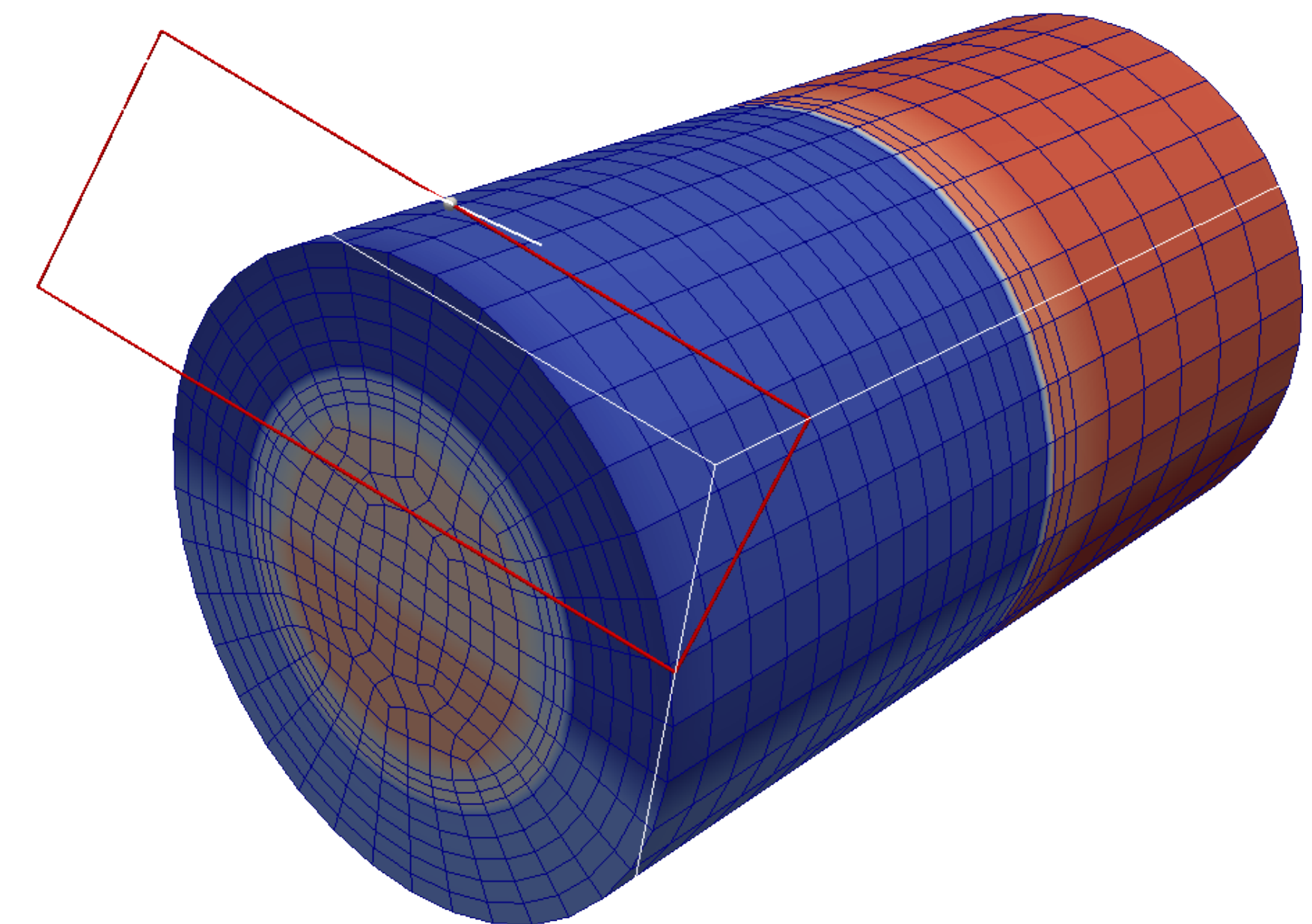


Color maps

- Intuitive idea :(
 - What about volumetric domains?

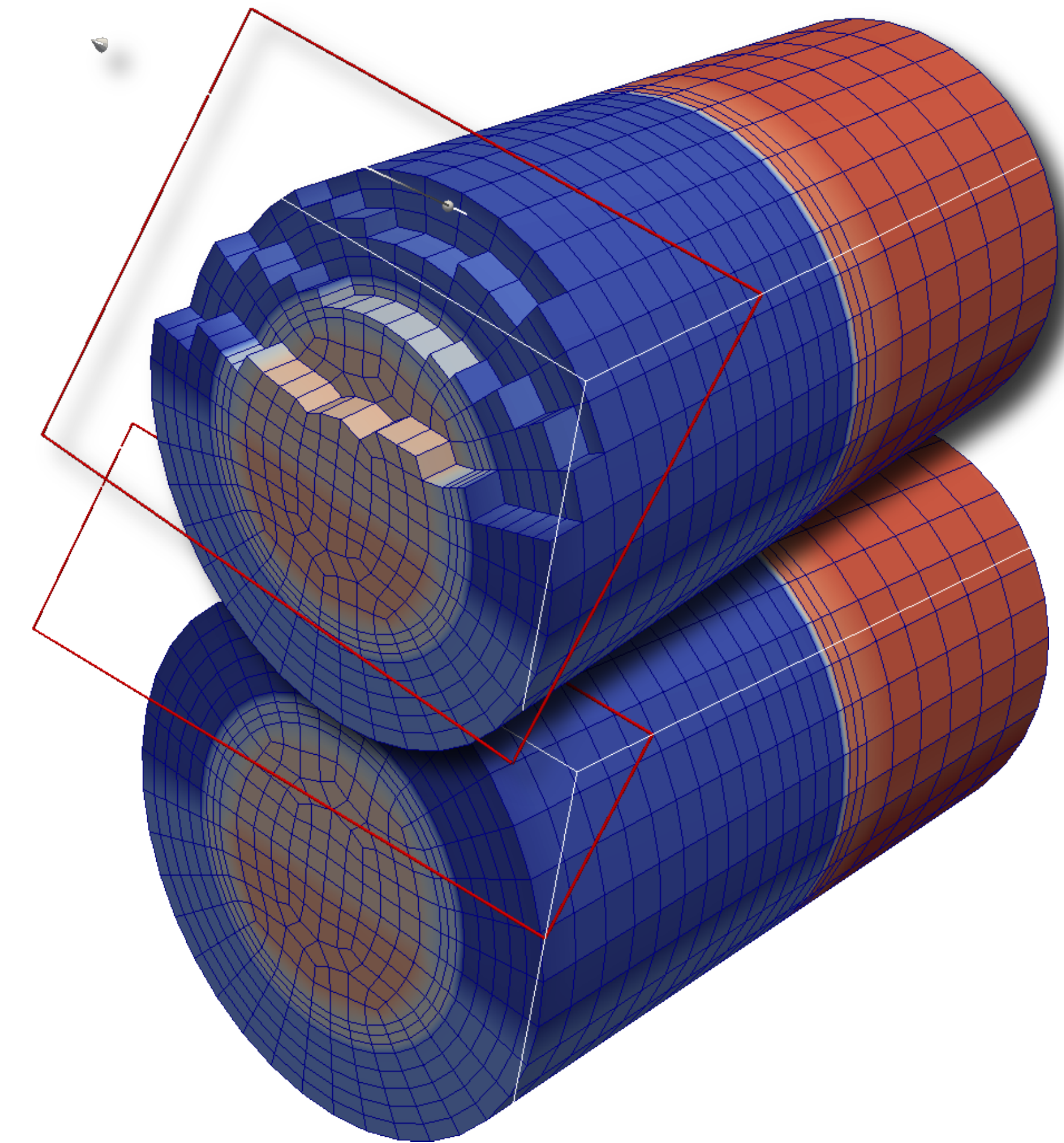
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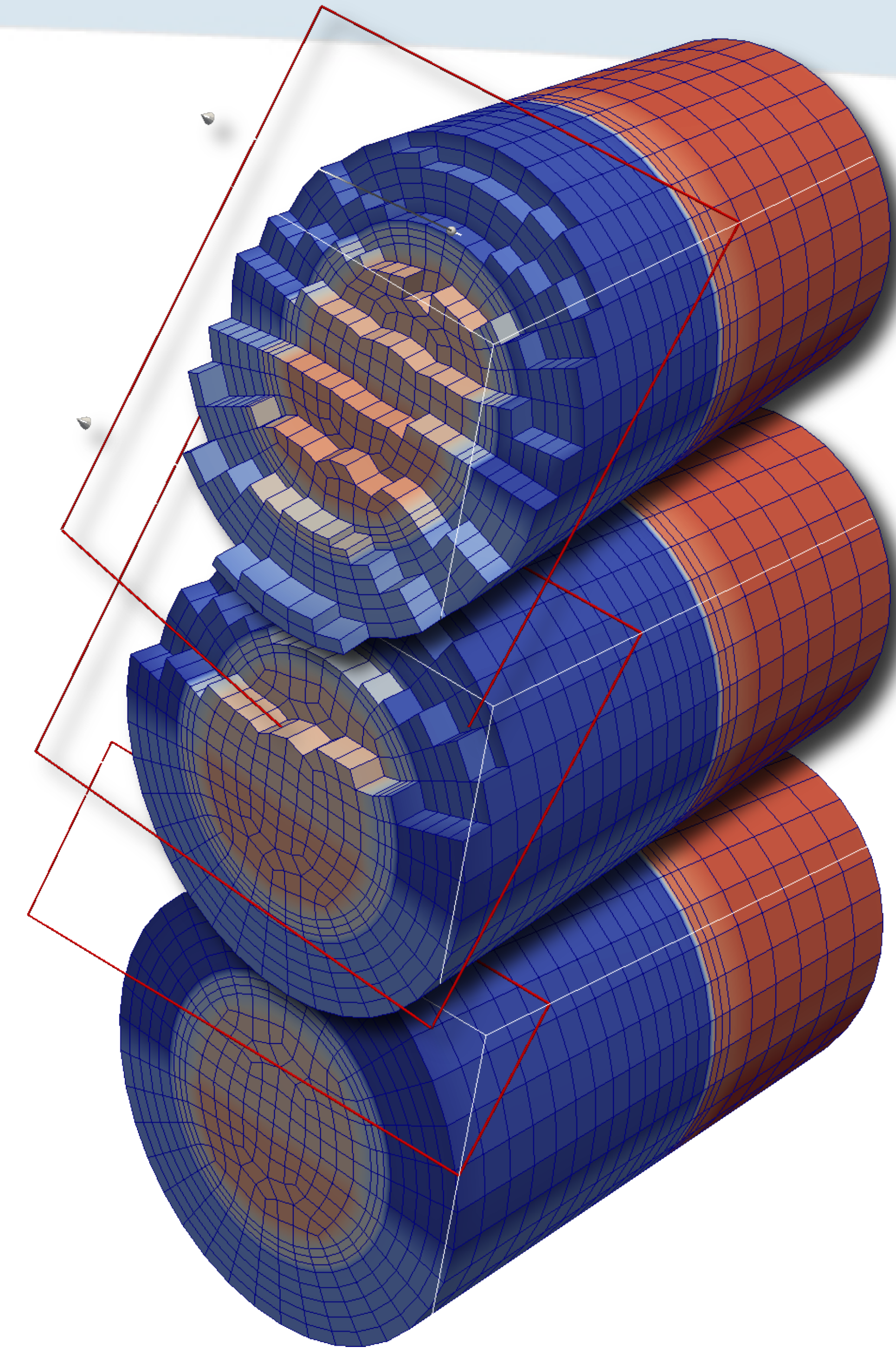
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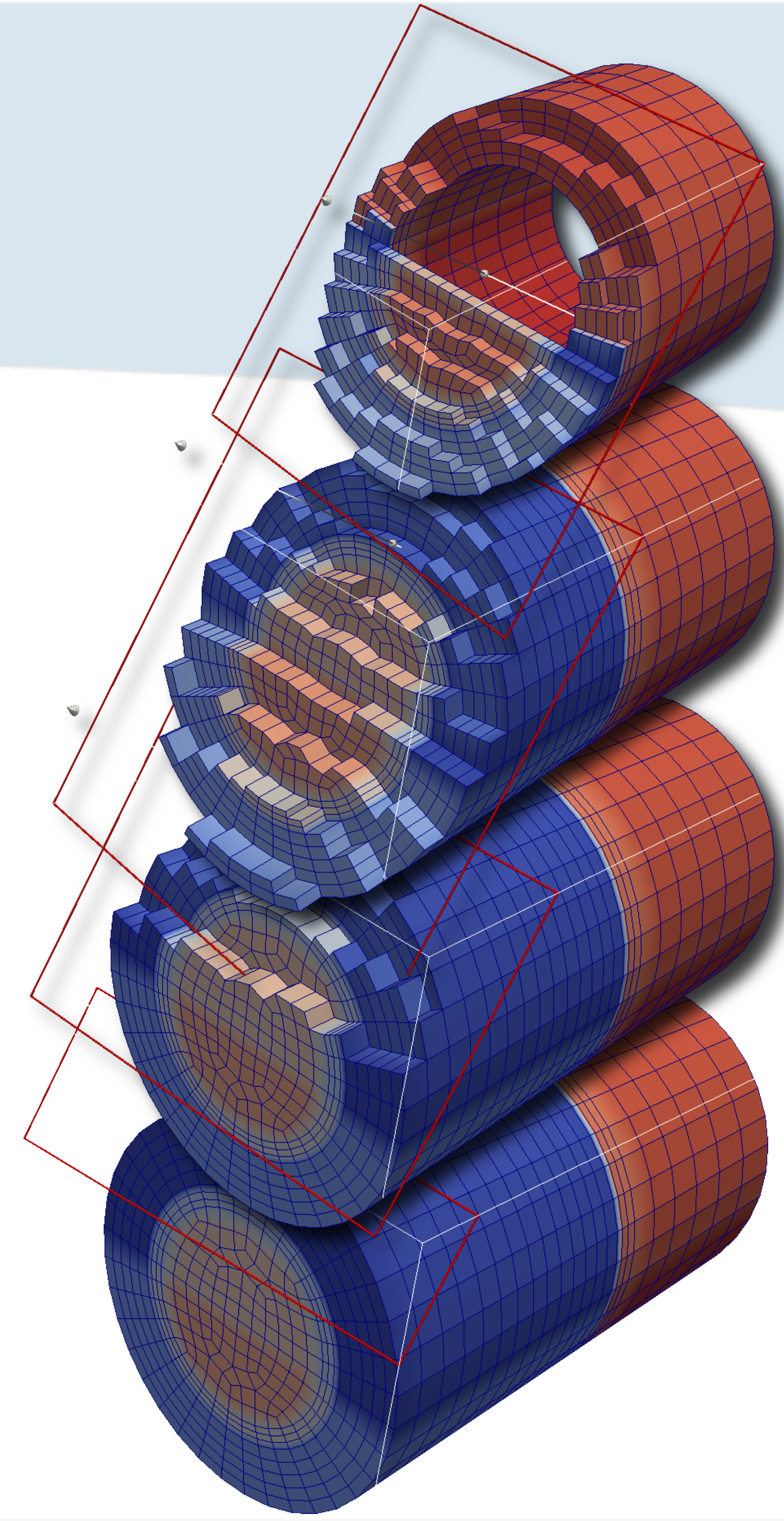
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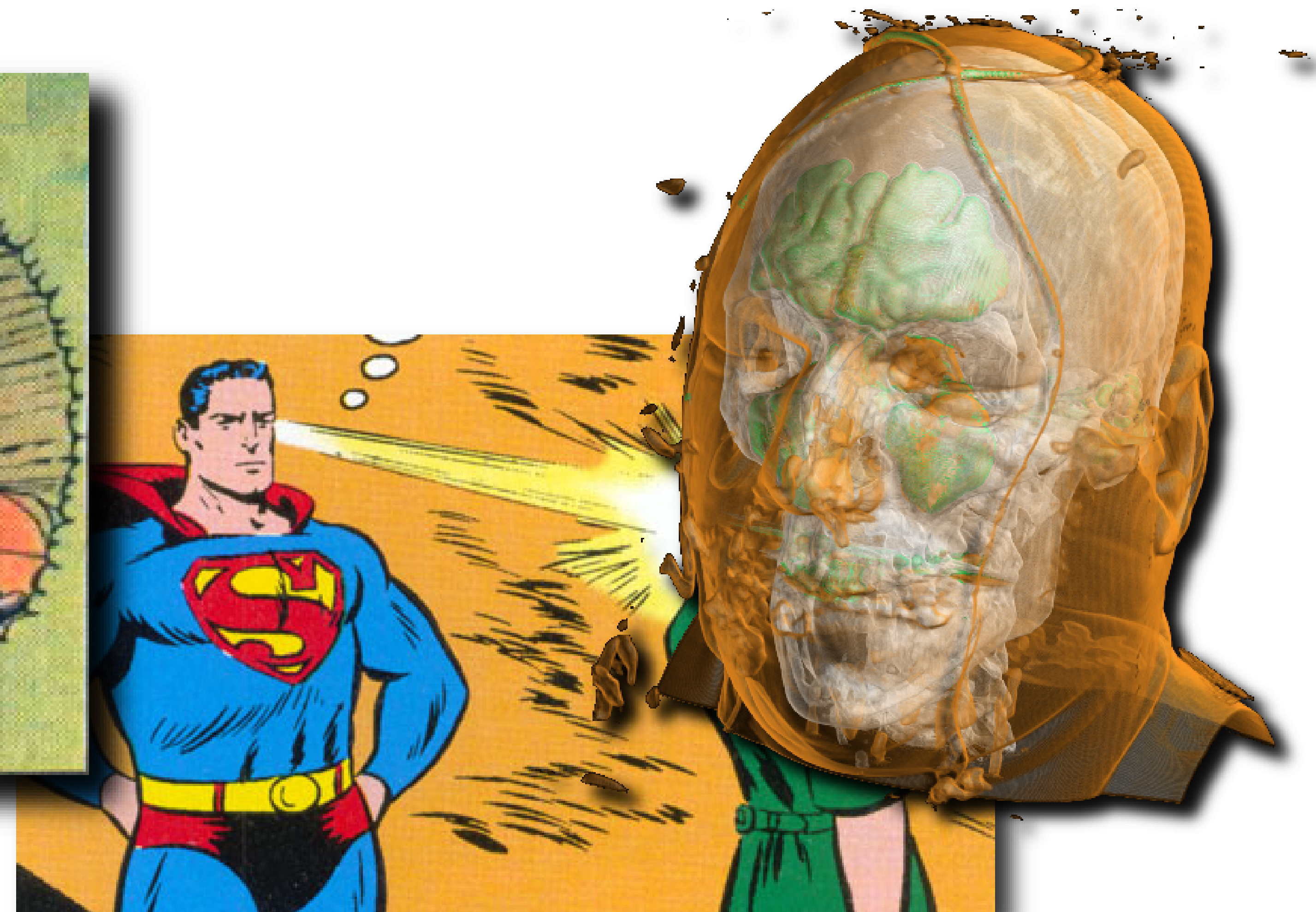
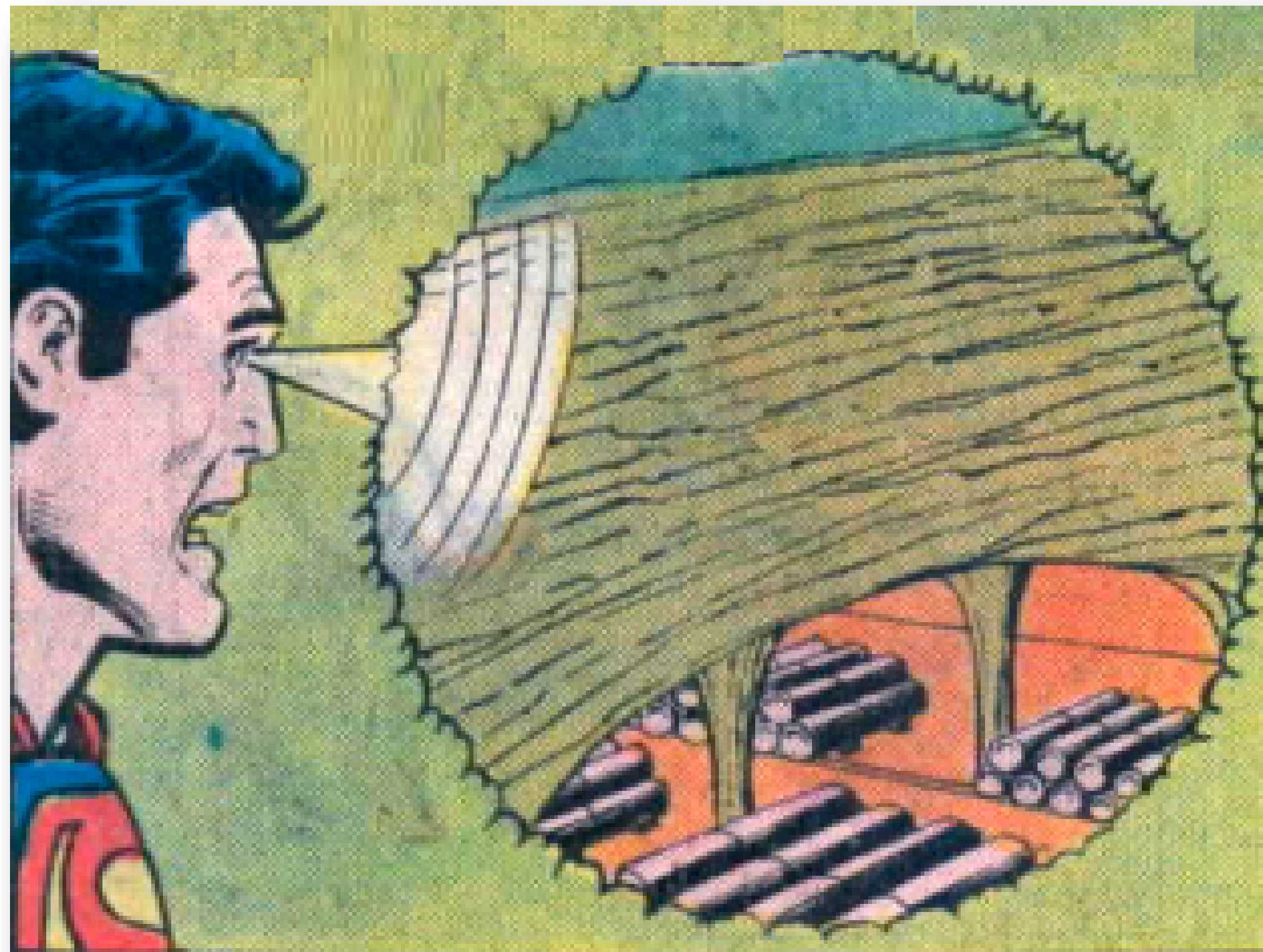
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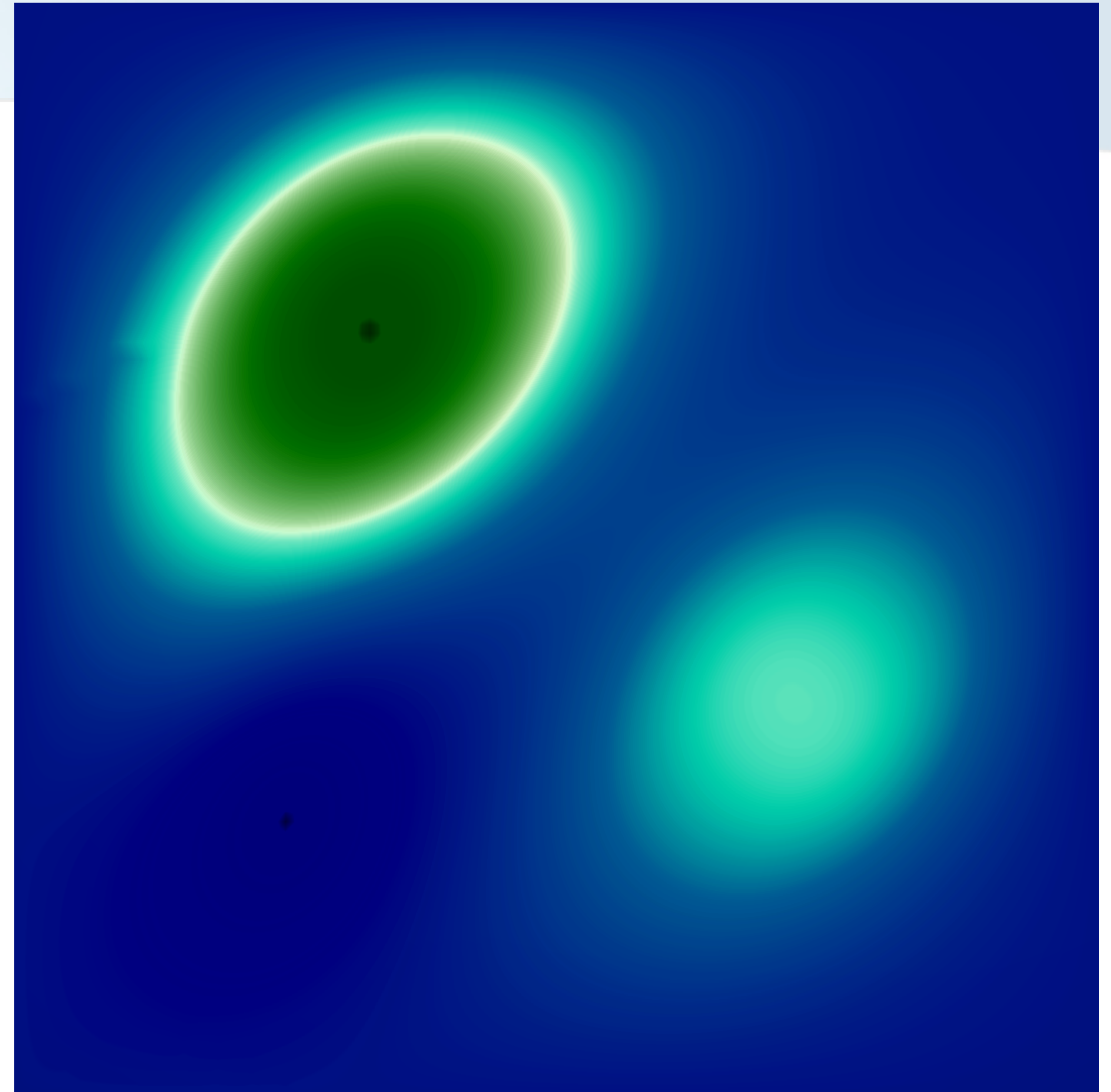
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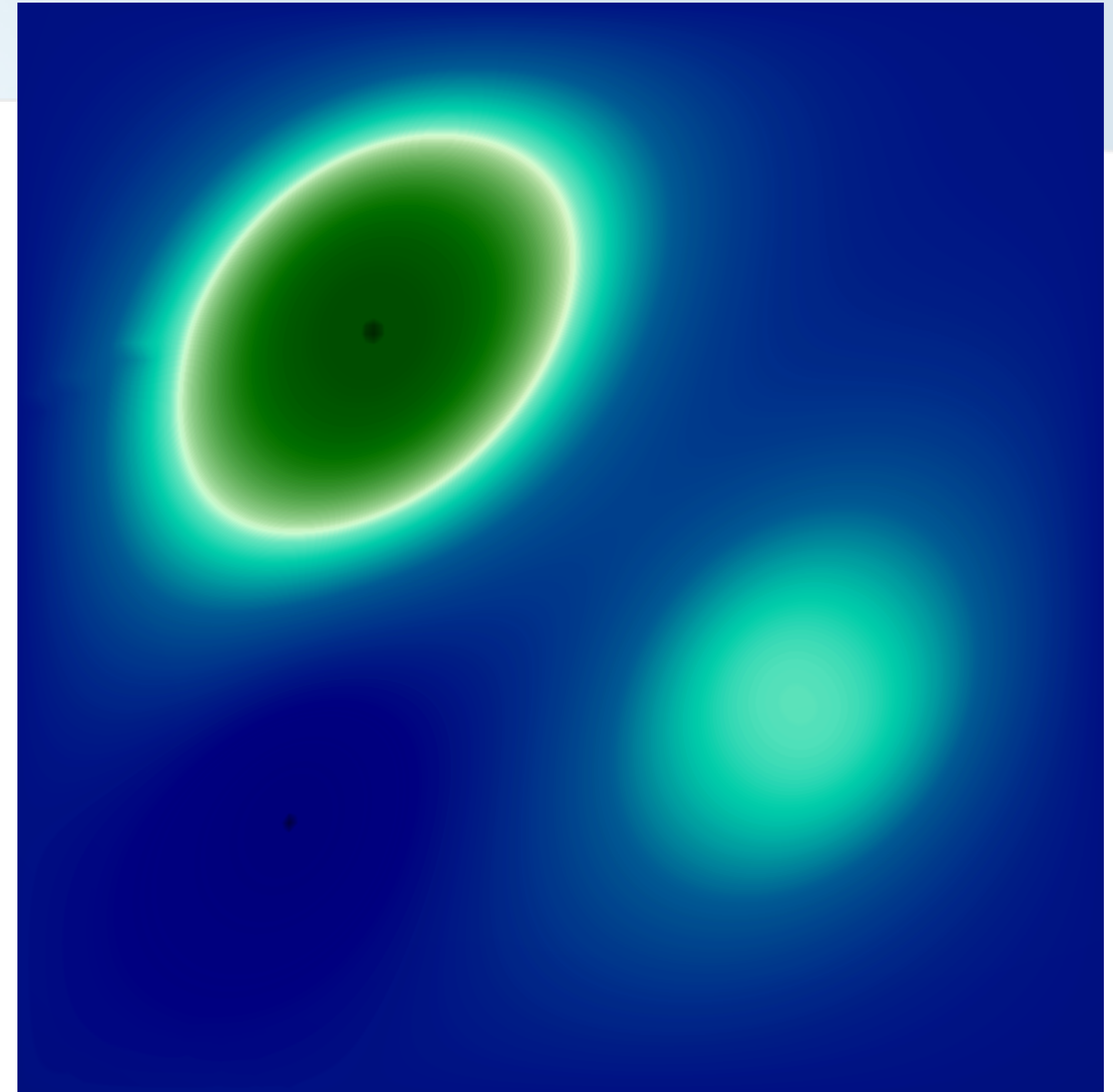
Scalar field geometry

- Continuous color maps



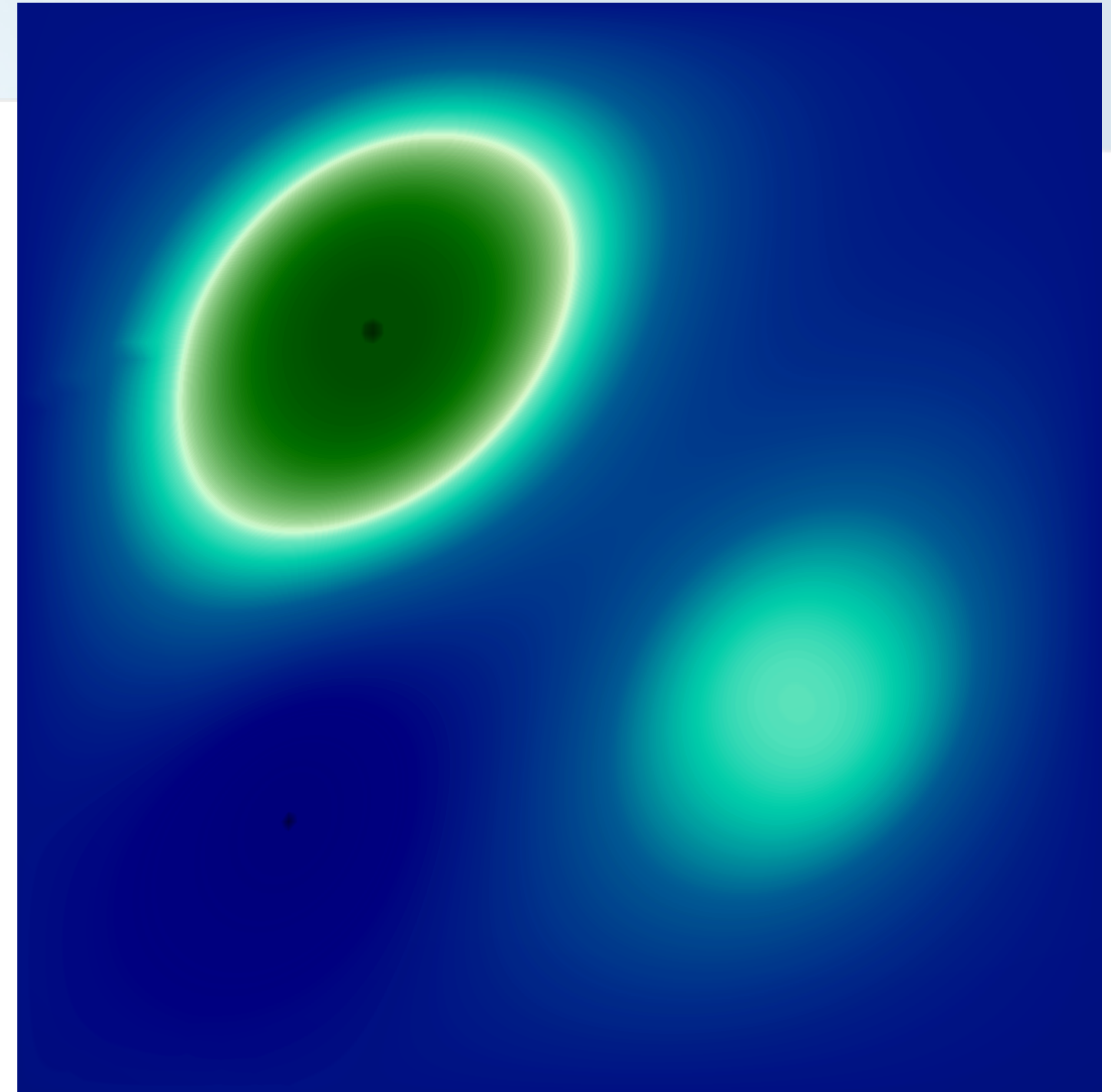
Scalar field geometry

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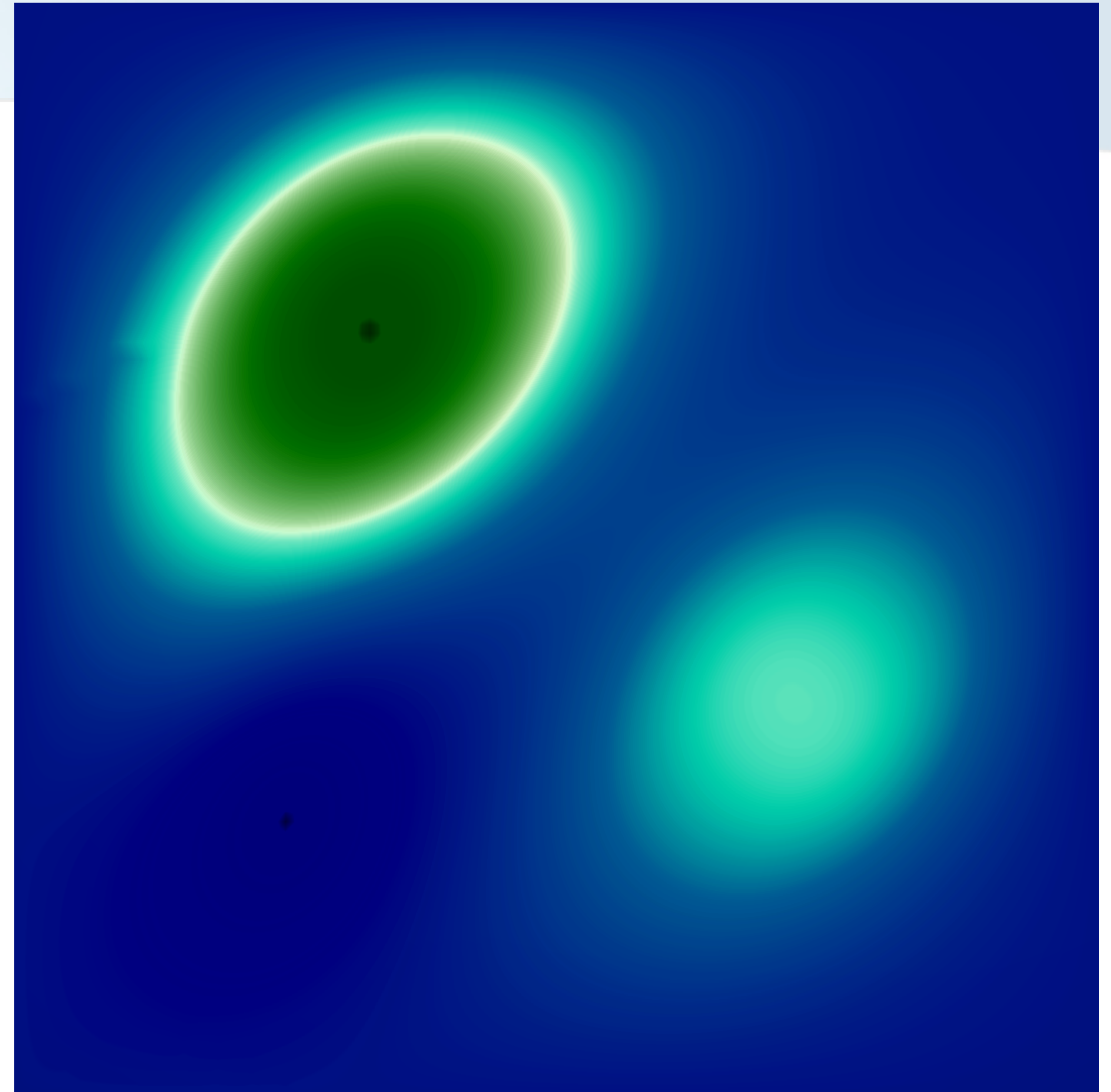
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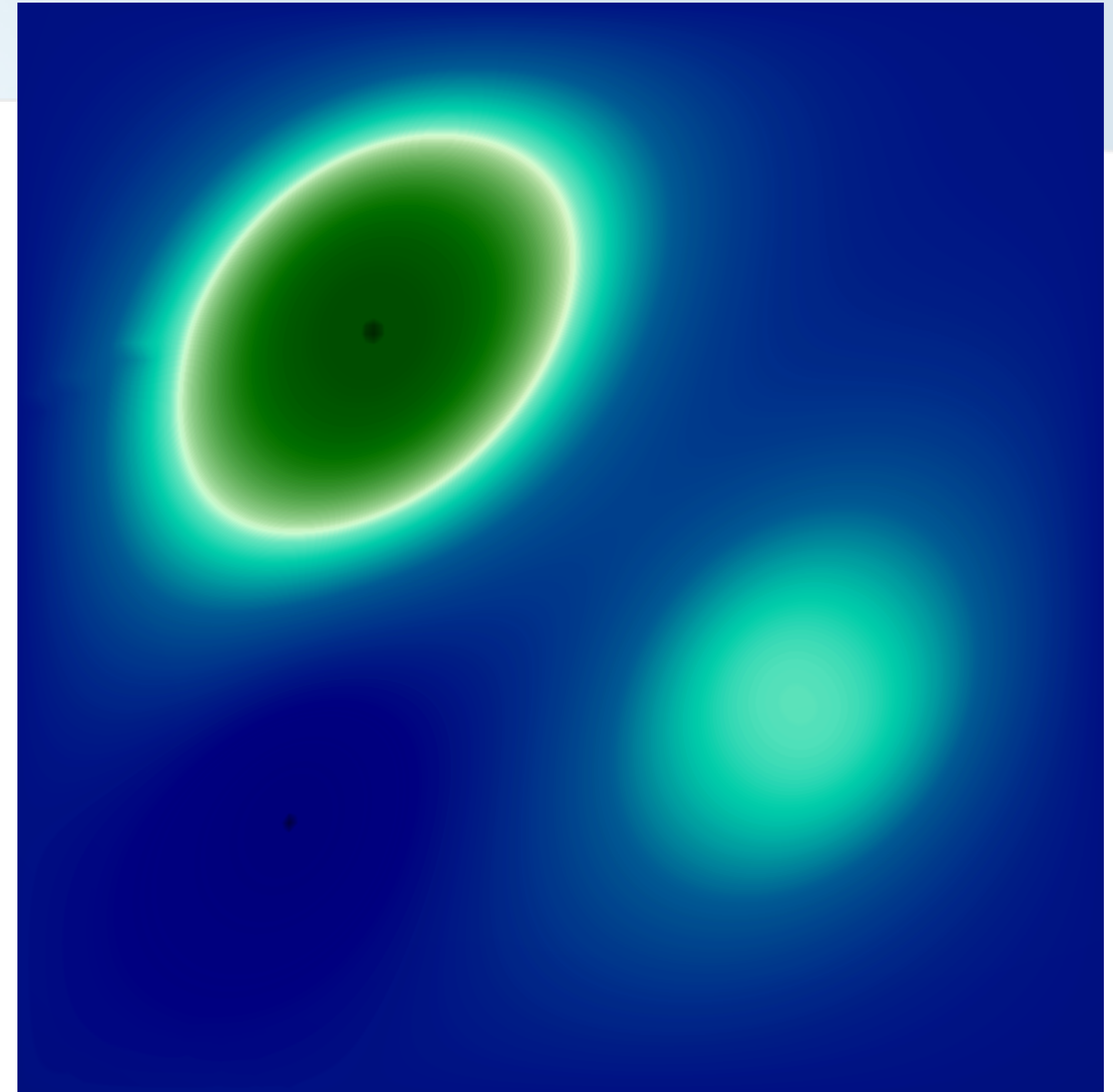
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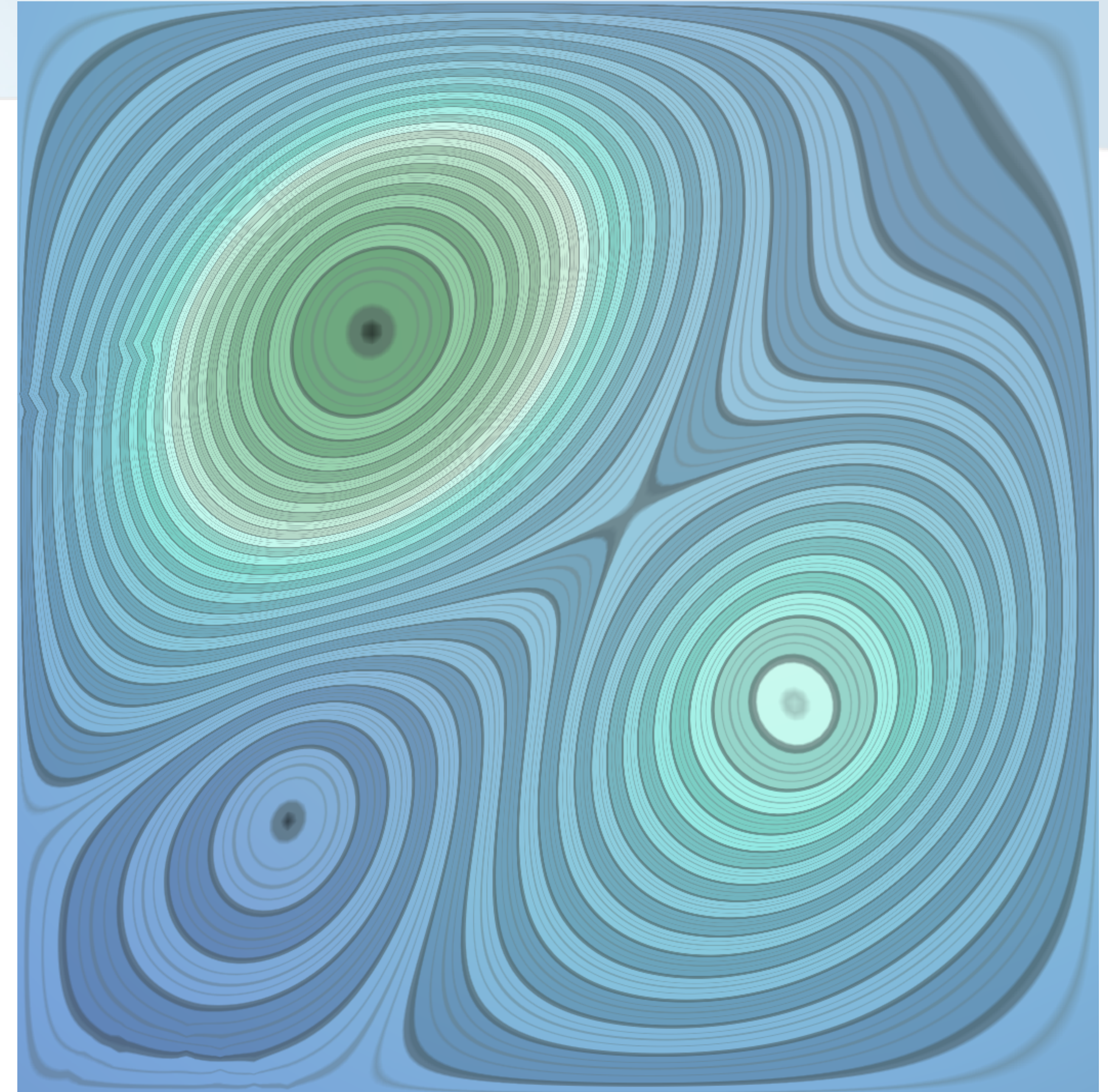
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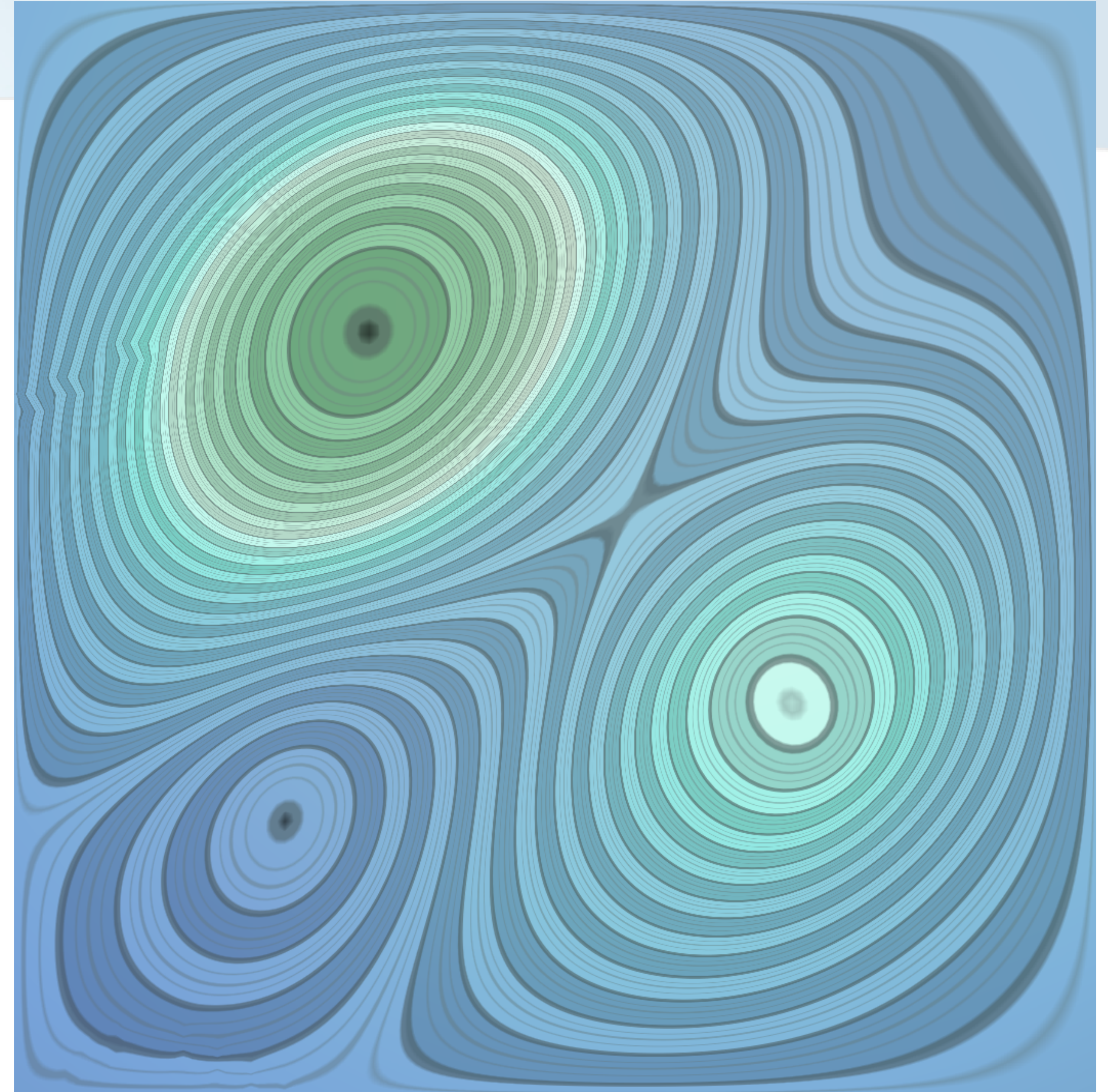
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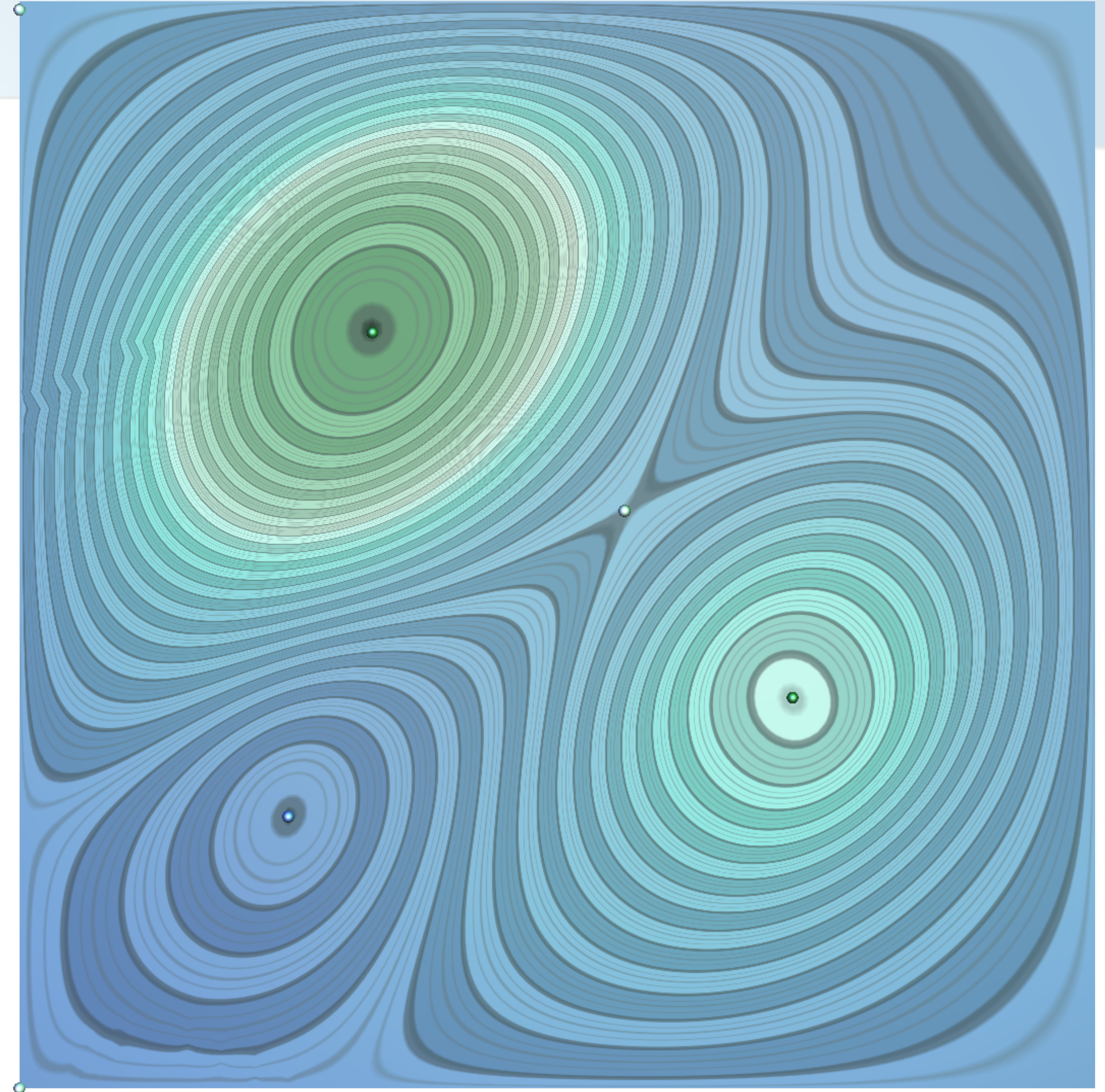
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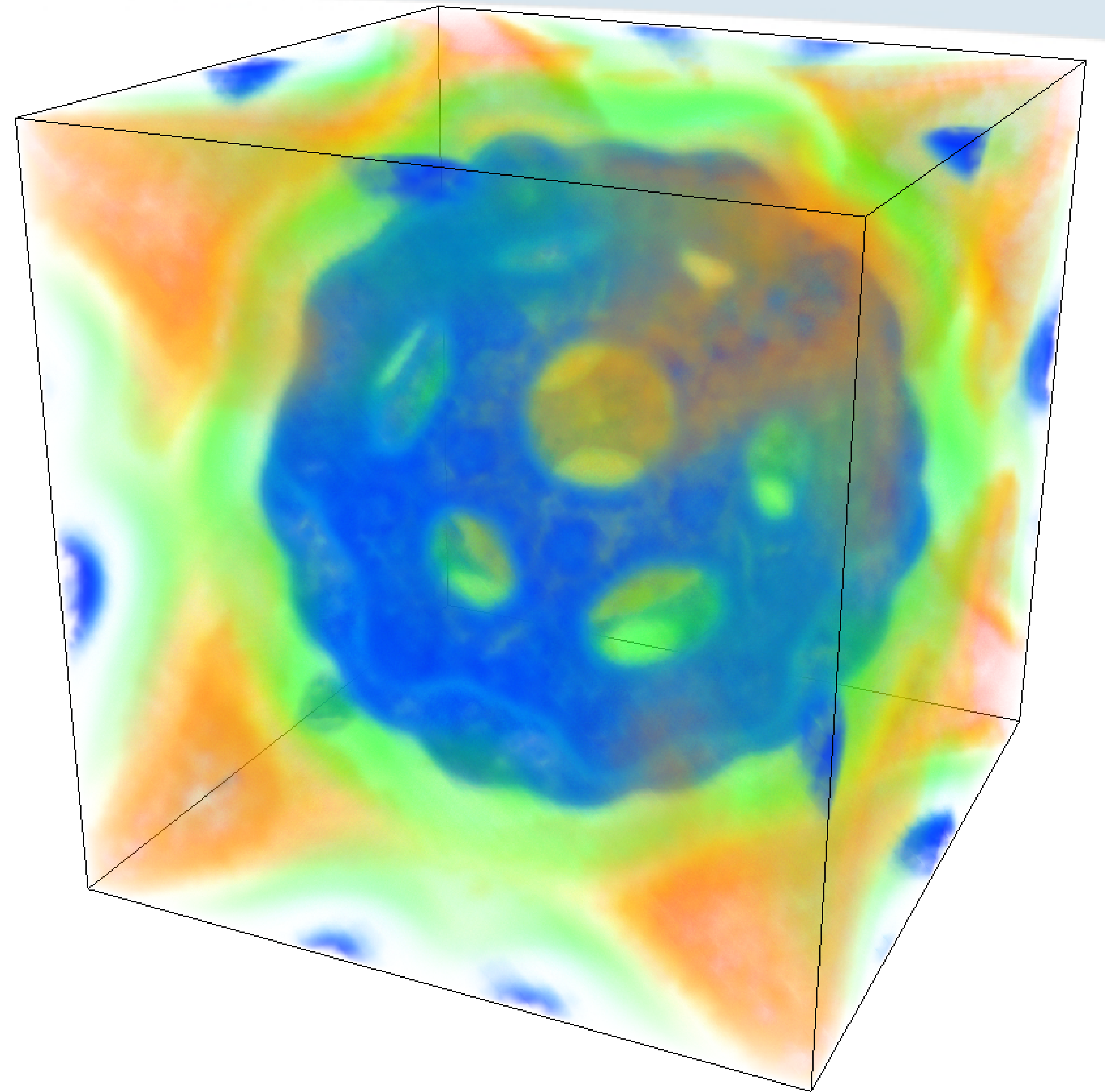
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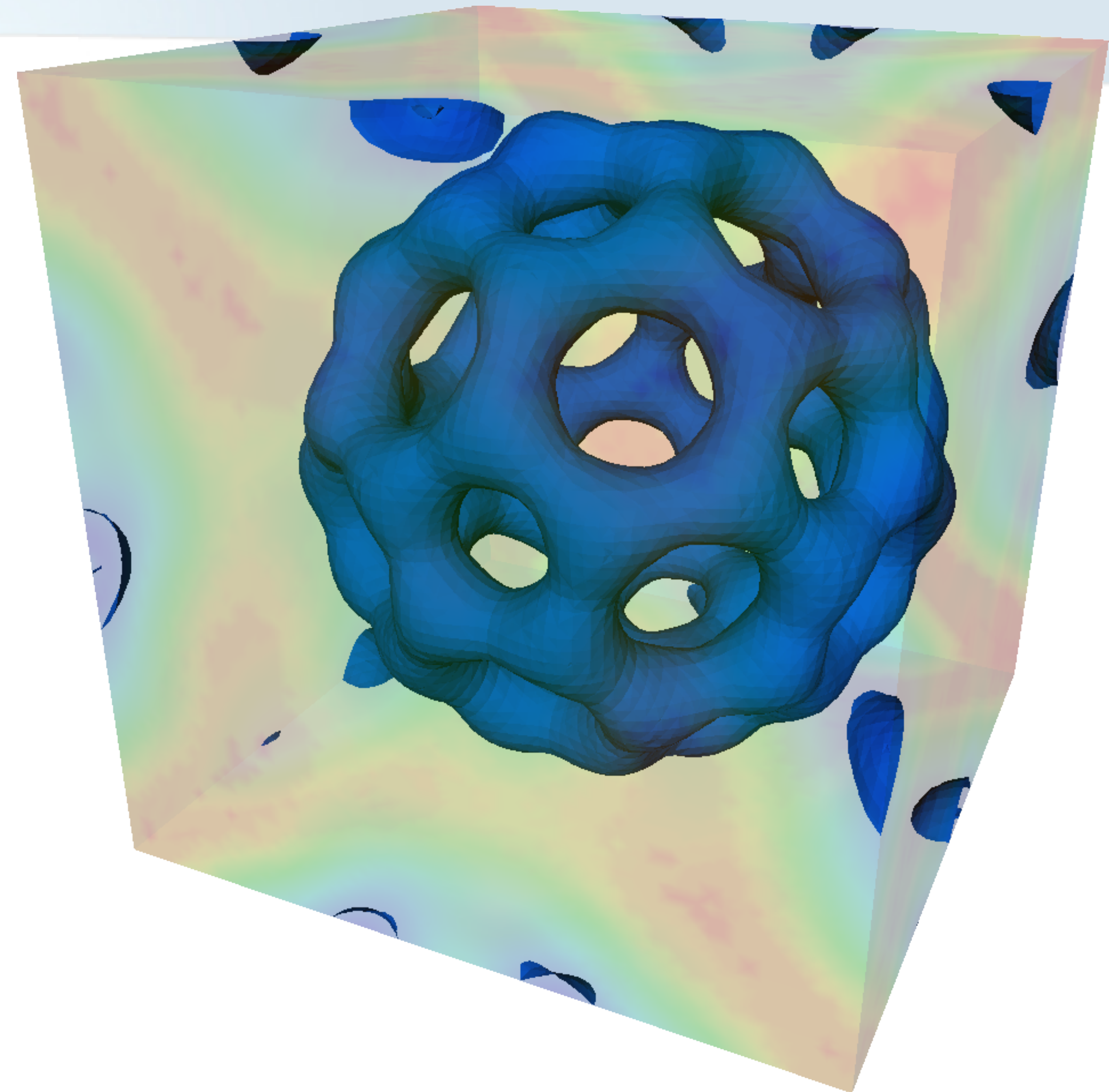
Query-driven visualization

- Visualize isolated regions of interests



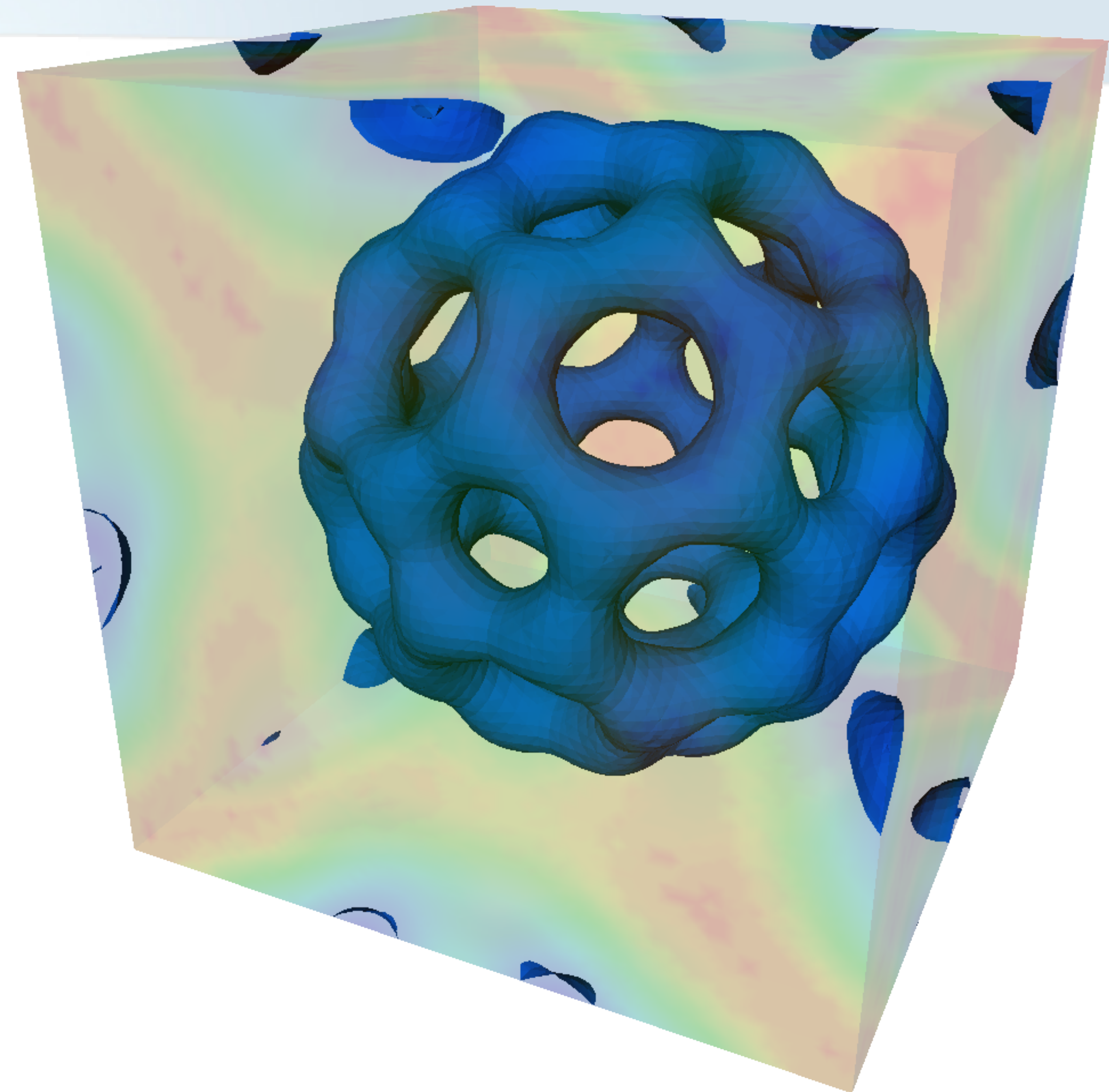
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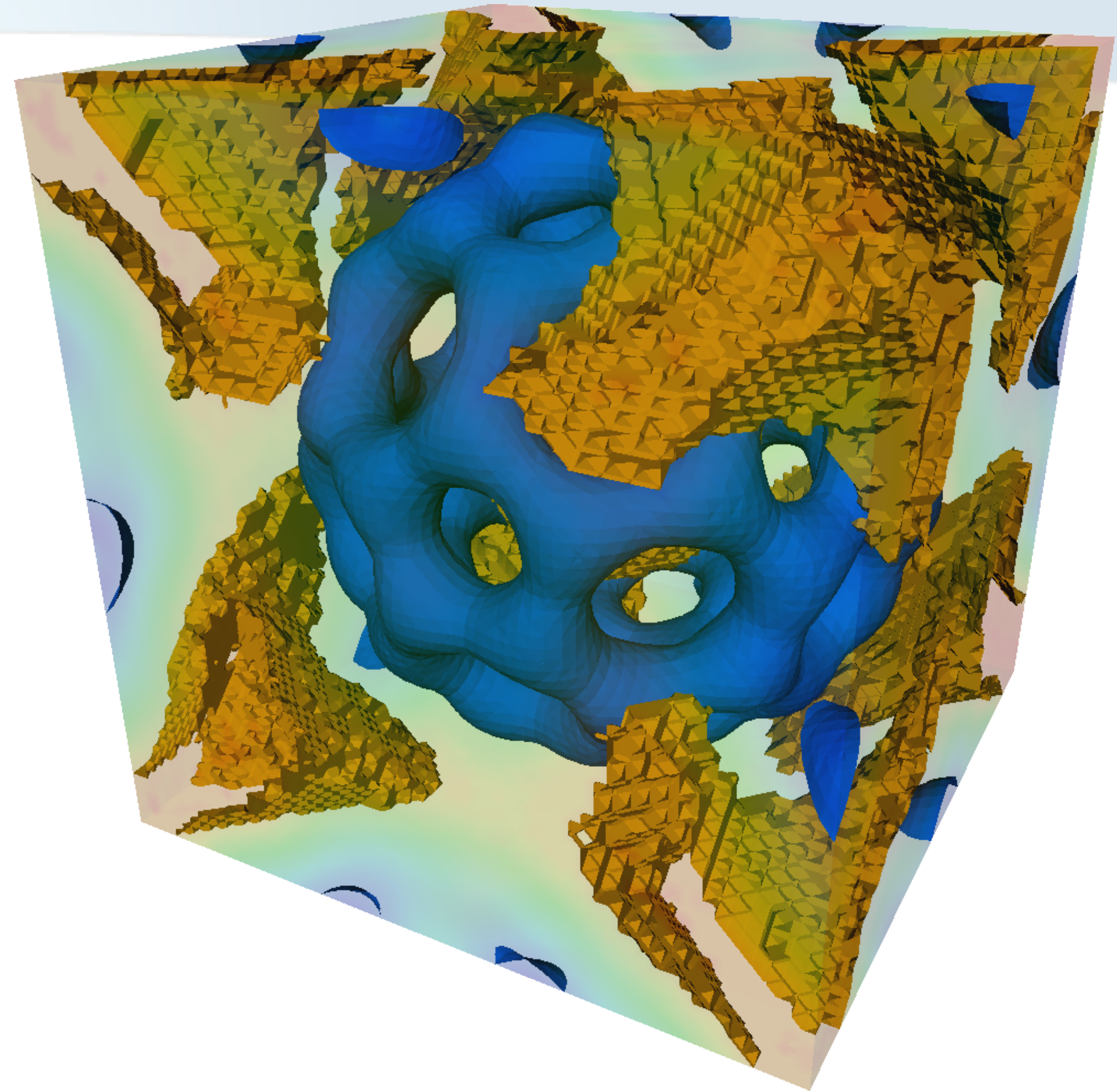
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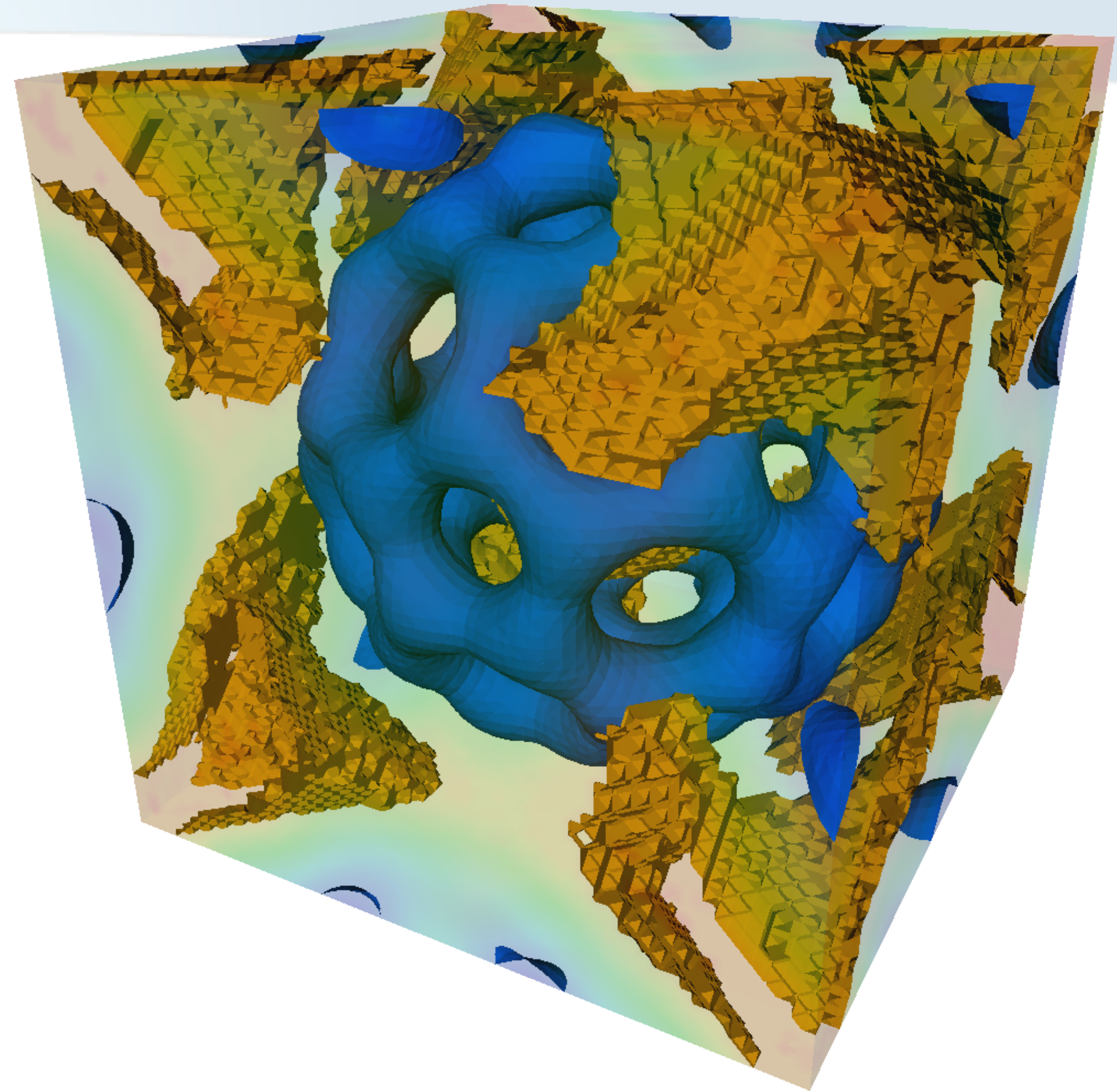
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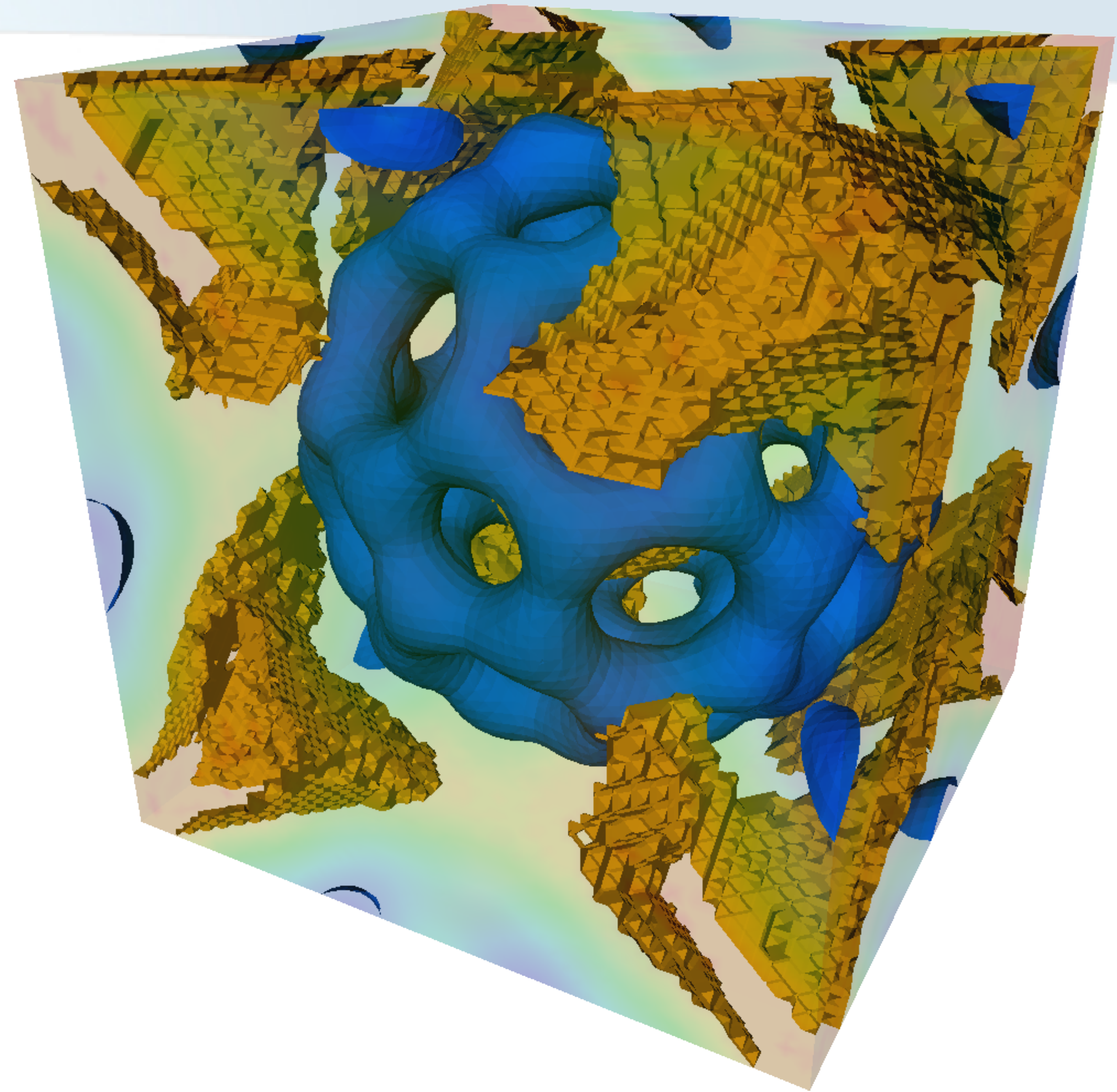
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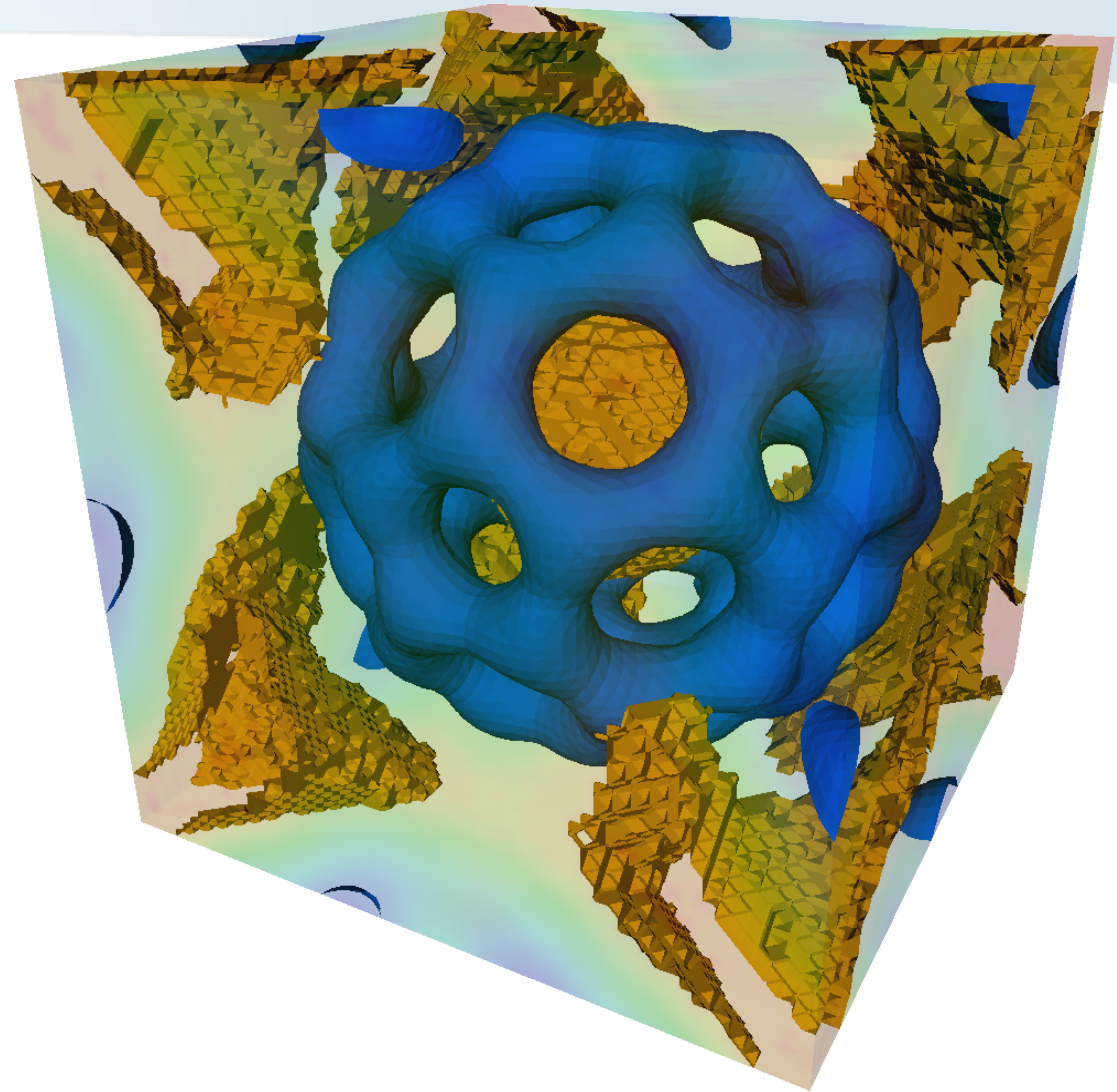
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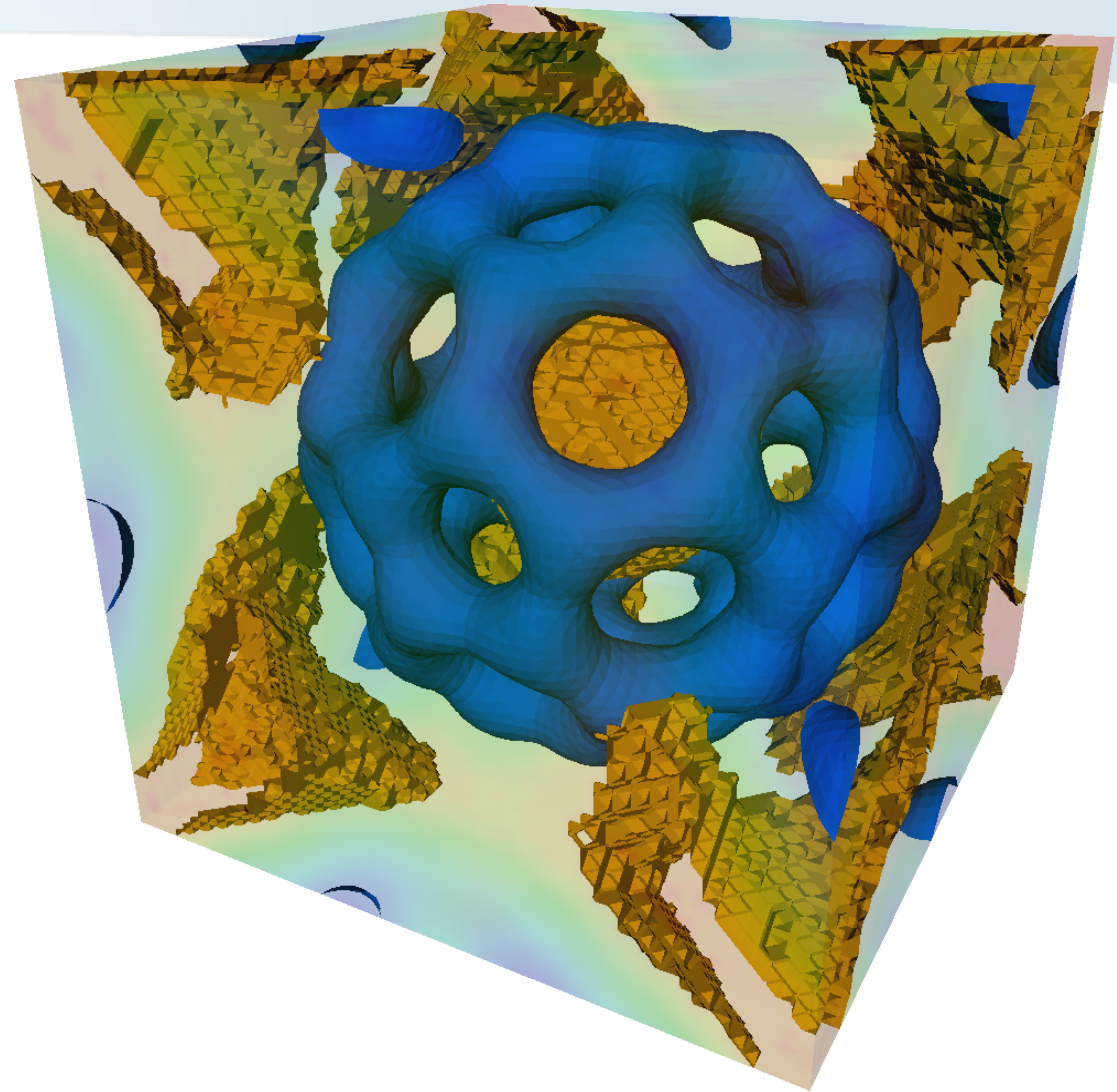
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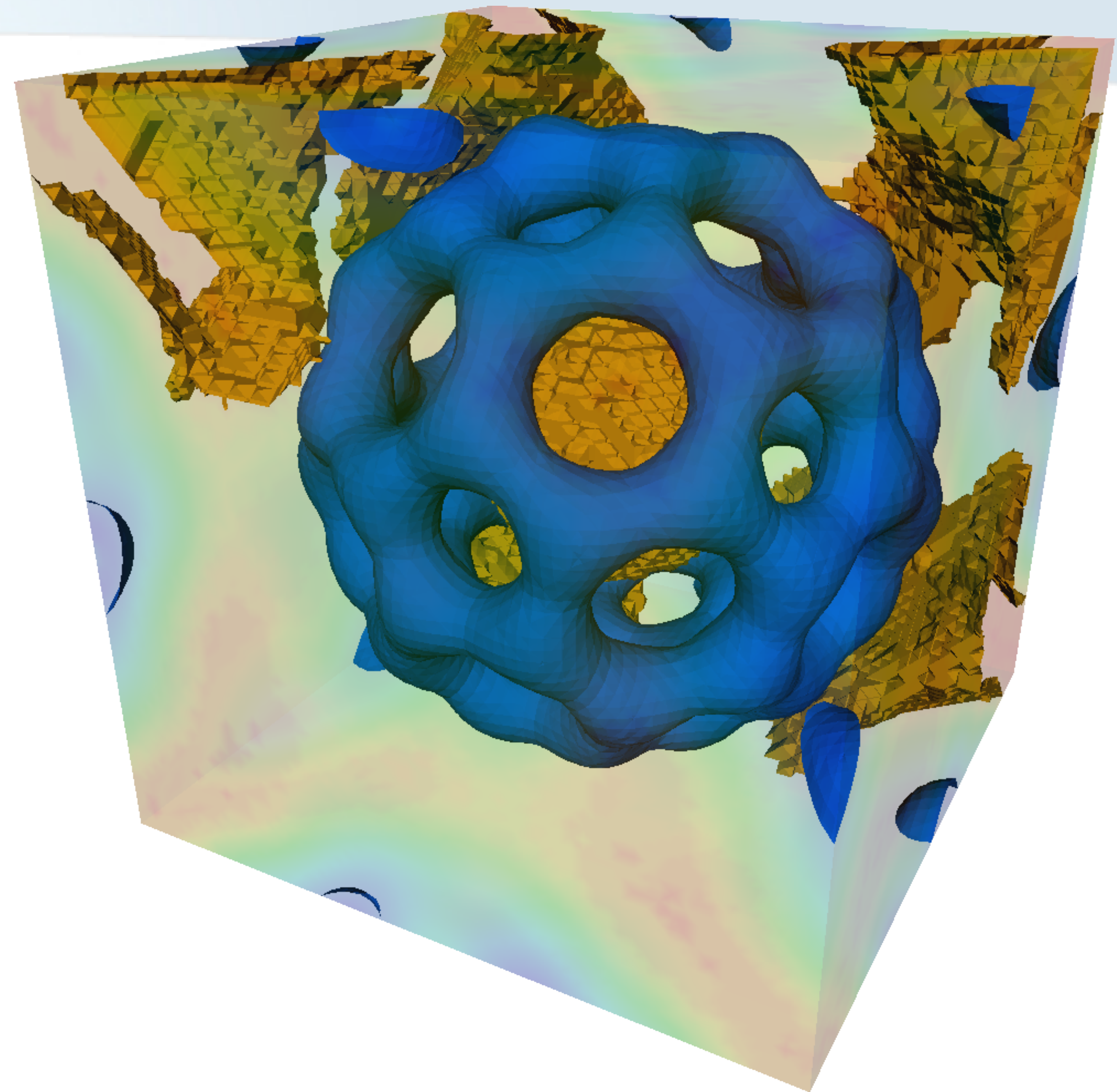
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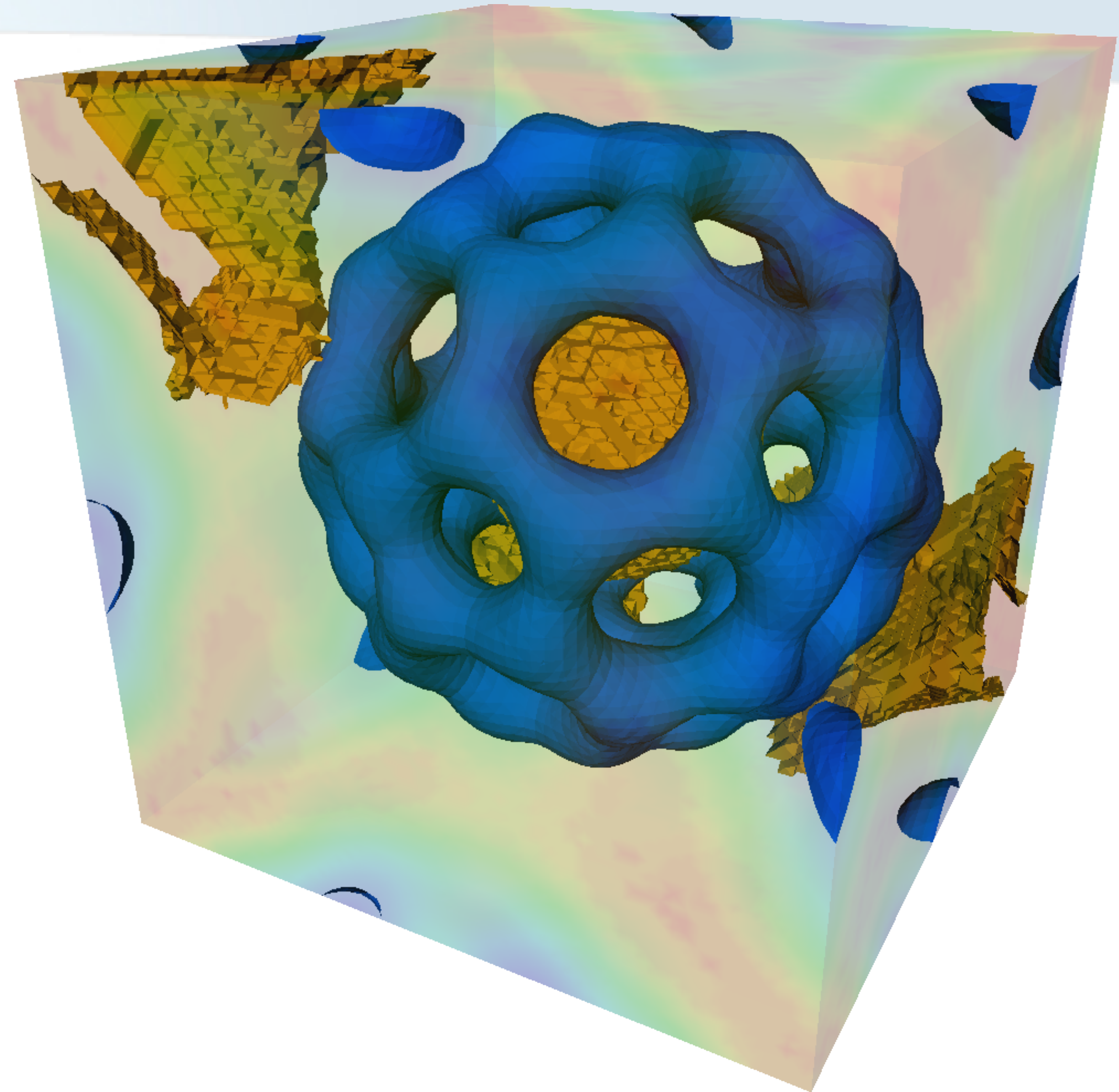
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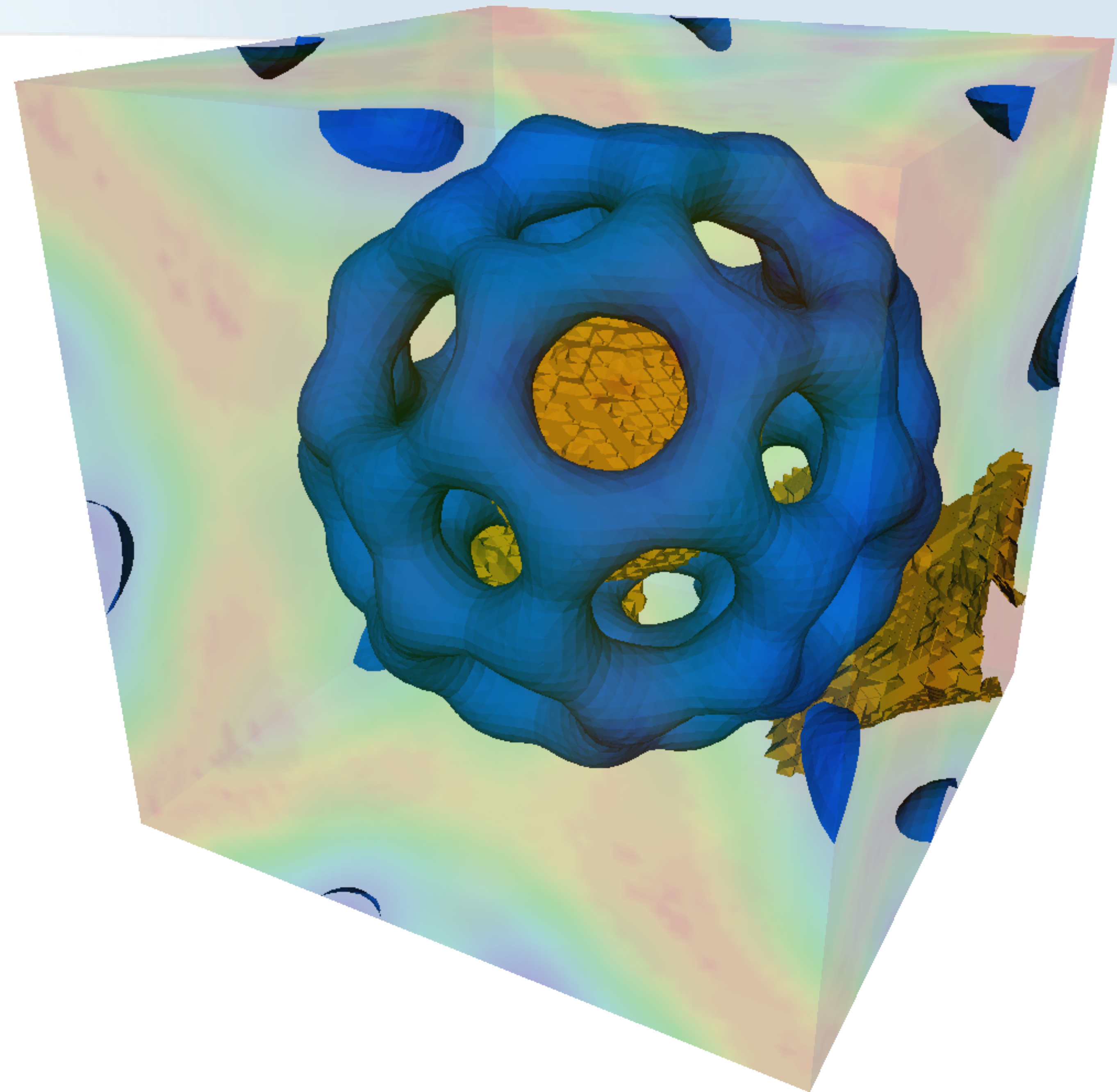
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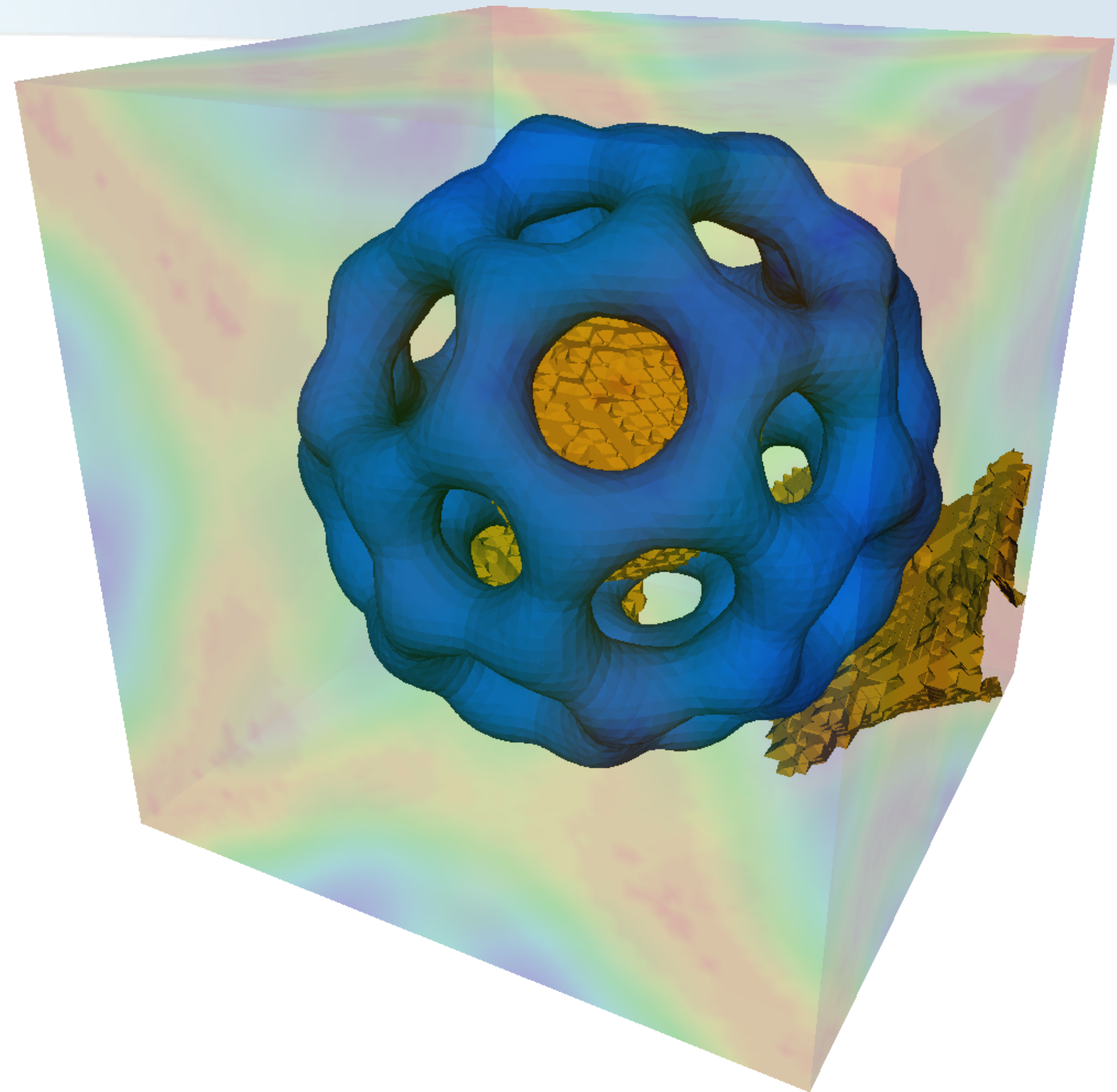
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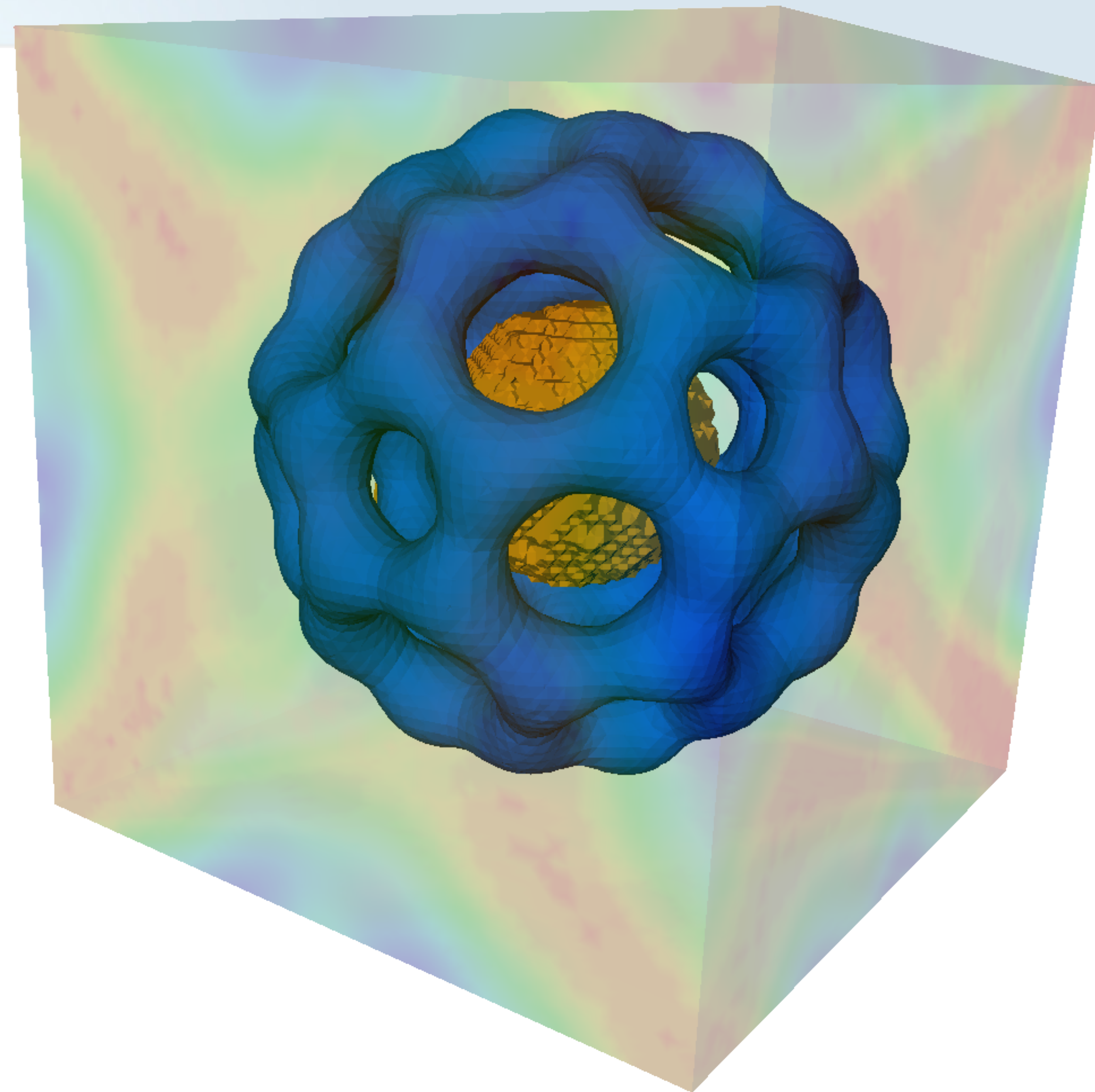
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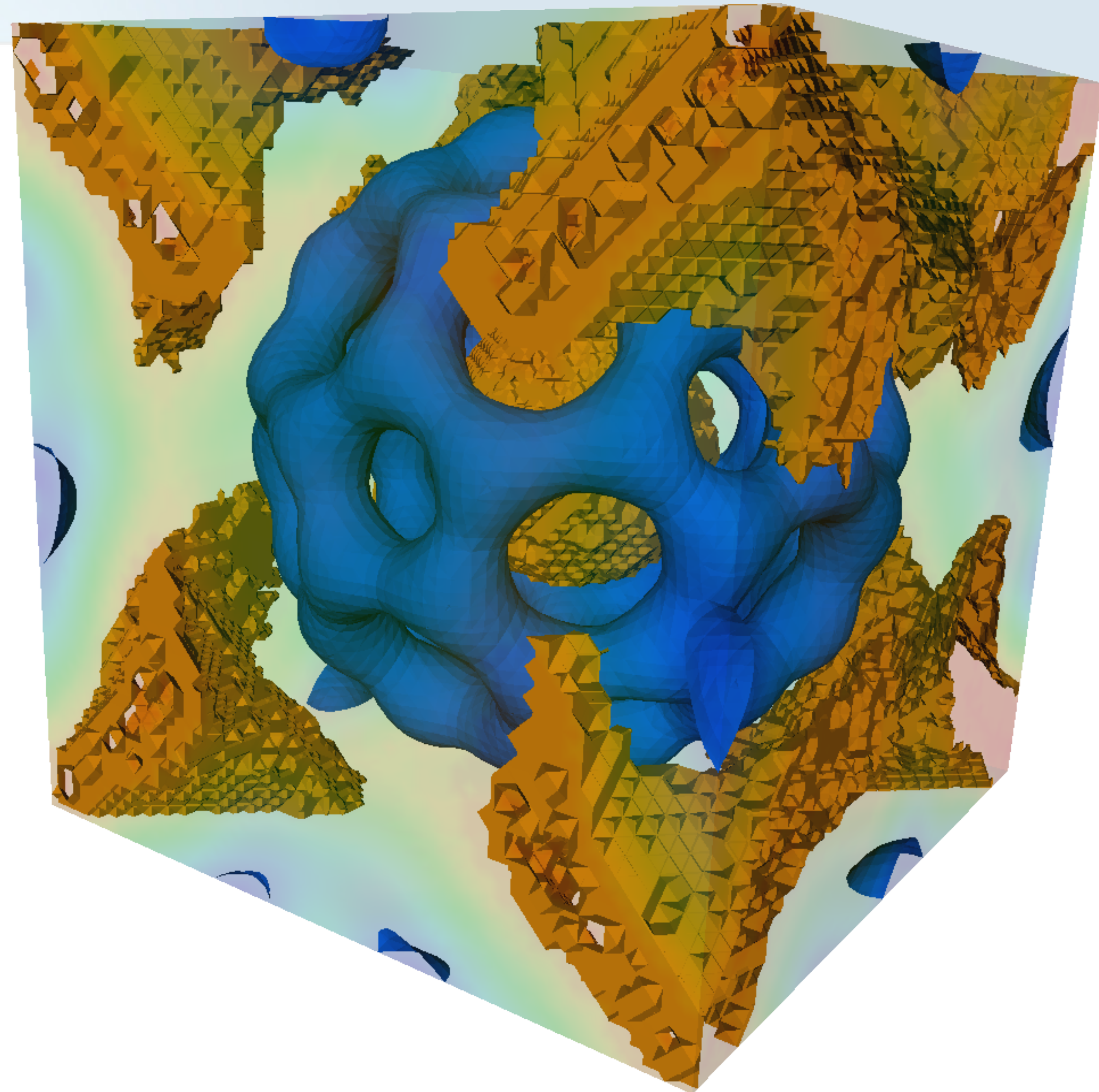
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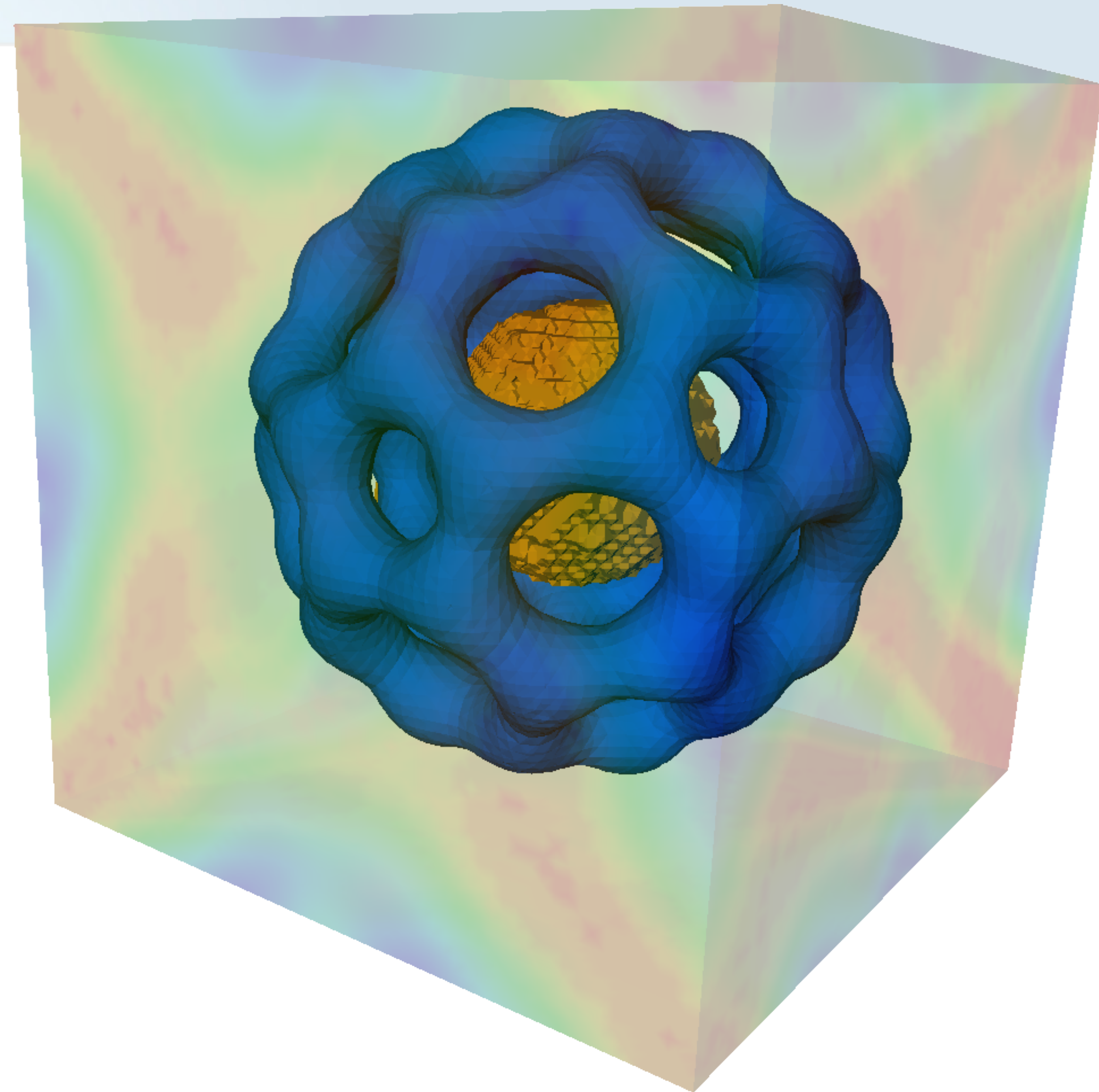
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- Implementation examples

Higher dimensional embedding

- Given 1D regular grid
 - Create a 1-triangulation embedded in \mathbb{R}^2

$$f : [0, 24] \rightarrow \mathbb{R}$$

$$x = x$$

$$y = f(x)$$

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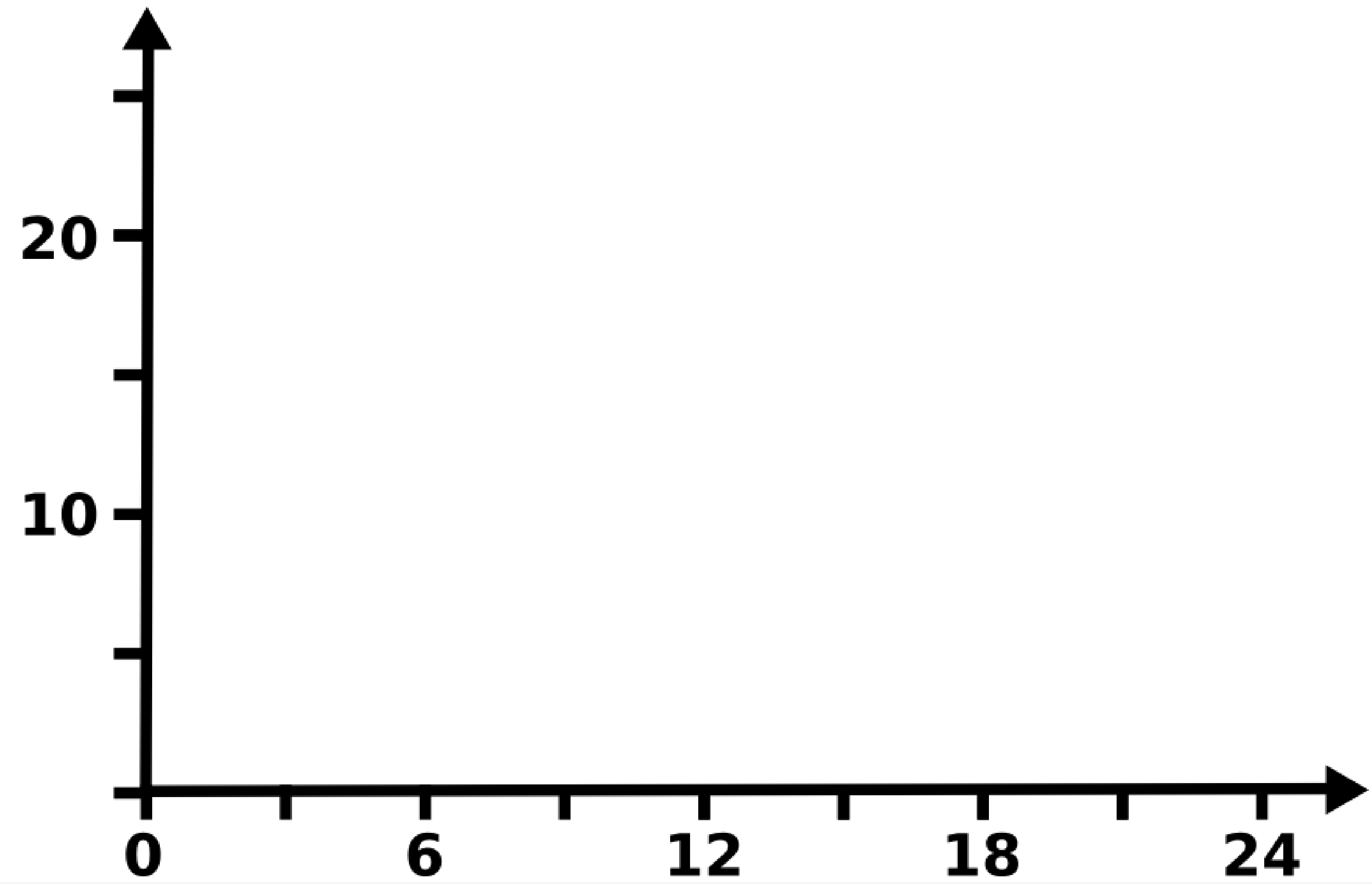
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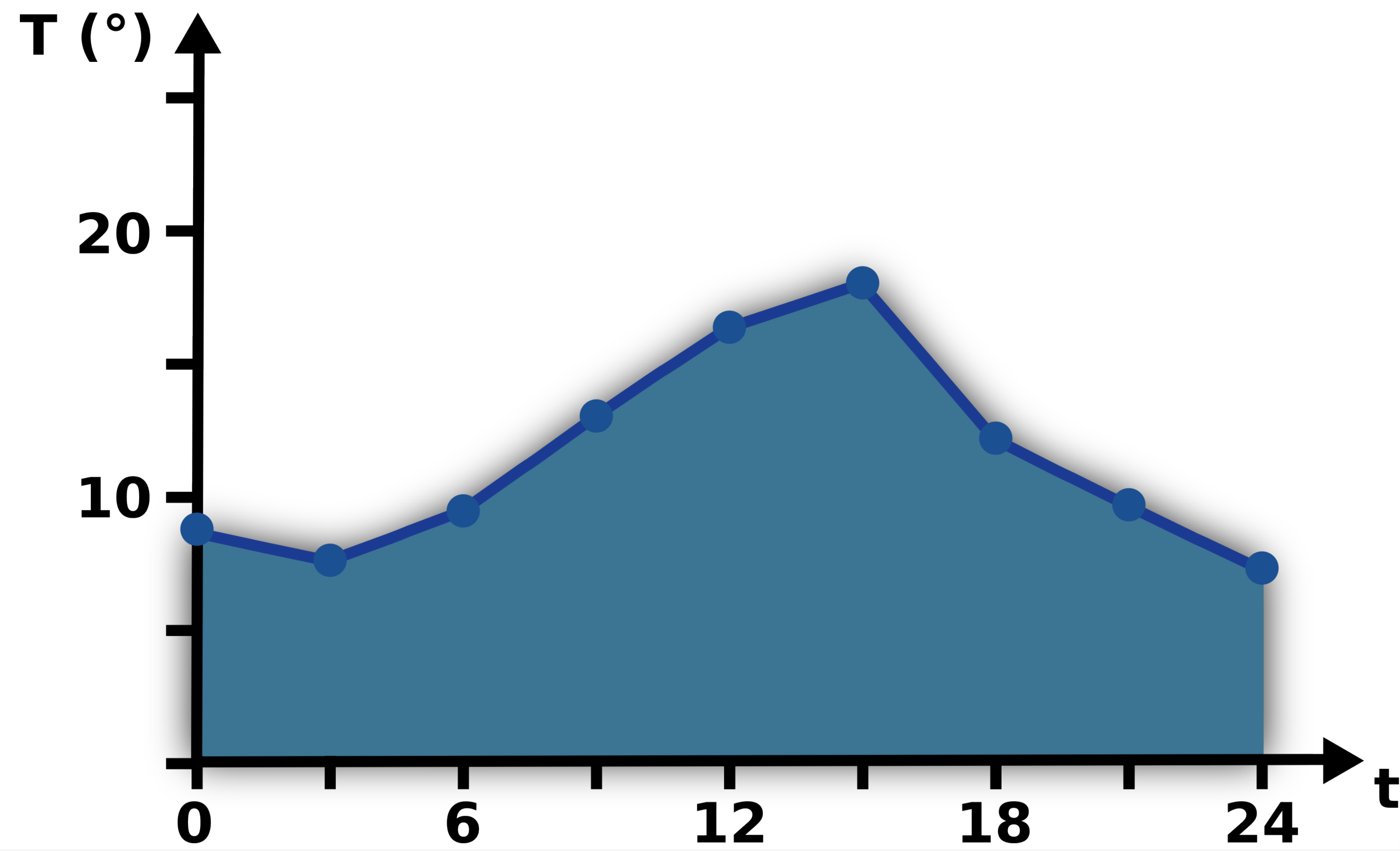
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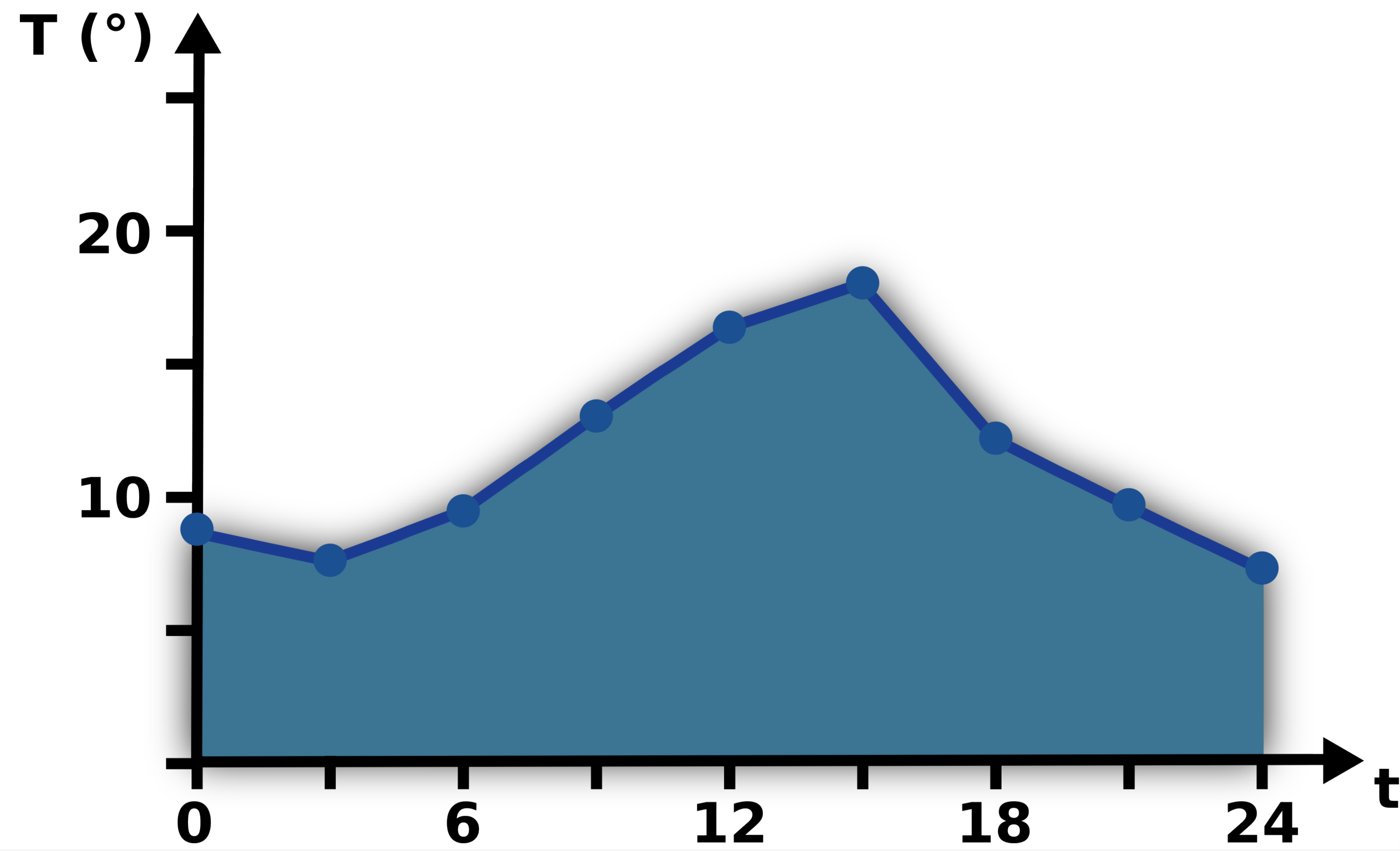
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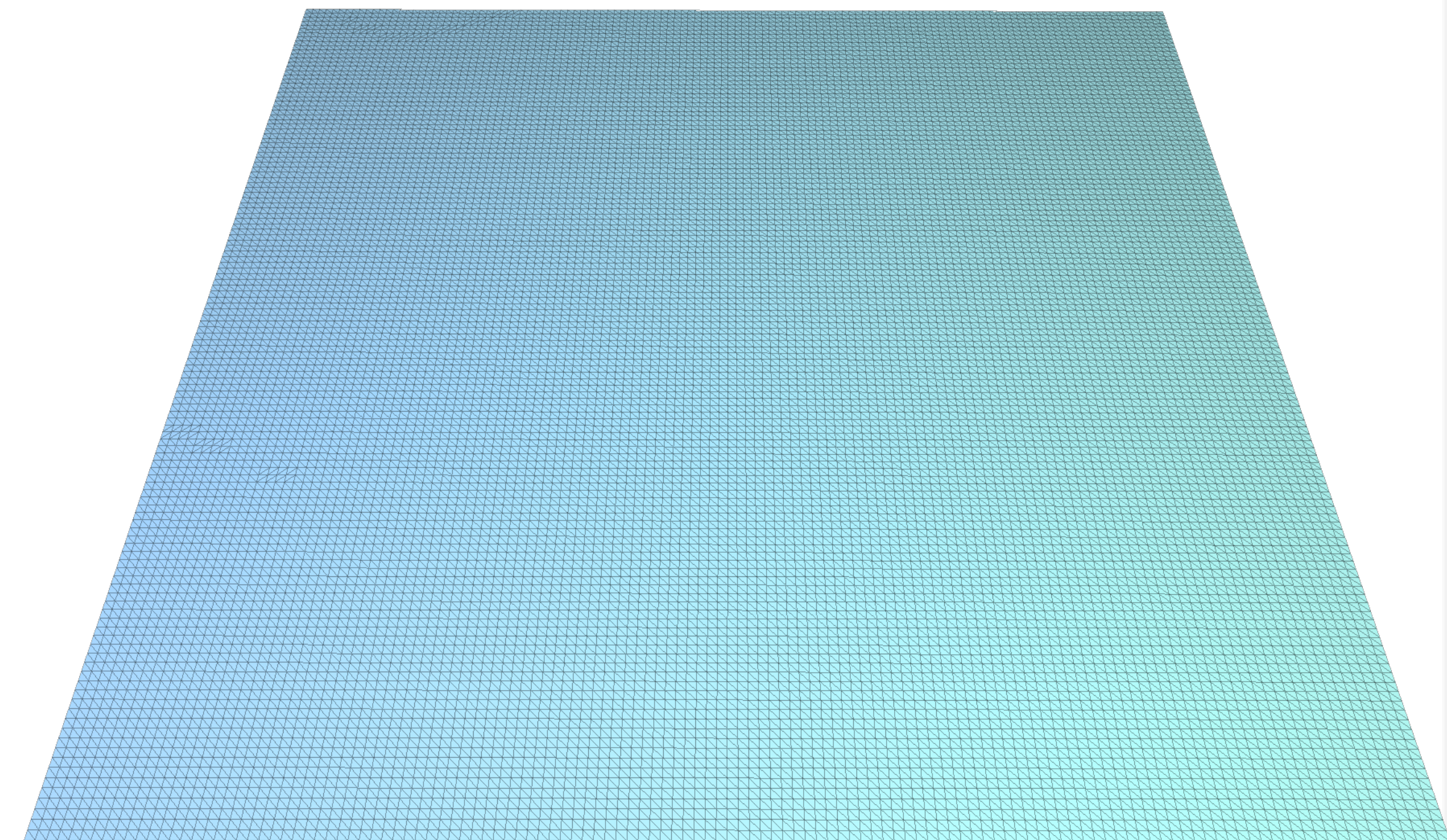
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Higher dimensional embedding

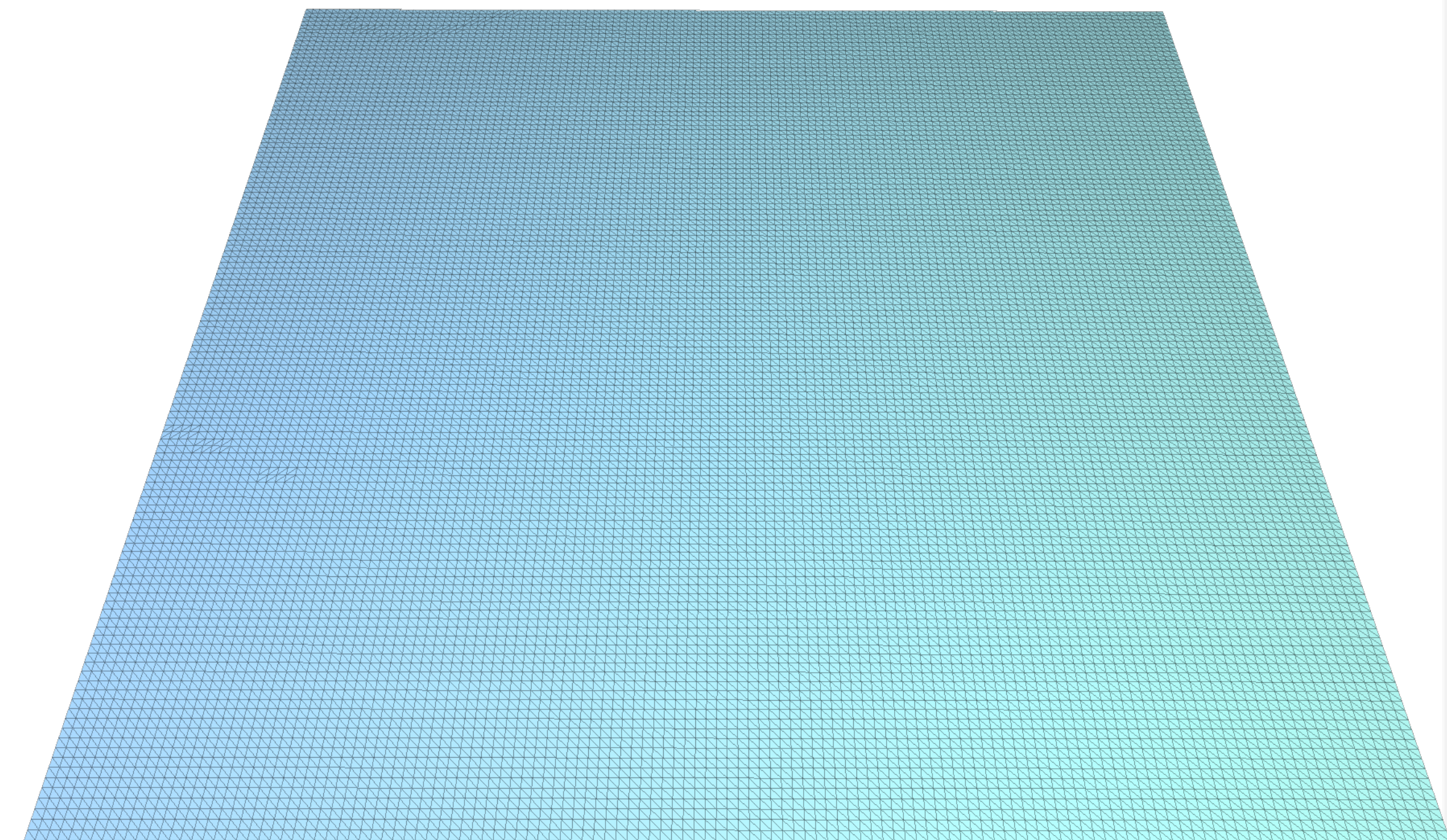
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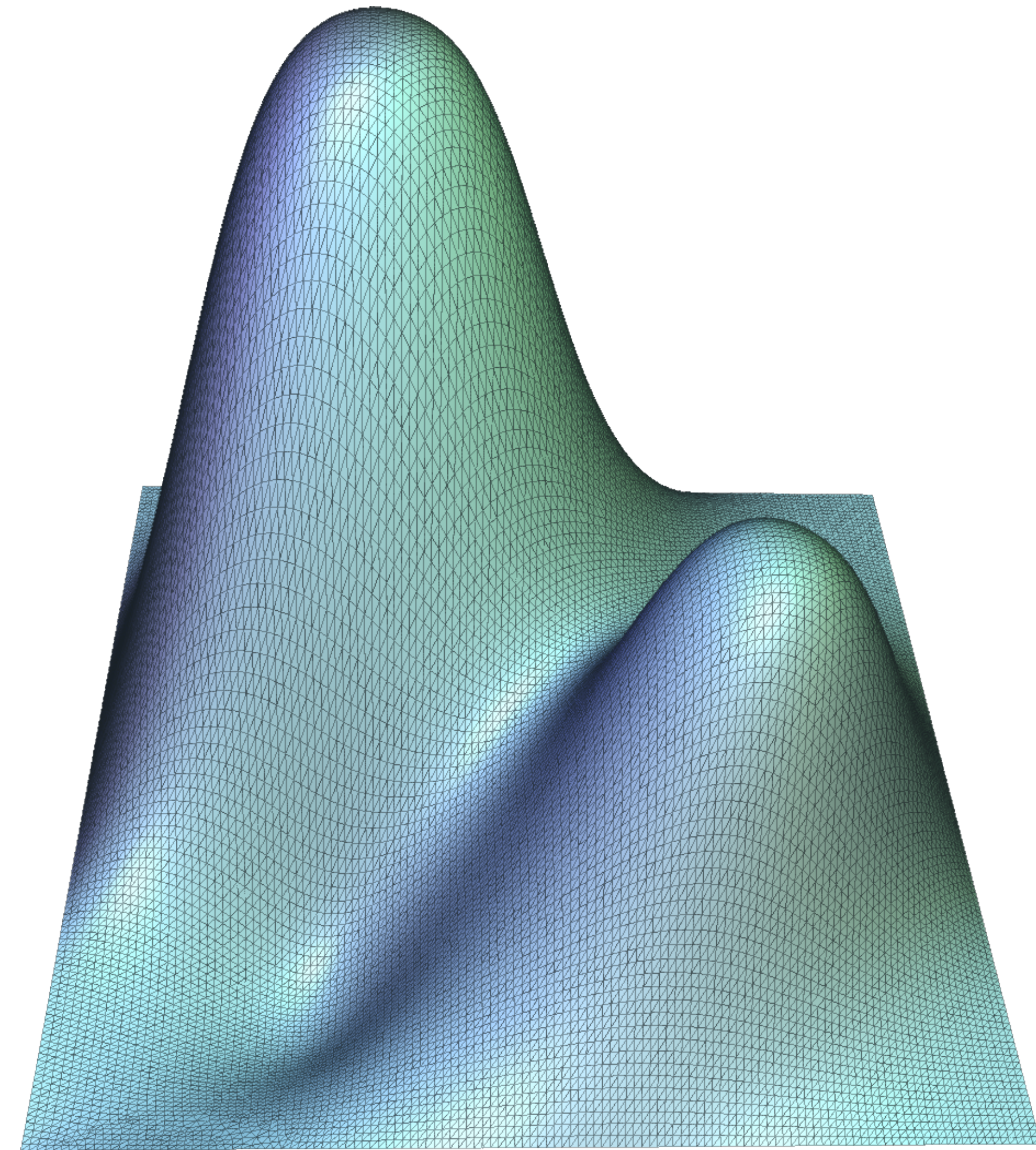
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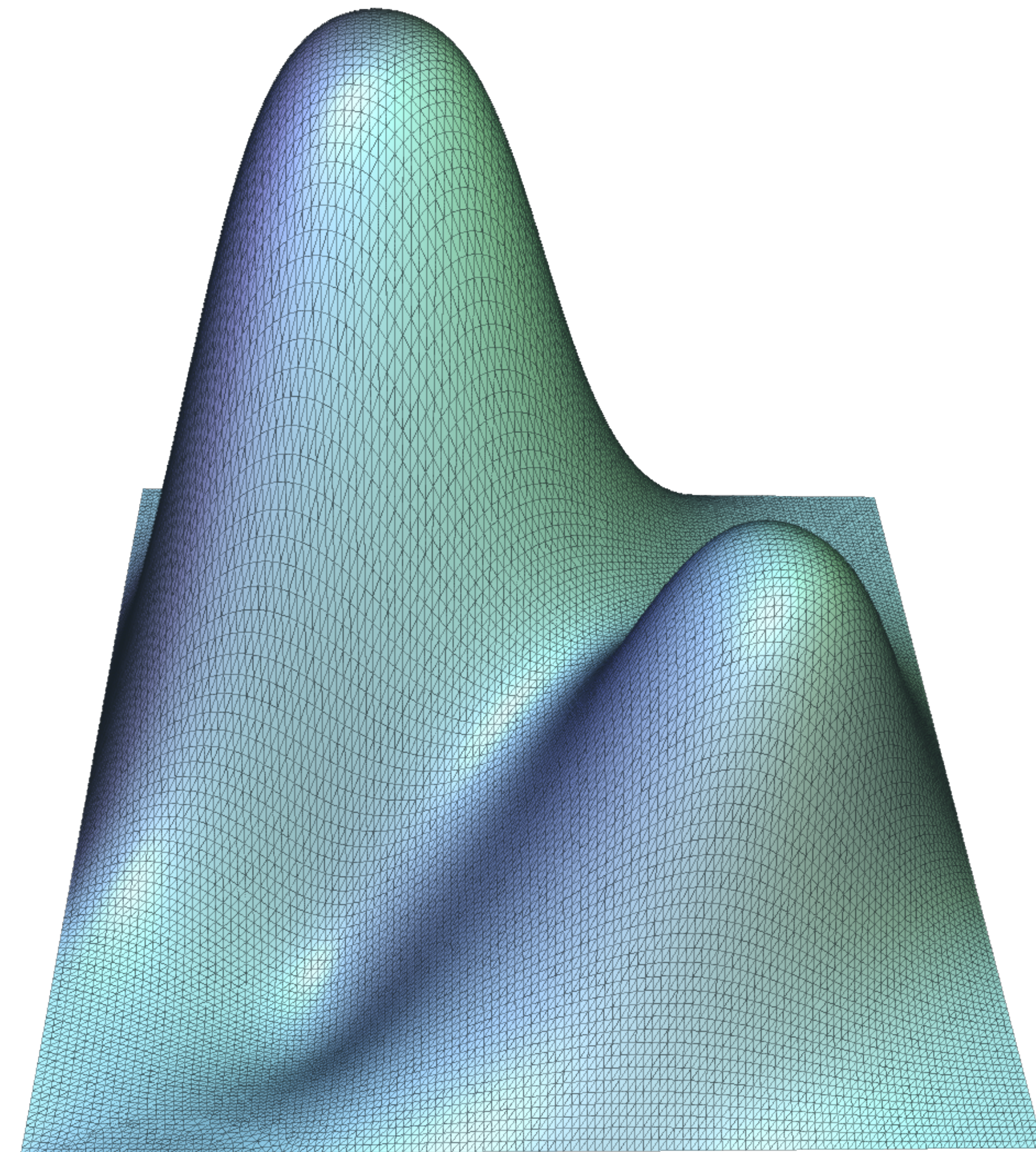
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Higher dimensional embedding

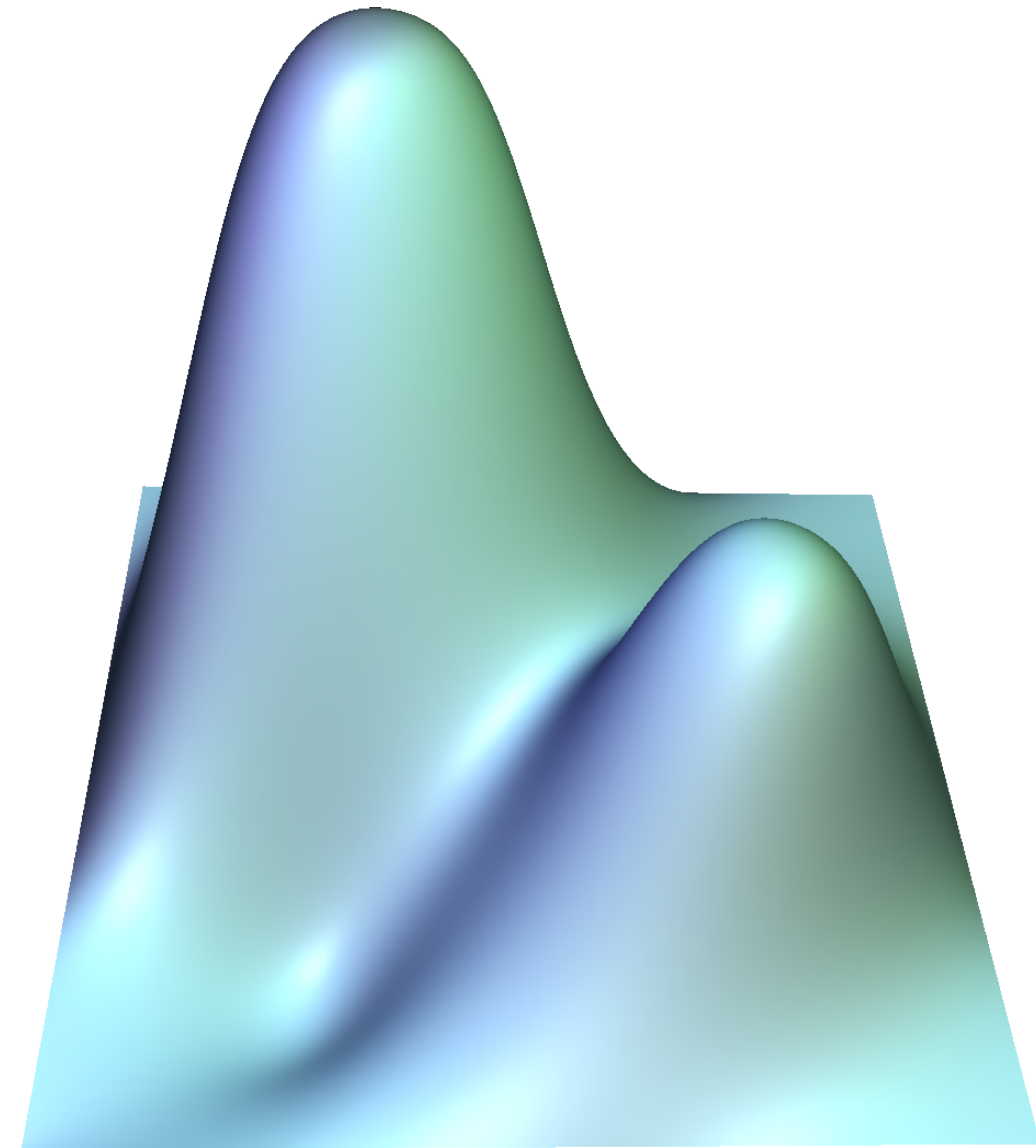
- Given 2D regular grid
 - Create a 2-triangulation embedded in \mathbb{R}^3
 - **VTK PolyData**

$$f : \mathcal{D} \subset \mathbb{R}^2 \rightarrow \mathbb{R}$$

$$x = x$$

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Recap on projective rendering

- Interactive graphics
 - Direct interaction with the GPU device driver

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 - DirectX

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- Simplistic rendering

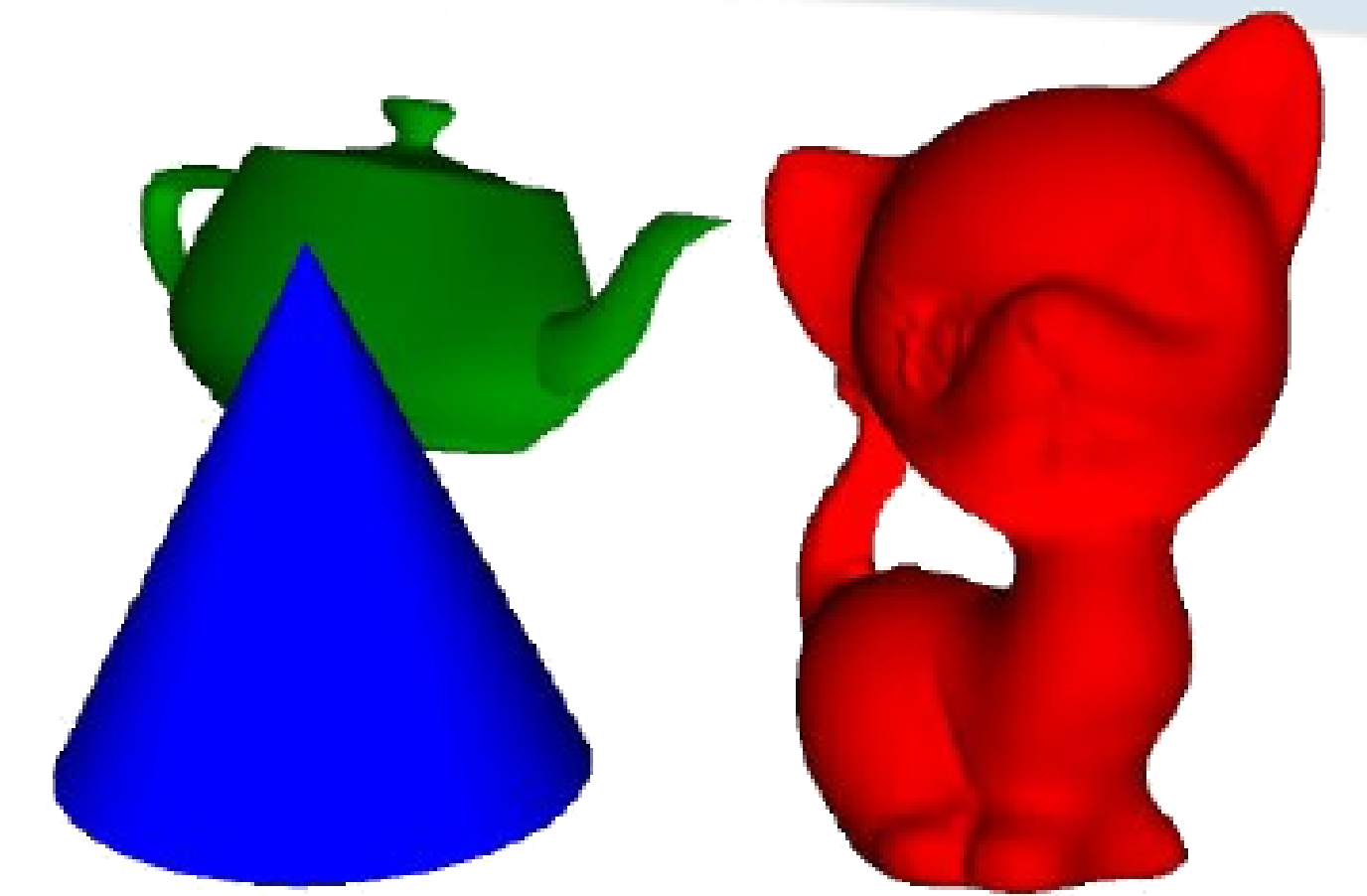
Recap on projective rendering

- Interactive graphics
 - Direct interaction with the GPU device driver
 - OpenGL
 - DirectX
- Simplistic rendering
 - Especially for light interaction simulation

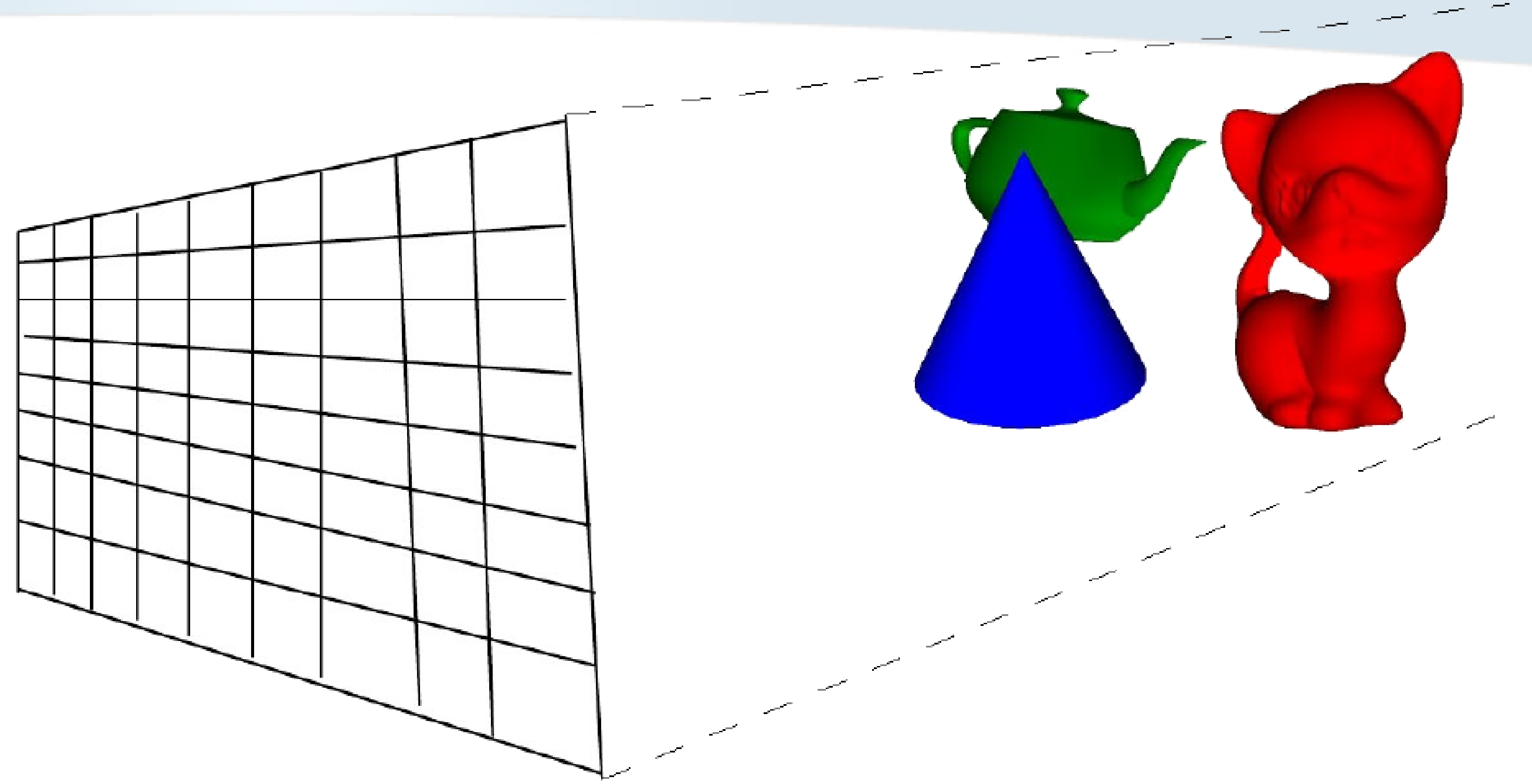
Recap on projective rendering

- Interactive graphics
 - Direct interaction with the GPU device driver
 - OpenGL
 - DirectX
- Simplistic rendering
 - Especially for light interaction simulation
 - Guarantees interactive feedback

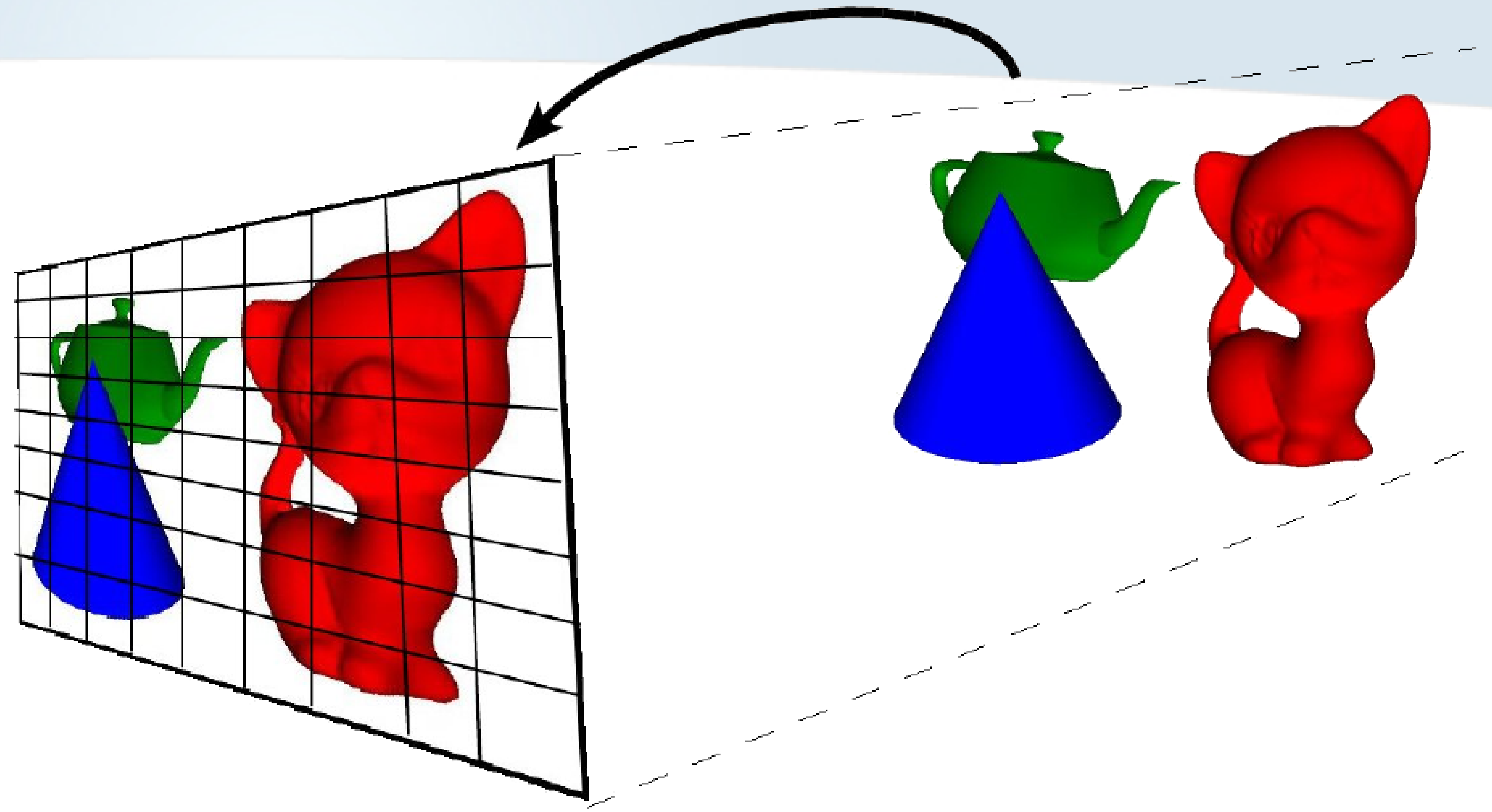
Recap on projective rendering



Recap on projective rendering

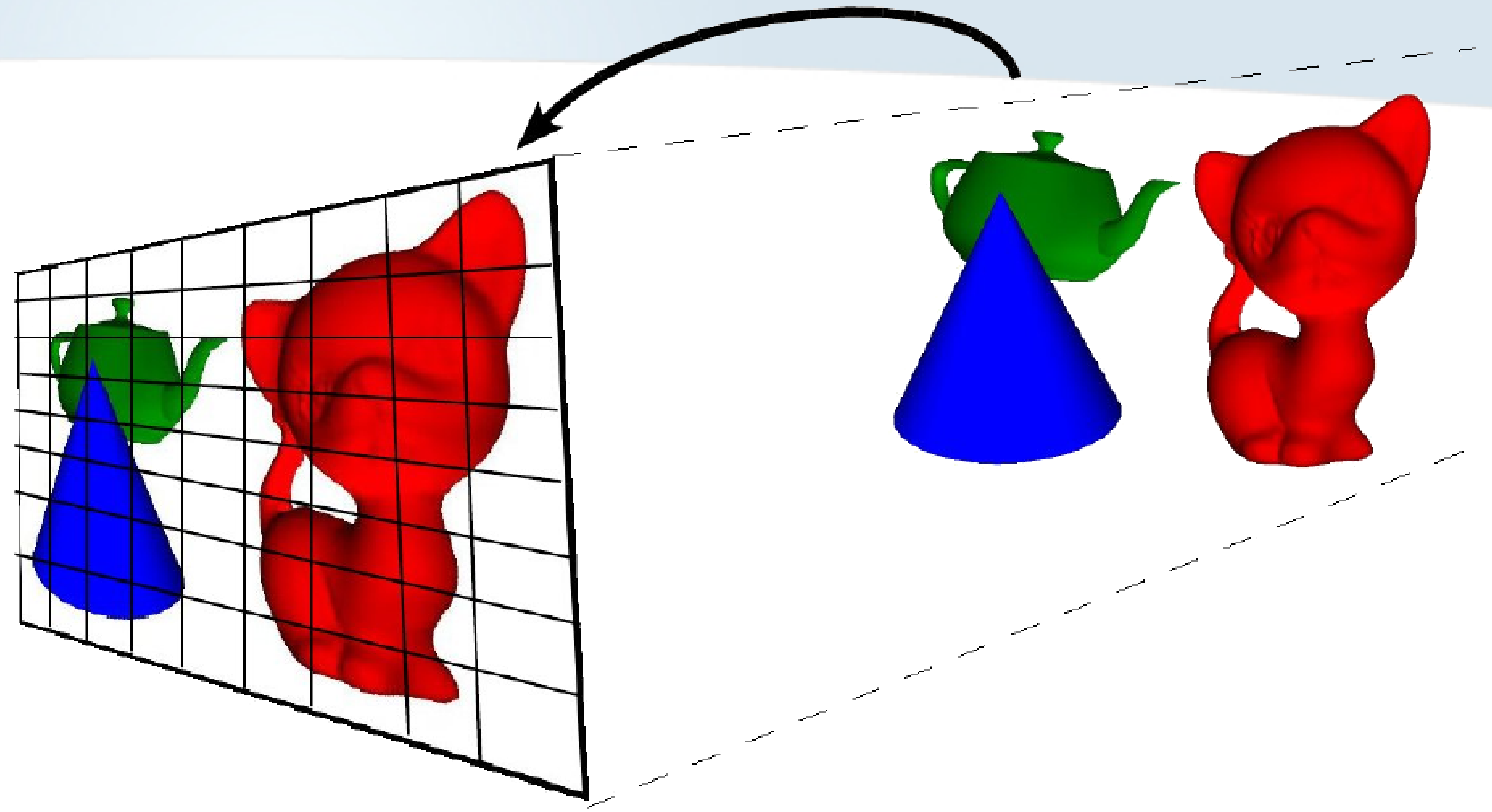


Recap on projective rendering



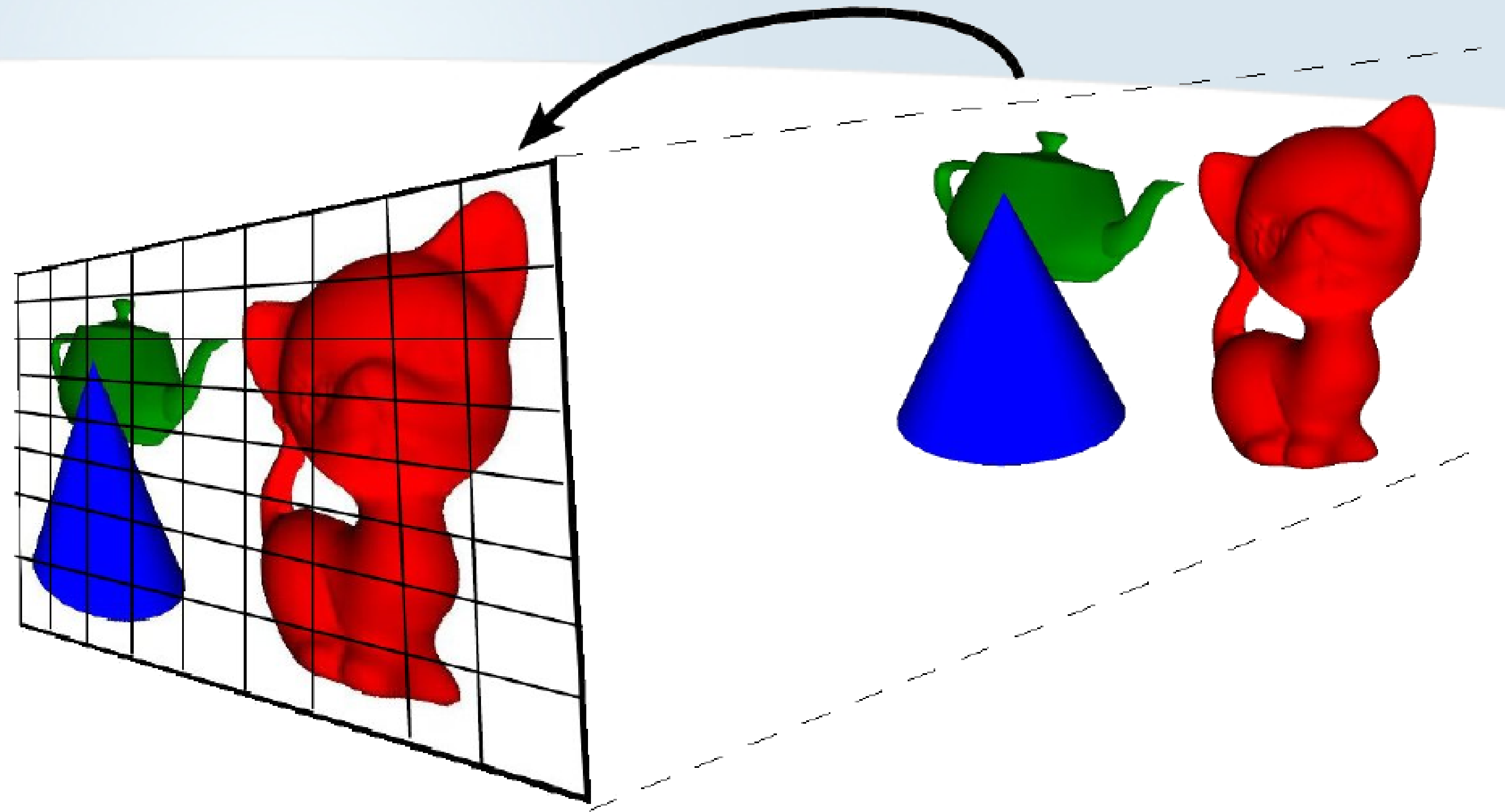
Recap on projective rendering

- Position matrices



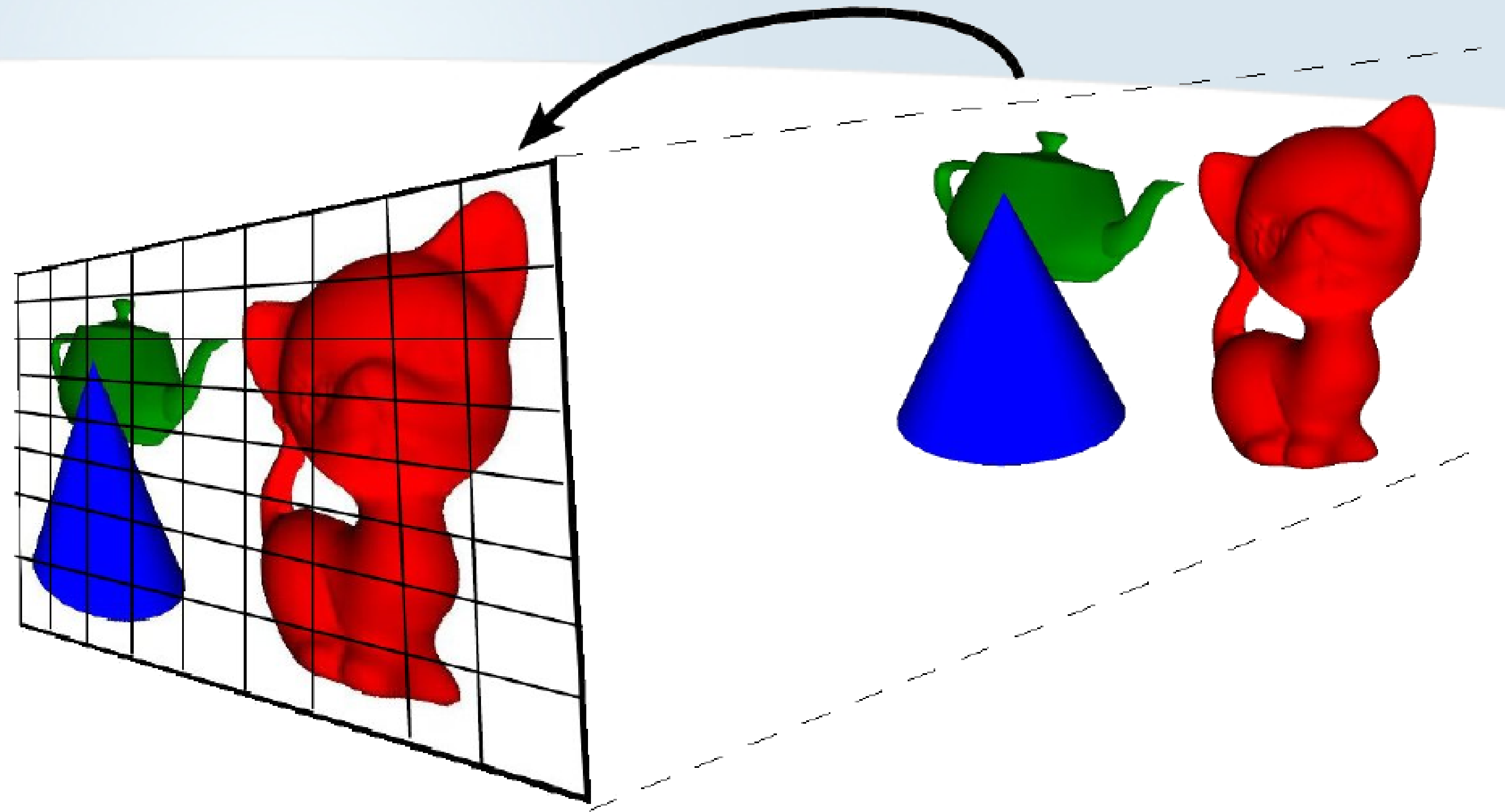
Recap on projective rendering

- Position matrices
- Color and light computation



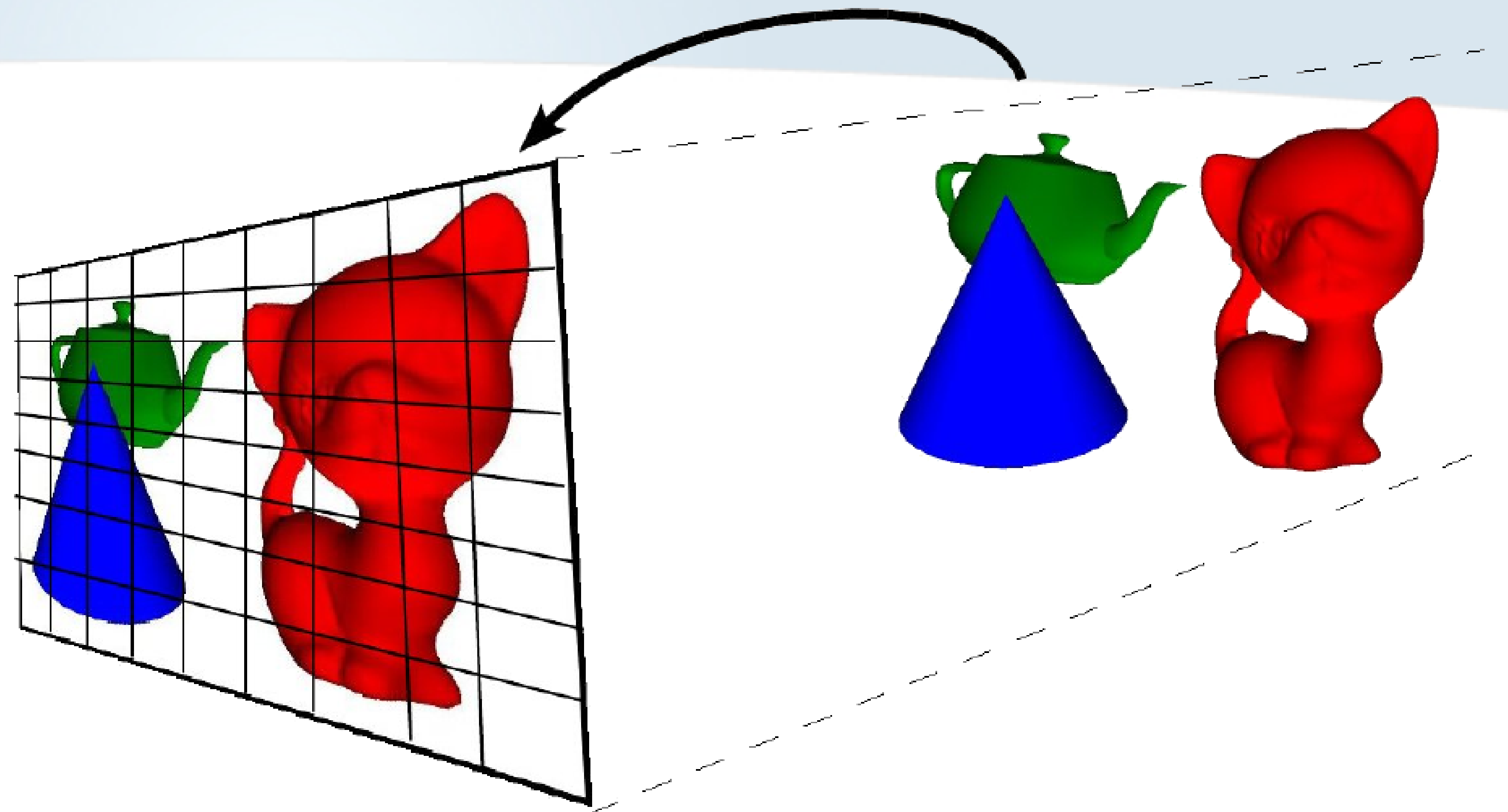
Recap on projective rendering

- Position matrices
- Color and light computation
- Projection matrix (camera)



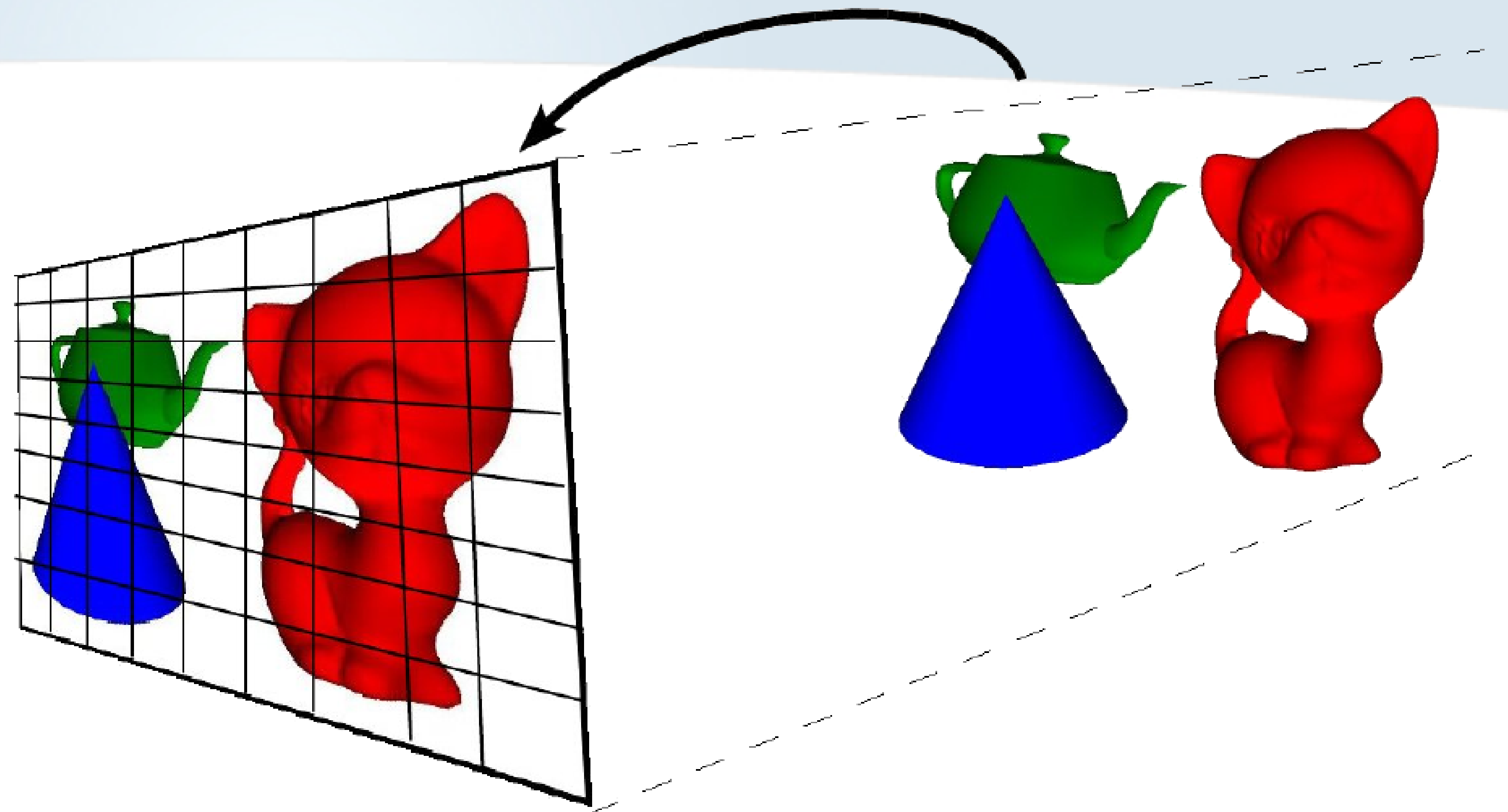
Recap on projective rendering

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 - **Matrix multiplication**



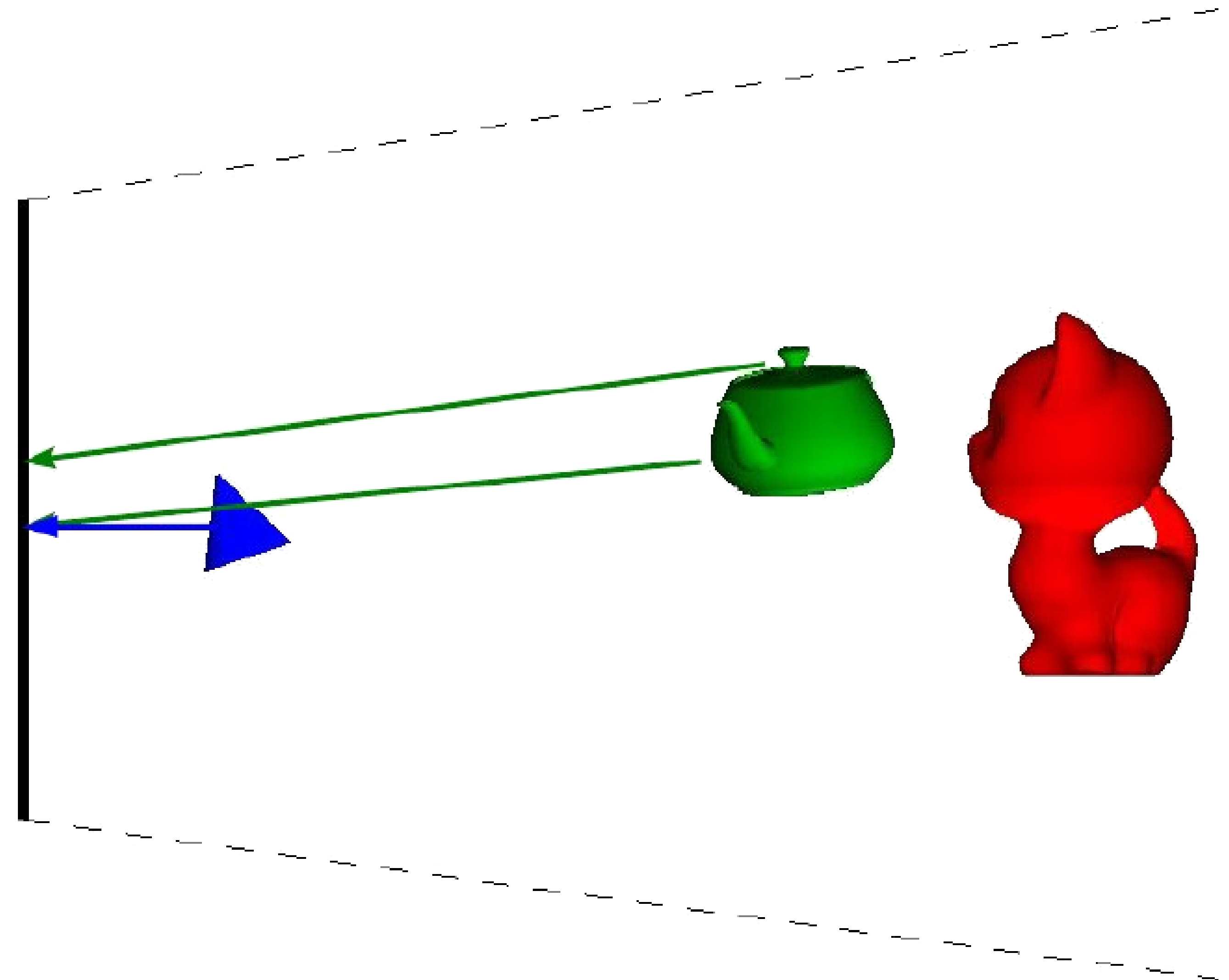
Recap on projective rendering

- Position matrices
- Color and light computation
- Projection matrix (camera)
 - **Matrix multiplication**
- Screen-space tests



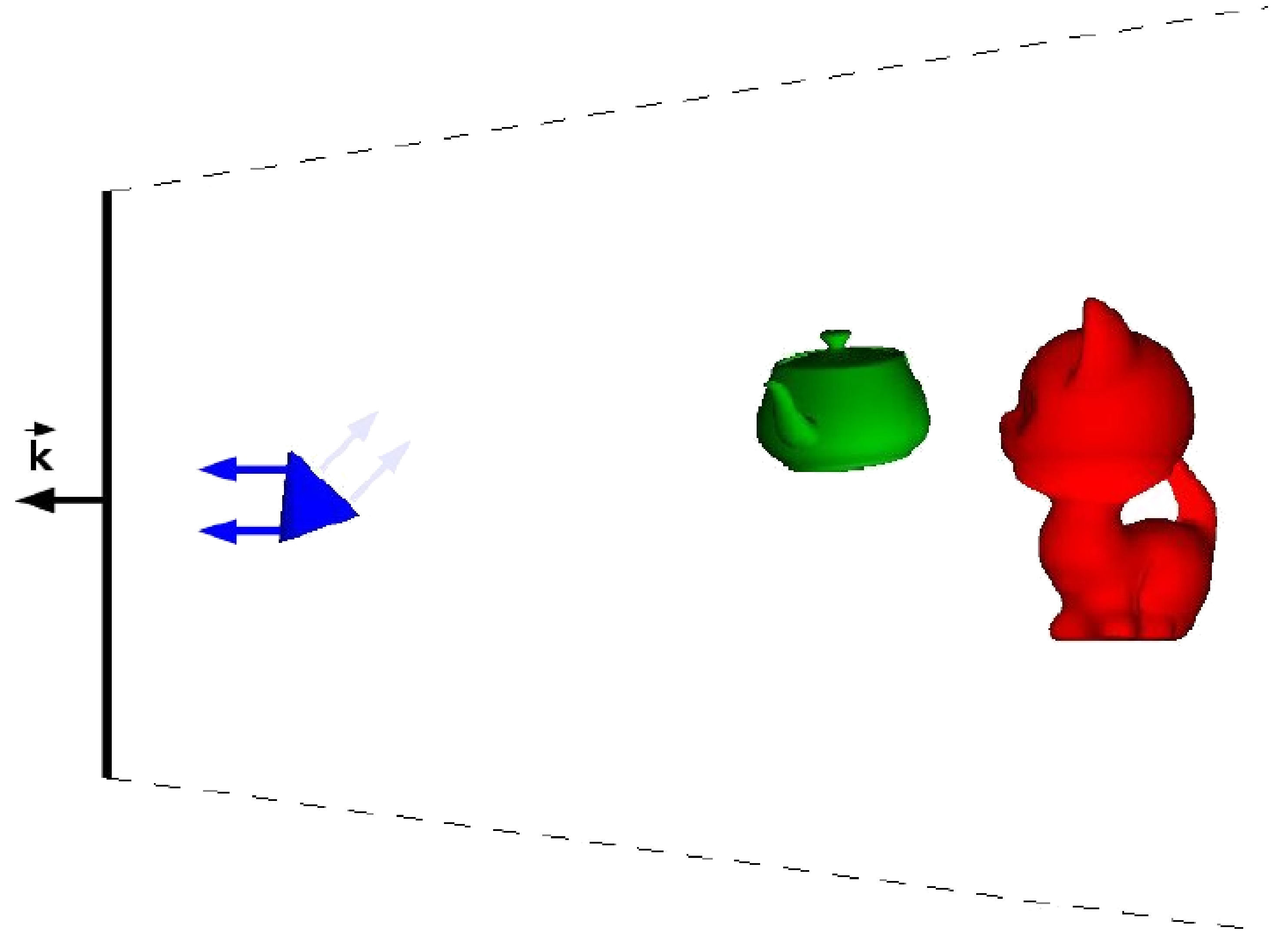
Recap on projective rendering

- Screen-space tests
 - Among others
 - Depth buffer
 - Back-face culling



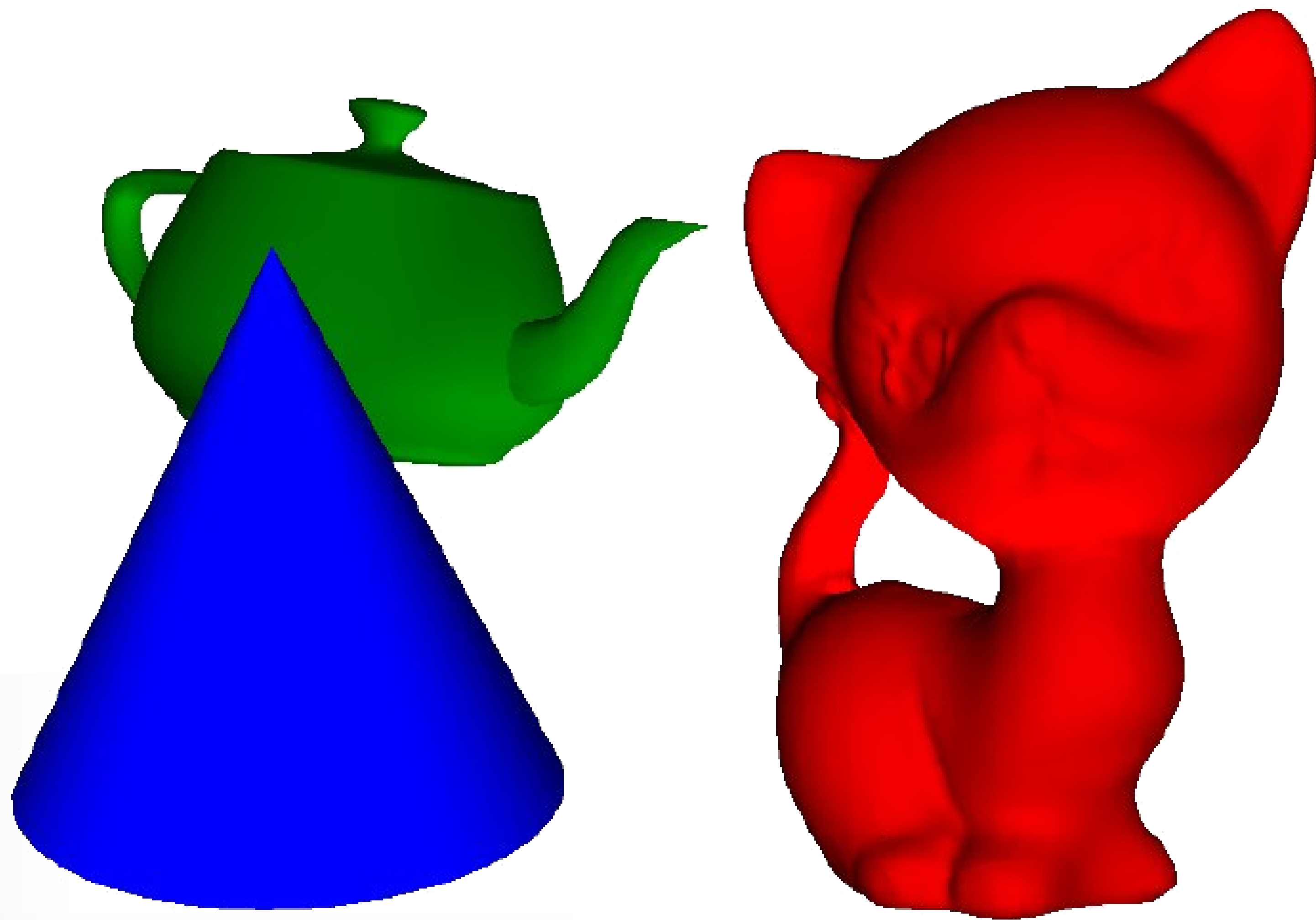
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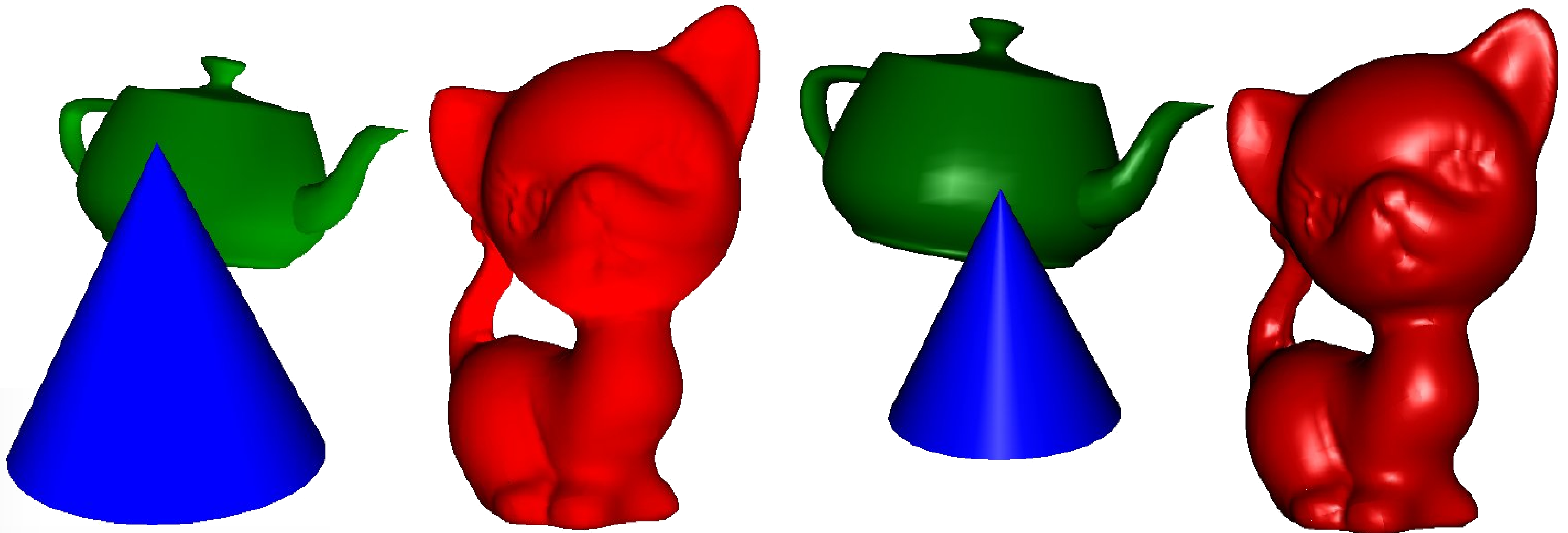
Recap on projective rendering

- Light modeling



Recap on projective rendering

- Light modeling

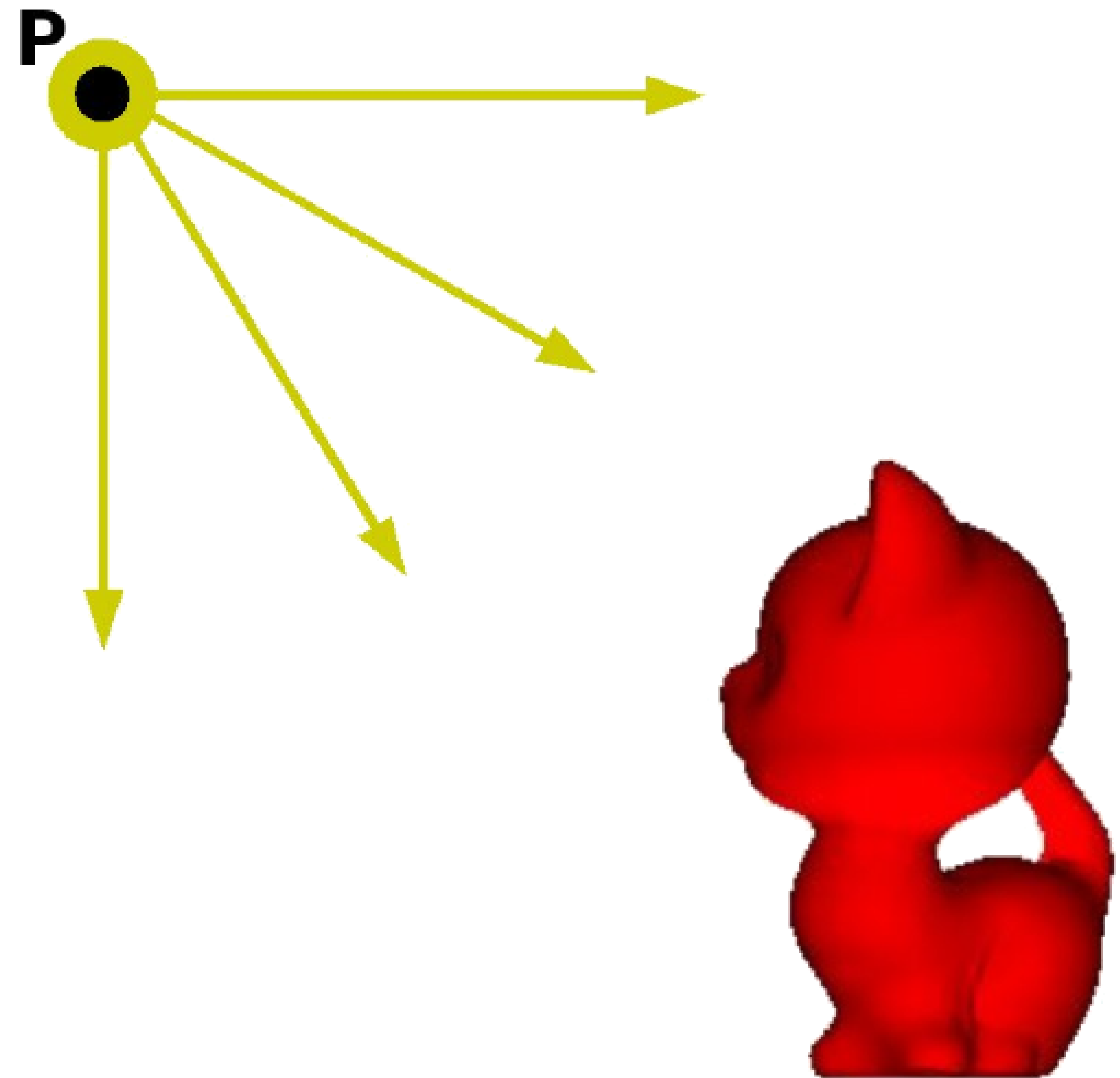


Recap on projective rendering

- Light modeling
 - Local model

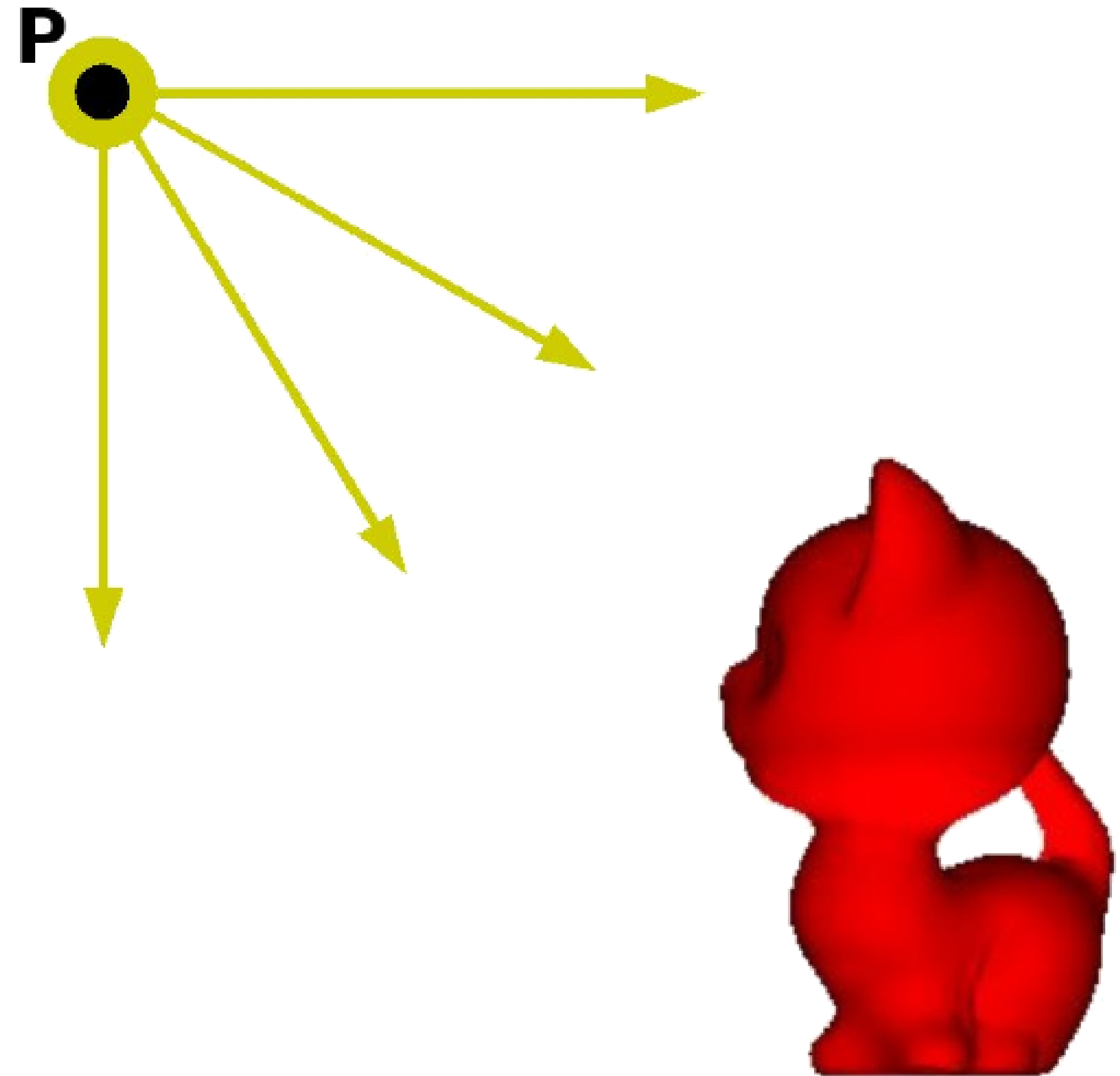
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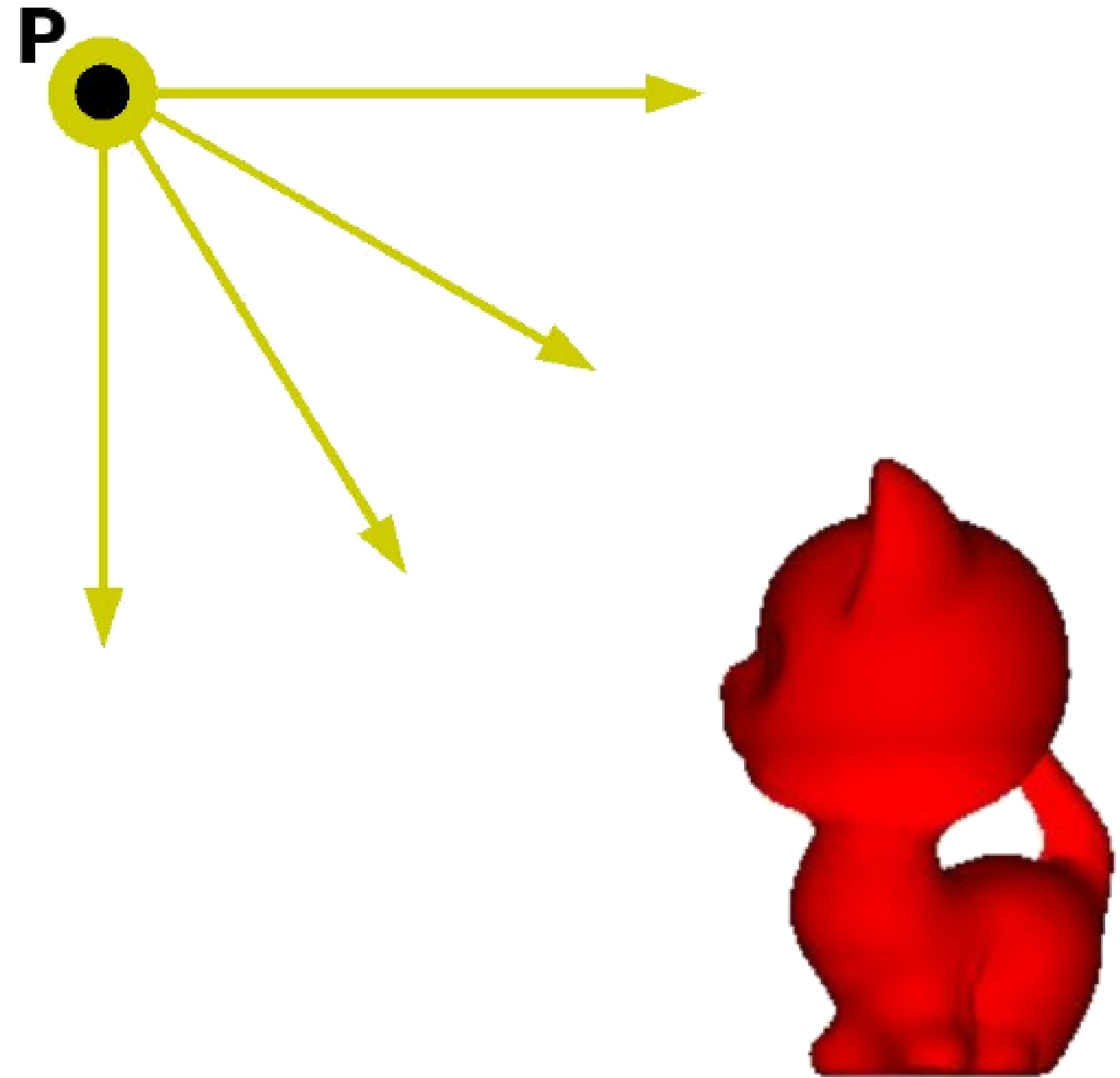
Recap on projective rendering

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 - Local model
 - Each object independently
 - Each polygon independently



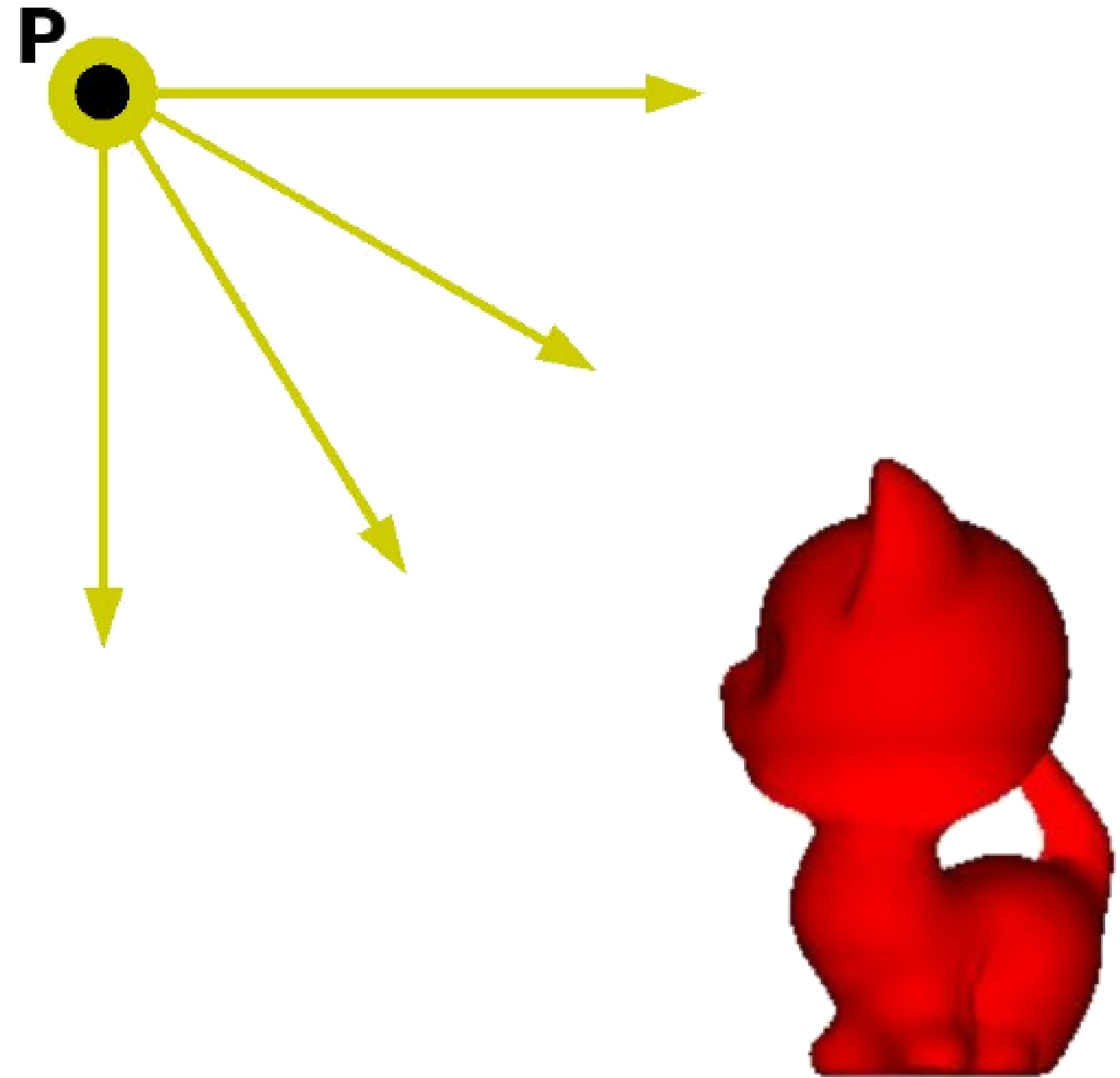
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 - Local model
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 - No shadow
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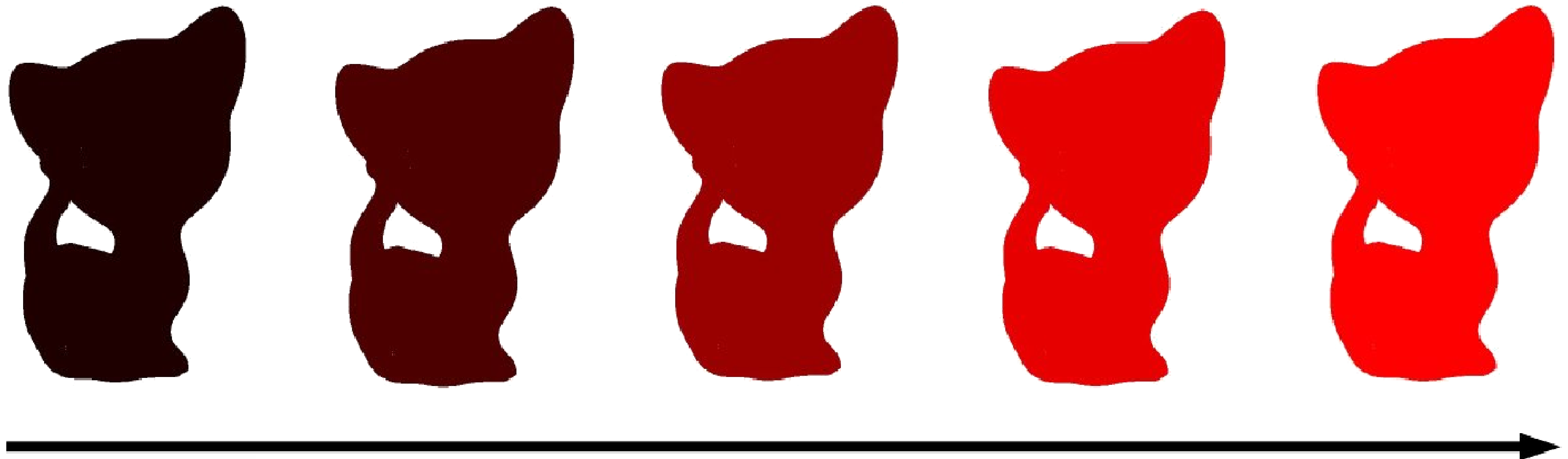
Recap on projective rendering

- Light modeling
 - Local model
 - Each object independently
 - Each polygon independently
 - No shadow
 - No inter-object interaction
- Ambient attributes
- Diffuse attributes
- Specular attributes



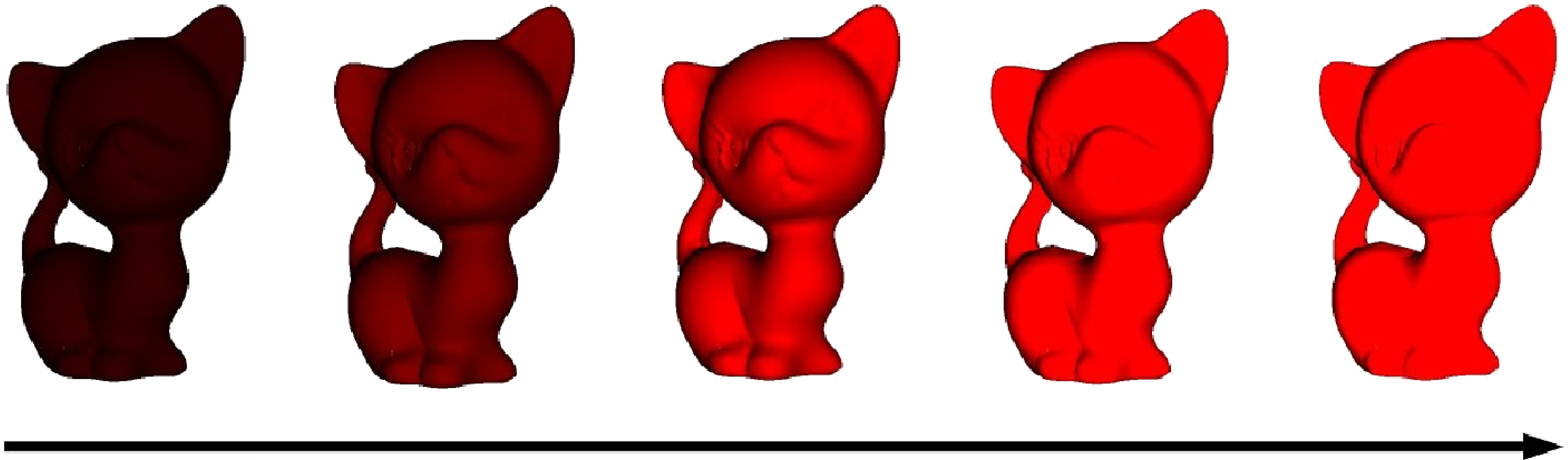
Recap on projective rendering

- Ambient contribution (the color of the object, per RGB channel)
 - $C_A(p) = k_a \times I_a$



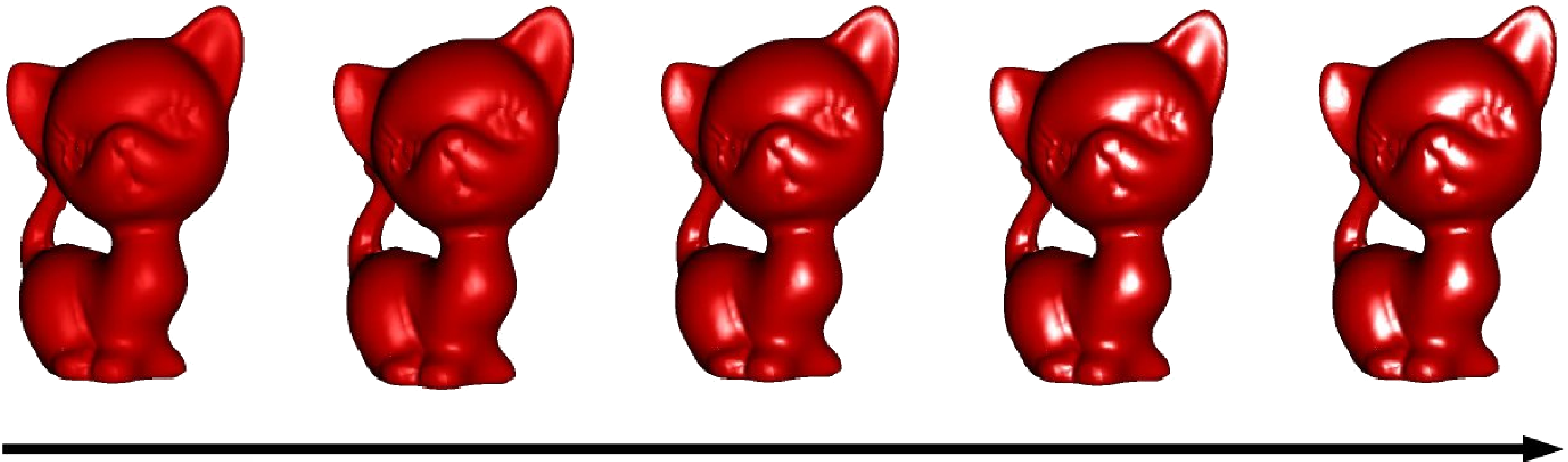
Recap on projective rendering

- Diffuse contribution (per RGB channel)
 - $C_D(p) = I_d \times k_d \times \cos(\vec{N}, \vec{L})$ if $\vec{N} \cdot \vec{L} \geq 0$



Recap on projective rendering

- Diffuse contribution (per RGB channel)
 - $C_S(p) = I_s \times k_s \times \cos(\vec{V}, \vec{R})^{Sh}$



Higher dimensional embedding

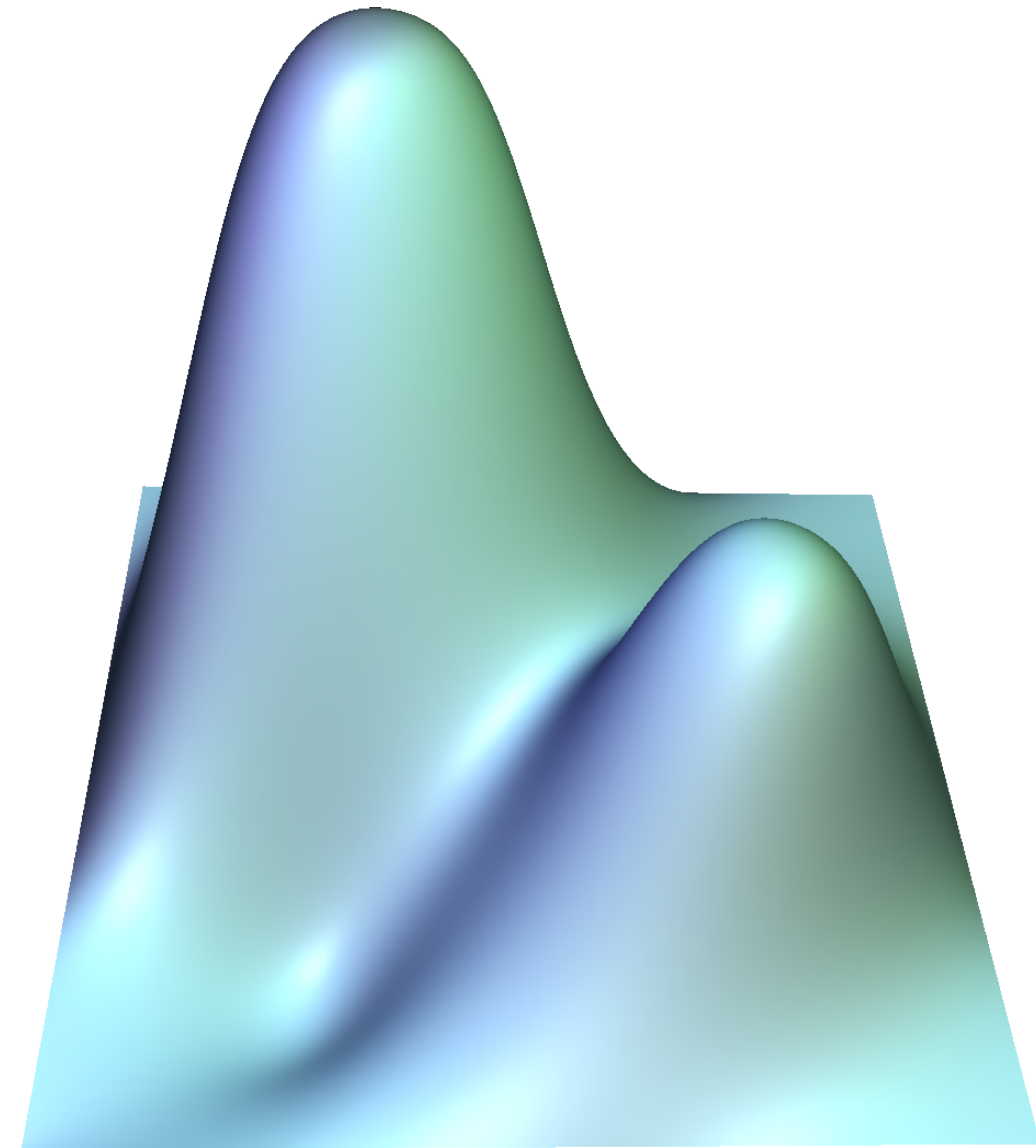
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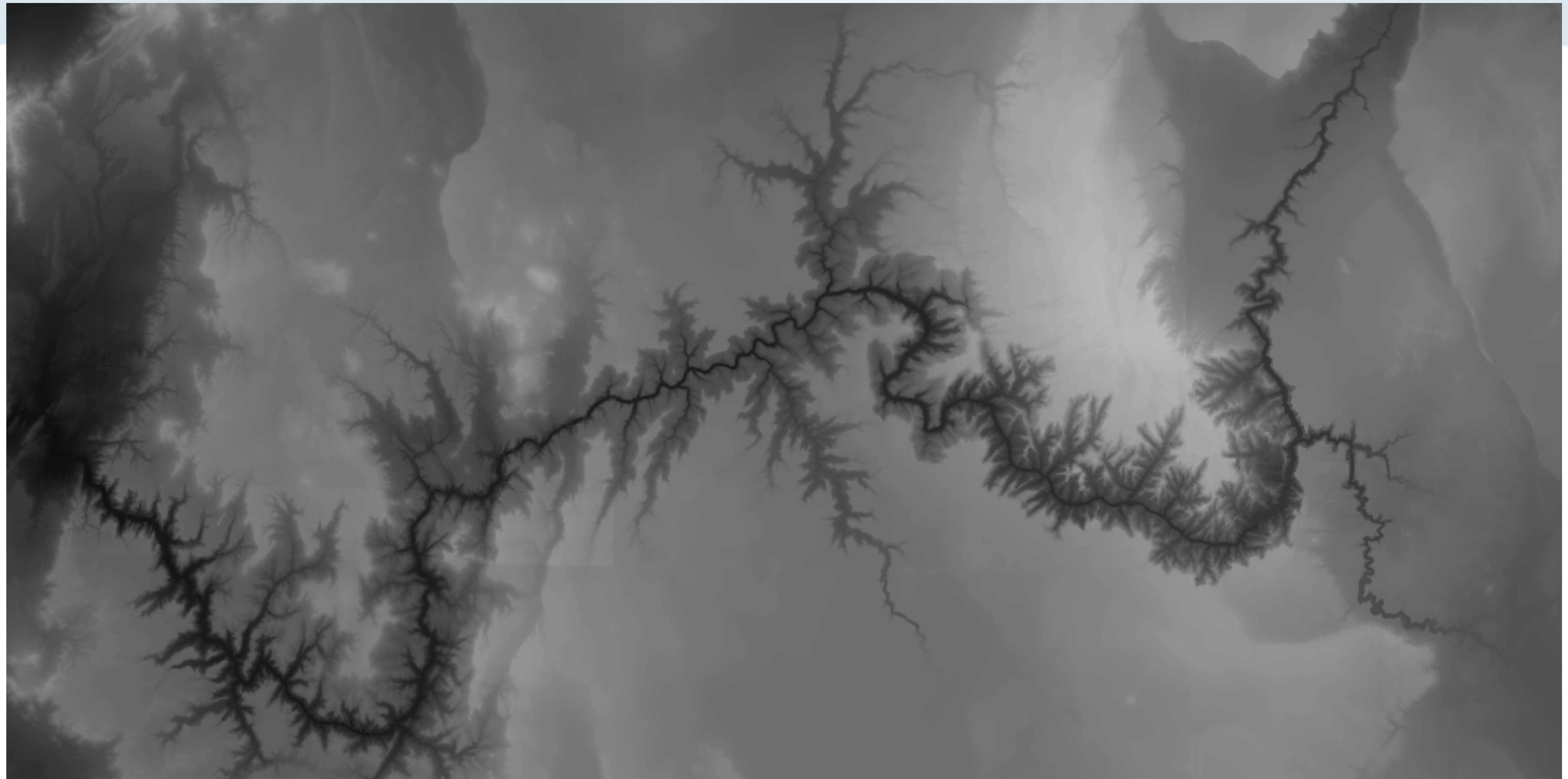
$$y = y$$

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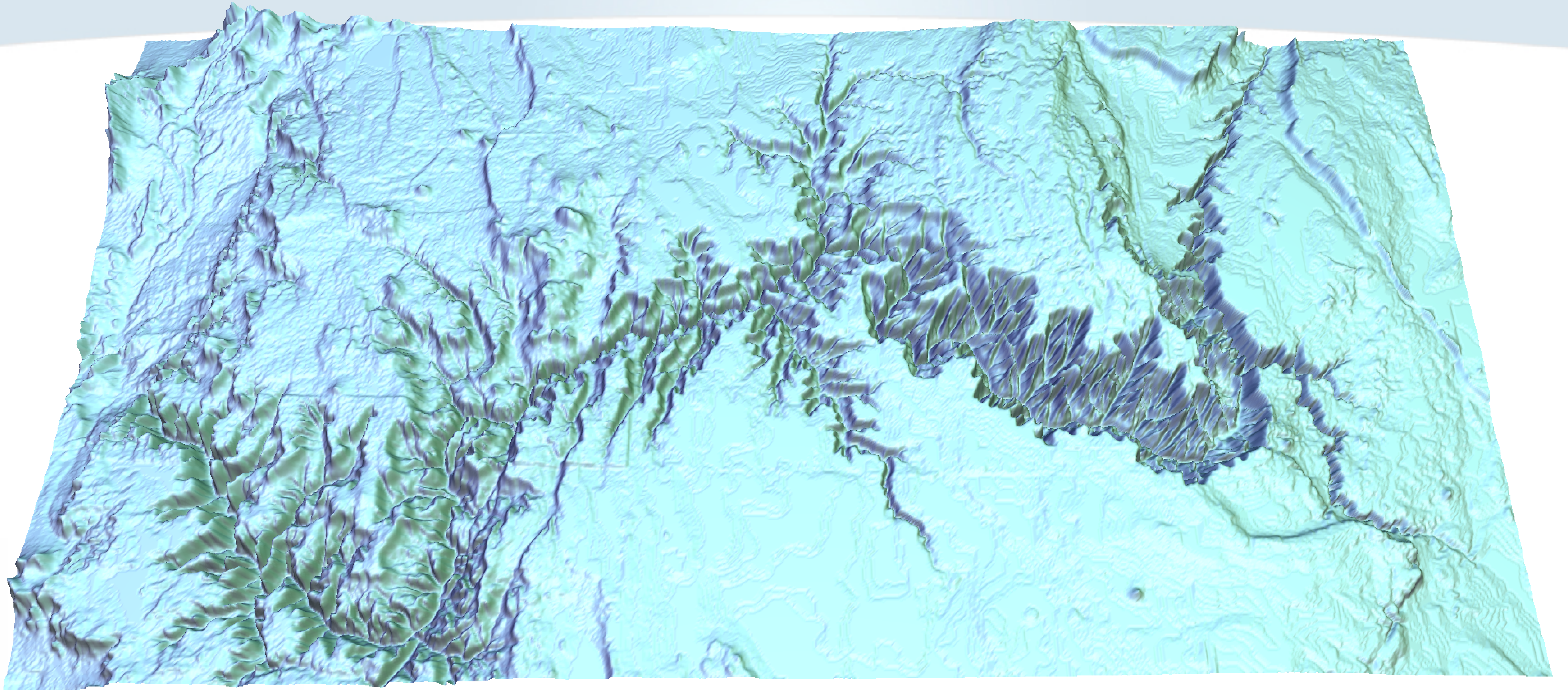


Elevation data-sets

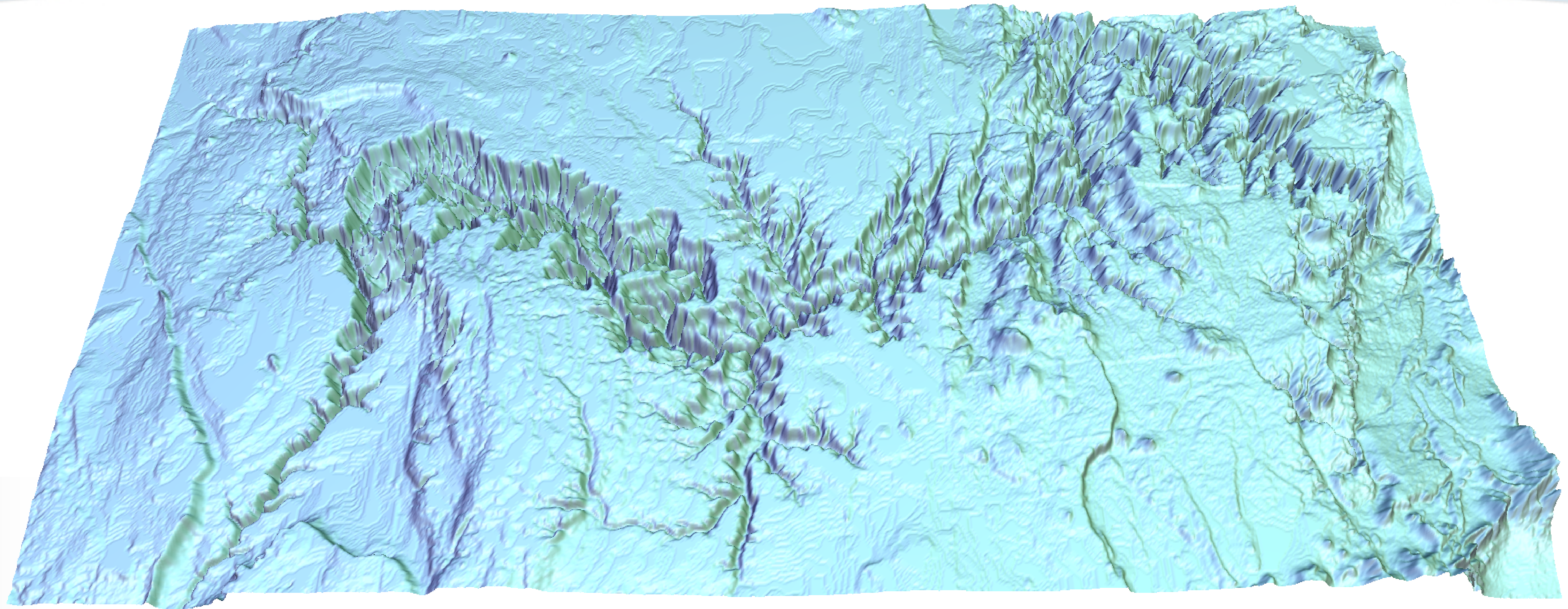
Elevation data-sets



Elevation data-sets

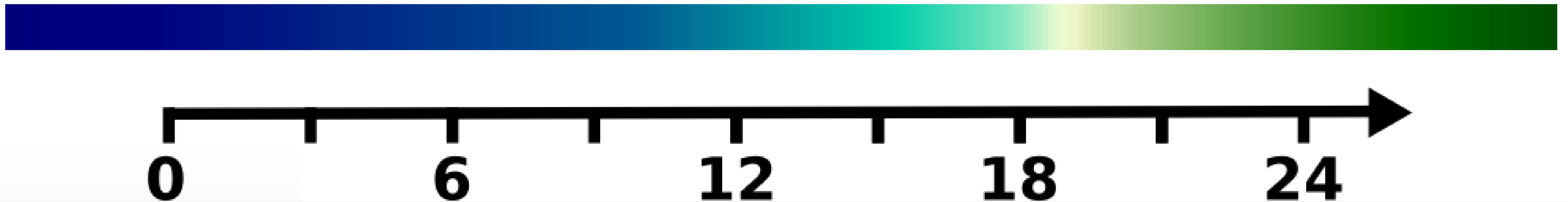


Elevation data-sets



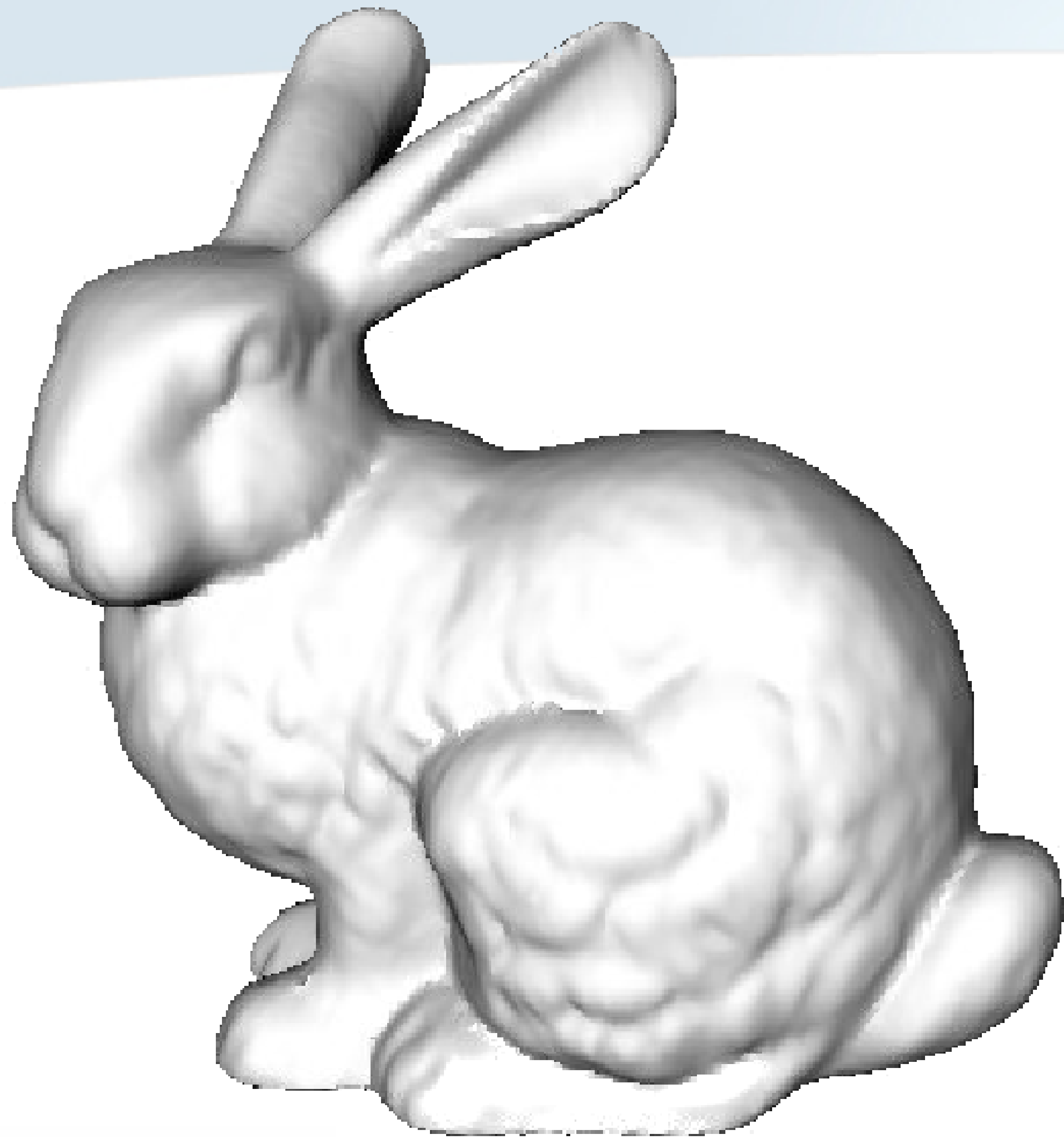
Additional information channels

- Domain with an embedding to \mathbb{R}^3
 - How can we encode scalar values?
- Intuitive idea
 - Use a perceptual channel **Color maps**
 - Arrange continuously a palette of colors
 - Map it to the real line (\mathcal{A})

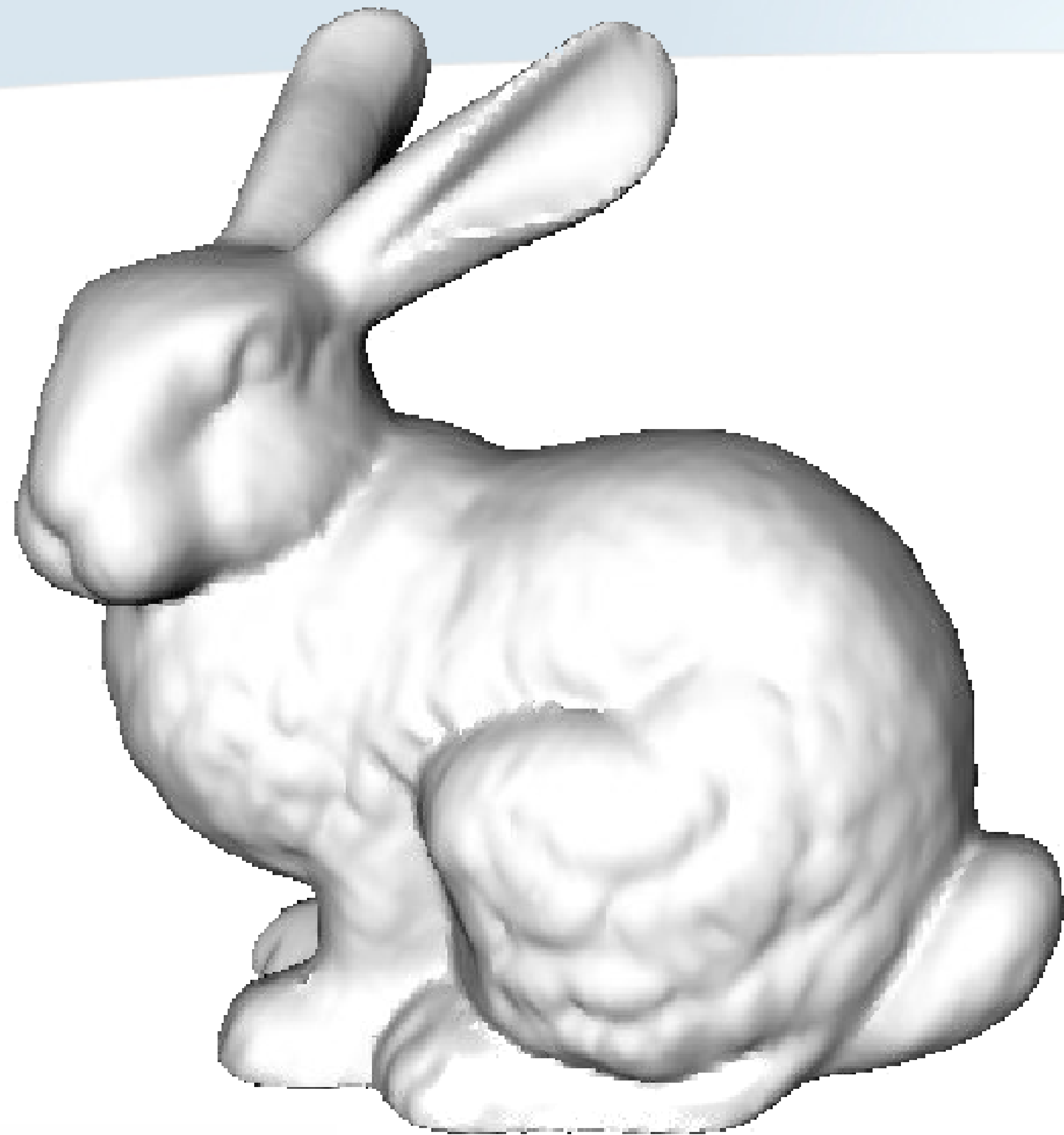


Recap on texture mapping

Recap on texture mapping



Recap on texture mapping



Recap on texture mapping

- Surface parameterization



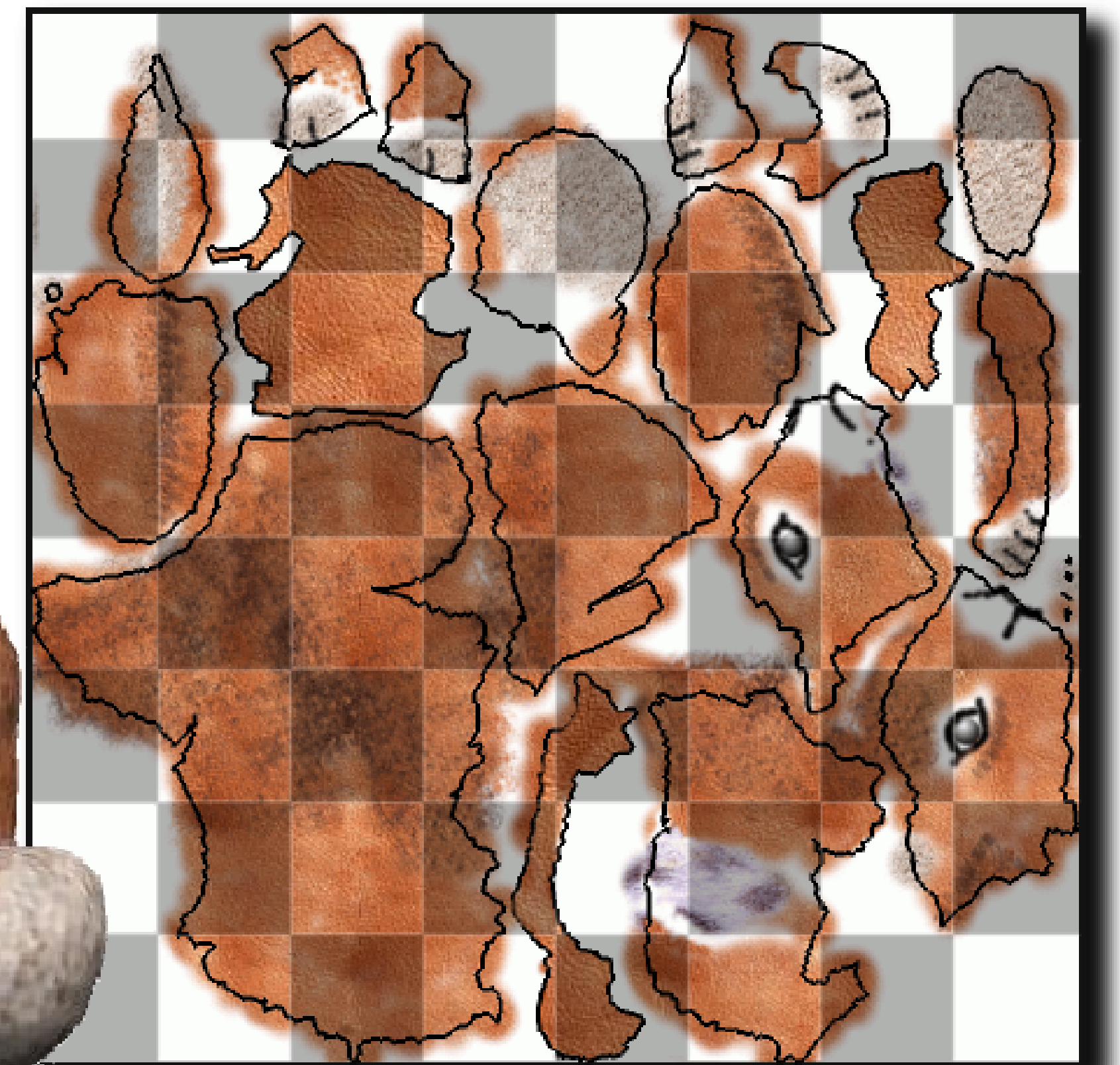
Recap on texture mapping

- Surface parameterization
 - Bijective map
 - $\phi : \mathcal{S}_i \subset \mathcal{S} \rightarrow \mathcal{D} \subset \mathbb{R}^2$



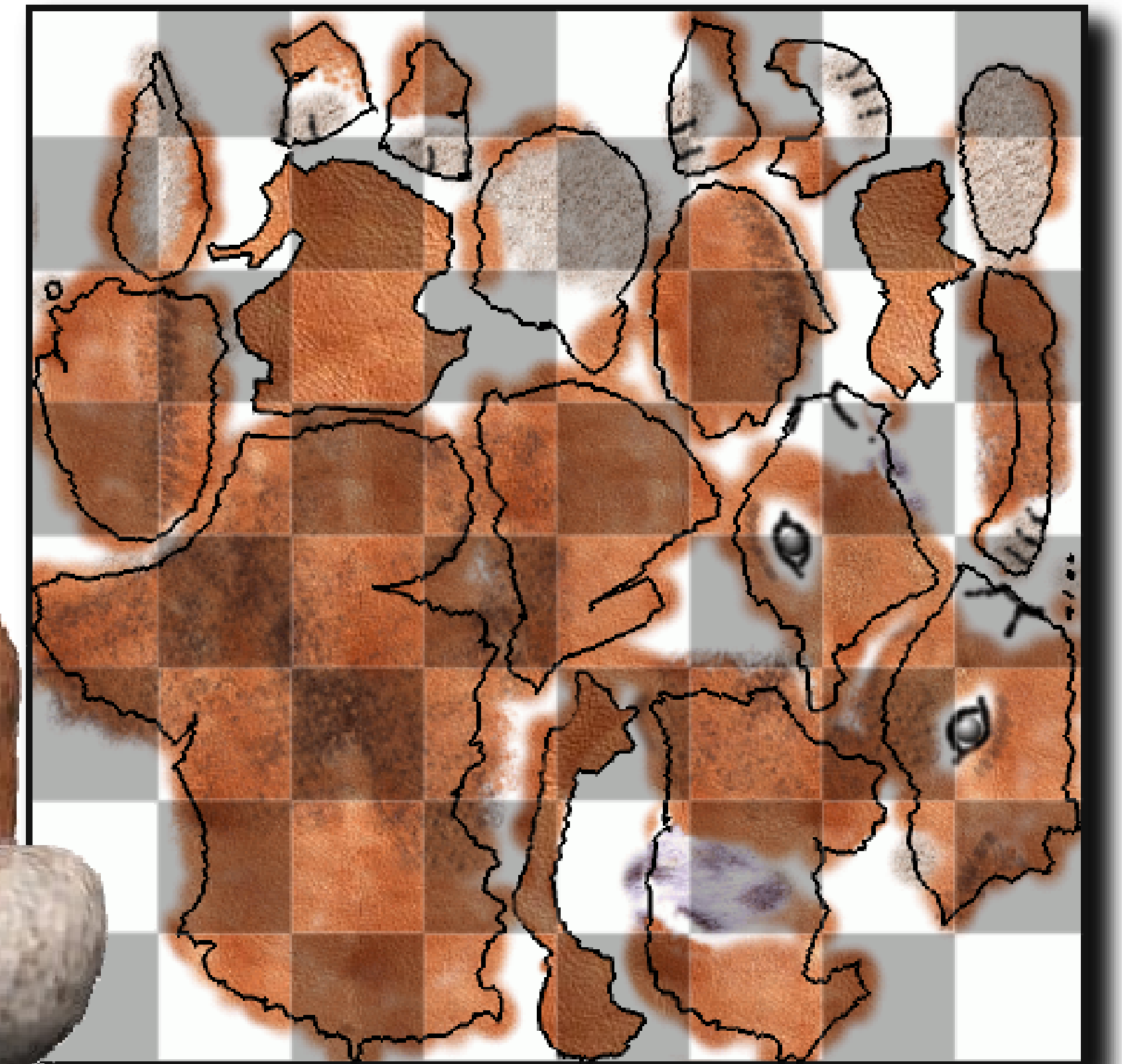
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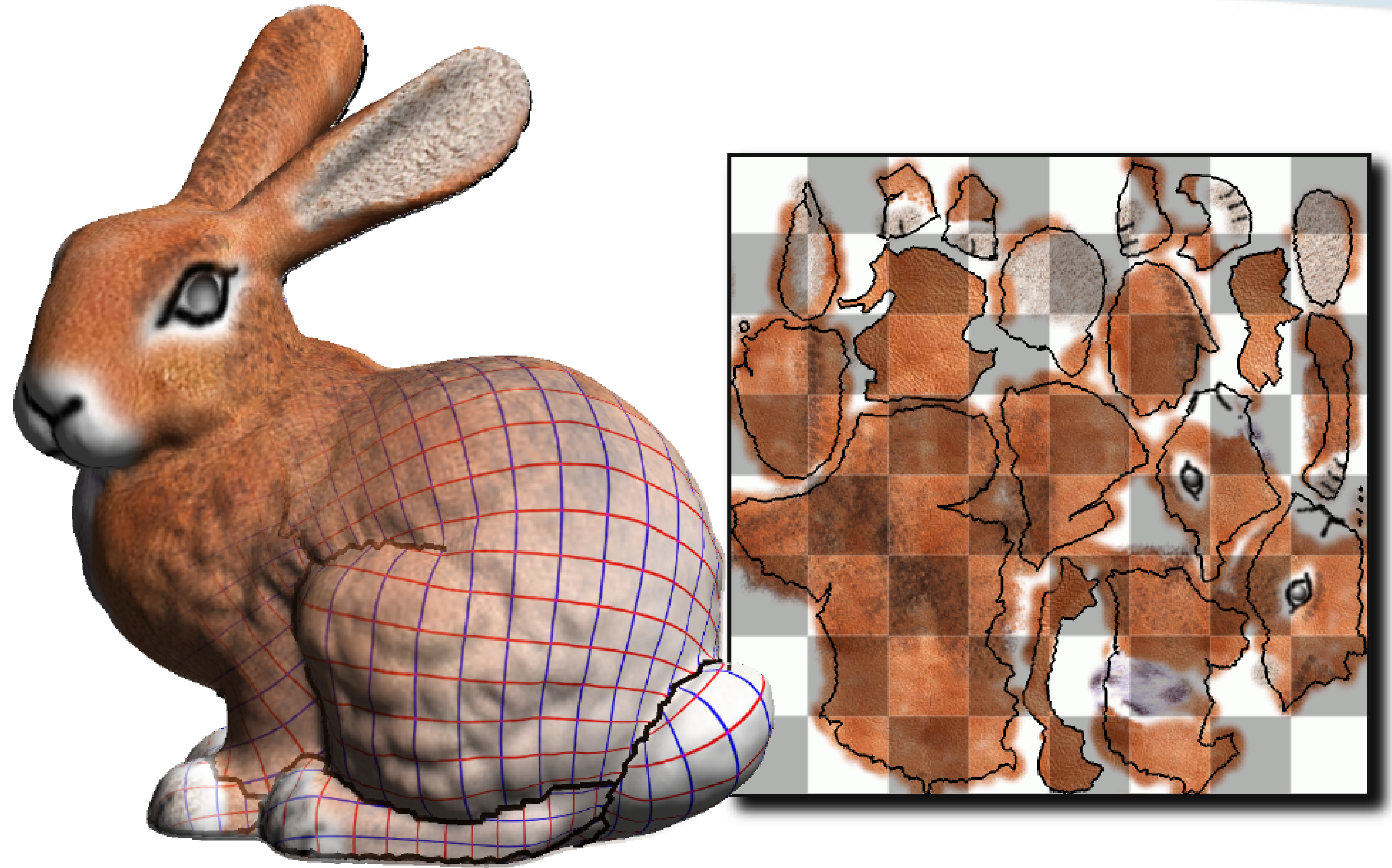
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 - $\phi : \mathcal{S}_i \subset \mathcal{S} \rightarrow \mathcal{D} \subset \mathbb{R}^2$
 - $\forall p \in \mathcal{S}_i \quad \phi(p) = (s, t)$



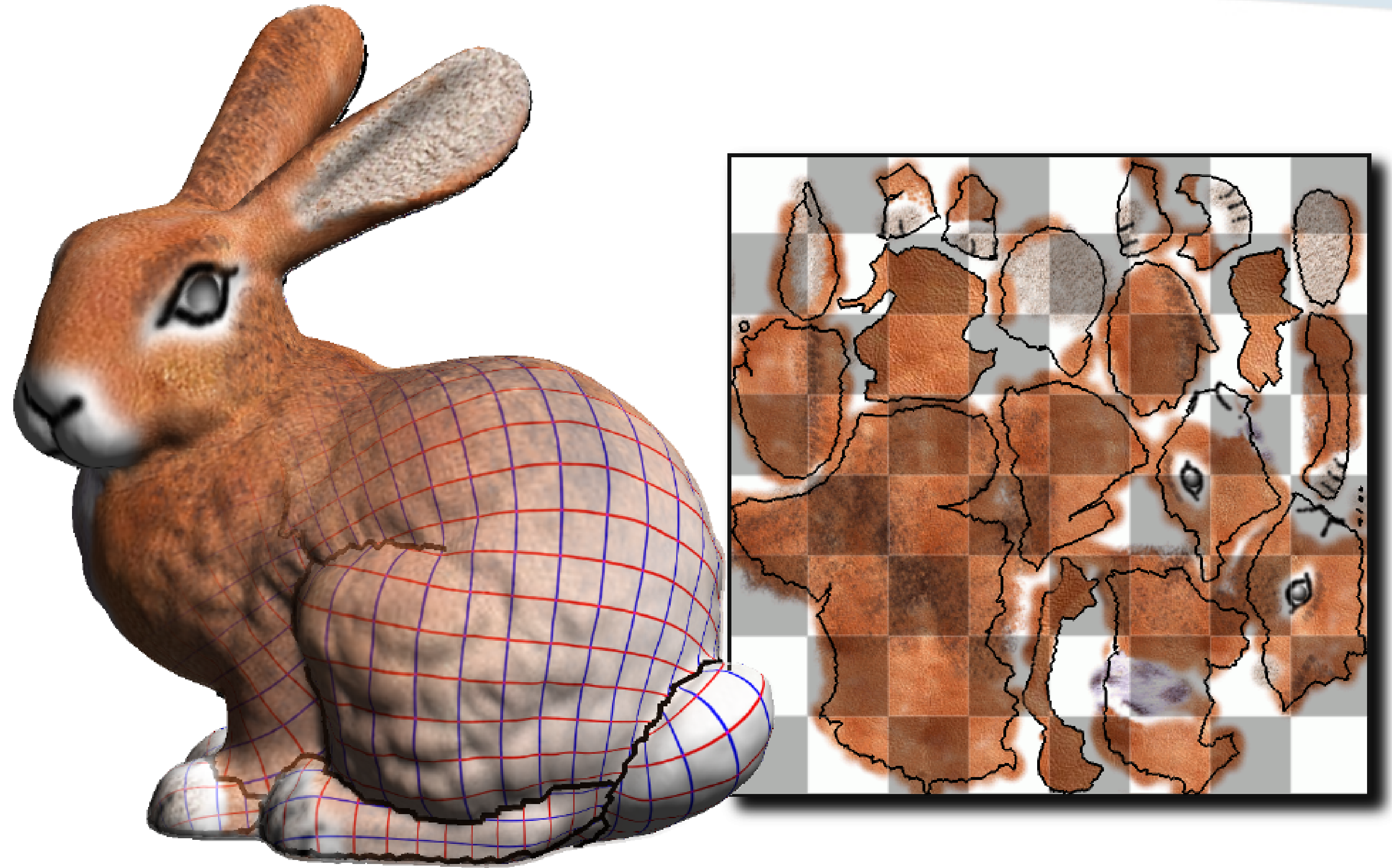
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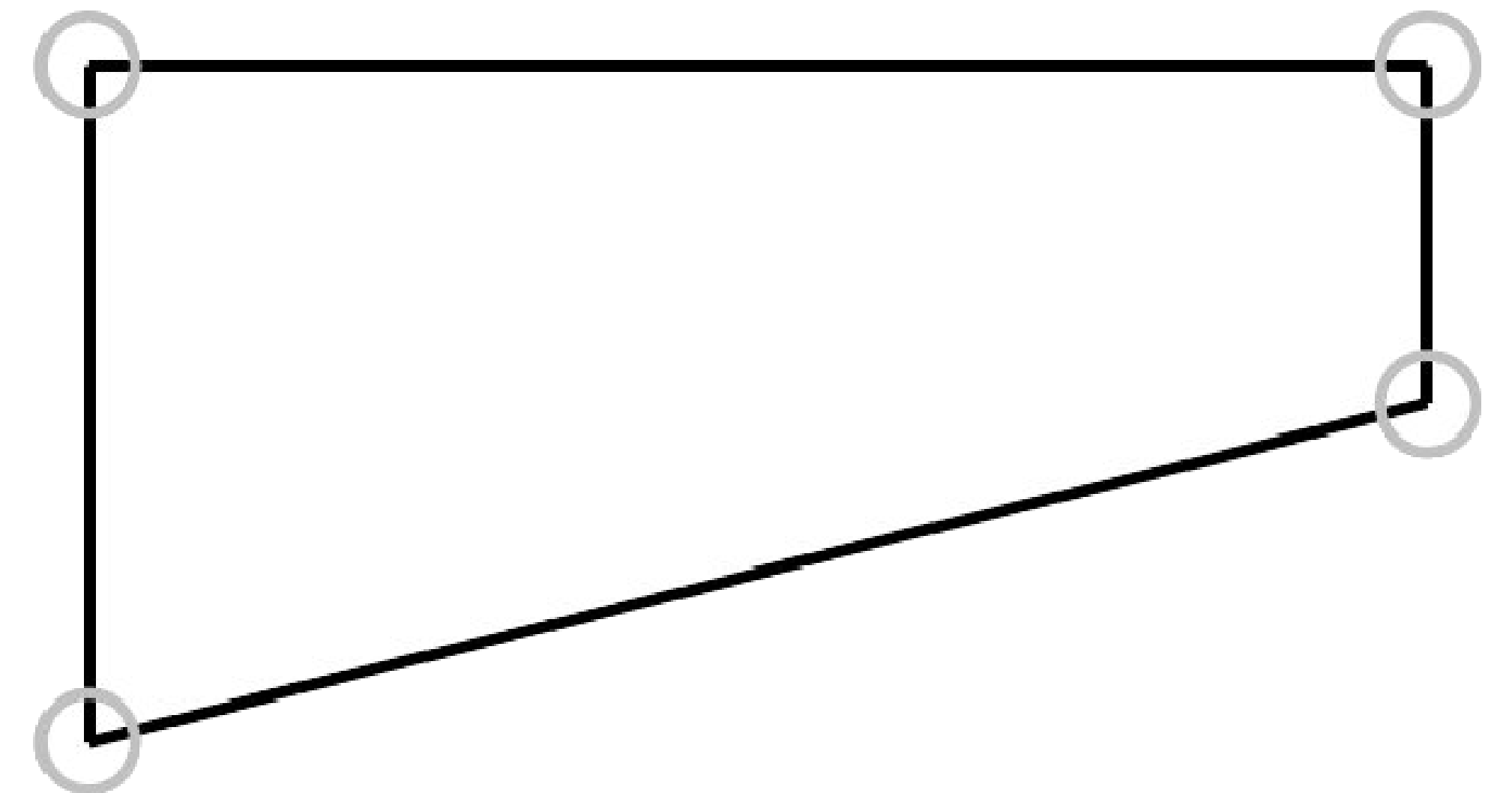
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- Each vertex:
 - Embedding in \mathbb{R}^3
 - (x, y, z)
 - Unfolding to \mathbb{R}^2
 - (s, t)



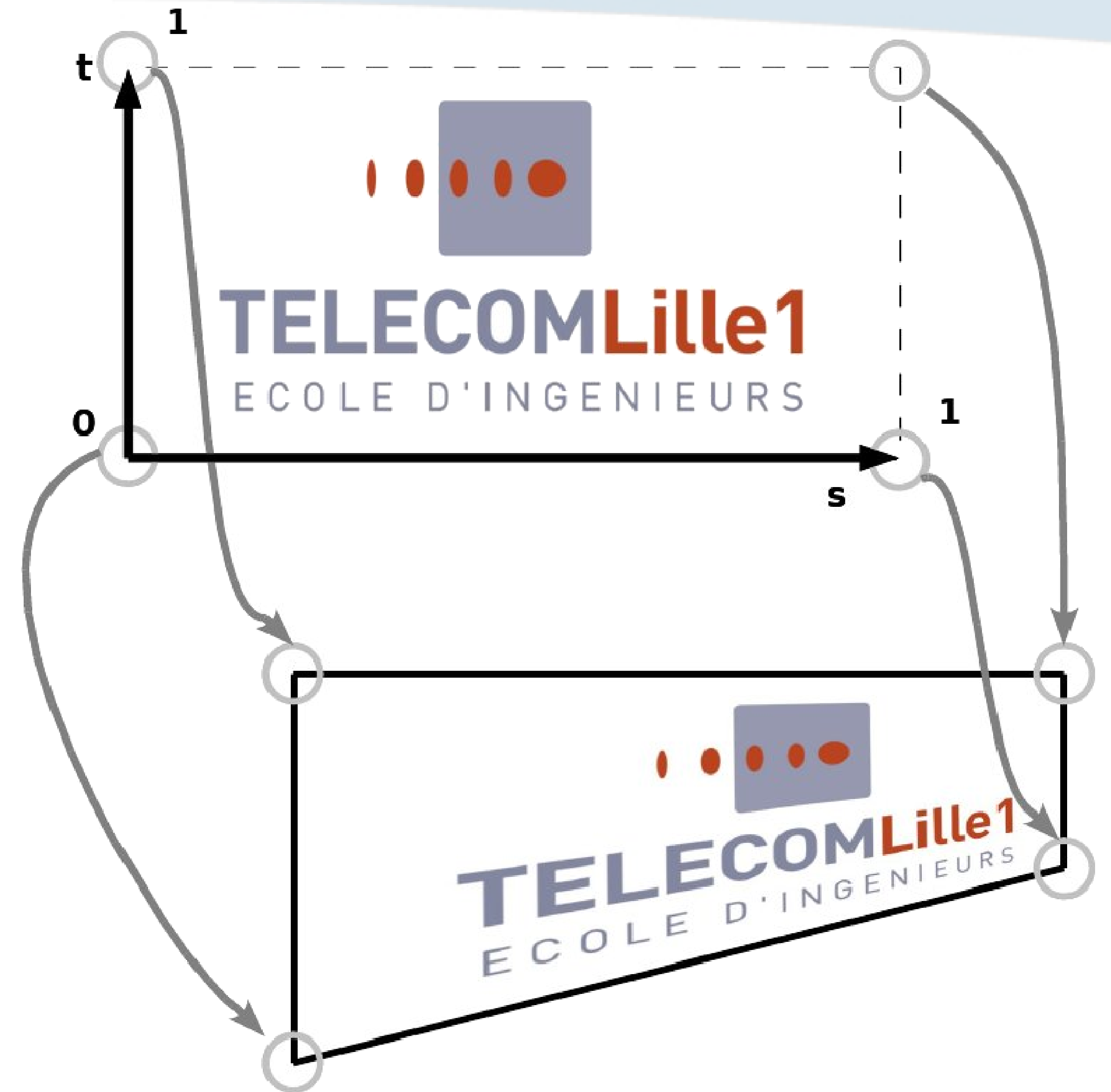
Recap on texture mapping

- Each vertex:
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 - (x, y, z)
 - Unfolding to \mathbb{R}^2
 - (s, t)
- What about the interior of the polygons?



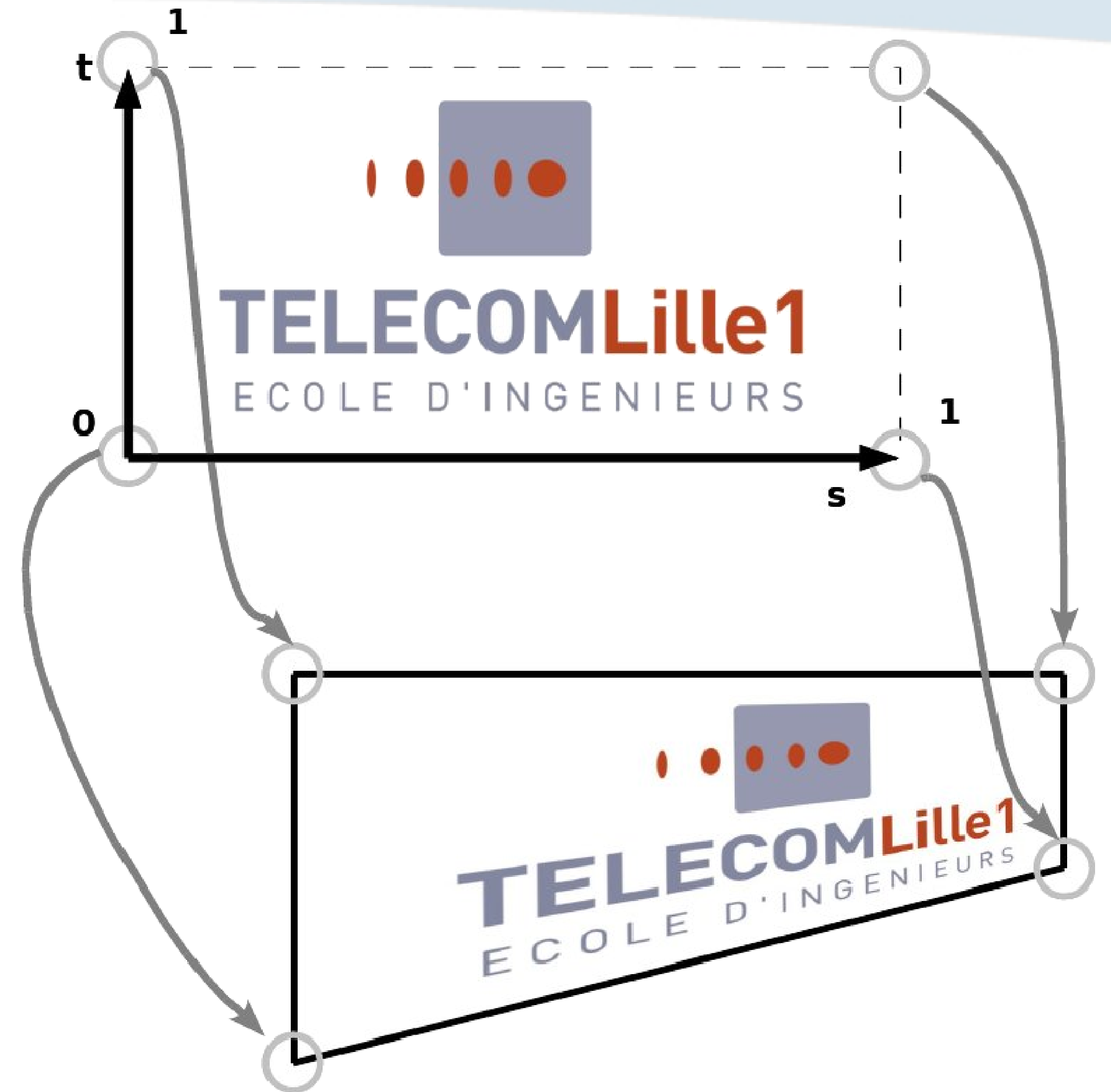
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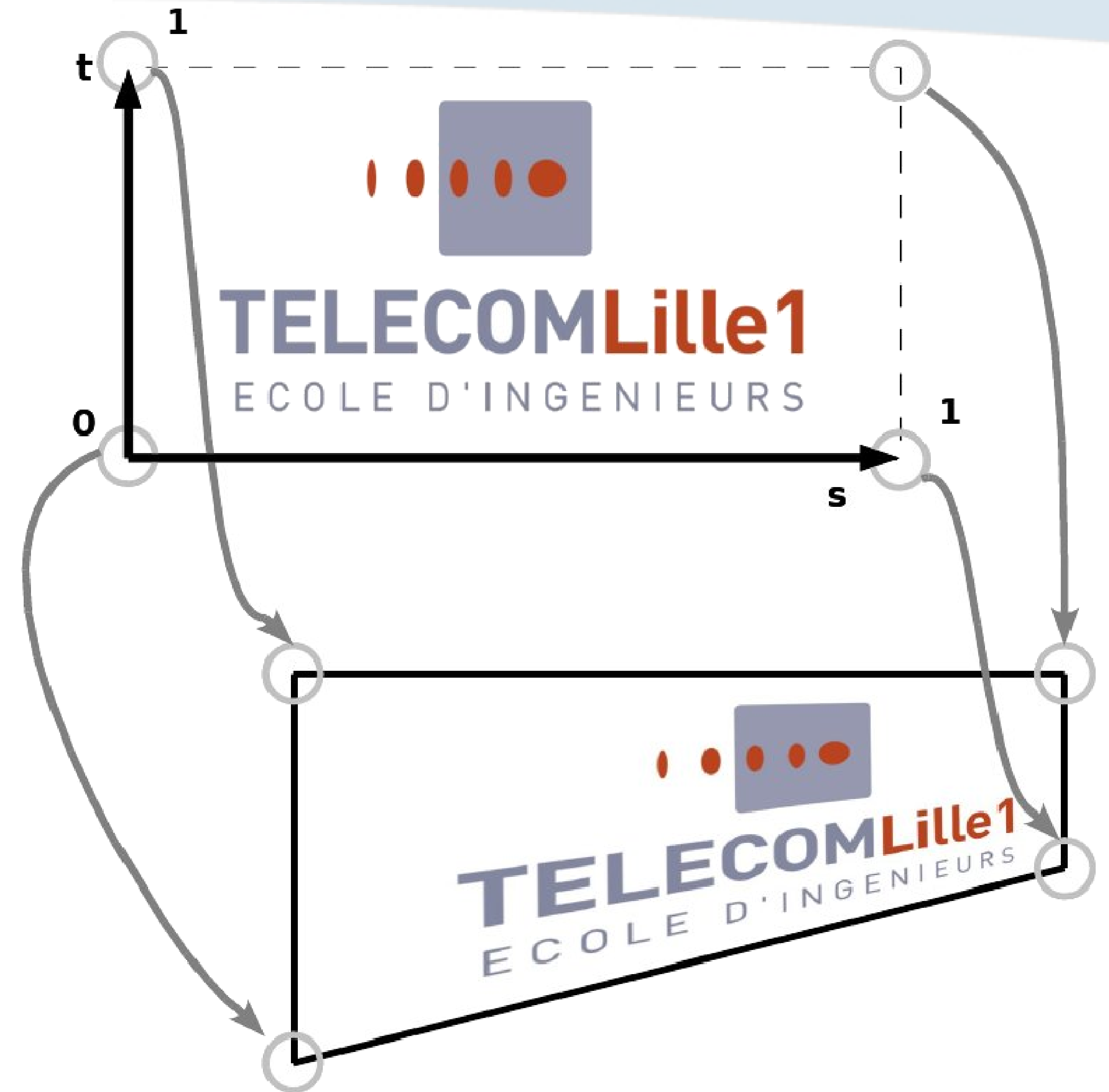
Recap on texture mapping

- Each vertex:
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 - (s, t)
- What about the interior of the polygons?
 - **Linear interpolation**



Recap on texture mapping

- Each vertex:
 - Embedding in \mathbb{R}^3
 - (x, y, z)
 - Unfolding to \mathbb{R}^2
 - (s, t)
- What about the interior of the polygons?
 - **Linear interpolation** (GPU)



Color maps for scalar field visualization

- Arrange continuously a palette of colors



Color maps for scalar field visualization

- Arrange continuously a palette of colors



Color maps for scalar field visualization

- Arrange continuously a palette of colors



- For each vertex: (break the bijection)
 - $\phi(v) = (f(v), 0)$

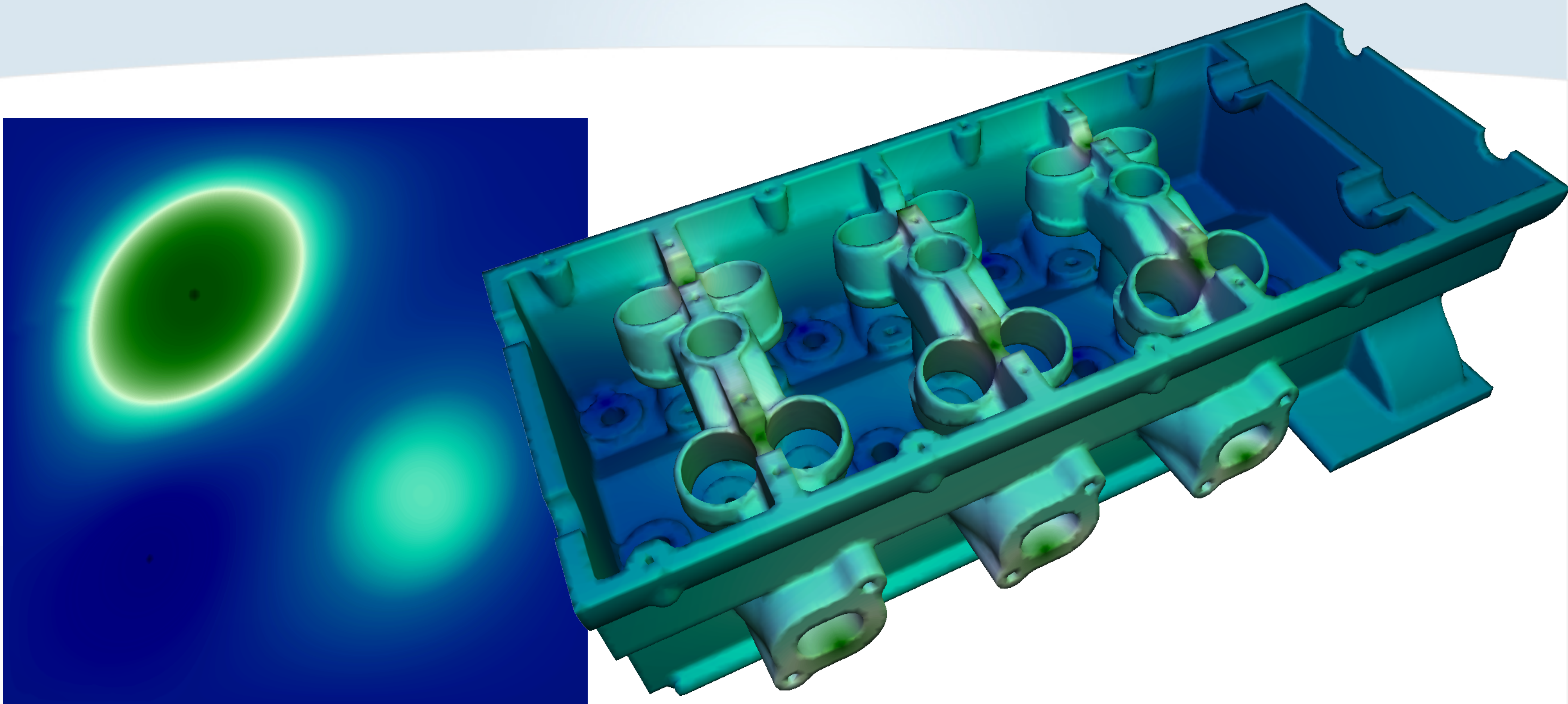
Color maps for scalar field visualization

- Arrange continuously a palette of colors



- For each vertex: (break the bijection)
 - $\phi(v) = (f(v), 0)$
 - Generic solution (arbitrary texture)

Color maps for scalar field visualization



Color maps for scalar field visualization



Color maps for scalar field visualization

- Continuously varying palettes
 - Difficult to evaluate variation



Color maps for scalar field visualization

- Continuously varying palettes
 - Difficult to evaluate variation
- Notion of level set
 - $f^{-1}(i) = \{p \in \mathcal{D} \mid f(p) = i\}$



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 - $f^{-1}(i) = \{p \in \mathcal{D} \mid f(p) = i\}$
 - **Global** and **local** information



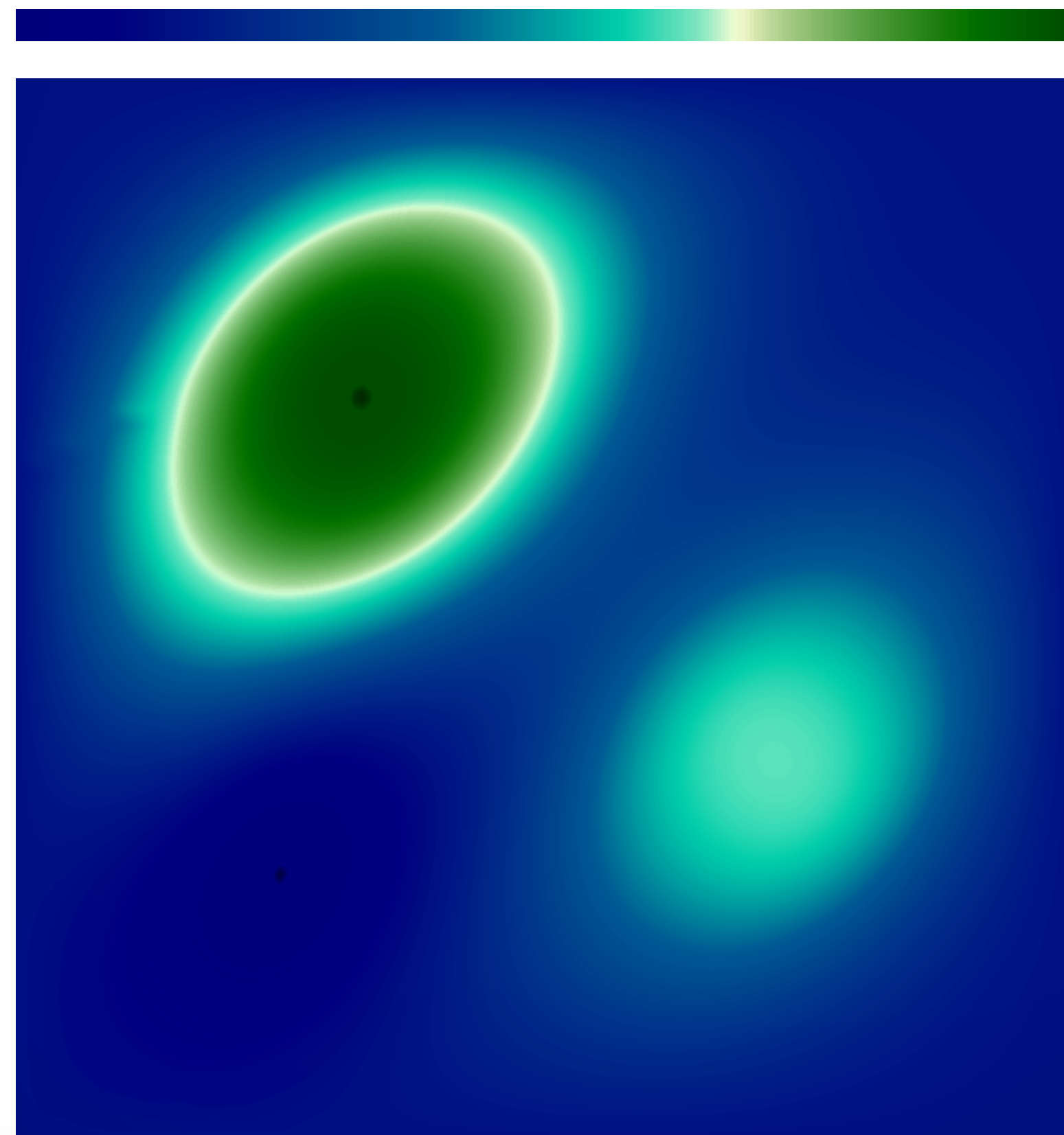
Color maps for scalar field visualization

- Continuously varying palettes
 - Difficult to evaluate variation
- Notion of level set
 - $f^{-1}(i) = \{p \in \mathcal{D} \mid f(p) = i\}$
 - **Global** and **local** information
- Explicit computation
 - A bit involved



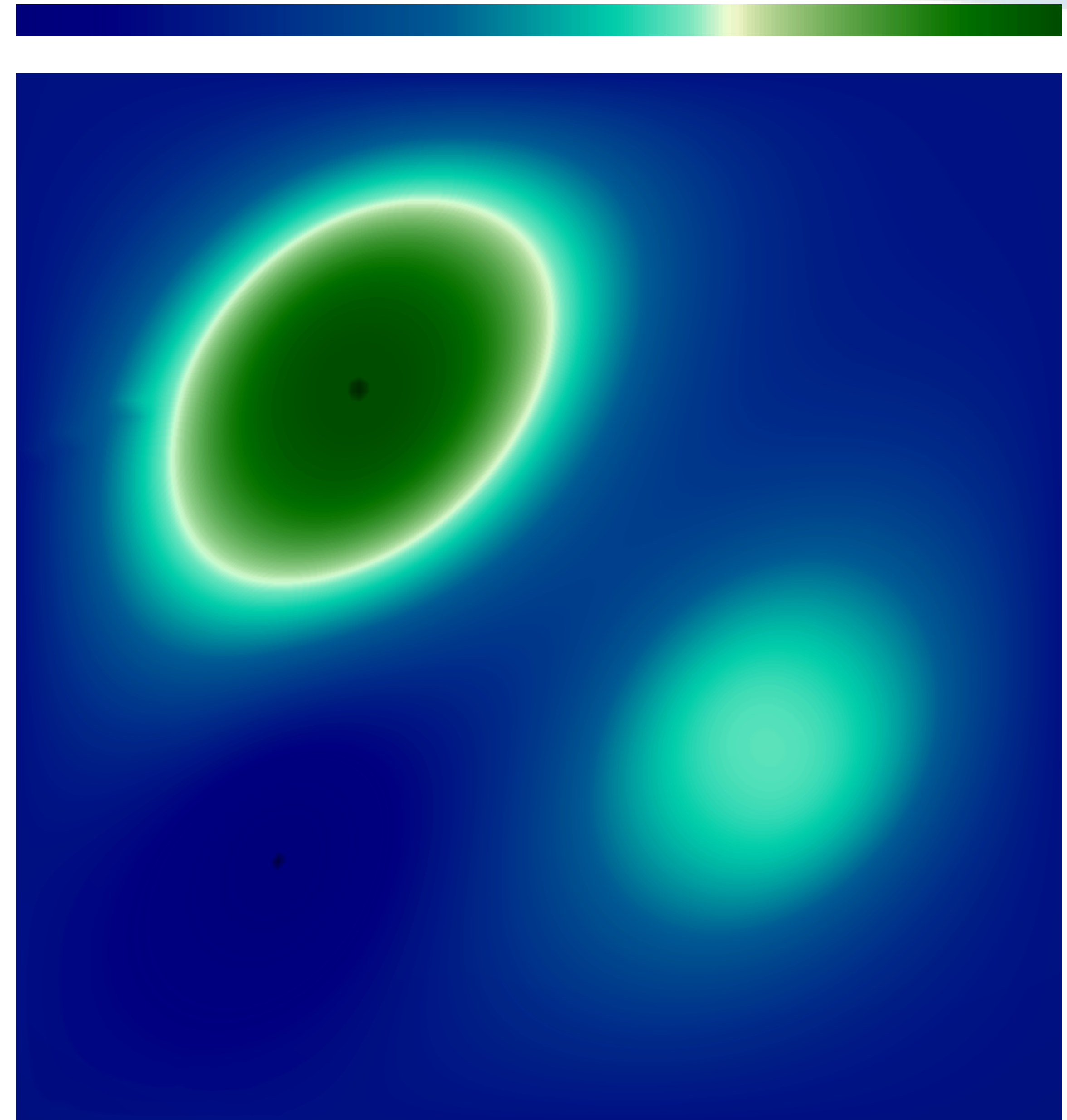
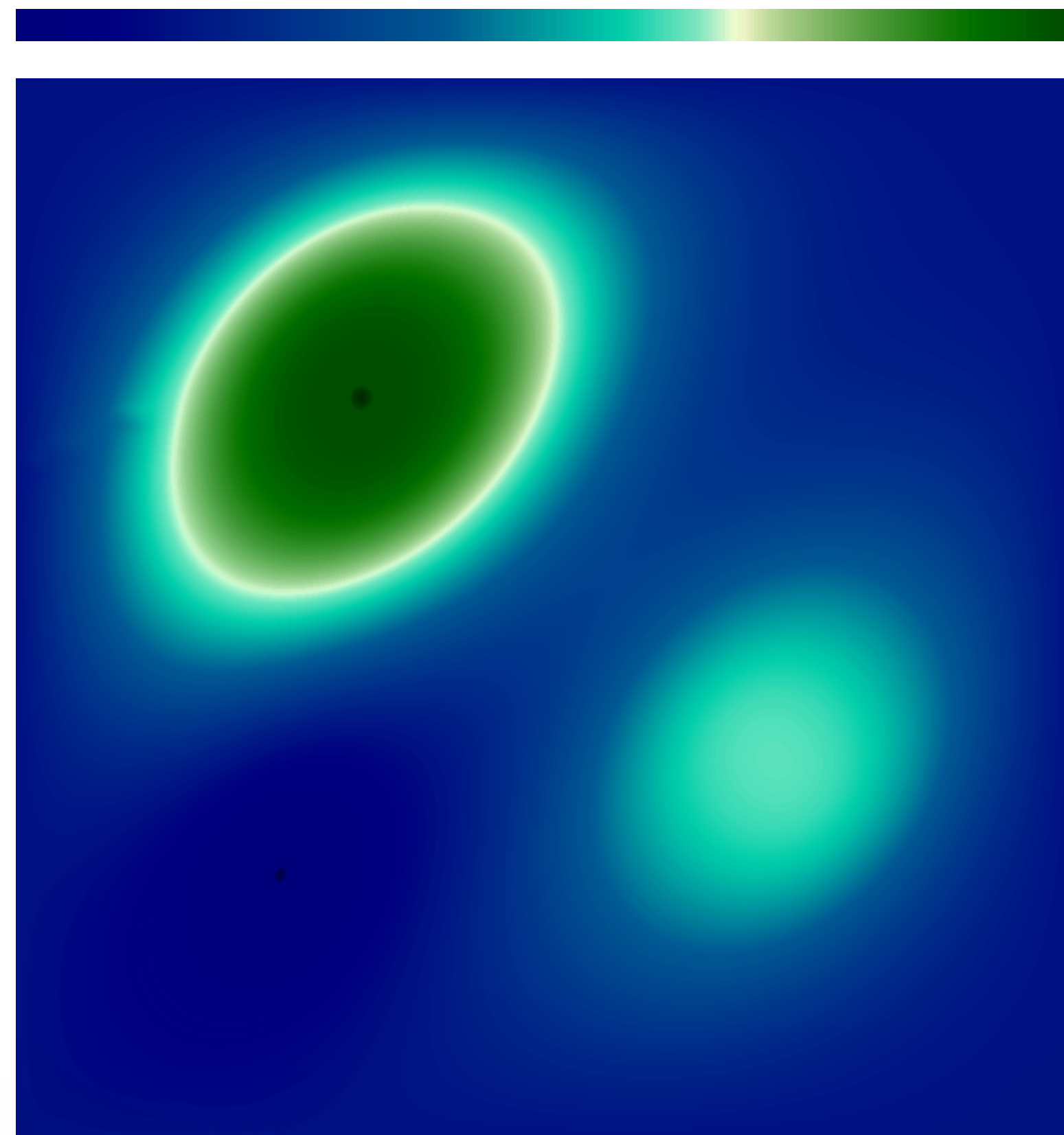
Color maps for scalar field visualization

- Implicit level set visualization
 - Play with the texture?



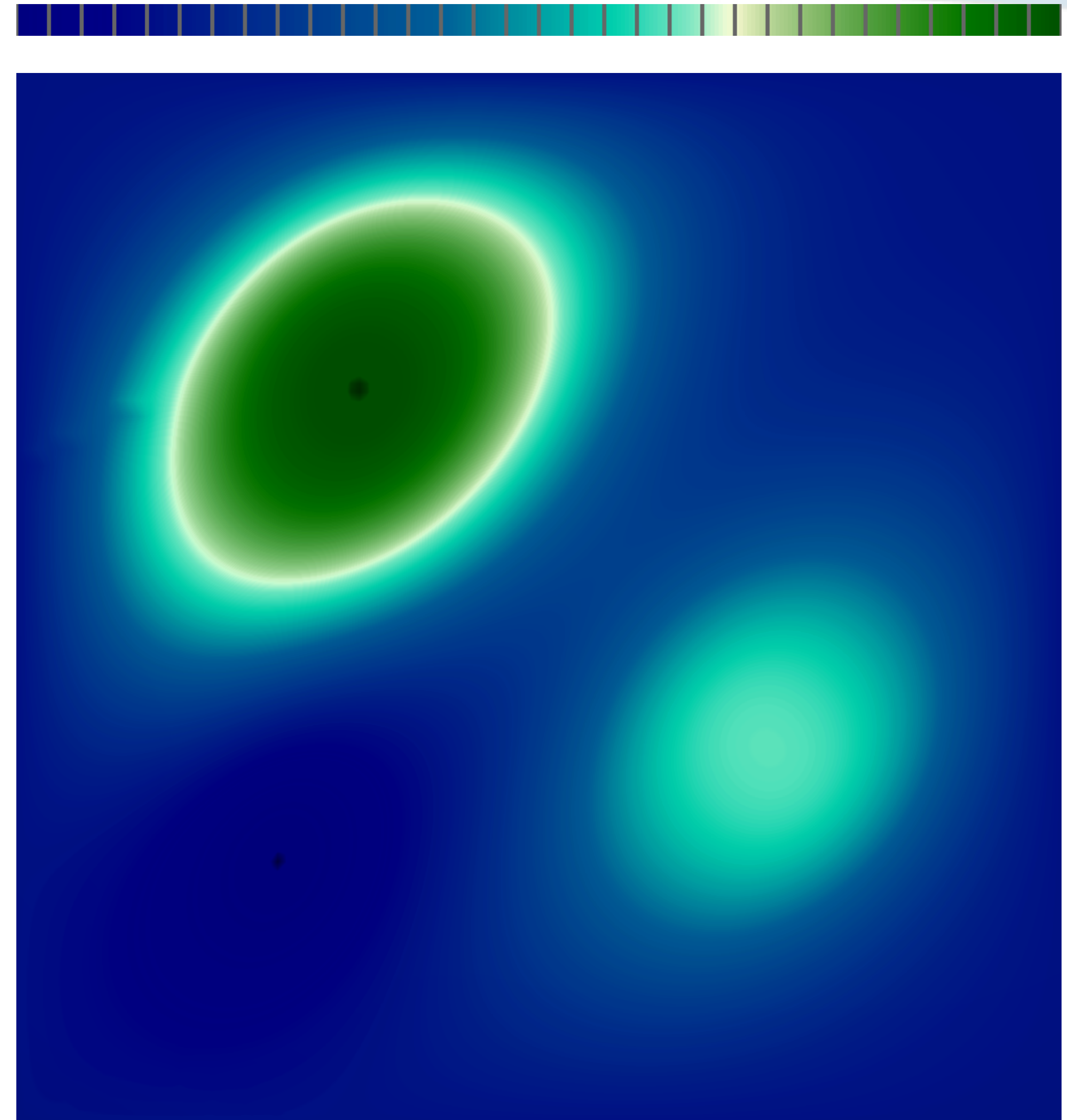
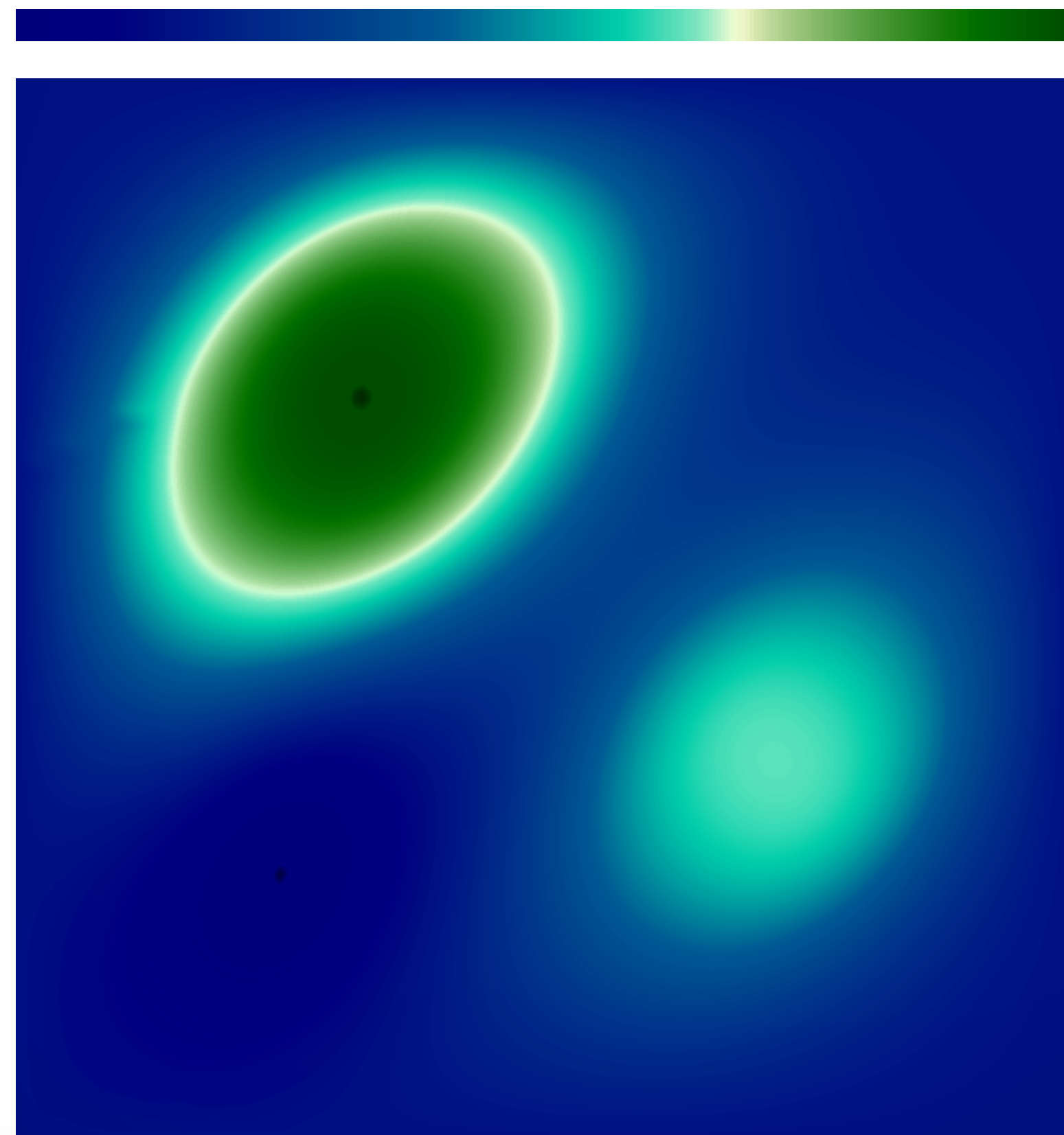
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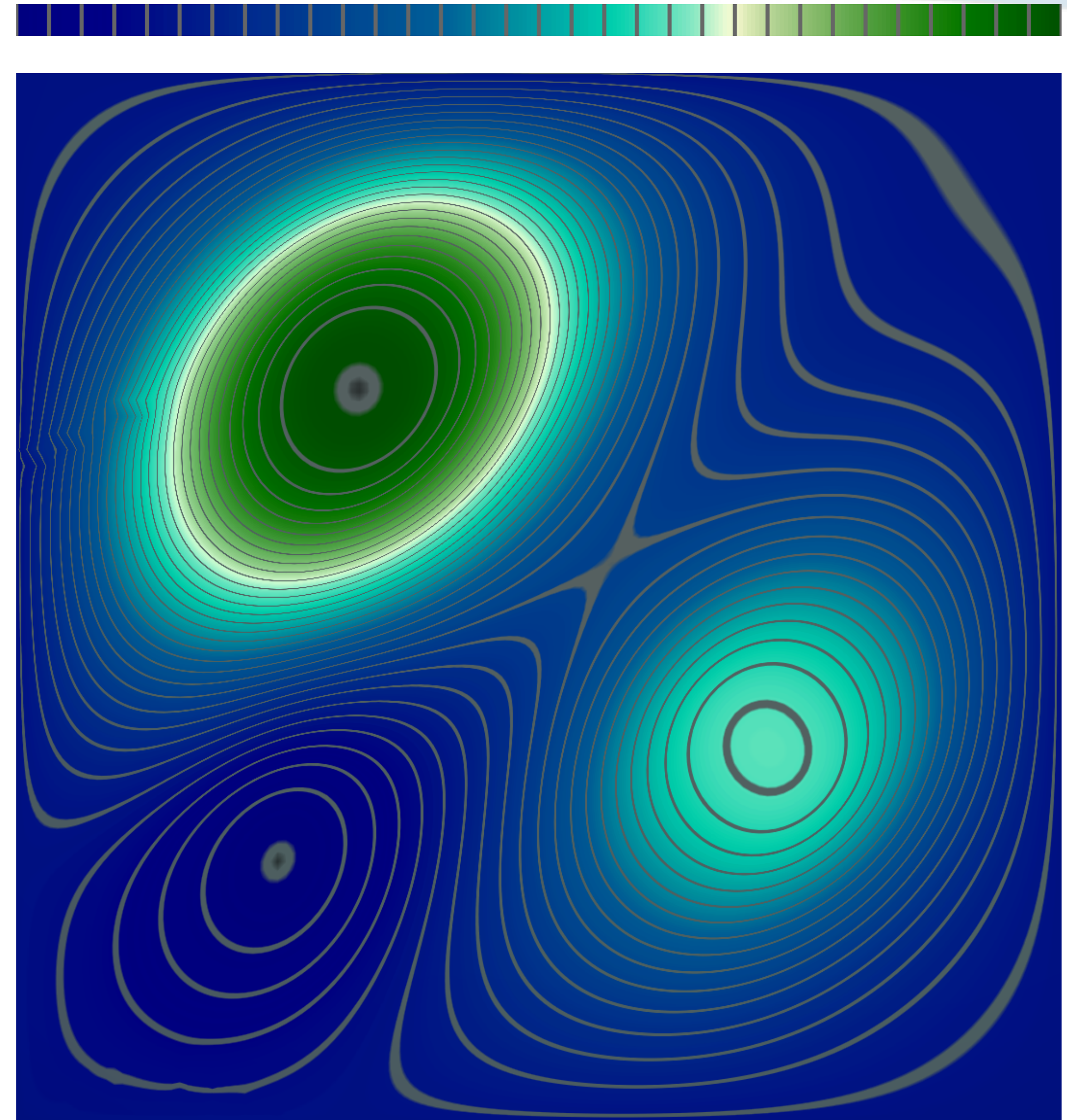
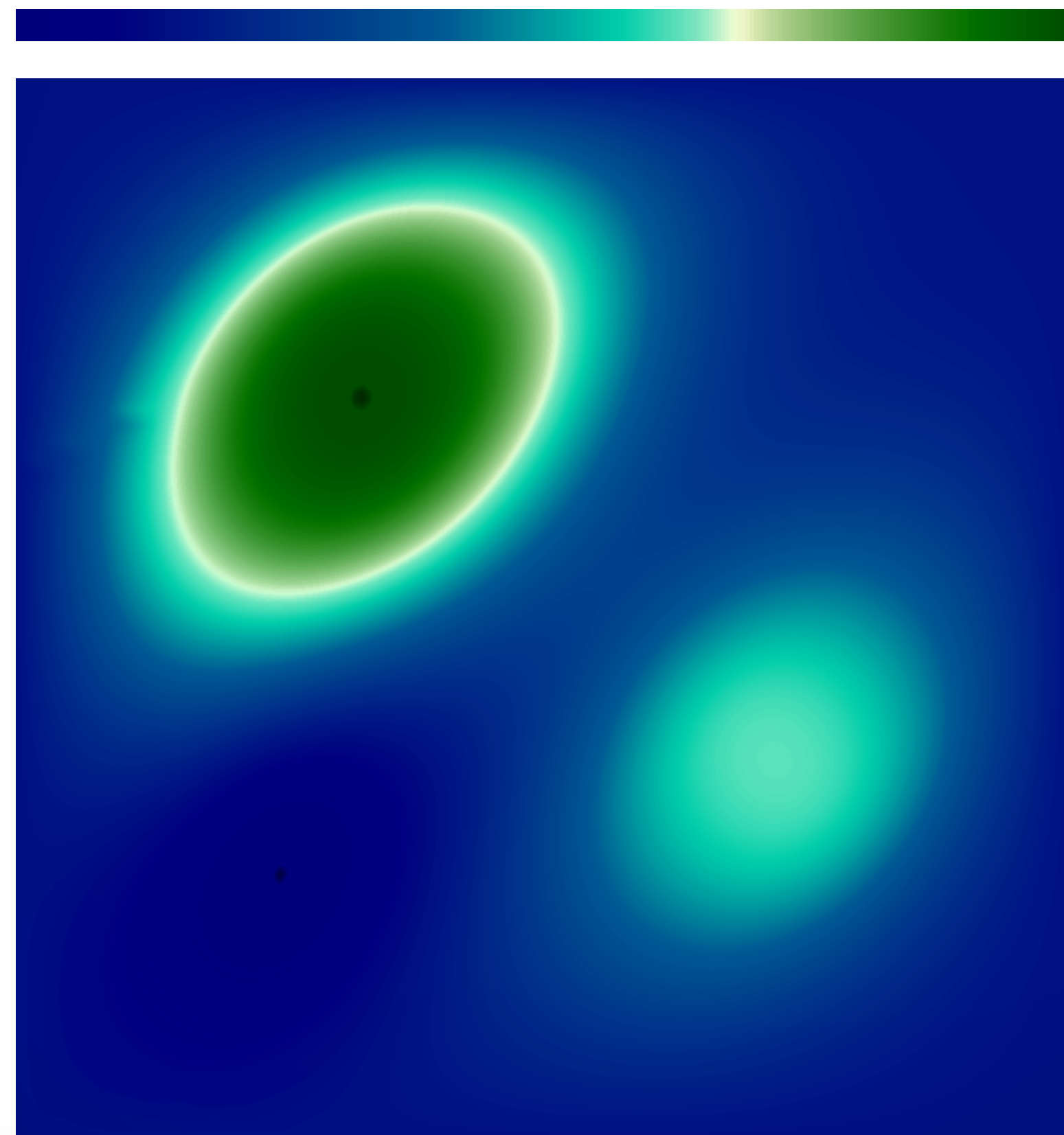
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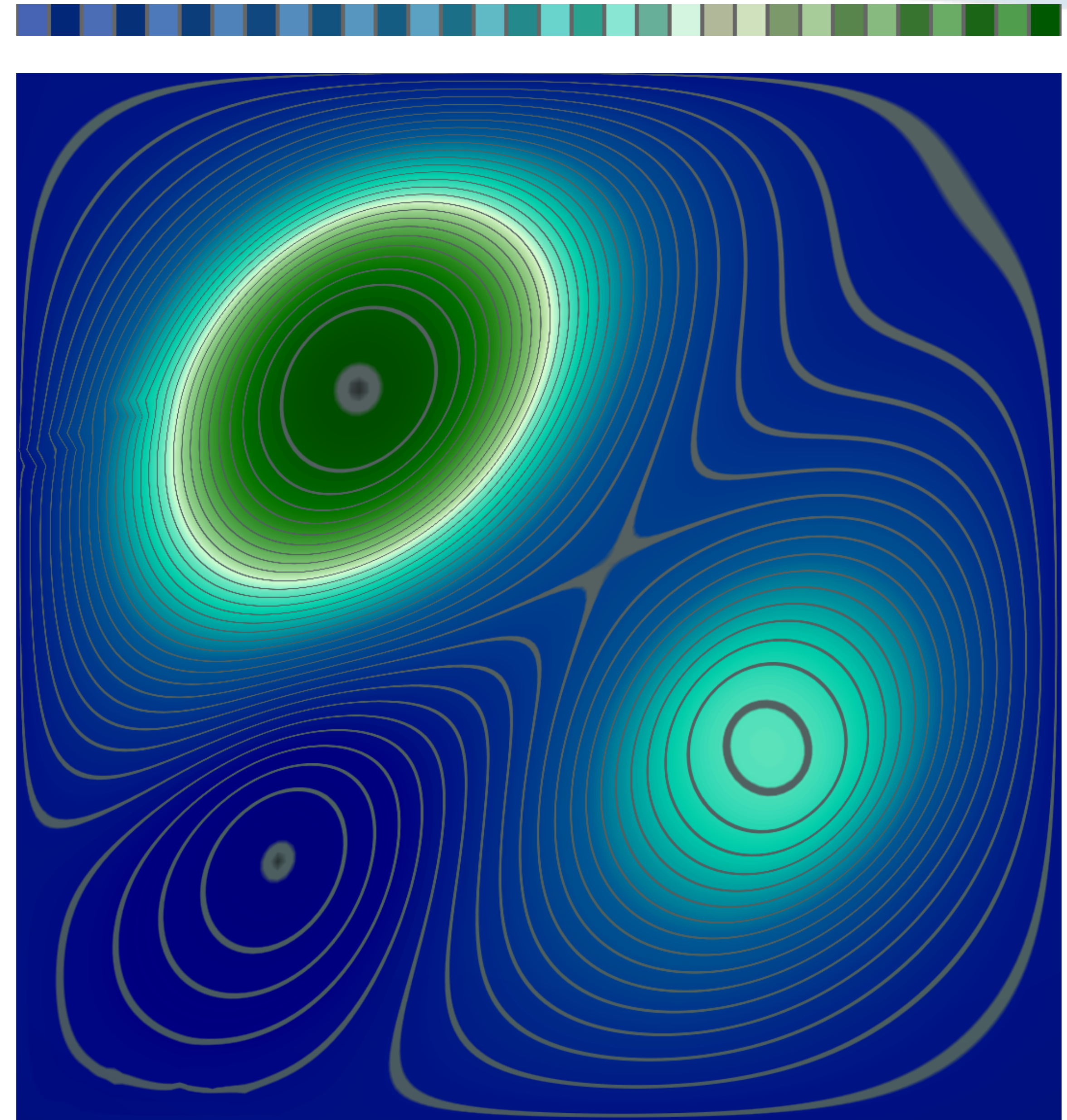
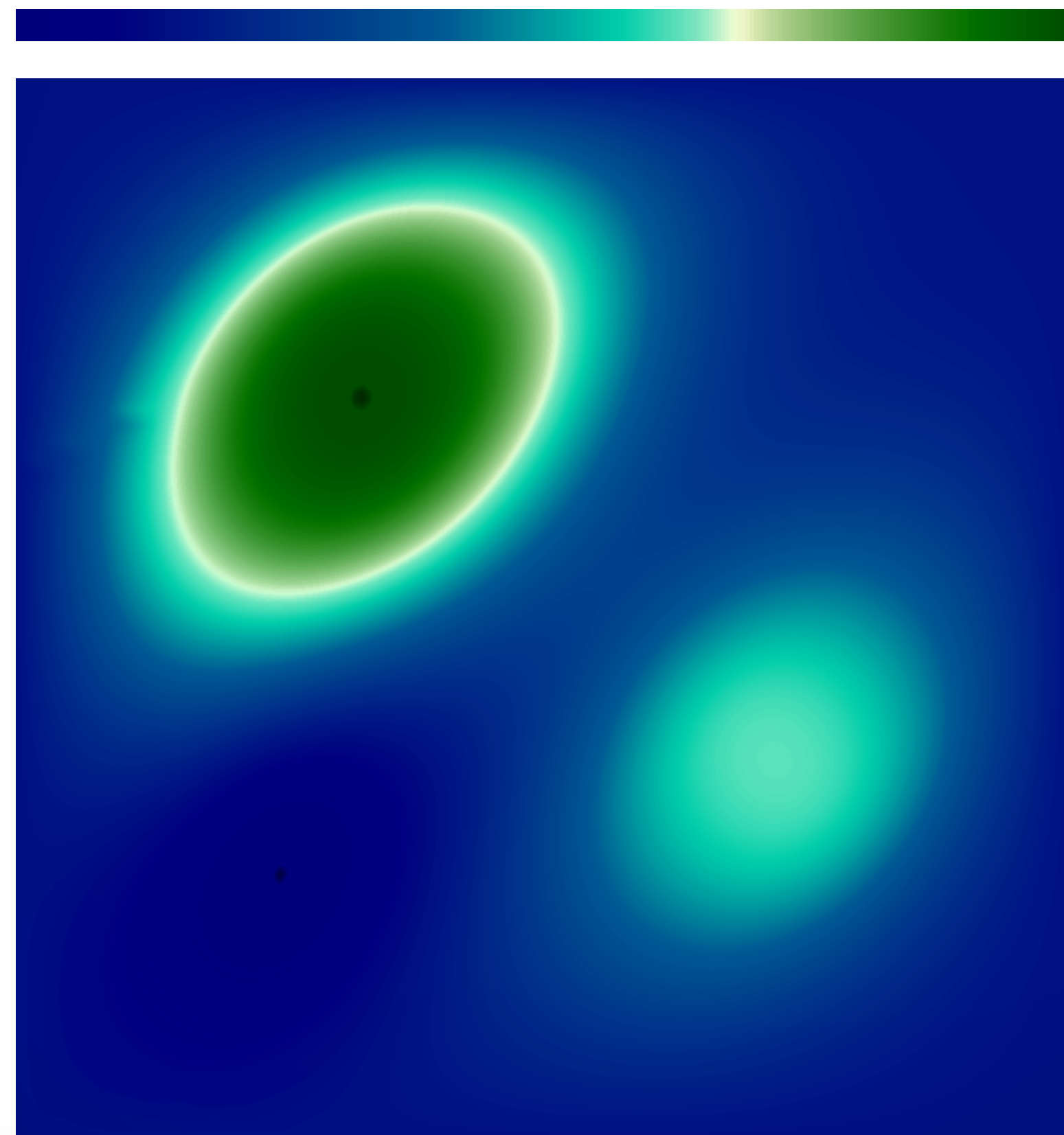
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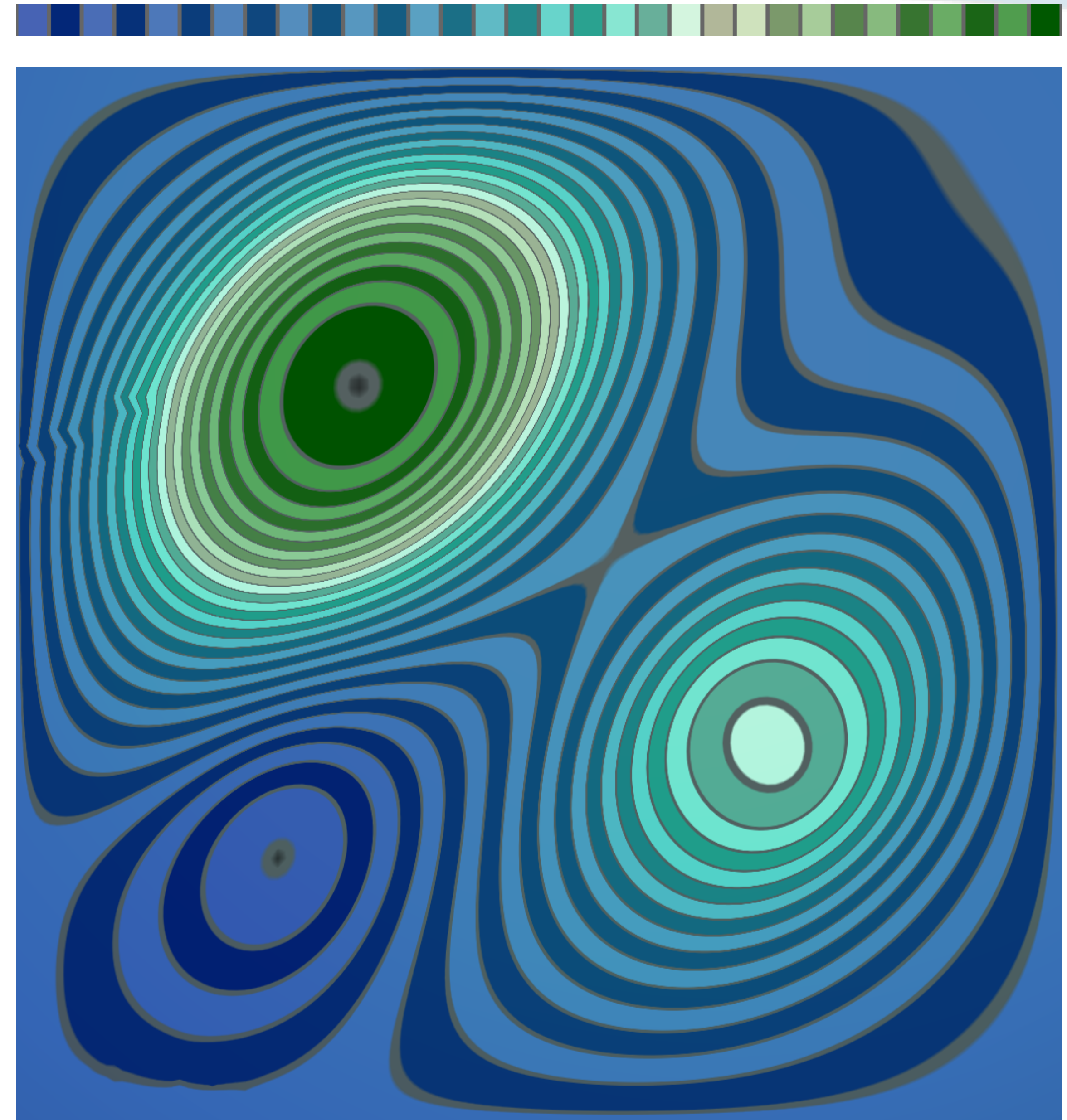
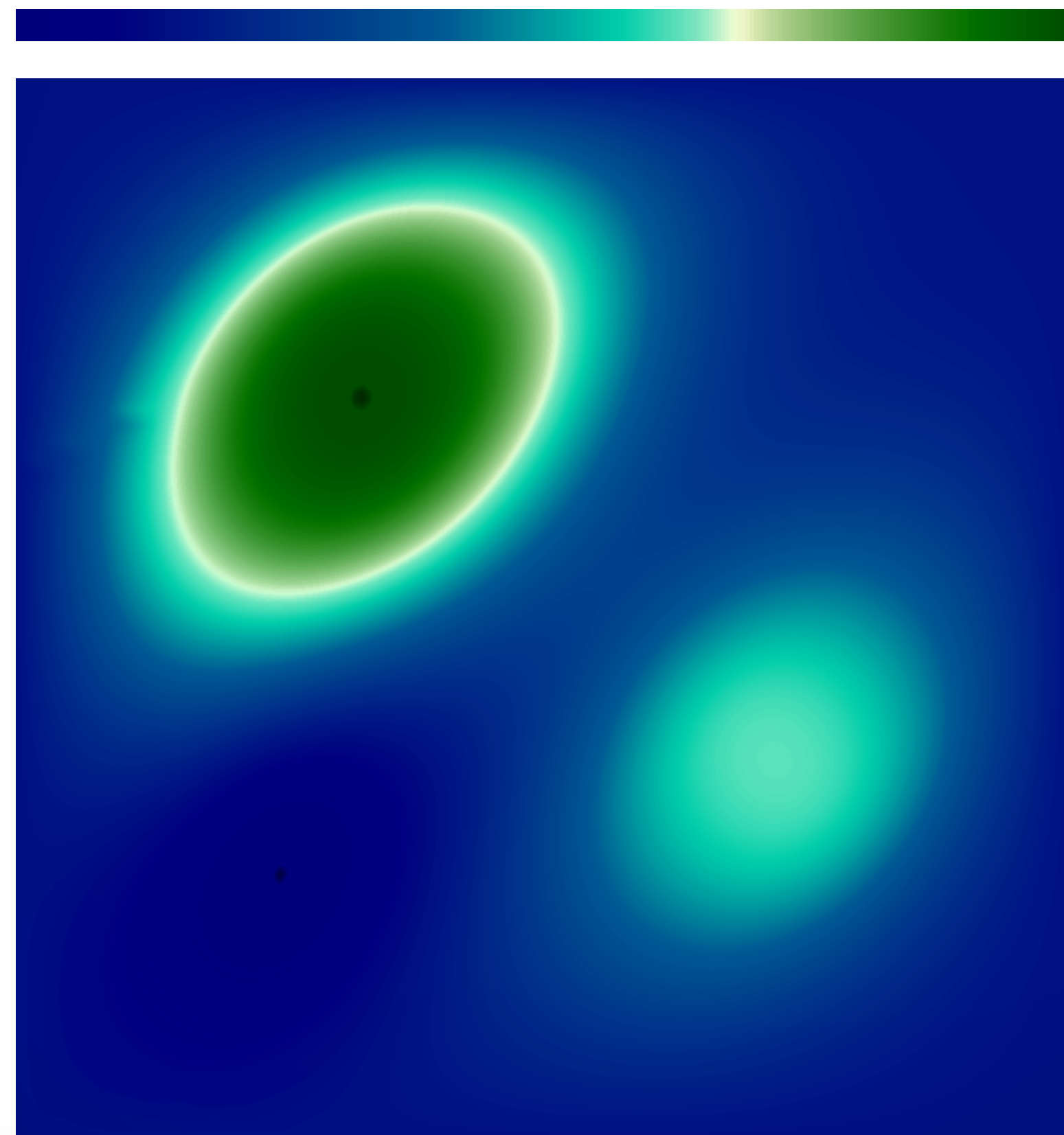
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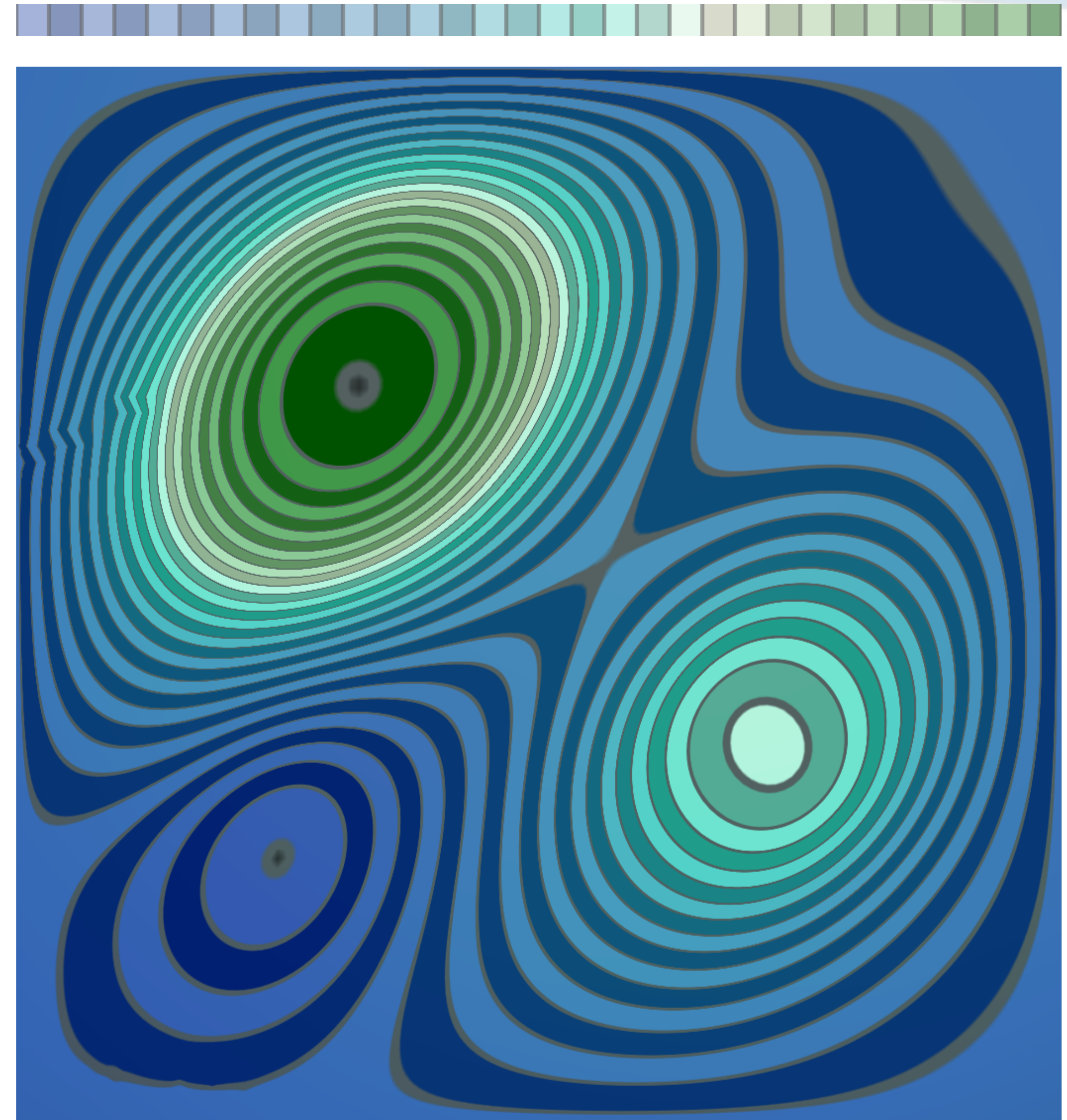
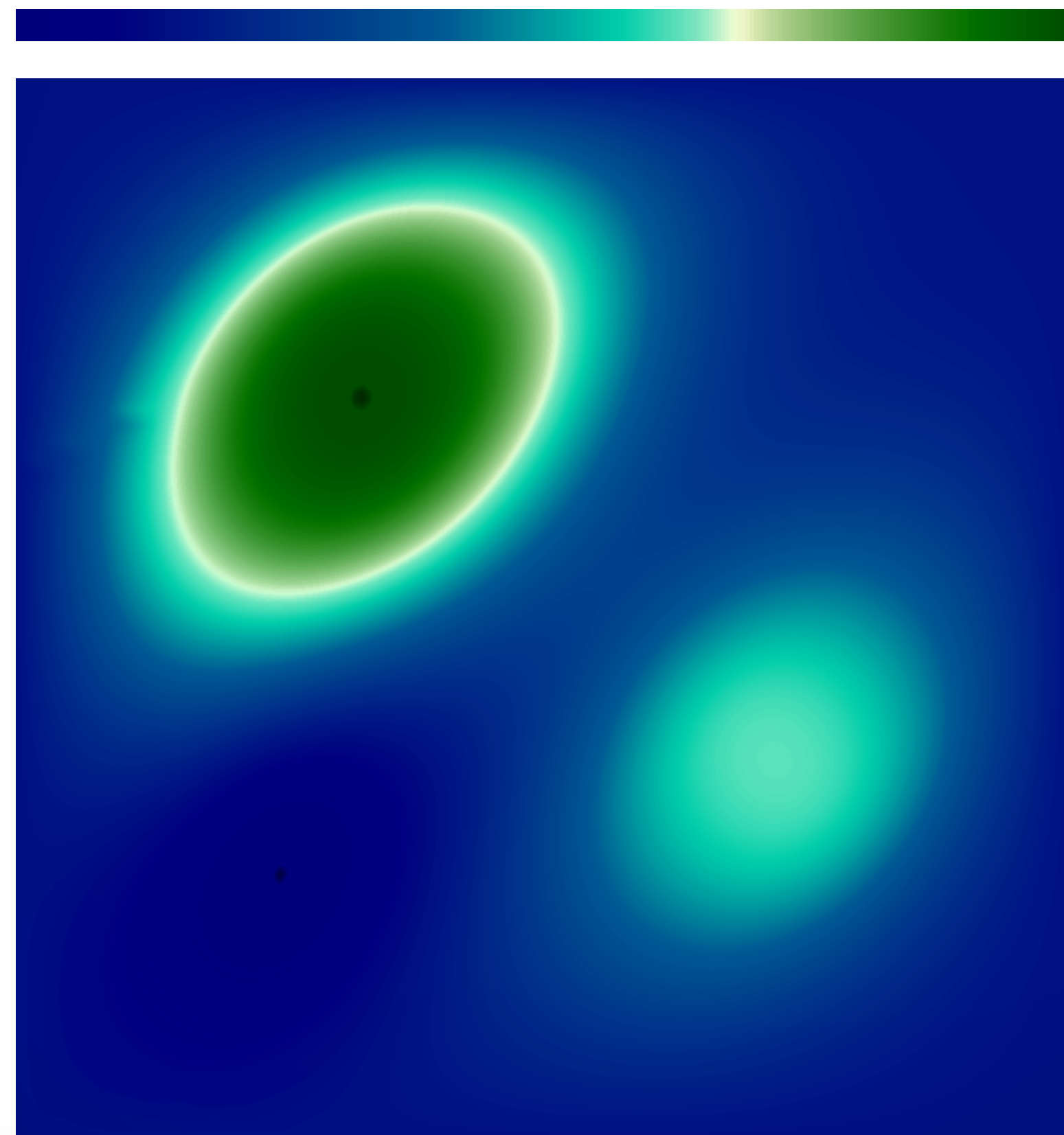
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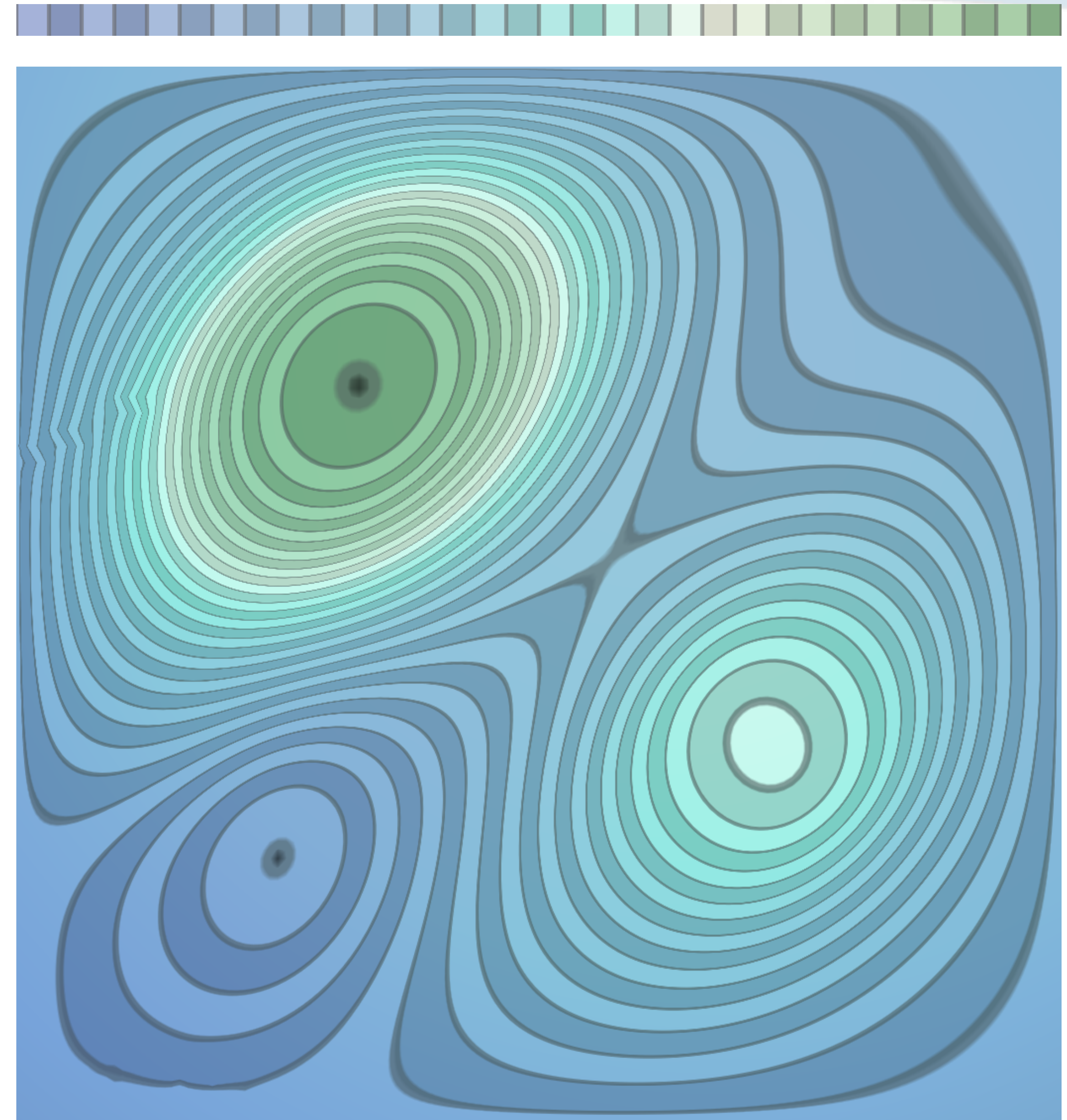
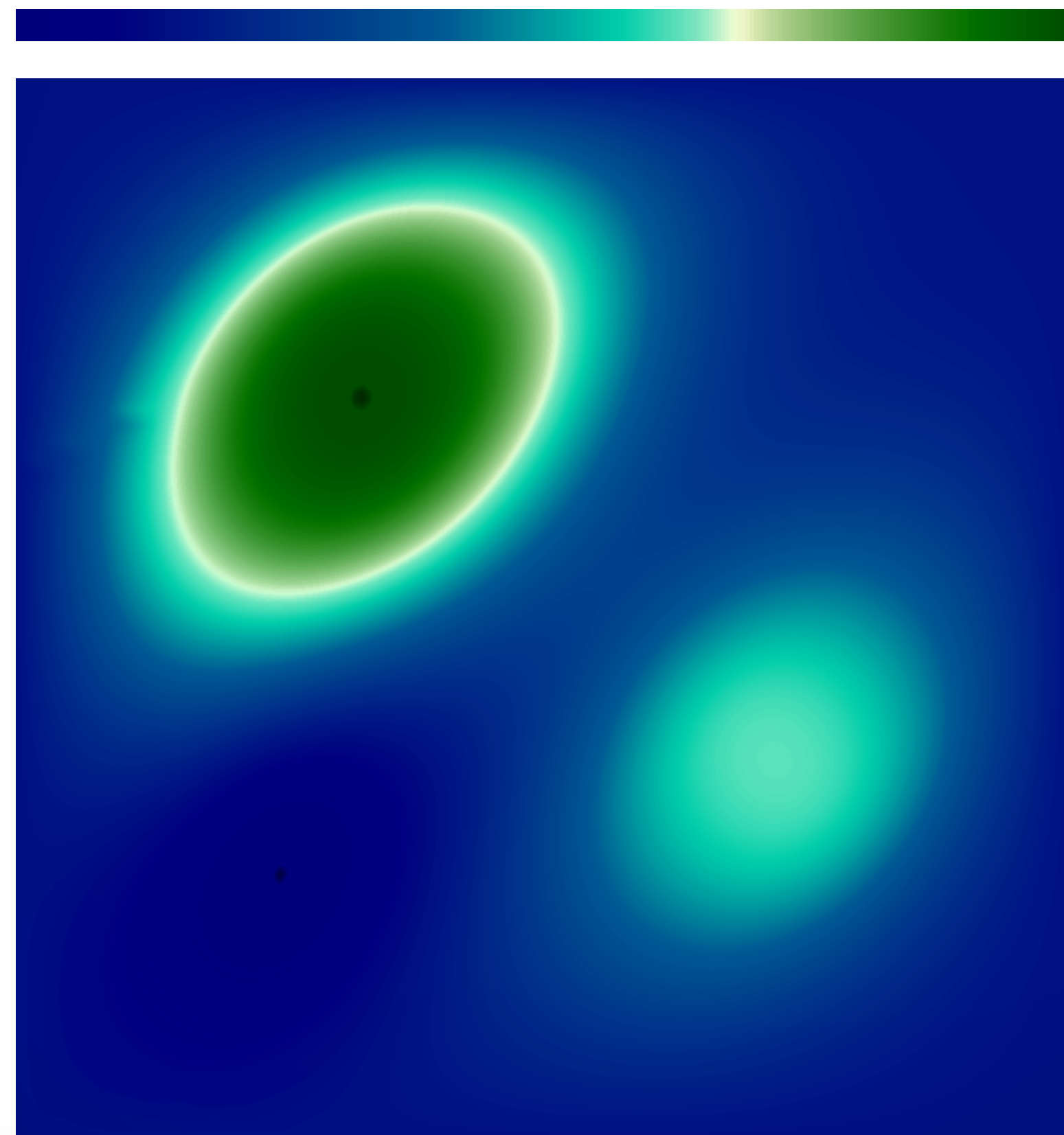
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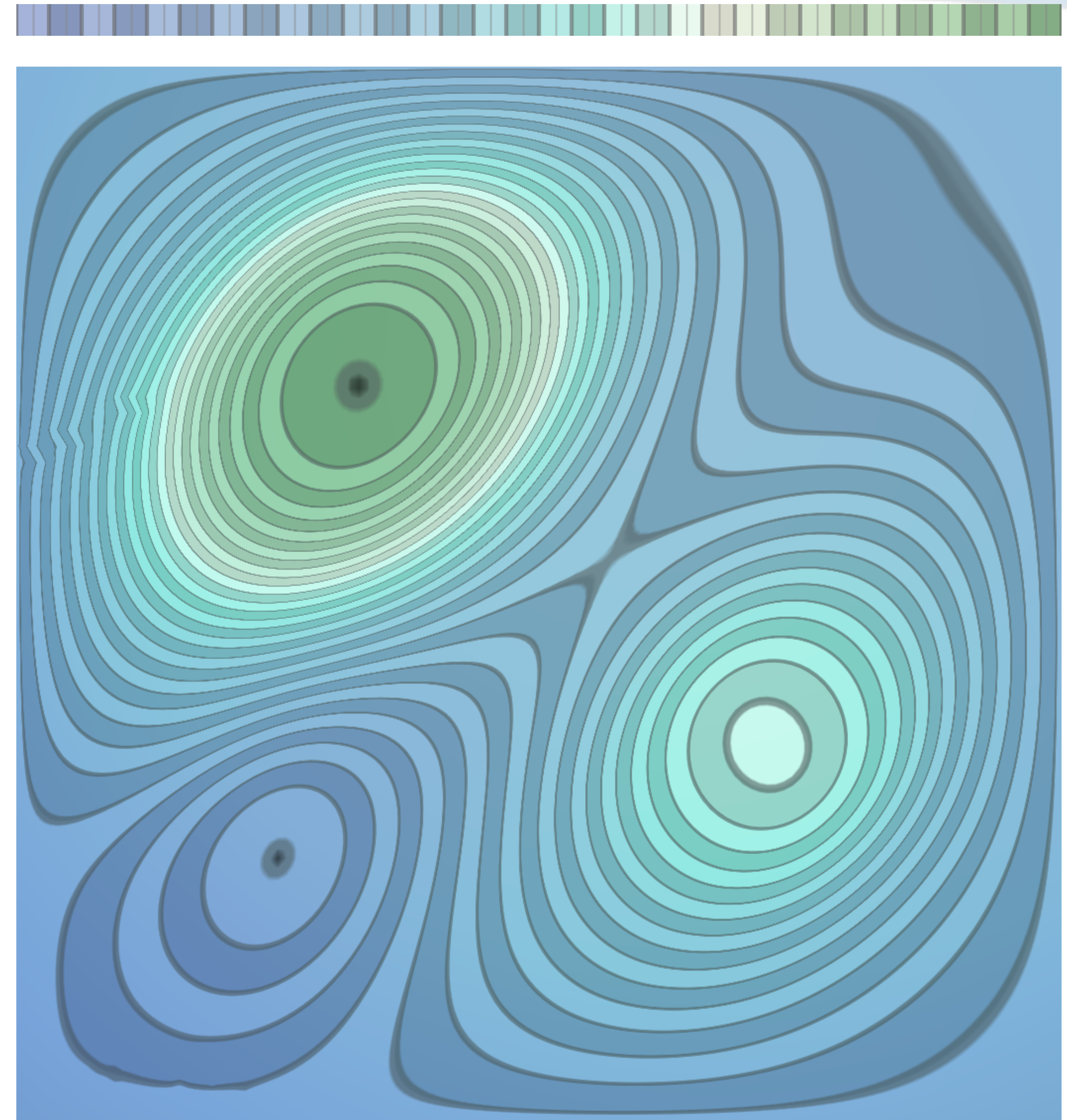
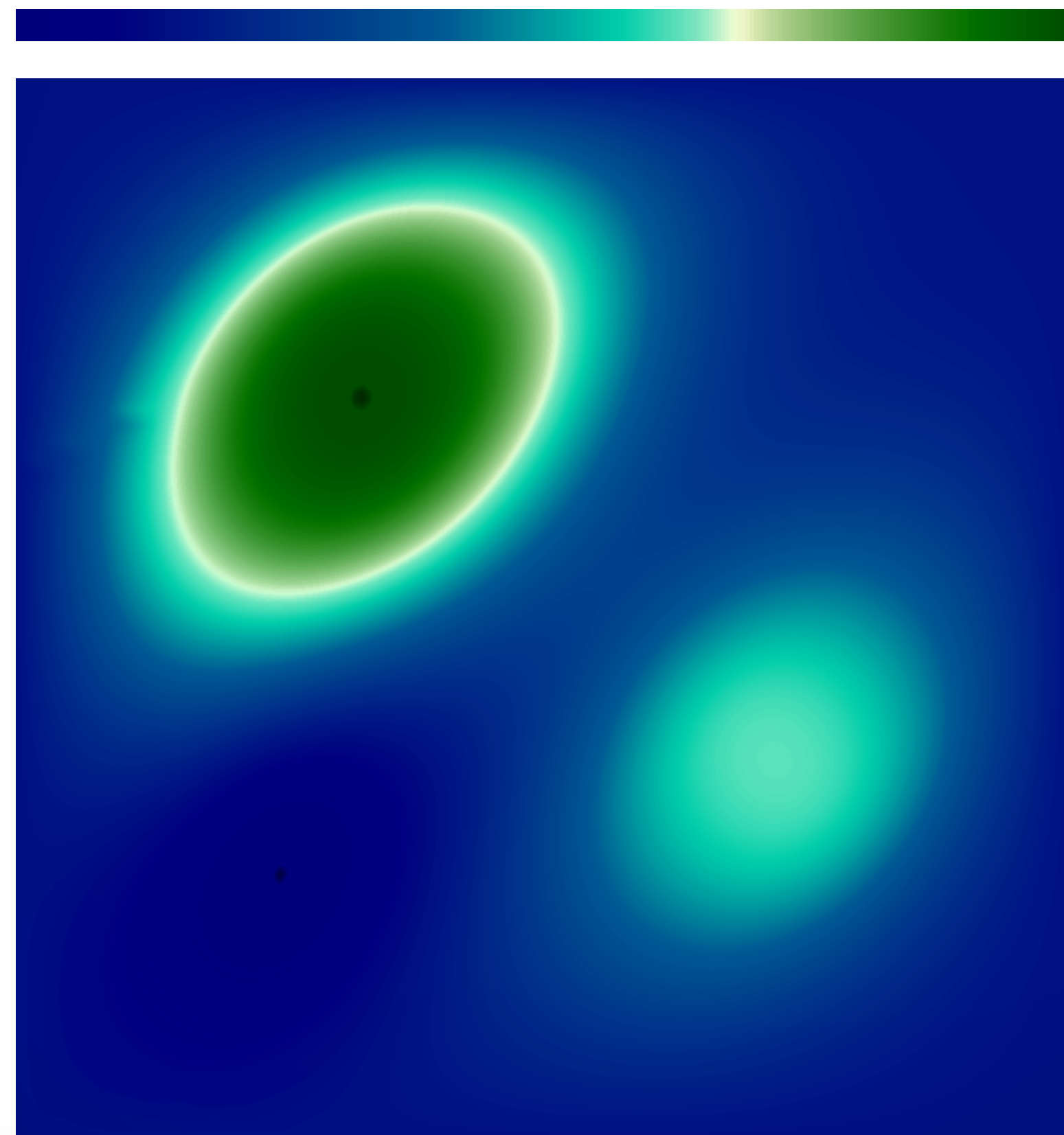
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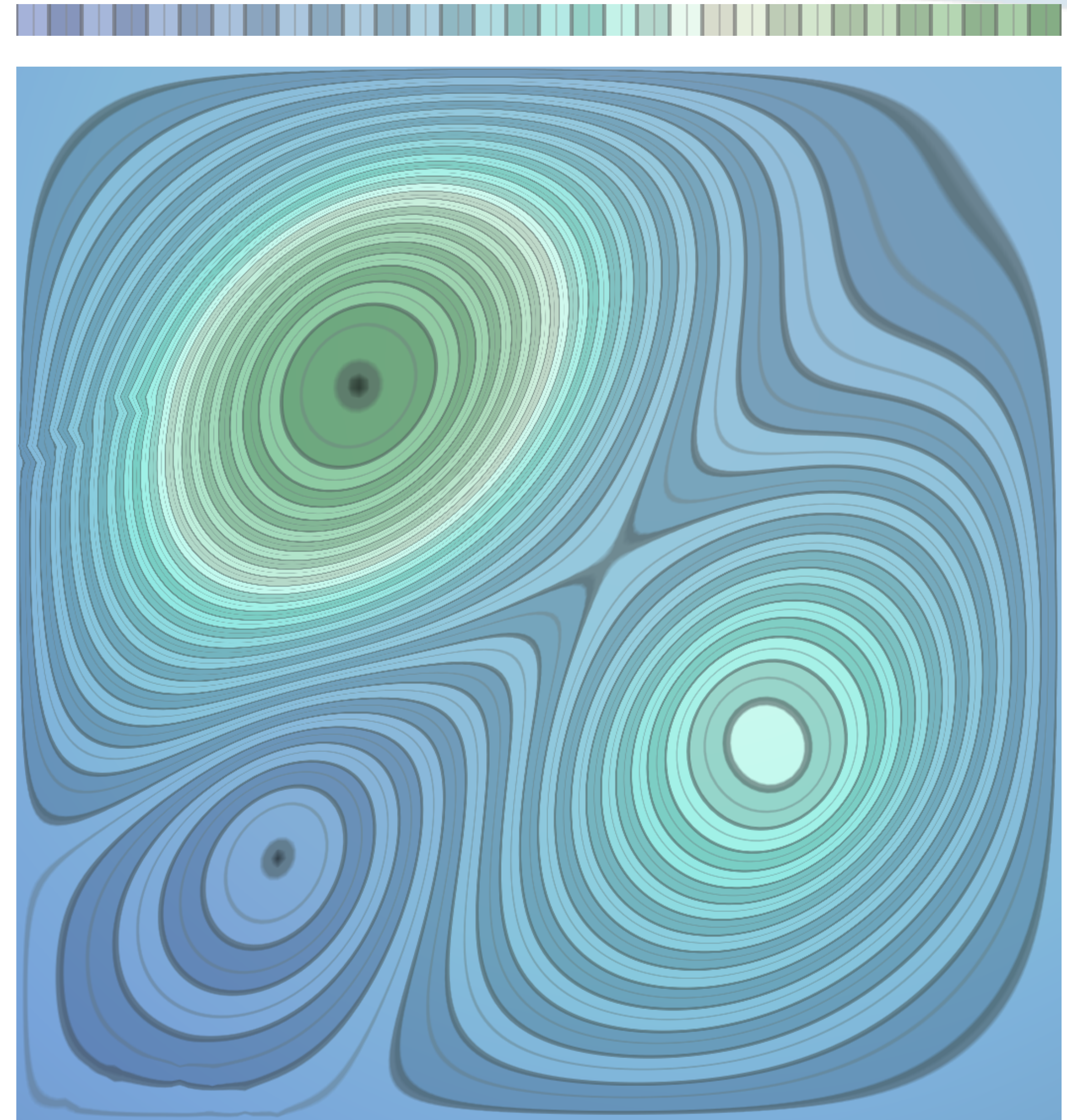
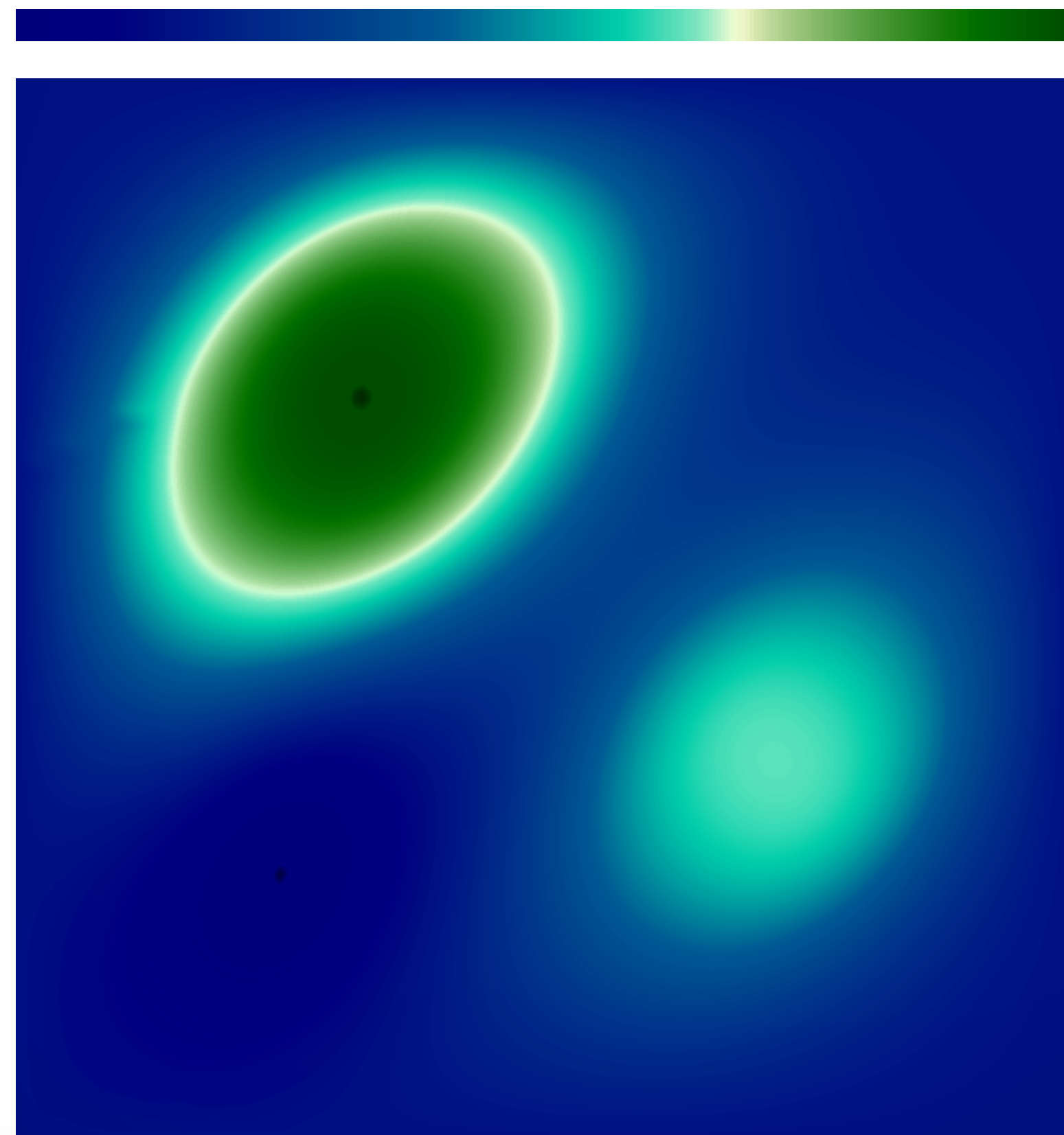
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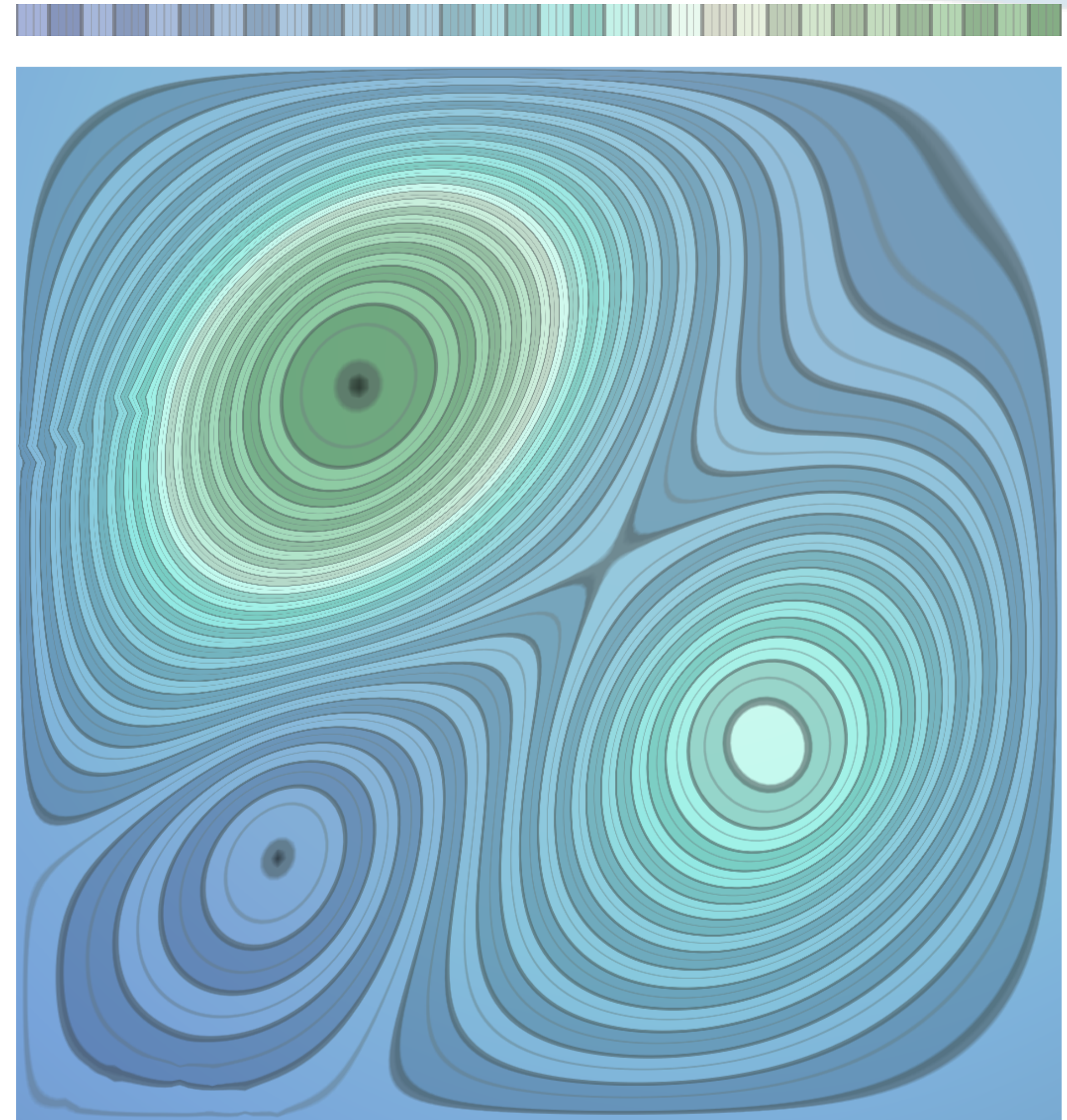
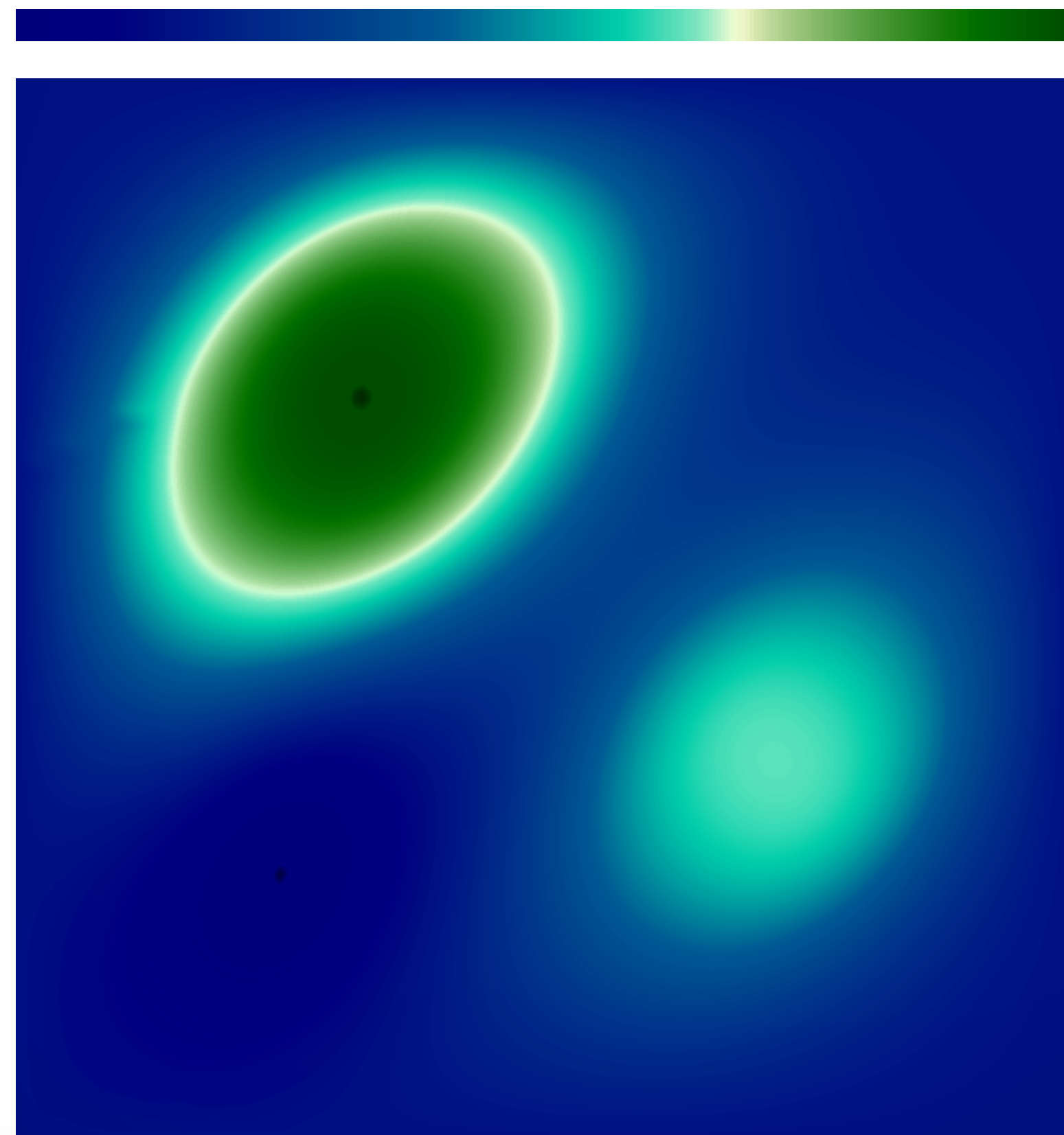
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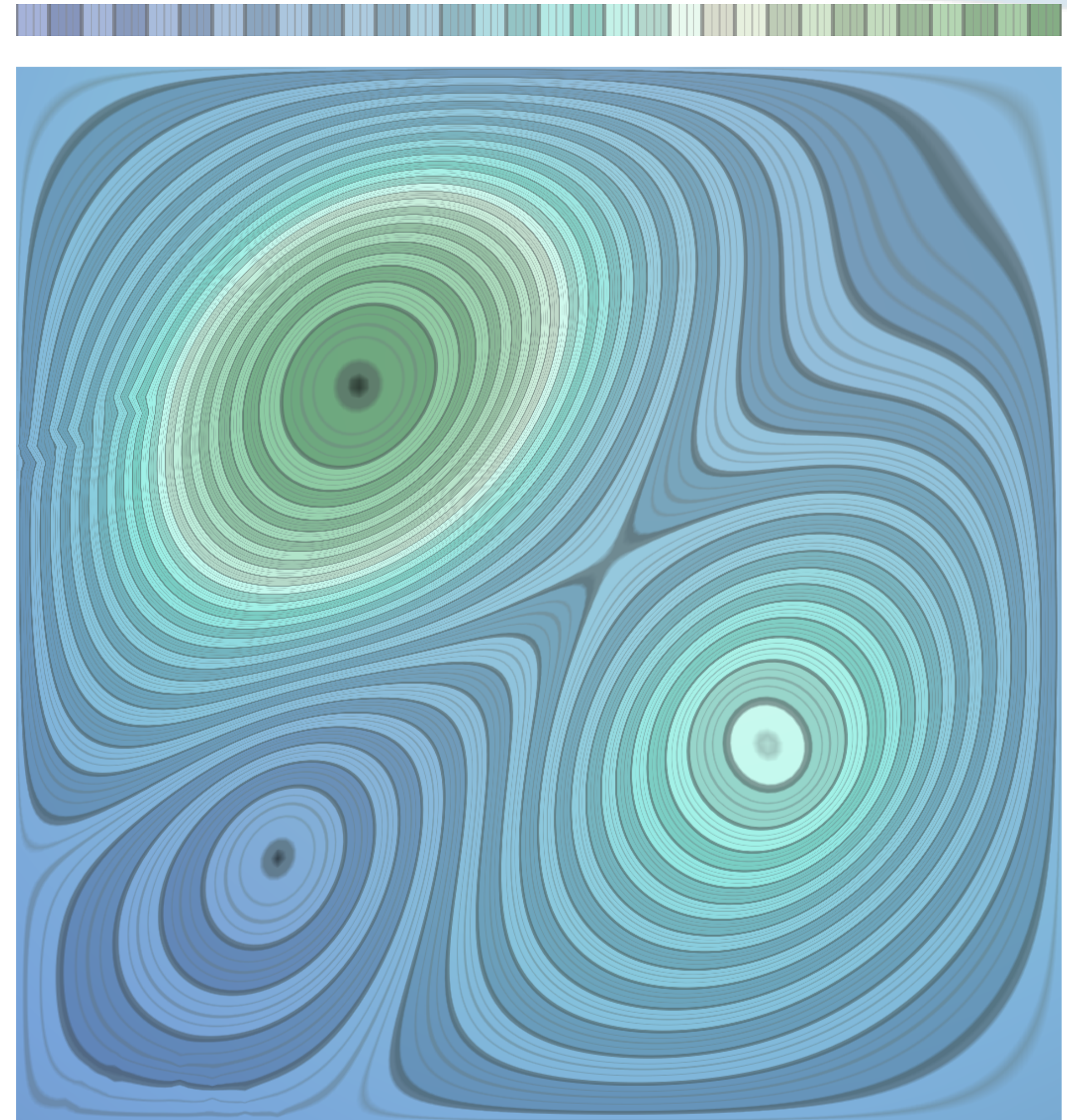
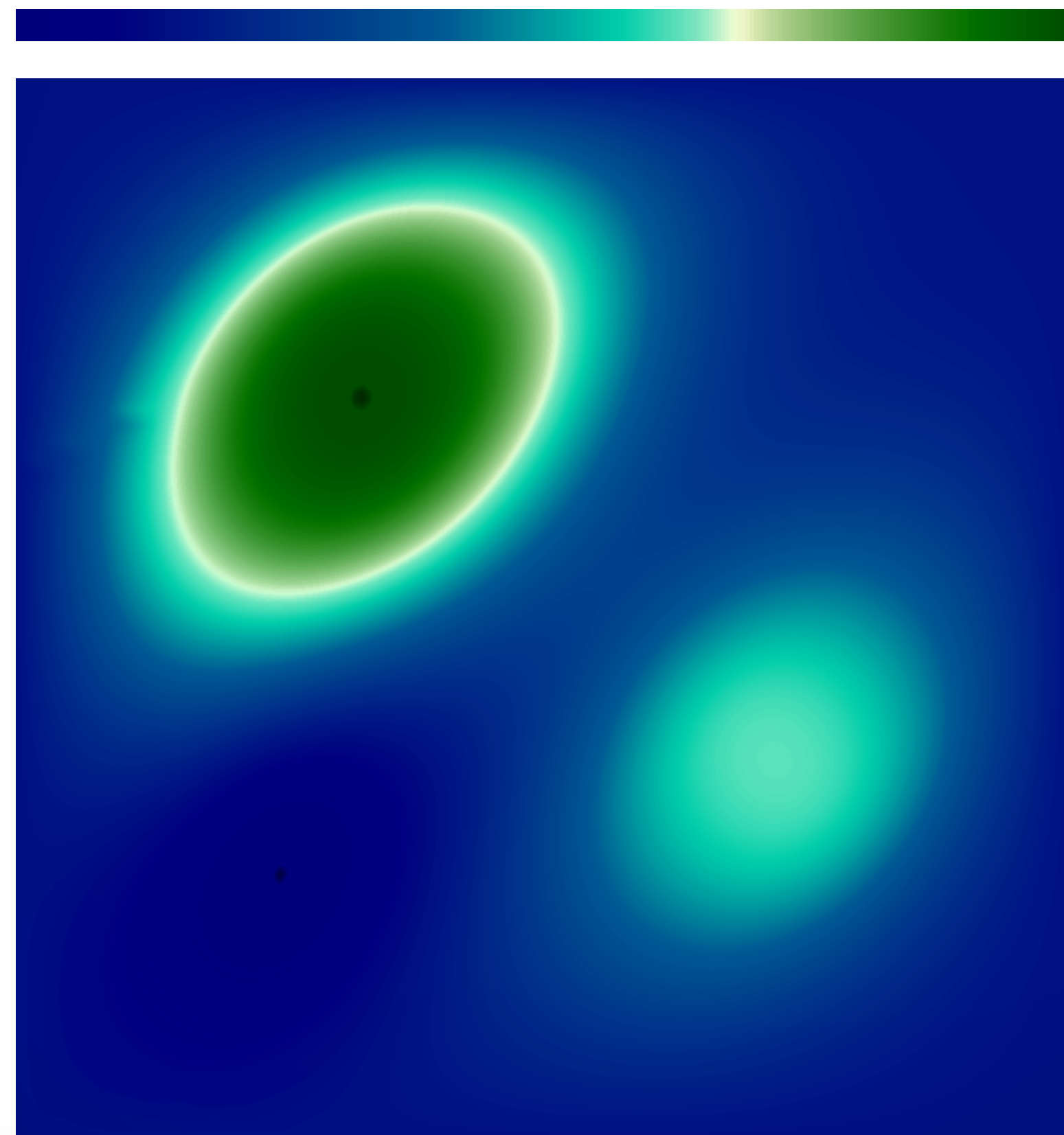
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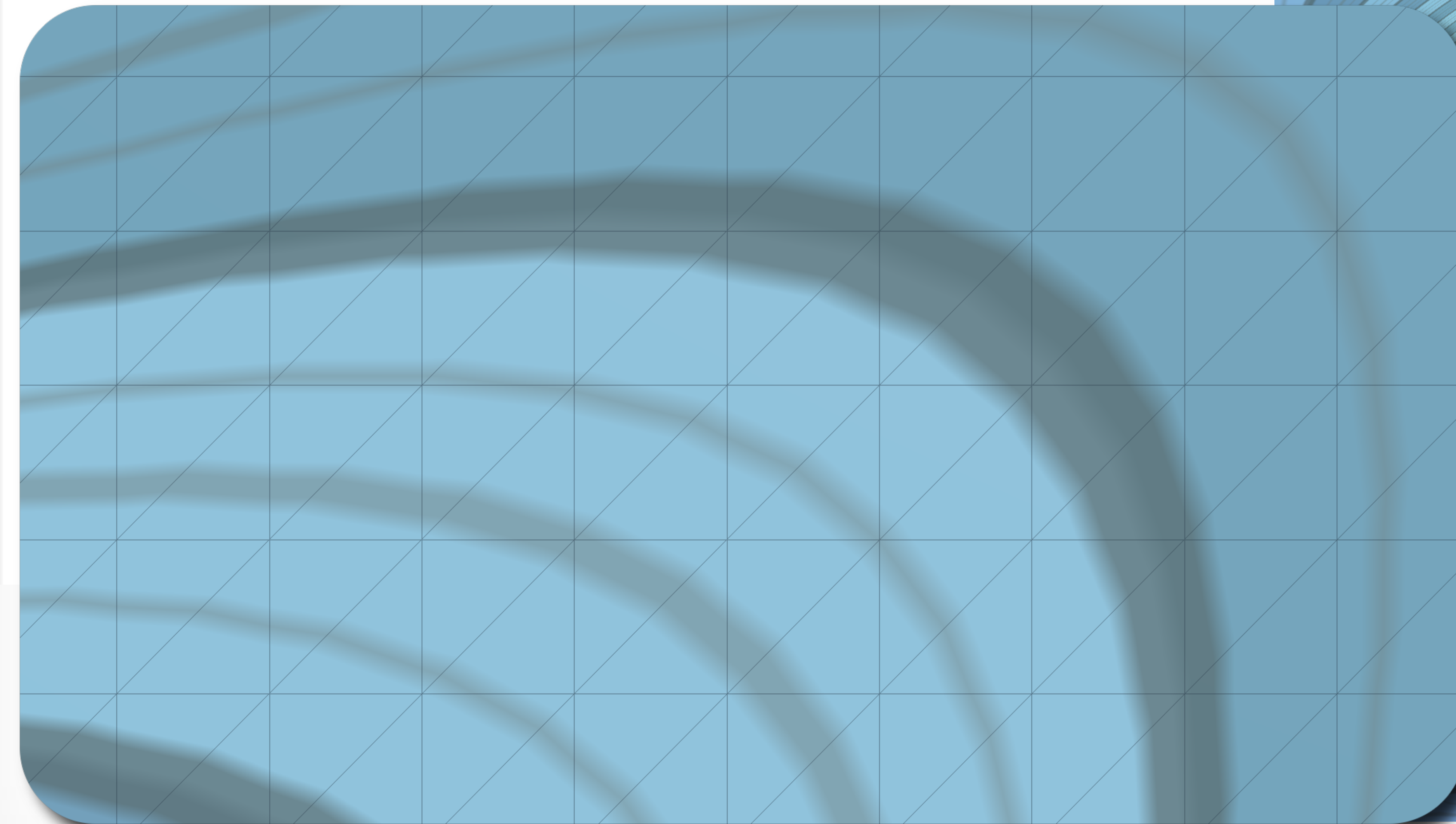
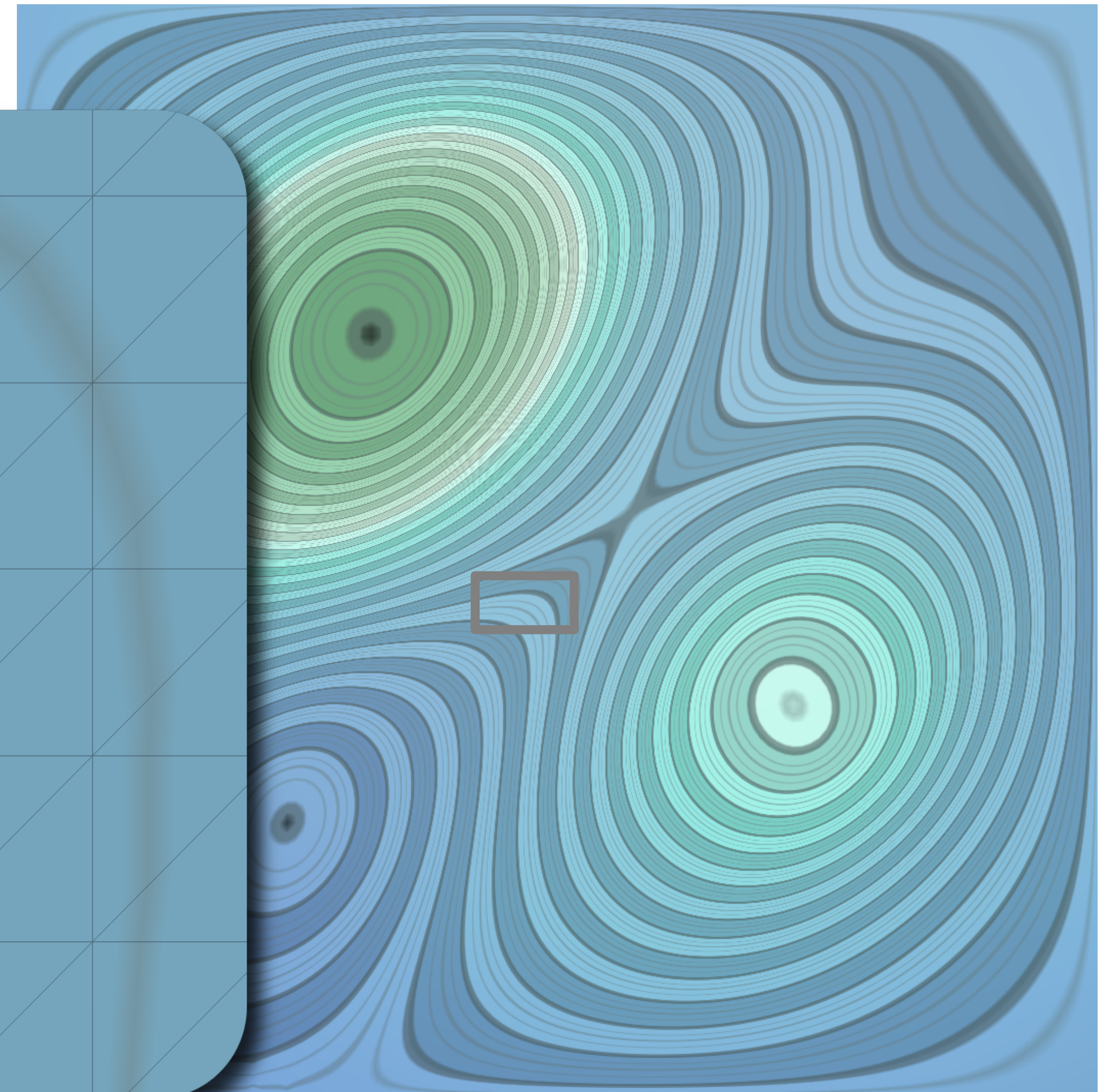
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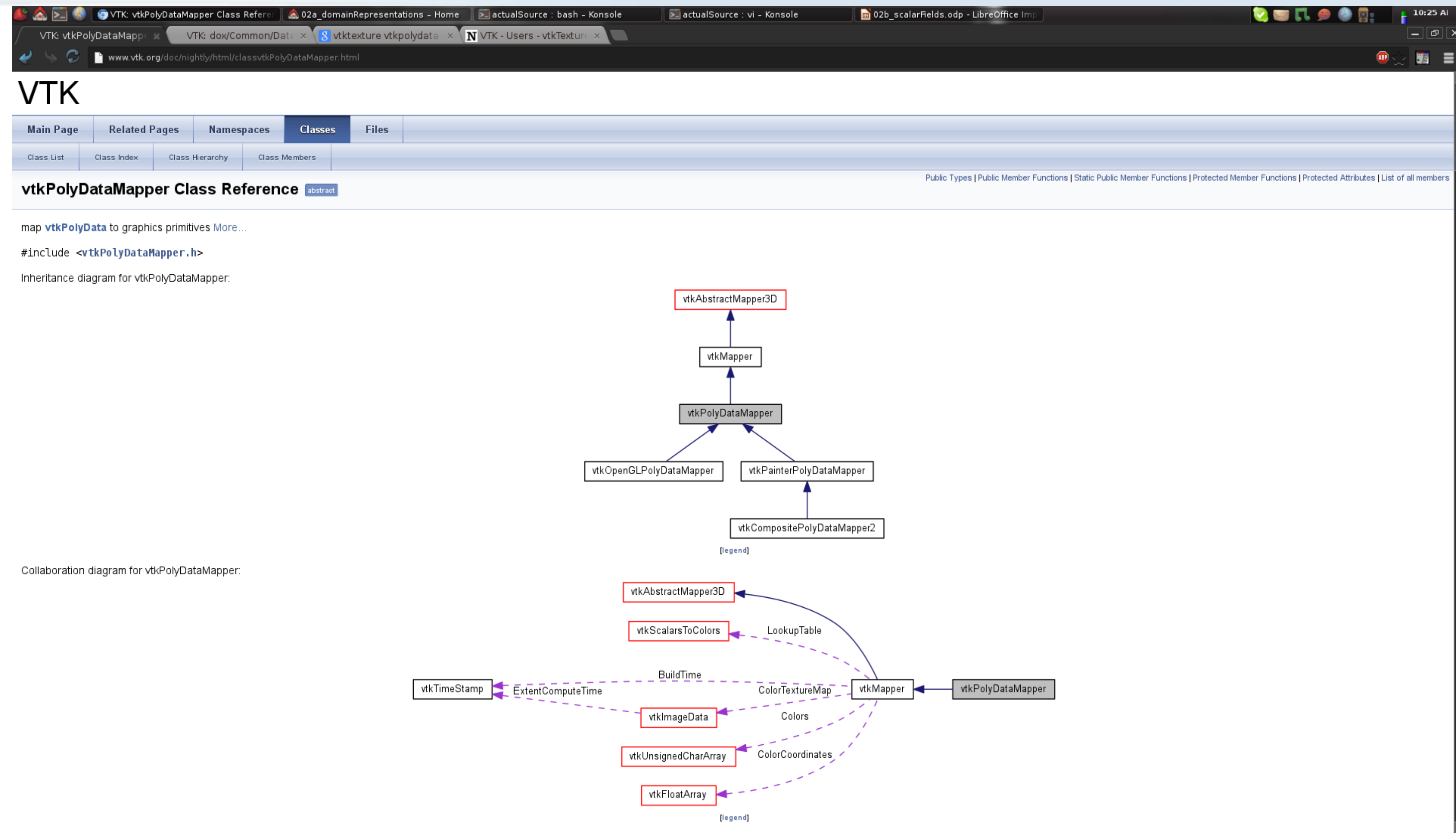
Color maps for scalar field visualization

- Implicit level set visualization



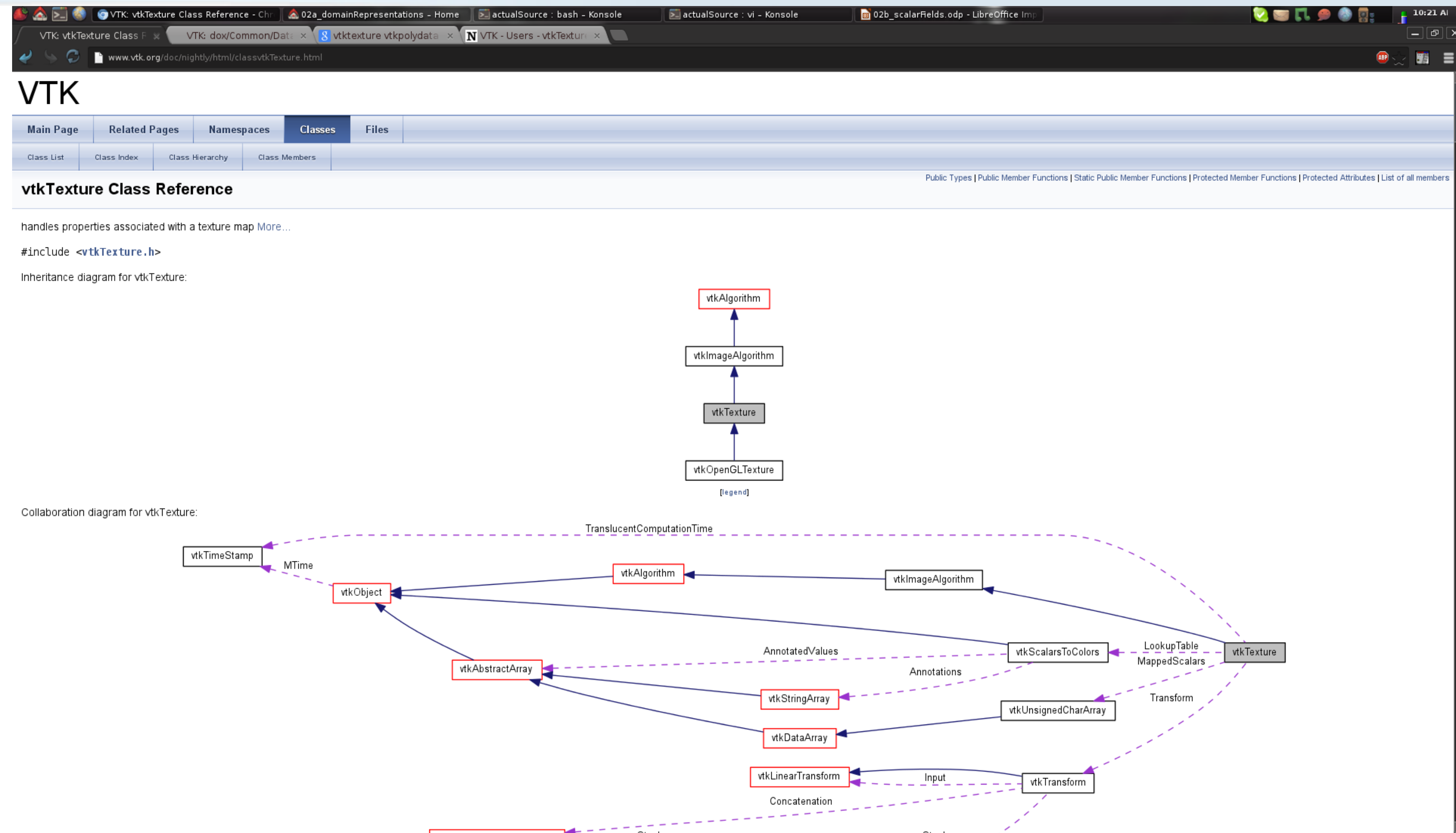
In practice

- VTK PolyDataMapper (2D)
 - Handles texture coordinates
 - Input: VTK PolyData



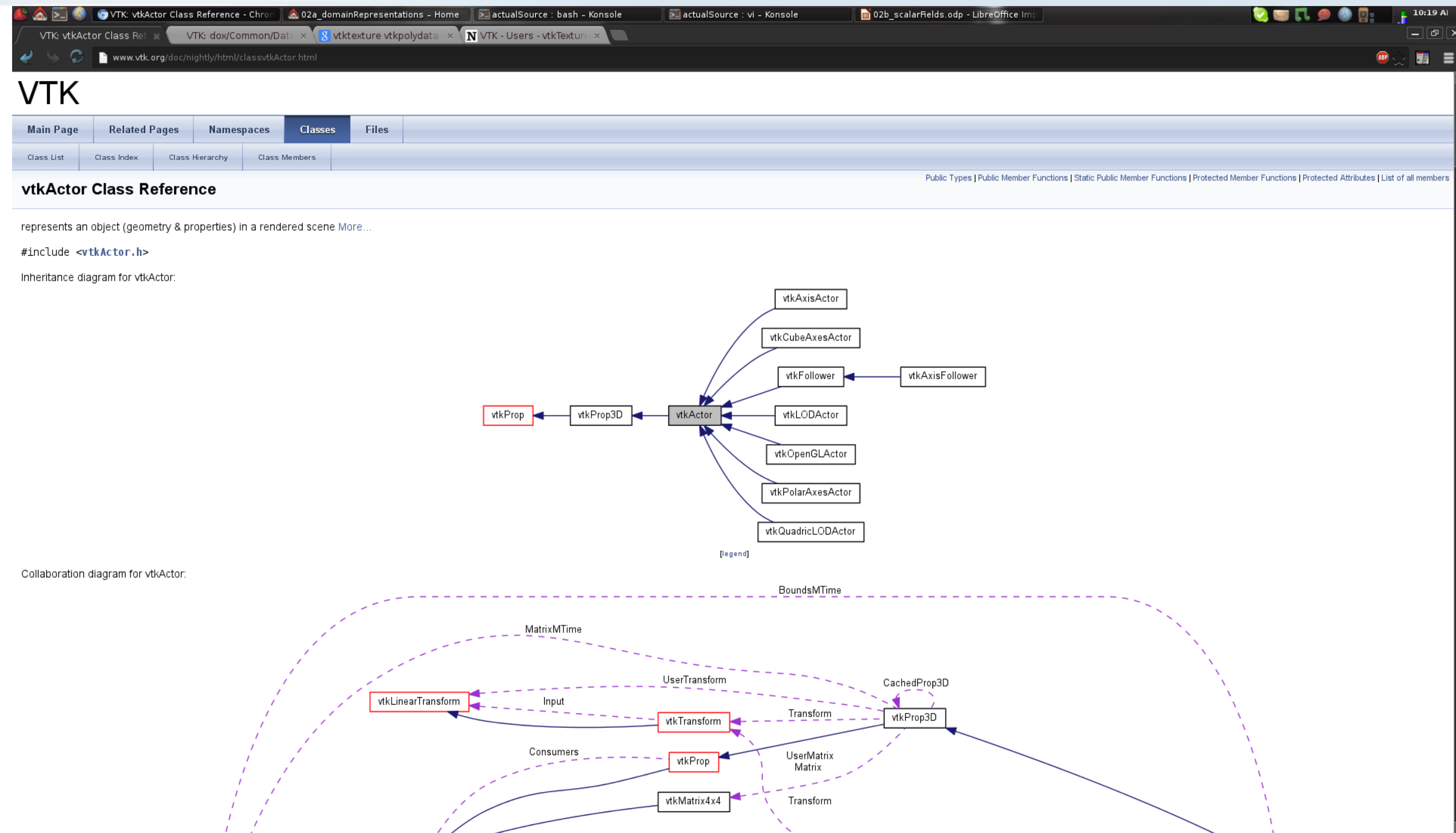
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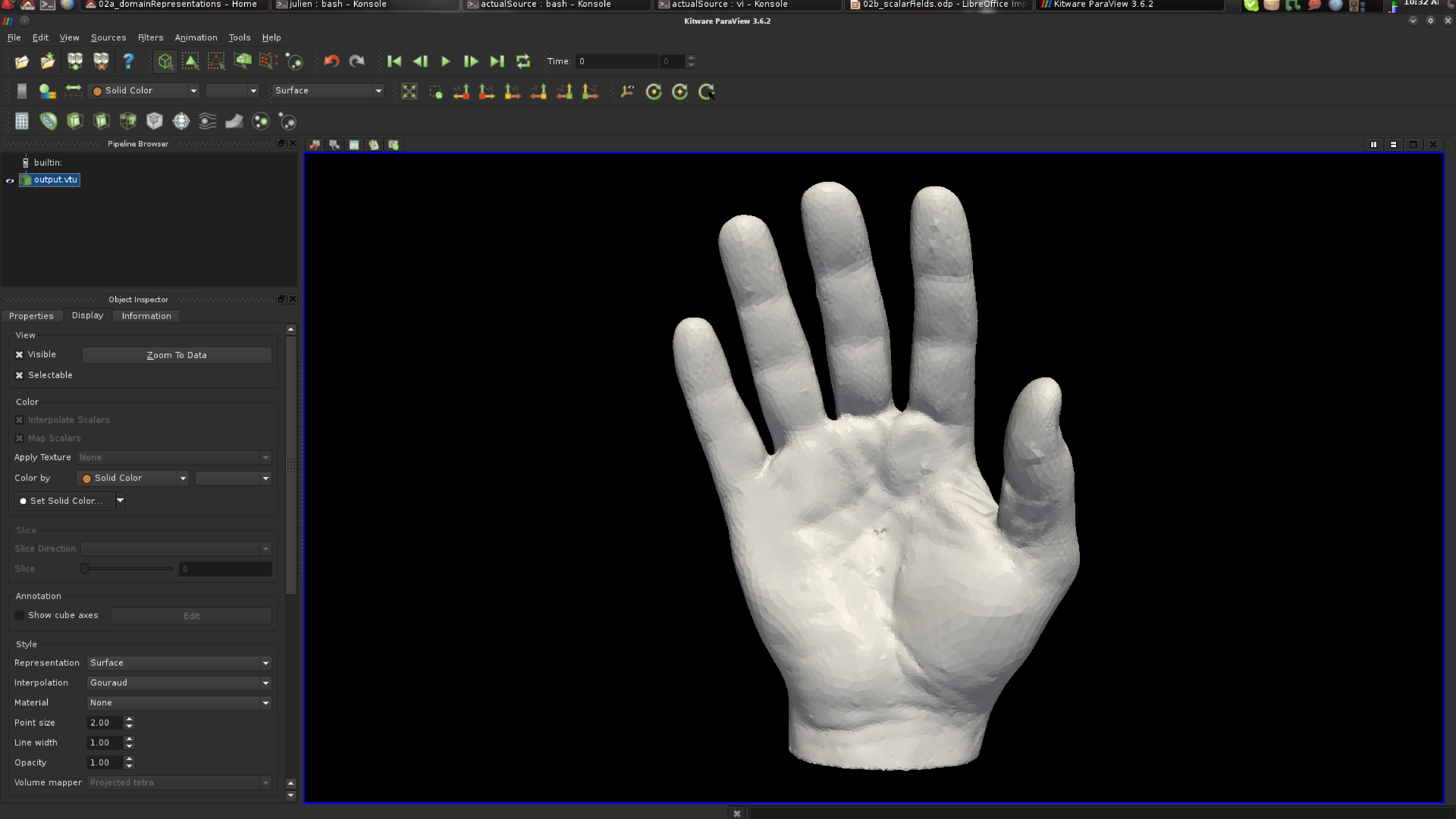
- VTK PolyDataMapper (2D)
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- VTK Texture
 - Represents a texture

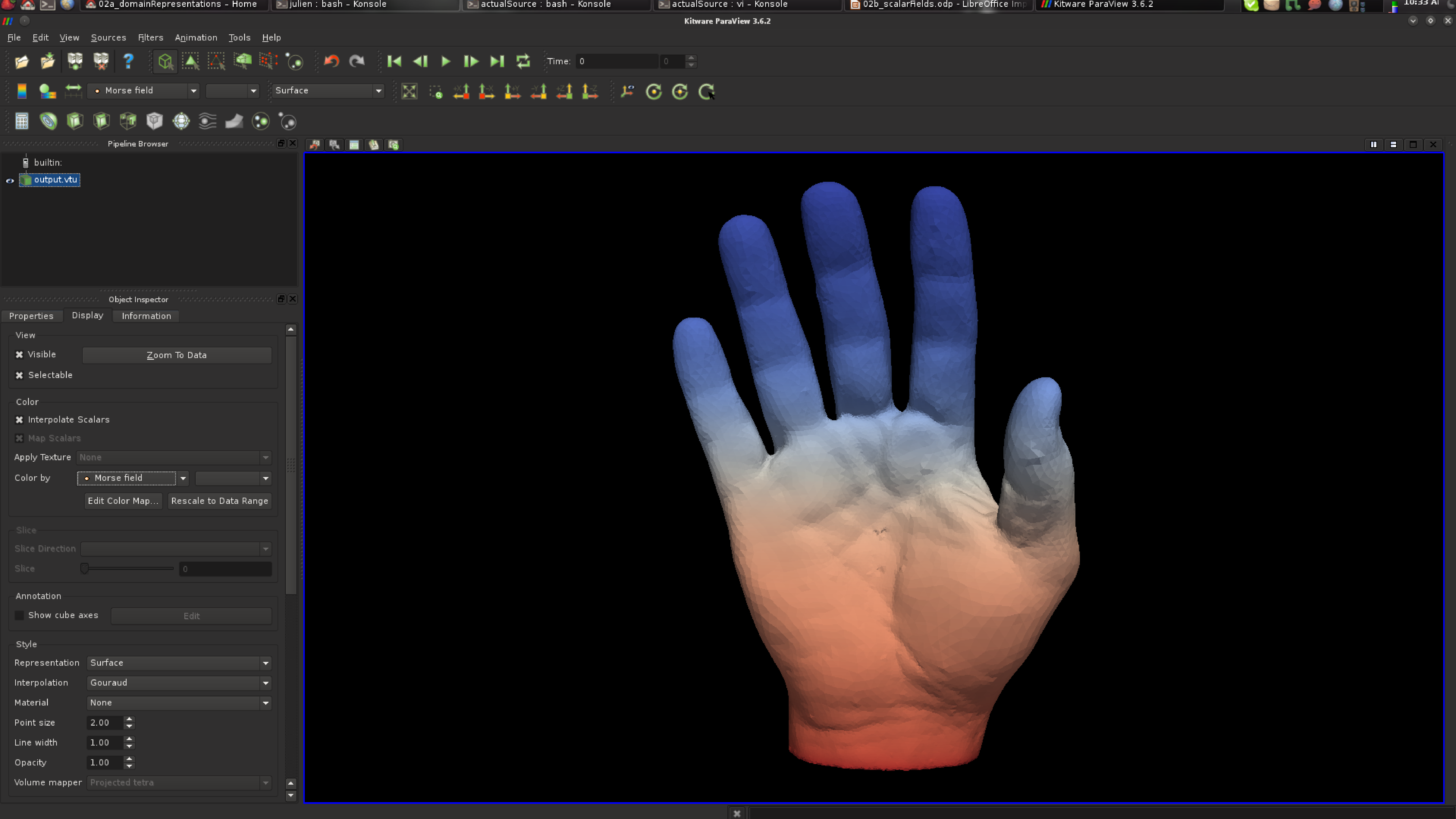


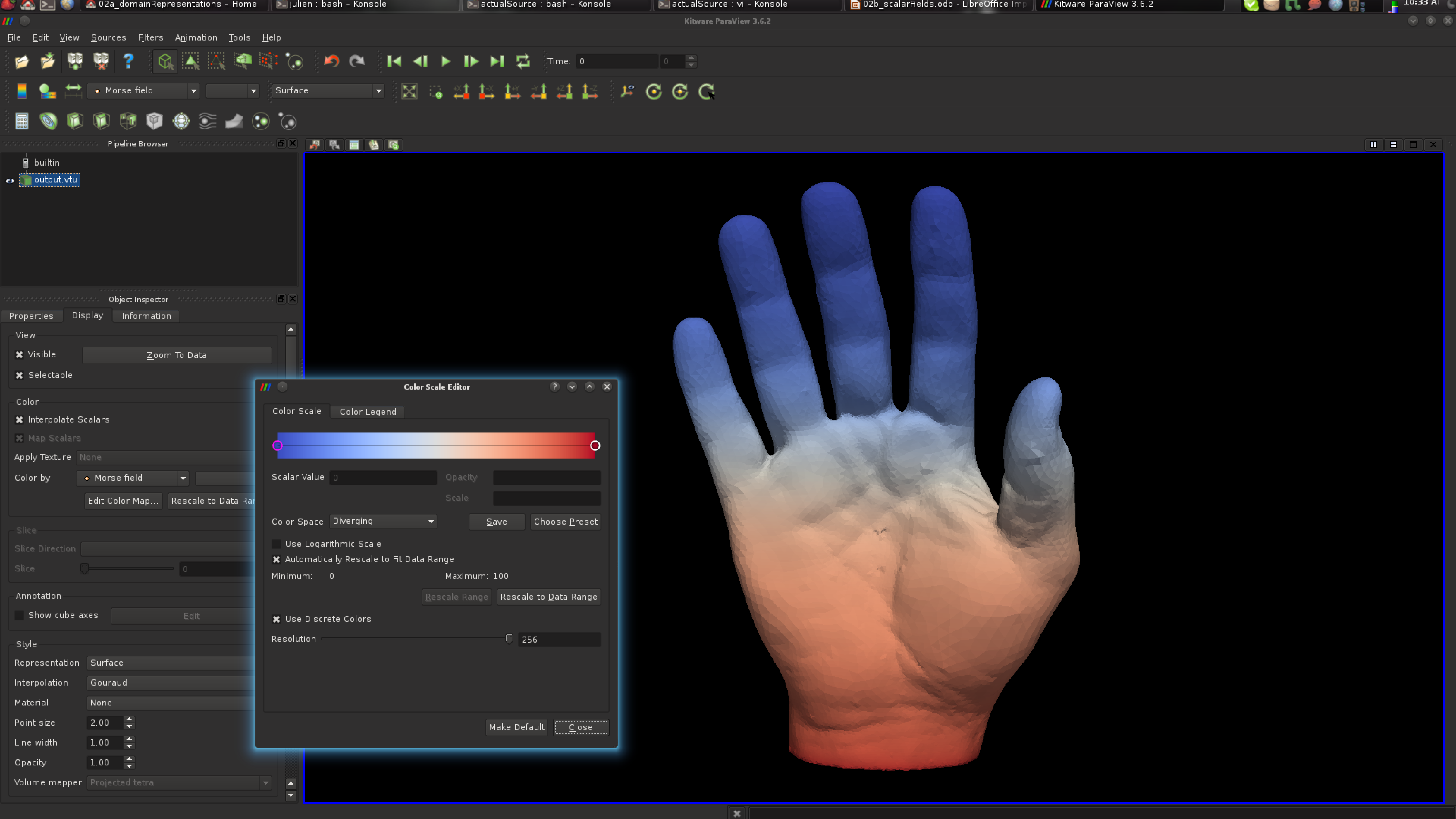
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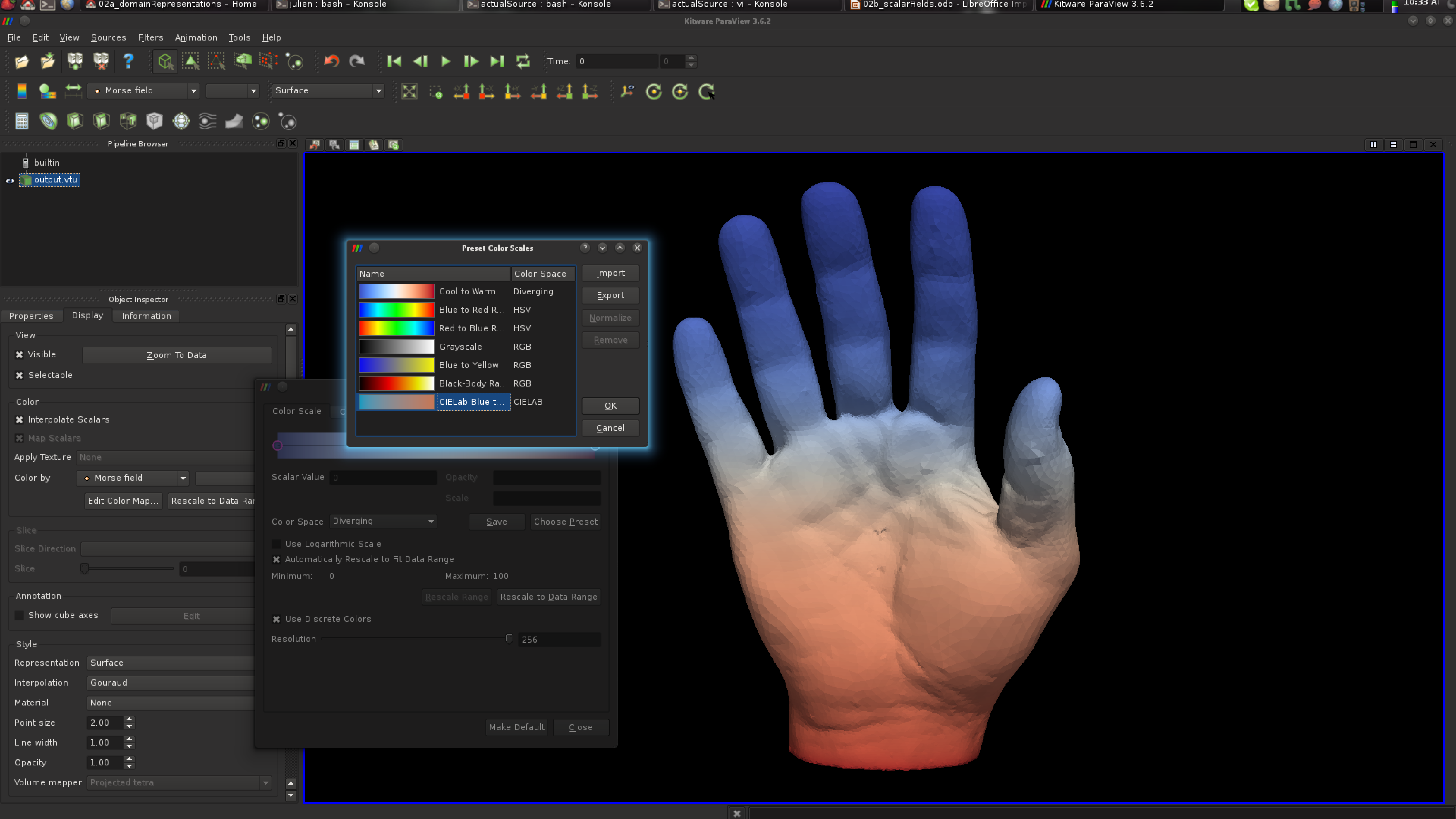
- VTK PolyDataMapper (2D)
 - Handles texture coordinates
 - Input: VTK PolyData
- VTK Texture
 - Represents a texture
- VTK Actor
 - Object representation for rendering
 - Inputs: texture and mapper

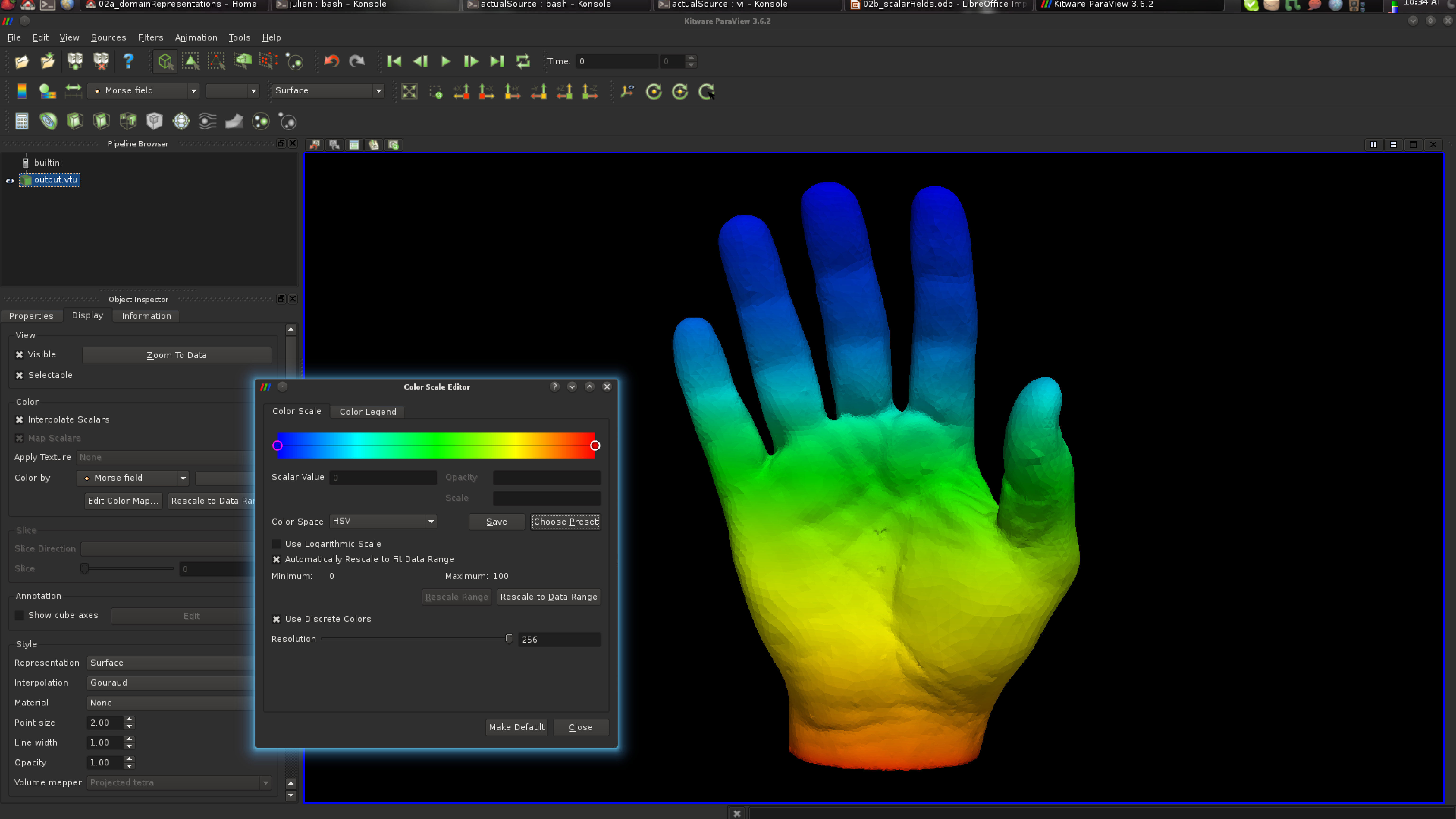






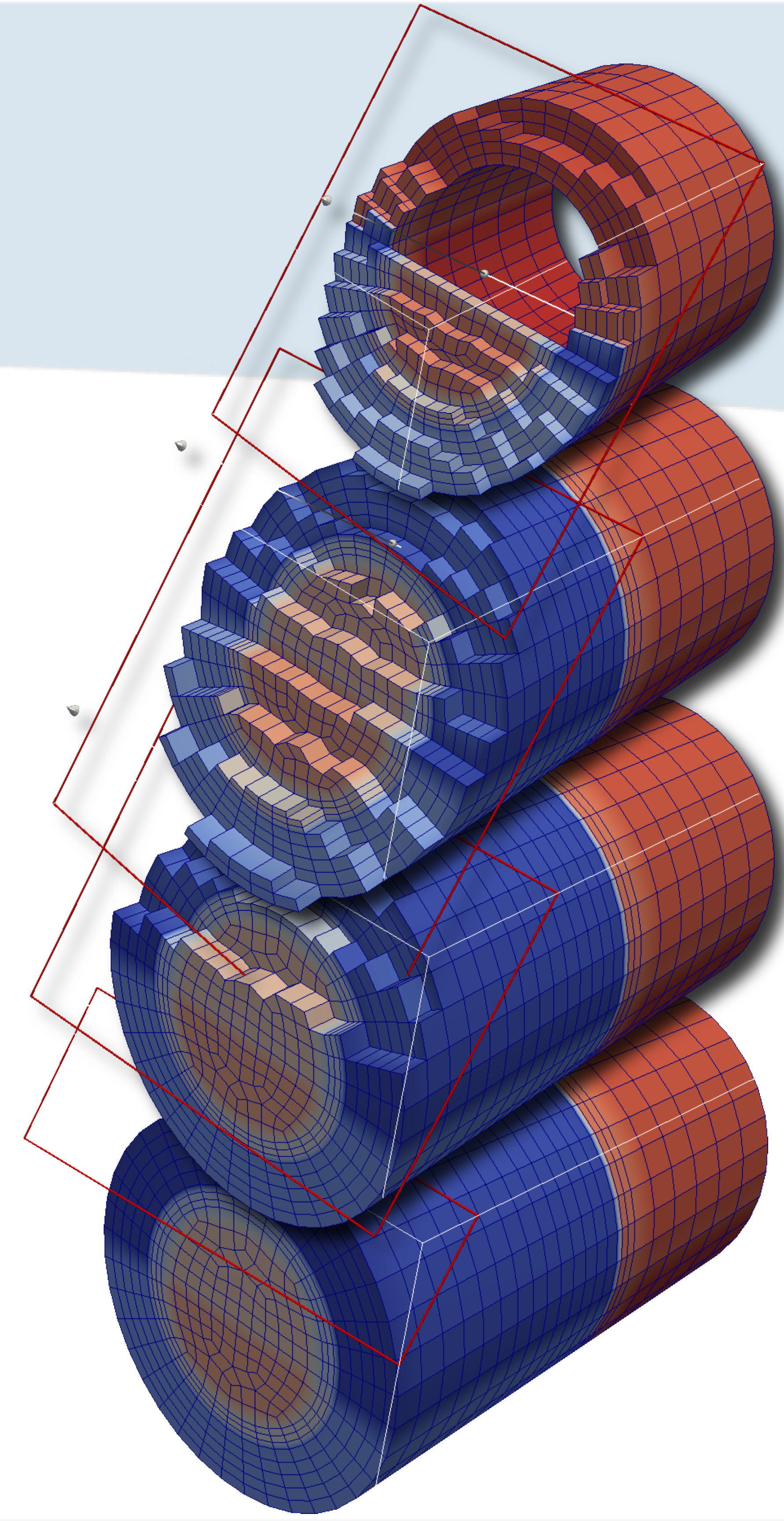






Color maps

- Not really useful for volumetric domains



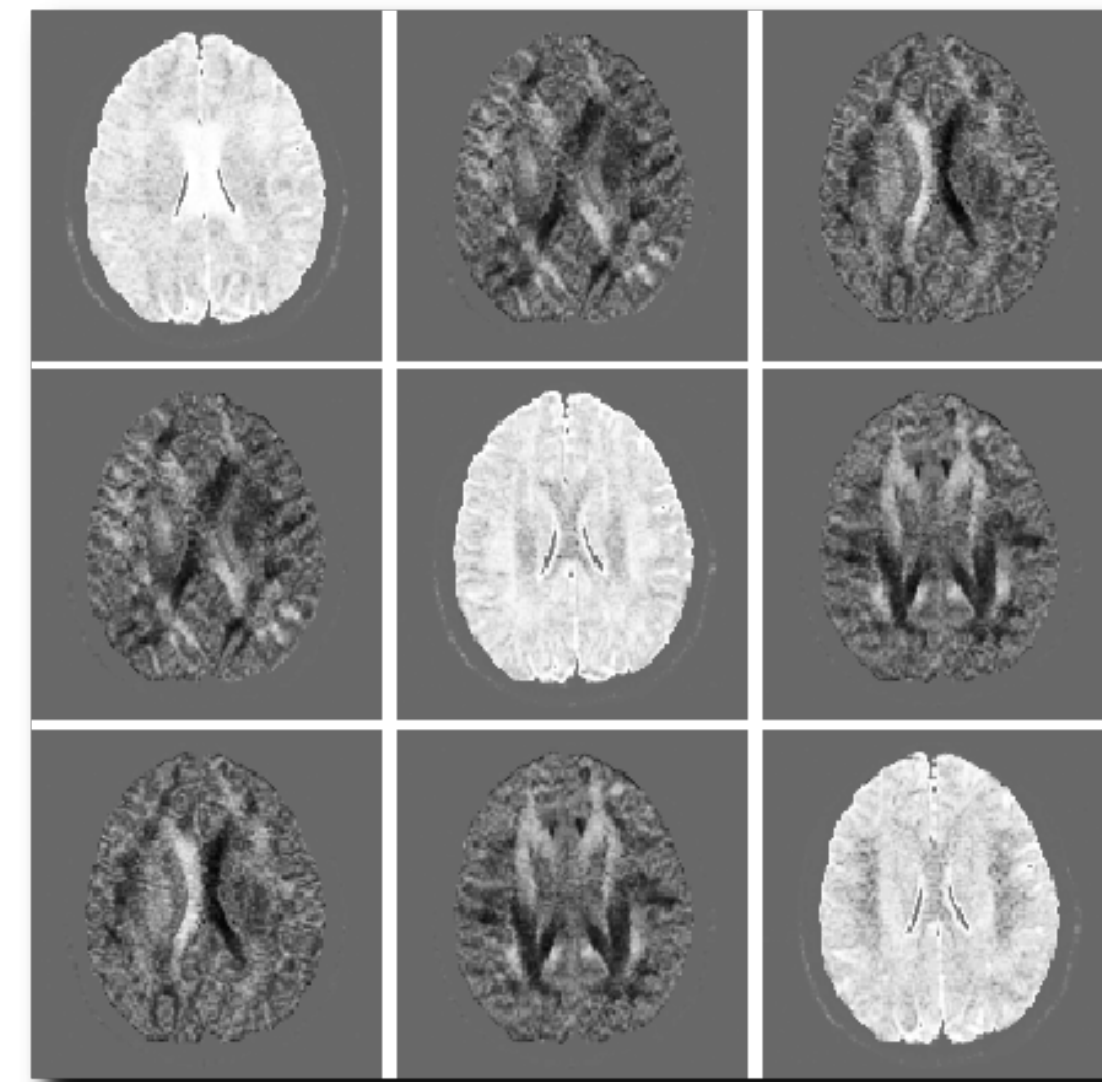
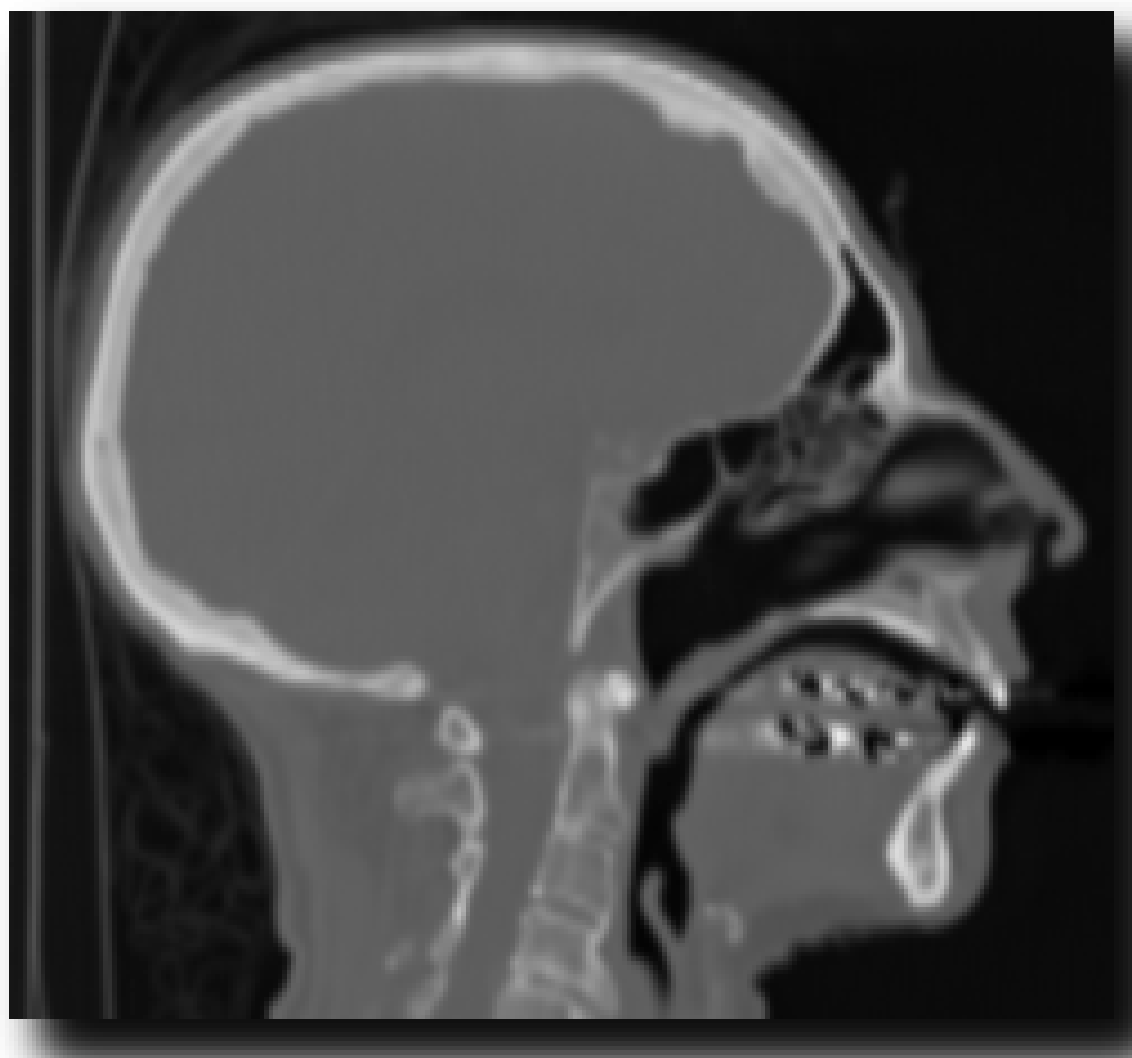
Color maps

- Not really useful for volumetric domains
 - Mimic Superman's supervision
 - Represent in an *intelligible* manner the interior



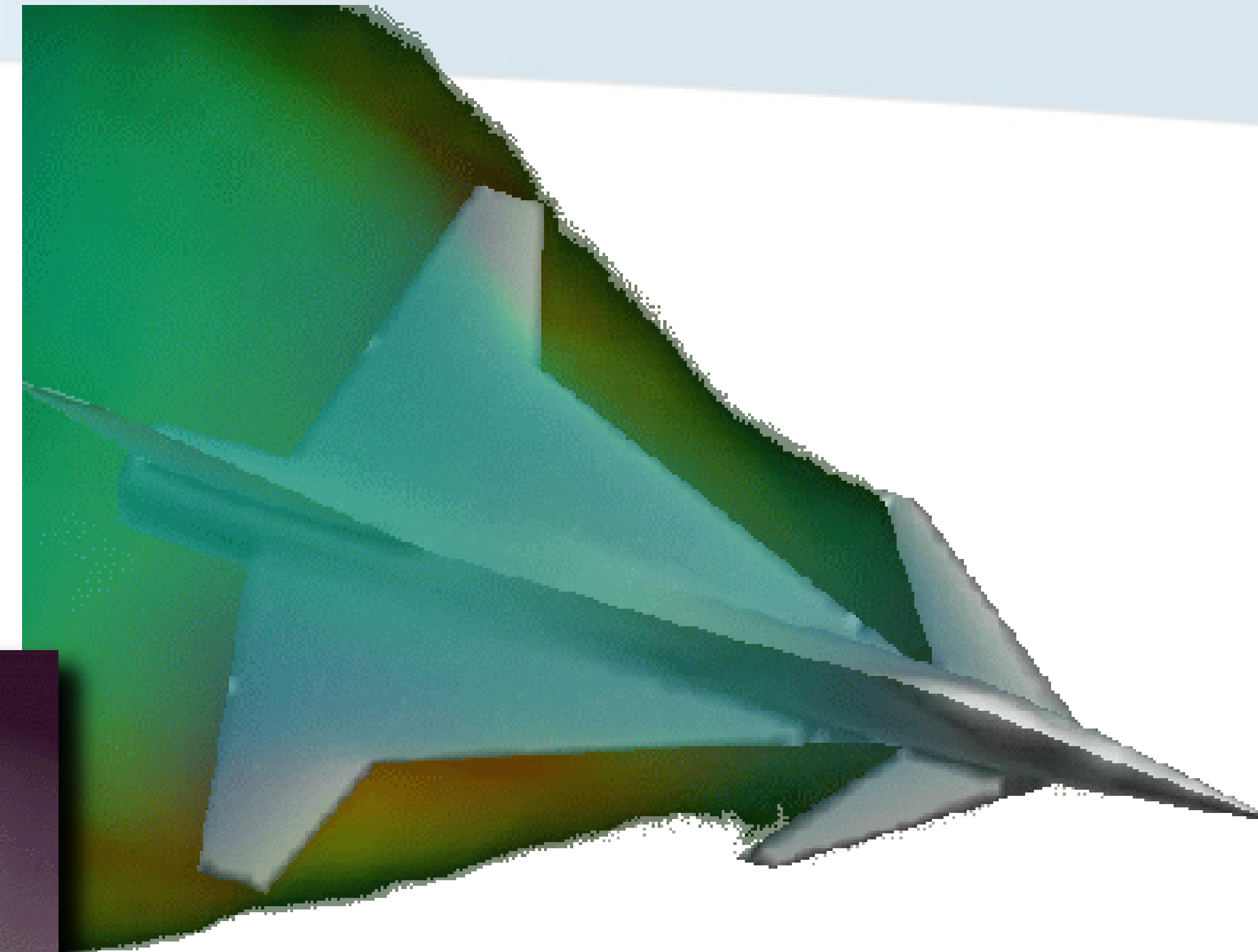
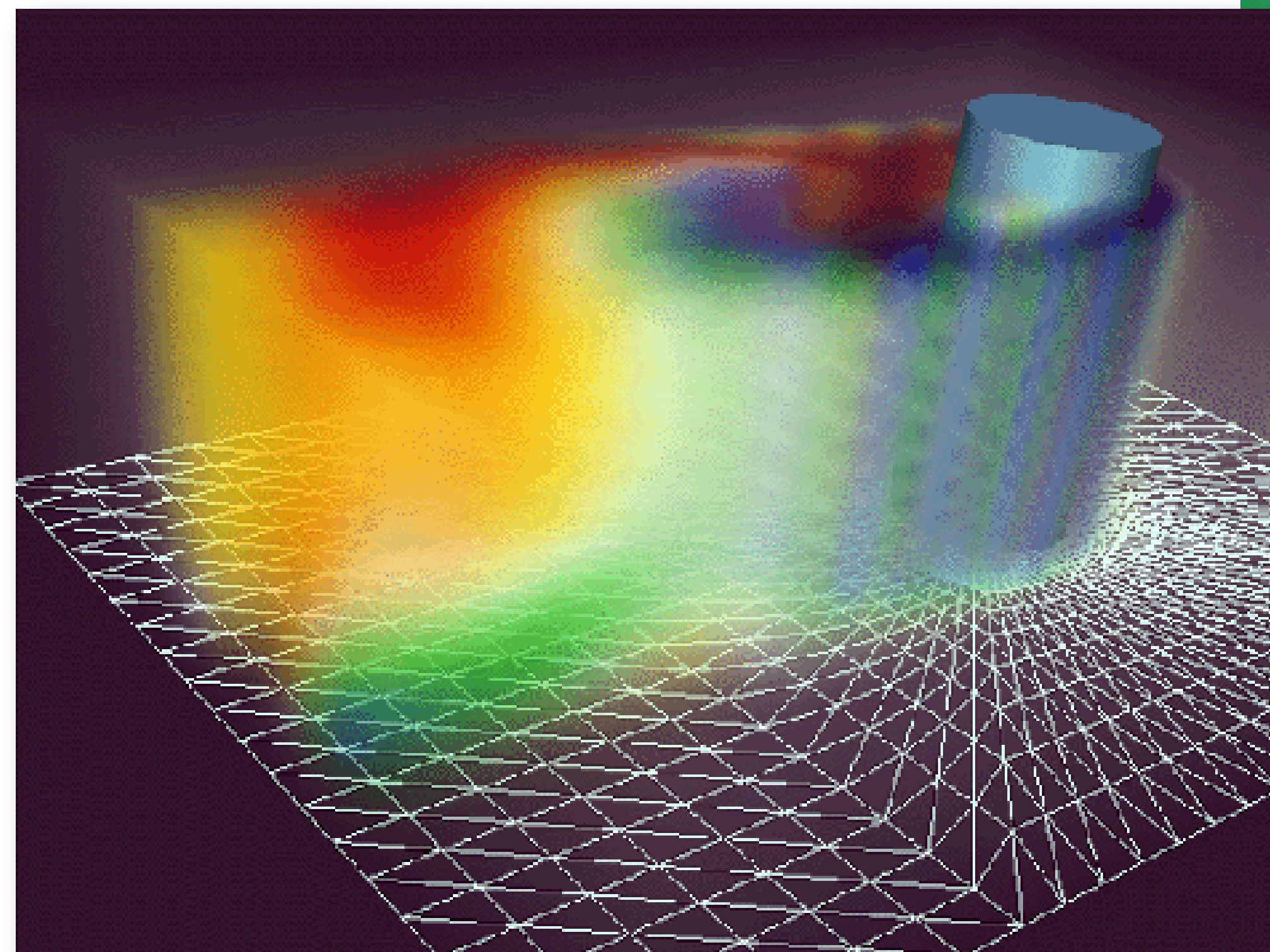
Volume rendering motivations

- Volumetric scalar fields
 - Acquired data-sets
 - Computed Tomography, Magnetic Reasonance, Ultrasound



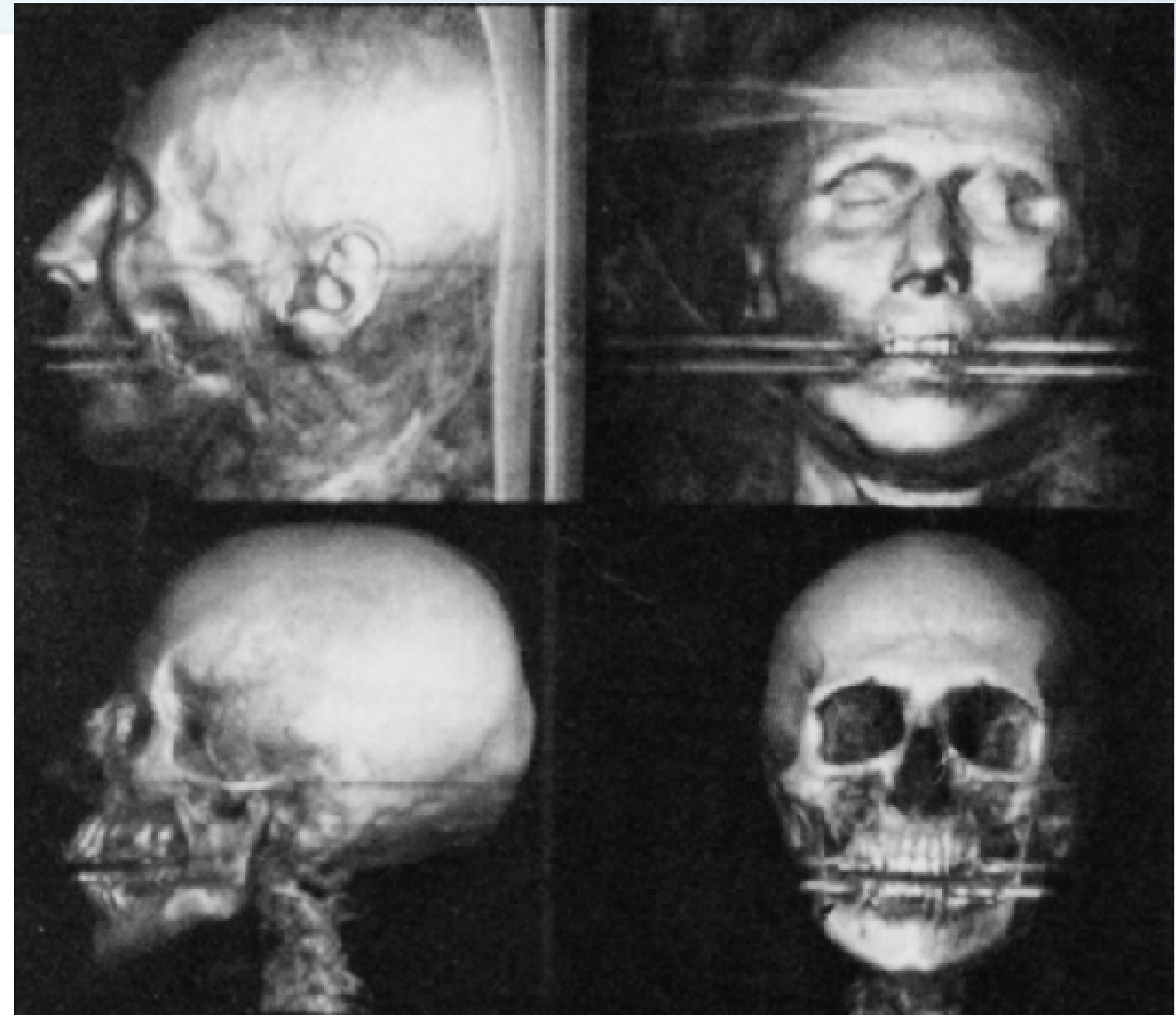
Volume rendering motivations

- Volumetric scalar fields
 - Simulated data-sets
 - Fluid dynamics
 - Pressure
 - Porosity
 - Temperature
 - Etc.



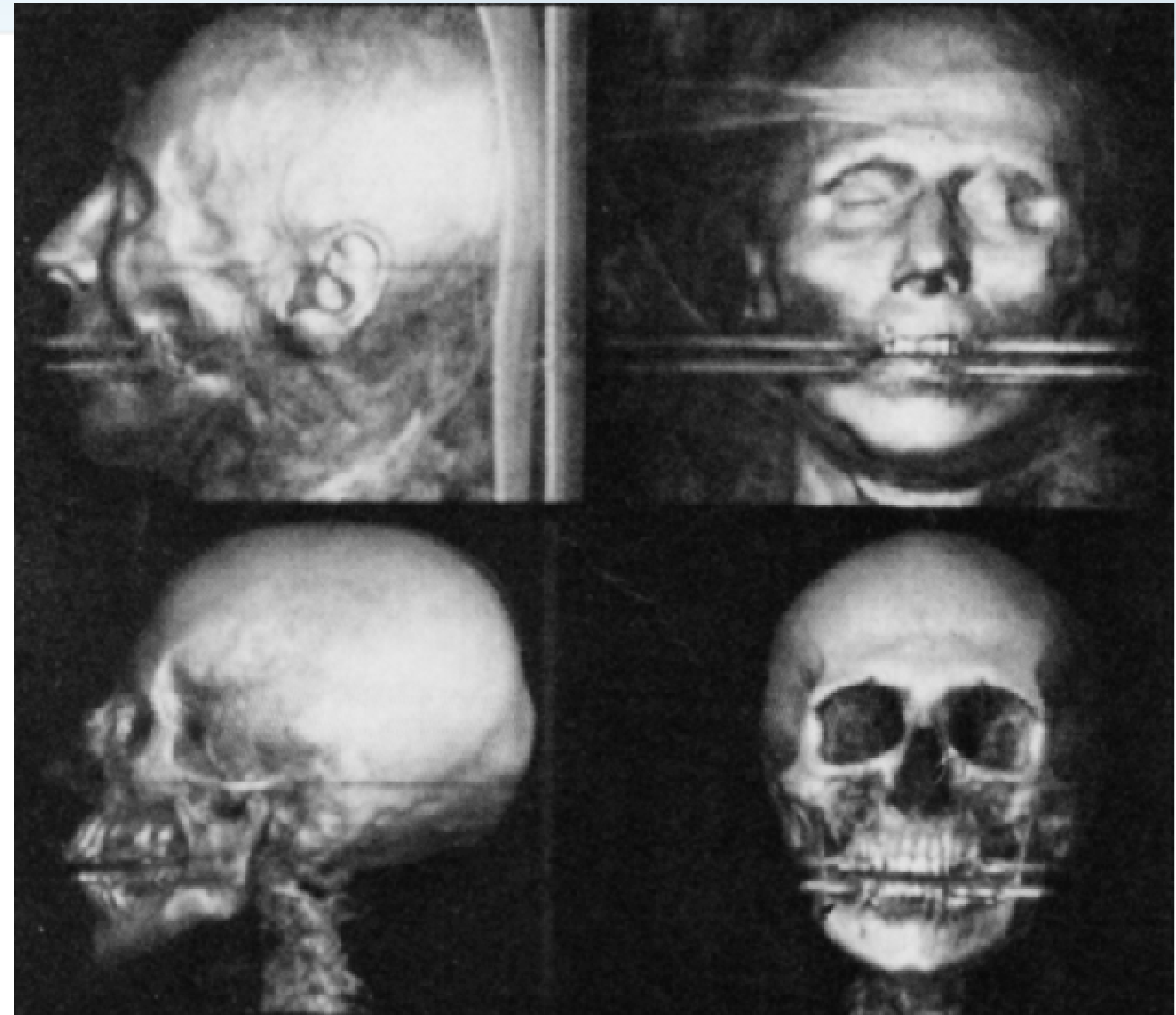
Volume rendering motivations

- Specific features
 - Represents all the field
 - Not only a few specific values
 - Many “layers”



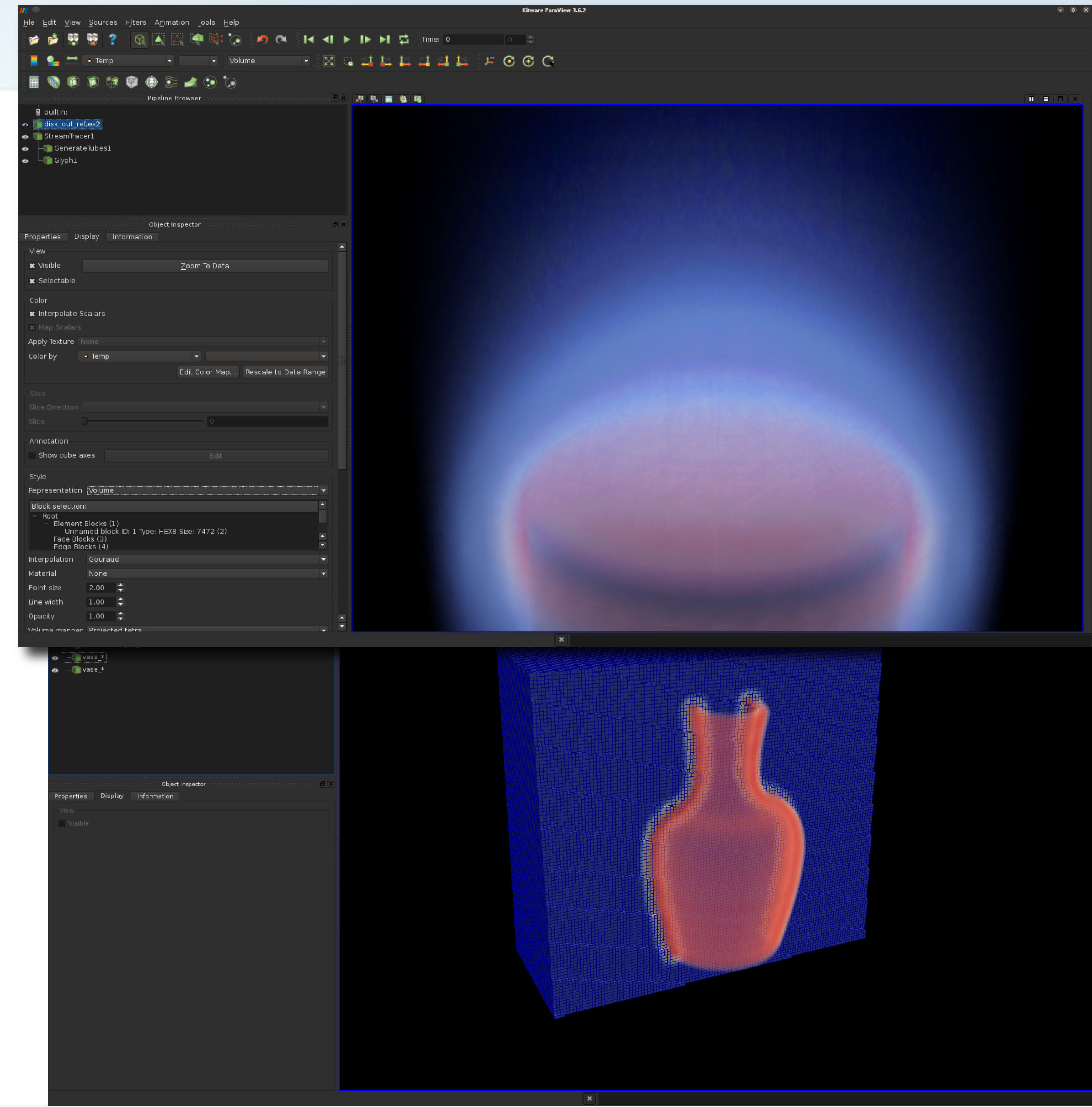
Volume rendering motivations

- Specific features
 - Represents all the field
 - Not only a few specific values
 - Many “layers”
- Key idea
 - Every cell should contribute
 - Blending by integration
 - Greater flexibility



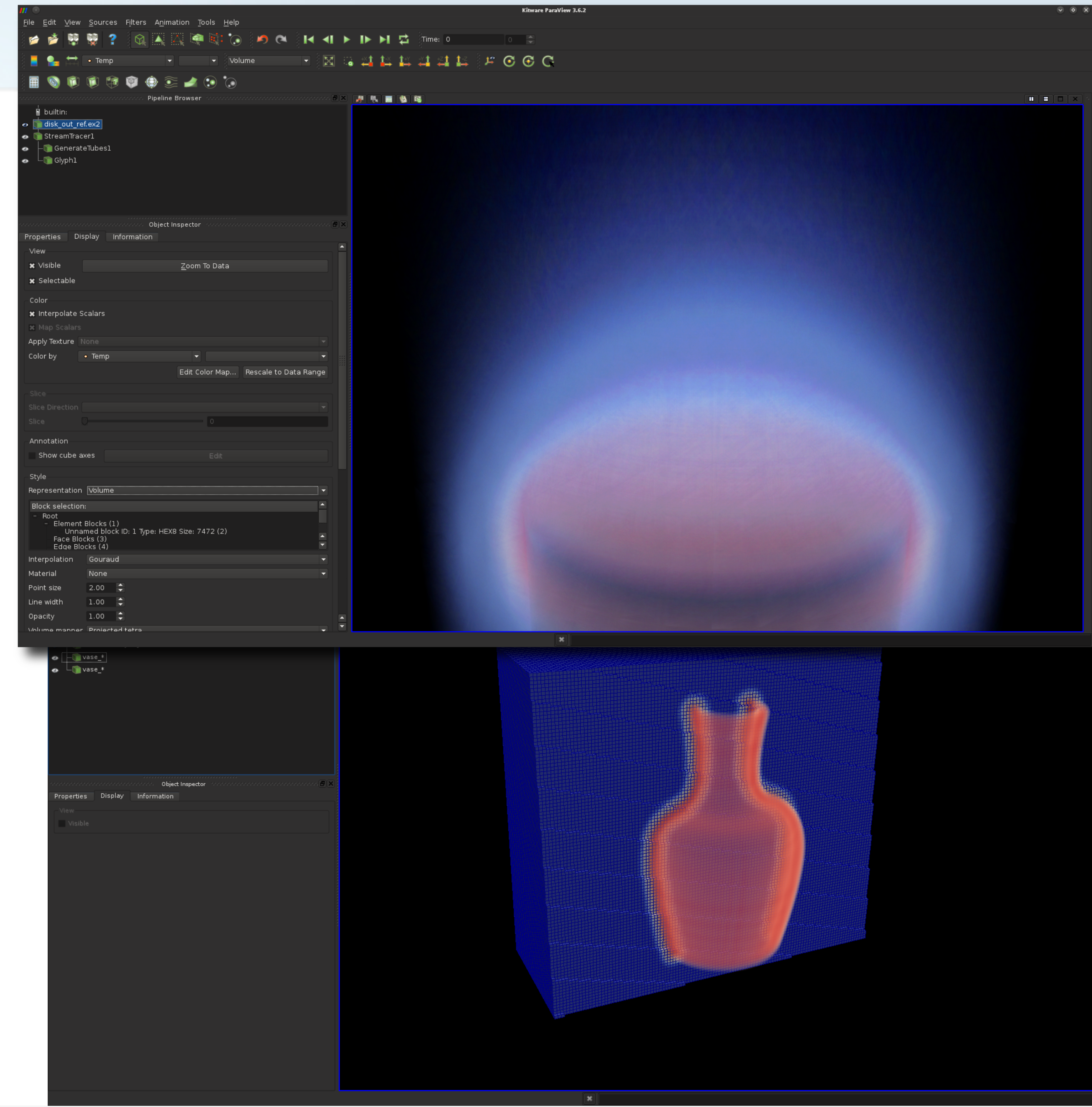
Volume rendering overview

- Rules to define



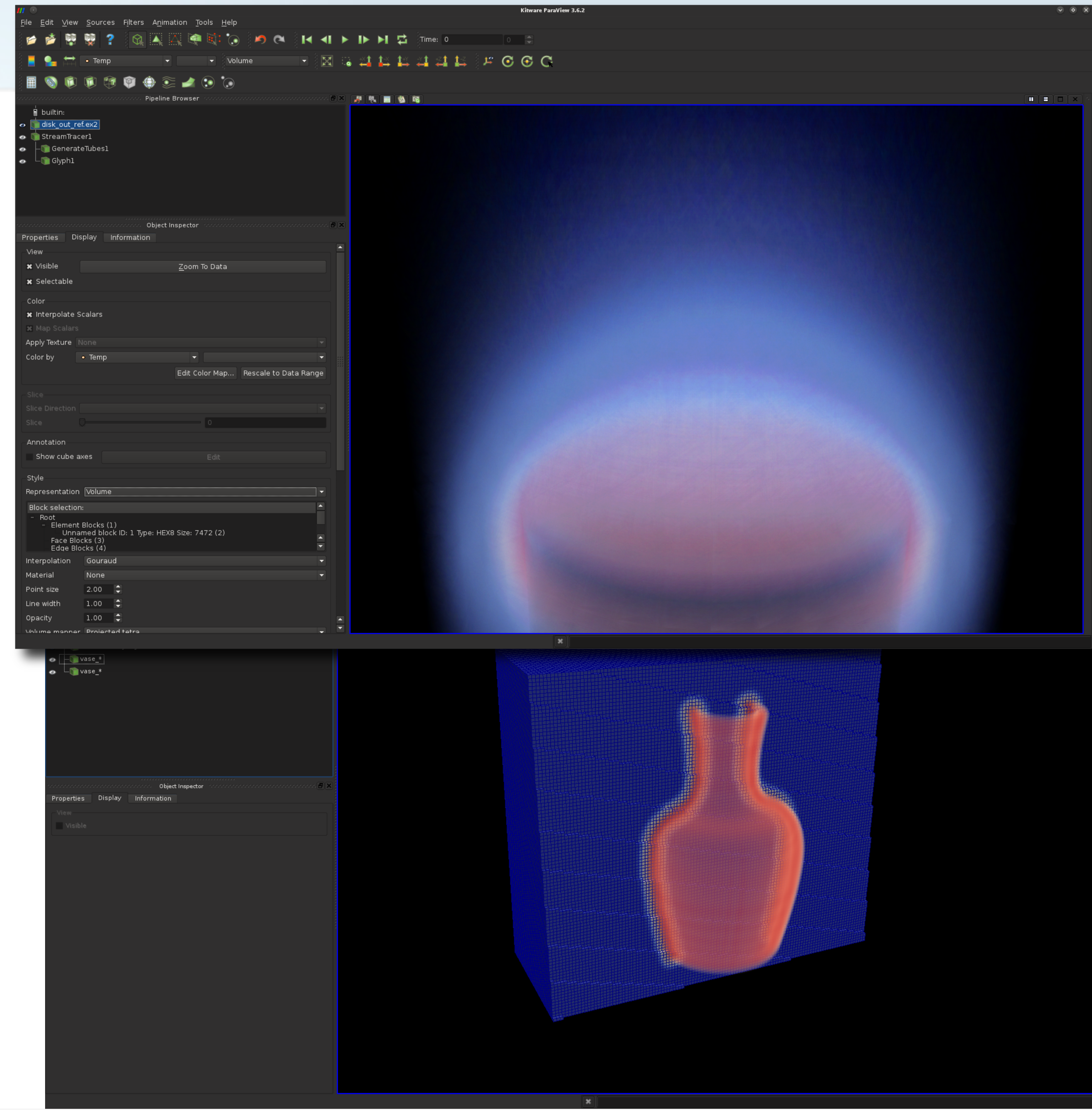
Volume rendering overview

- Rules to define
 - The properties of the “layers”



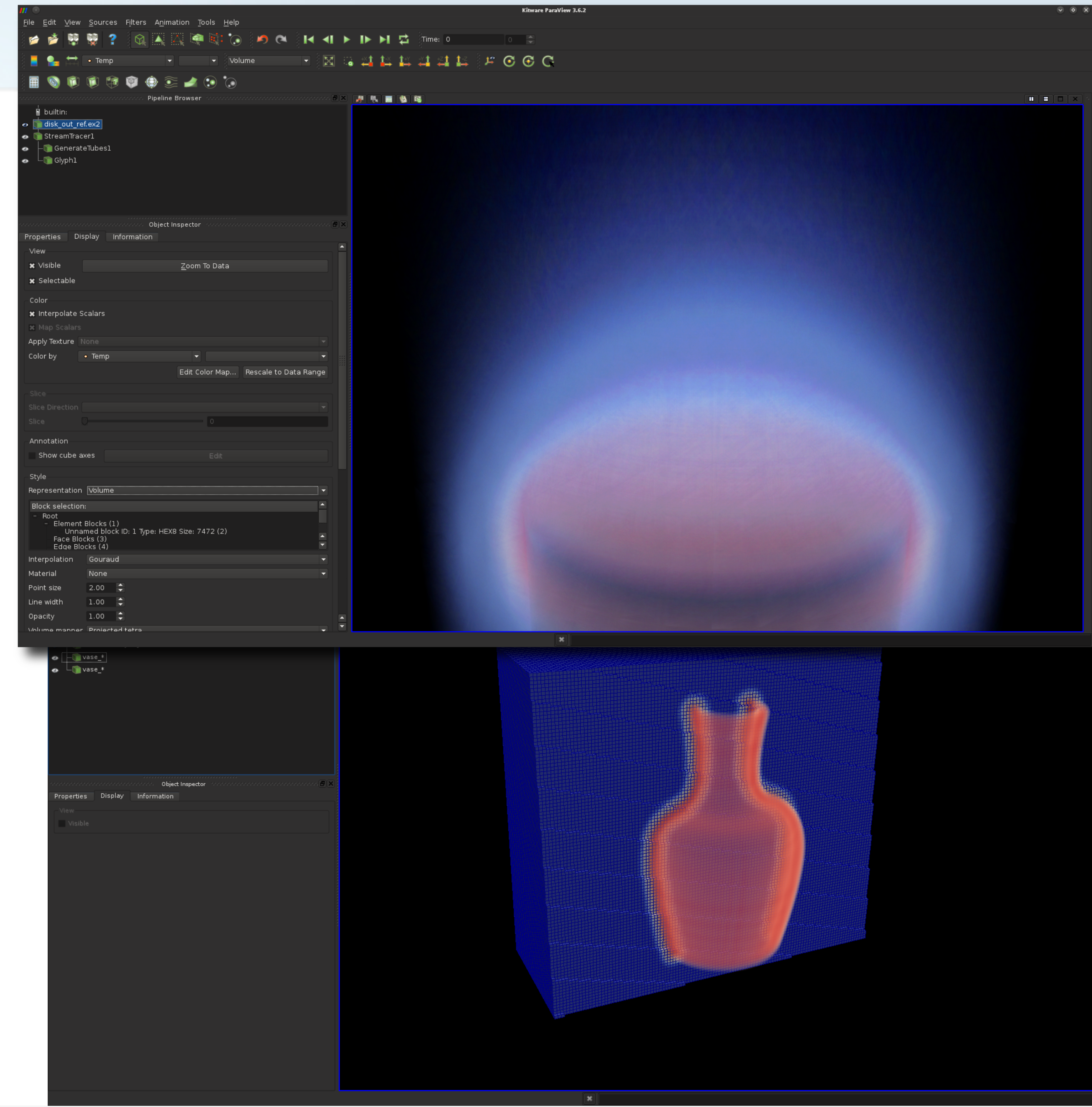
Volume rendering overview

- Rules to define
 - ~~The properties of the “layers”~~
 - The properties of the level sets



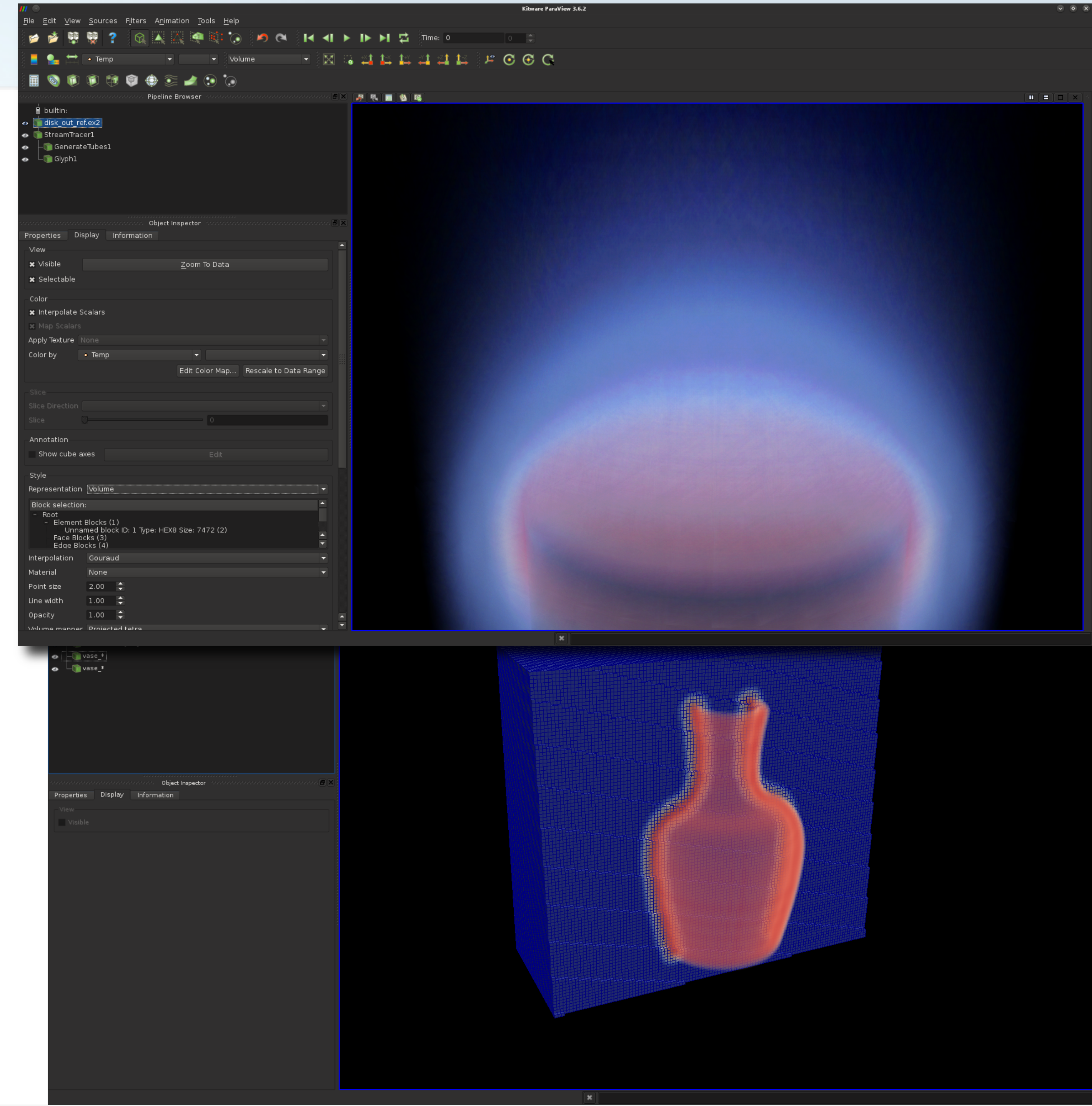
Volume rendering overview

- Rules to define
 - ~~The properties of the “layers”~~
 - The properties of the level sets
 - Color
 - Opacity



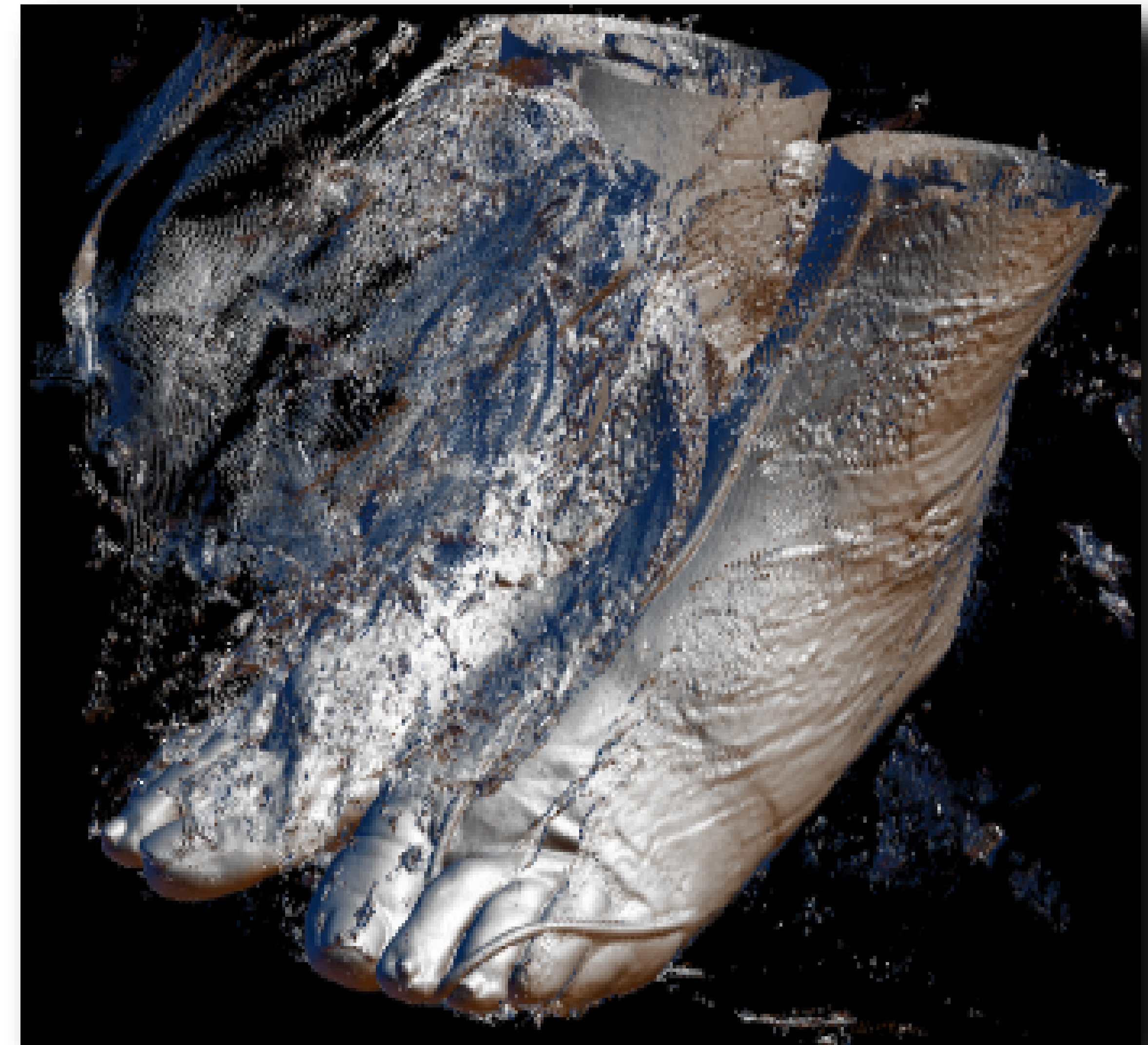
Volume rendering overview

- Rules to define
 - ~~The properties of the “layers”~~
 - The properties of the level sets
 - Color
 - Opacity
- Rendering
 - Accumulation process
 - View-dependent



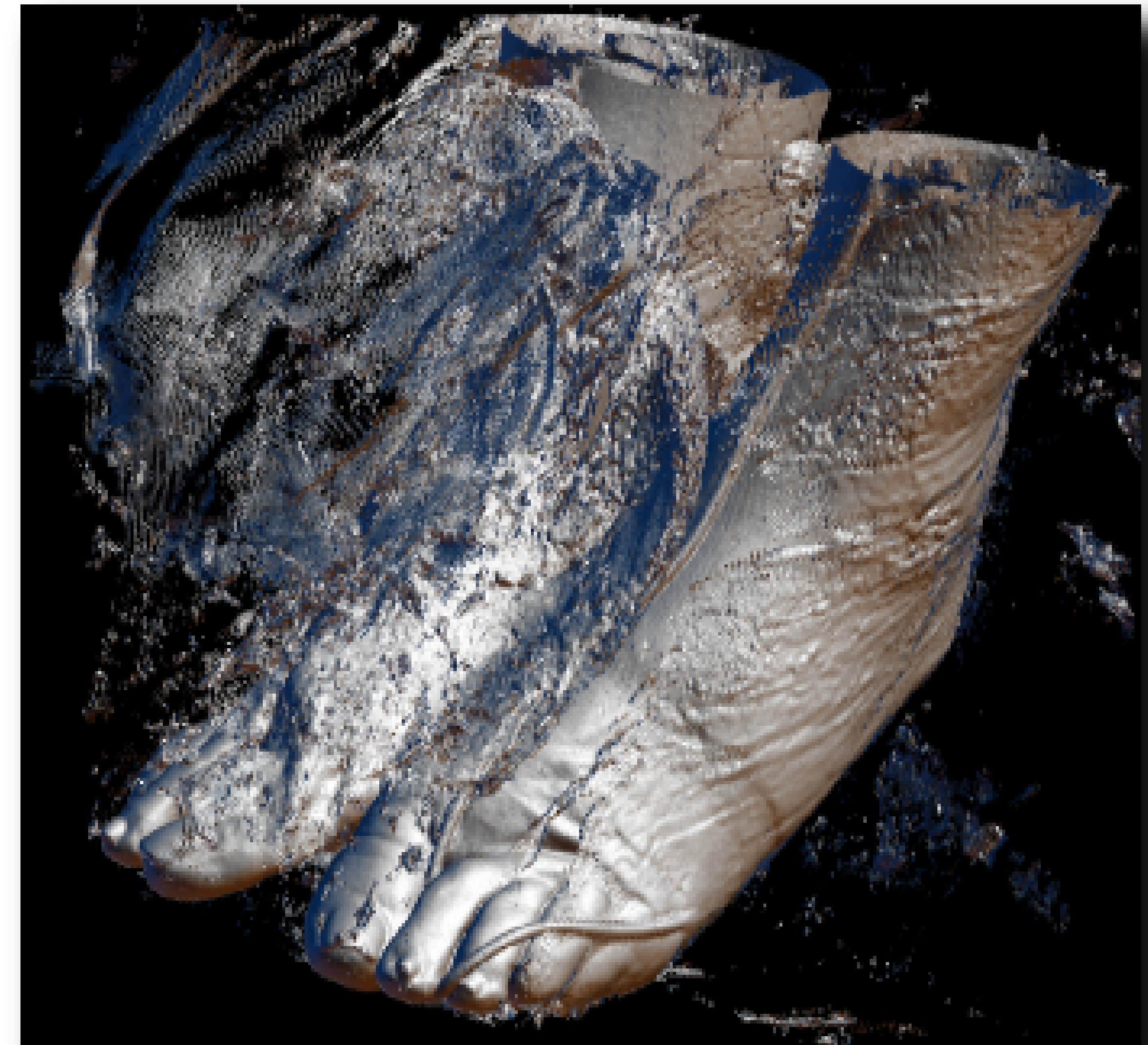
Transfer functions

- Assign distinct *materials* (function intervals)
 - To different properties
 - Color, Opacity



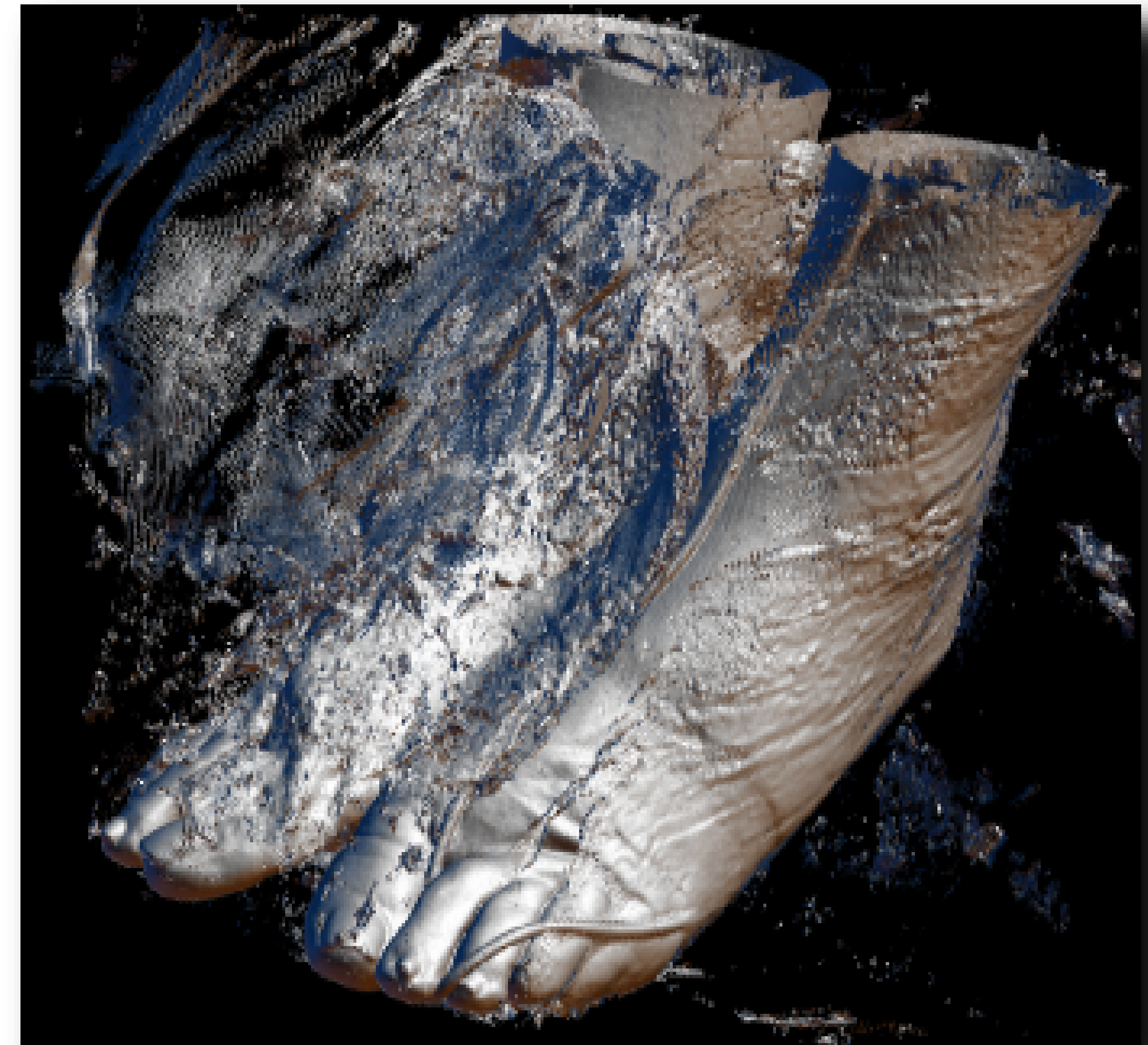
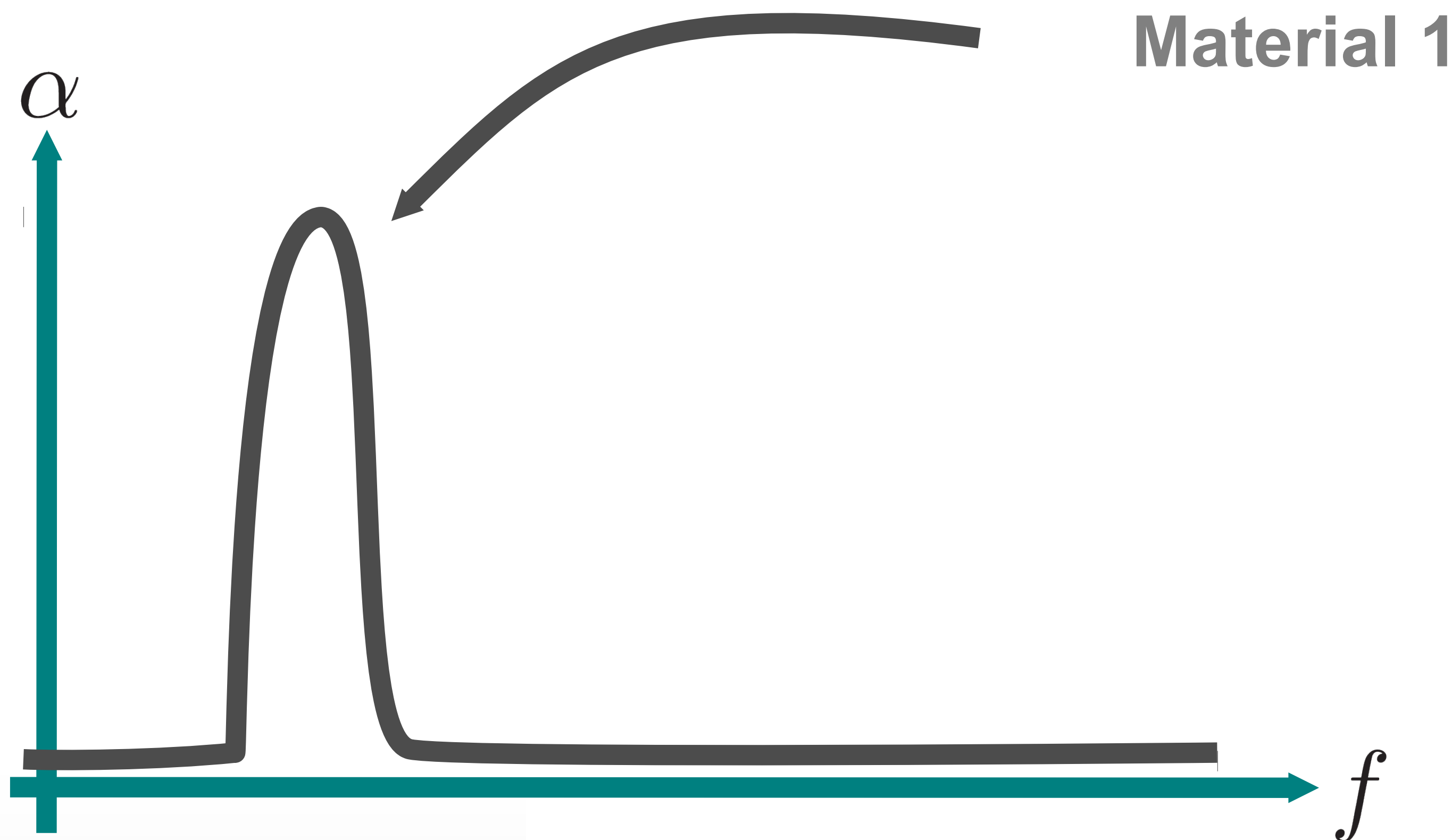
Transfer functions

- Assign distinct *materials* (function intervals)
 - To different properties
 - Color, Opacity



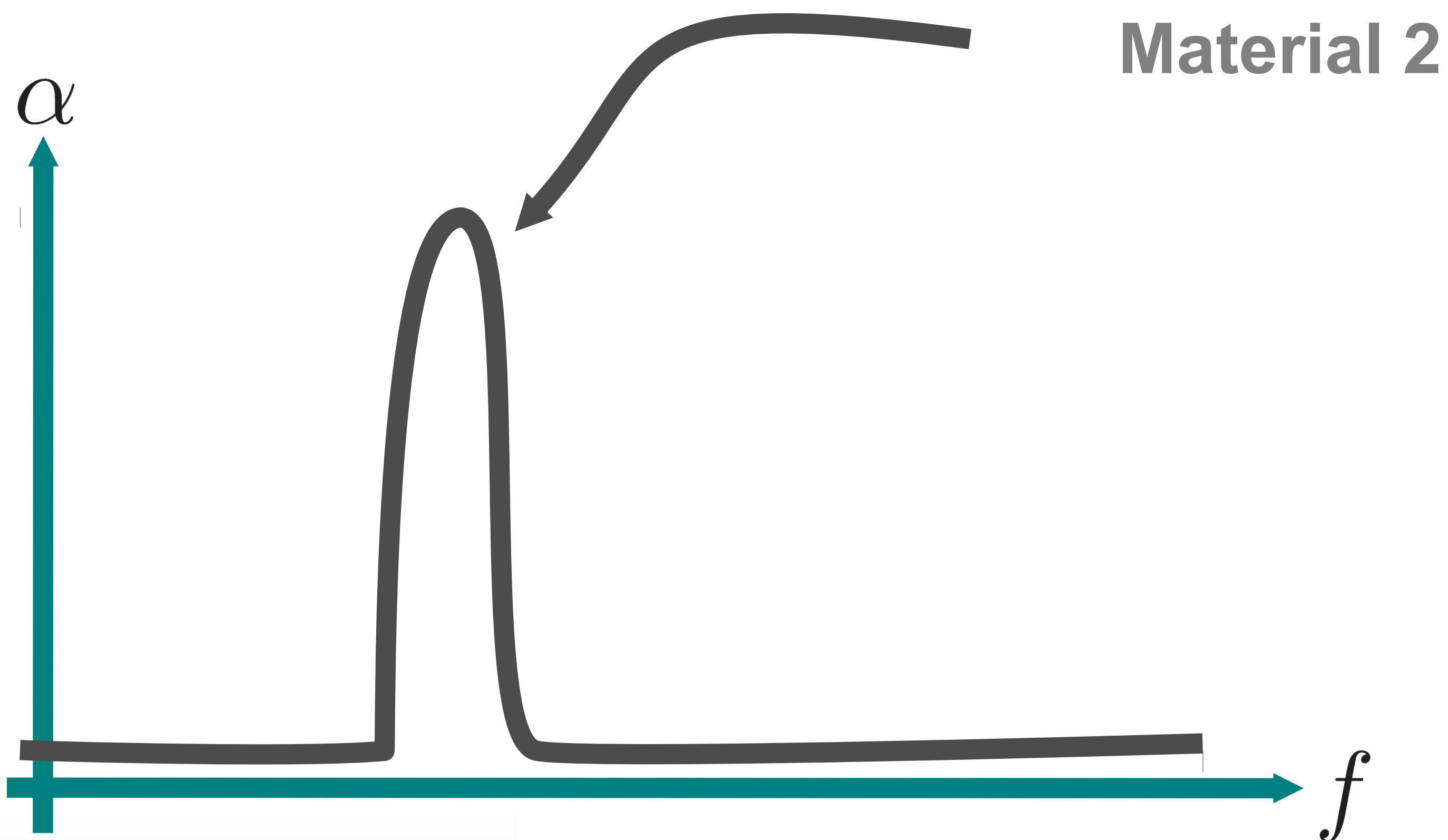
Transfer functions

- Assign distinct *materials* (function intervals)
 - To different properties
 - Color, Opacity



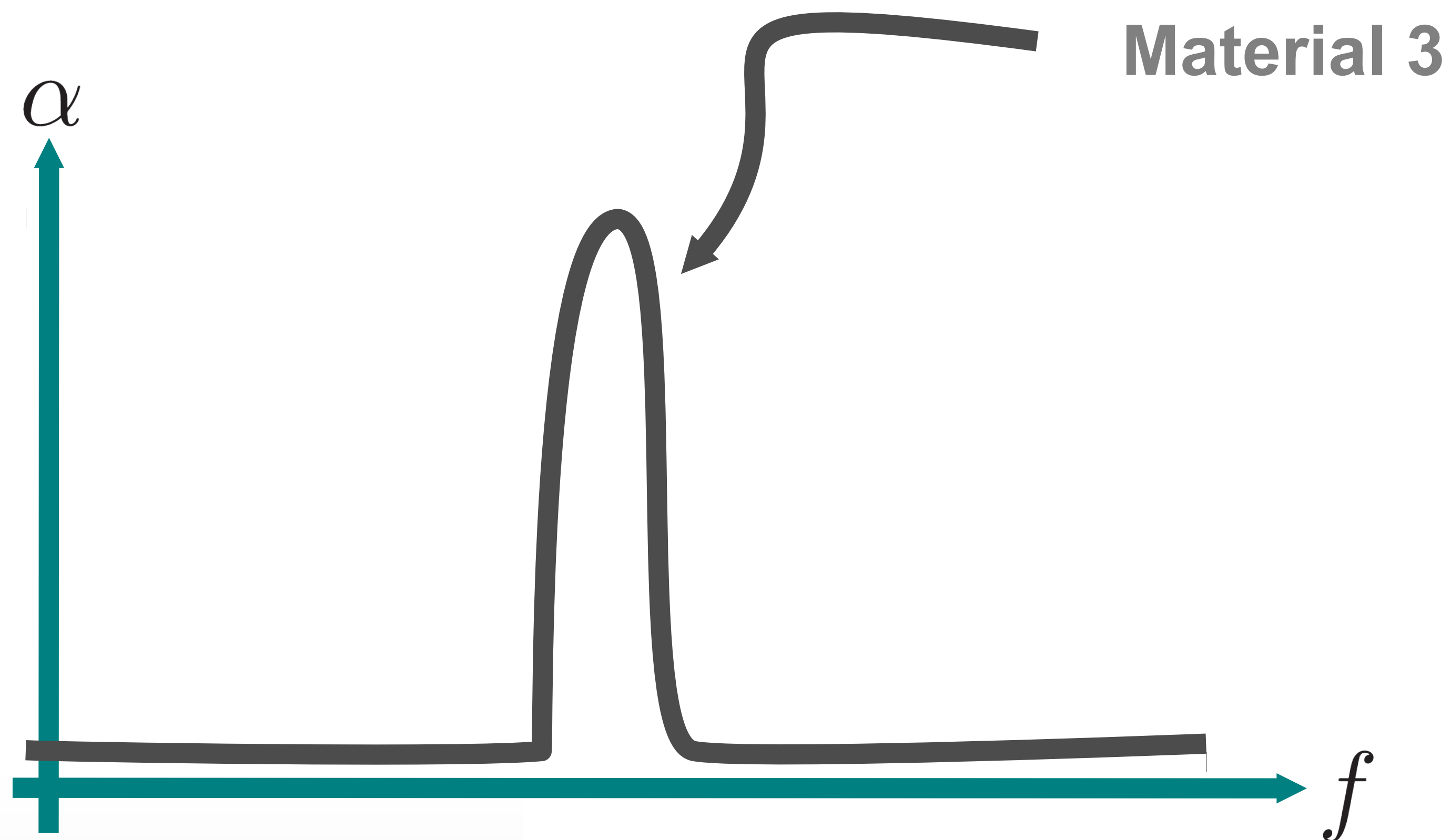
Transfer functions

- Assign distinct *materials* (function intervals)
 - To different properties
 - Color, Opacity



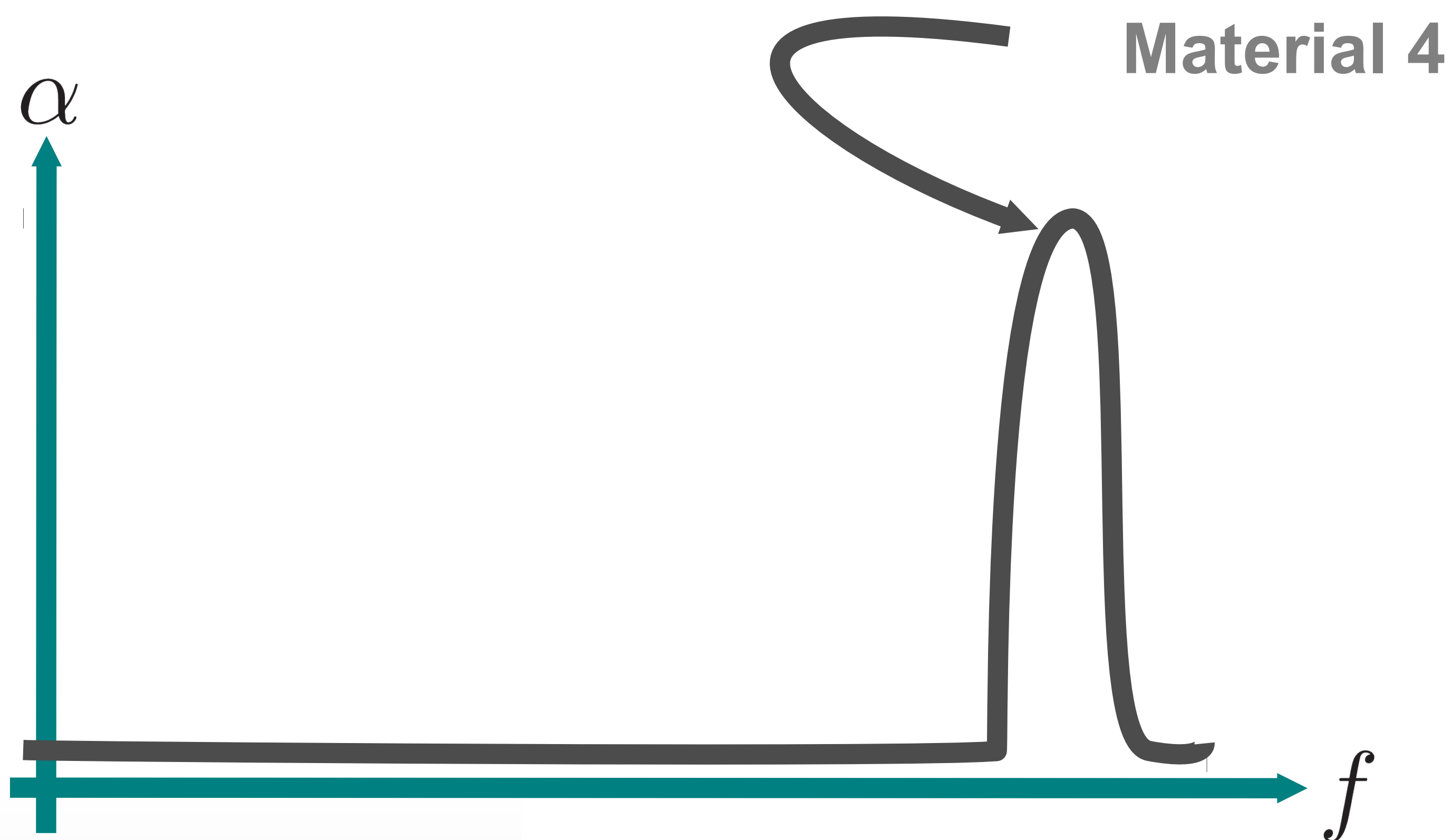
Transfer functions

- Assign distinct *materials* (function intervals)
 - To different properties
 - Color, Opacity

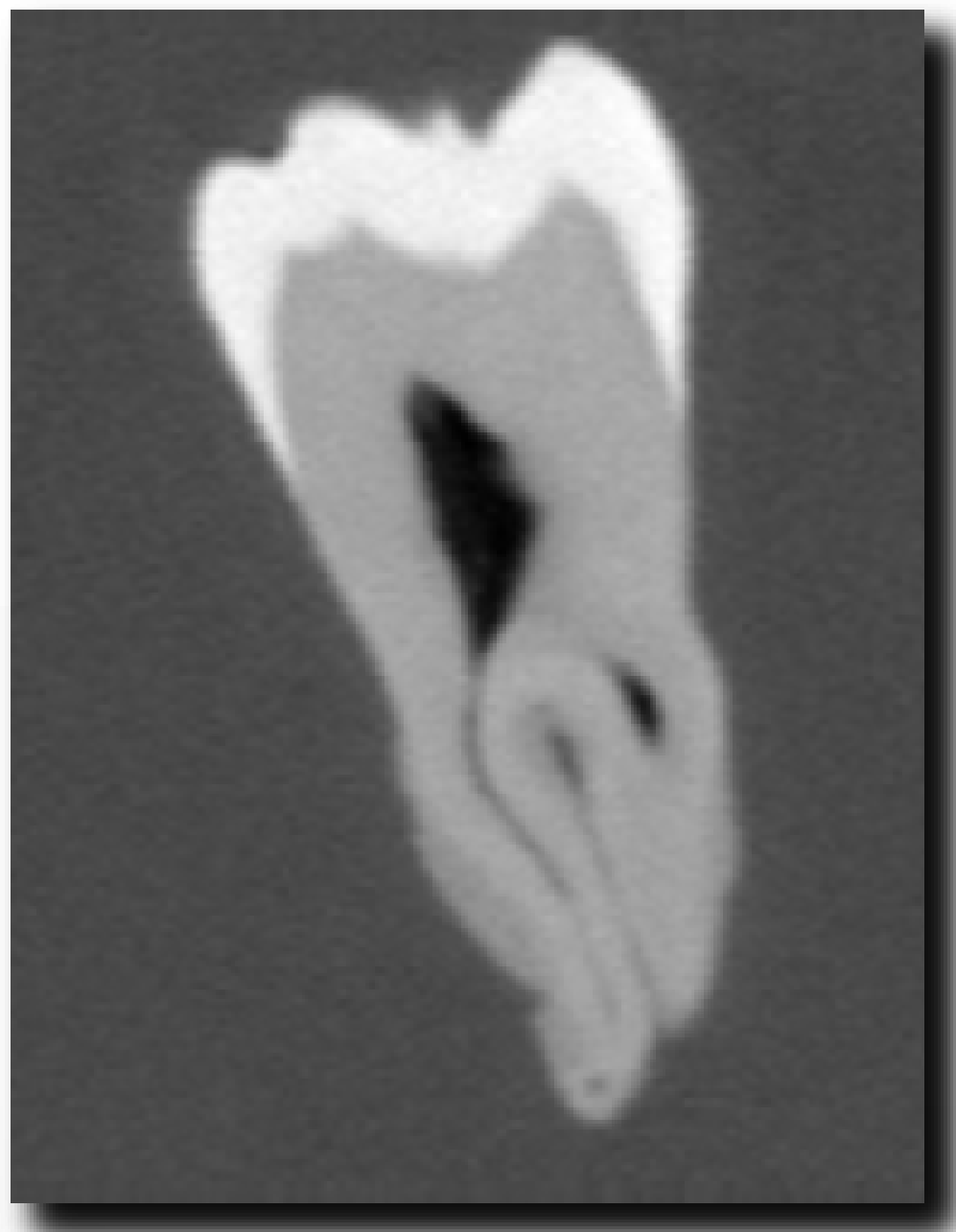


Transfer functions

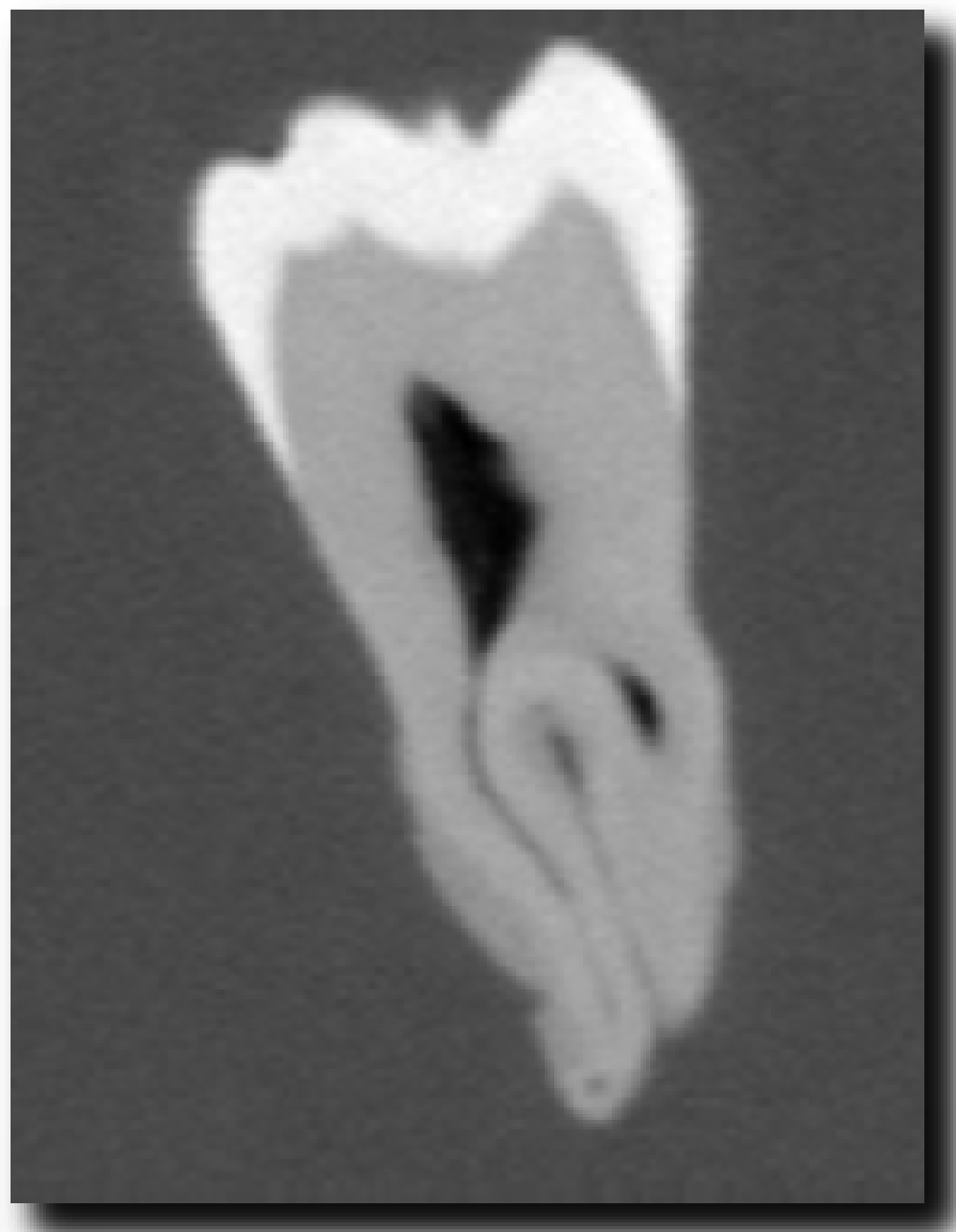
- Assign distinct *materials* (function intervals)
 - To different properties
 - Color, Opacity



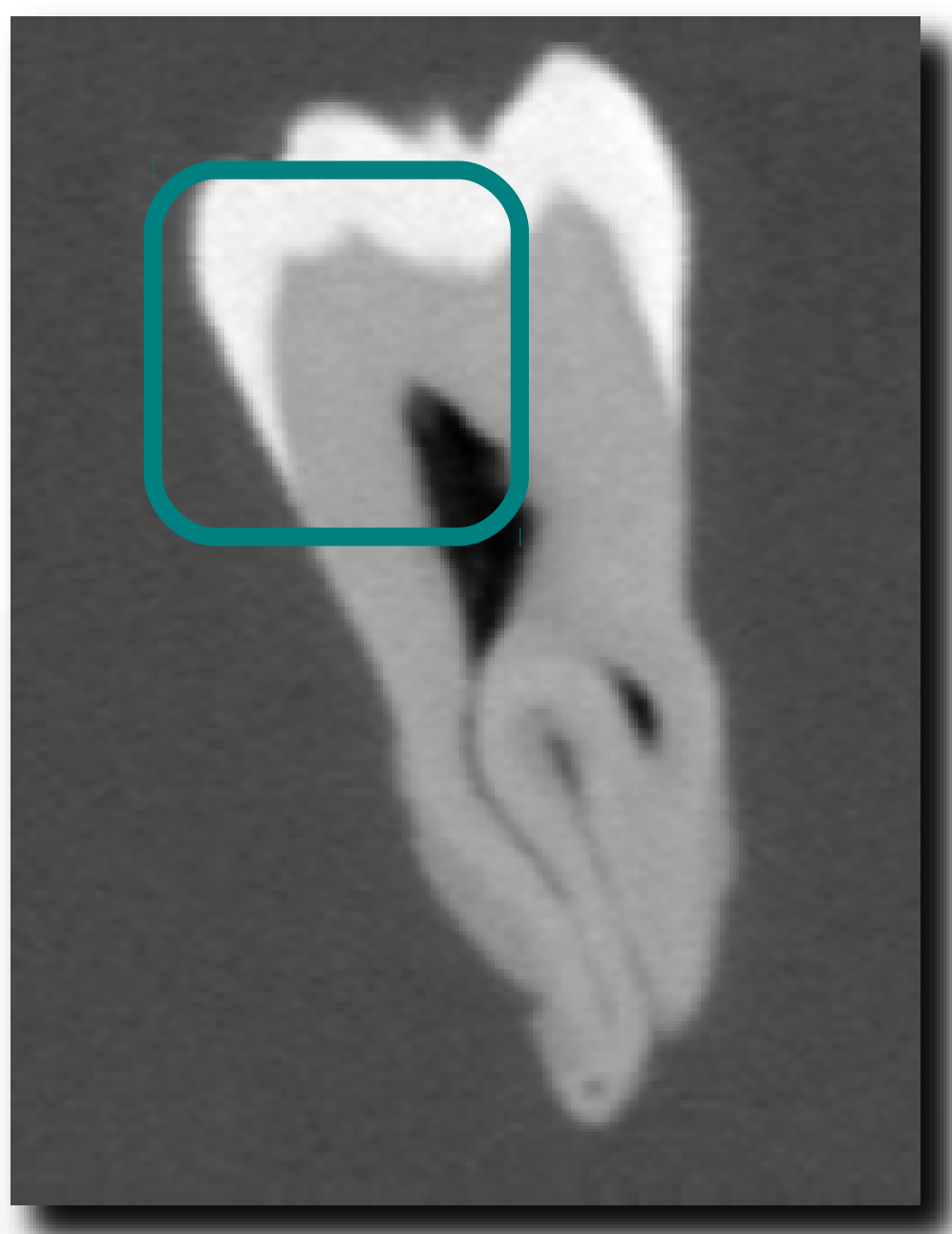
Transfer function examples



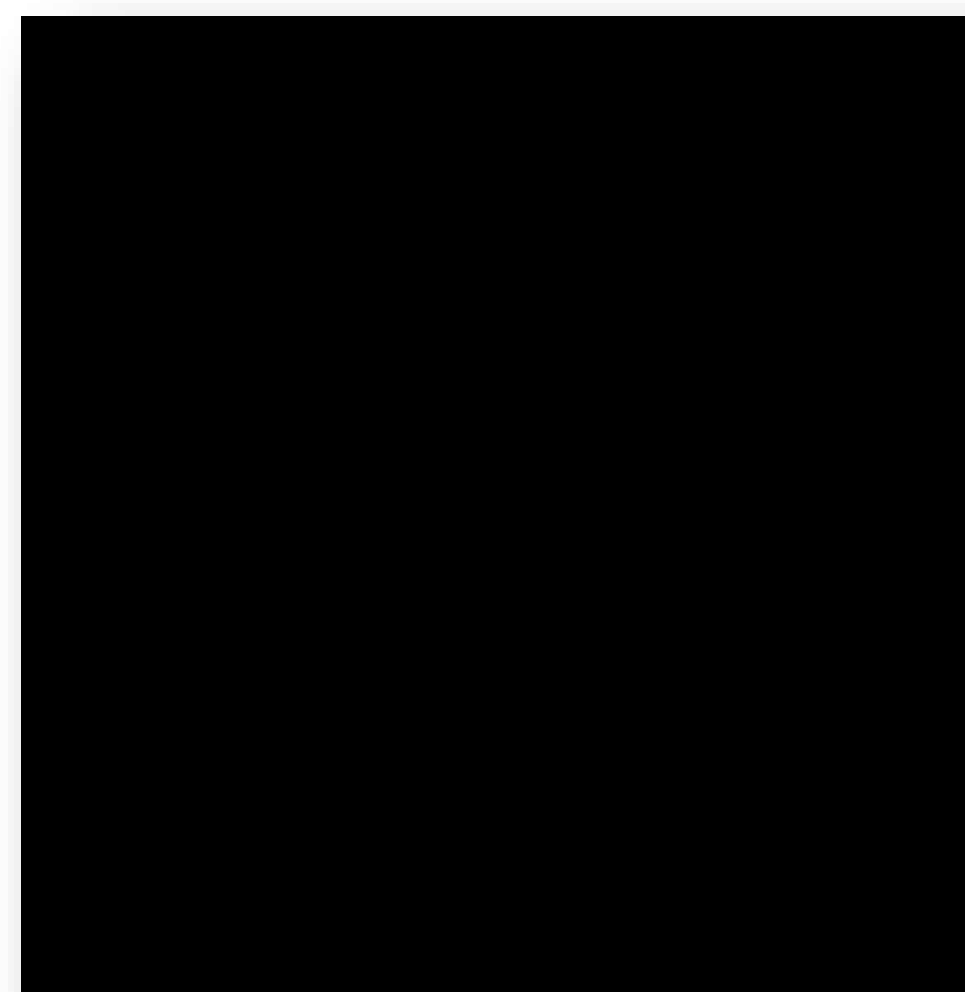
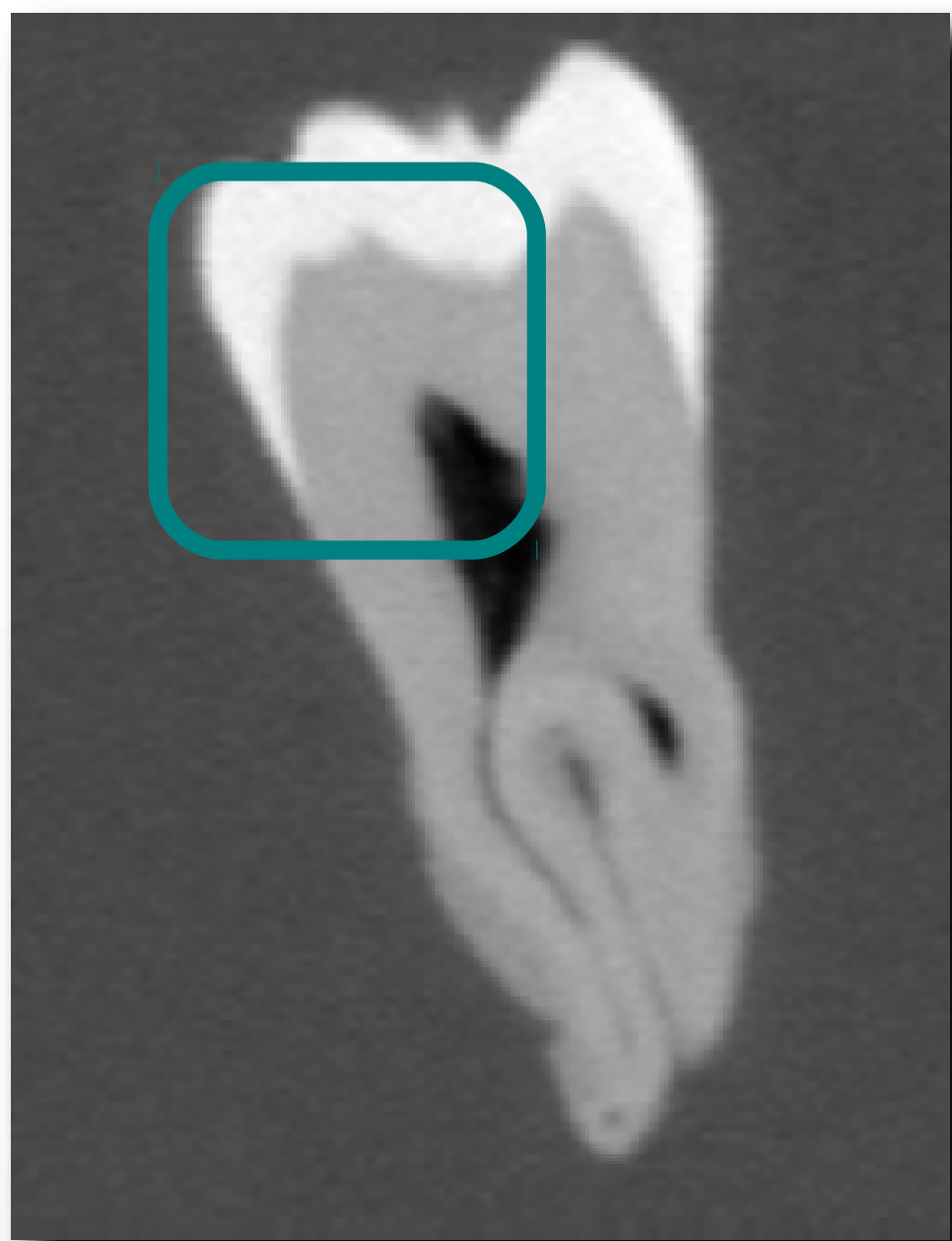
Transfer function examples



Transfer function examples



Transfer function examples

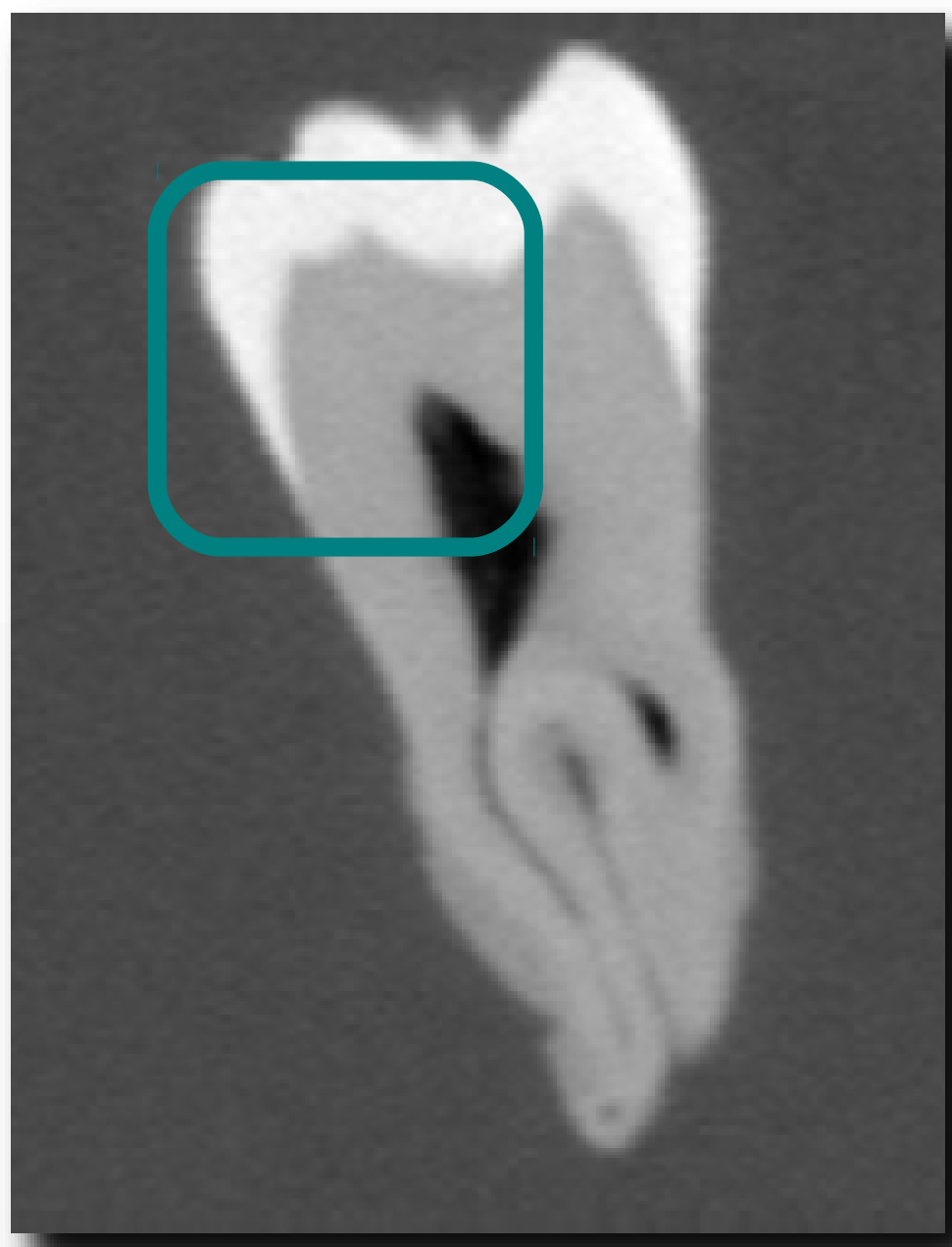
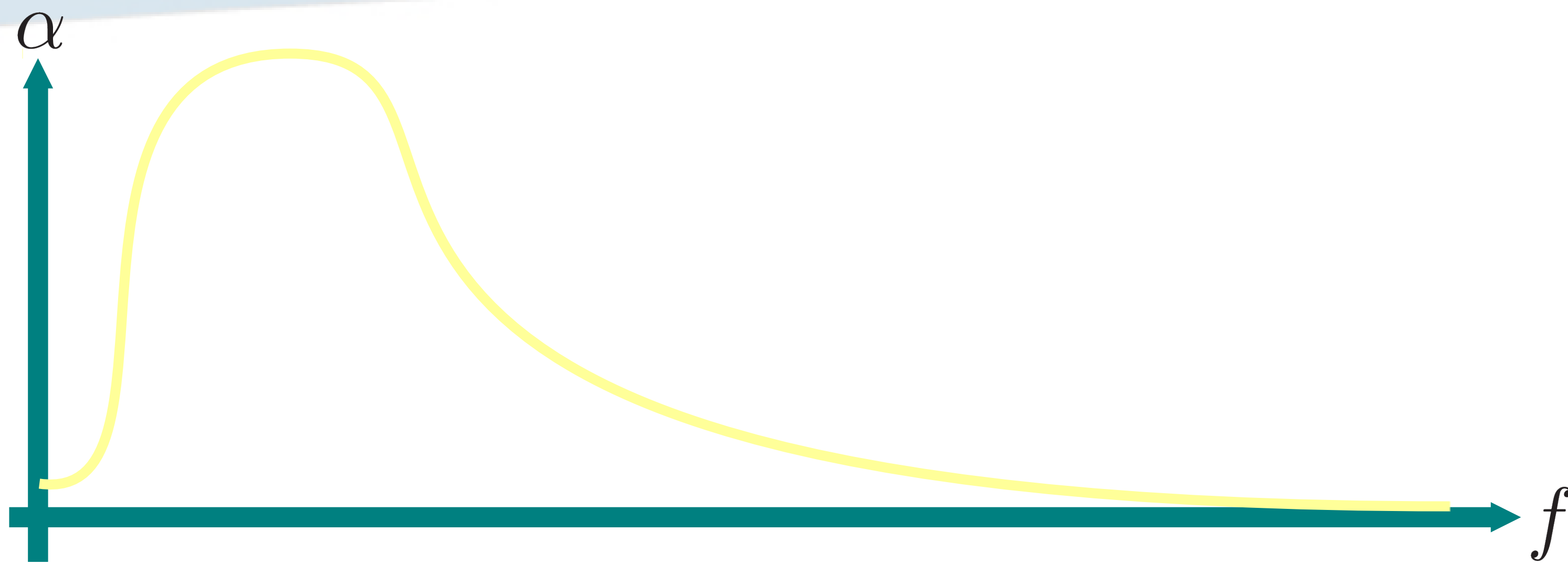


Color

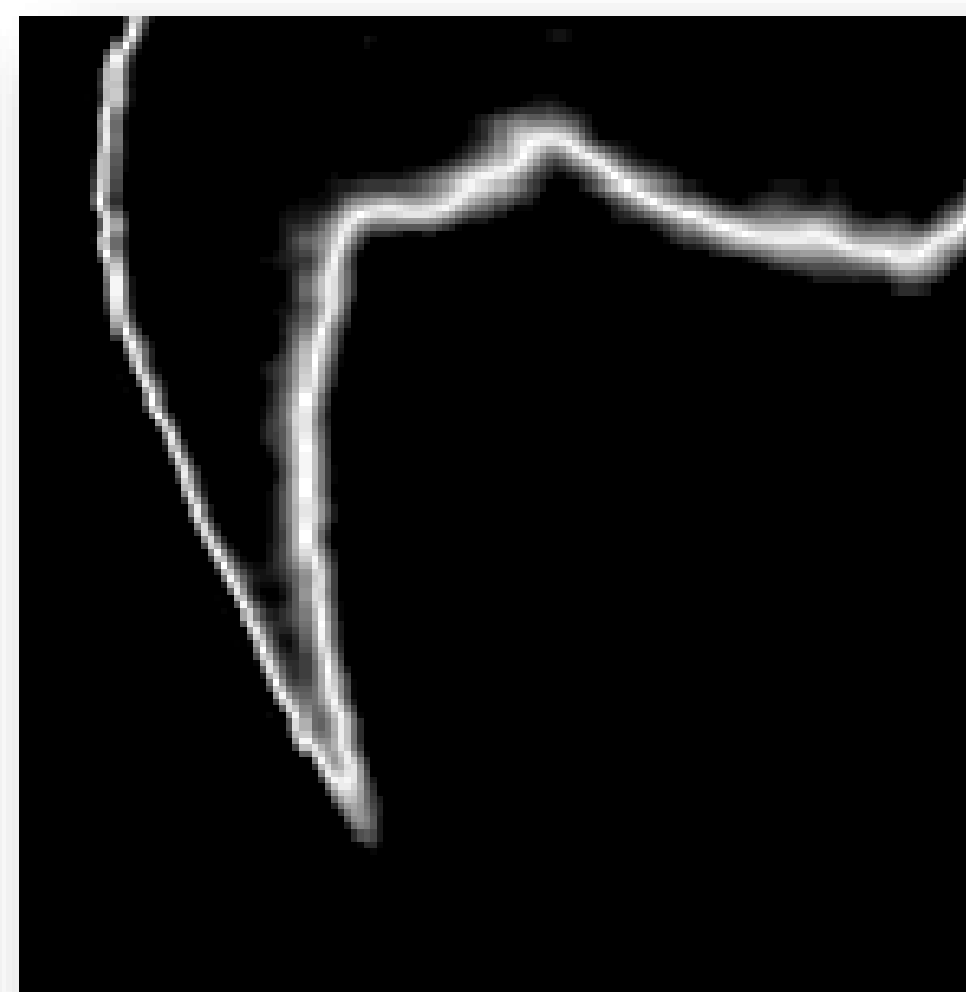


Opacity

Transfer function examples

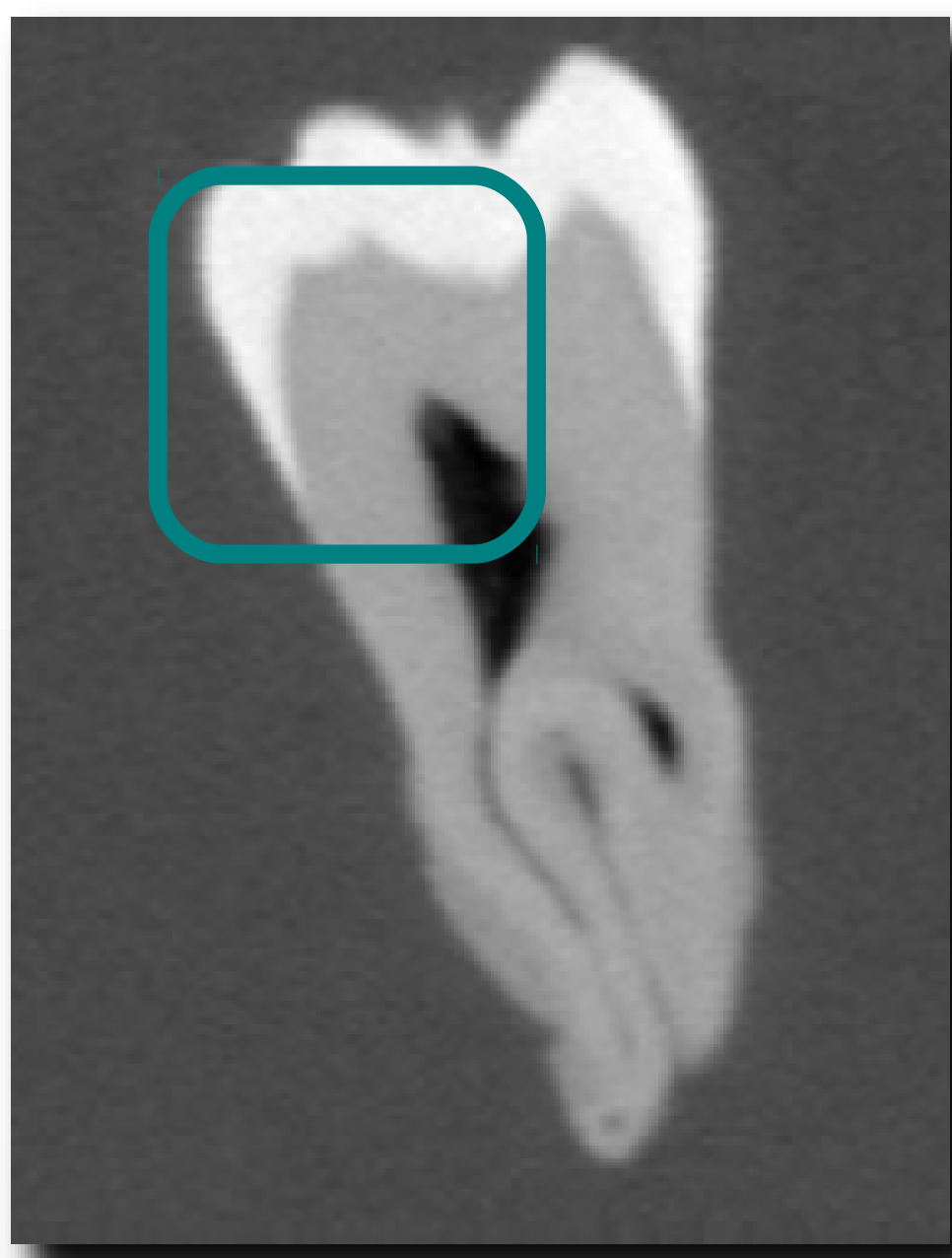
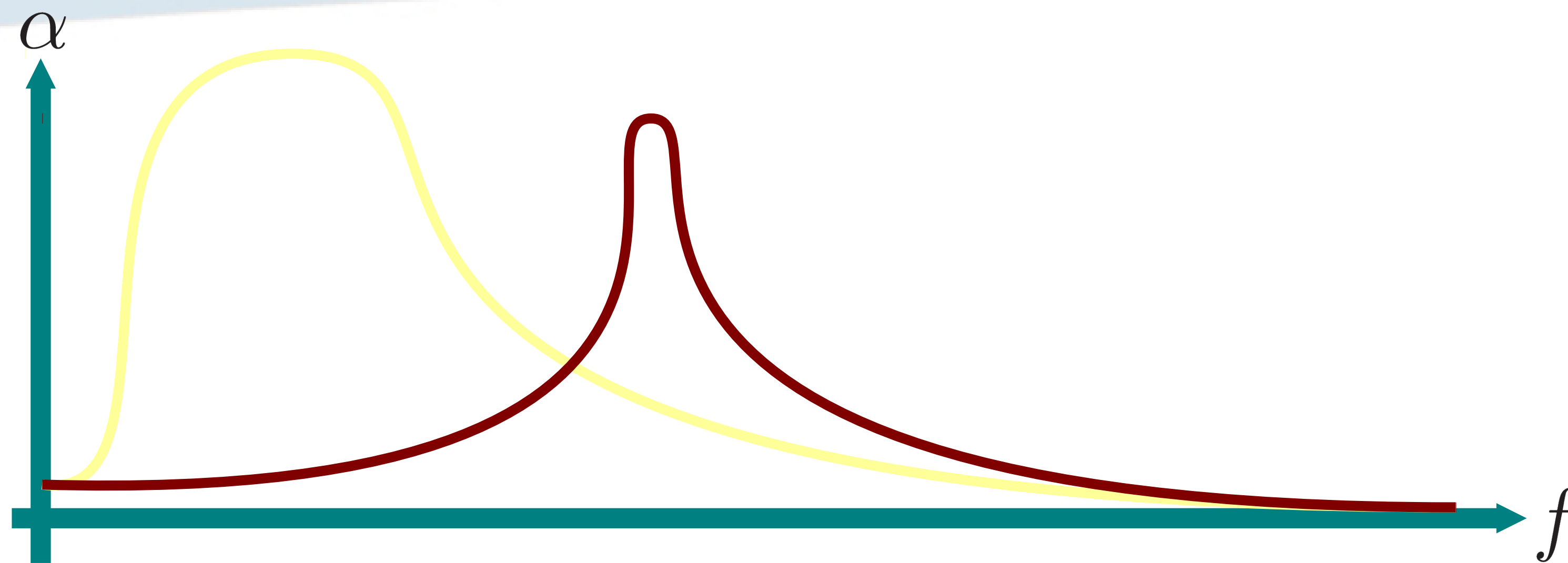


Color

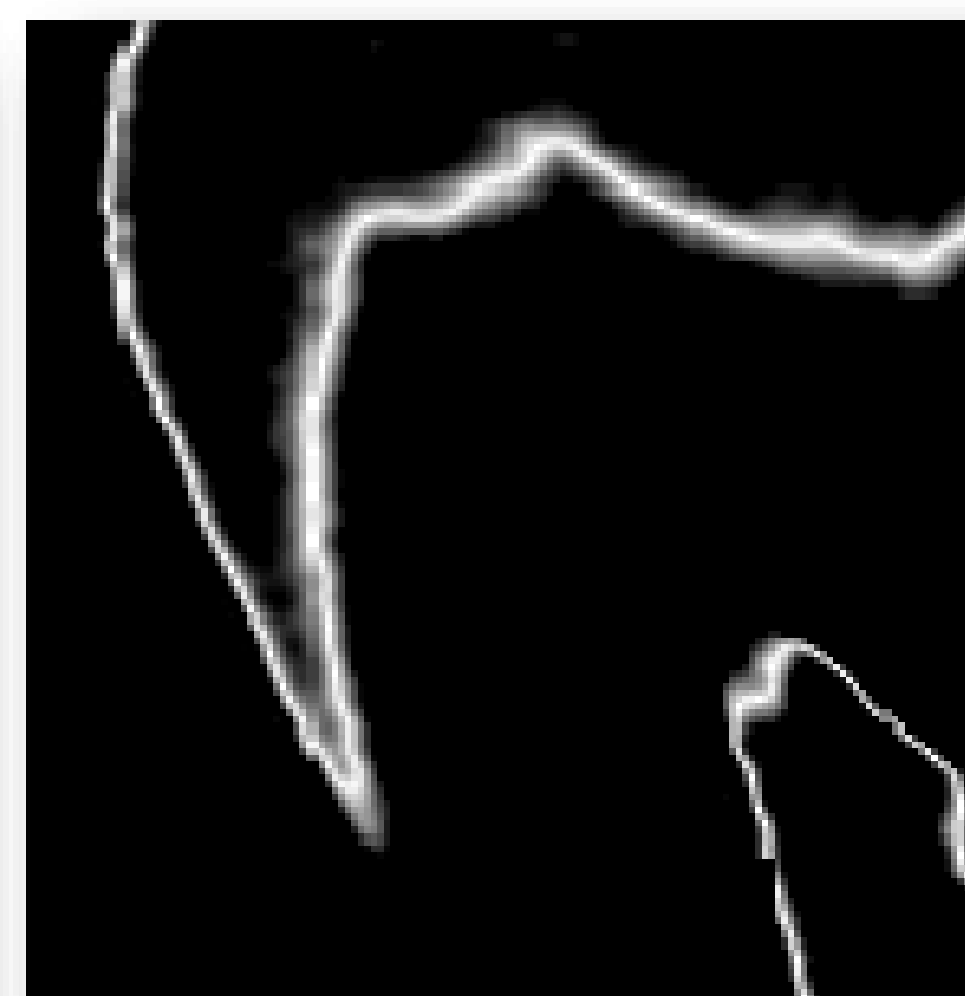


Opacity

Transfer function examples

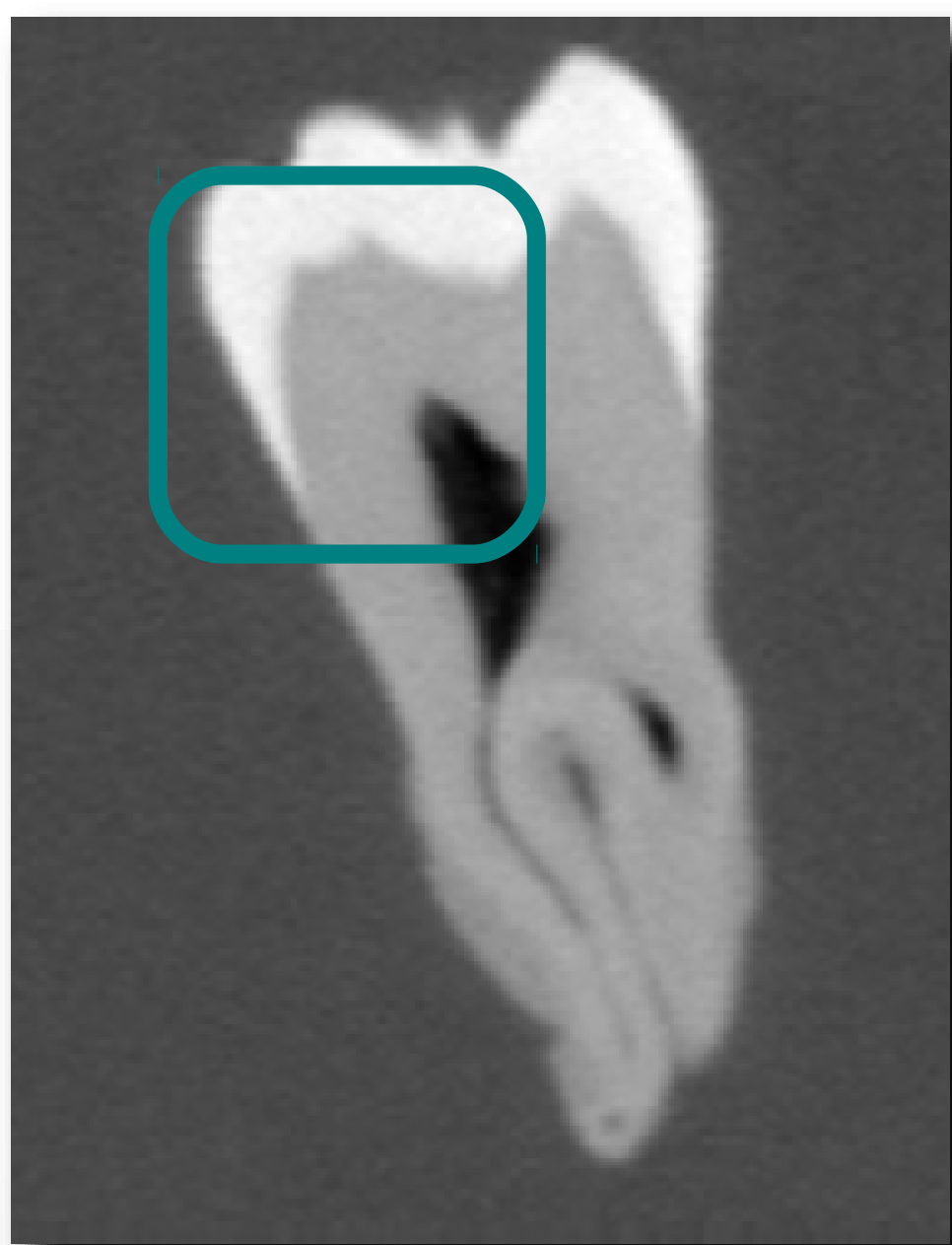
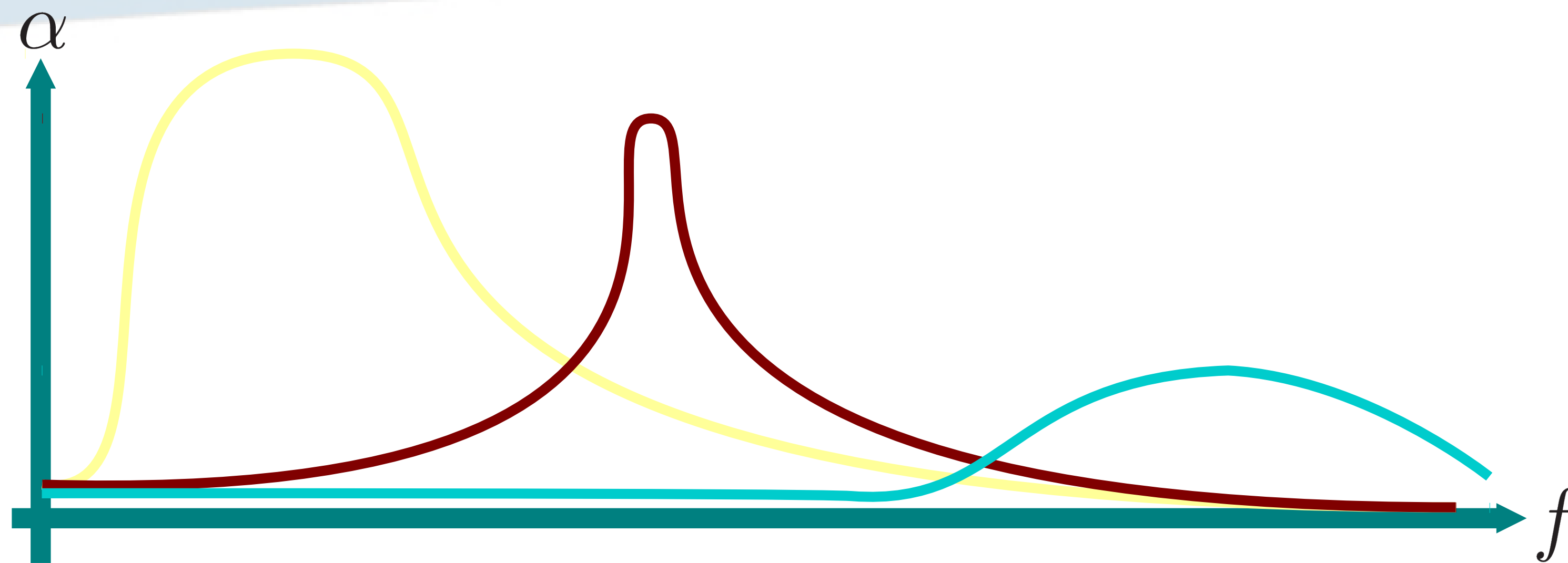


Color



Opacity

Transfer function examples

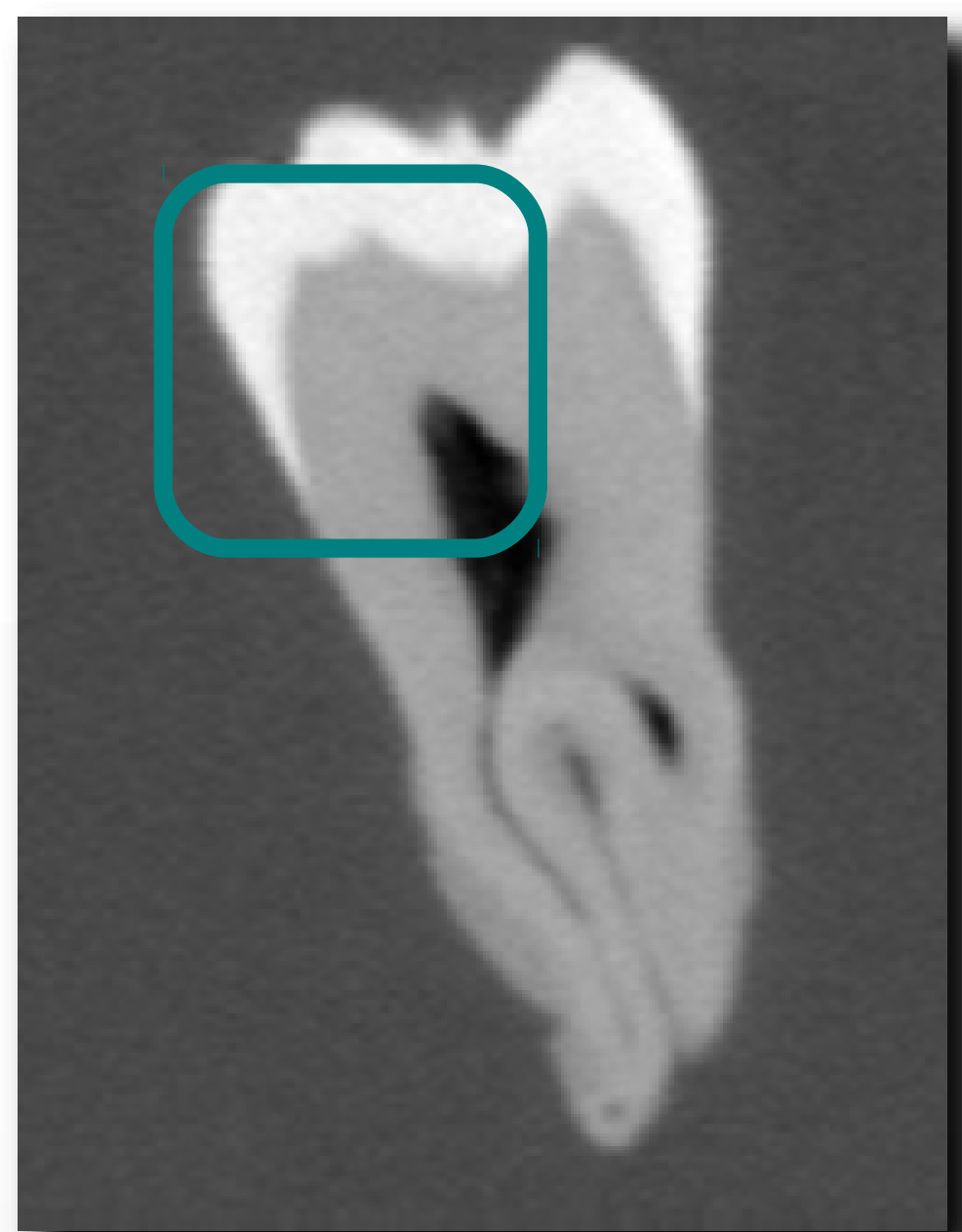
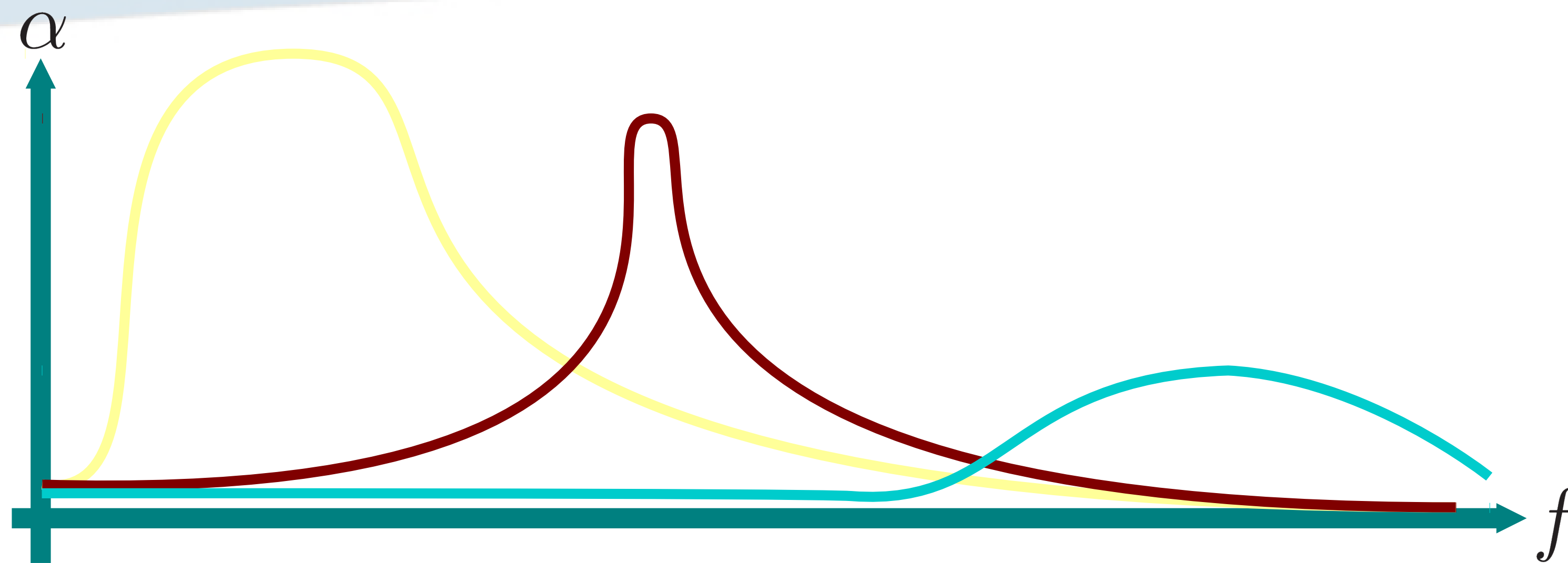


Color



Opacity

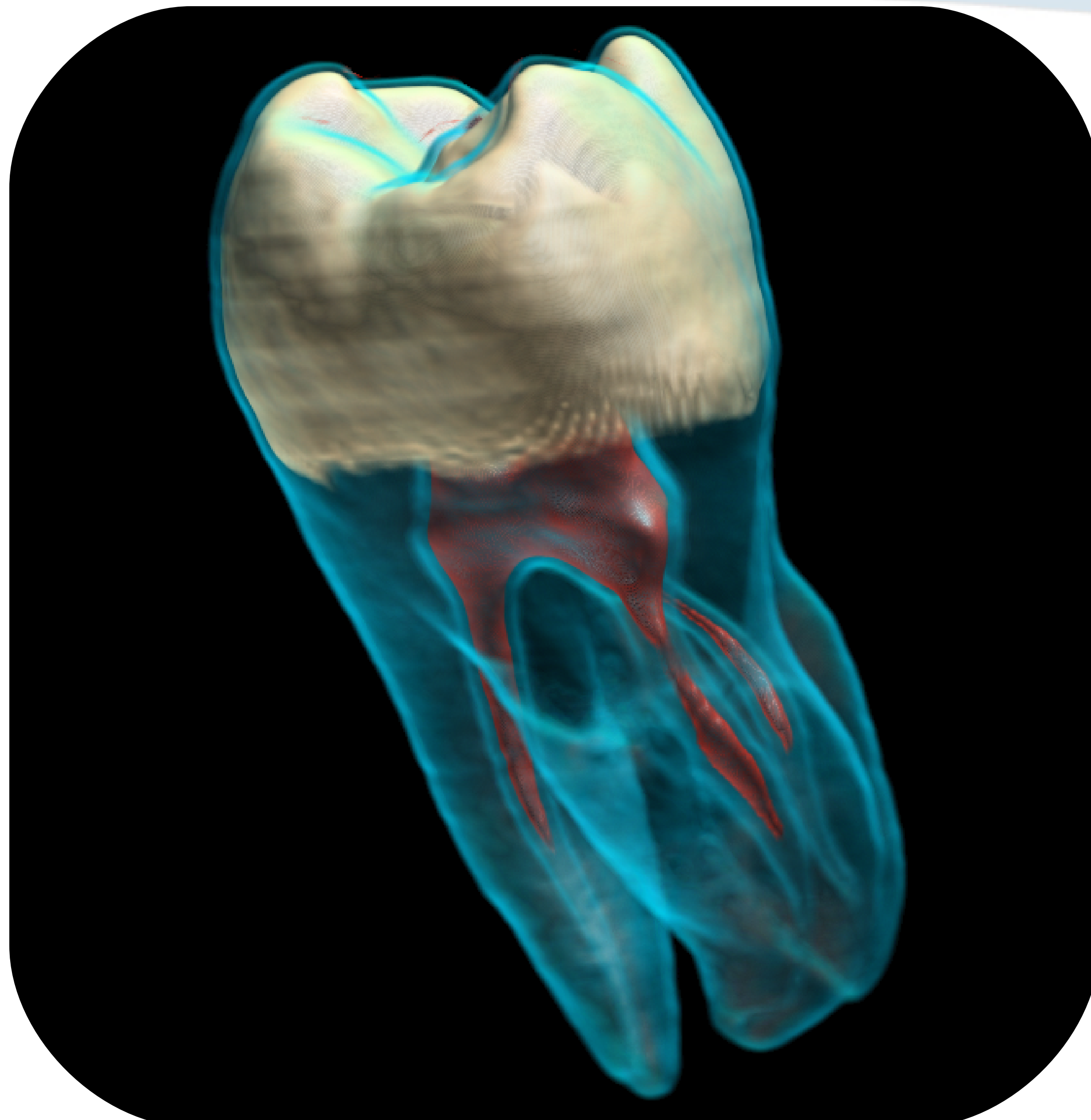
Transfer function examples



Color

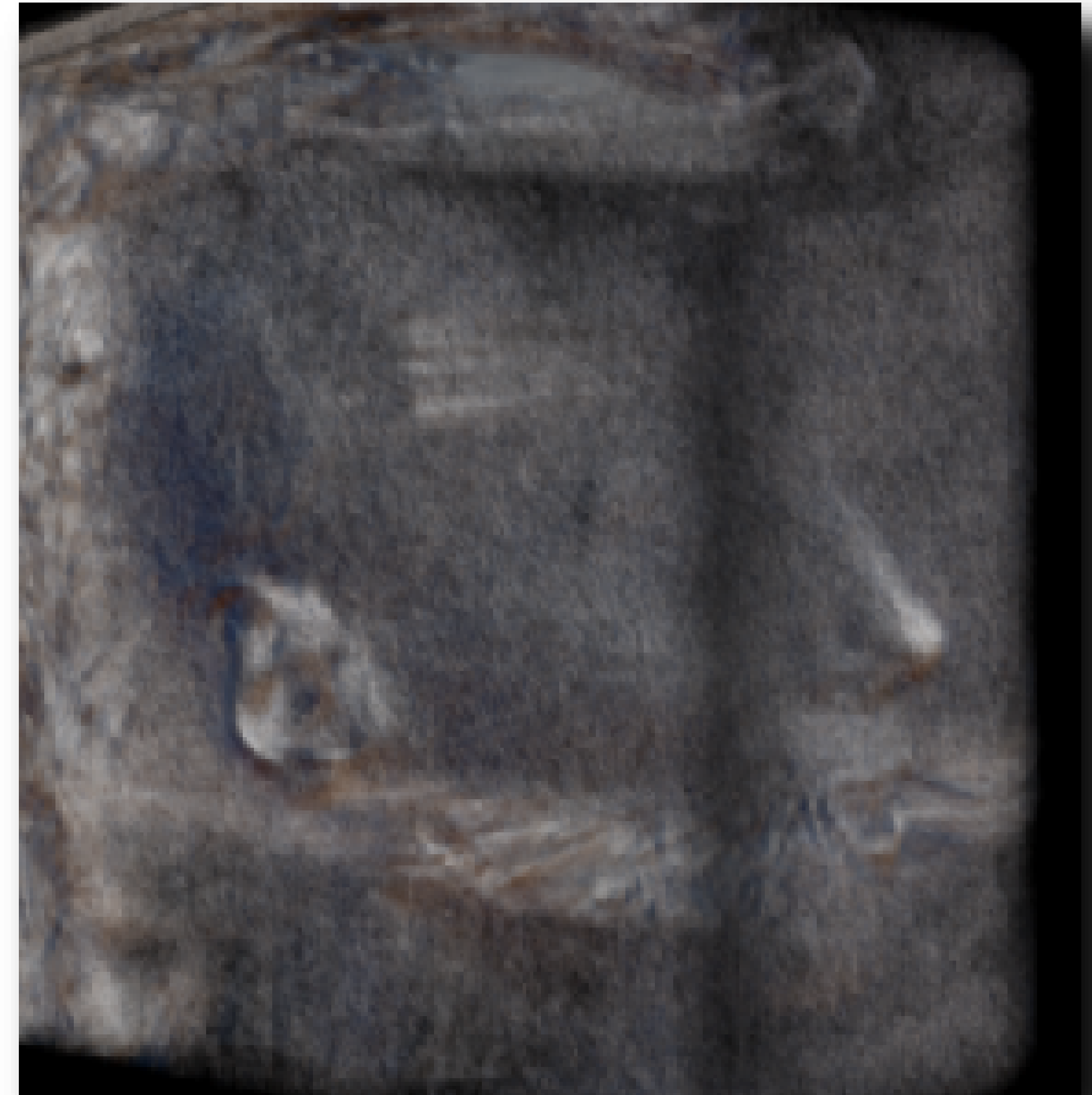


Opacity



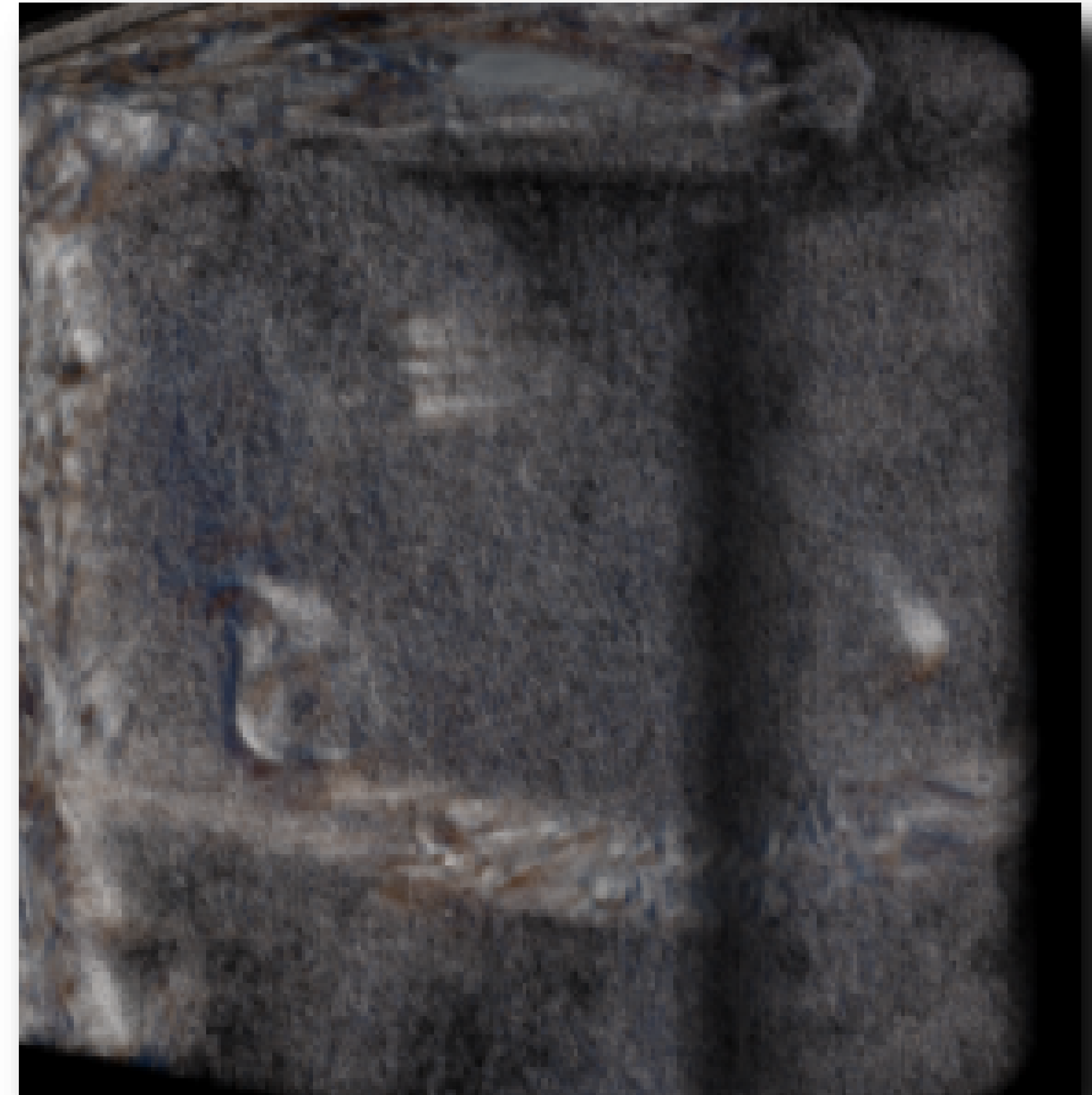
From a user's perspective

- Finding the “right” transfer function can be difficult
 - Experienced users
 - Knowledge of the data-set



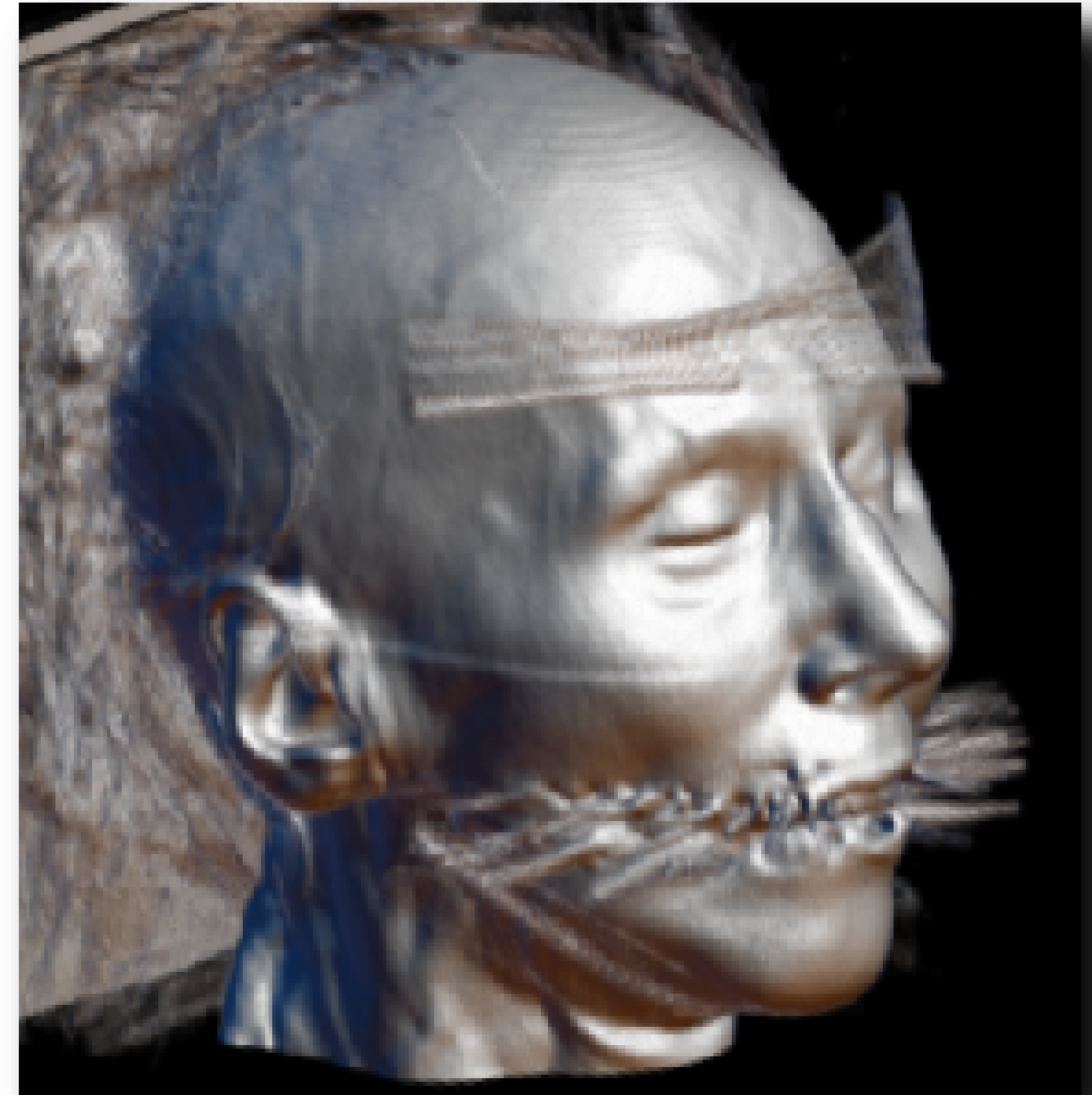
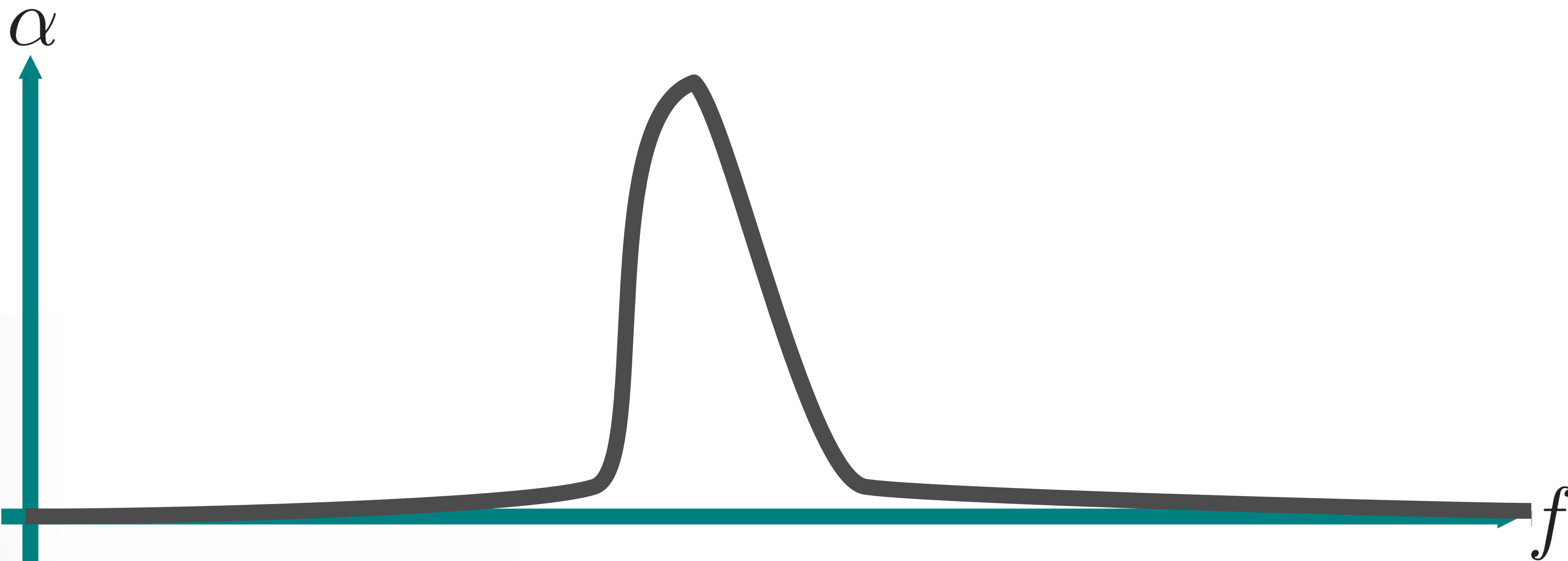
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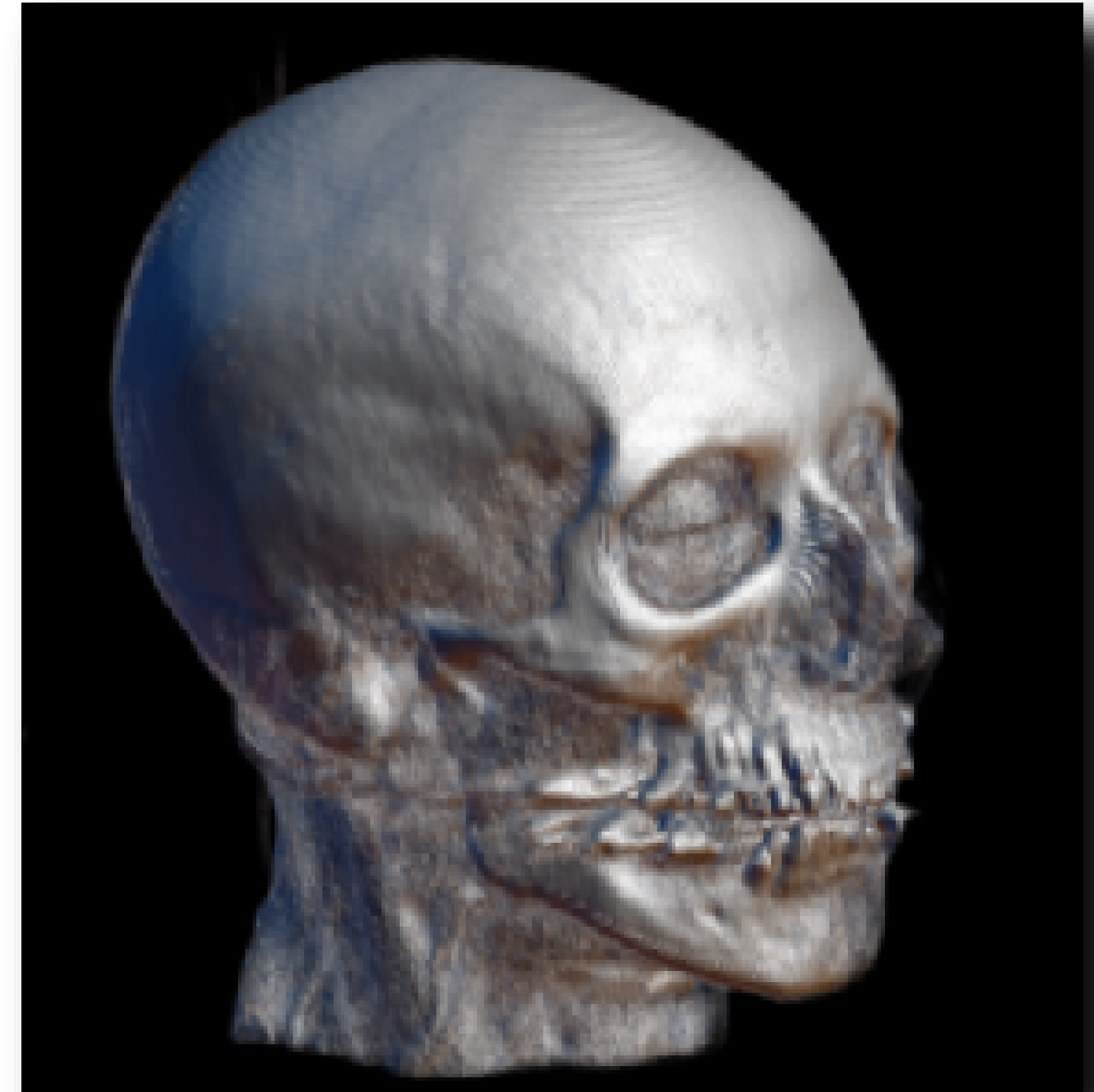
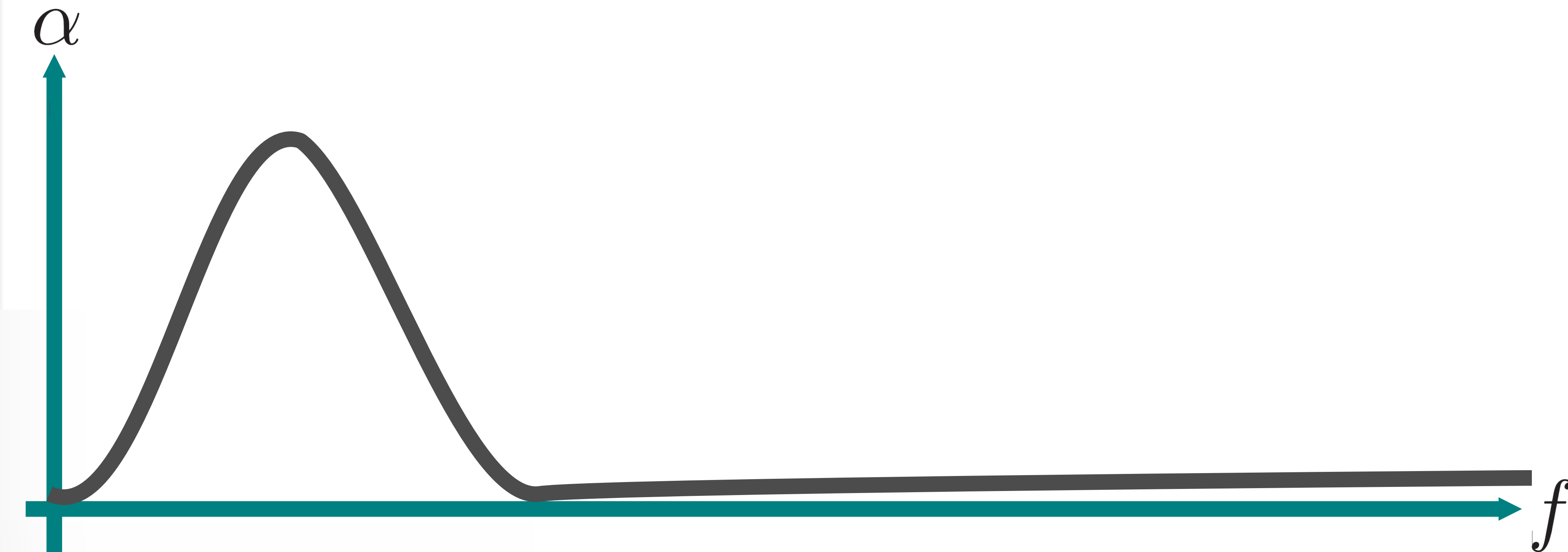
From a user's perspective

- Finding the “right” transfer function can be difficult
 - Experienced users
 - Knowledge of the data-set



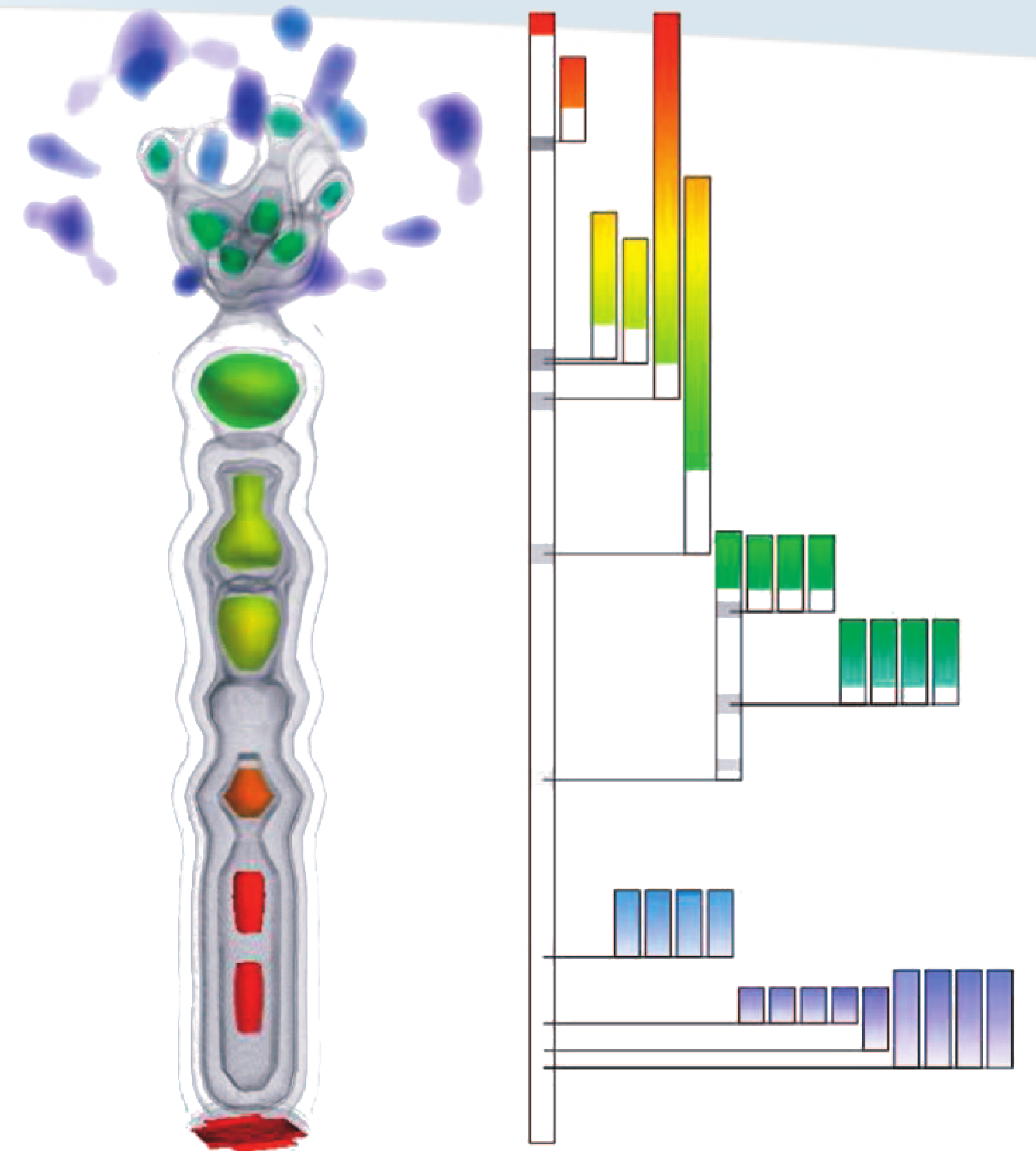
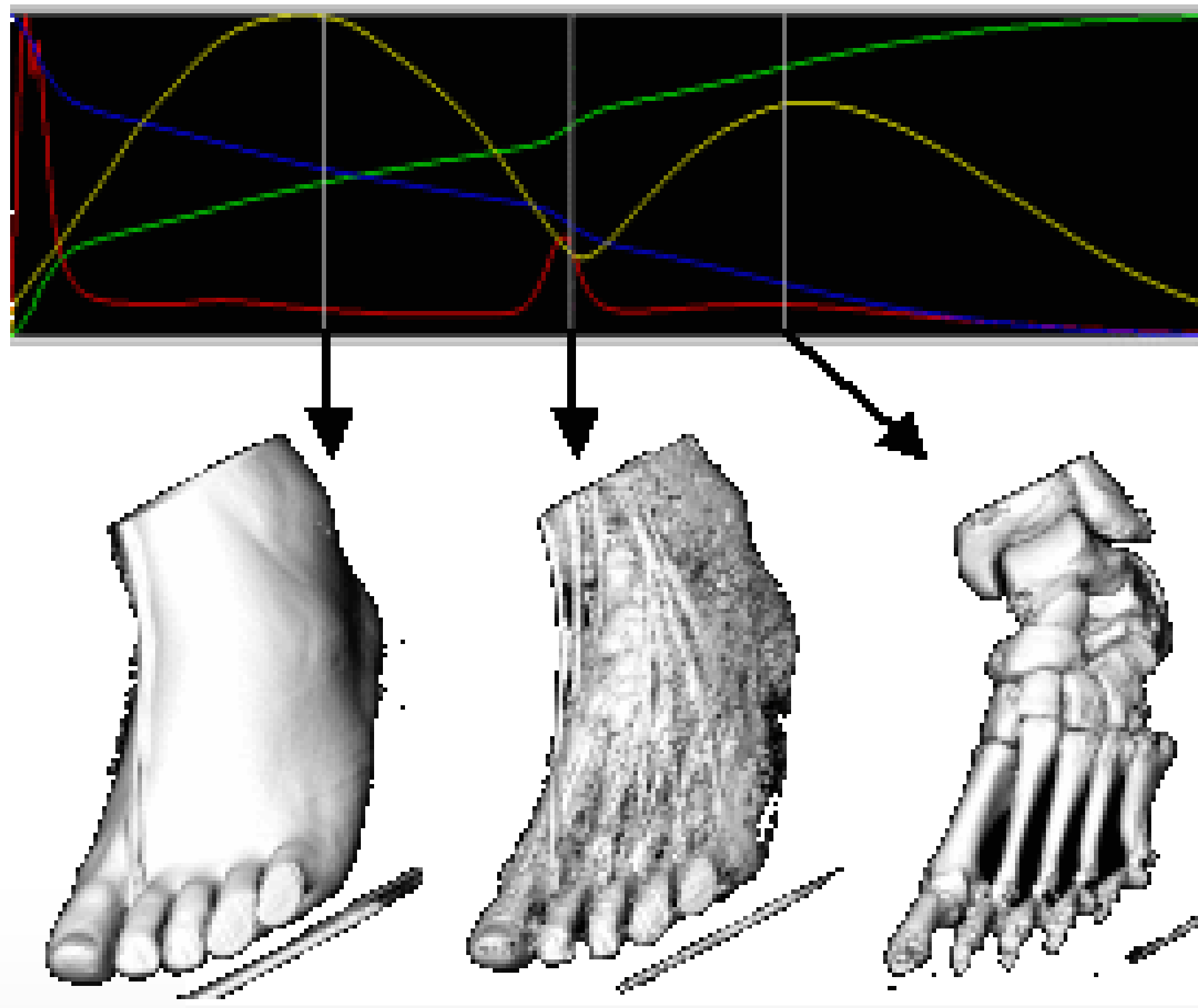
From a user's perspective

- Finding the “right” transfer function can be difficult
 - Experienced users
 - Knowledge of the data-set

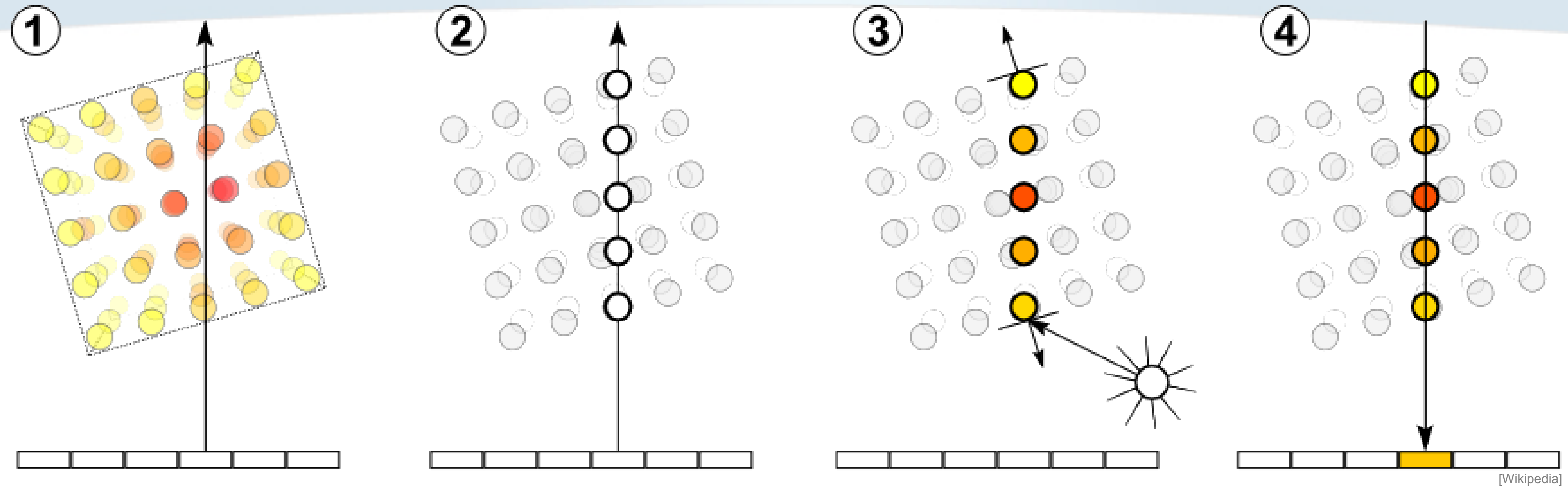


From a user's perspective

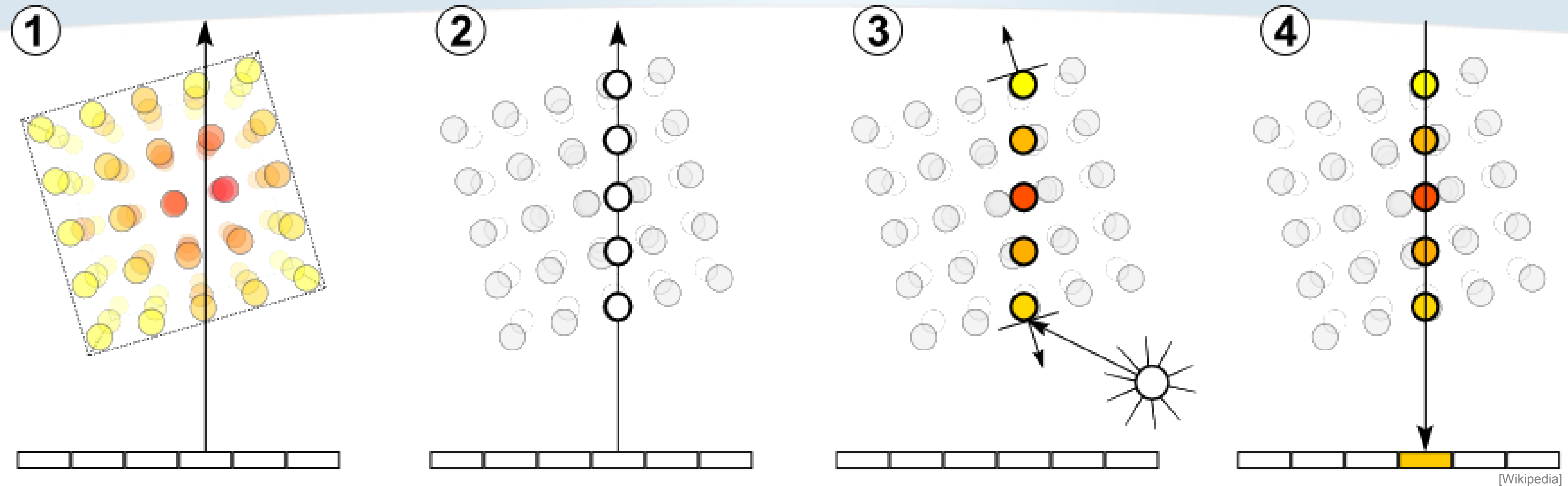
- Semi-automated techniques
 - Contour spectrum
 - Topology controlled volume rendering



Volume rendering: how does it work?

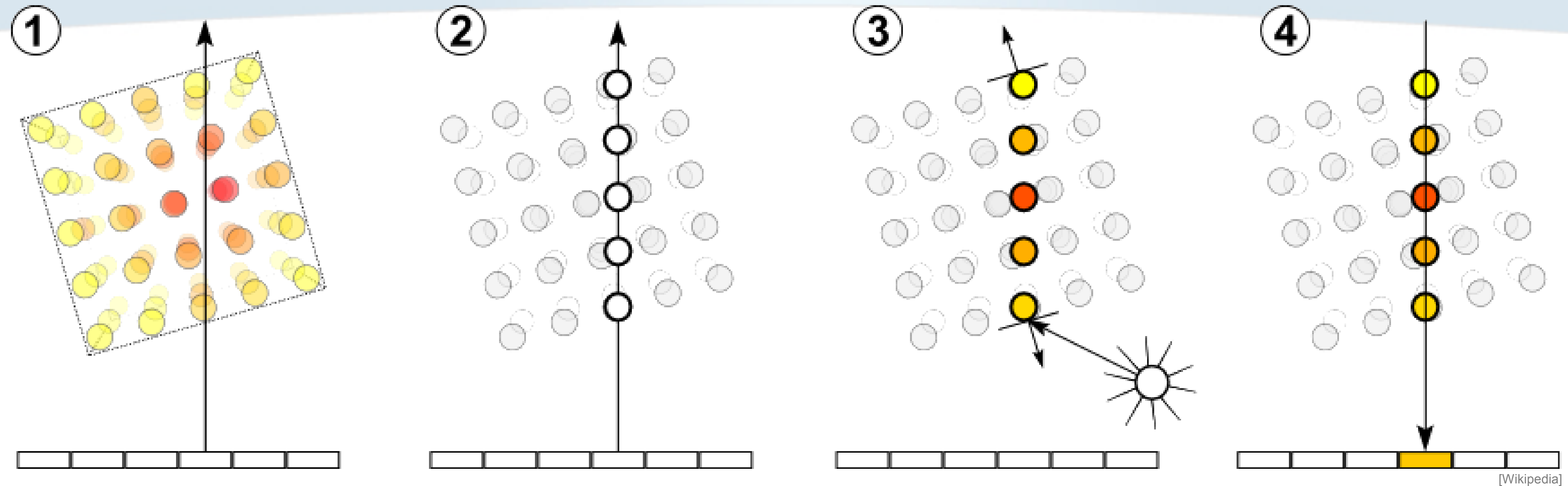


Volume rendering: how does it work?



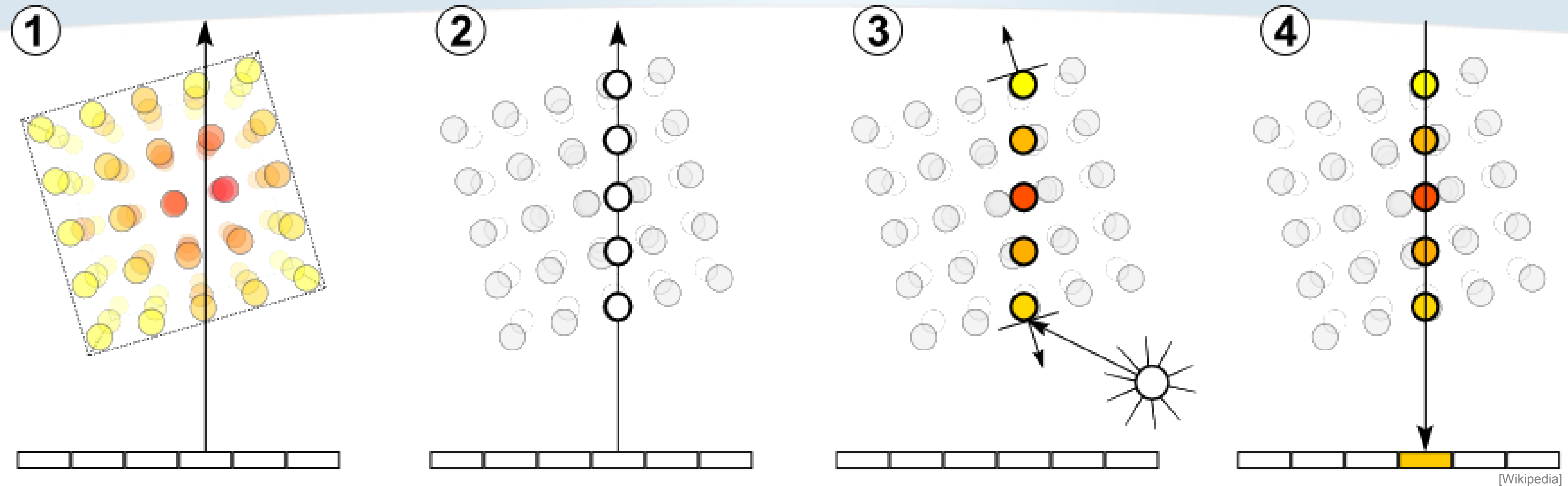
- Ray casting

Volume rendering: how does it work?



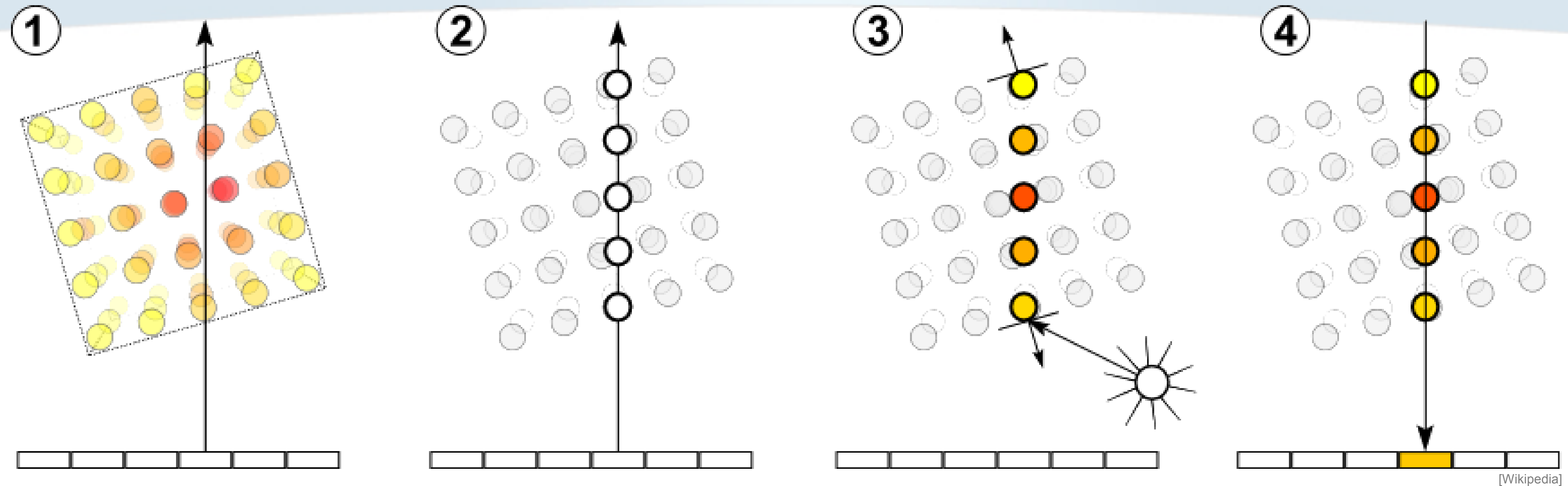
- Ray casting
- Sampling

Volume rendering: how does it work?



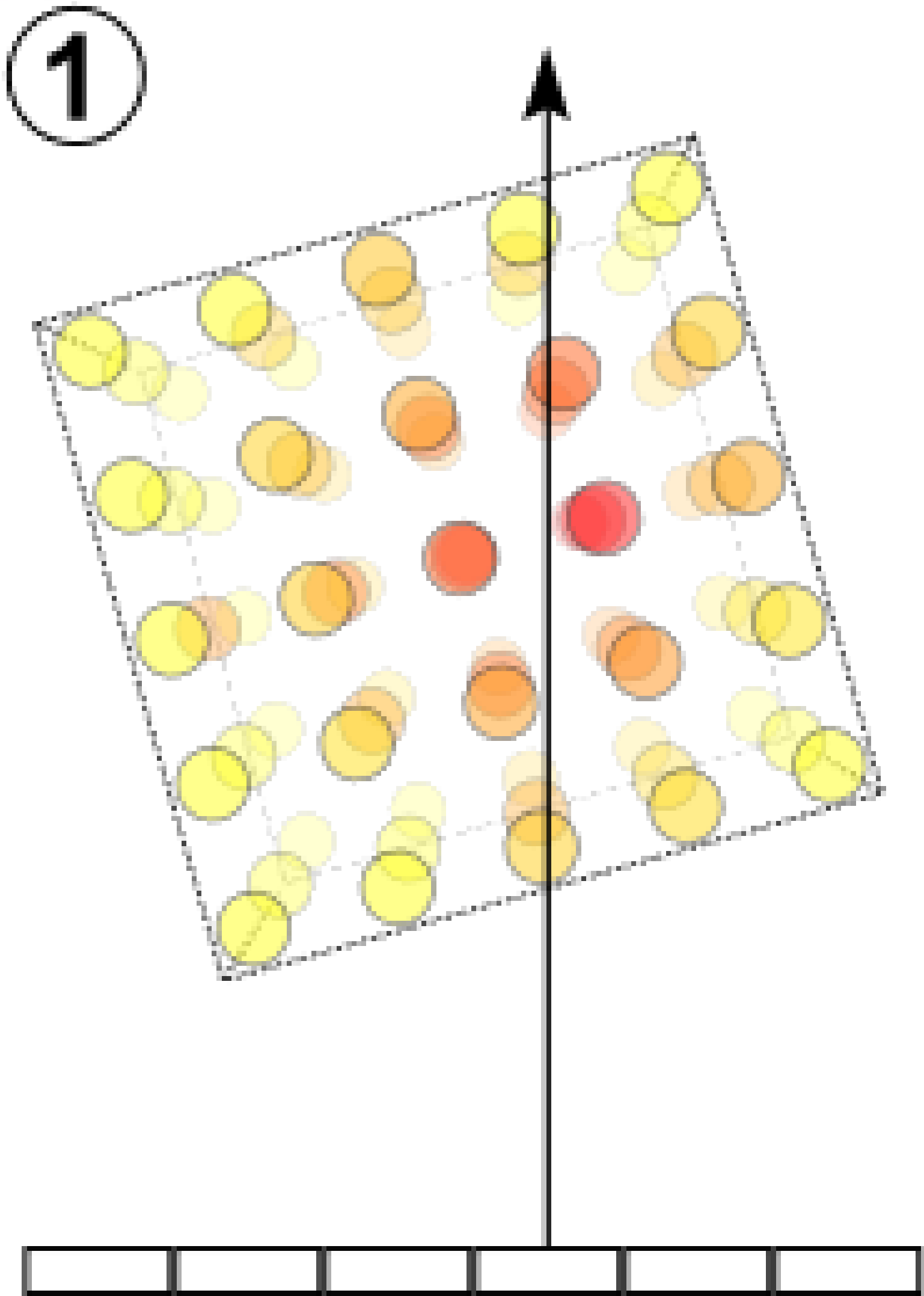
- Ray casting
- Sampling
- Shading

Volume rendering: how does it work?



- Ray casting
- Sampling
- Shading
- Compositing

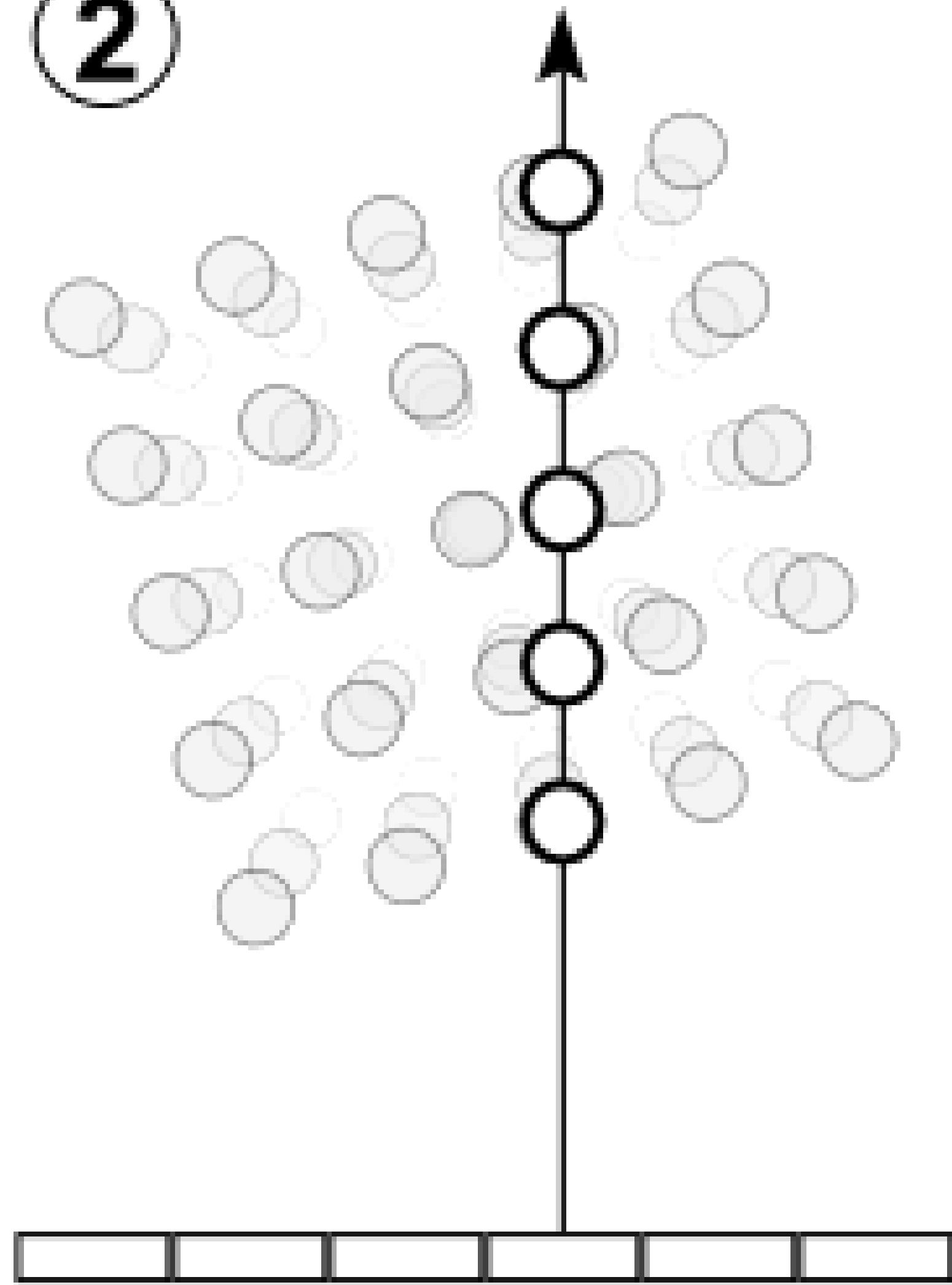
Ray casting



- For each pixel (screen space)
 - Cast a ray
 - Direction of observation
 - Intersection problem
 - Which cells are traversed by the ray?
 - Accelerating structures (octrees)

Sampling

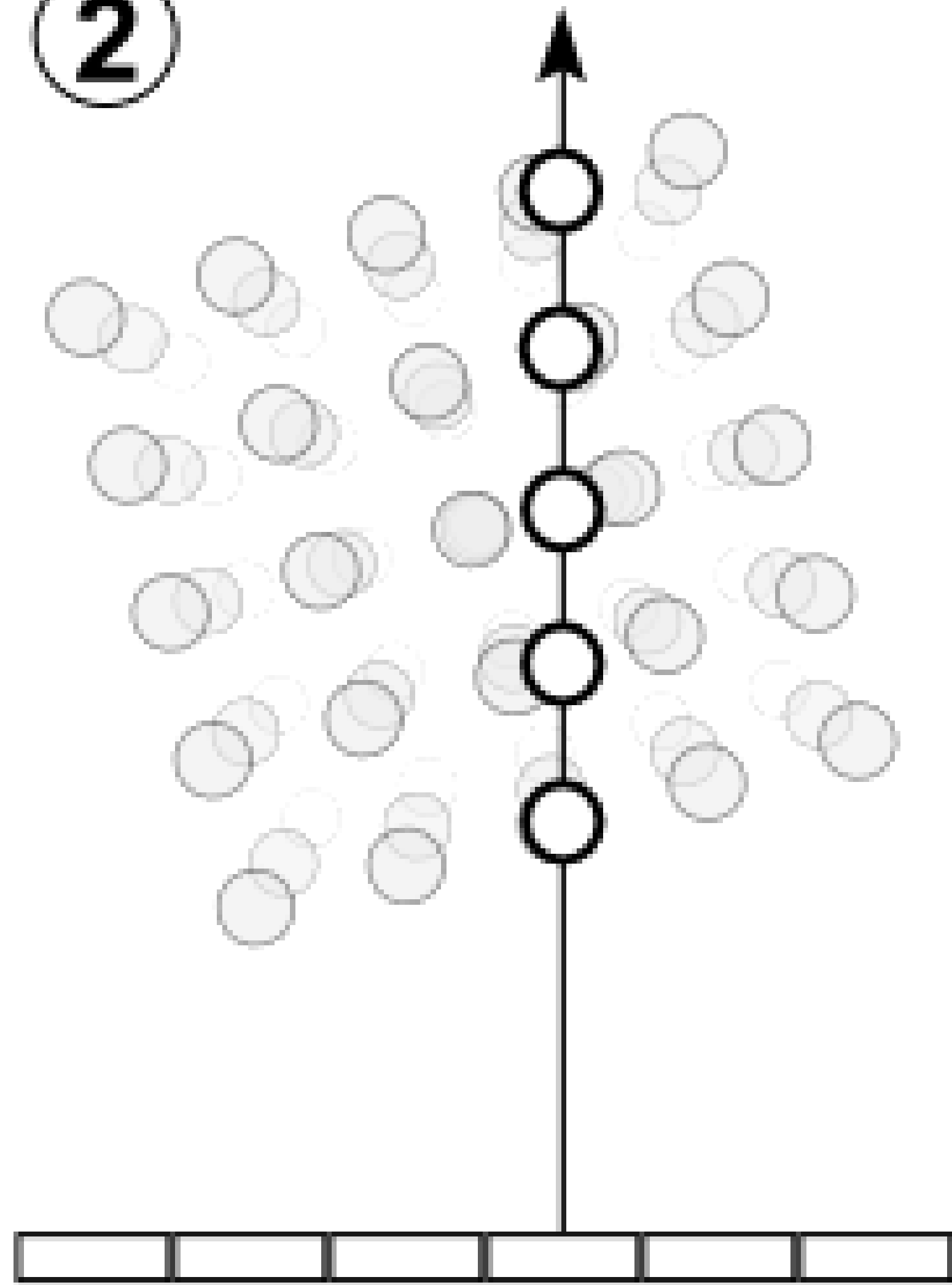
②



- Along each ray:

Sampling

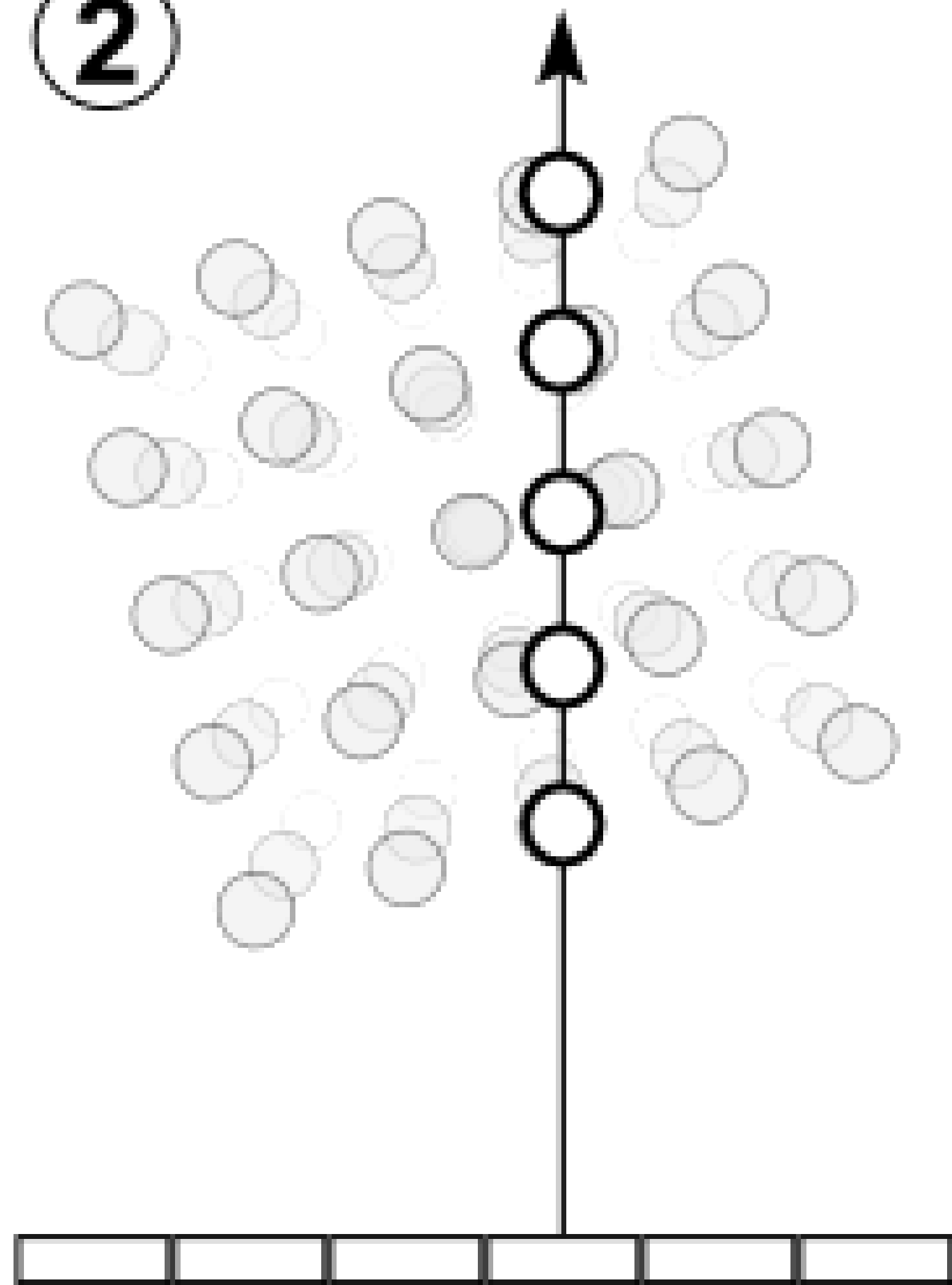
②



- Along each ray:
 - Sample the data along the ray
 - Intersection with the edges

Sampling

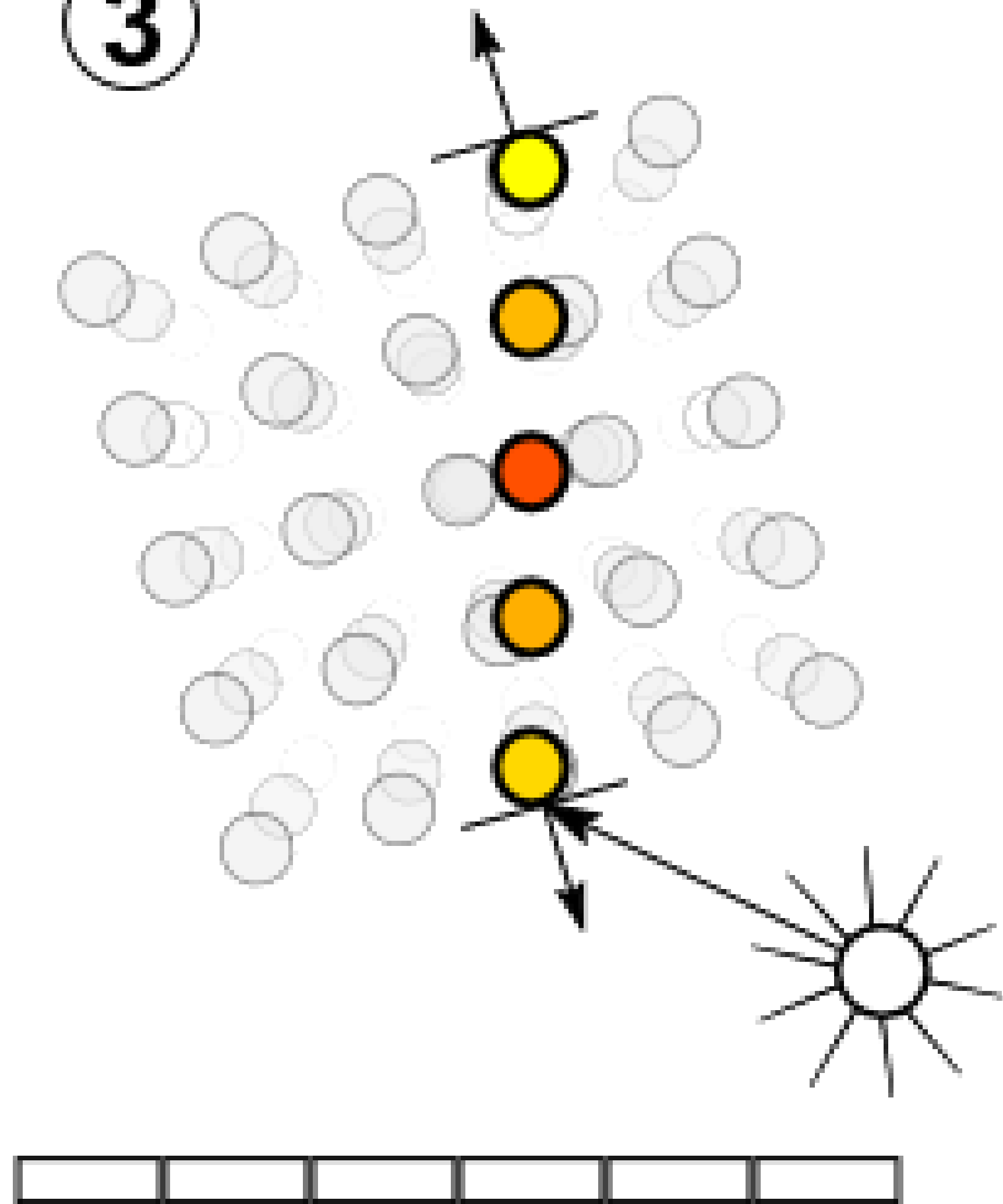
②



- Along each ray:
 - Sample the data along the ray
 - Intersection with the edges
 - Compute the function value on the samples
 - Based on the domain interpolant

Shading

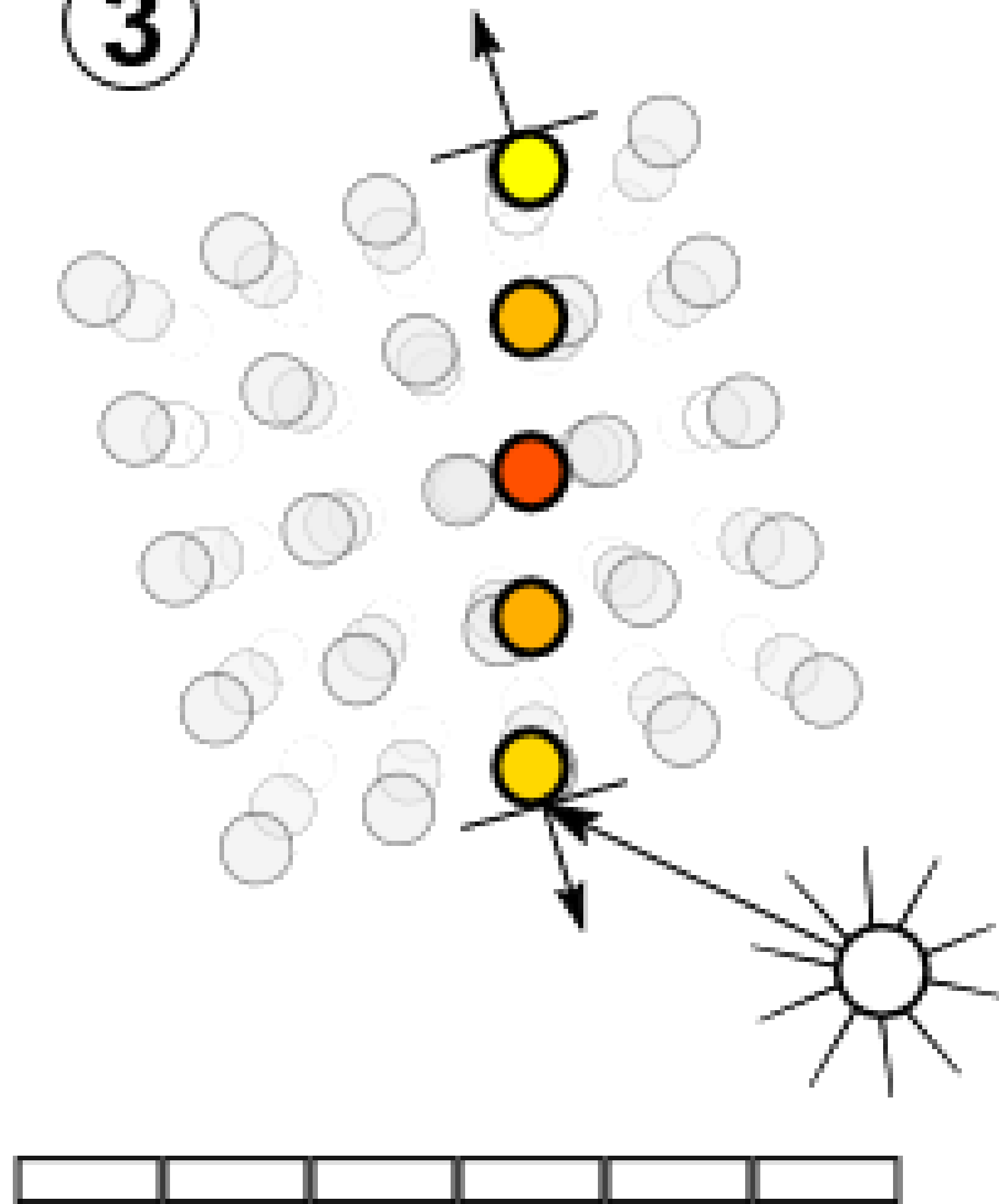
3



- Light computation for each sample

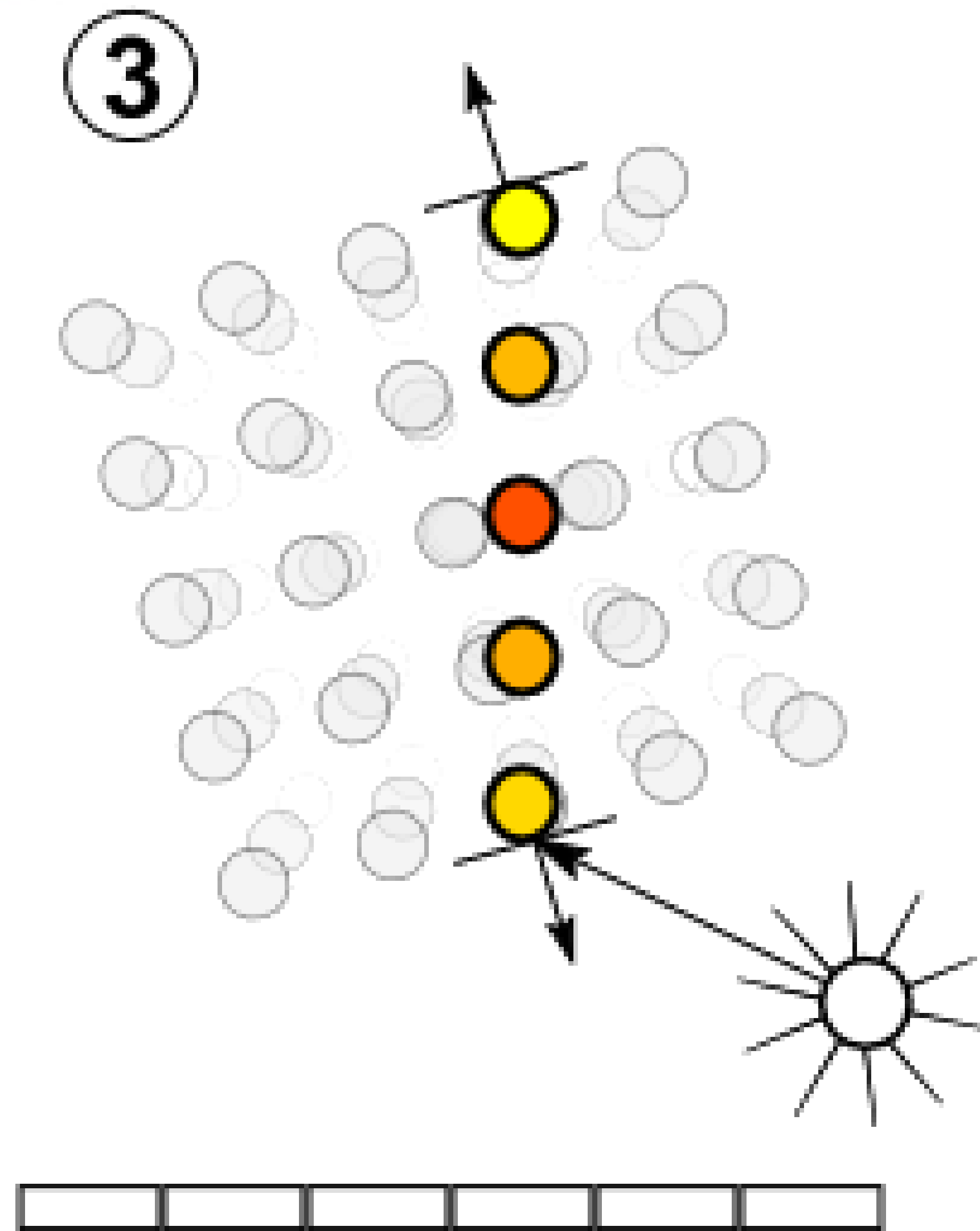
Shading

3



- Light computation for each sample
 - Retrieve the corresponding color (transfer)

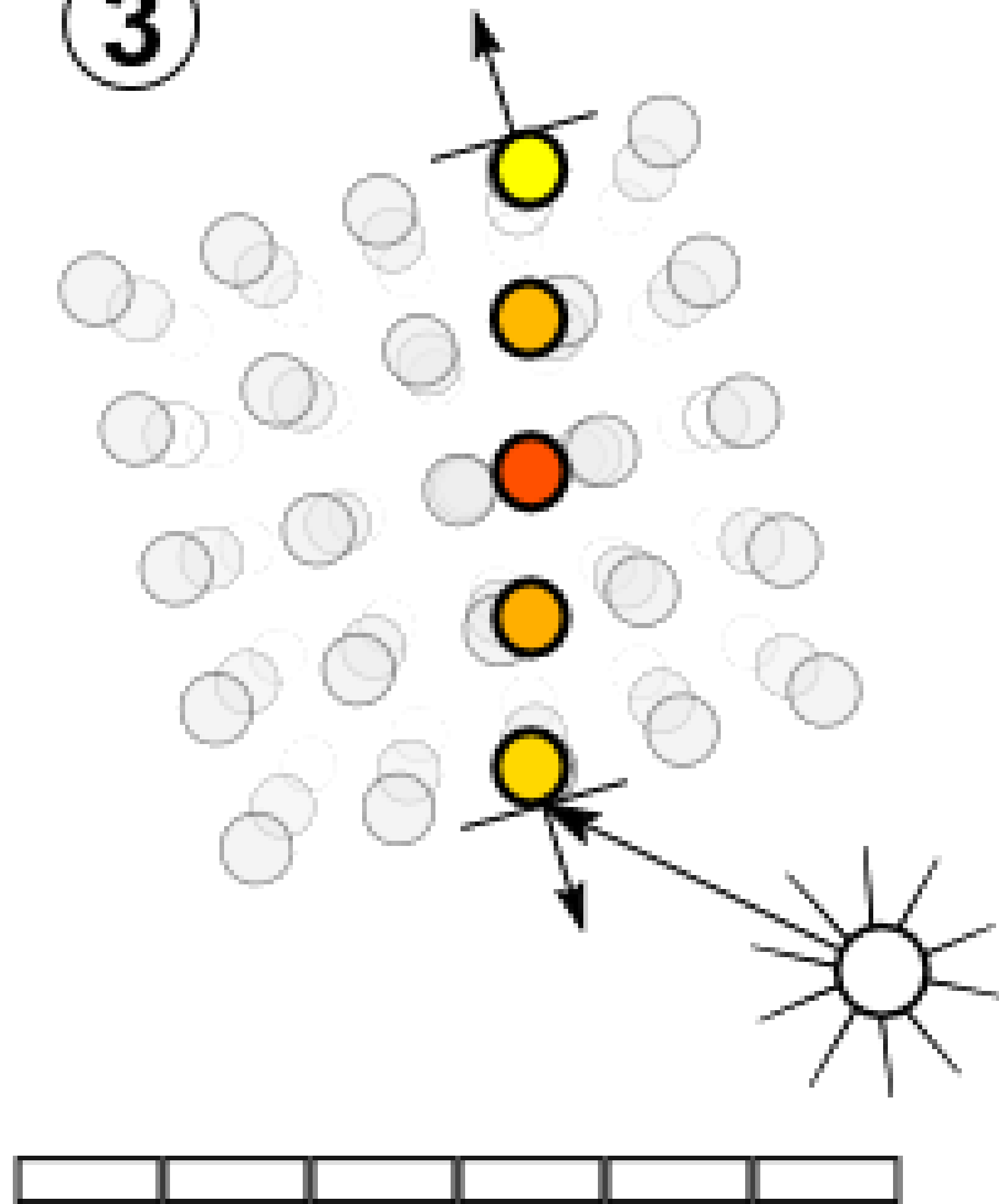
Shading



- Light computation for each sample
 - Retrieve the corresponding color (transfer)
 - Retrieve the surface normal

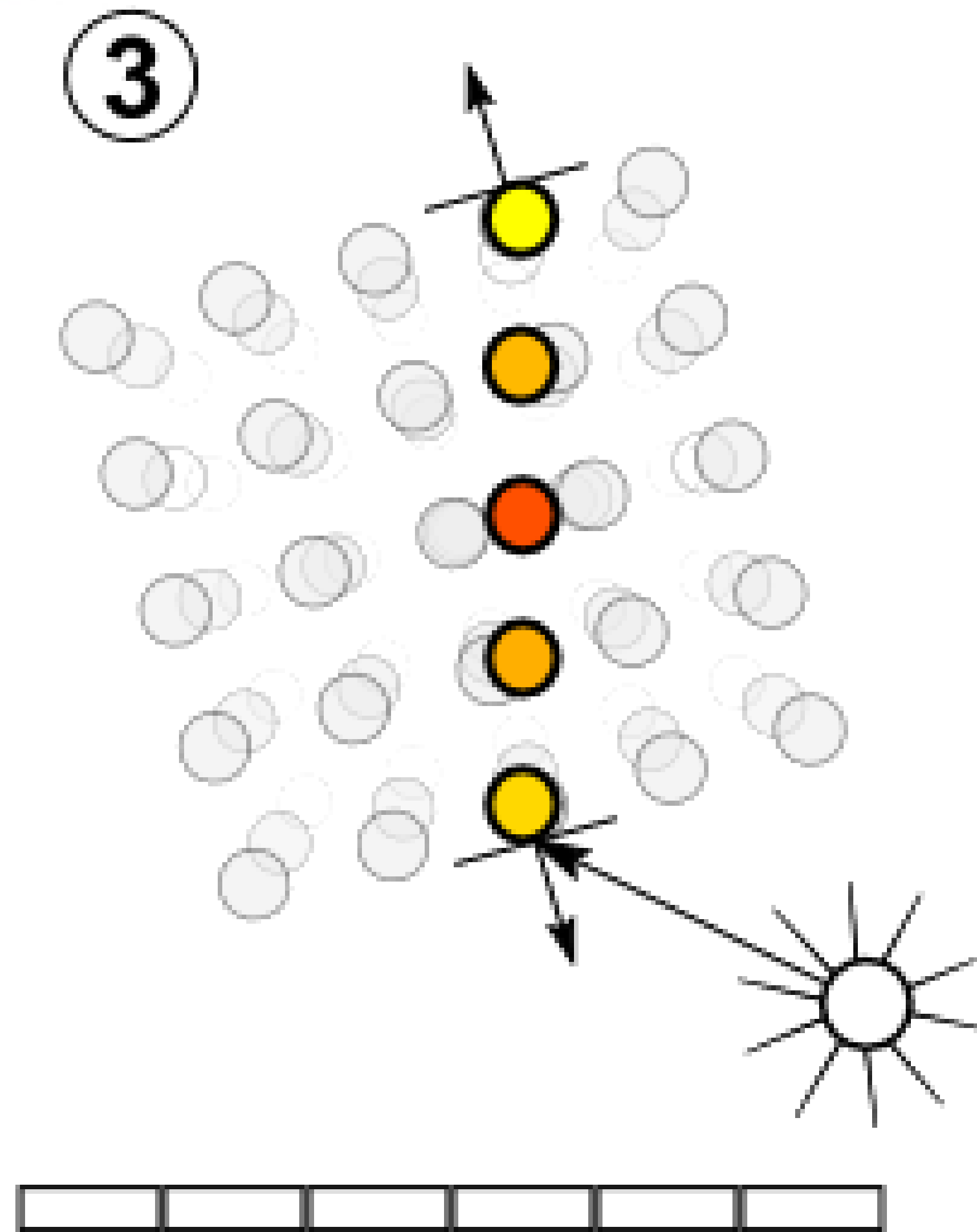
Shading

3



- Light computation for each sample
 - Retrieve the corresponding color (transfer)
 - Retrieve the surface normal
 - Normal to the isosurface

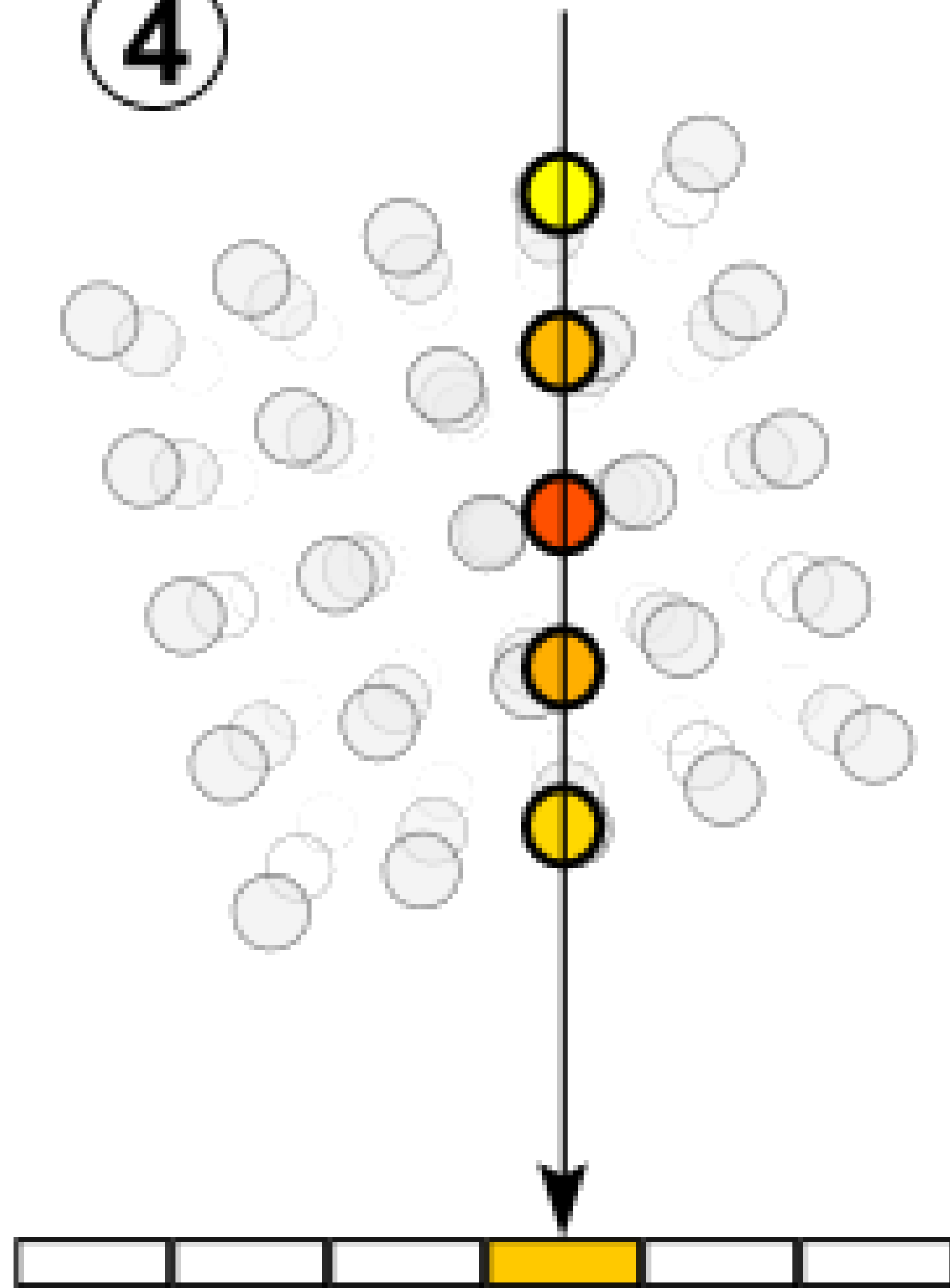
Shading



- Light computation for each sample
 - Retrieve the corresponding color (transfer)
 - Retrieve the surface normal
 - Normal to the isosurface
 - Shade the sample accordingly
 - Normal
 - View direction
 - Color

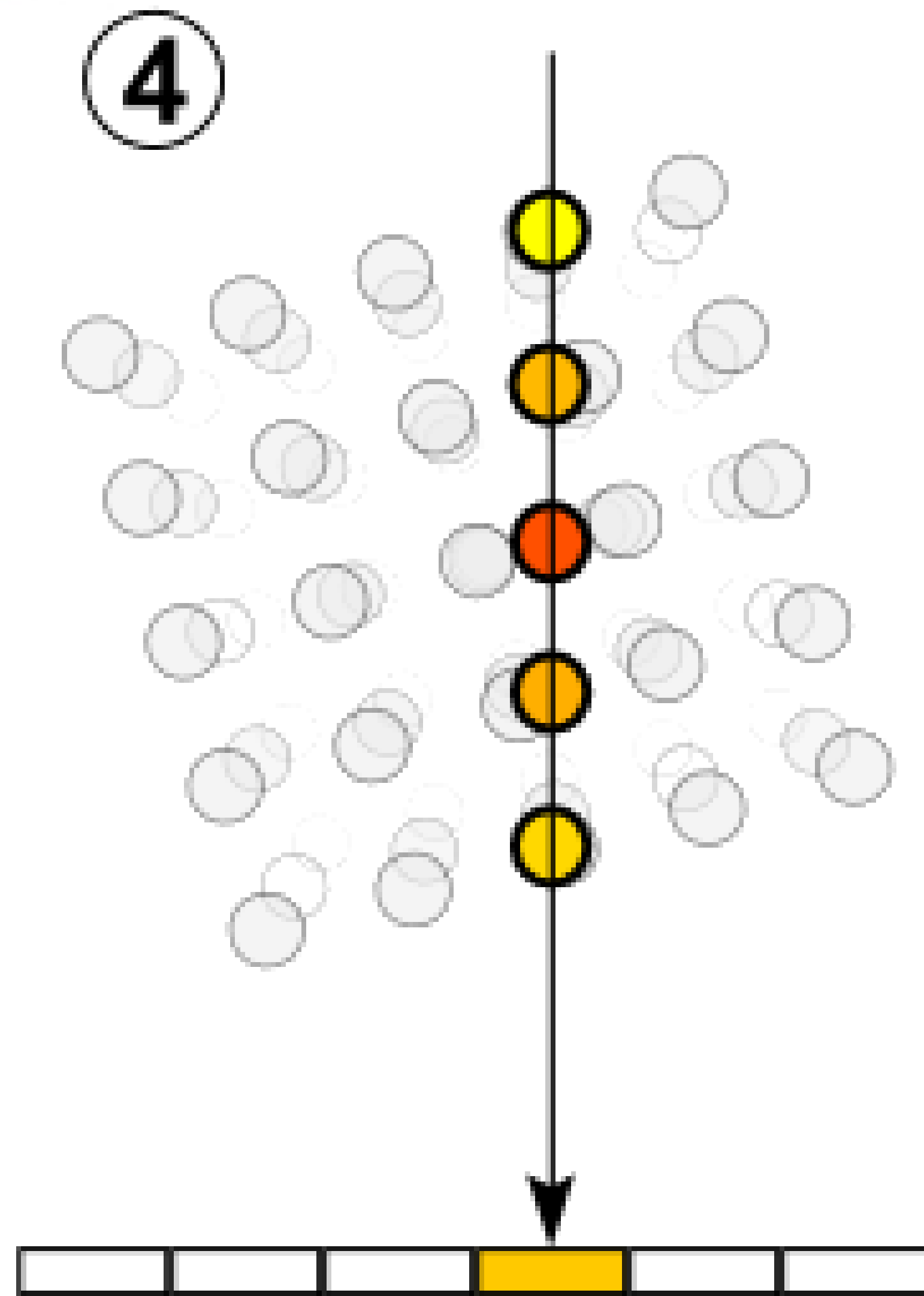
Compositing

④



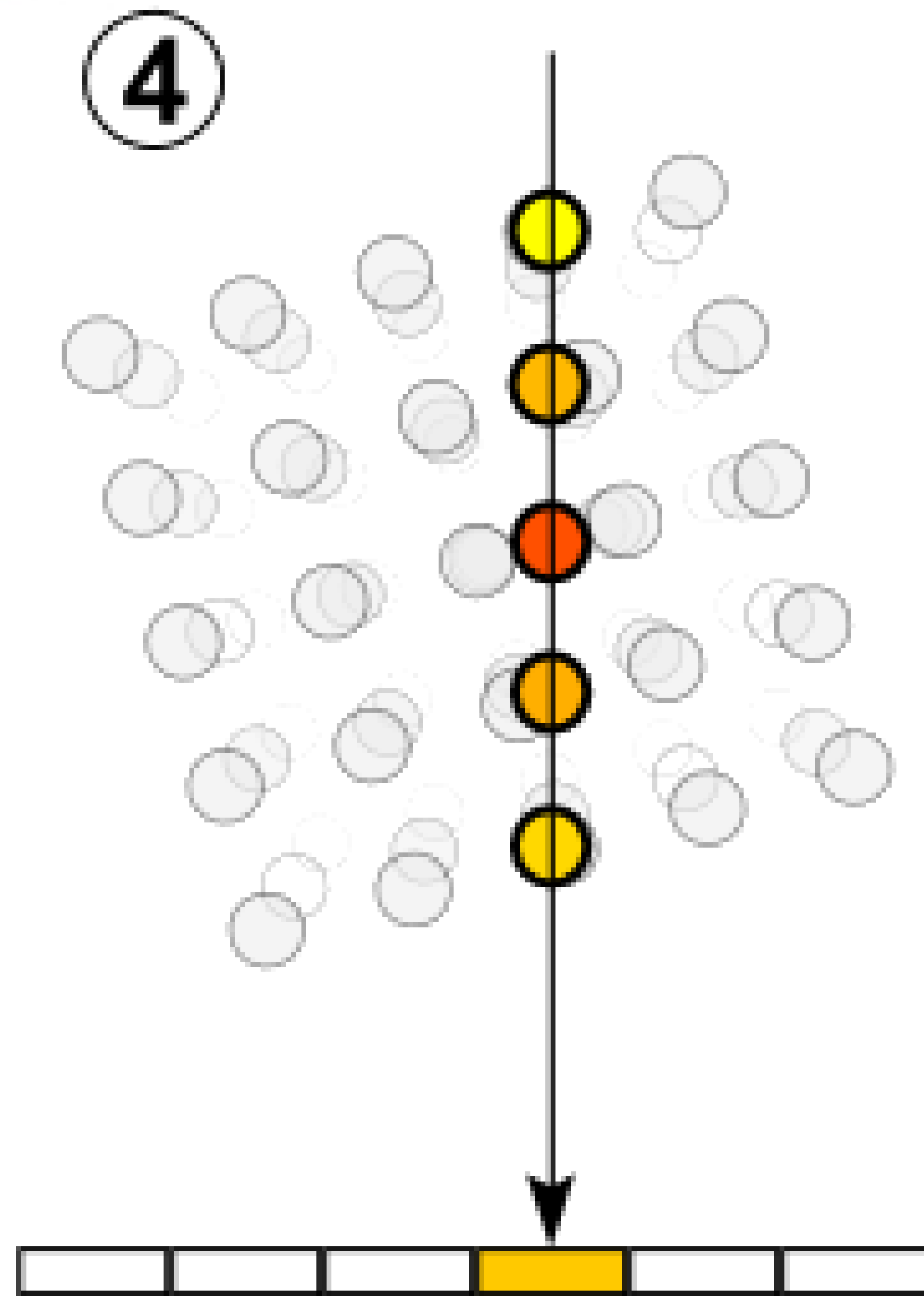
- Integrate all the samples' contributions

Compositing



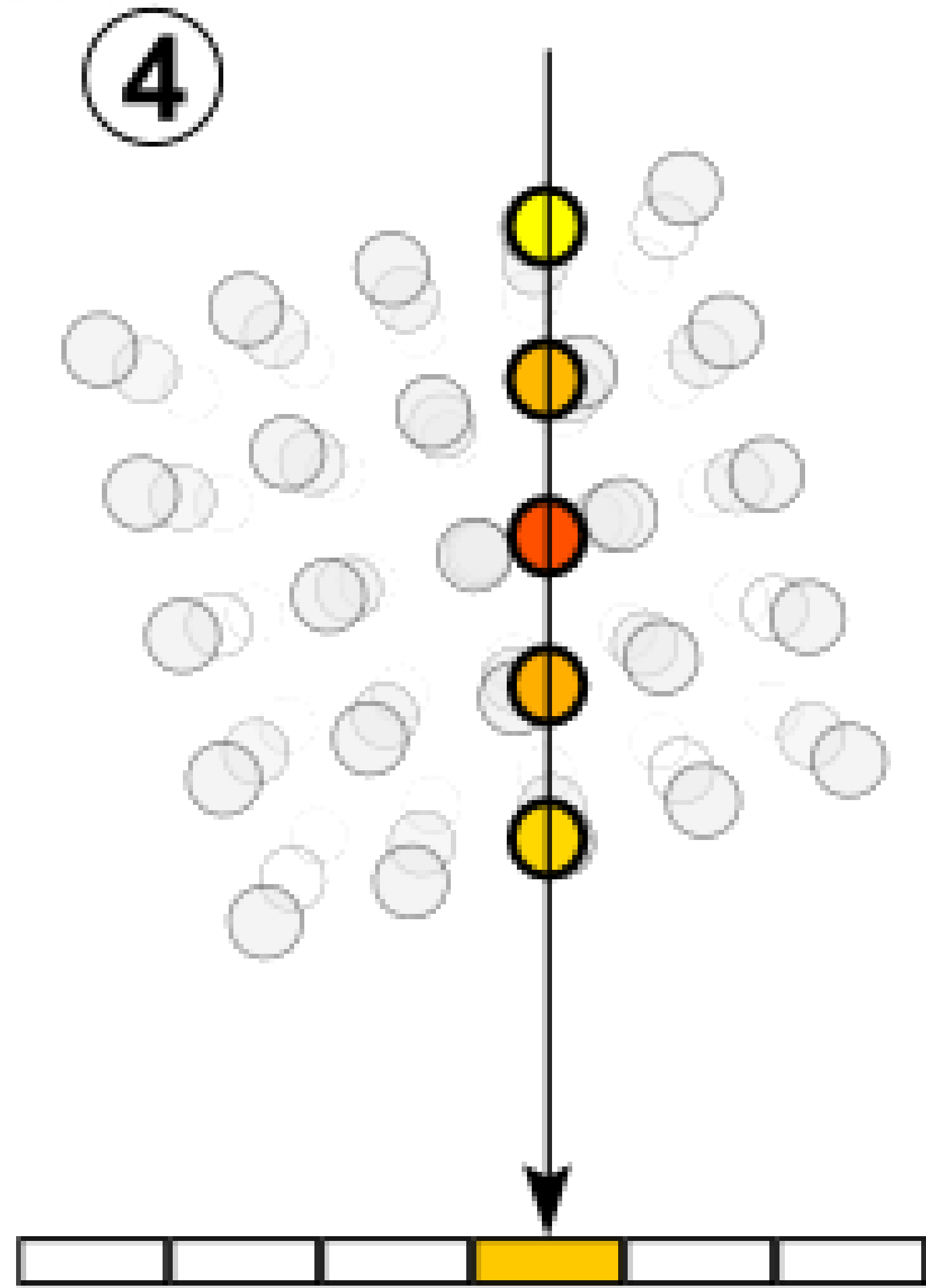
- Integrate all the samples' contributions
 - Along each ray
 - From the back to the front

Compositing



- Integrate all the samples' contributions
 - Along each ray
 - From the back to the front
 - At each sample
 - Retrieve the opacity value (transfer)

Compositing



- Integrate all the samples' contributions
 - Along each ray
 - From the back to the front
 - At each sample
 - Retrieve the opacity value (transfer)
 - Composition along the ray
 - Blend the color of the samples
 - Based on the opacity of the samples

Color blending

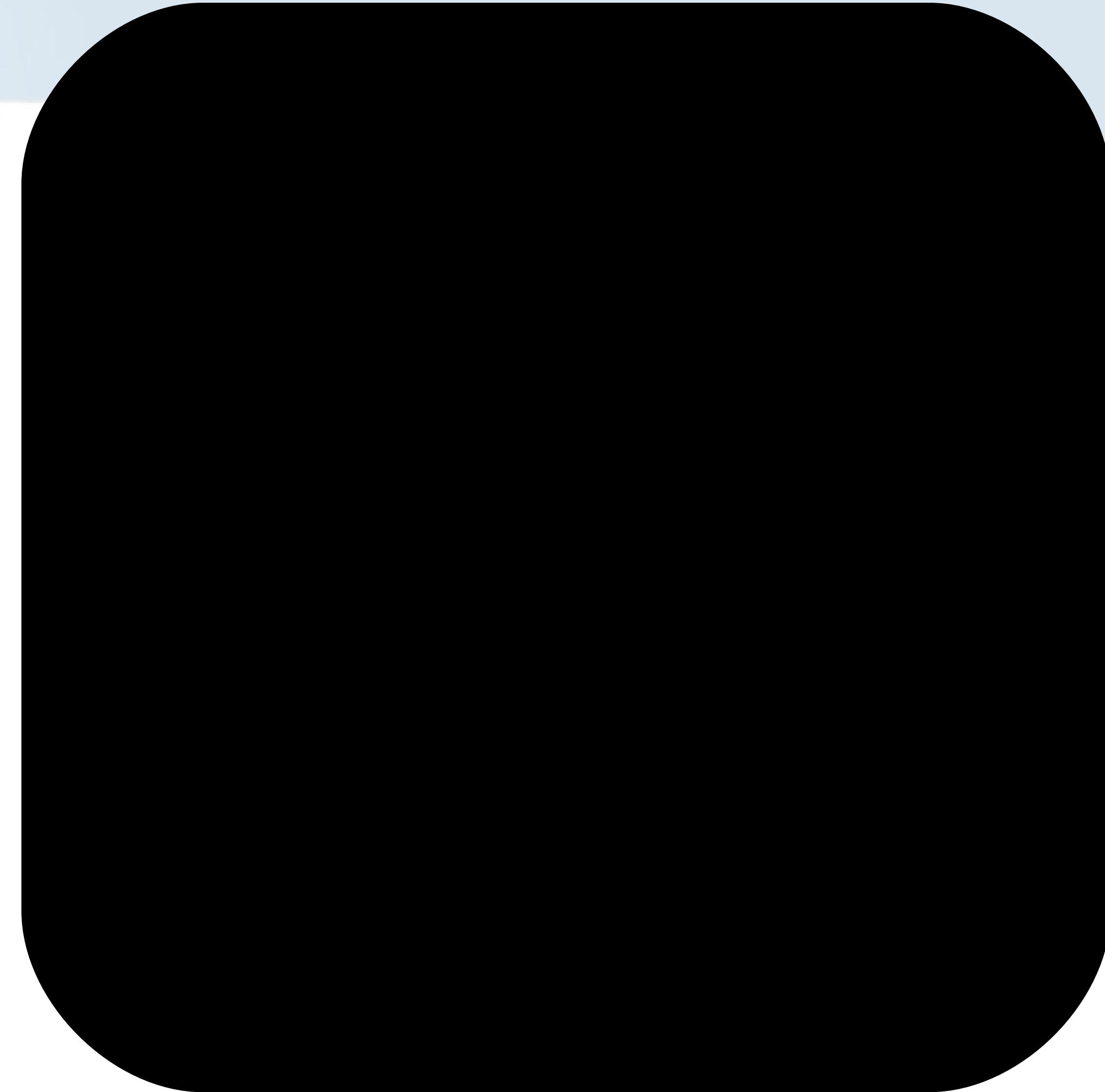
- Screen space operation
 - Blend the colors of the samples
 - Based on their opacity

Color blending

- Screen space operation
 - Blend the colors of the samples
 - Based on their opacity
- Order matters!

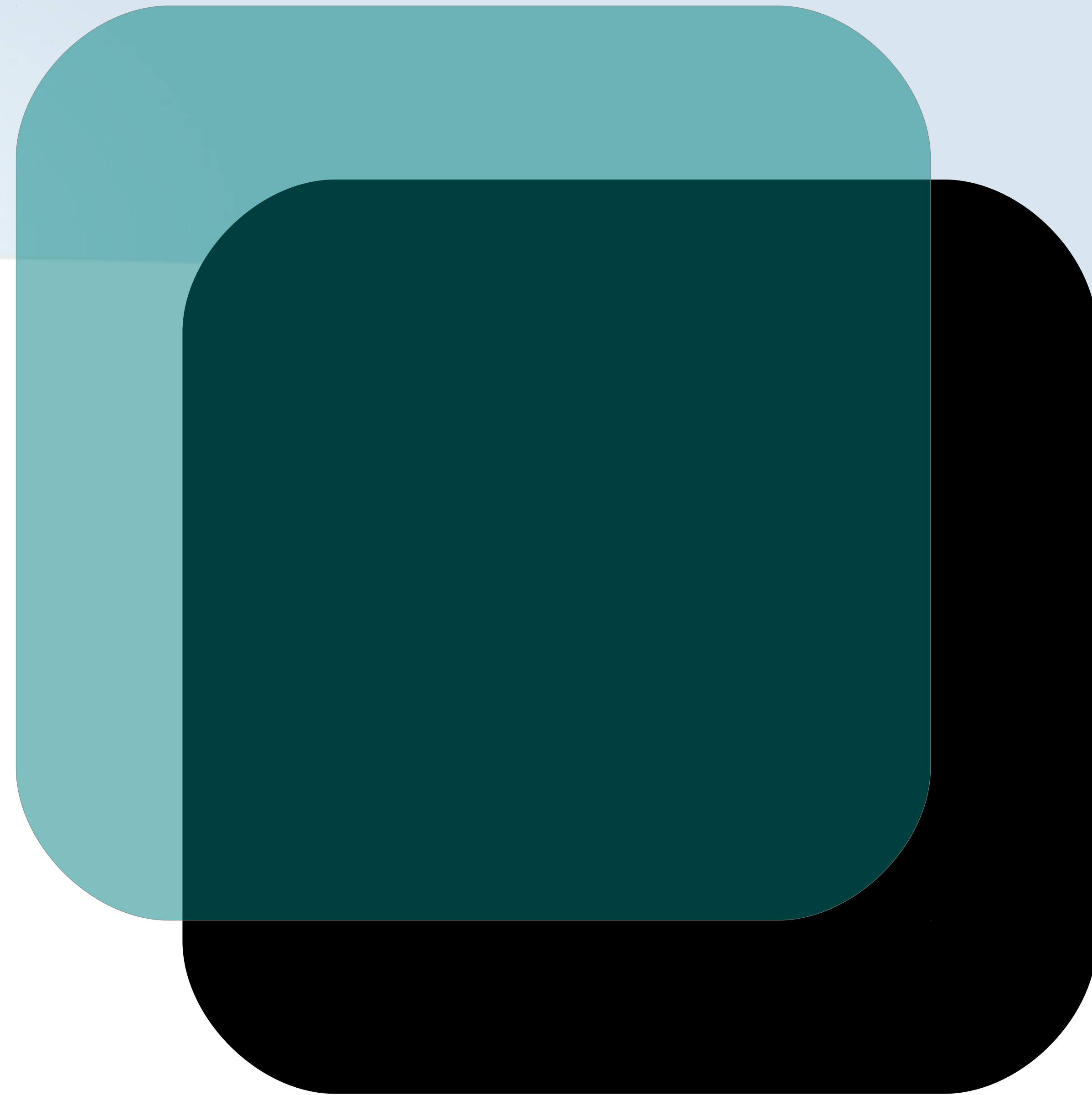
Color blending

- Screen space operation
 - Blend the colors of the samples
 - Based on their opacity
- Order matters!
 - $C_a = (0, 0, 0)$, $\alpha_a = 1$



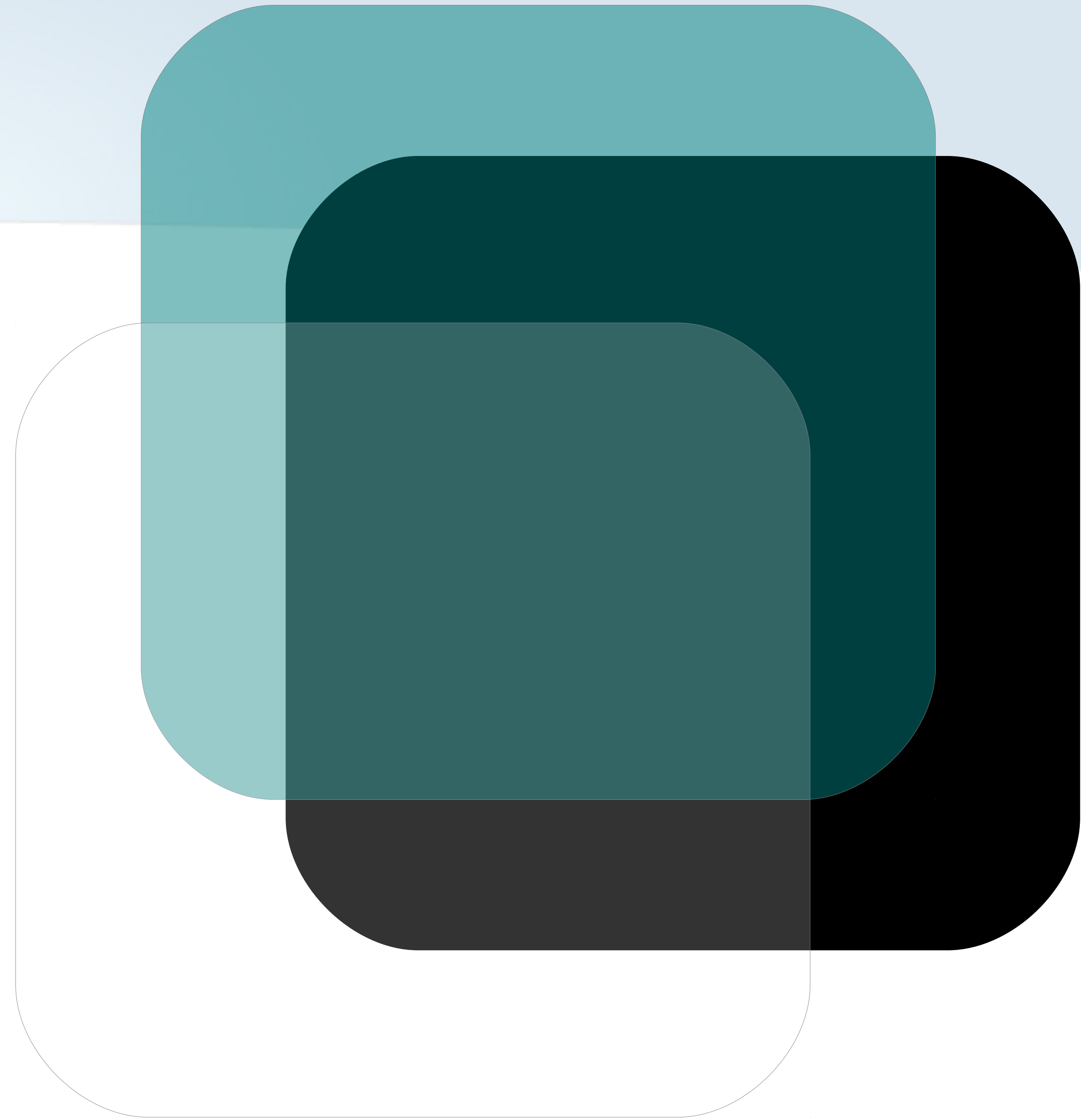
Color blending

- Screen space operation
 - Blend the colors of the samples
 - Based on their opacity
- Order matters!
 - $C_a = (0, 0, 0), \alpha_a = 1$
 - $C_b = (0, 1, 0), \alpha_b = 0.5$



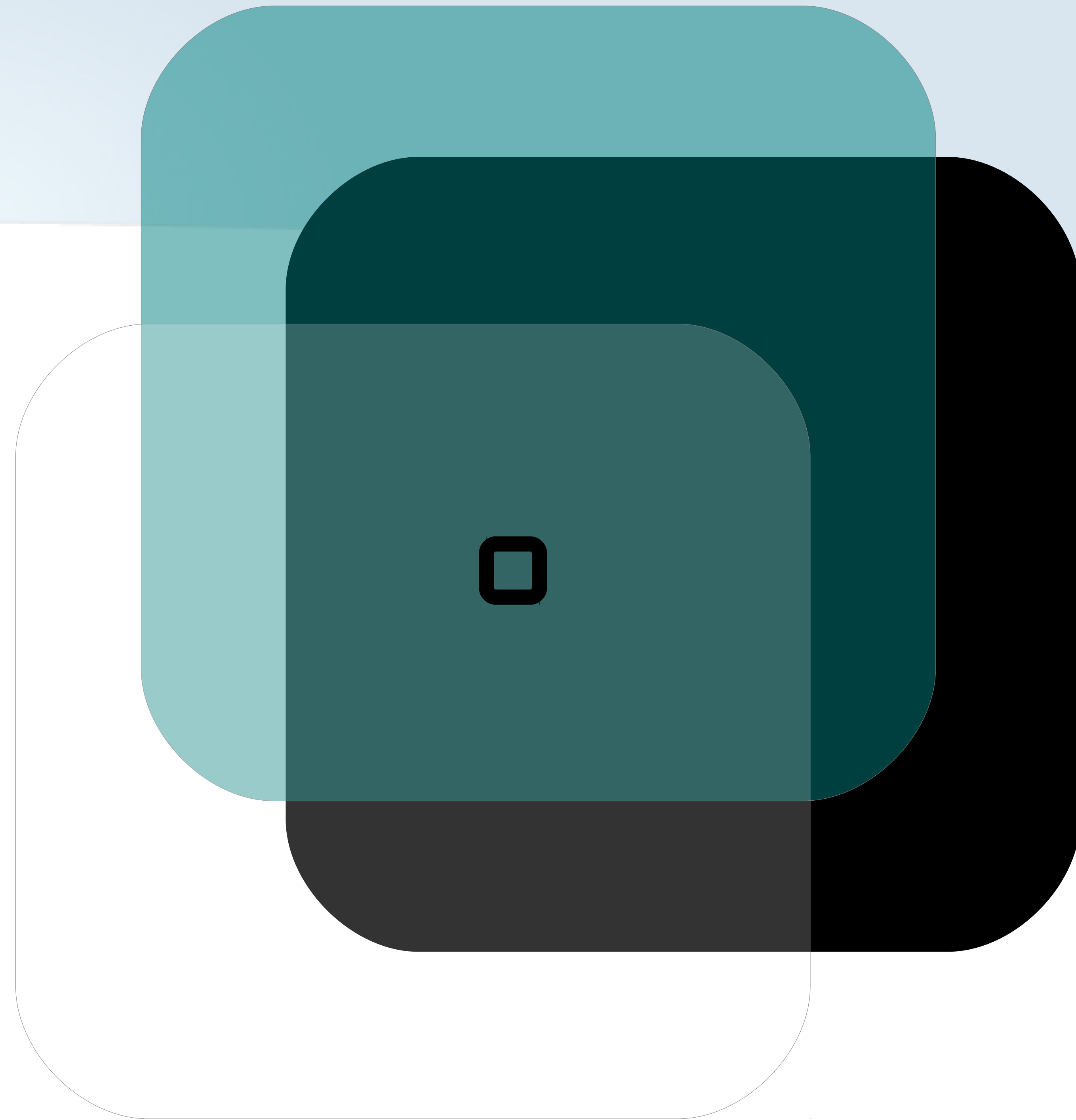
Color blending

- Screen space operation
 - Blend the colors of the samples
 - Based on their opacity
- Order matters!
 - $C_a = (0, 0, 0), \alpha_a = 1$
 - $C_b = (0, 1, 0), \alpha_b = 0.5$
 - $C_c = (1, 1, 1), \alpha_c = 0.1$



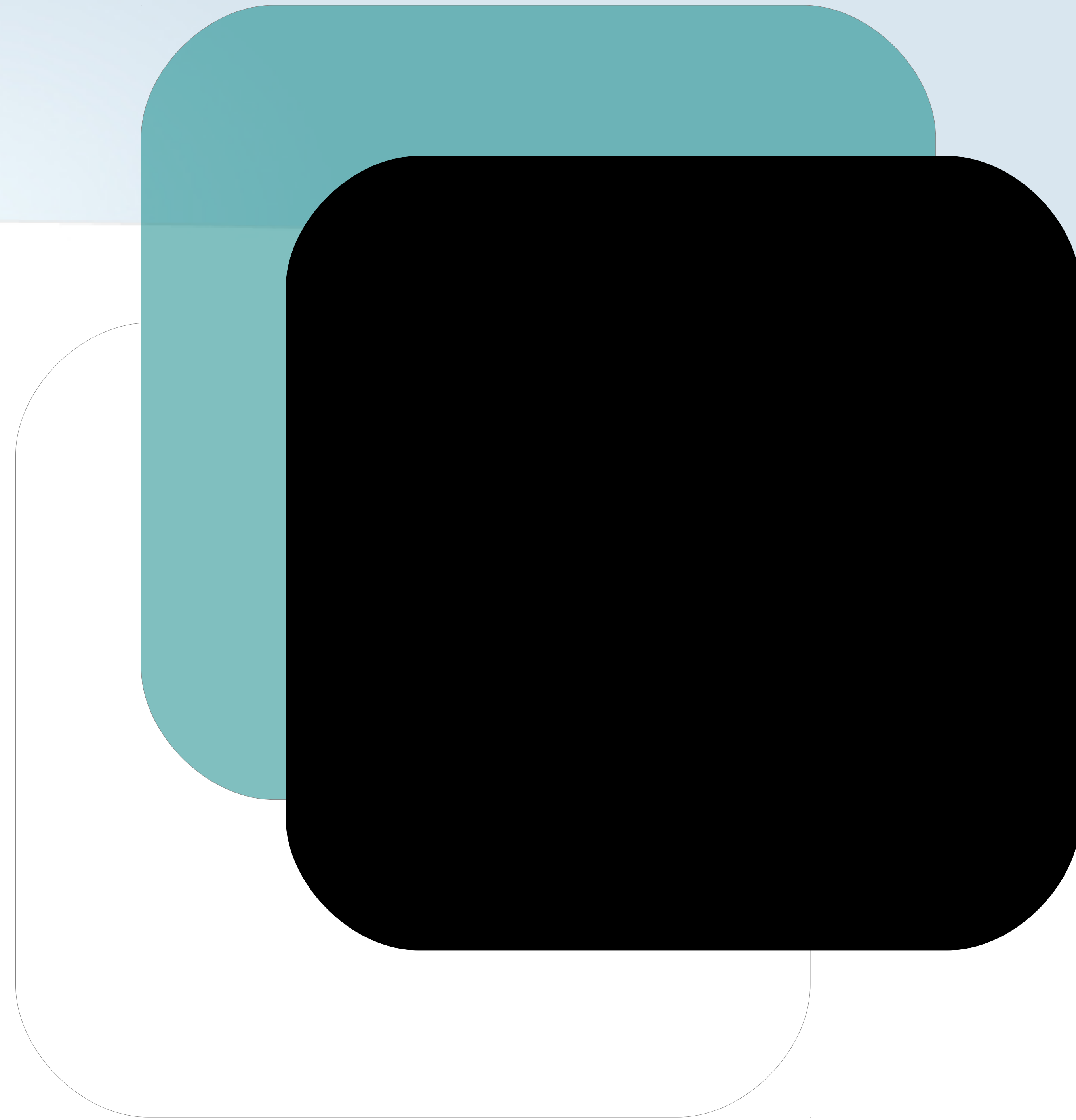
Color blending

- Screen space operation
 - Blend the colors of the samples
 - Based on their opacity
- Order matters!
 - $C_a = (0, 0, 0), \alpha_a = 1$
 - $C_b = (0, 1, 0), \alpha_b = 0.5$
 - $C_c = (1, 1, 1), \alpha_c = 0.1$



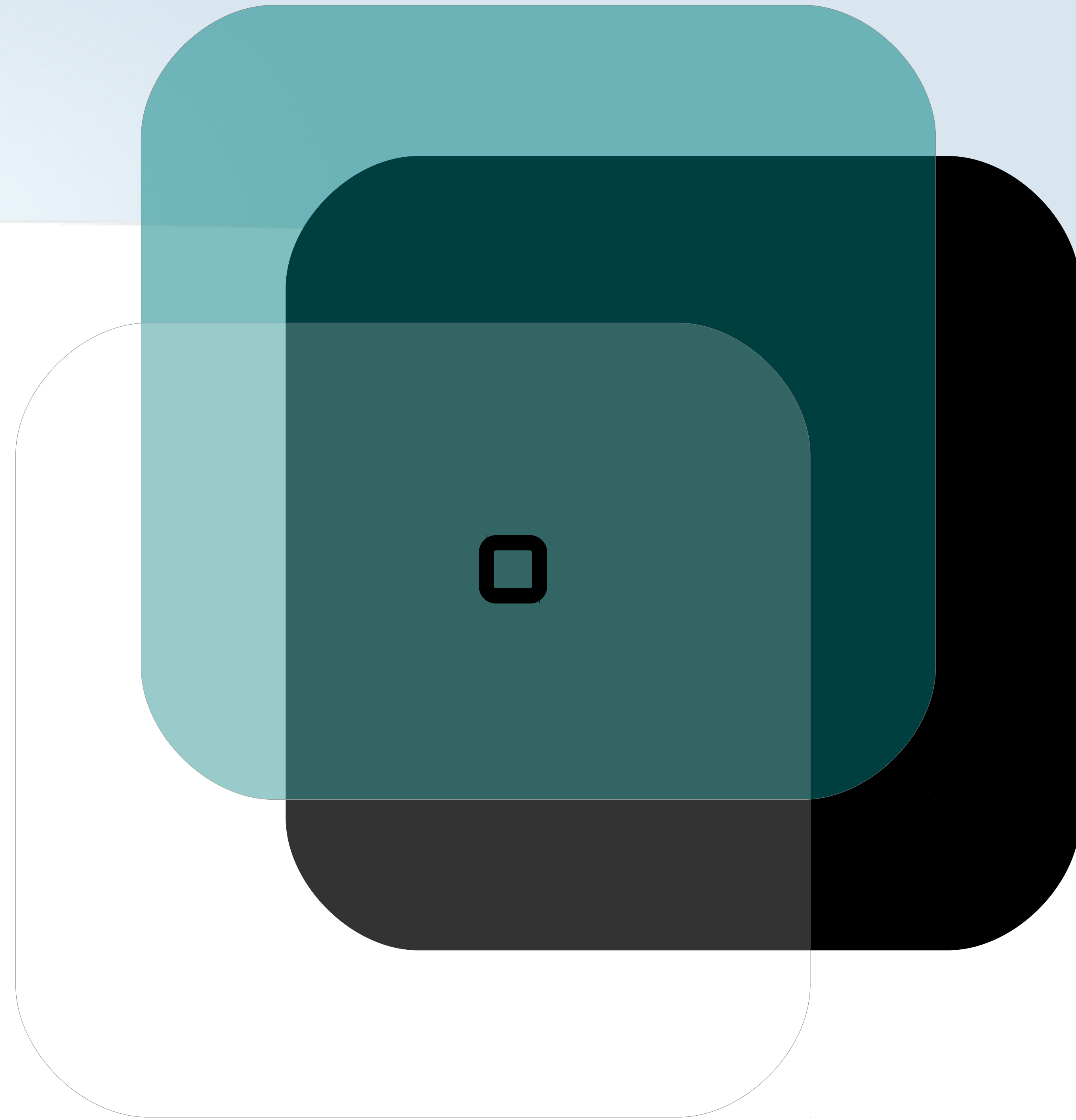
Color blending

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 - $C_a = (0, 0, 0), \alpha_a = 1$
 - $C_b = (0, 1, 0), \alpha_b = 0.5$
 - $C_c = (1, 1, 1), \alpha_c = 0.1$



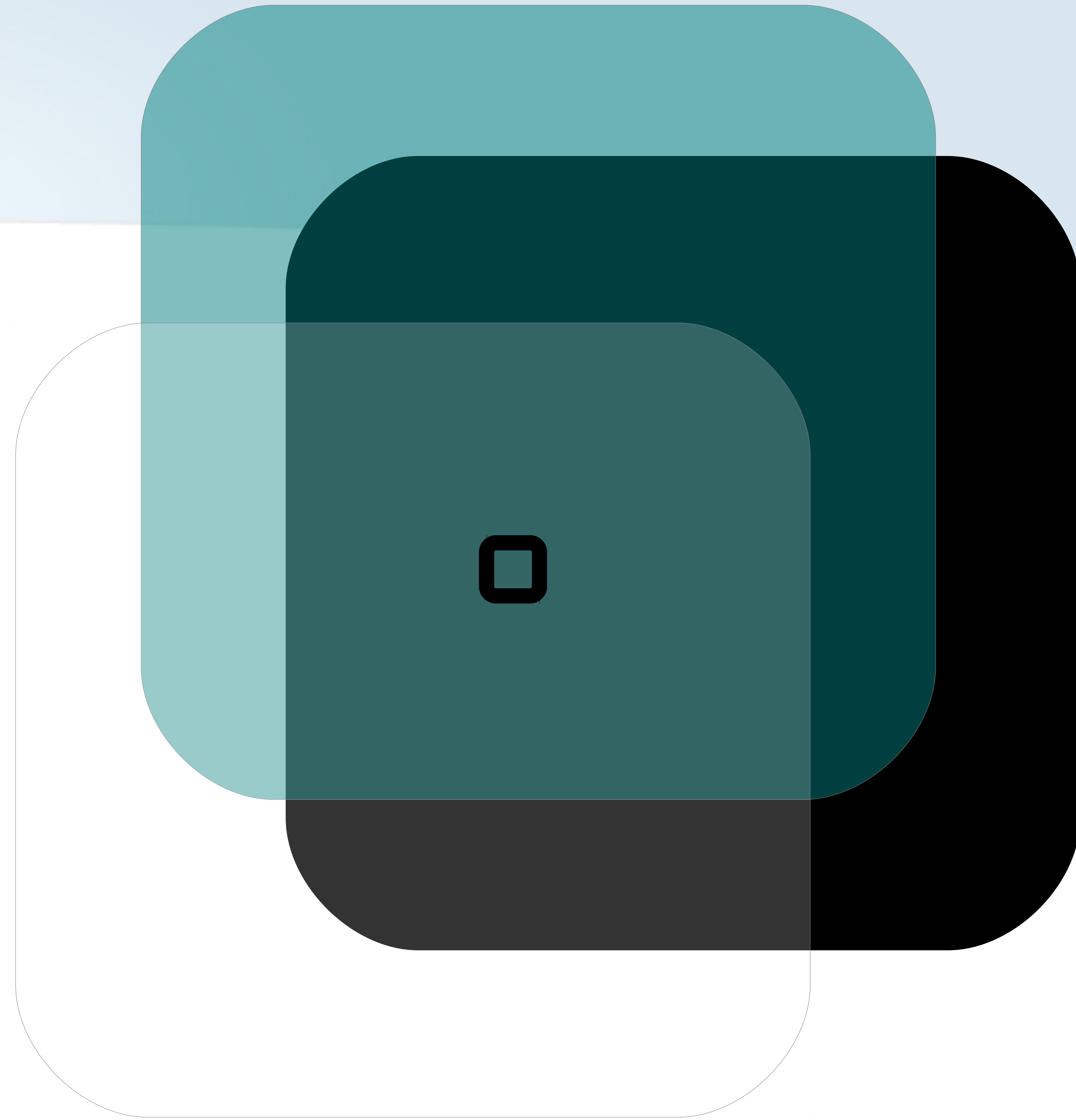
Color blending

- Screen space operation
 - Blend the colors of the samples
 - Based on their opacity
- Order matters!
 - $C_a = (0, 0, 0), \alpha_a = 1$
 - $C_b = (0, 1, 0), \alpha_b = 0.5$
 - $C_c = (1, 1, 1), \alpha_c = 0.1$



Color blending

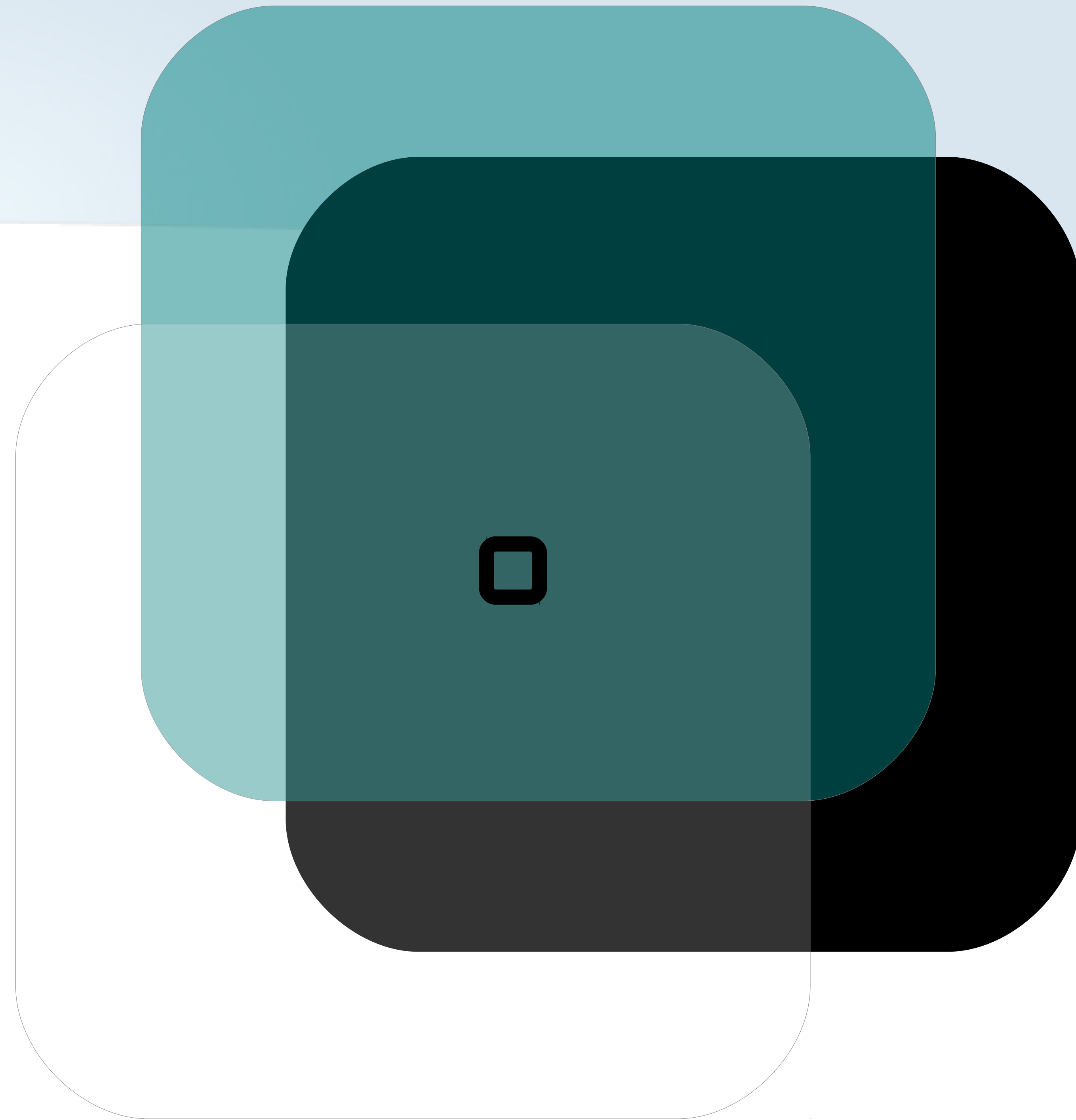
- Screen space operation
 - Blend the colors of the samples
 - Based on their opacity
- Order matters!



$$C'(i) = \alpha(i) \times C(i) + (1 - \alpha(i)) \times \alpha(i - 1) \times C(i - 1)$$

Color blending

- Screen space operation
 - Blend the colors of the samples
 - Based on their opacity
- Order matters!



$$\alpha'(i) = \alpha(i) + (1 - \alpha(i)) \times \alpha(i - 1)$$

$$C'(i) = \alpha(i) \times C(i) + (1 - \alpha(i)) \times \alpha(i - 1) \times C(i - 1)$$

Compositing schemes

- Color intensity along the ray

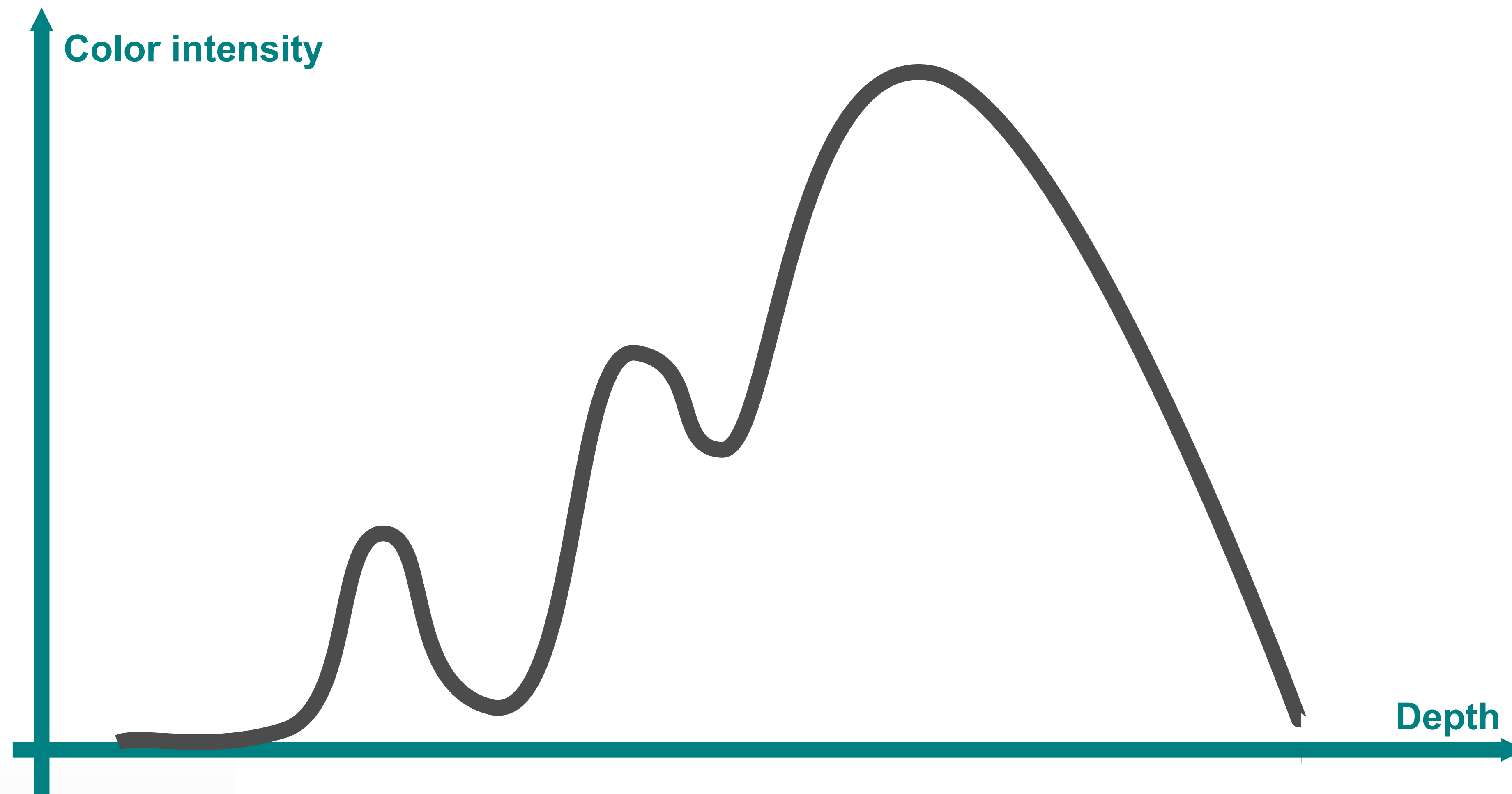
Compositing schemes

- Color intensity along the ray



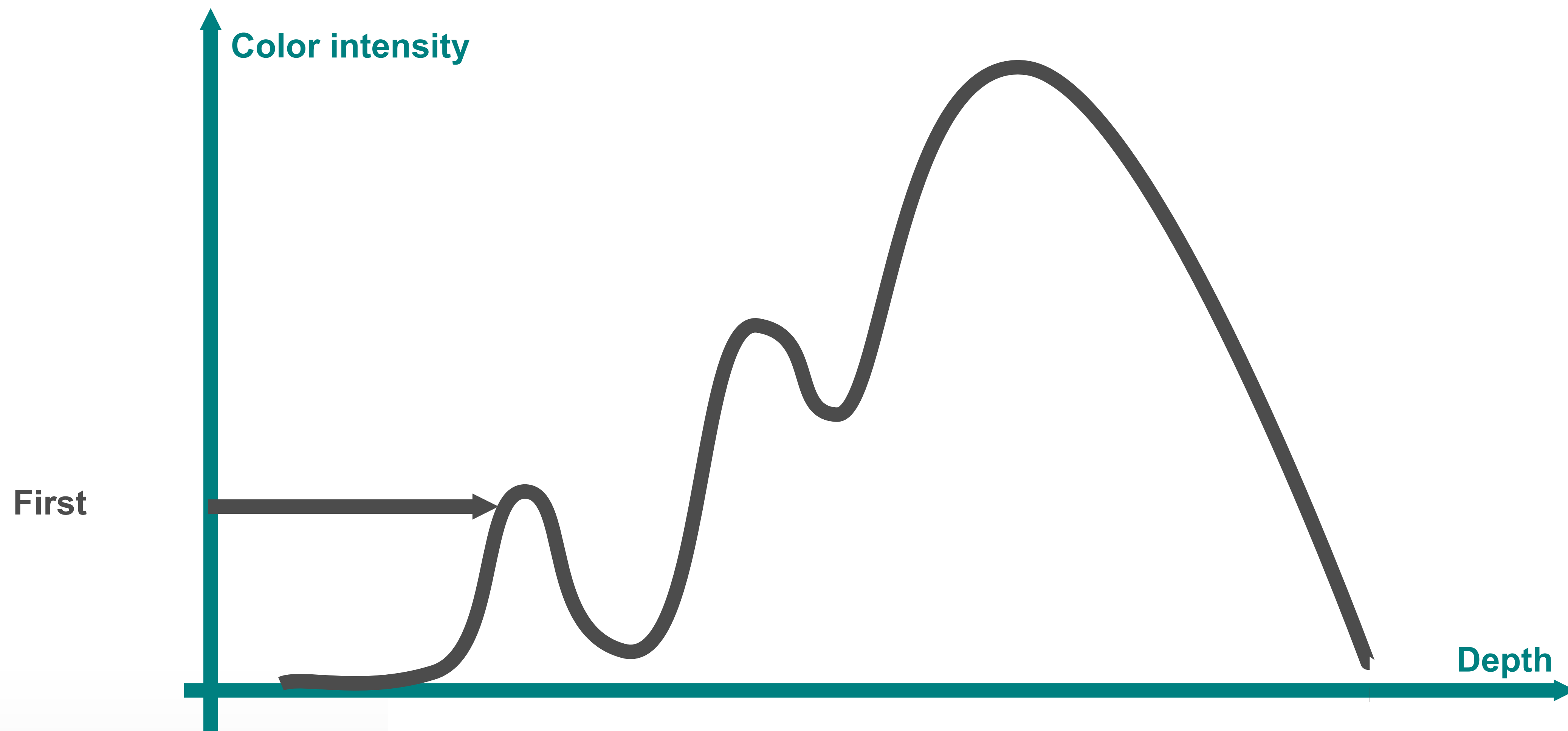
Compositing schemes

- Color intensity along the ray



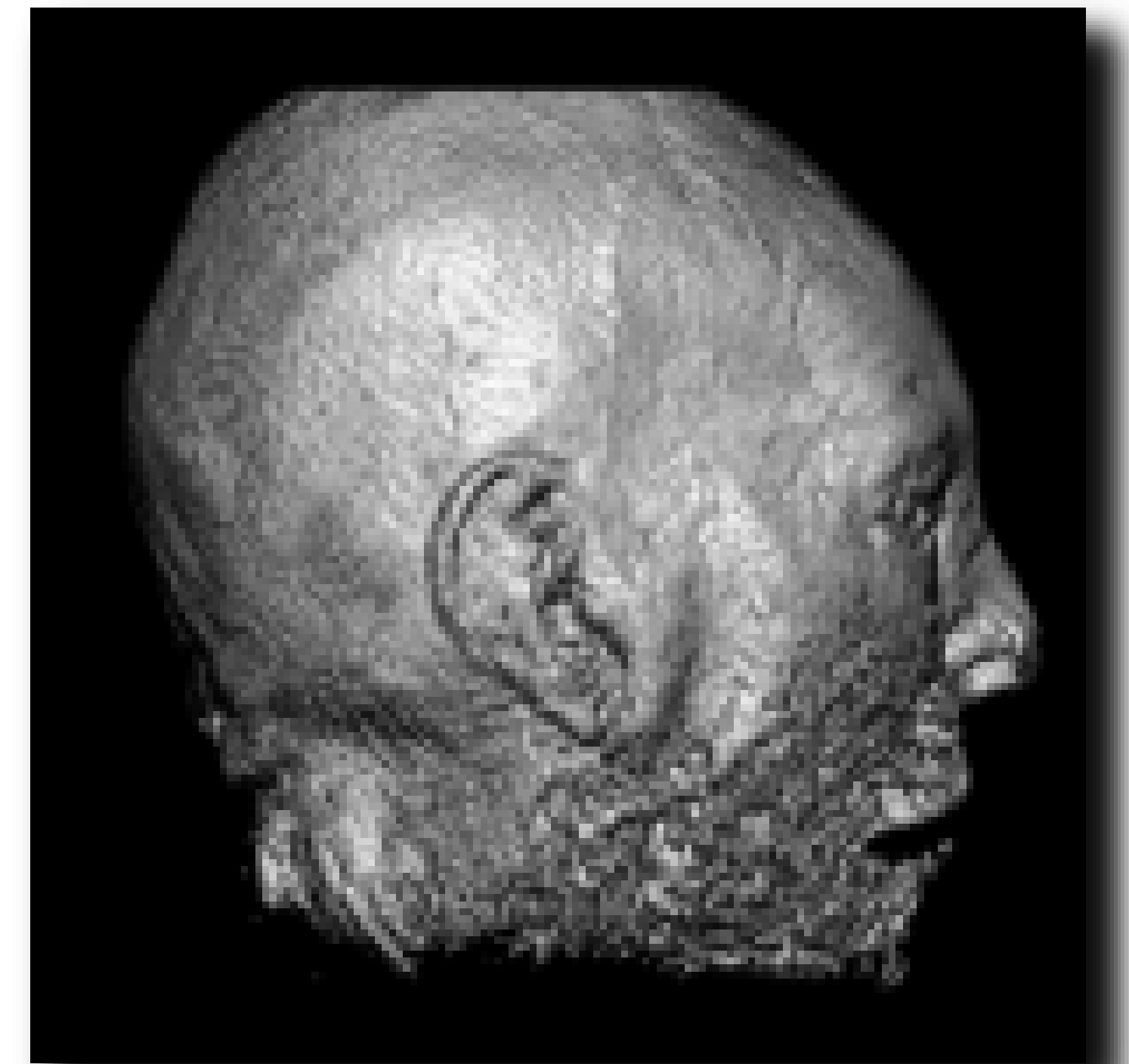
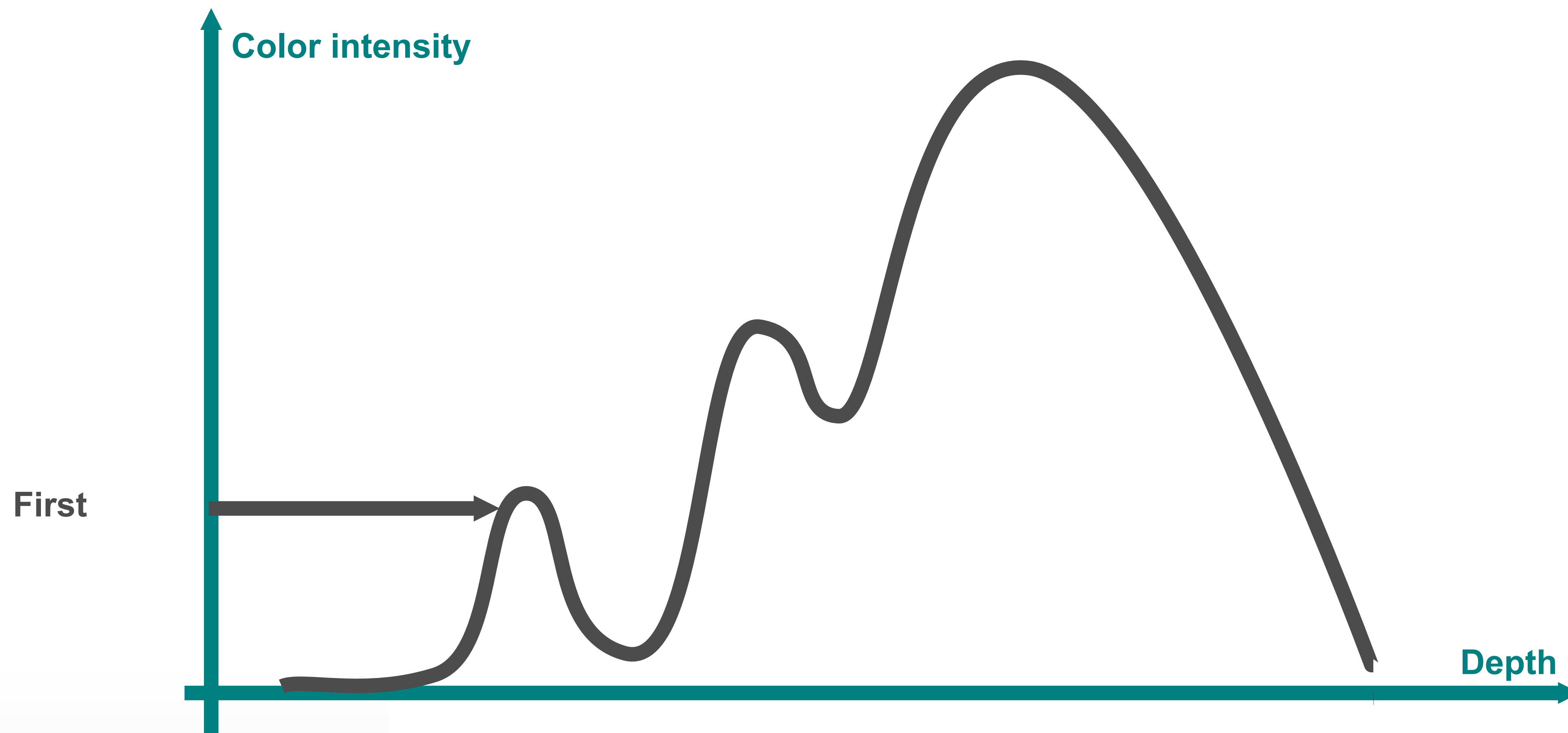
Compositing schemes

- Color intensity along the ray



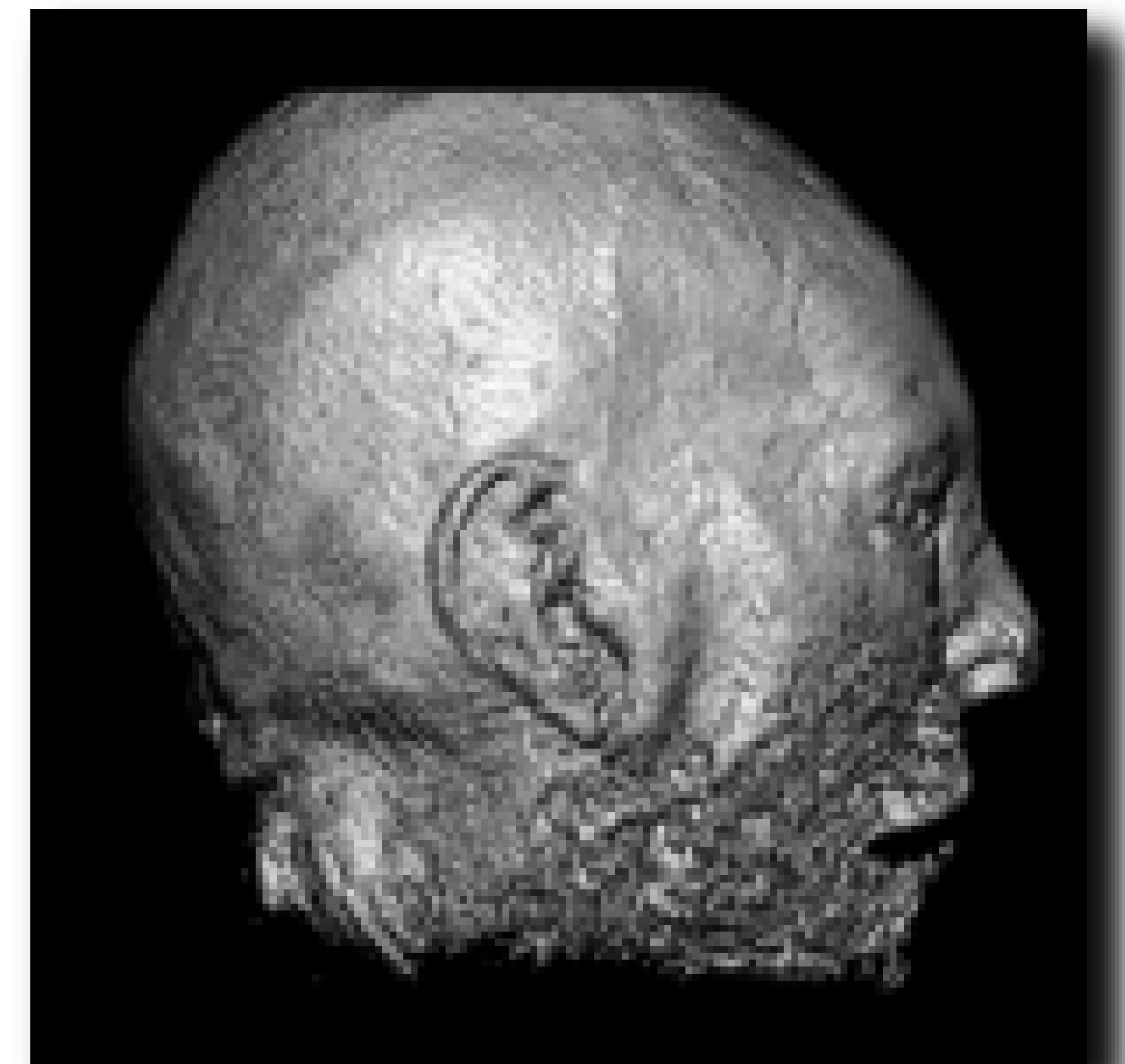
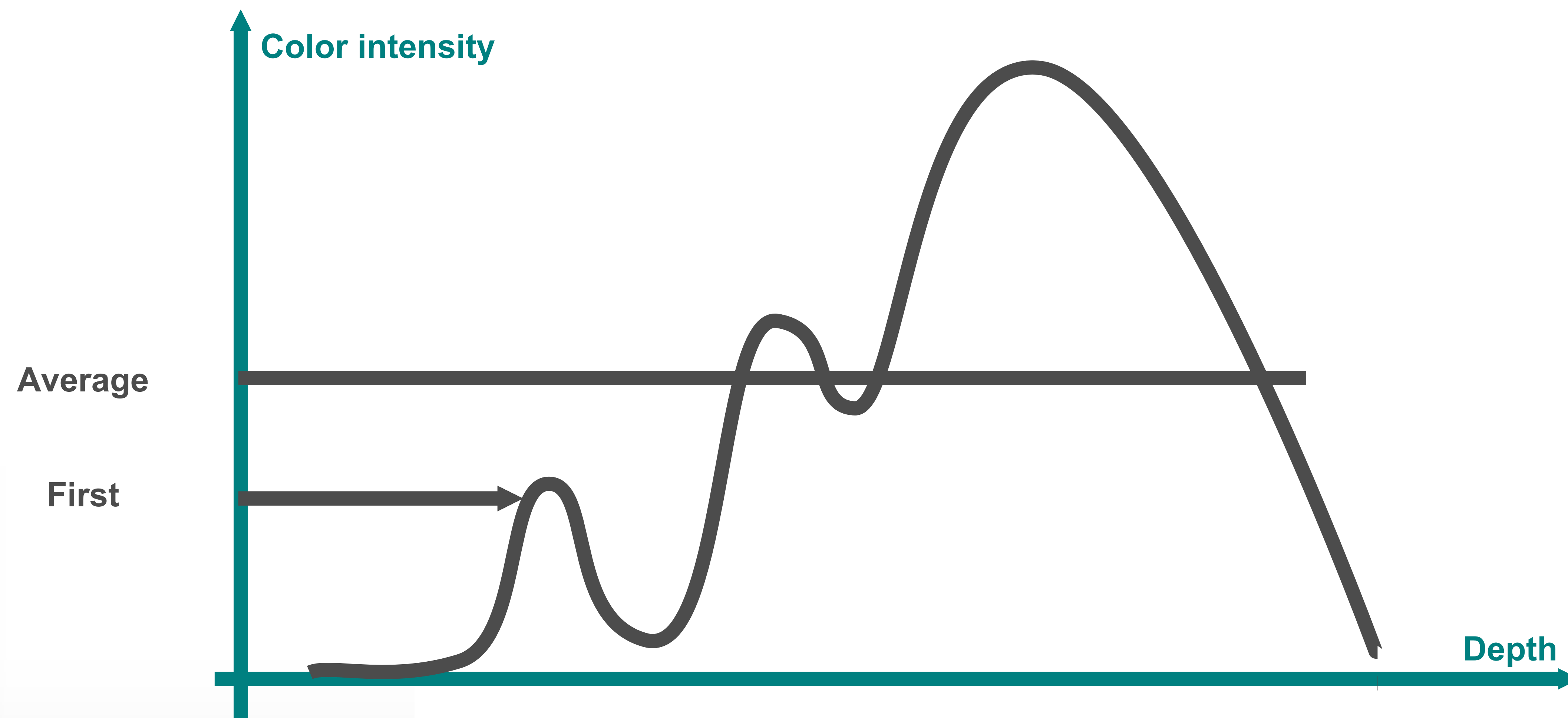
Compositing schemes

- Color intensity along the ray



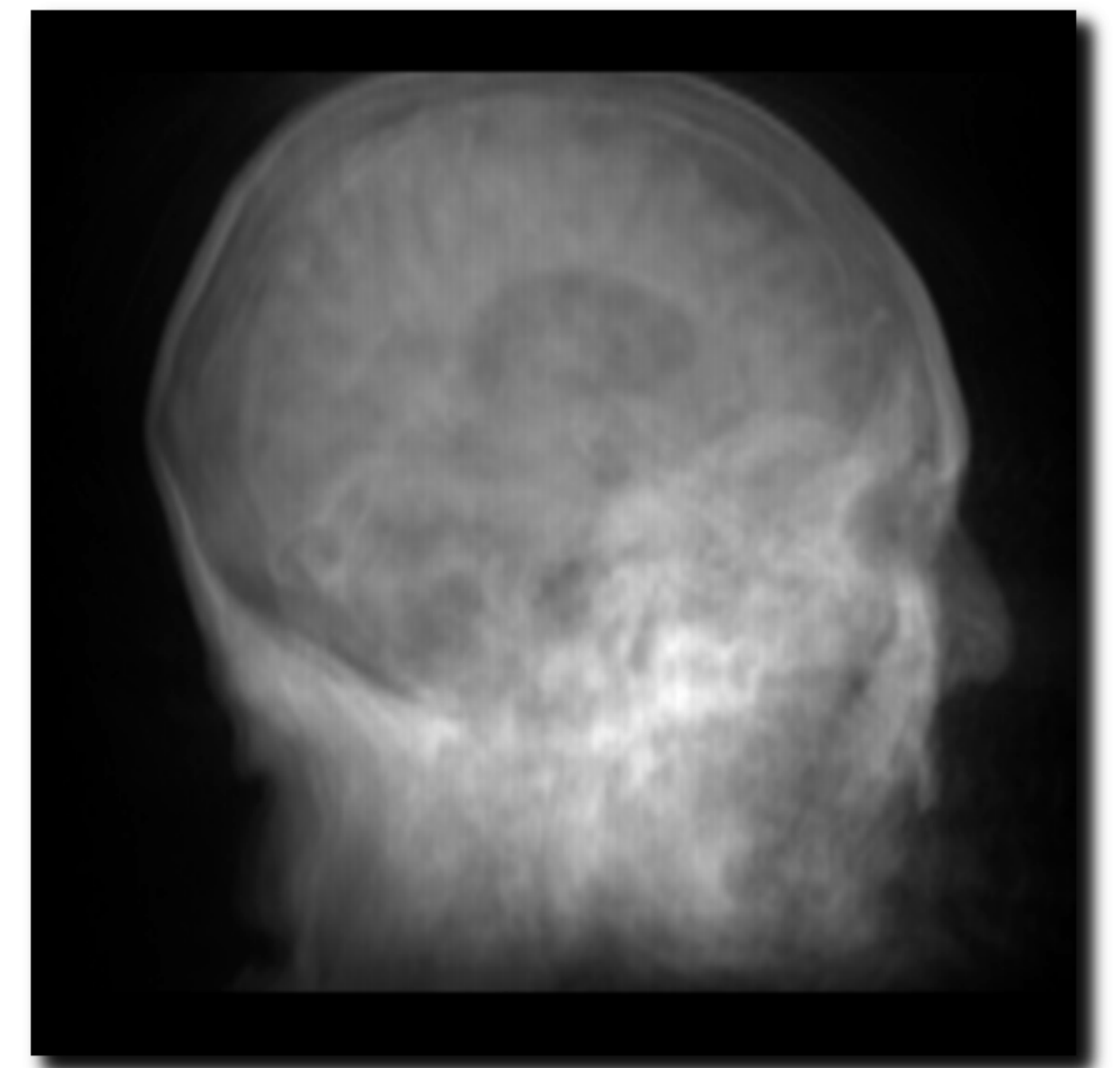
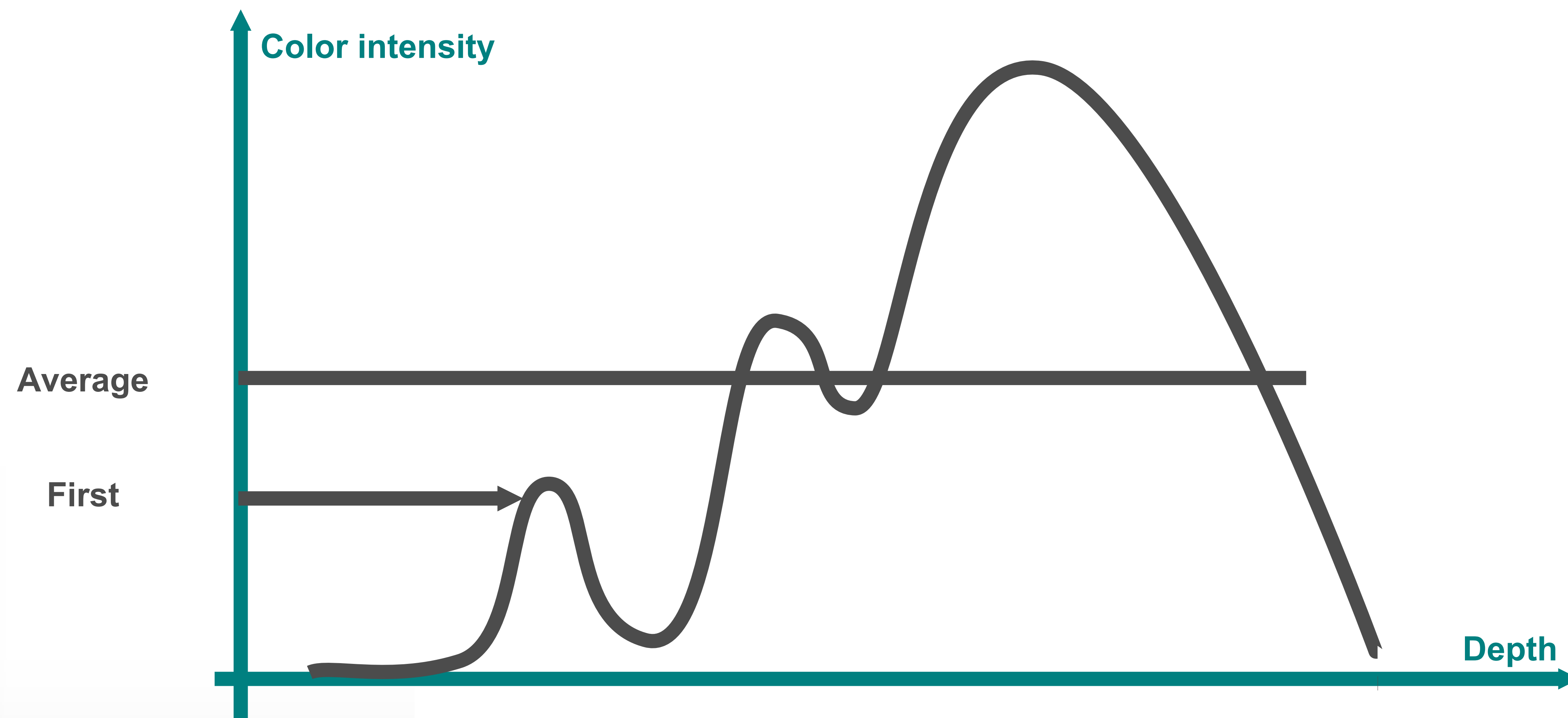
Compositing schemes

- Color intensity along the ray



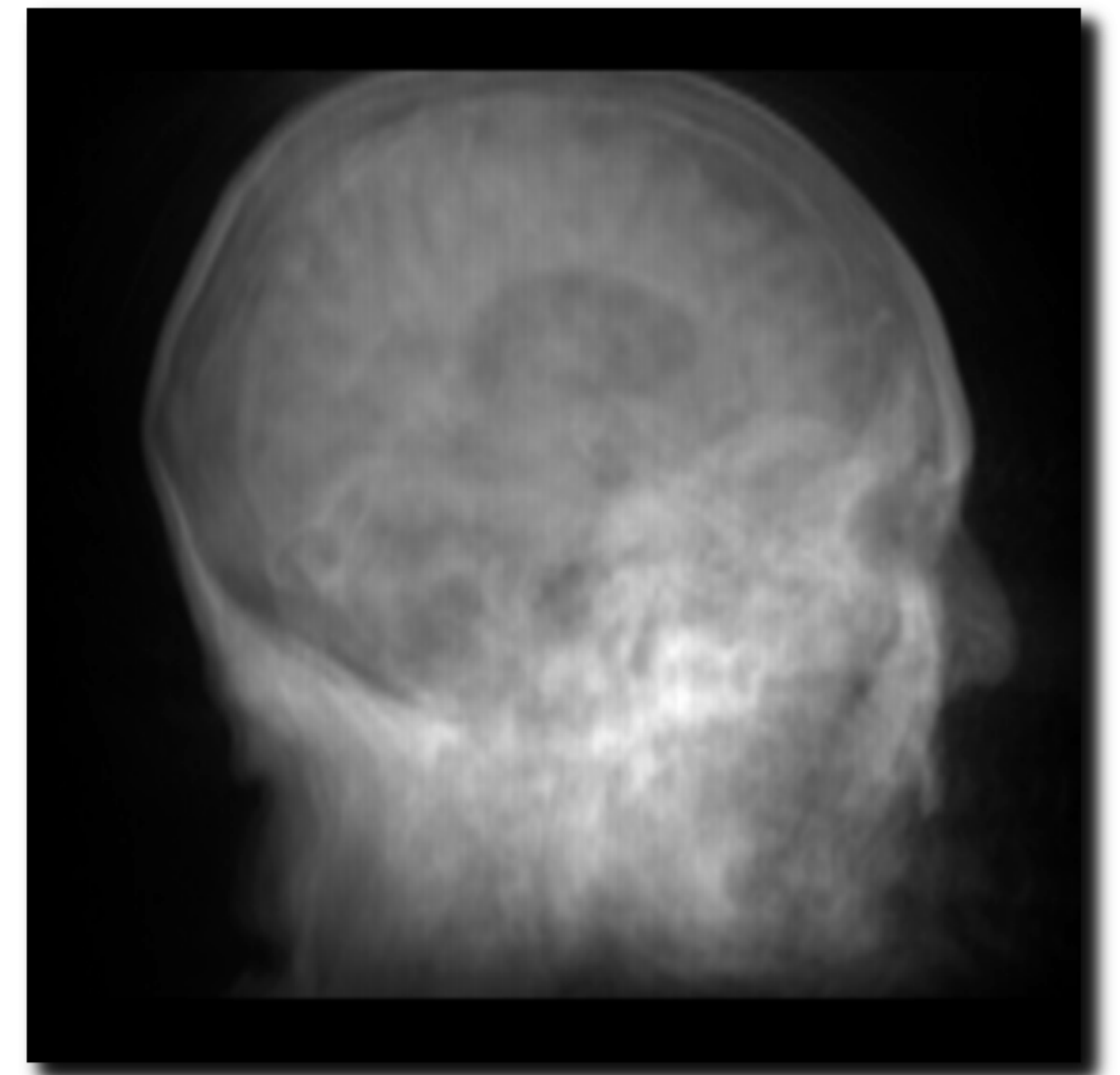
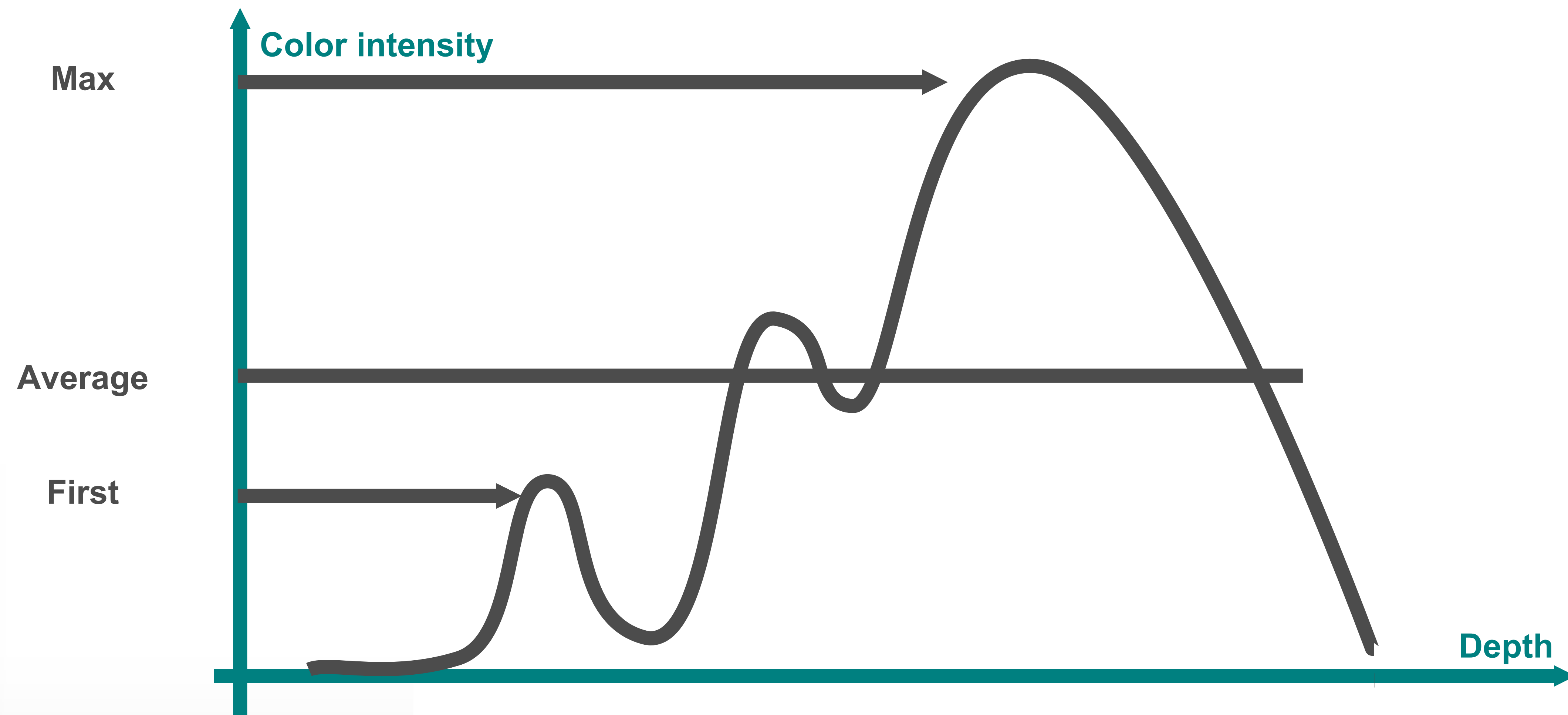
Compositing schemes

- Color intensity along the ray



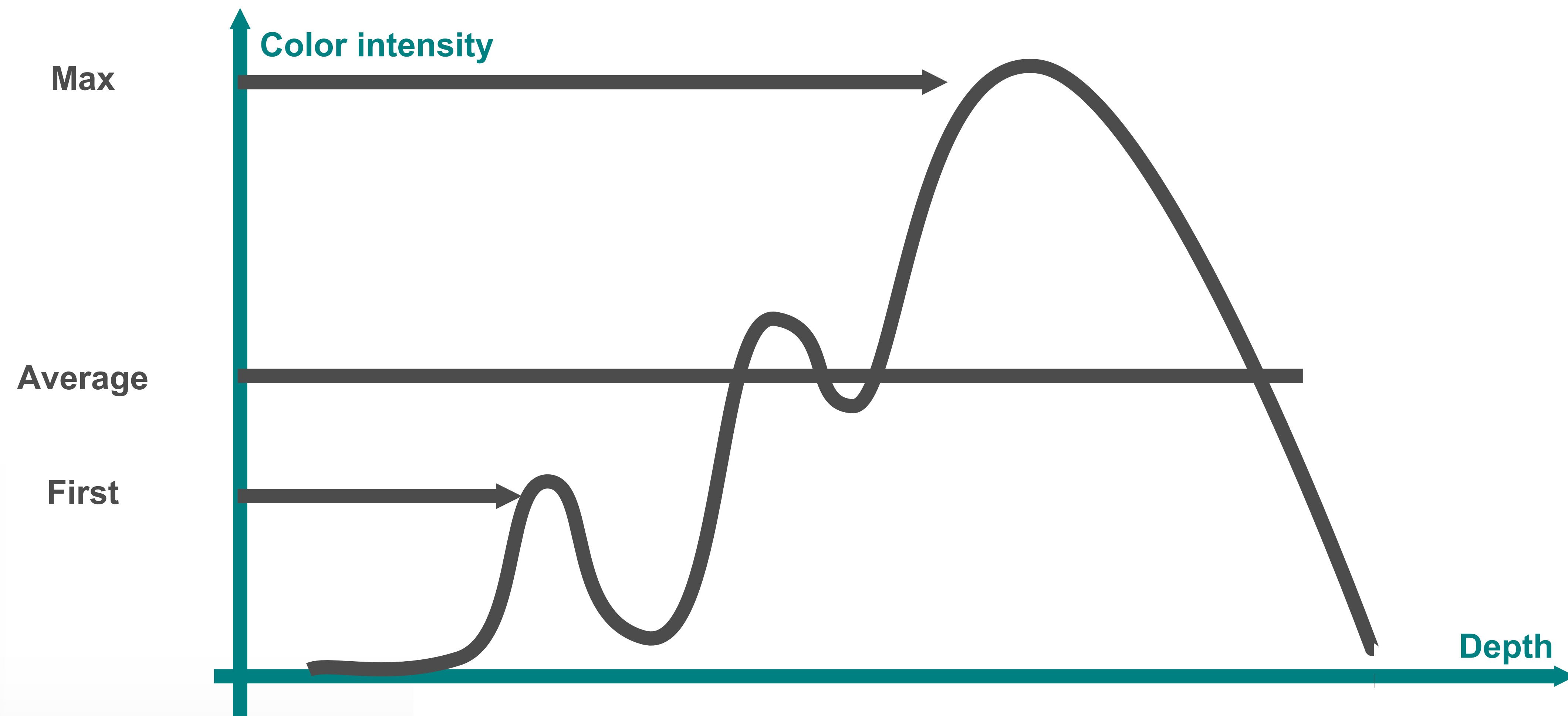
Compositing schemes

- Color intensity along the ray



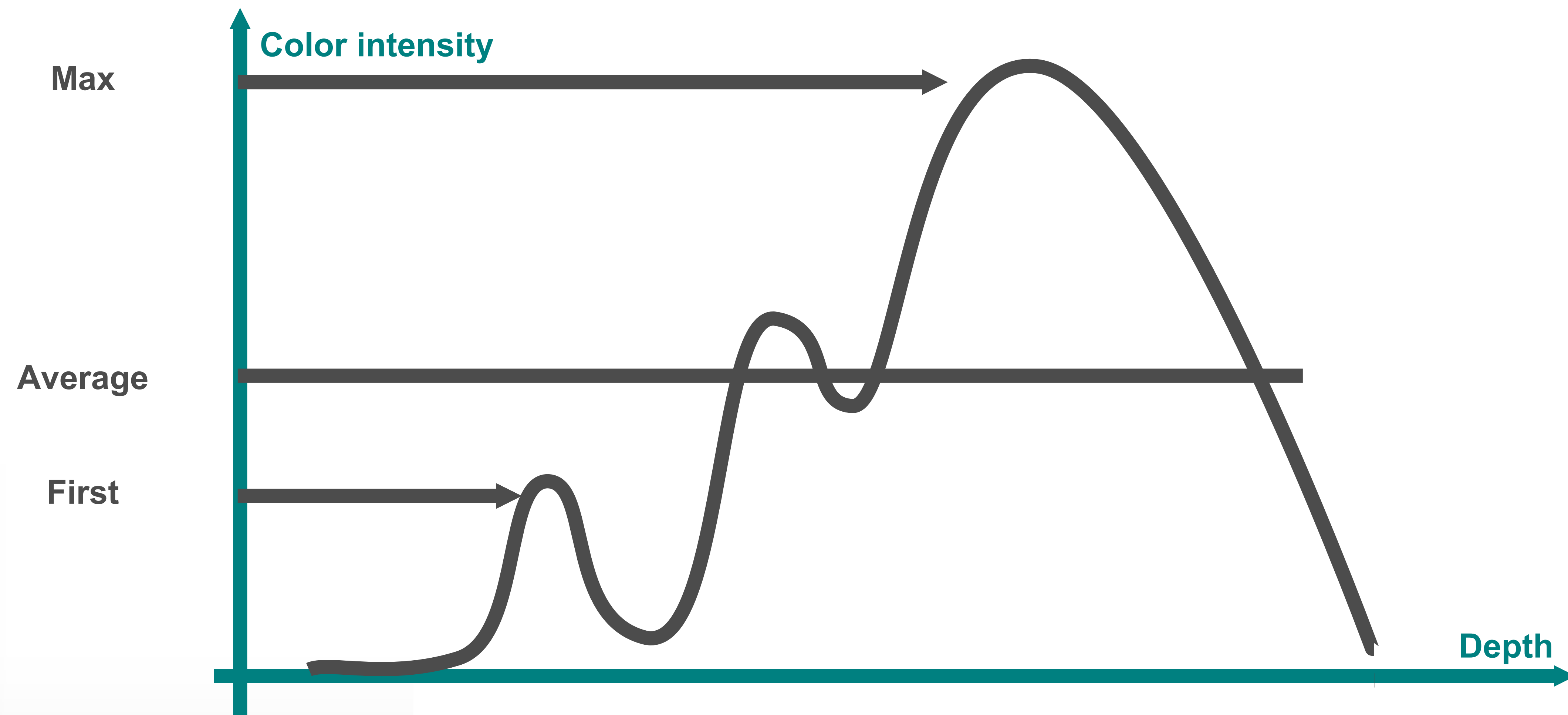
Compositing schemes

- Color intensity along the ray



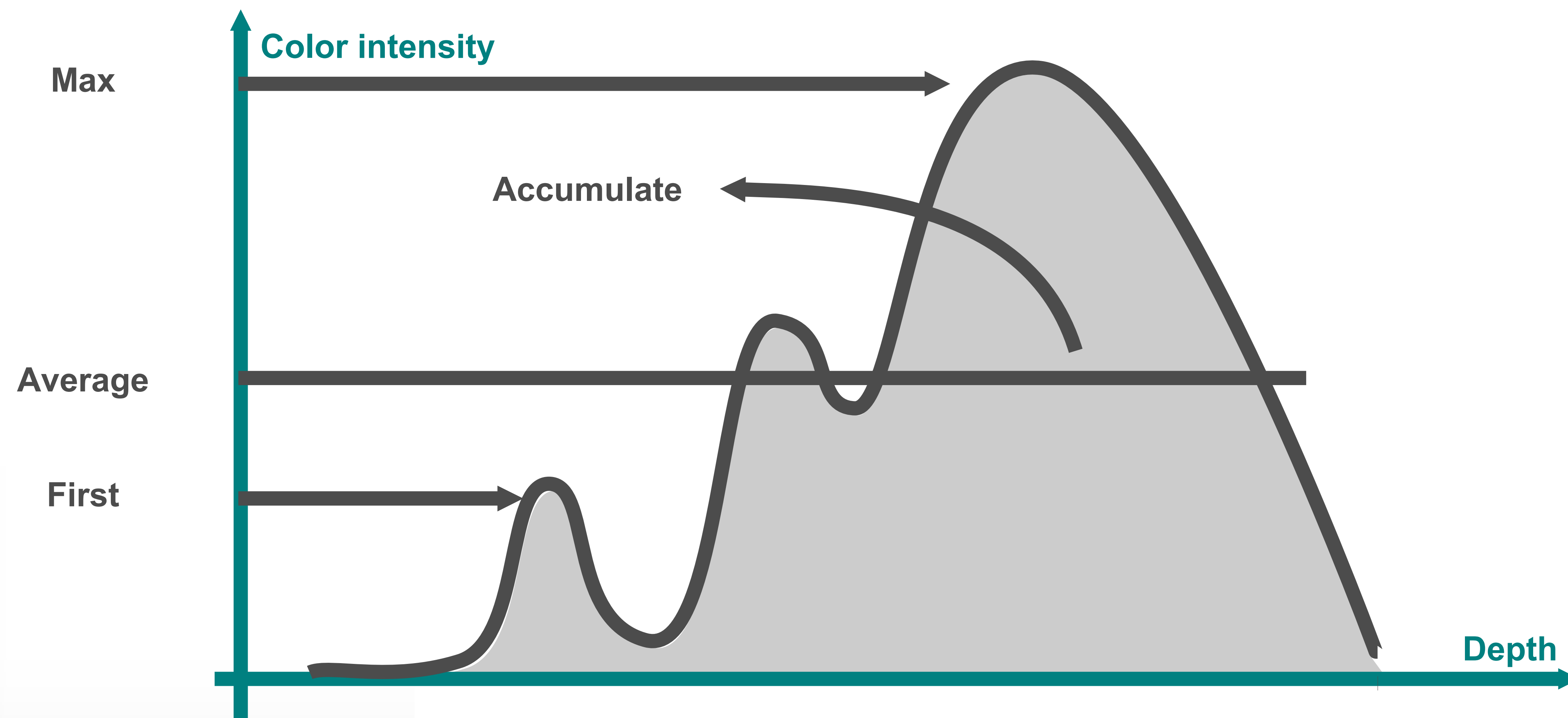
Compositing schemes

- Color intensity along the ray



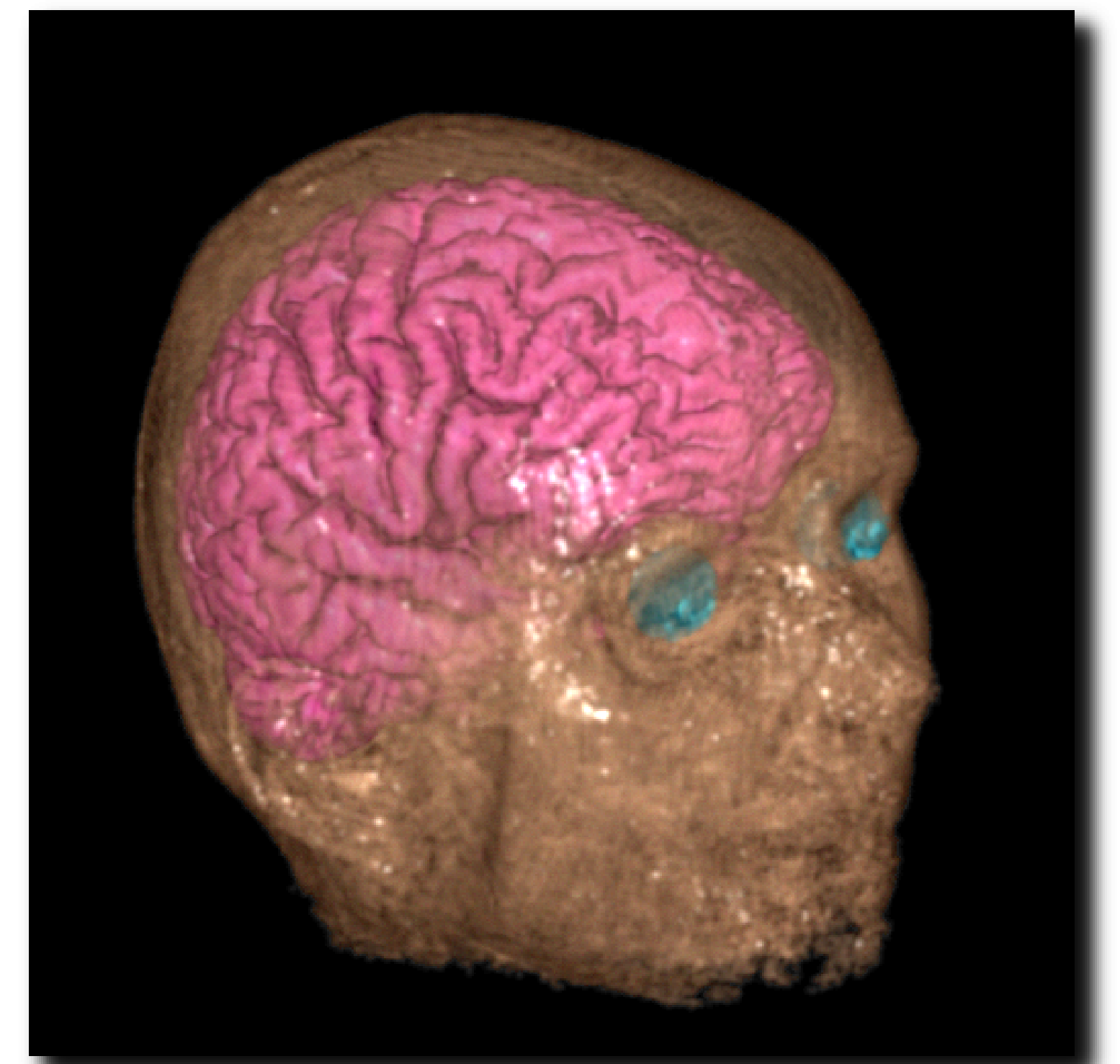
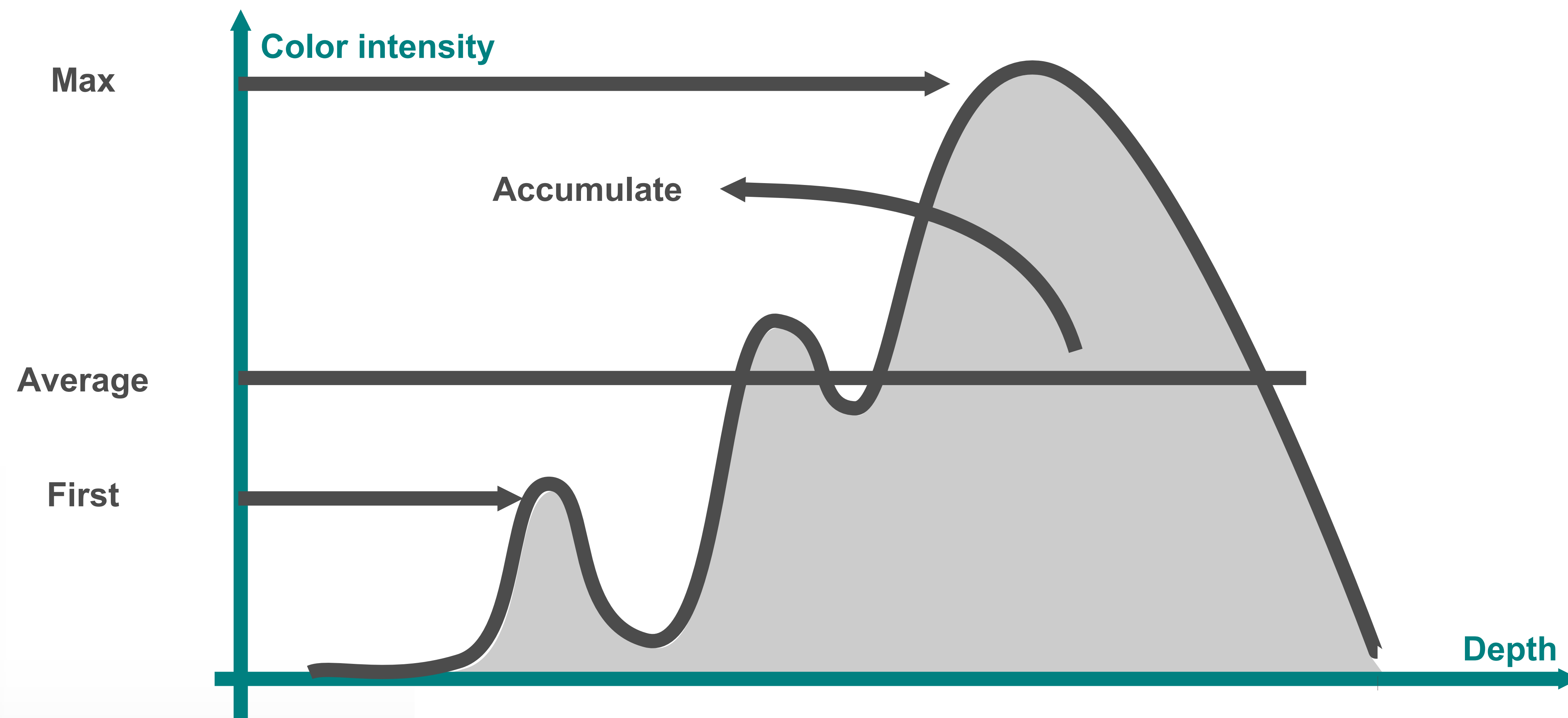
Compositing schemes

- Color intensity along the ray



Compositing schemes

- Color intensity along the ray



Accumulation compositing

- From back to front

Accumulation compositing

- From back to front

Eye



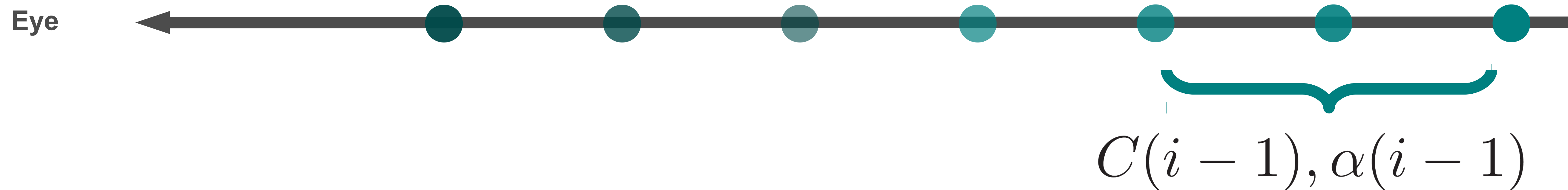
Accumulation compositing

- From back to front



Accumulation compositing

- From back to front



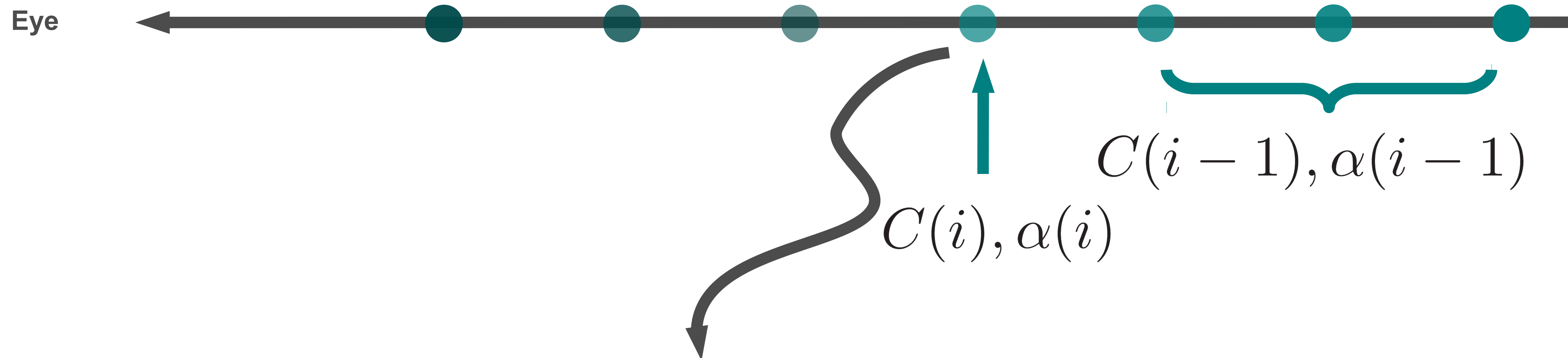
Accumulation compositing

- From back to front



Accumulation compositing

- From back to front



$$C'(i) = \alpha(i) \times C(i) + (1 - \alpha(i)) \times \alpha(i-1) \times C(i-1)$$
$$\alpha'(i) = \alpha(i) + (1 - \alpha(i)) \times \alpha(i-1)$$

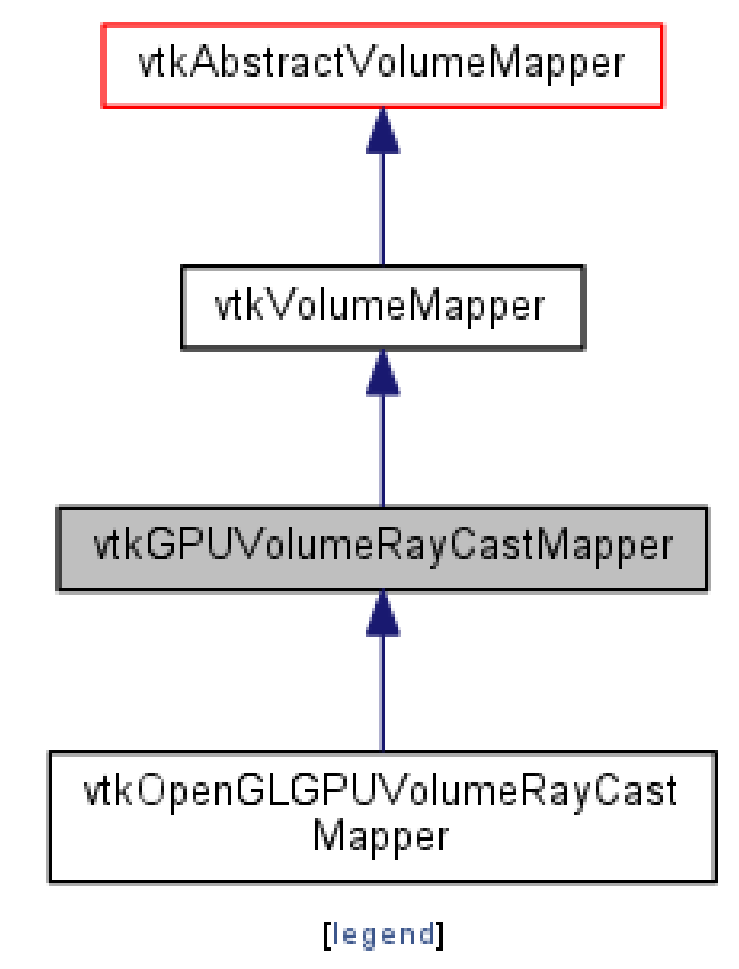
vtkGPUVolumeRayCastMapper Class Reference abstract

[Public Types](#) | [Public Member Functions](#) | [Static Public Member Functions](#) | [Protected Member Functions](#) | [Protected Attributes](#) | [List of all members](#)

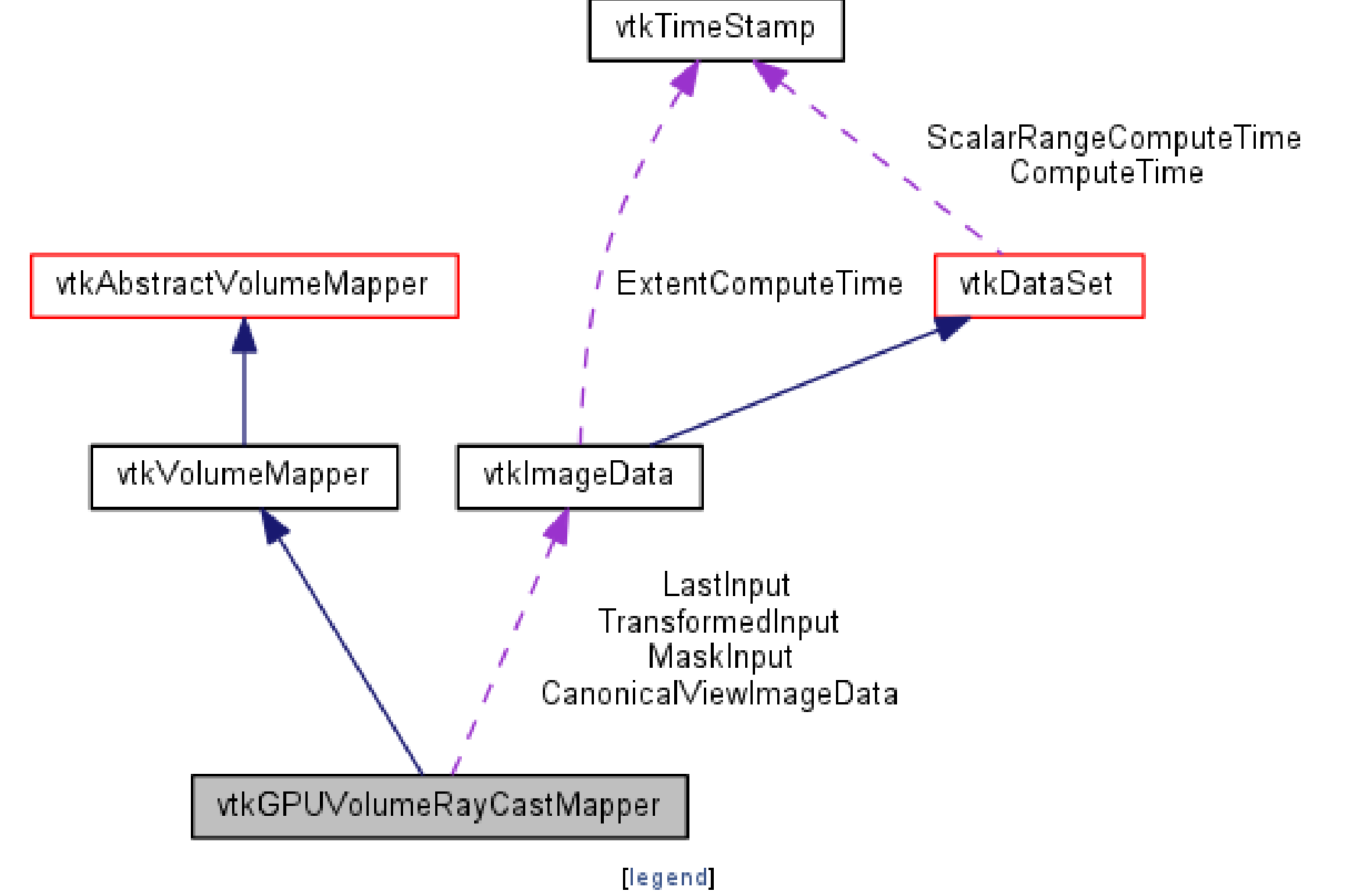
Ray casting performed on the GPU. [More...](#)

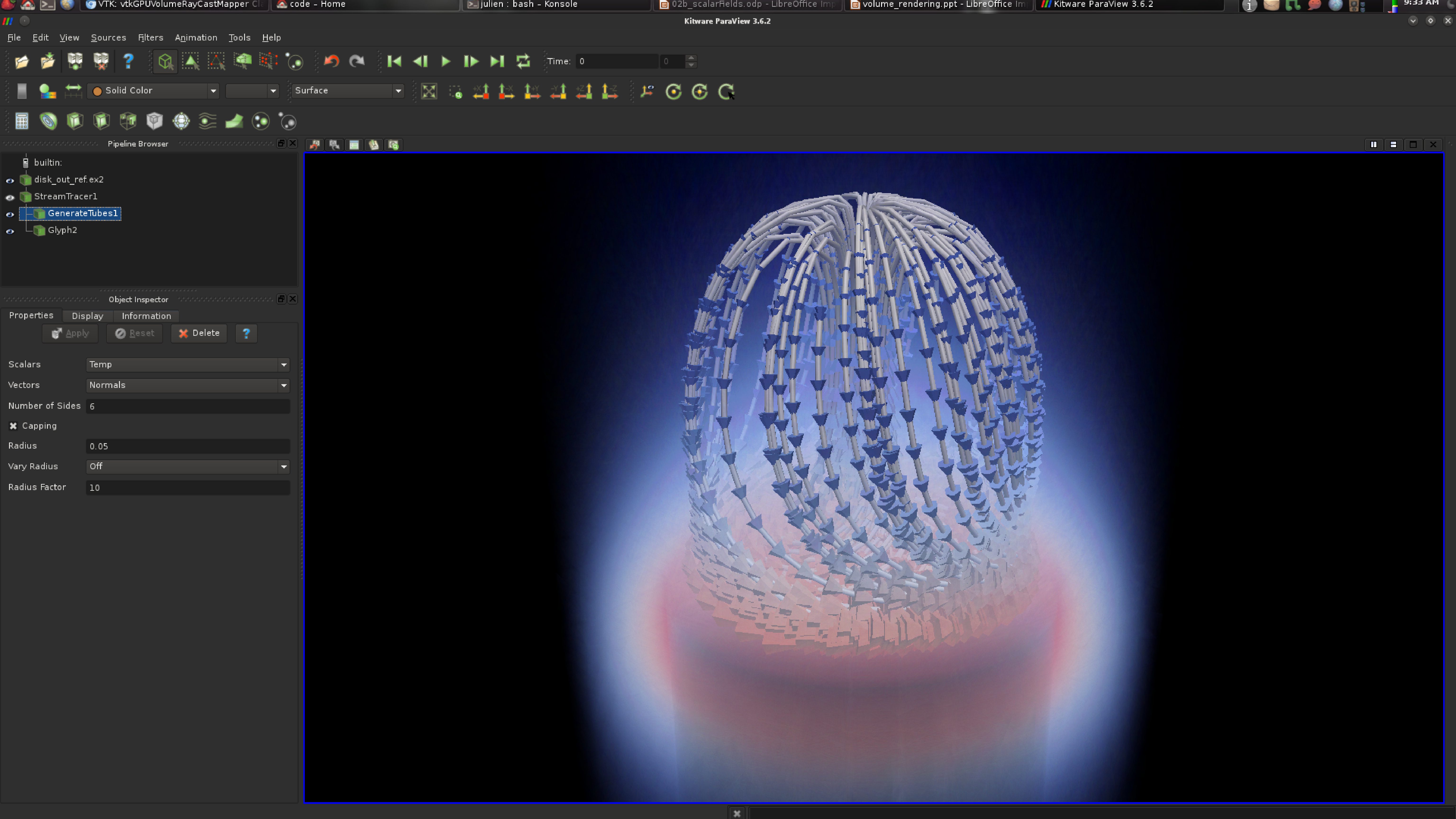
```
#include <vtkGPUVolumeRayCastMapper.h>
```

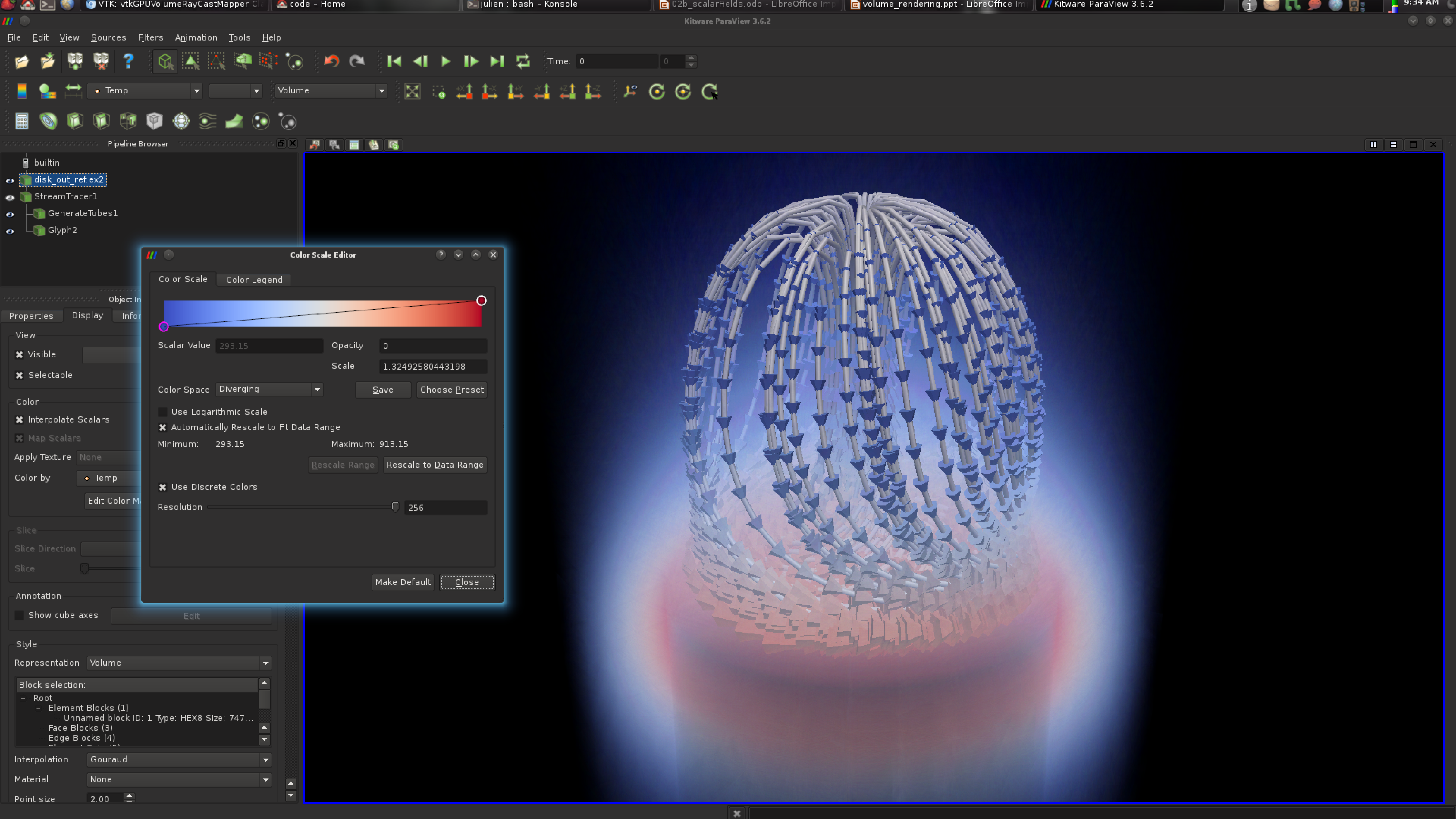
Inheritance diagram for vtkGPUVolumeRayCastMapper:

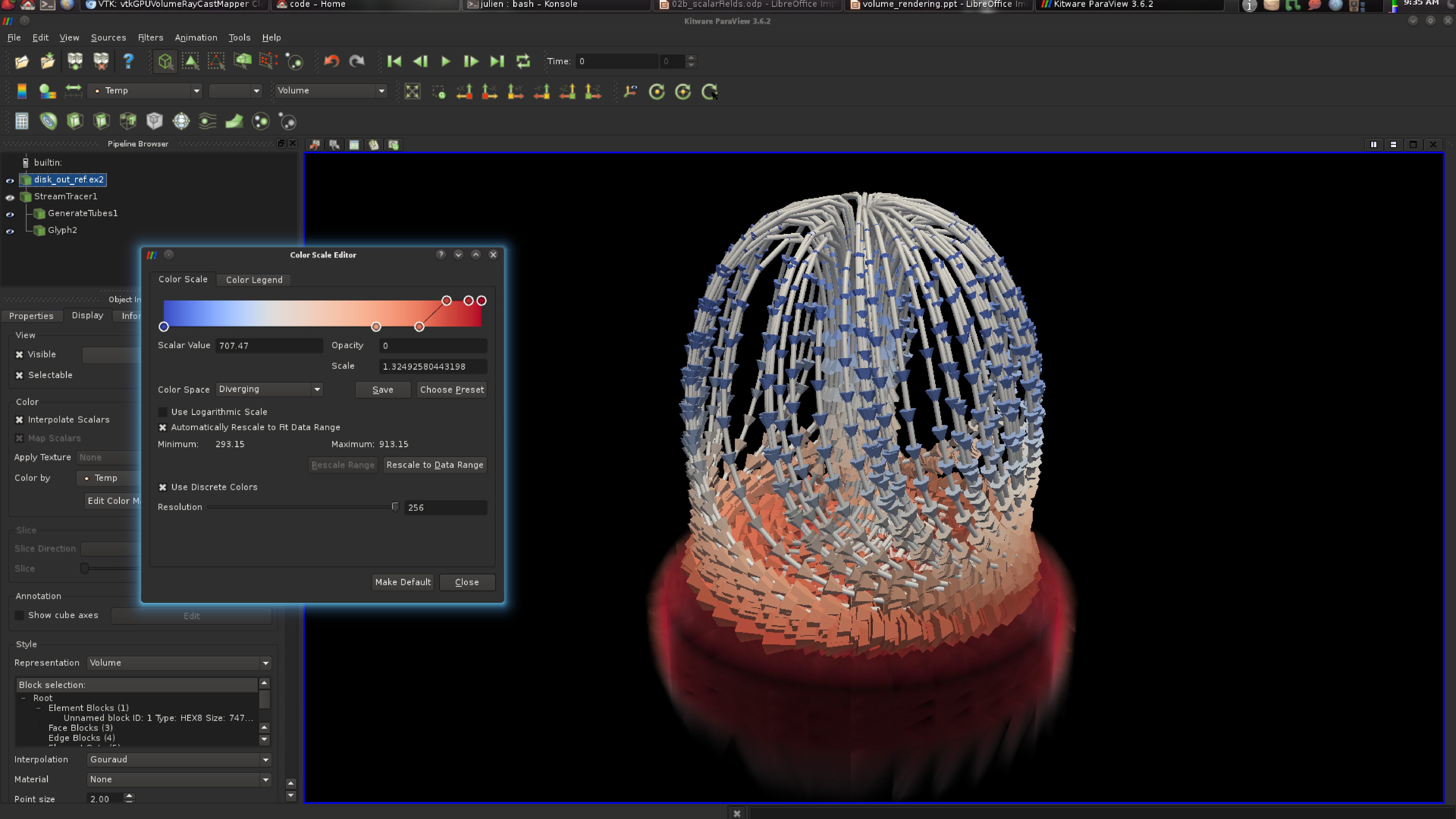


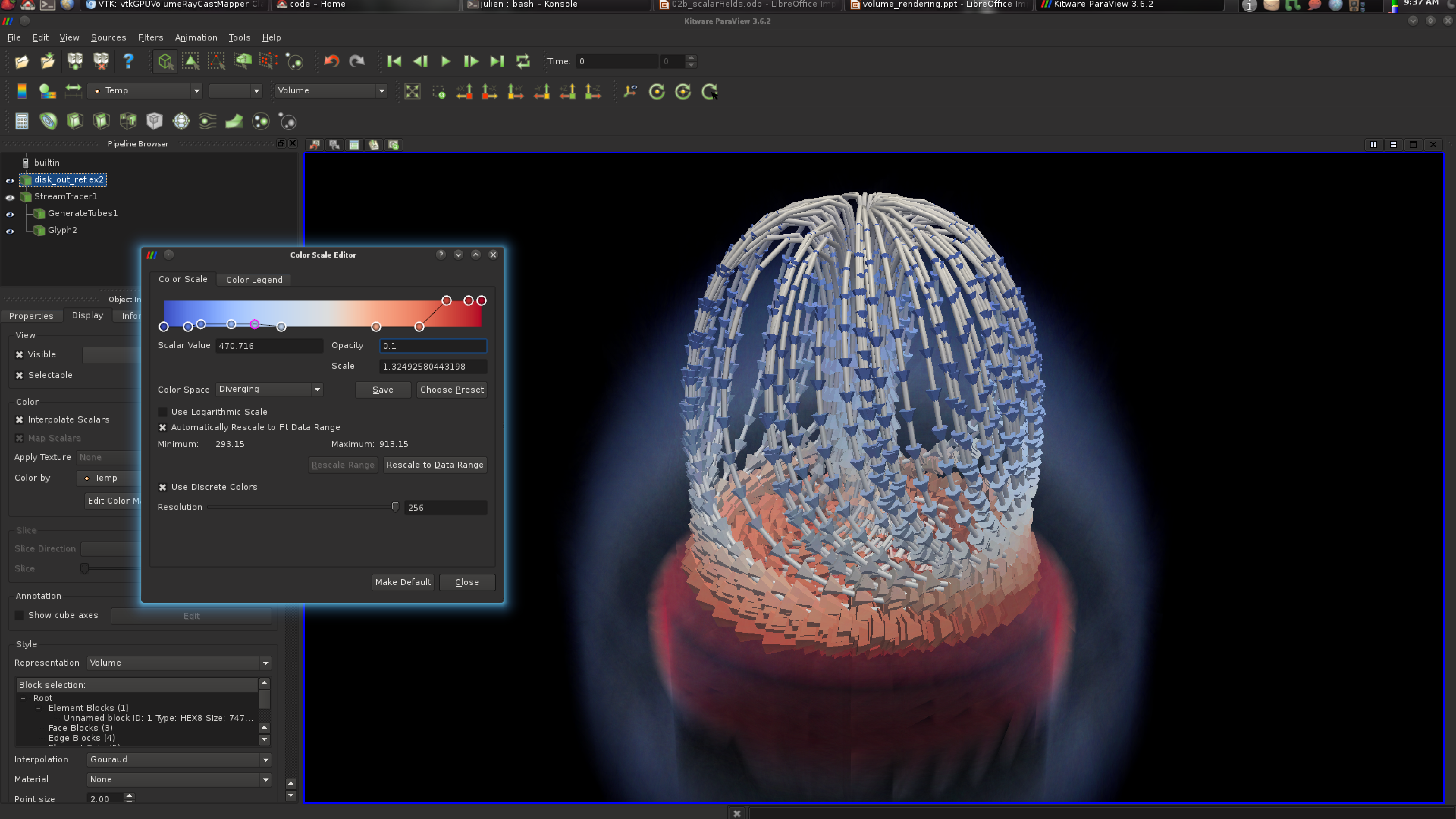
Collaboration diagram for vtkGPUVolumeRayCastMapper:

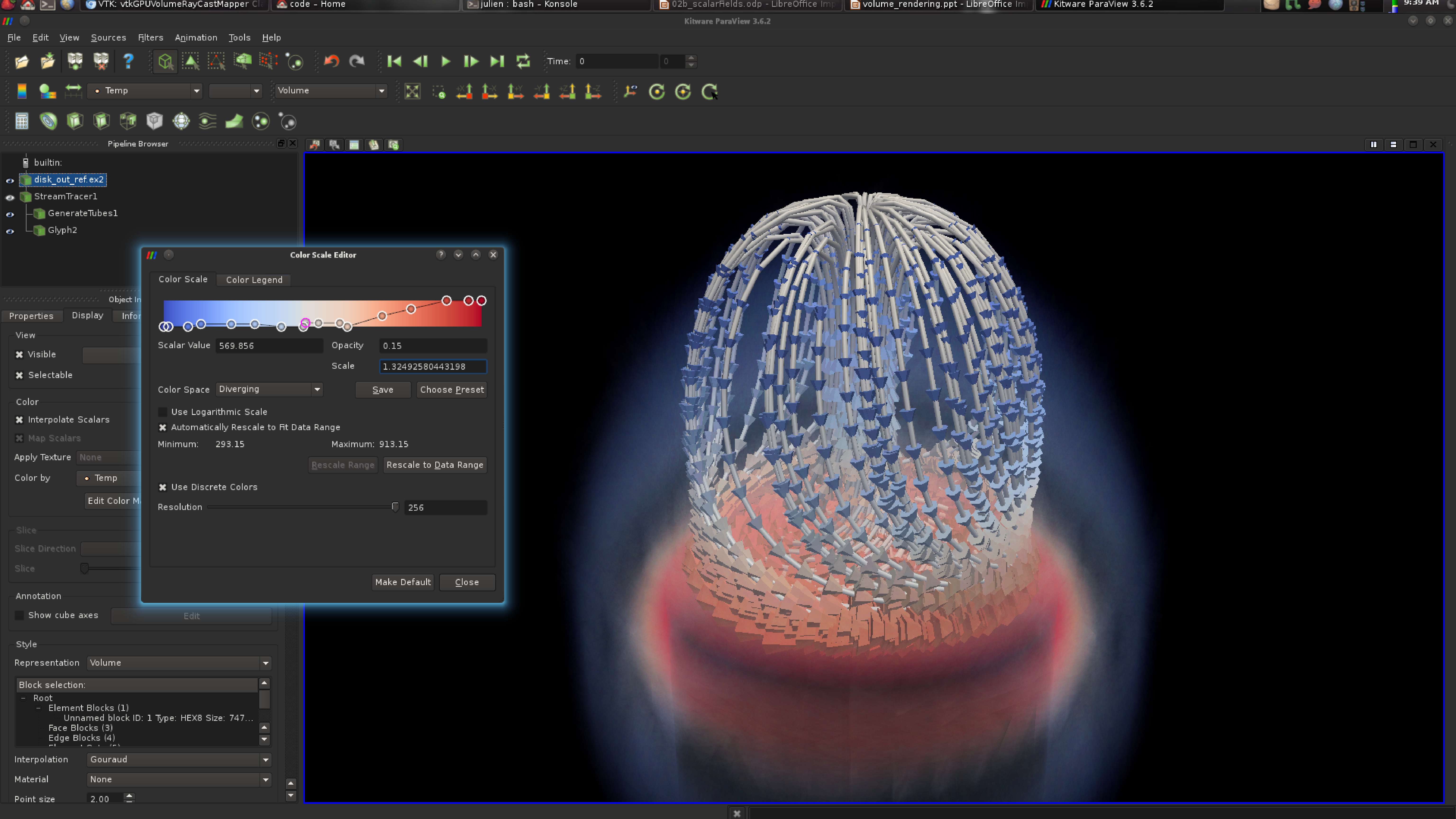












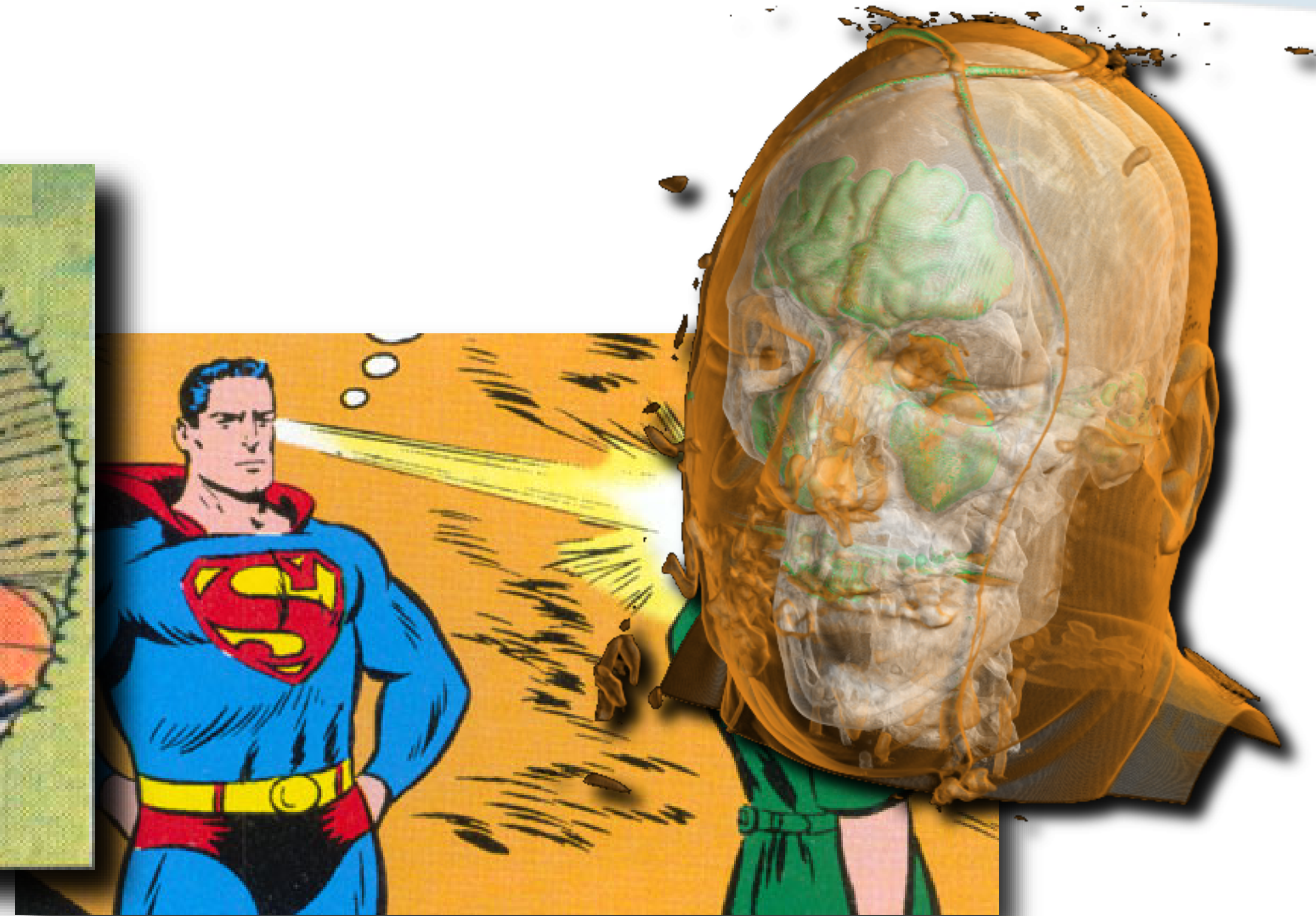
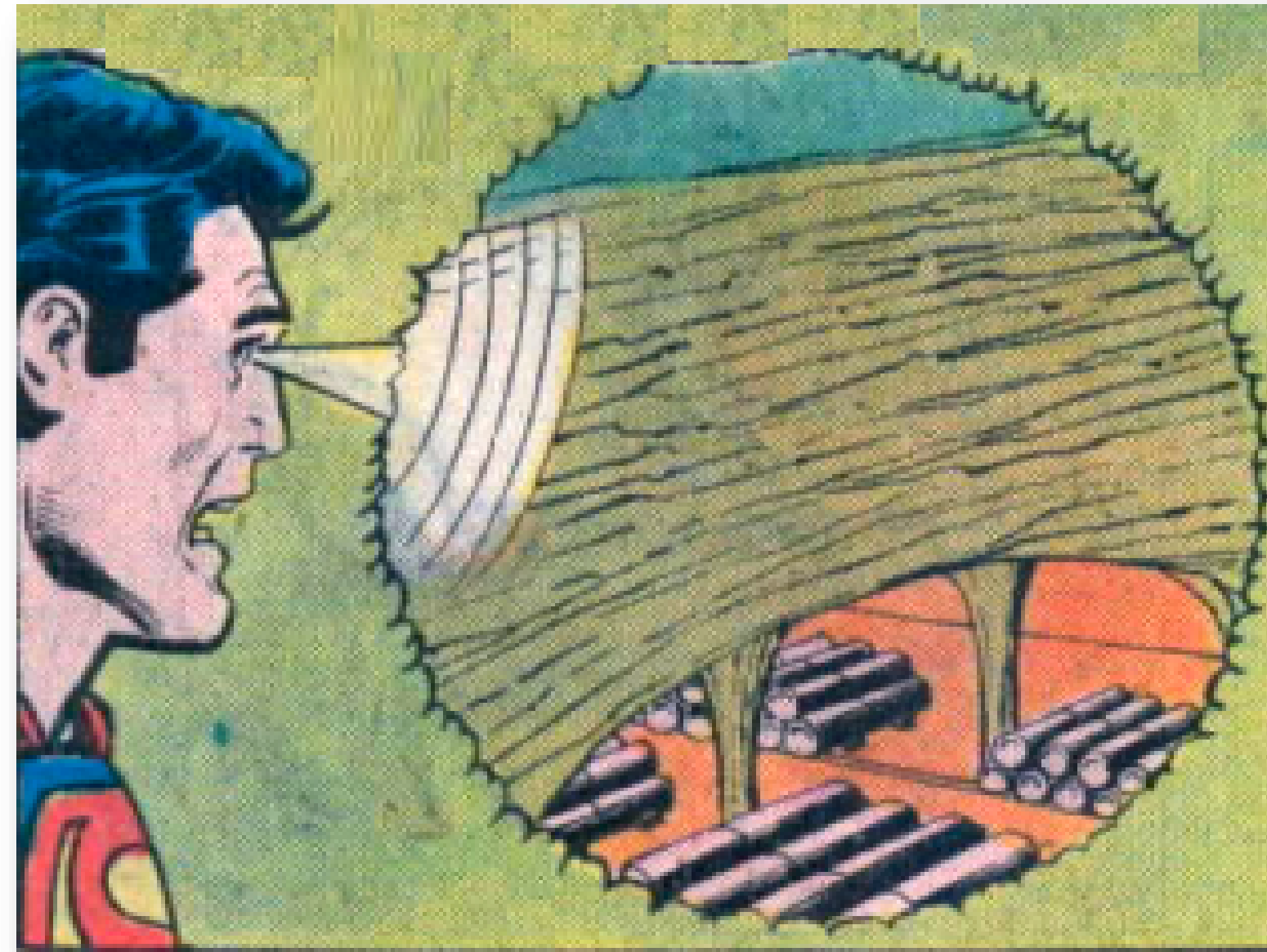
Pros and Cons

- Simple algorithm
- Inherently parallel
- High quality renderings

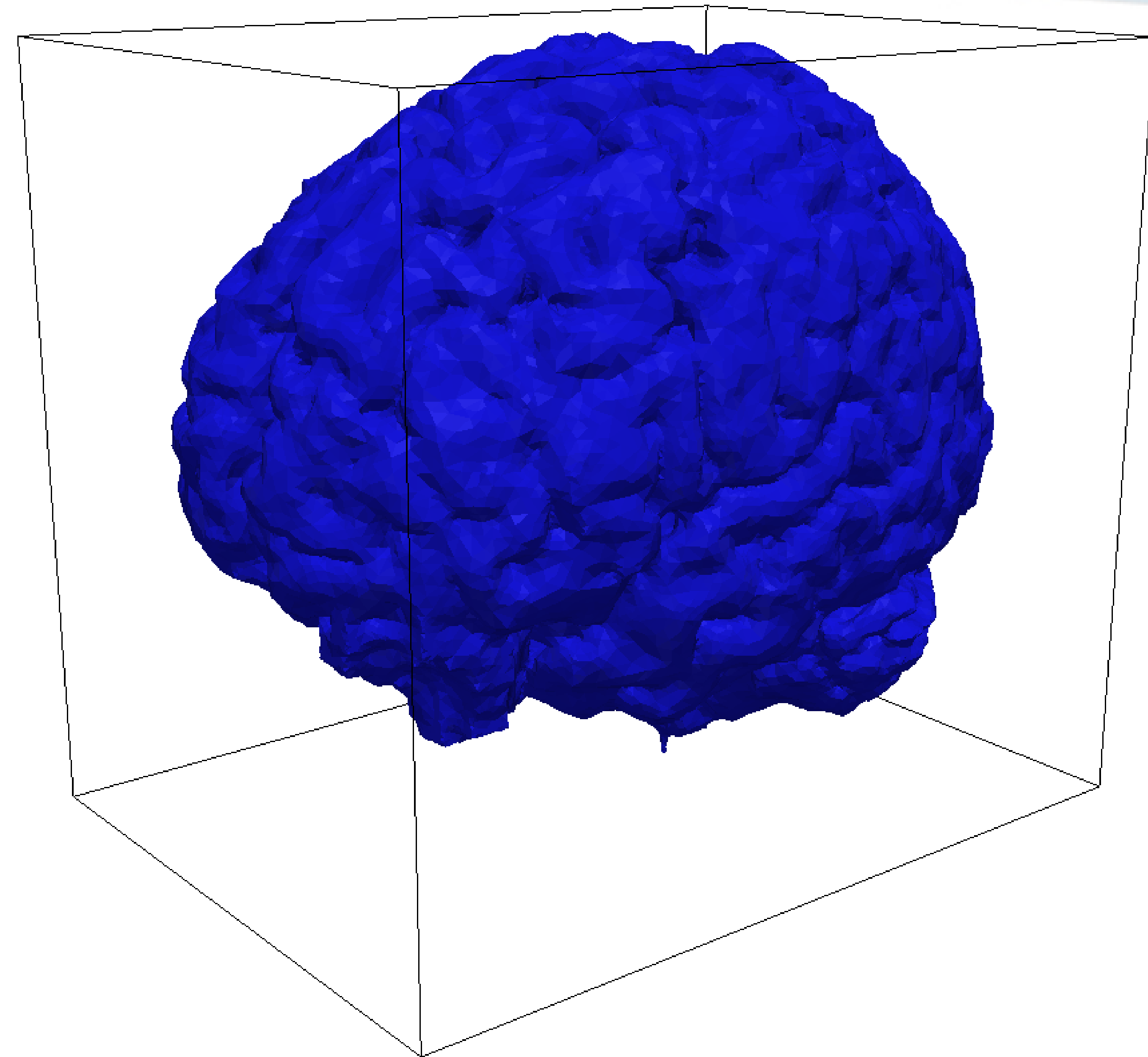


Pros and Cons

- Simple algorithm
- Inherently parallel
- High quality renderings
- SLOW!
 - Lots of rays
 - Lots of samples
- Transfer function design may not be intuitive

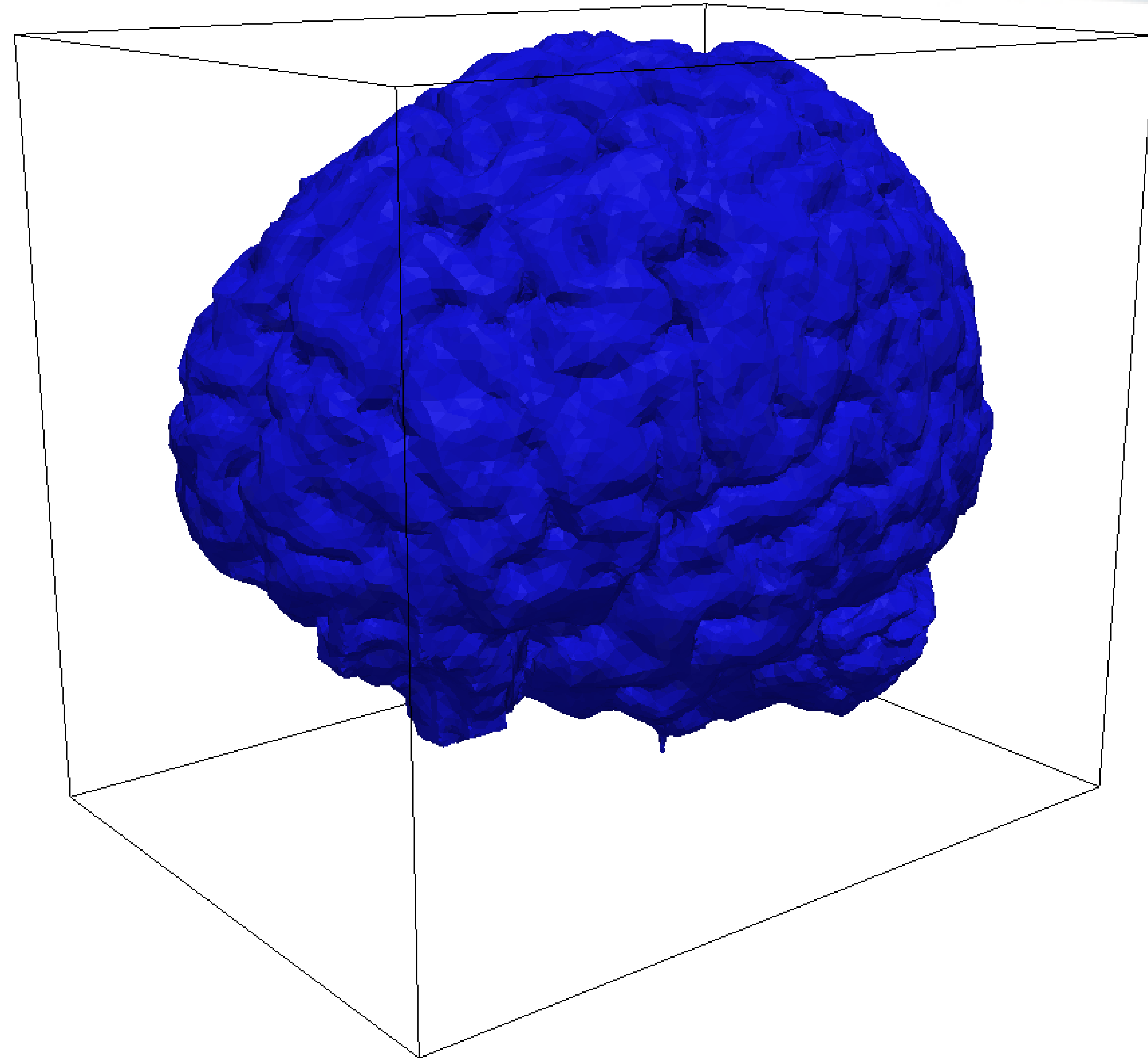


Level set extraction



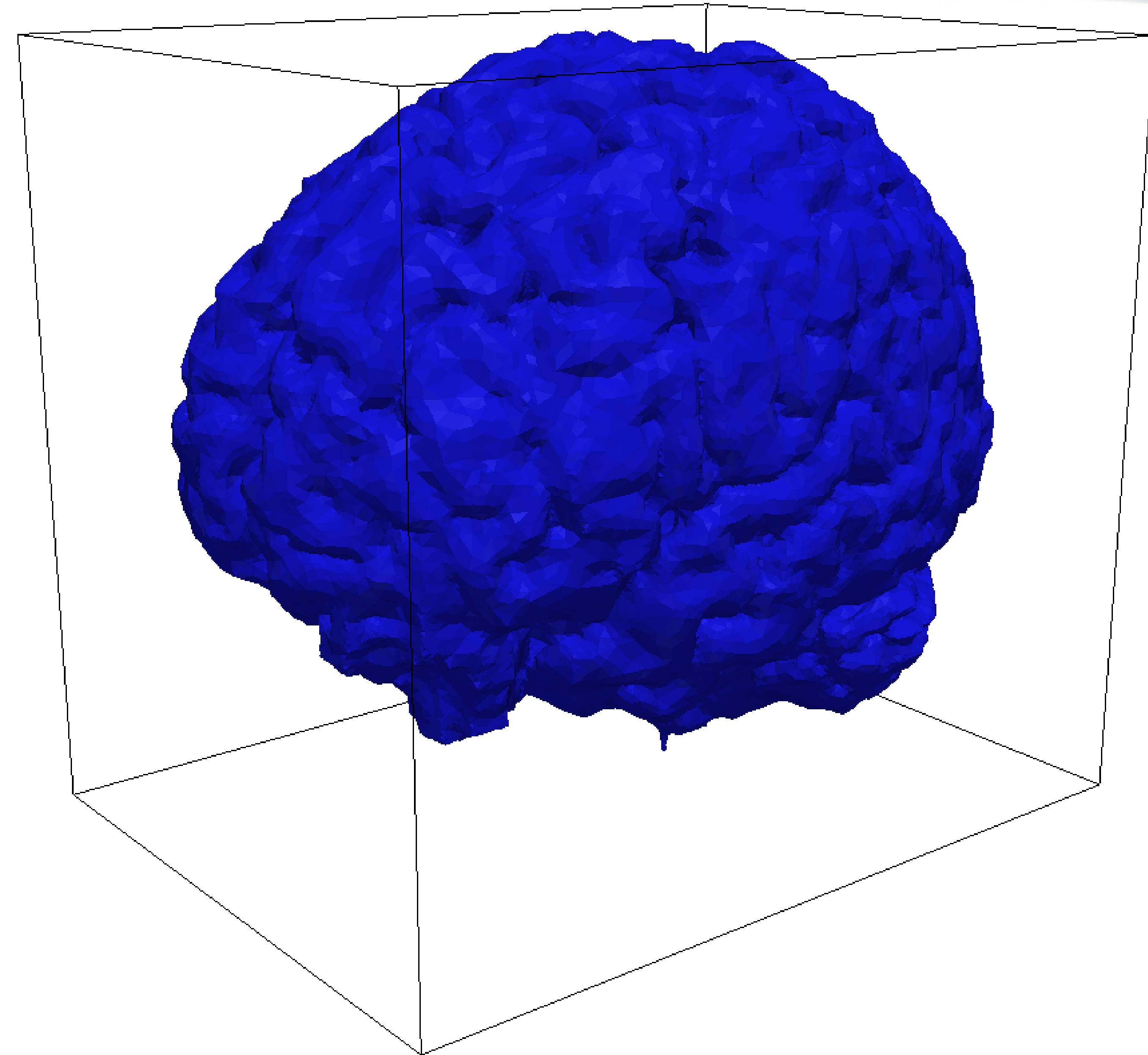
Level set extraction

- Exact geometry visualization



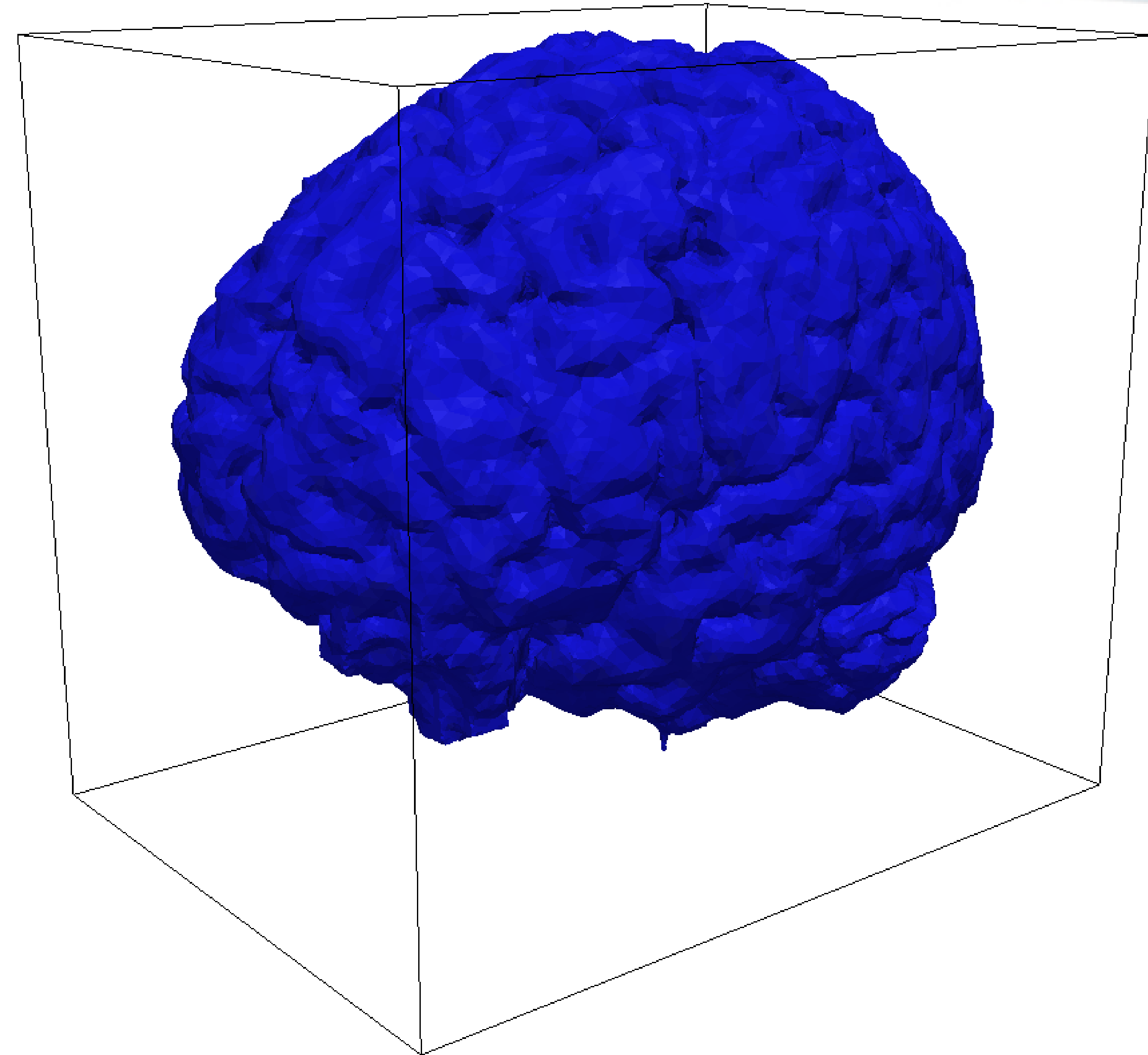
Level set extraction

- Exact geometry visualization
- Regions of interests



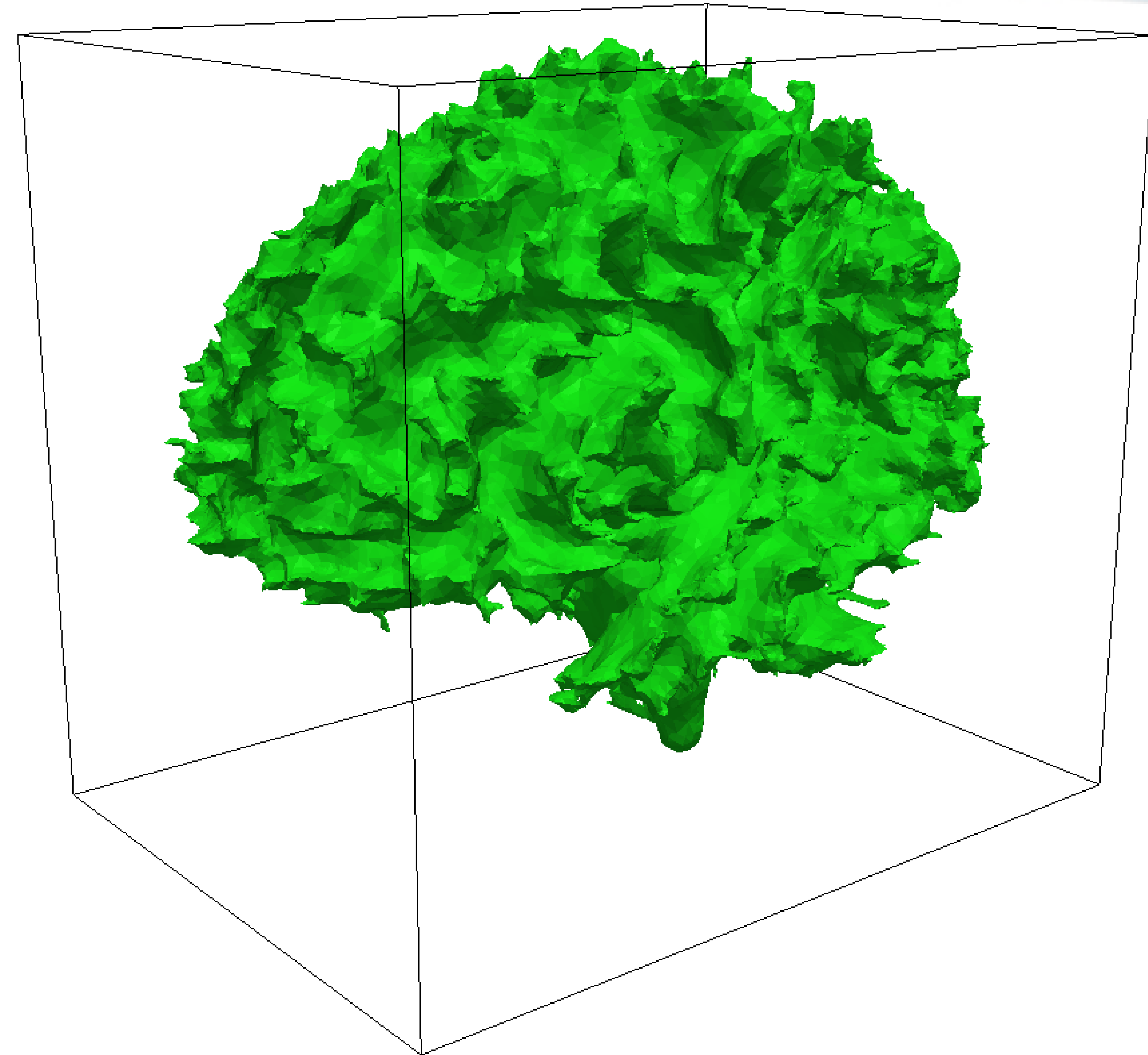
Level set extraction

- Exact geometry visualization
- Regions of interests
 - Identify
 - Study
 - Visualize



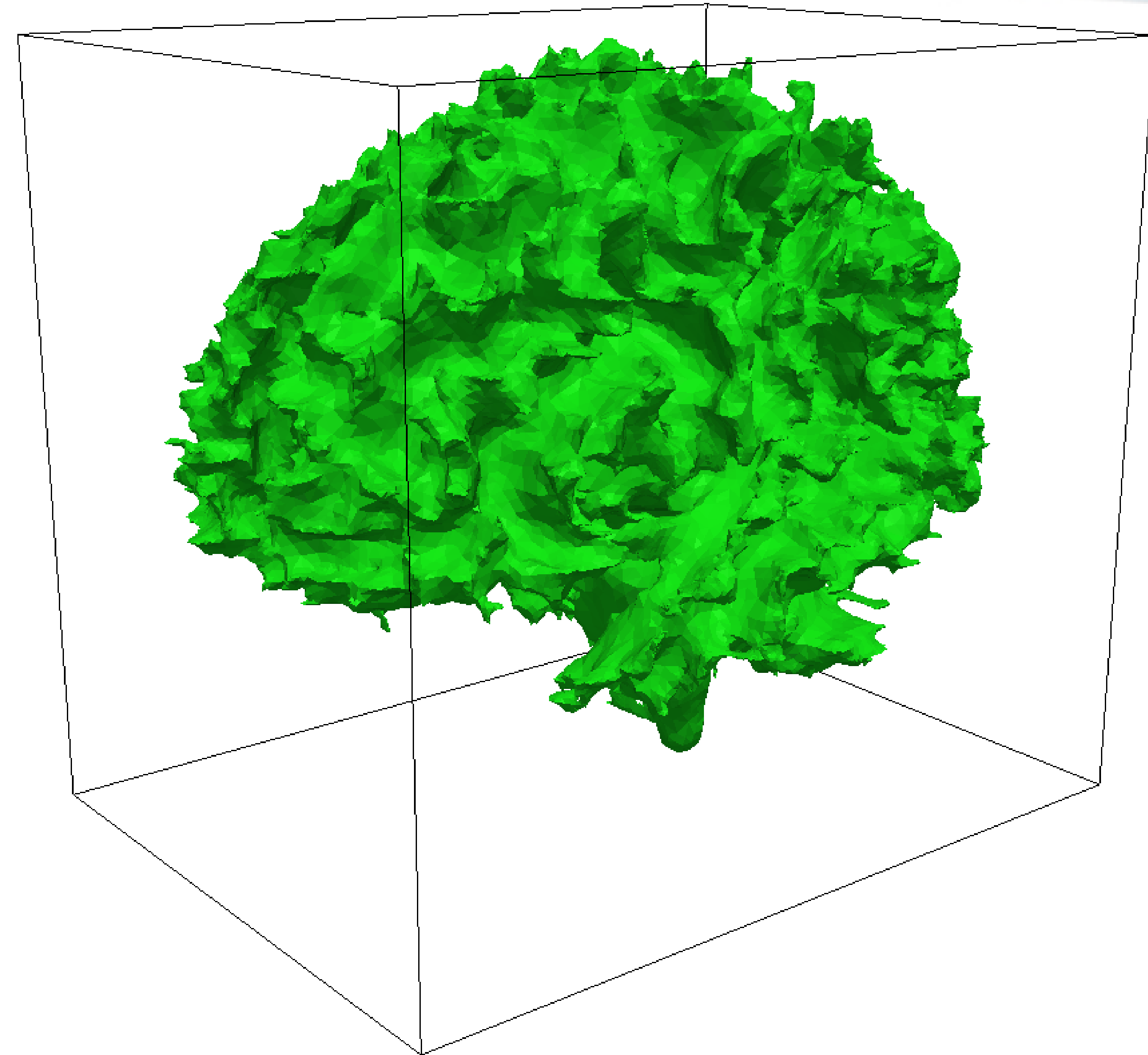
Level set extraction

- Exact geometry visualization
- Regions of interests
 - Identify
 - Study
 - Visualize
 - Different layers



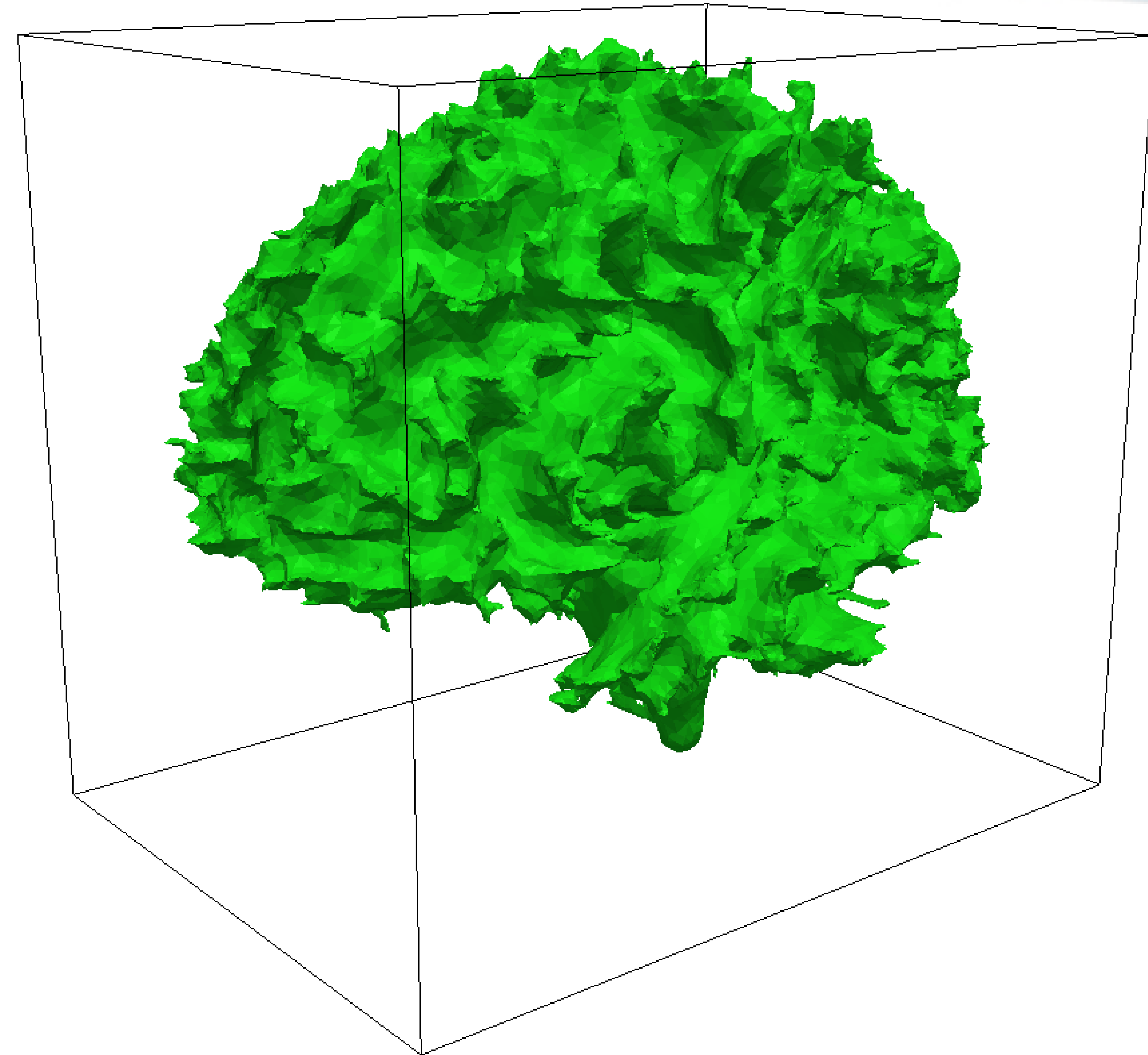
Level set extraction

- Exact geometry visualization
- Regions of interests
 - Identify
 - Study
 - Visualize
 - Different layers
 - Different level sets



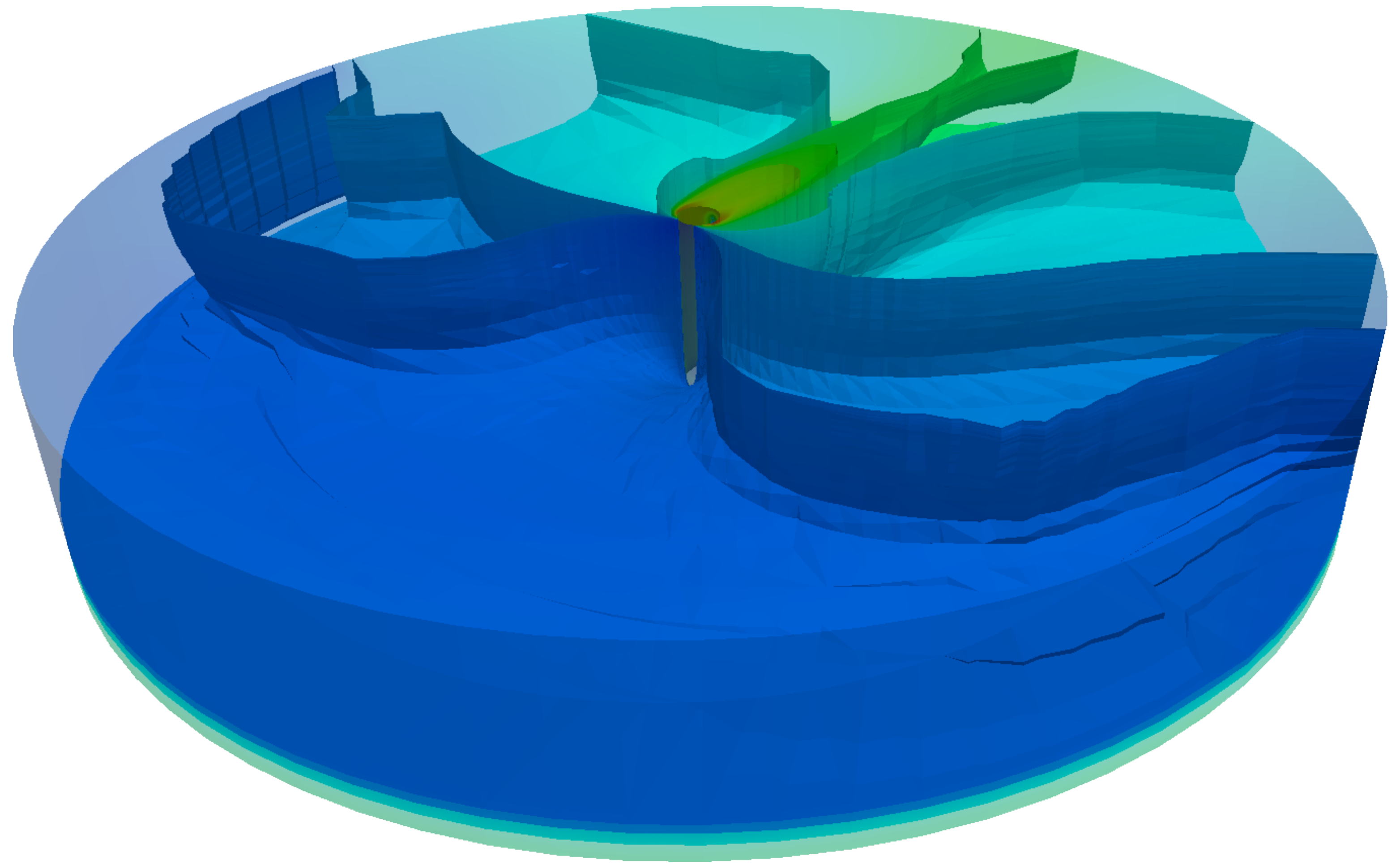
Level set extraction

- Exact geometry visualization
- Regions of interests
 - Identify
 - Study
 - Visualize
 - Different layers
 - Different level sets
- Towards data analysis

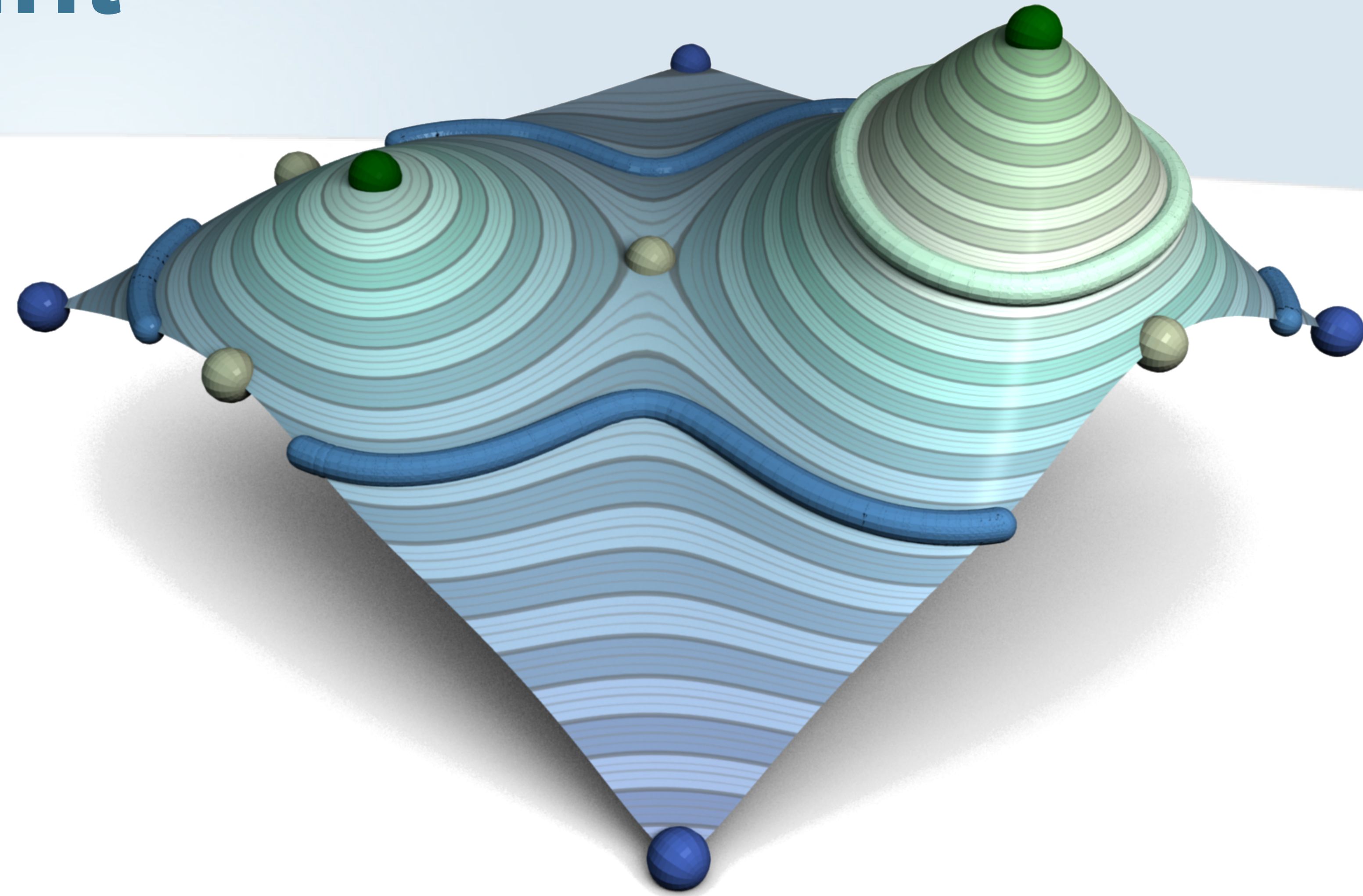


Level set summary

- Level set extraction
 - PL-manifold domains
 - Regular grids
- Acceleration structures
- Topological cleaning

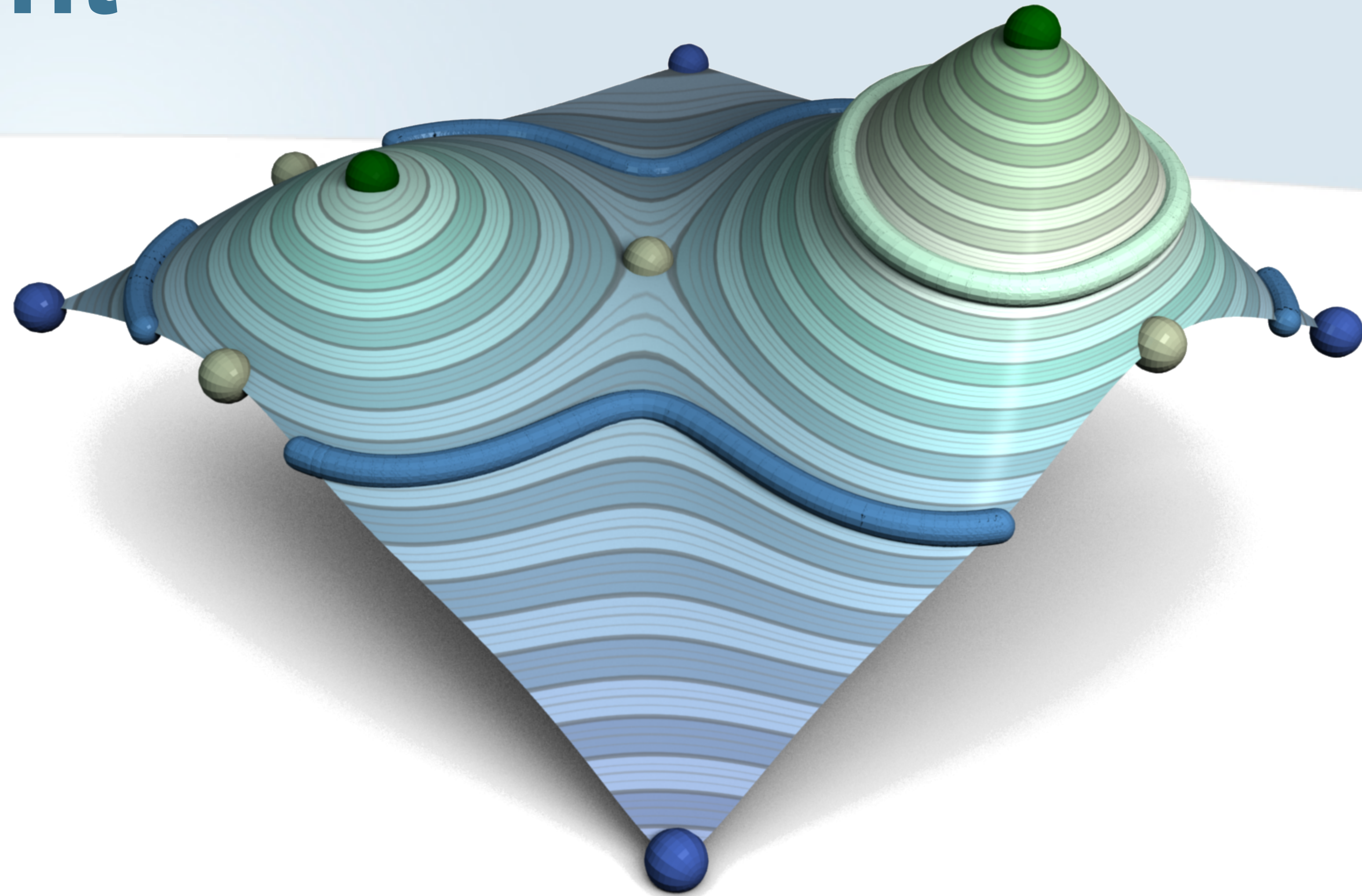


Notion of critical point



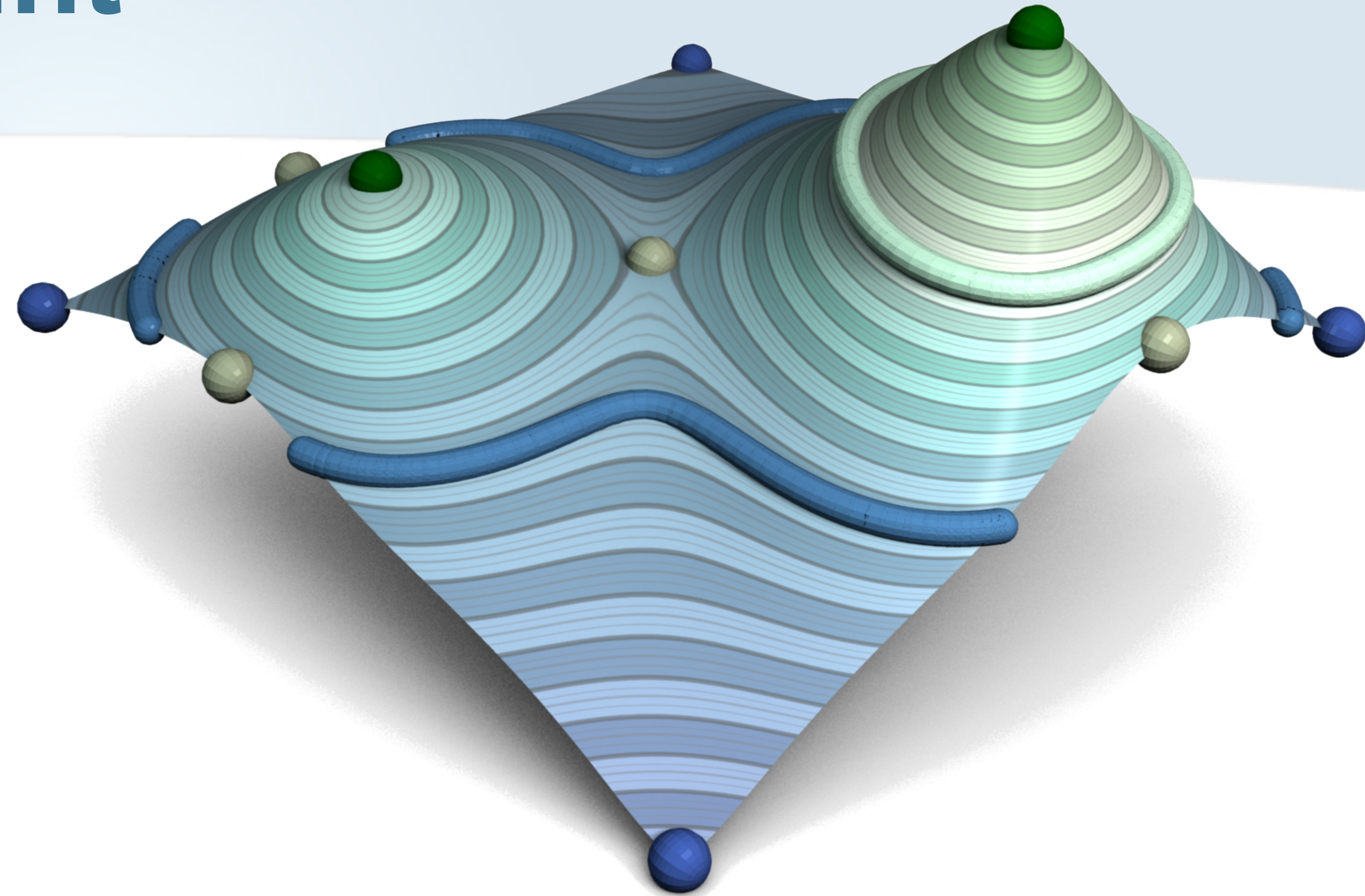
Notion of critical point

- Points where ∇f vanishes



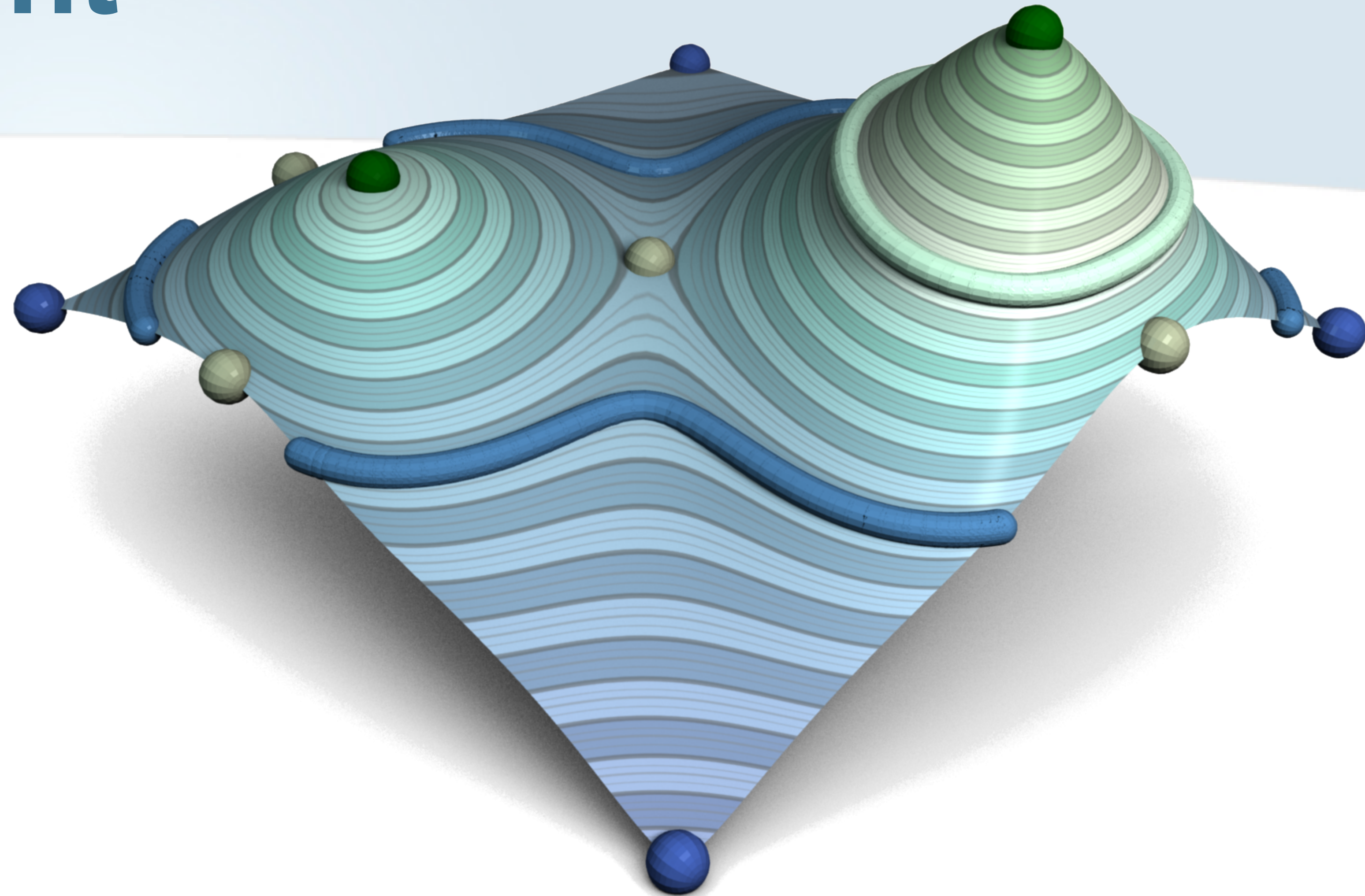
Notion of critical point

- Points where ∇f vanishes
 - Minima, maxima, saddles



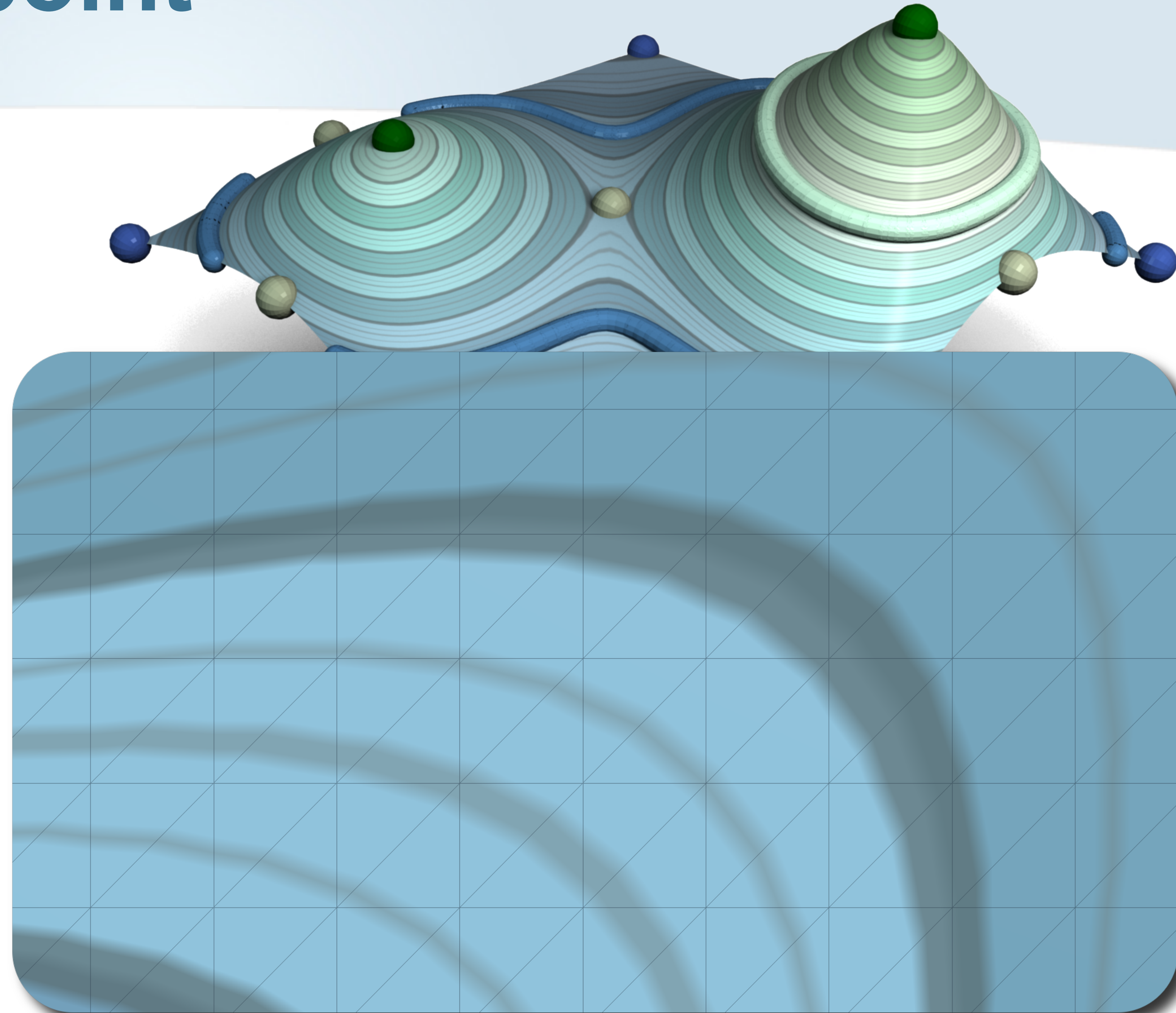
Notion of critical point

- Points where ∇f vanishes
 - Minima, maxima, saddles
 - **Topological changes**



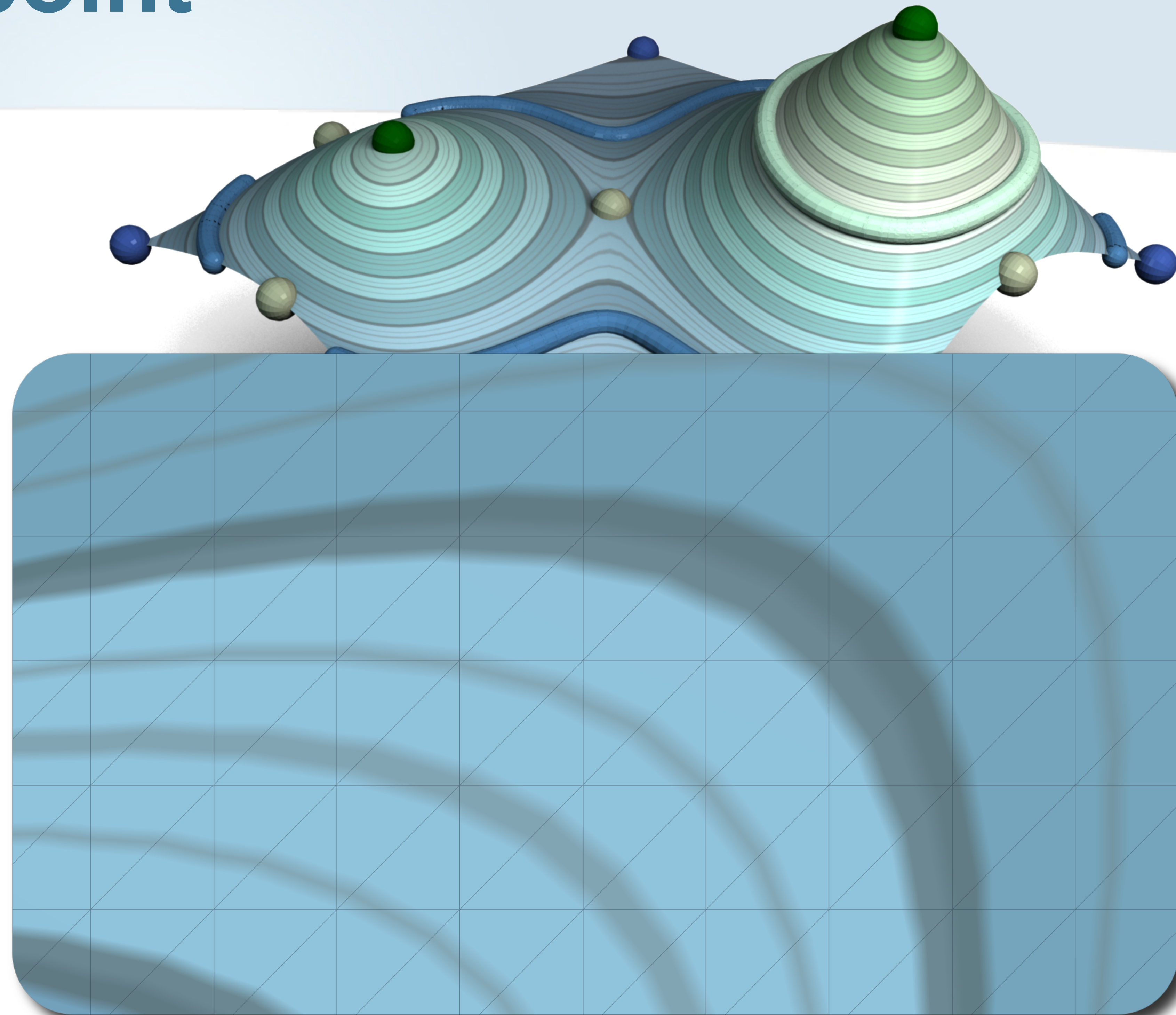
Notion of critical point

- Points where ∇f vanishes
 - Minima, maxima, saddles
 - **Topological changes**
 - PL interpolant



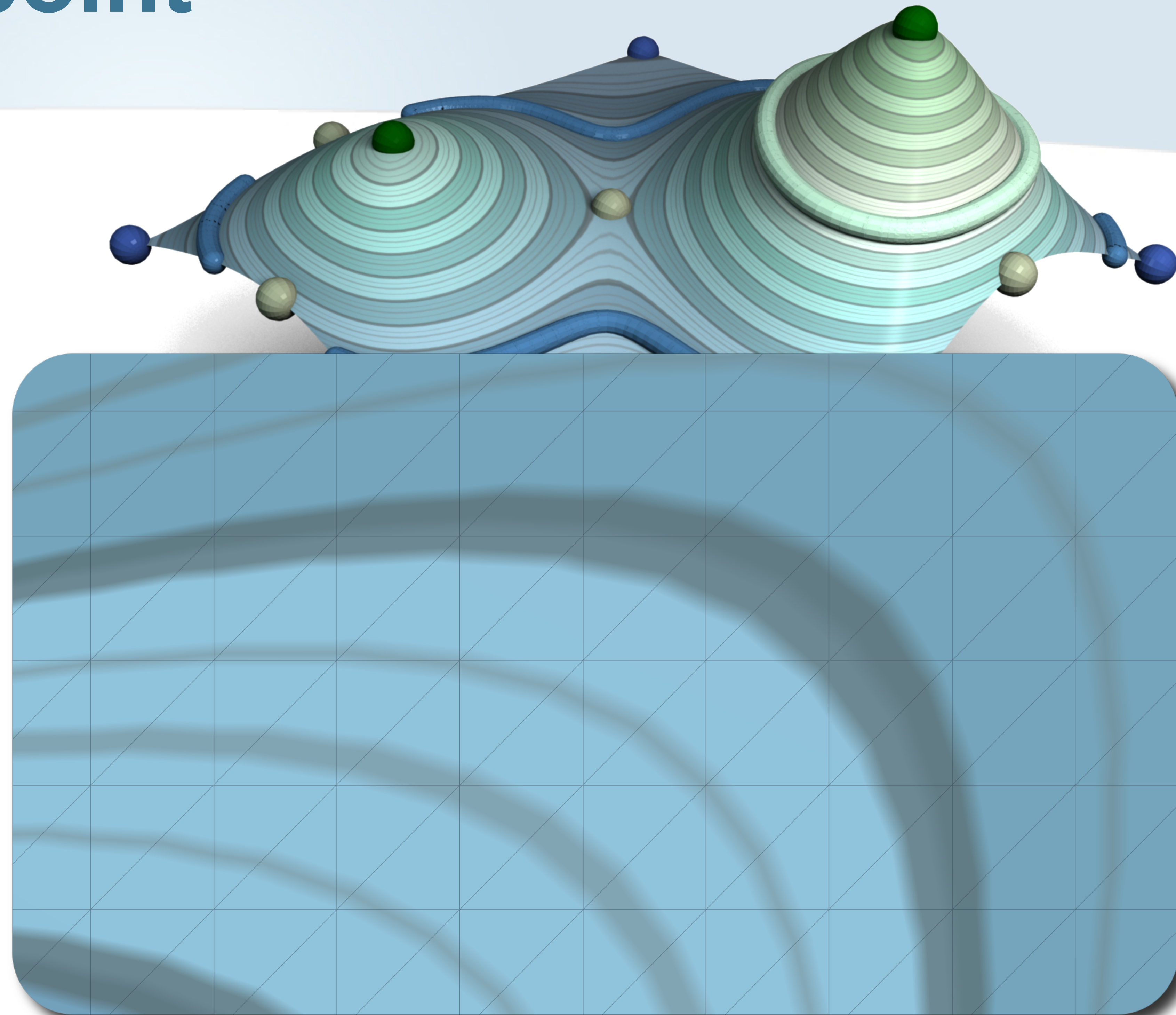
Notion of critical point

- Points where ∇f vanishes
 - Minima, maxima, saddles
 - **Topological changes**
 - PL interpolant
 - Barycentric coordinates on simplices



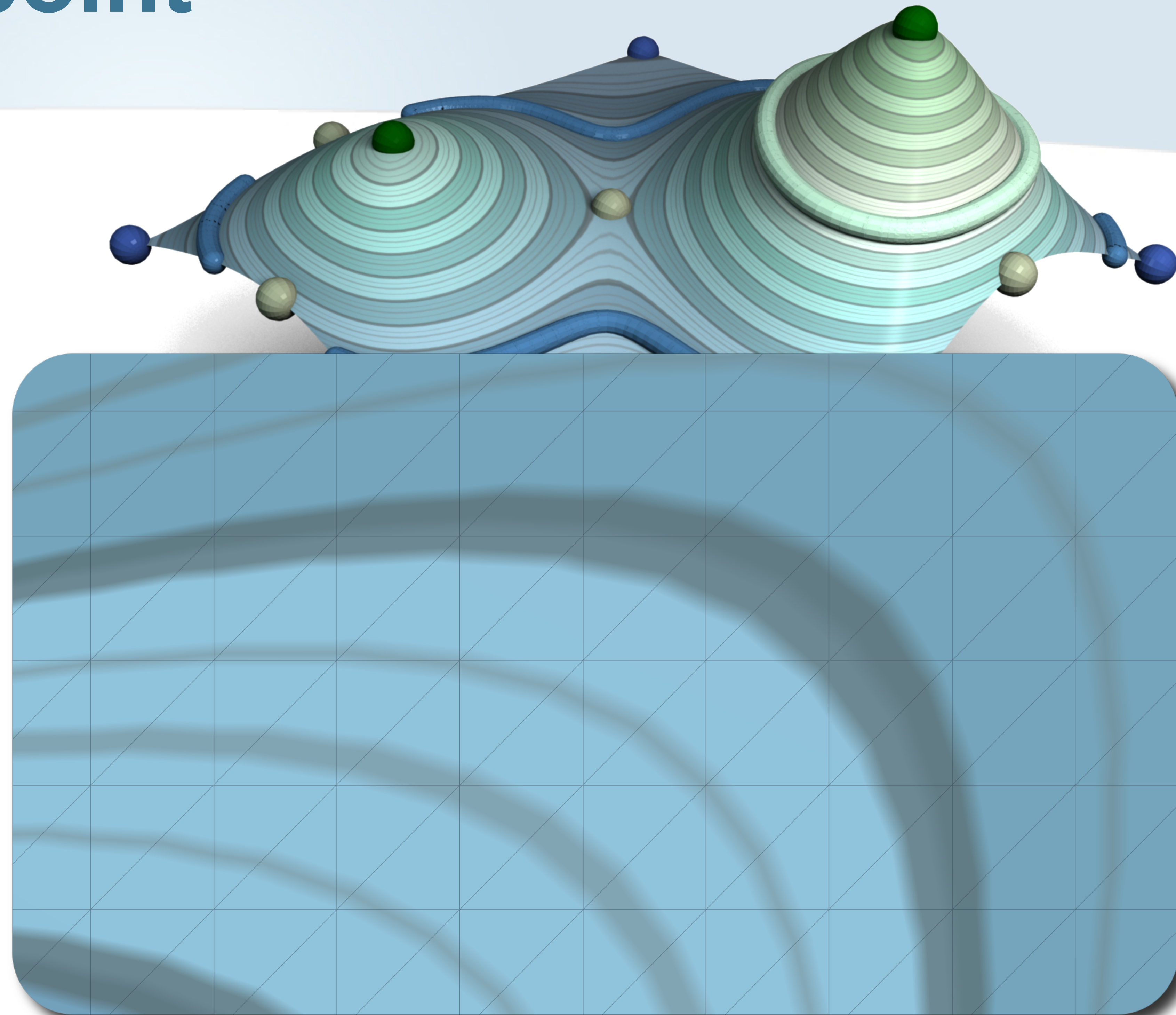
Notion of critical point

- Points where ∇f vanishes
 - Minima, maxima, saddles
 - **Topological changes**
 - PL interpolant
 - Barycentric coordinates on simplices
 - **Only on vertices**



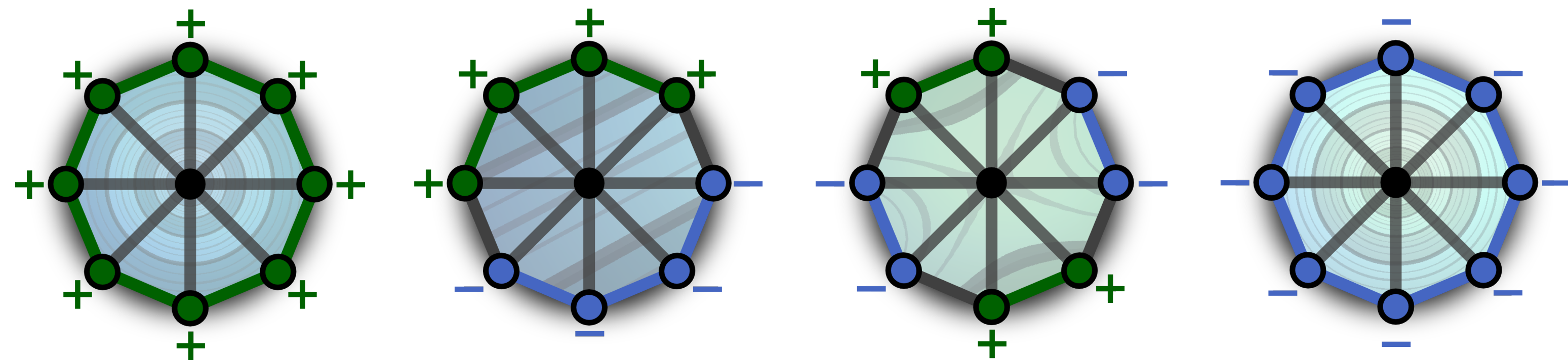
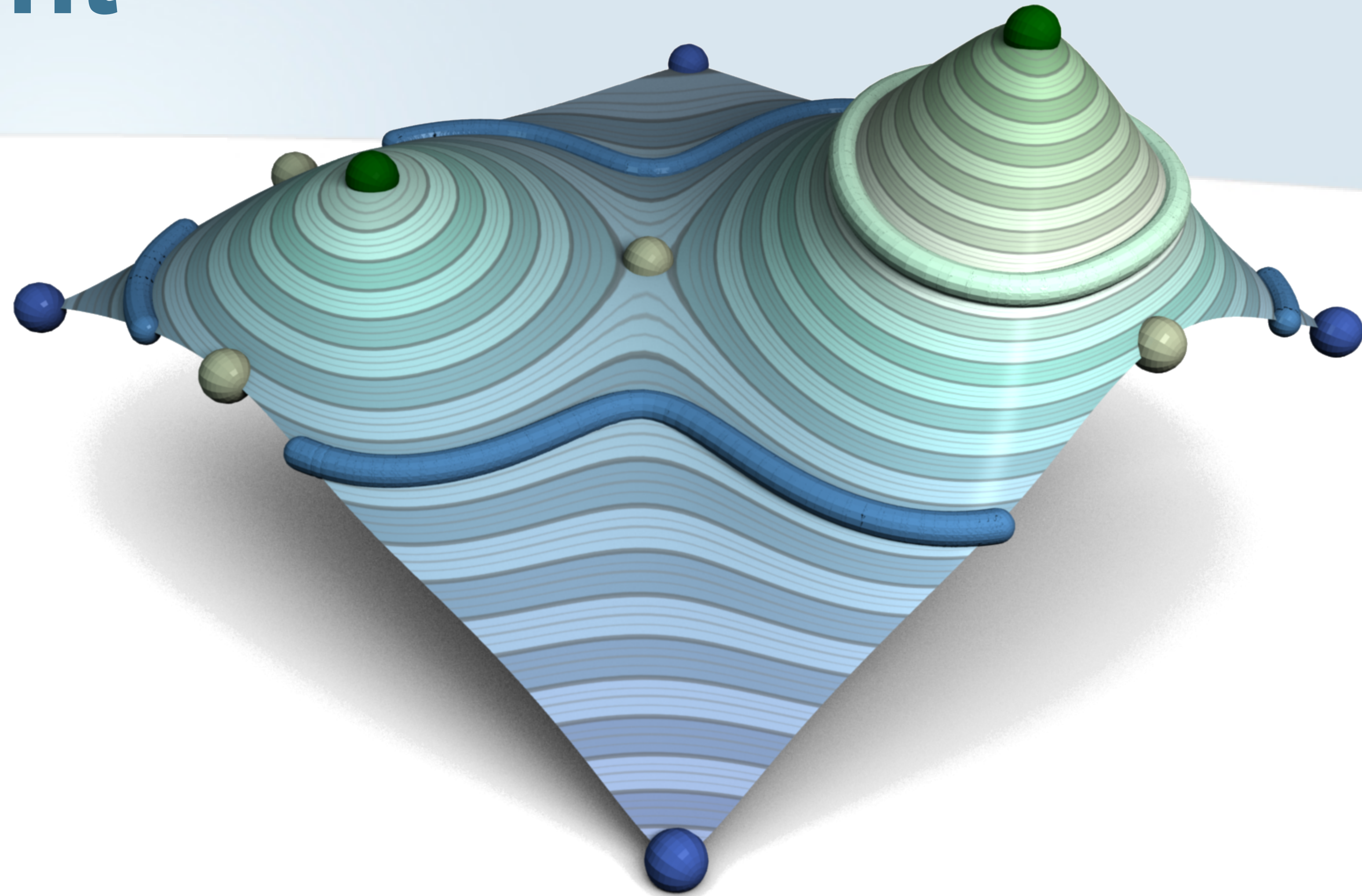
Notion of critical point

- Points where ∇f vanishes
 - Minima, maxima, saddles
 - **Topological changes**
 - PL interpolant
 - Barycentric coordinates on simplices
 - **Only on vertices**
 - Combinatorial characterization



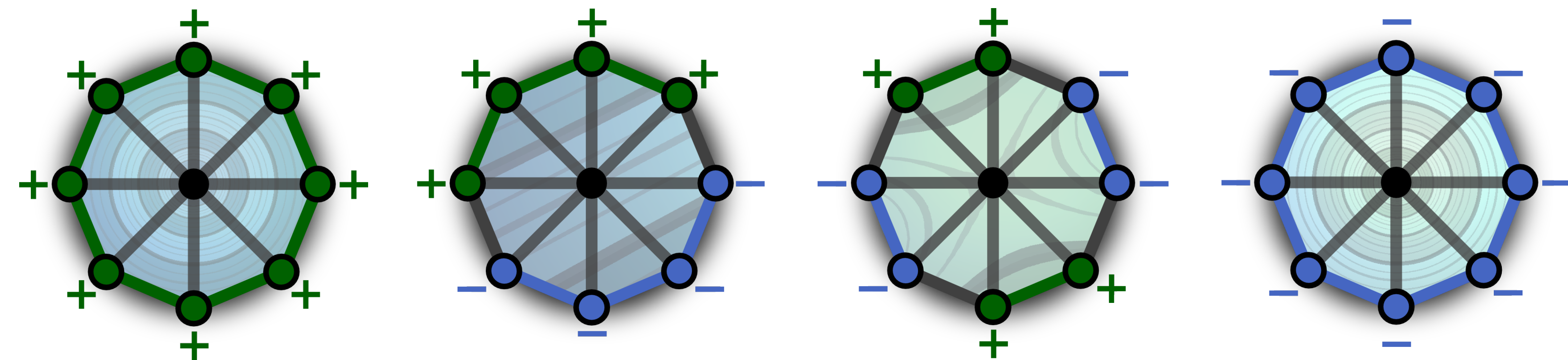
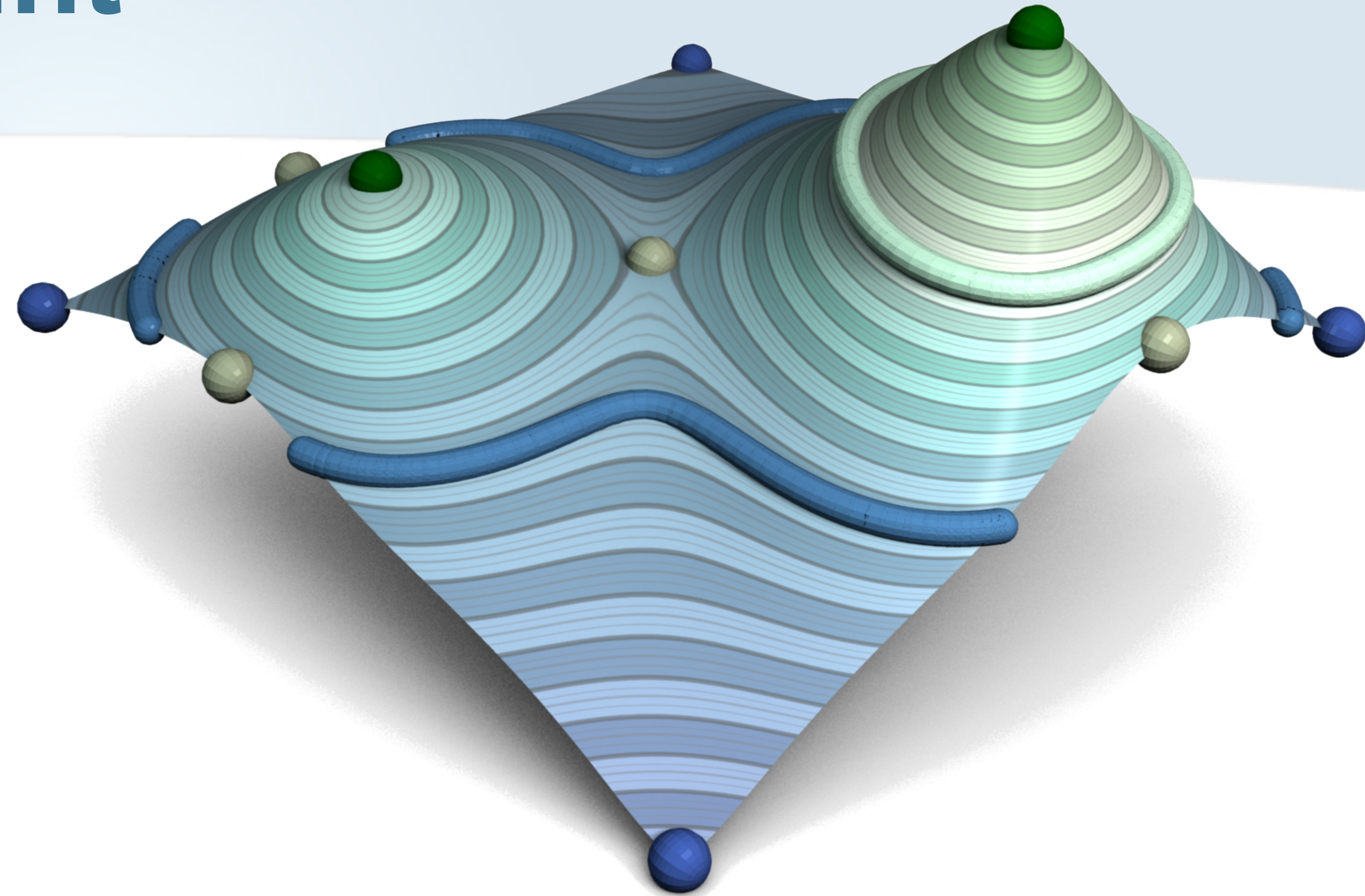
Notion of critical point

- Combinatorial identification



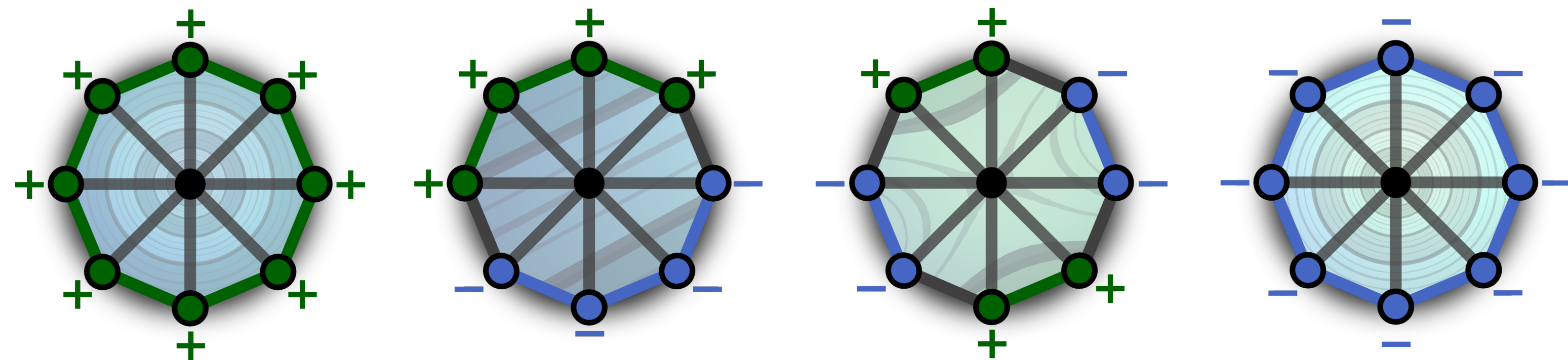
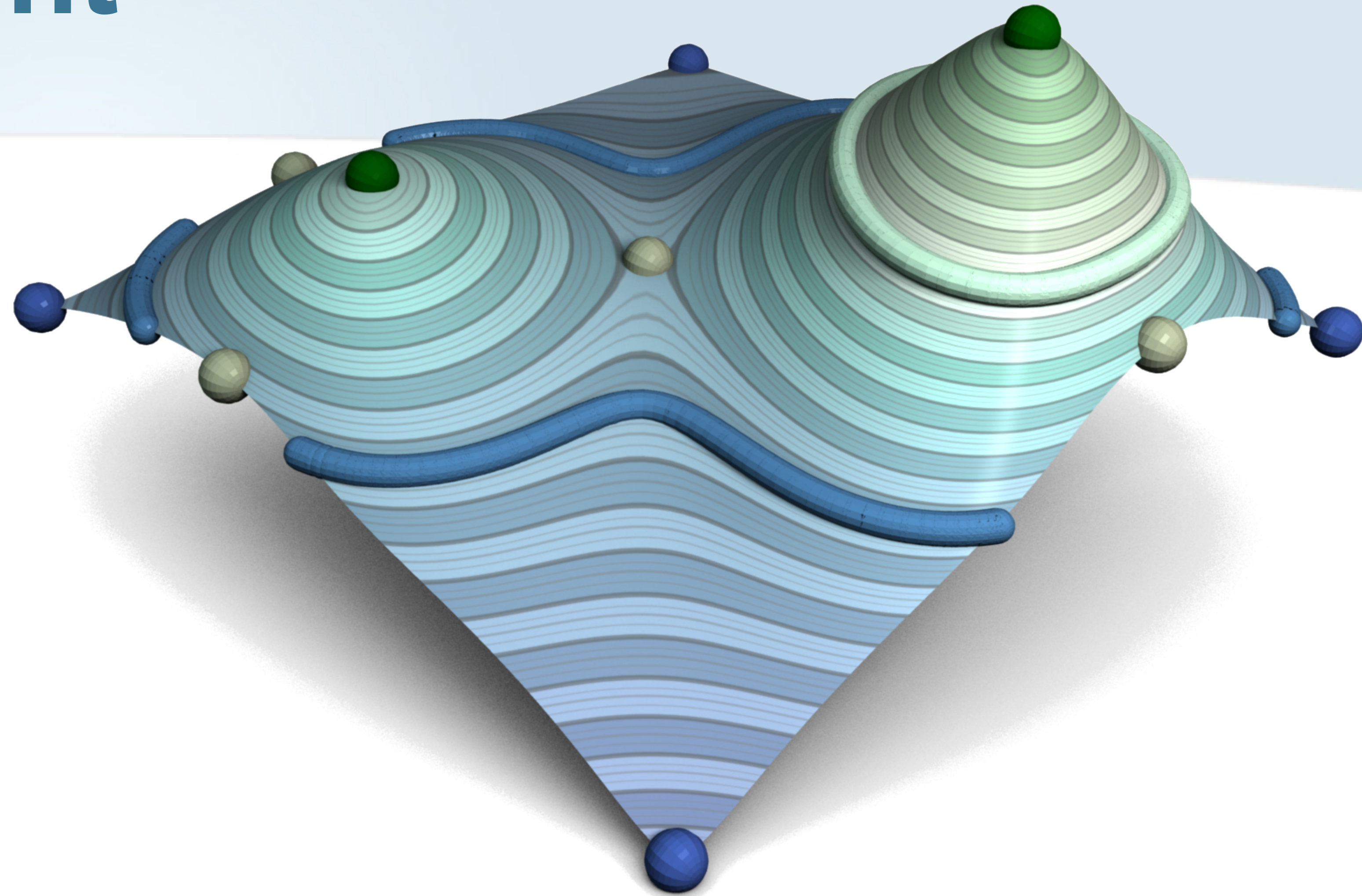
Notion of critical point

- Combinatorial identification
 - Star of a simplex σ



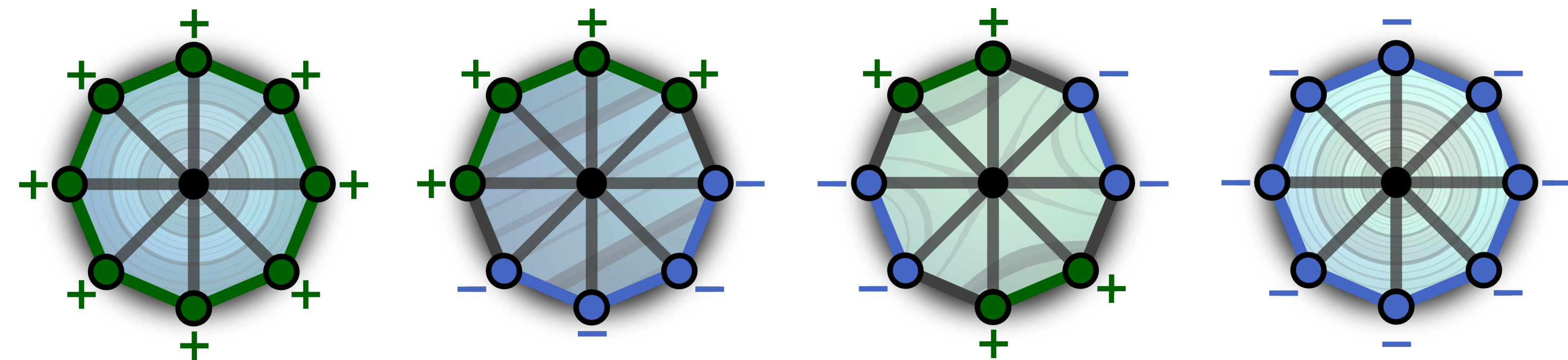
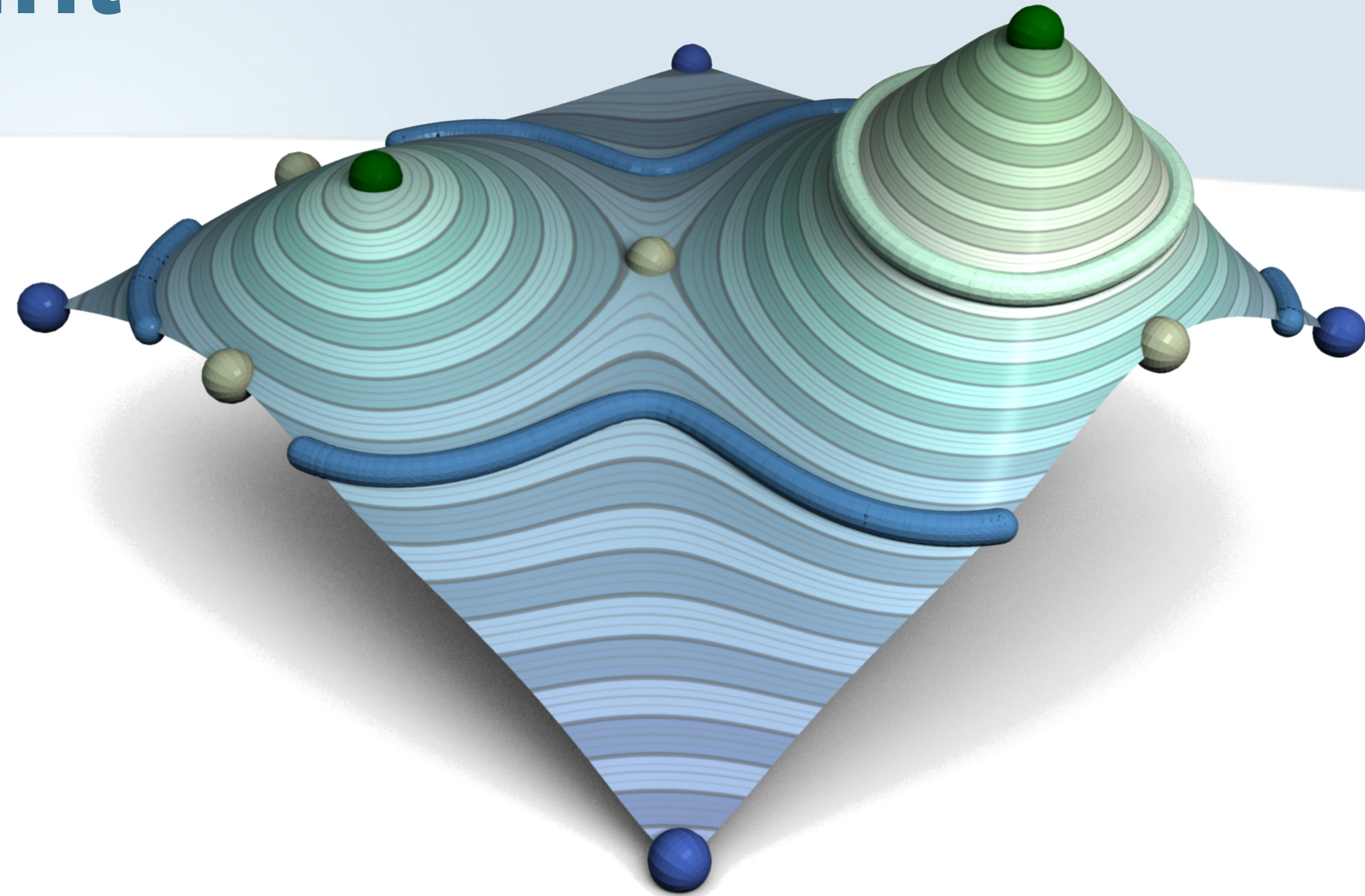
Notion of critical point

- Combinatorial identification
 - Star of a simplex σ
 - Simplices that contain σ as a face



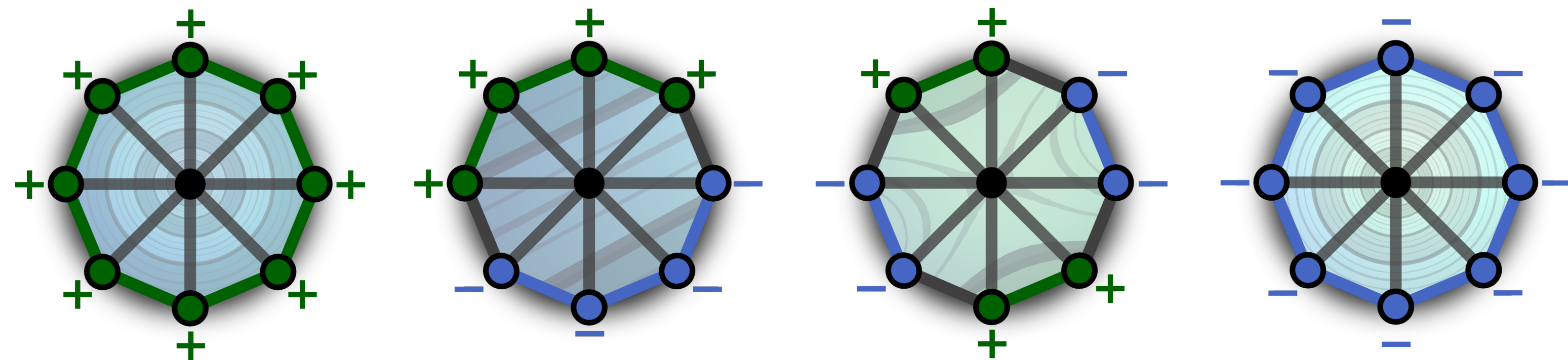
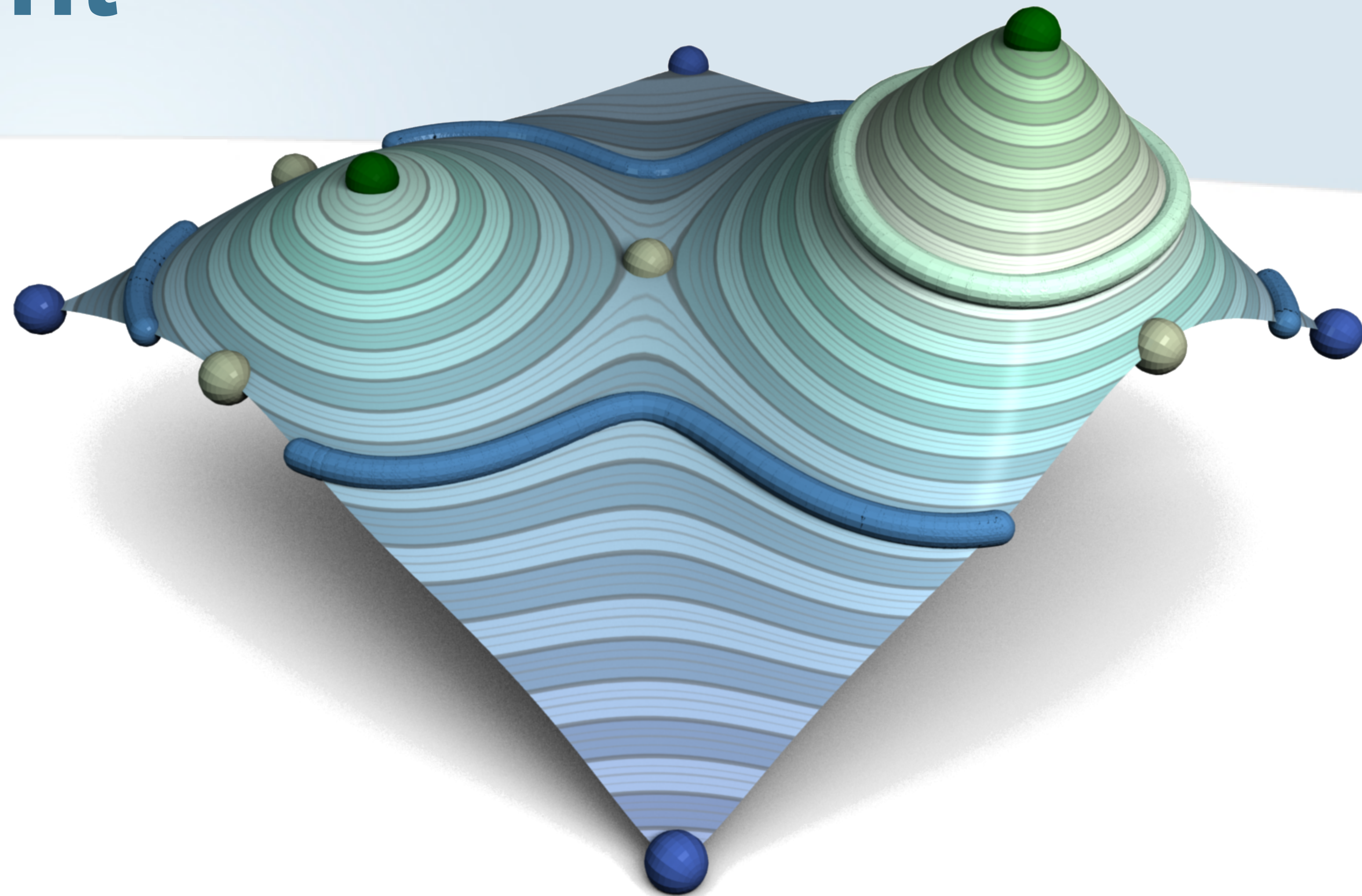
Notion of critical point

- Combinatorial identification
 - Star of a simplex σ
 - Simplices that contain σ as a face
 - Link of a simplex



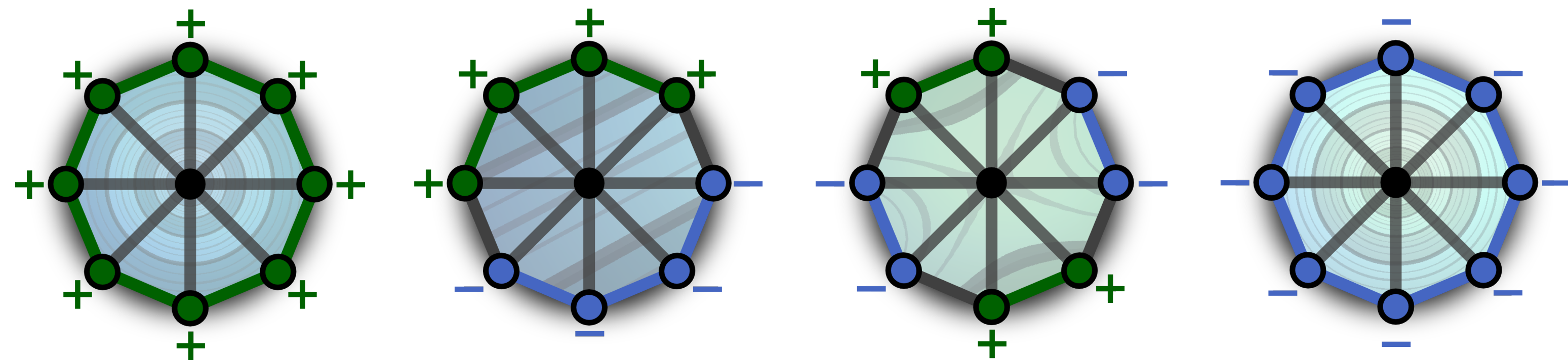
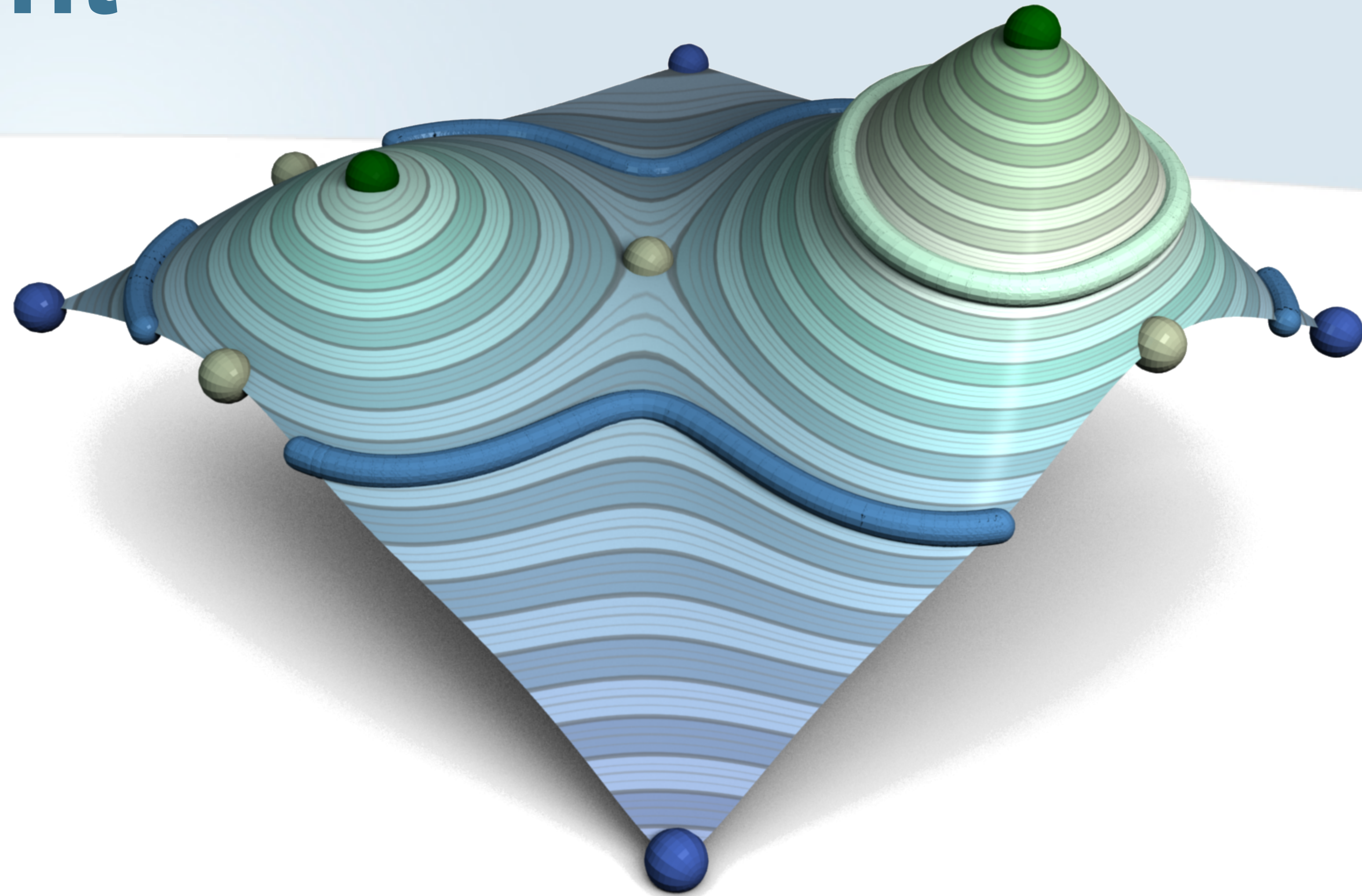
Notion of critical point

- Combinatorial identification
 - Star of a simplex σ
 - Simplices that contain σ as a face
 - Link of a simplex
 - Simplices of the closure of the star that do not contain σ as a face



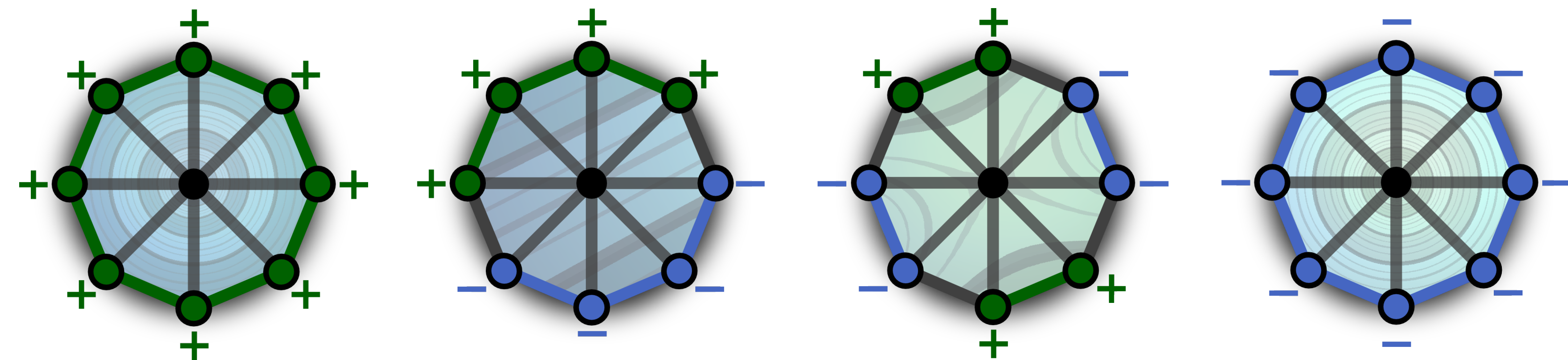
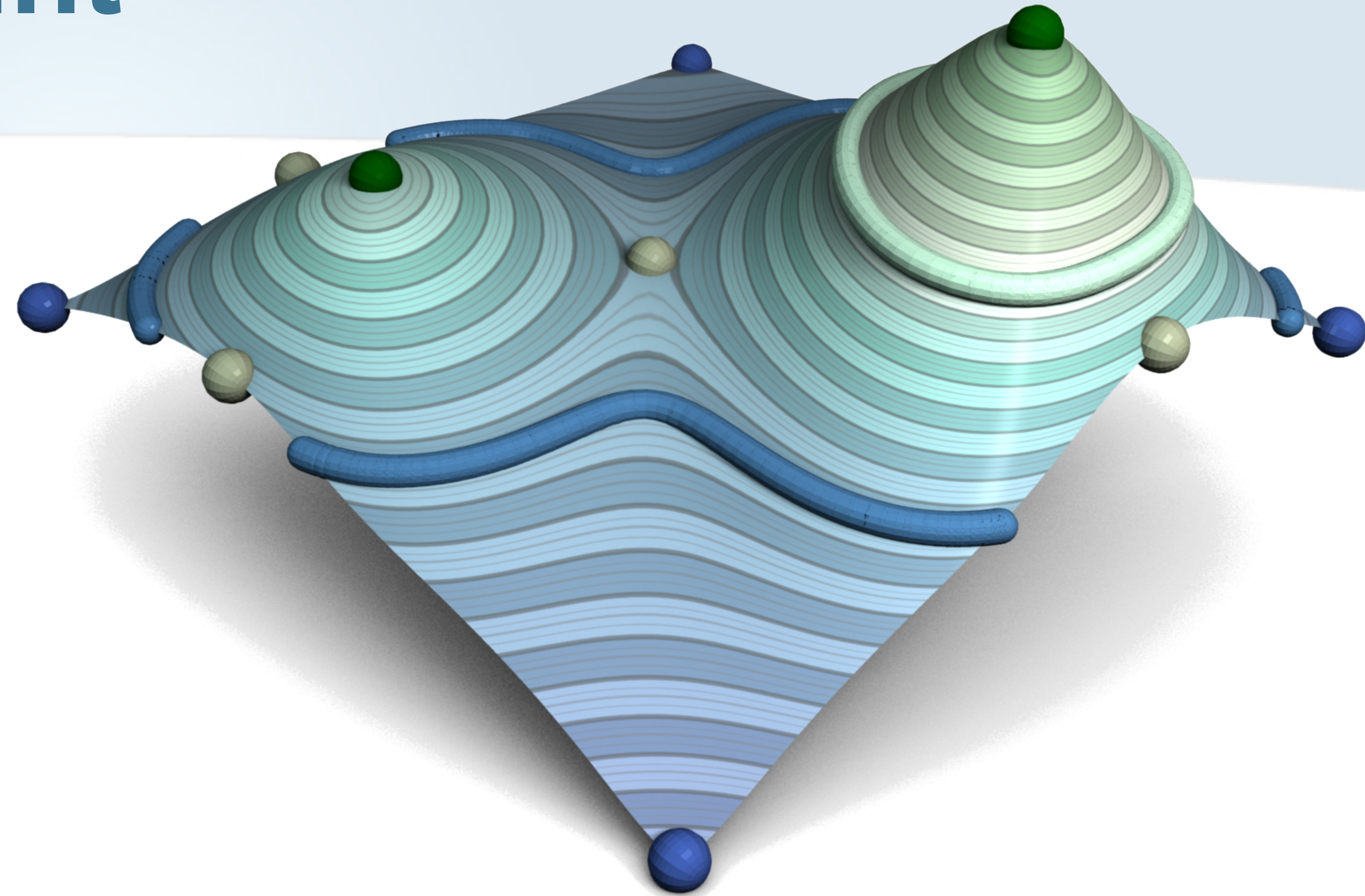
Notion of critical point

- Combinatorial identification
 - Lower link of v



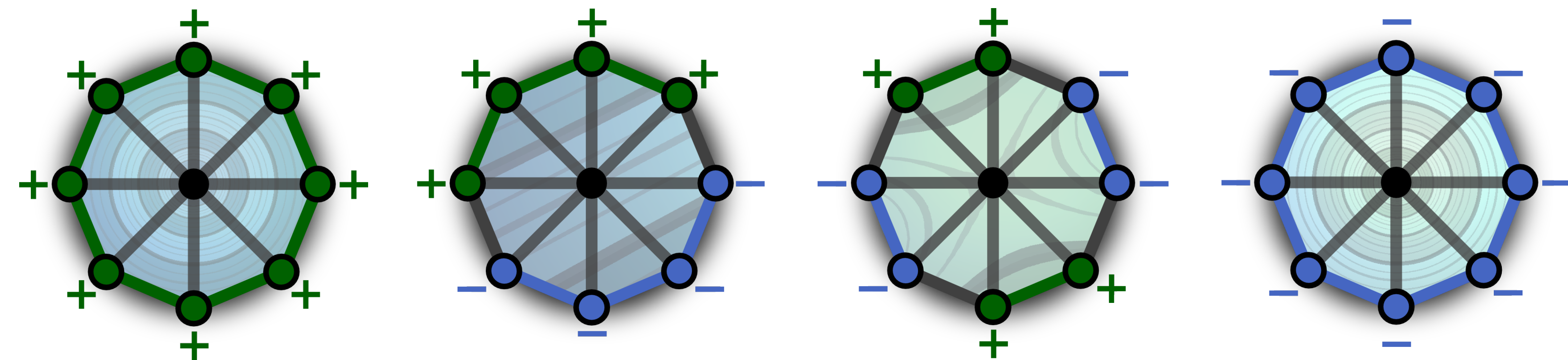
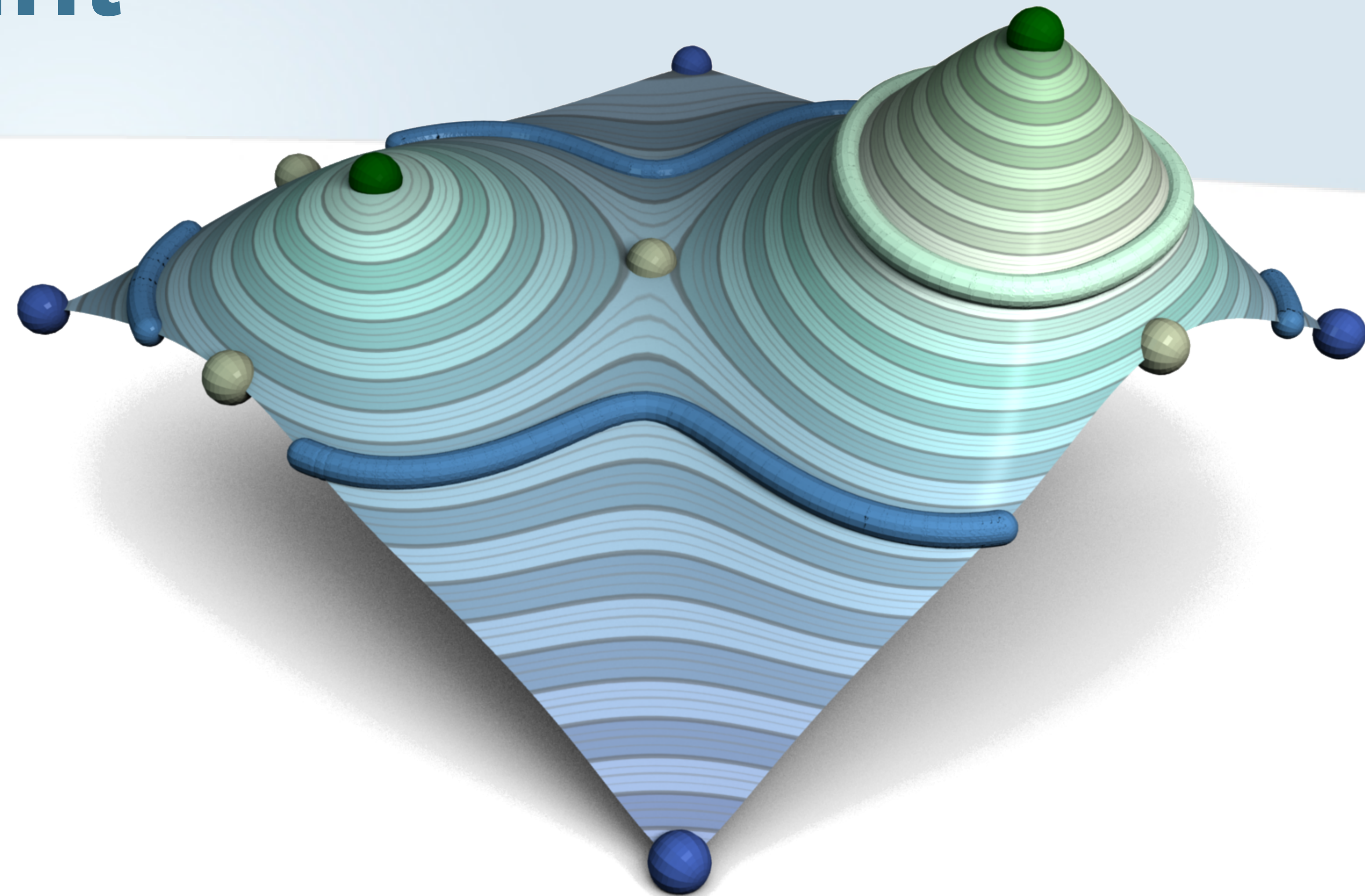
Notion of critical point

- Combinatorial identification
 - Lower link of v
 - Simplices whose function values are strictly below $f(v)$



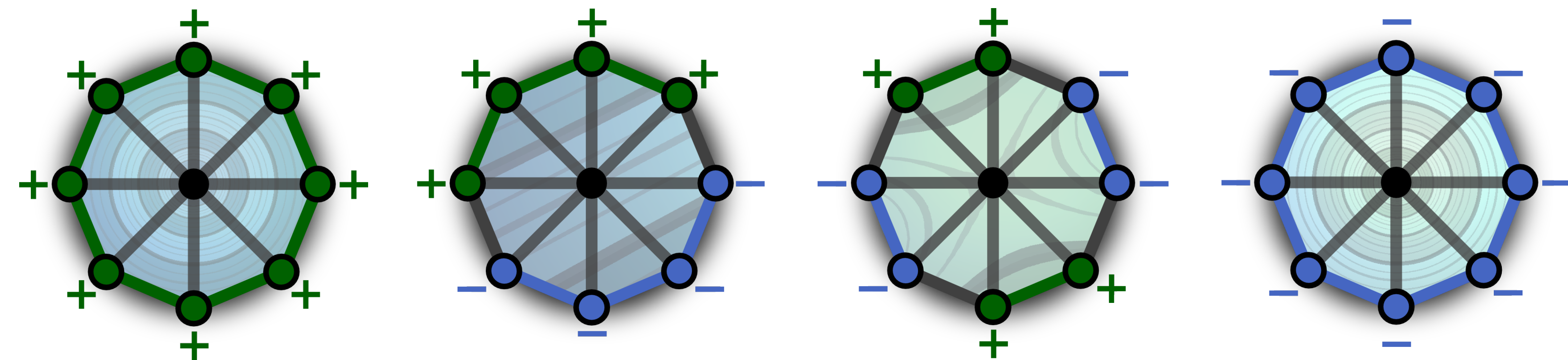
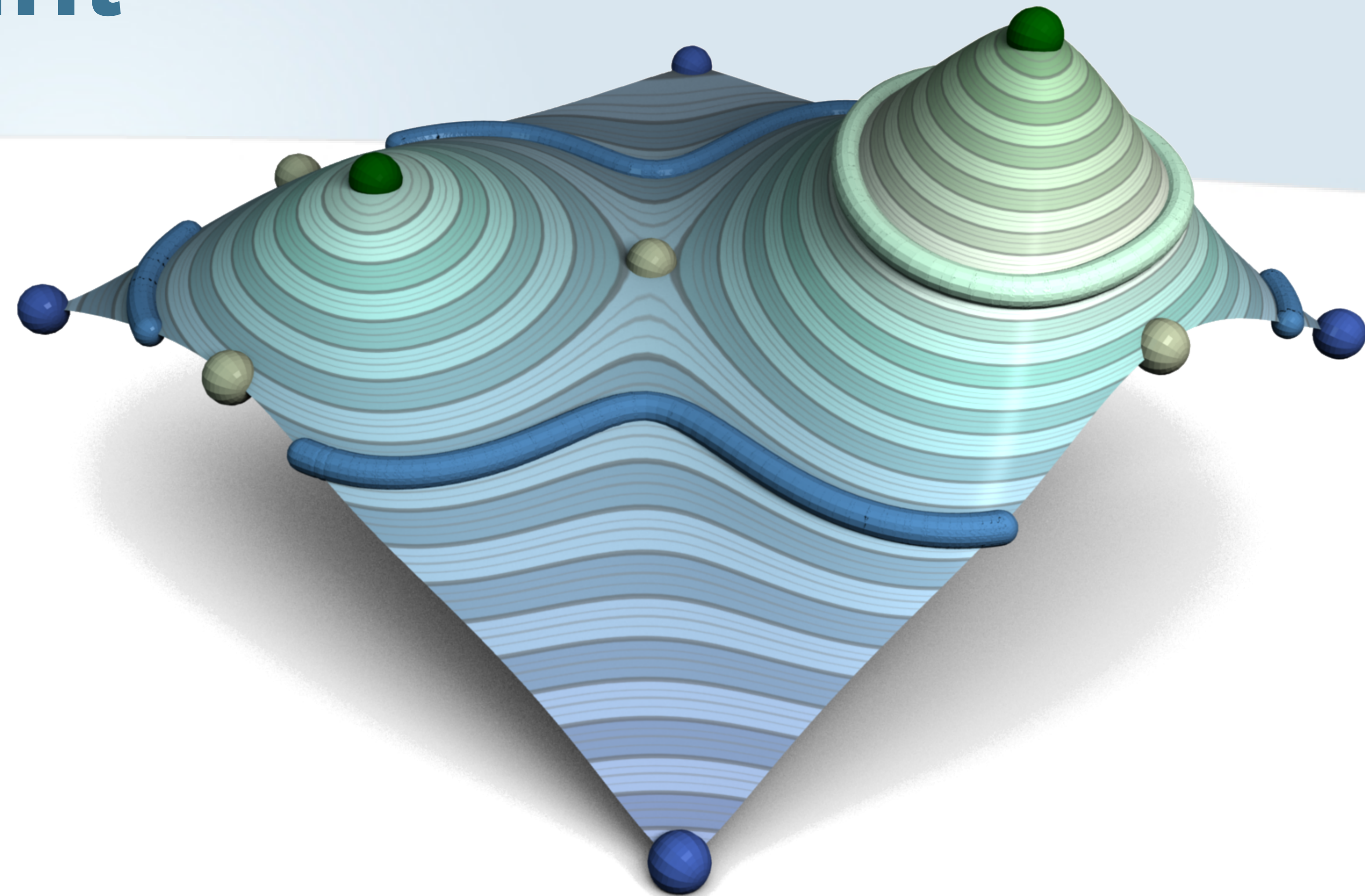
Notion of critical point

- Combinatorial identification
 - Lower link of v
 - Simplices whose function values are strictly below $f(v)$
 - Upper link of v



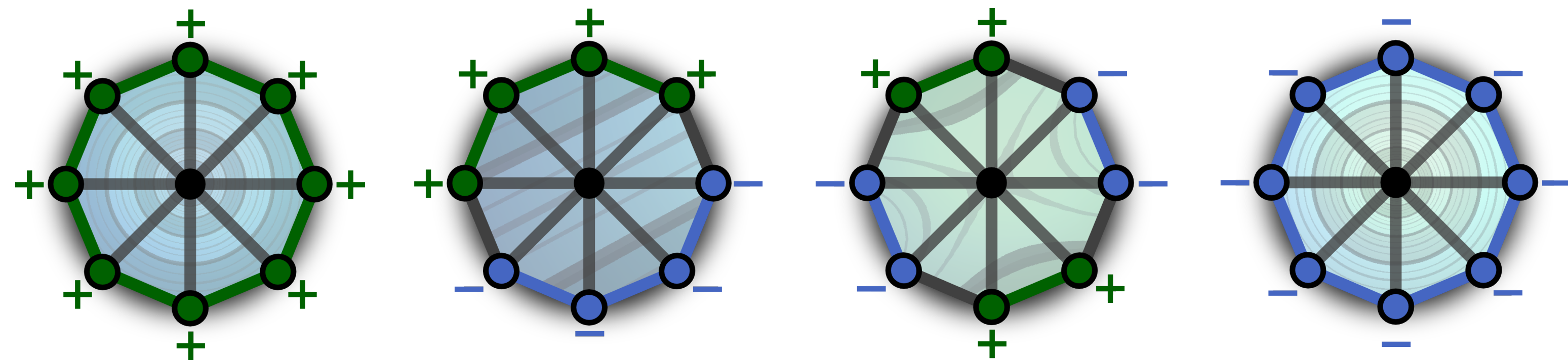
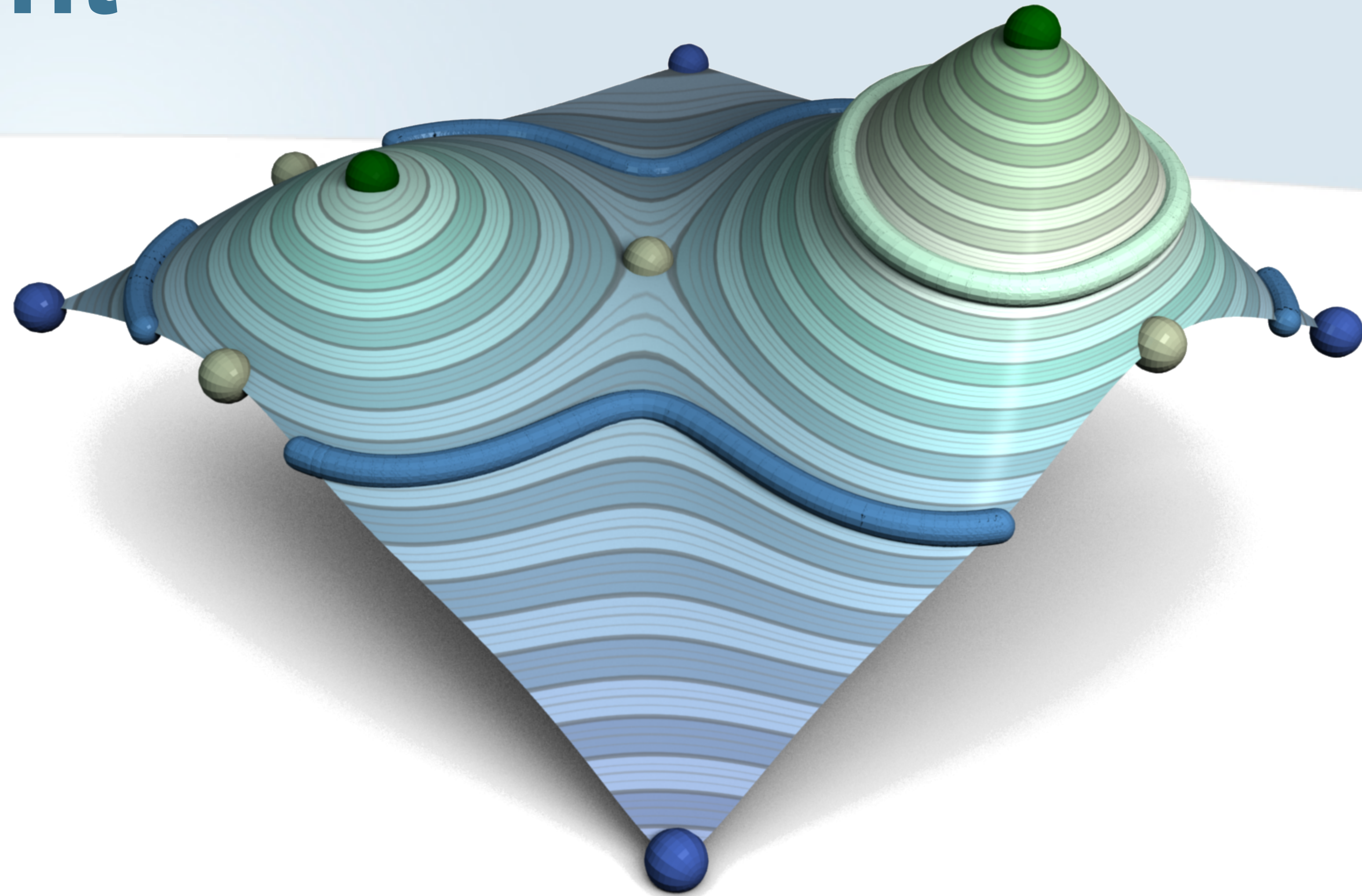
Notion of critical point

- Combinatorial identification
 - Lower link of v
 - Simplices whose function values are strictly below $f(v)$
 - Upper link of v
 - Simplices whose function values are strictly above $f(v)$



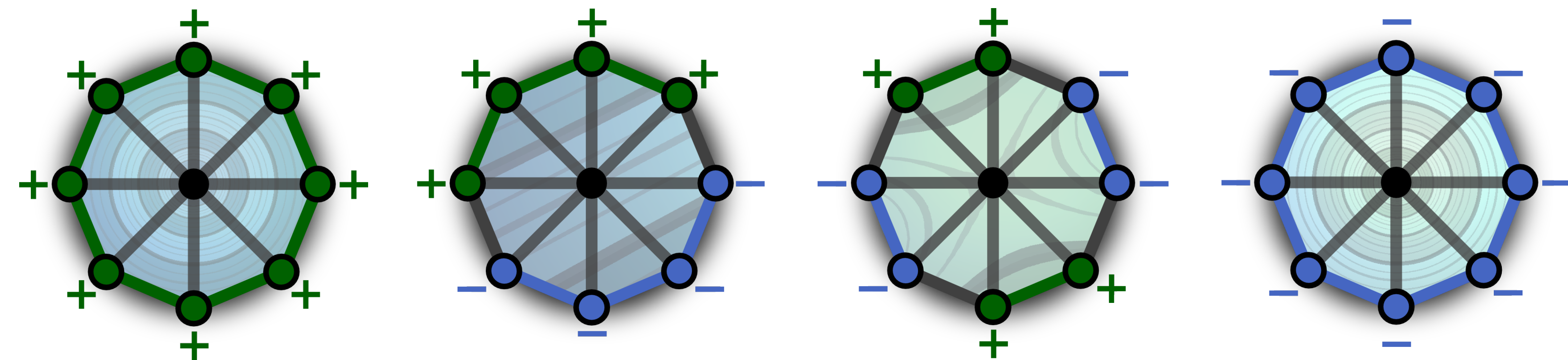
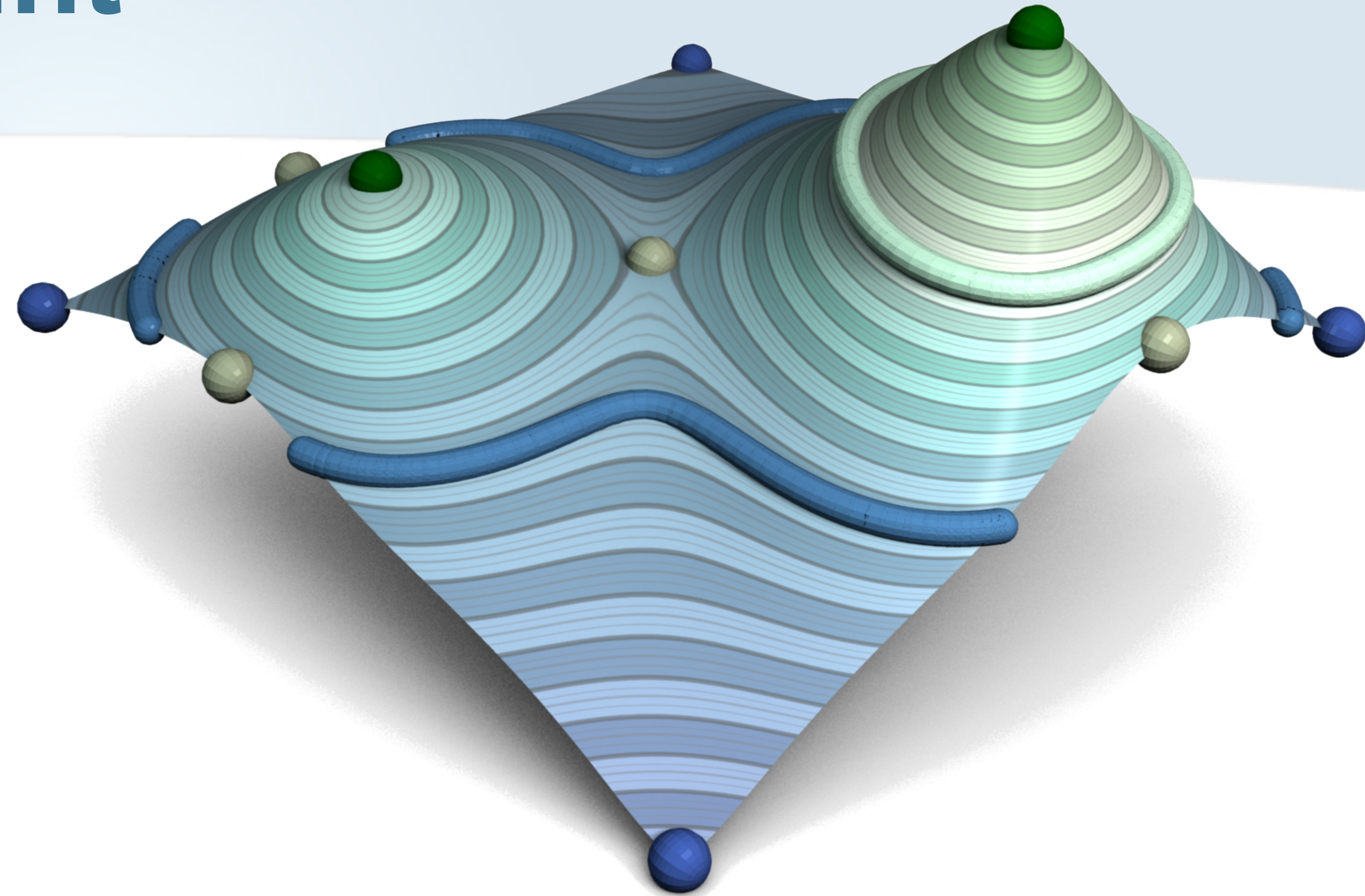
Notion of critical point

- Combinatorial identification



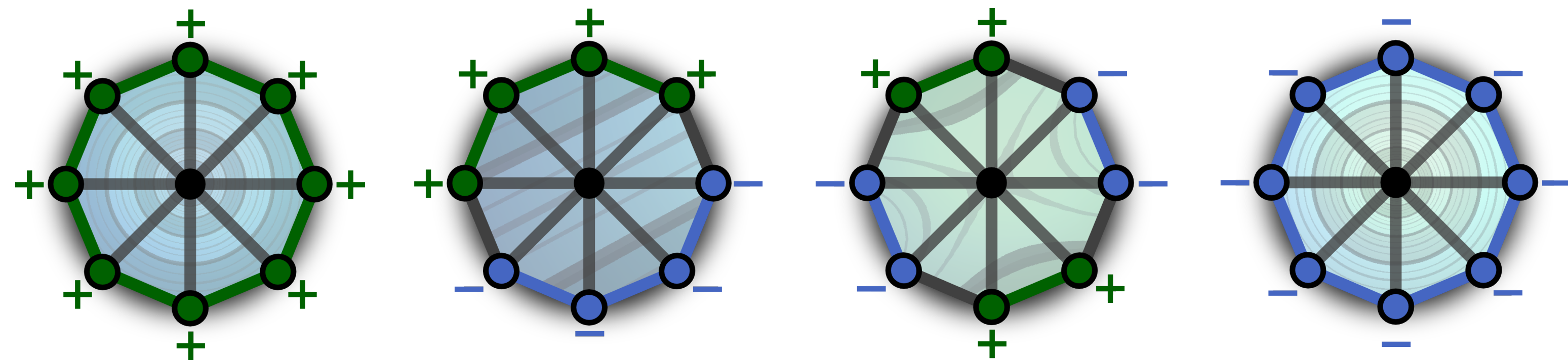
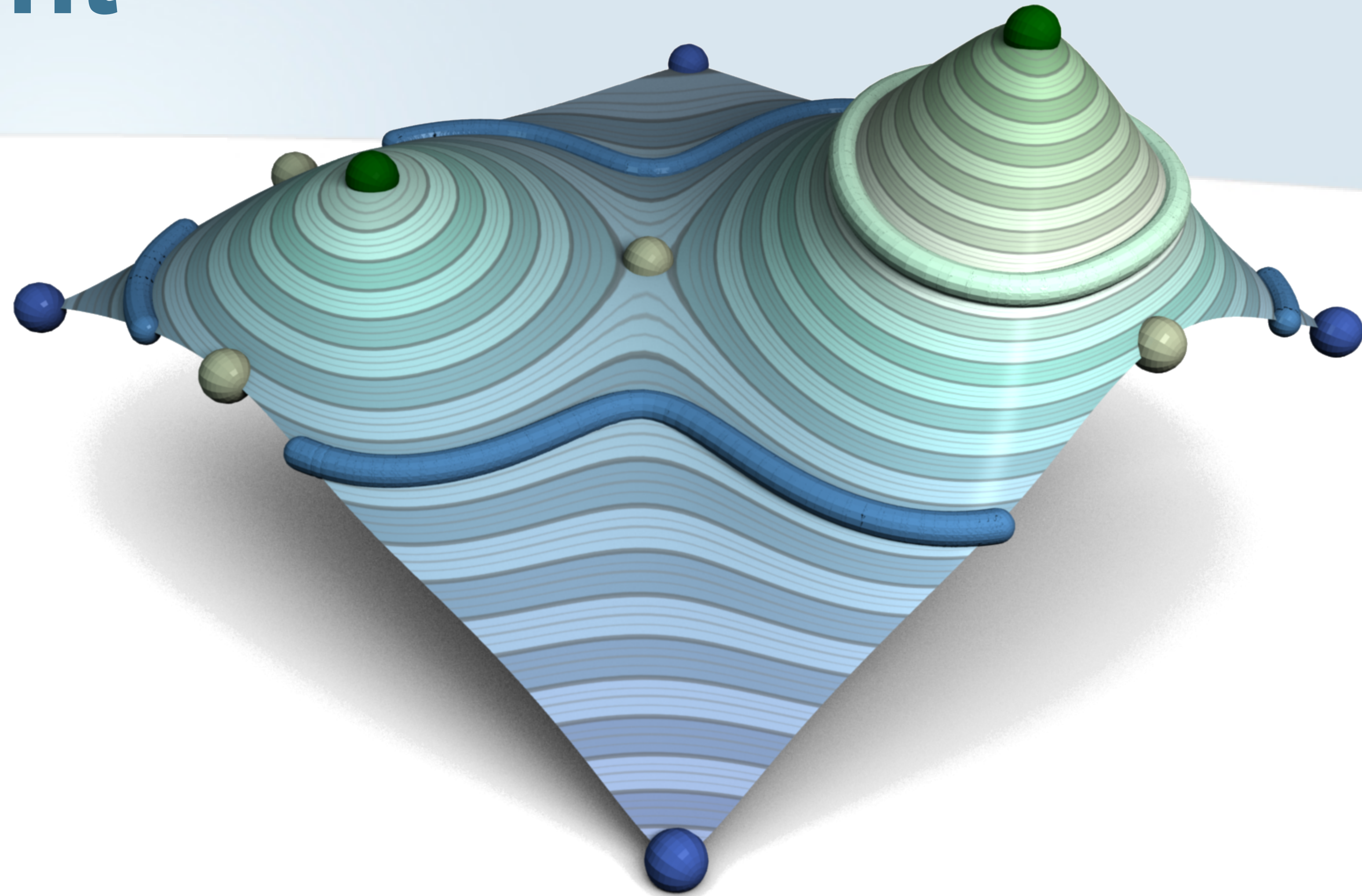
Notion of critical point

- Combinatorial identification
 - Minimum



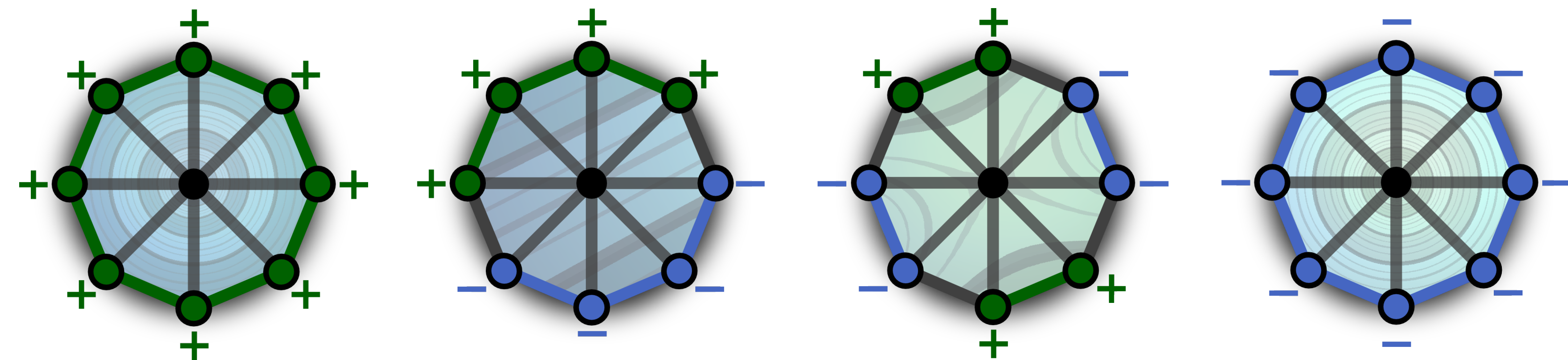
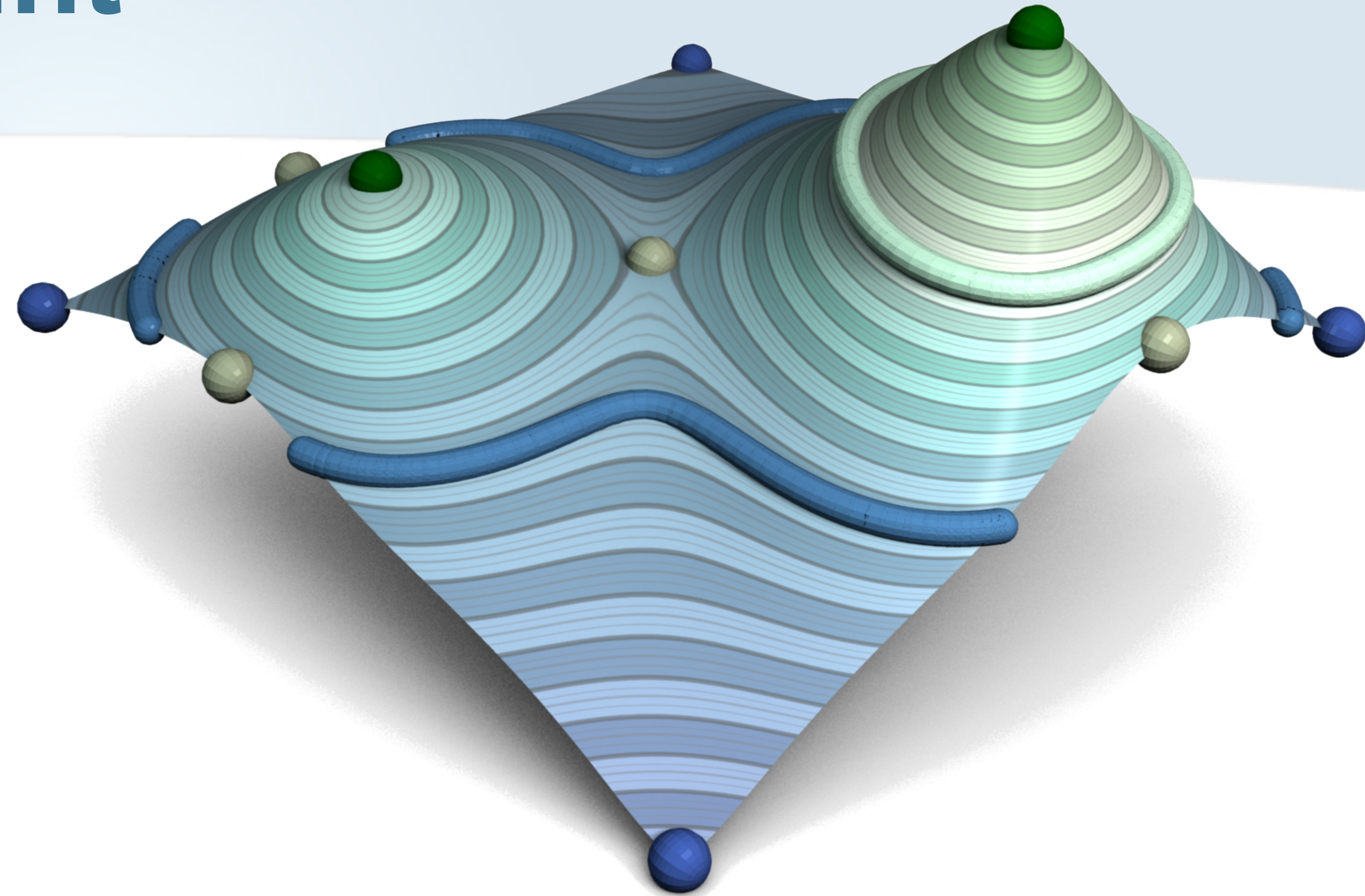
Notion of critical point

- Combinatorial identification
 - Minimum
 - Empty lower link



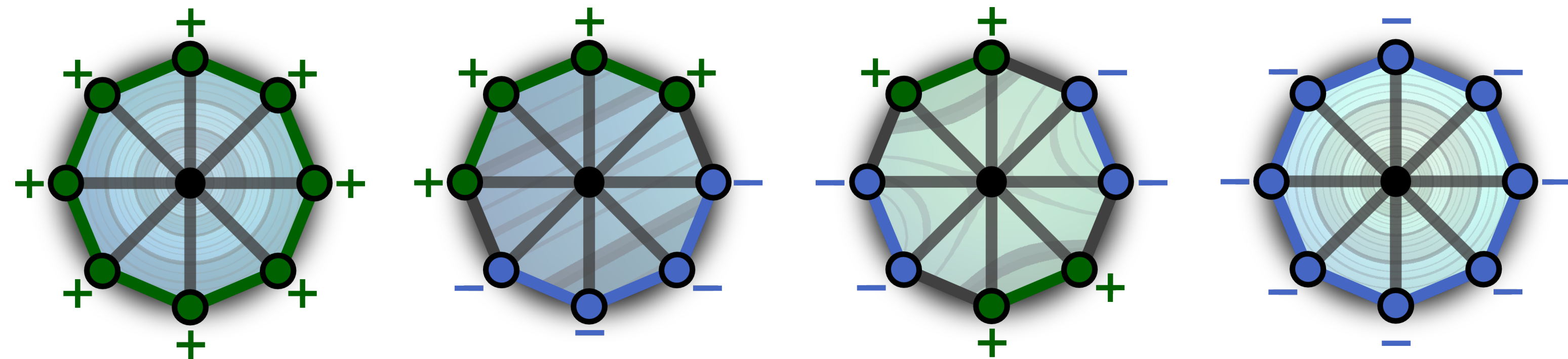
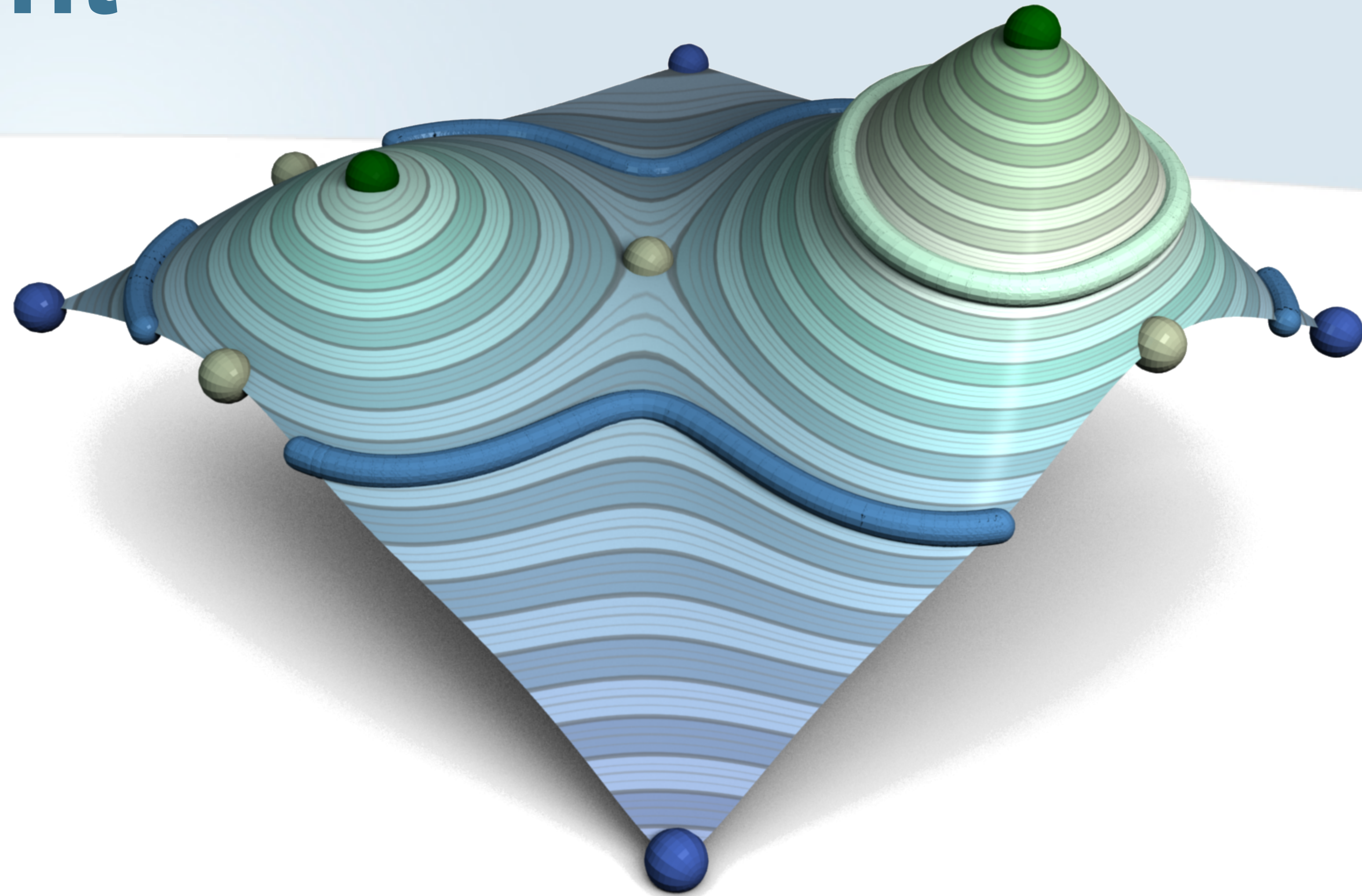
Notion of critical point

- Combinatorial identification
 - Minimum
 - Empty lower link
 - Maximum



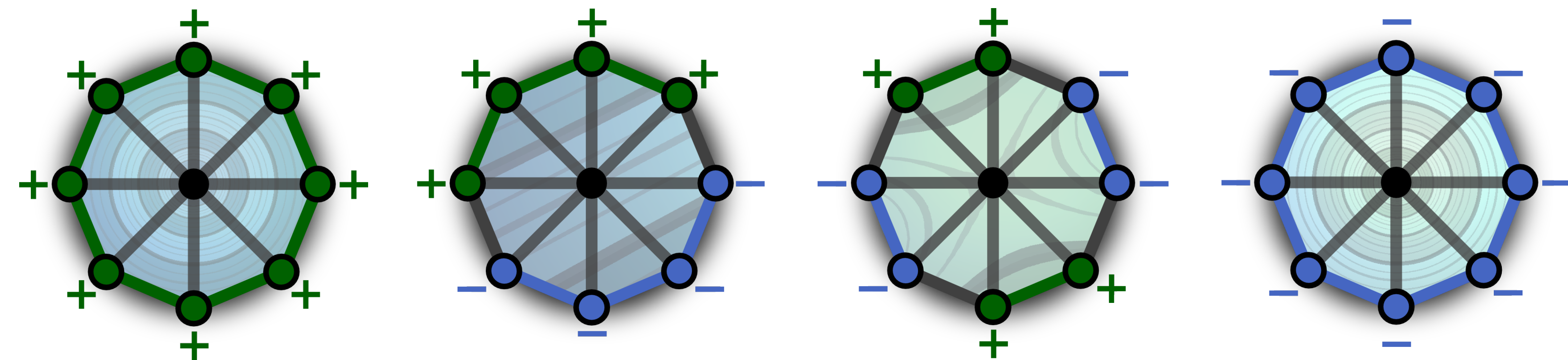
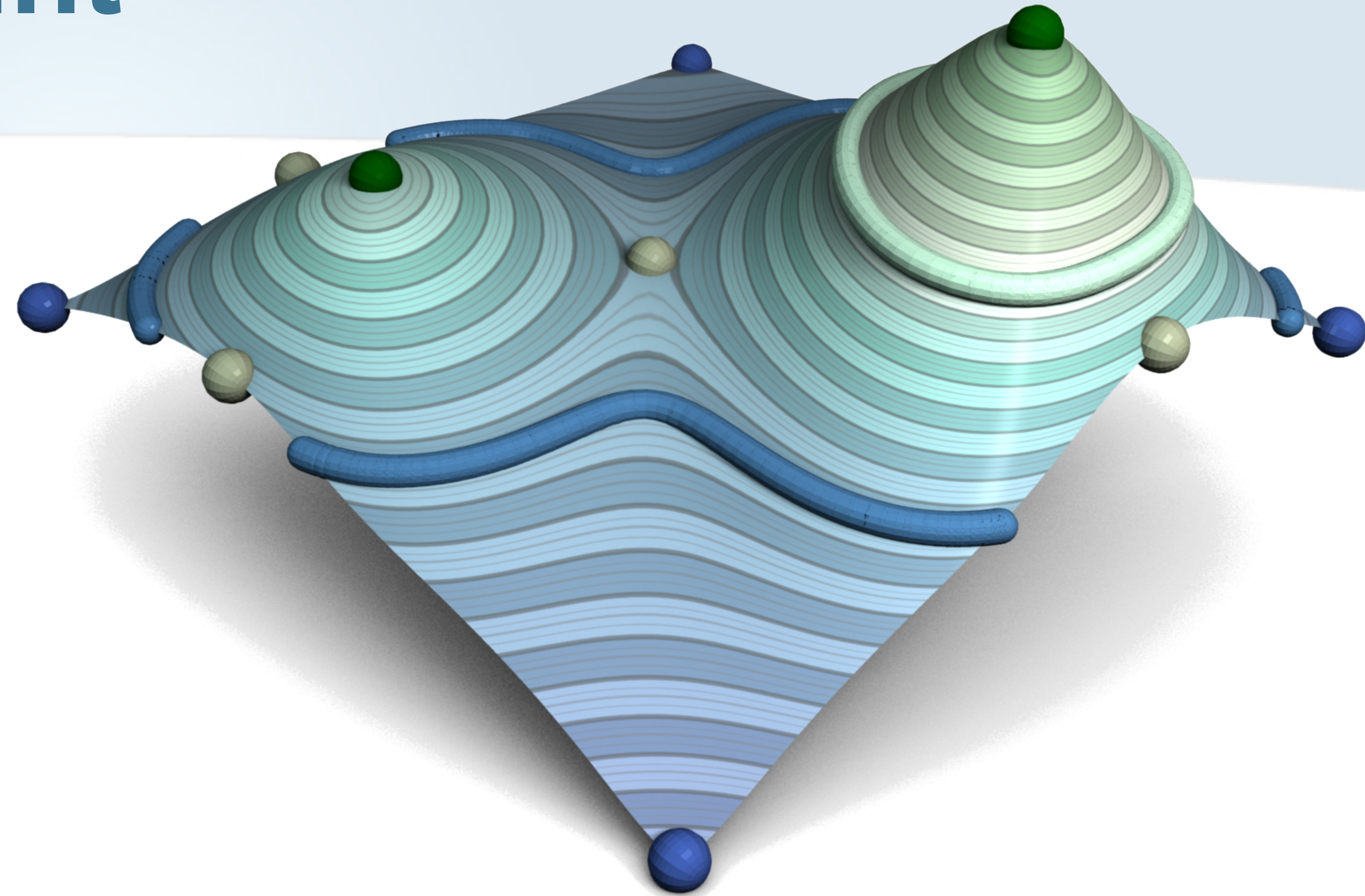
Notion of critical point

- Combinatorial identification
 - Minimum
 - Empty lower link
 - Maximum
 - Empty upper link



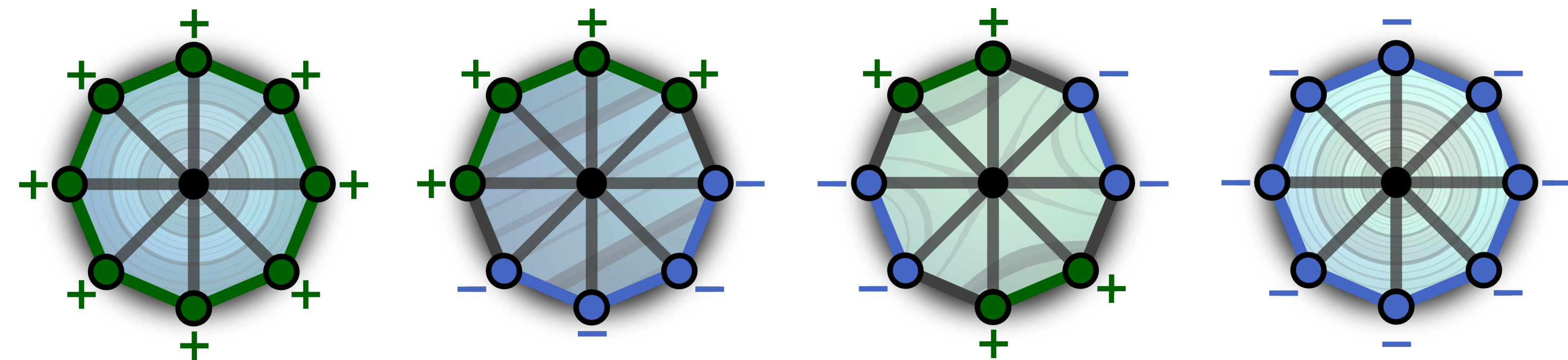
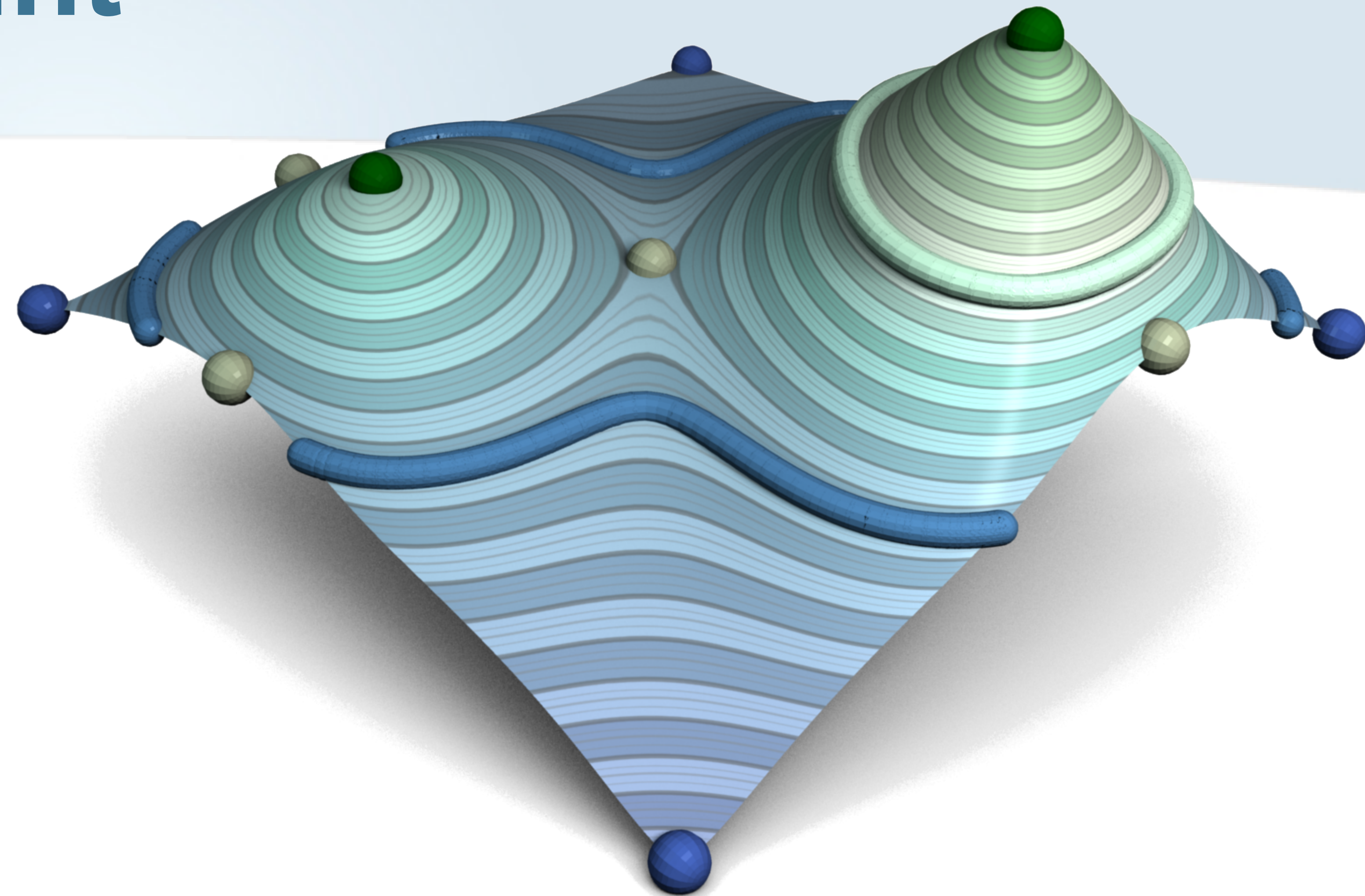
Notion of critical point

- Combinatorial identification
 - Minimum
 - Empty lower link
 - Maximum
 - Empty upper link
 - Regular point



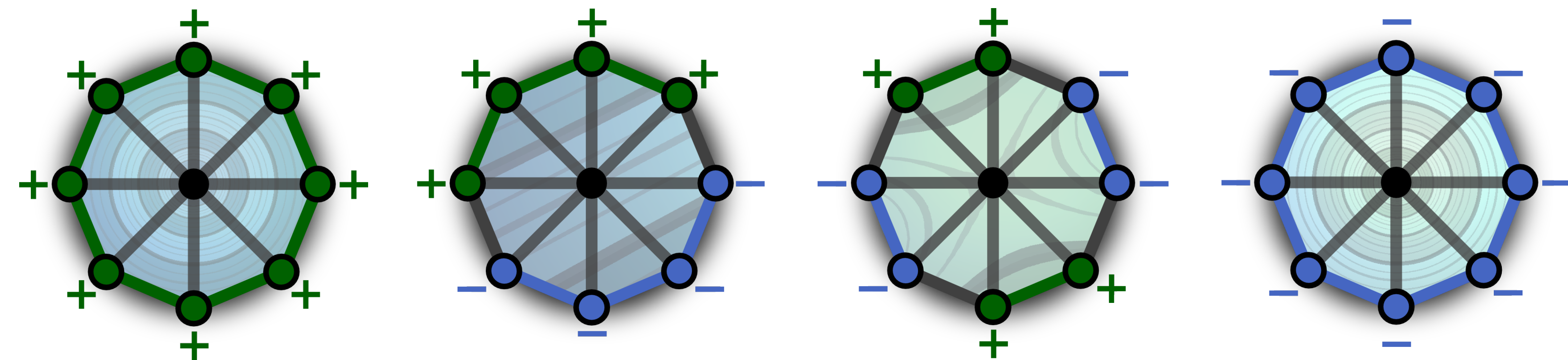
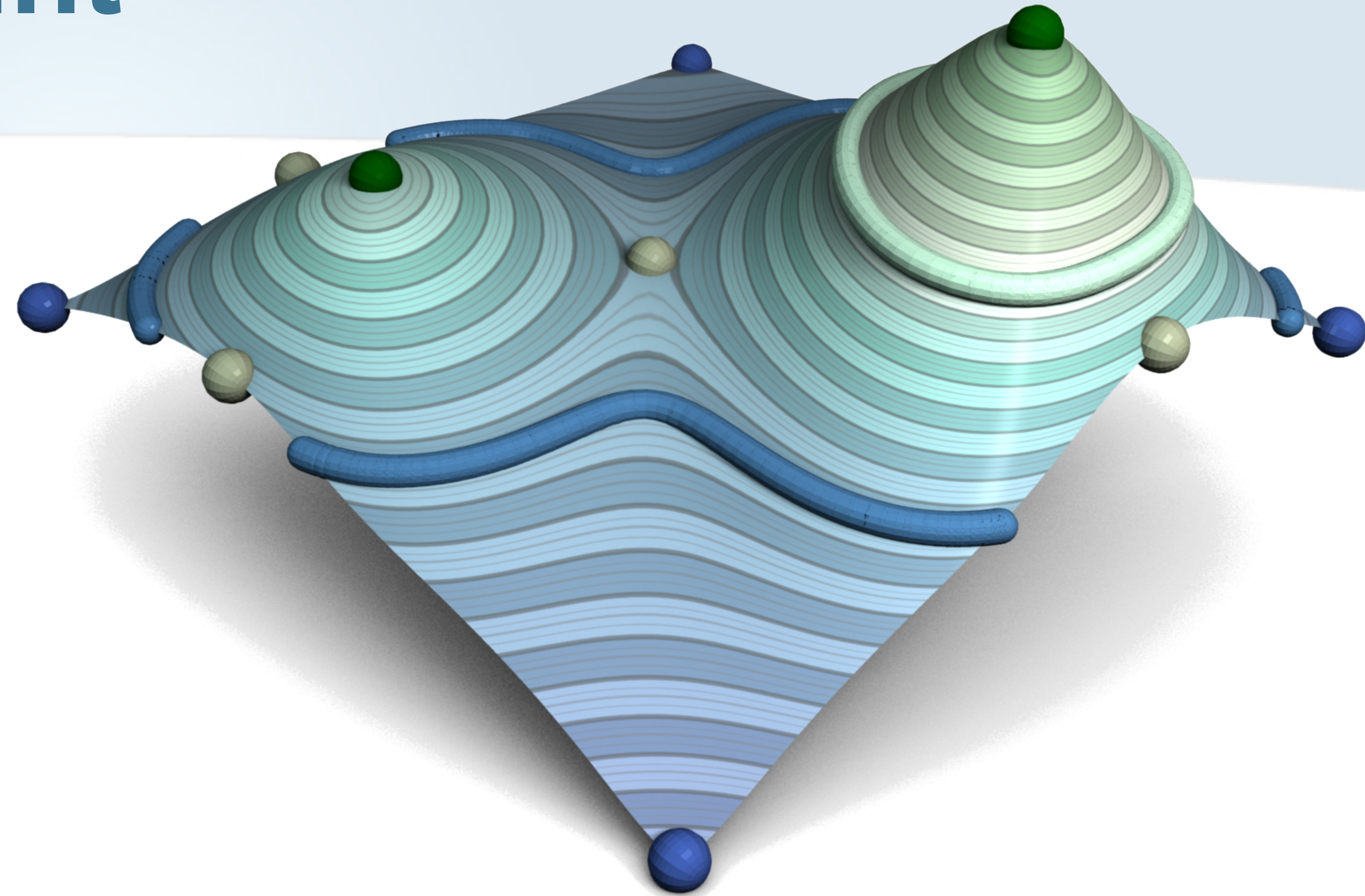
Notion of critical point

- Combinatorial identification
 - Minimum
 - Empty lower link
 - Maximum
 - Empty upper link
 - Regular point
 - Lower and upper links both *simply connected*



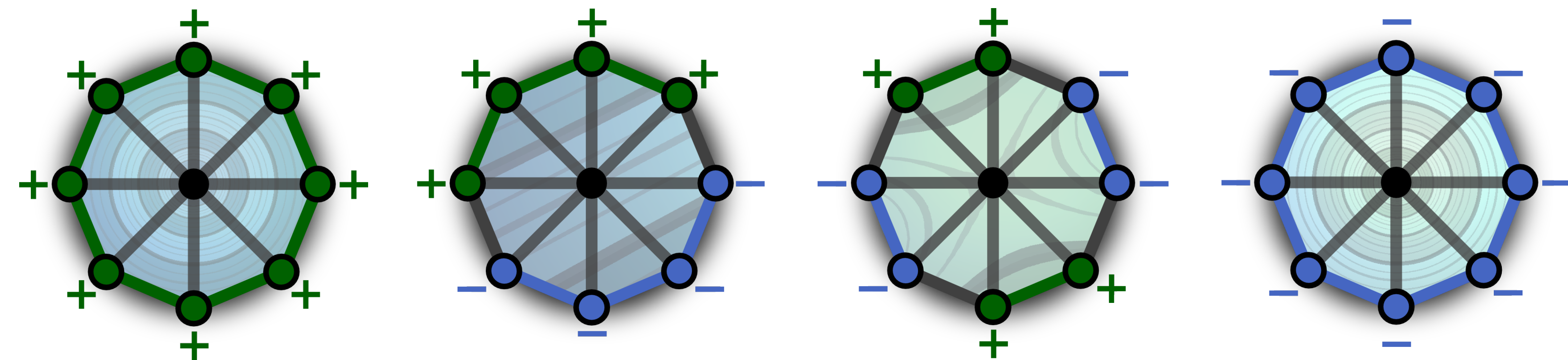
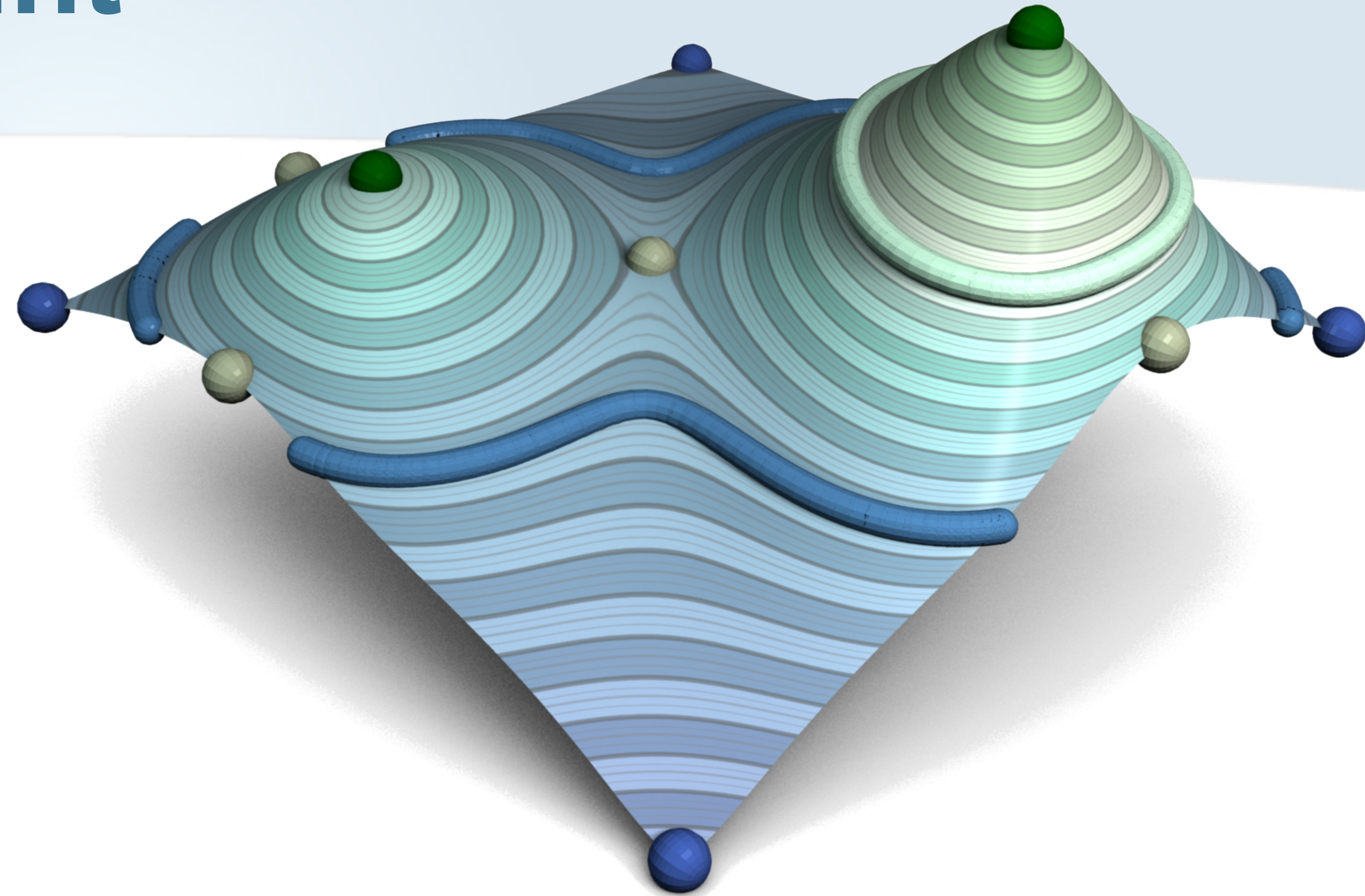
Notion of critical point

- Combinatorial identification
 - Everything else



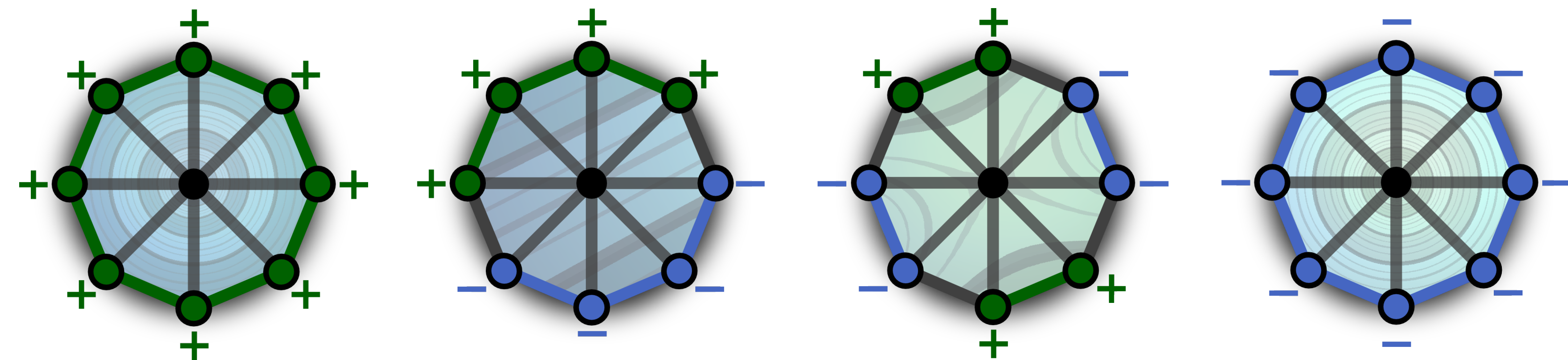
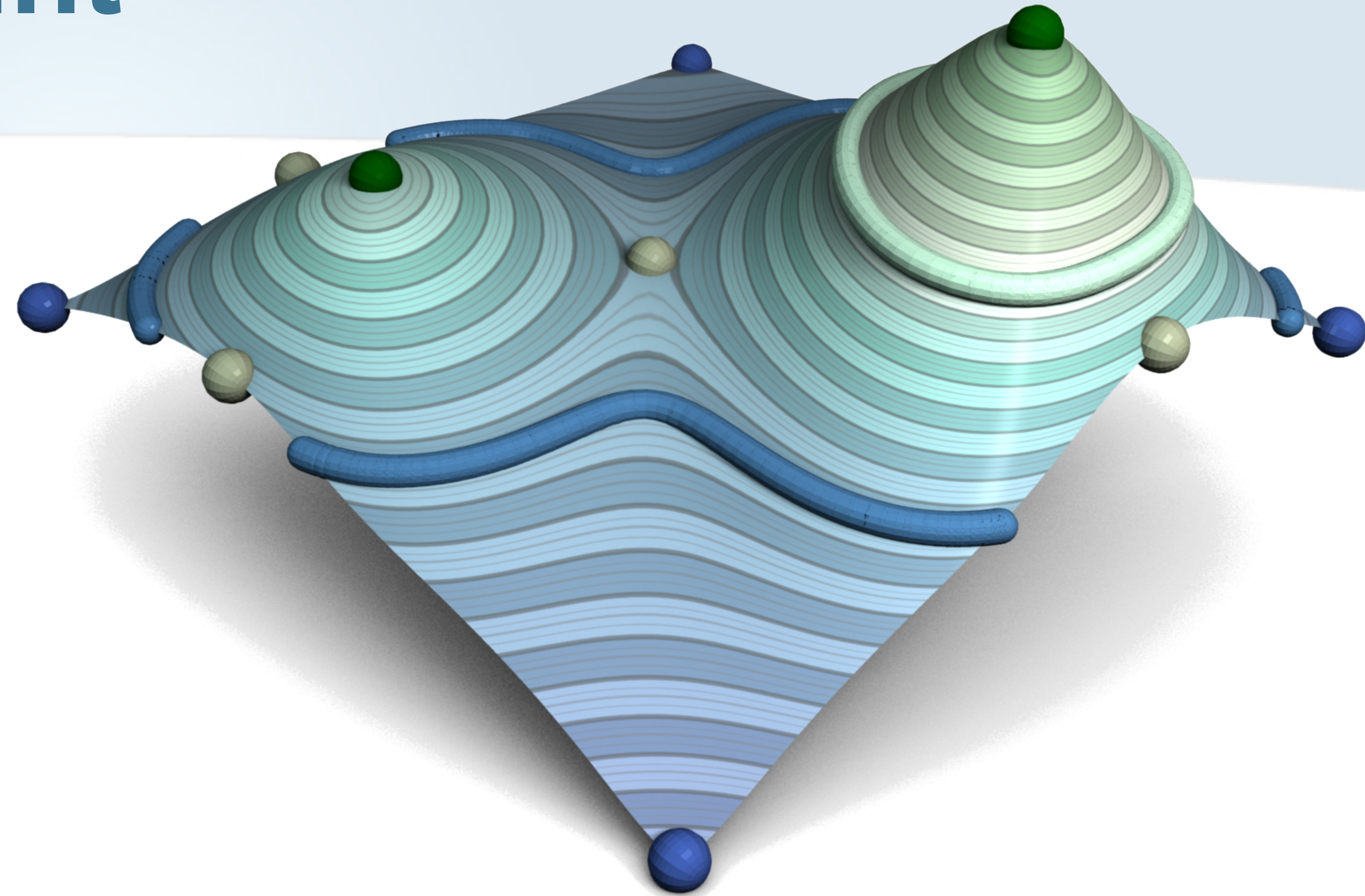
Notion of critical point

- Combinatorial identification
 - Everything else
 - Saddle



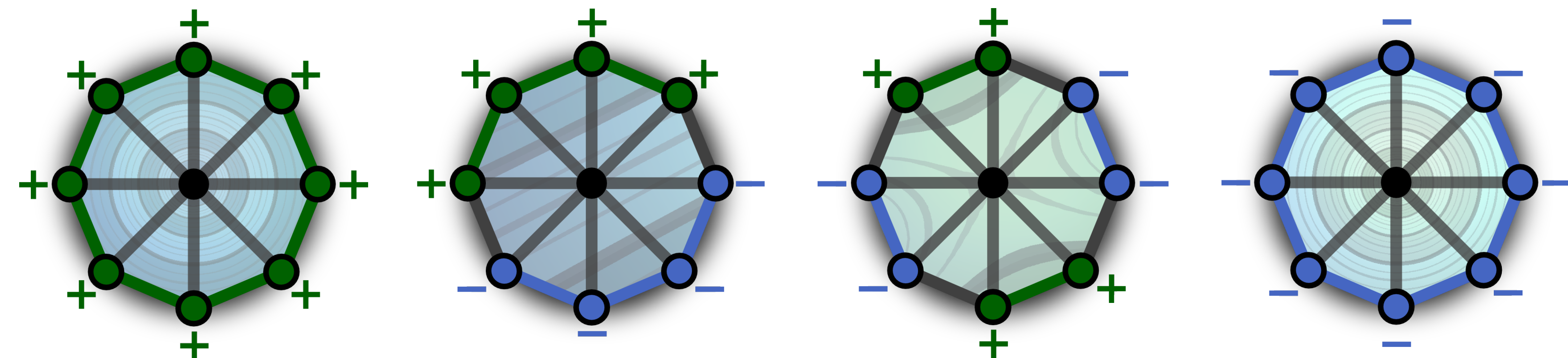
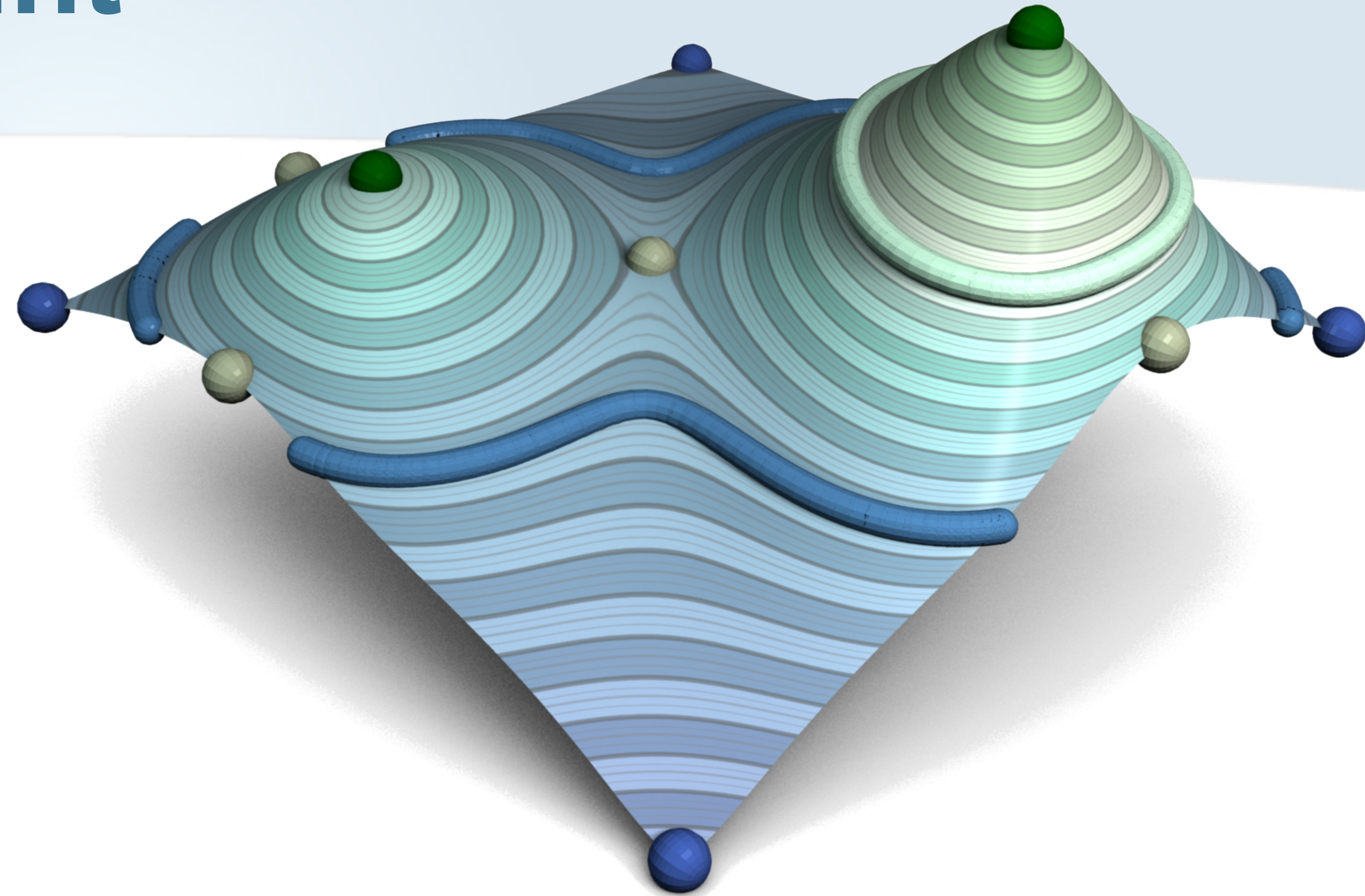
Notion of critical point

- Combinatorial identification
 - Everything else
 - Saddle
- Works in arbitrary dimension



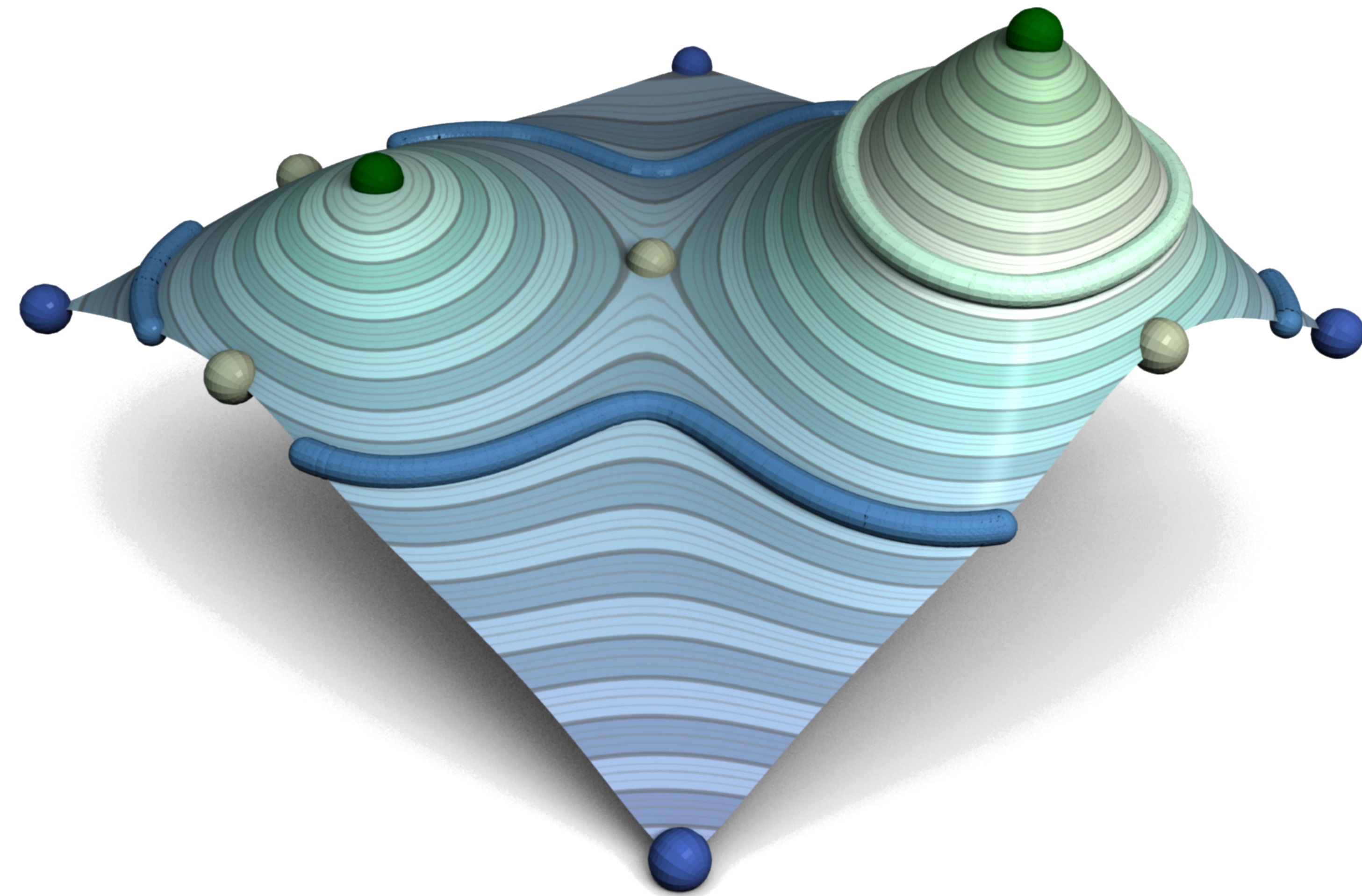
Notion of critical point

- Combinatorial identification
 - Everything else
 - Saddle
- Works in arbitrary dimension
- Value of a critical point
 - *Critical value*



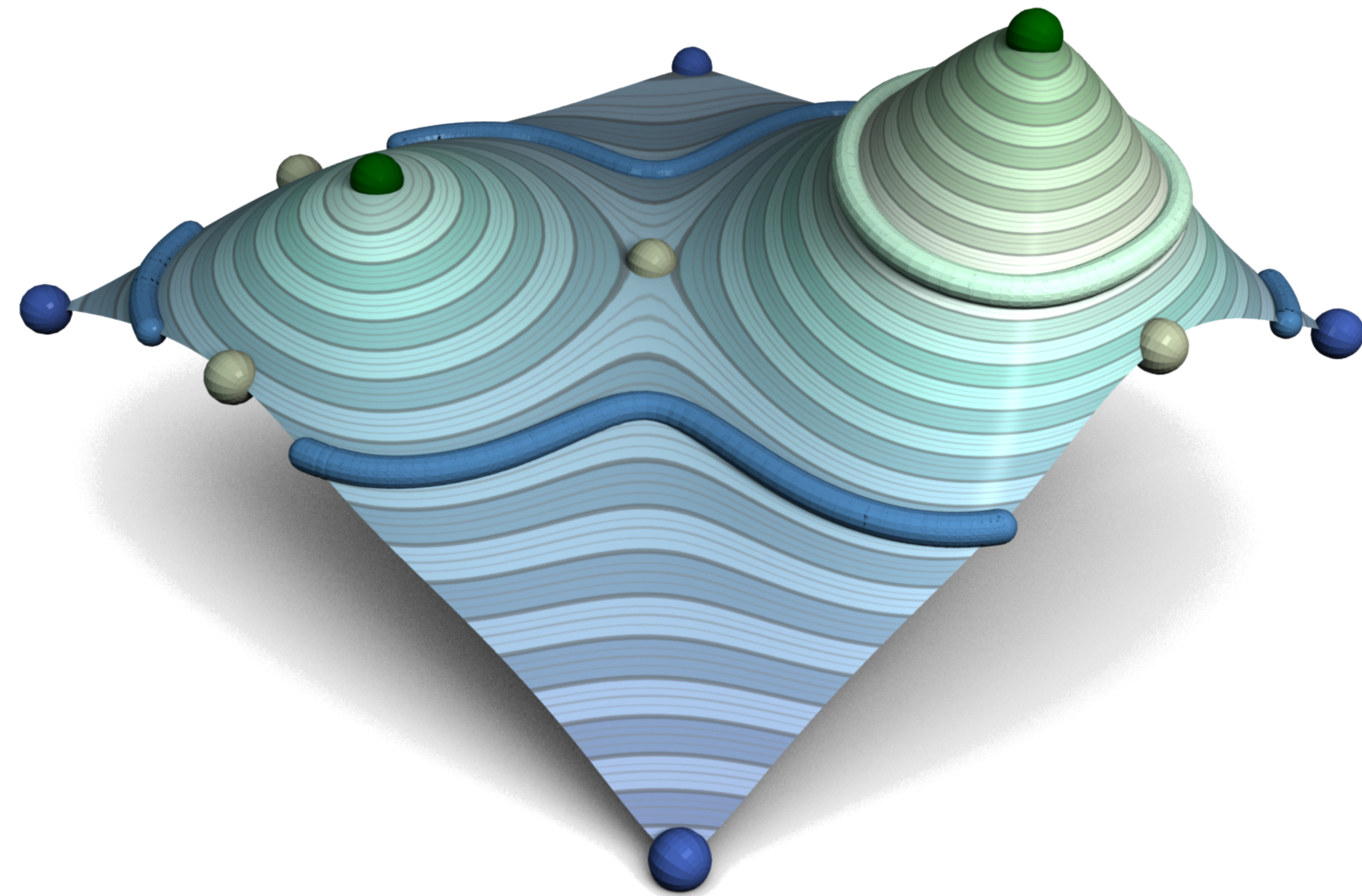
Level sets

- Given a domain \mathcal{D} of dimension d
- Level set
 - $f^{-1}(i) = \{p \in \mathcal{D} / f(p) = i\}$



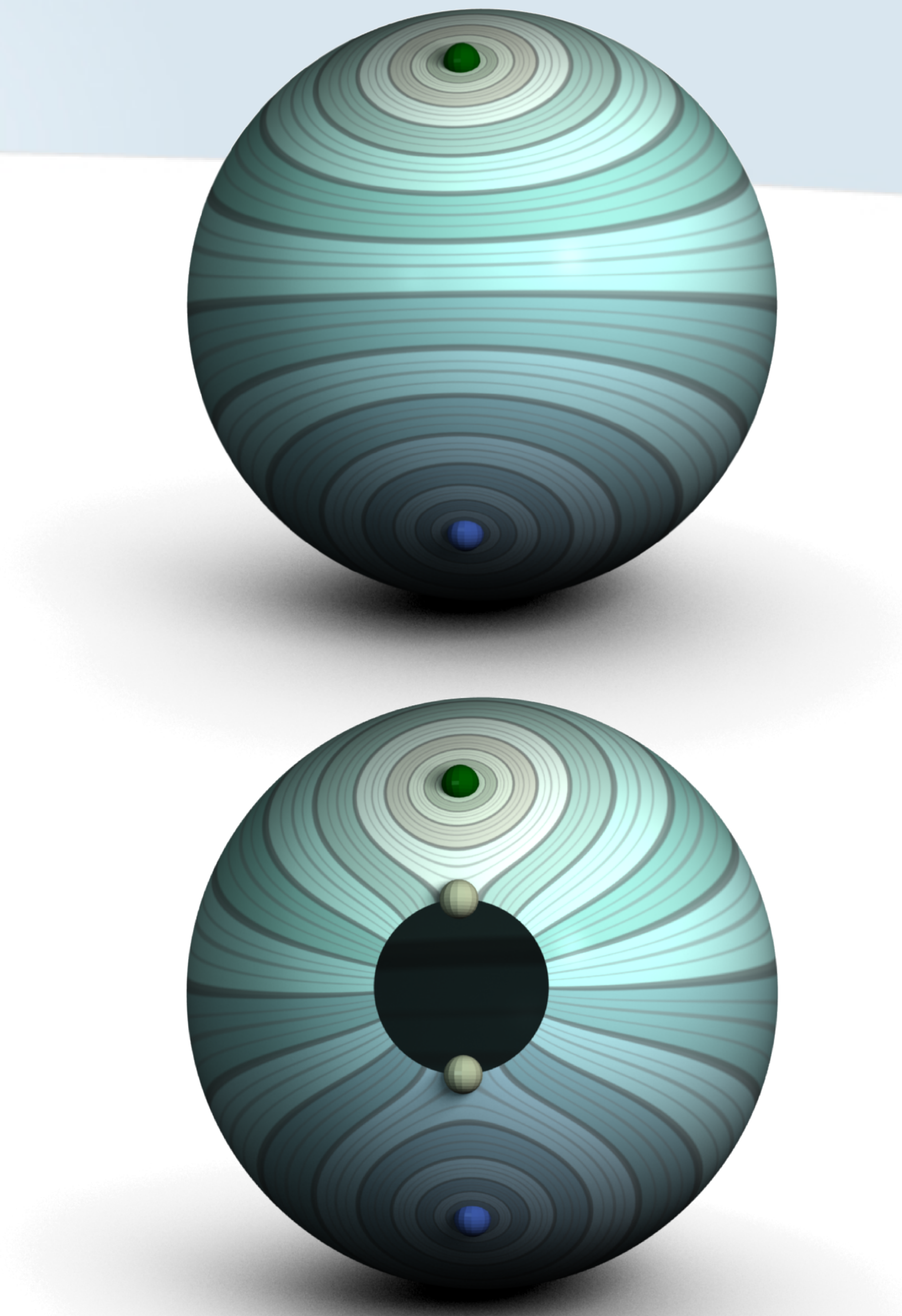
Level sets

- Given a domain \mathcal{D} of dimension d
 - Level set
 - $f^{-1}(i) = \{p \in \mathcal{D} / f(p) = i\}$
 - If i is not a critical value
 - $f^{-1}(i)$ is a $(d-1)$ manifold



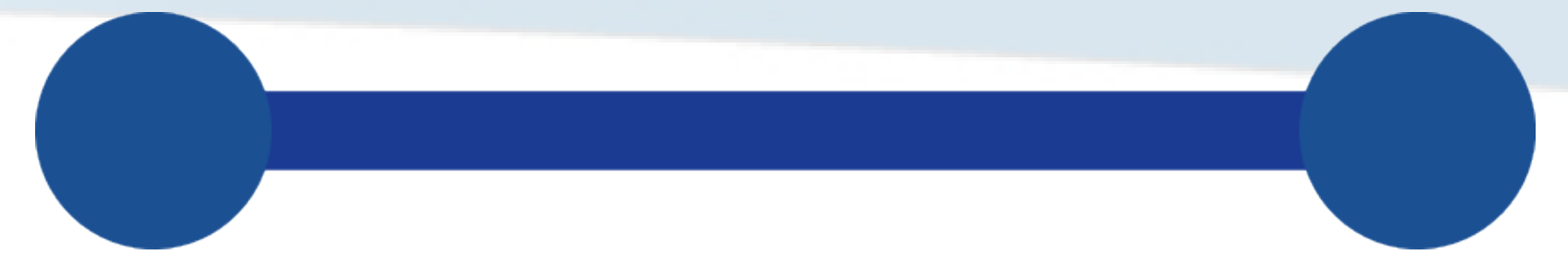
Level sets

- Given a domain \mathcal{D} of dimension d
 - Level set
 - $f^{-1}(i) = \{p \in \mathcal{D} \mid f(p) = i\}$
 - If i is not a critical value
 - $f^{-1}(i)$ is a $(d-1)$ manifold
- If \mathcal{D} is closed, $f^{-1}(i)$ is closed
 - Otherwise it may be open

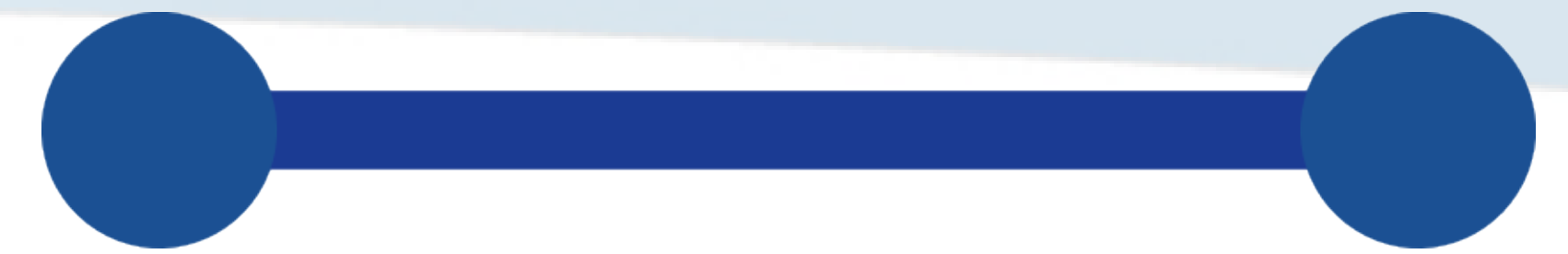


Level set in a 1-simplex

- Let \mathcal{D} be a single edge
 - $f(v_0)$
 - $f(v_1)$
 - $f(v_0) < f(v_1)$

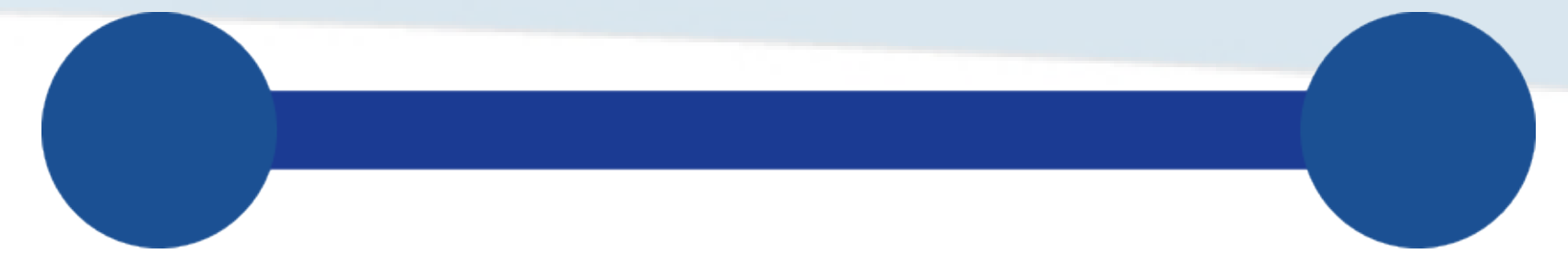


Level set in a 1-simplex



- Let \mathcal{D} be a single edge
 - $f(v_0)$
 - $f(v_1)$
 - $f(v_0) < f(v_1)$
- Let i be an isovalue

Level set in a 1-simplex



- Let \mathcal{D} be a single edge
 - $f(v_0)$
 - $f(v_1)$
 - $f(v_0) < f(v_1)$
- Let i be an isovalue
 - $f^{-1}(i) = \{p \in \mathcal{D} \mid f(p) = i\}$
 - 0-manifold

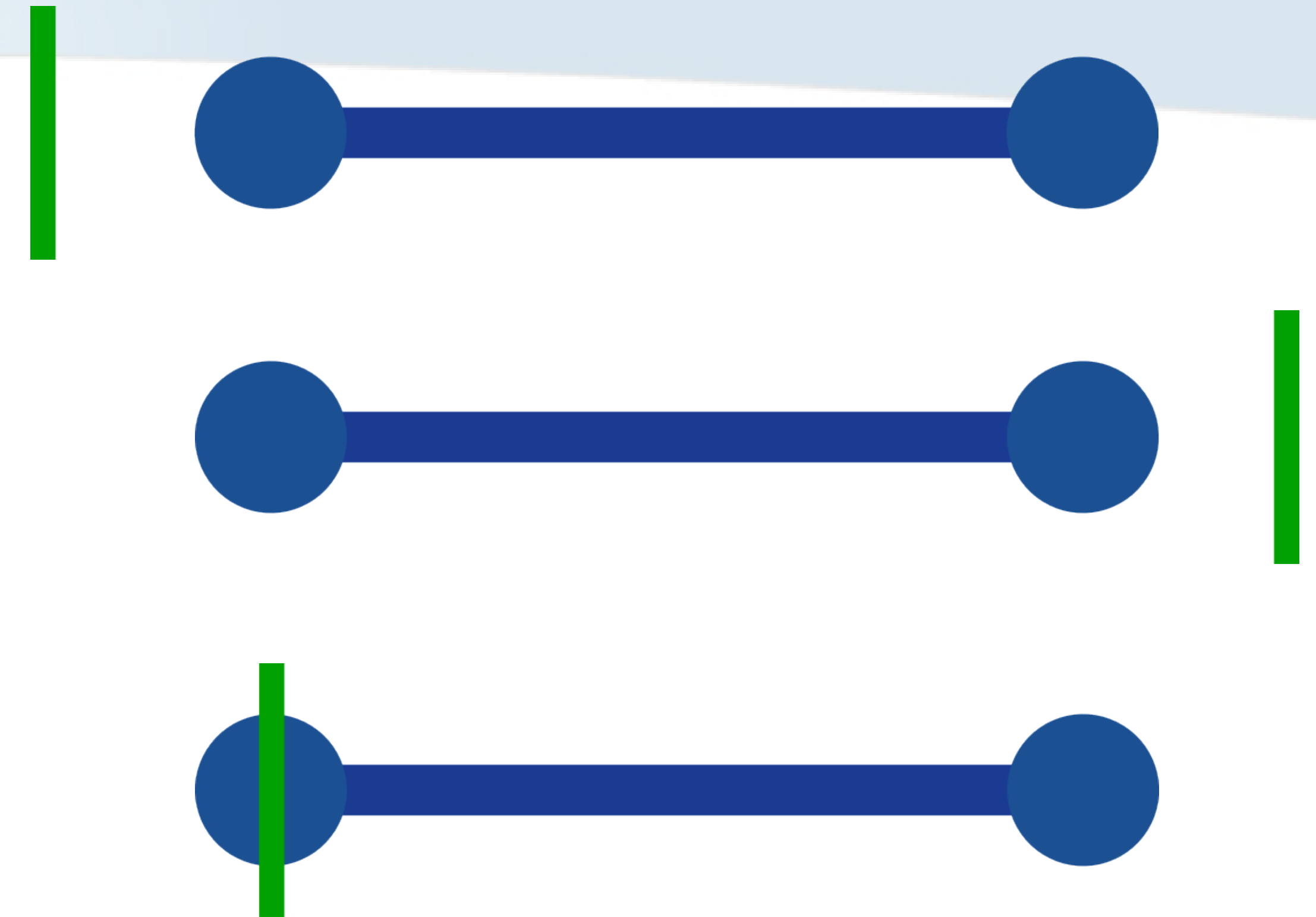
Level set in a 1-simplex

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- Let i be an isovalue
 - $f^{-1}(i) = \{p \in \mathcal{D} \mid f(p) = i\}$
 - 0-manifold
 - If intersection, **3 cases only**



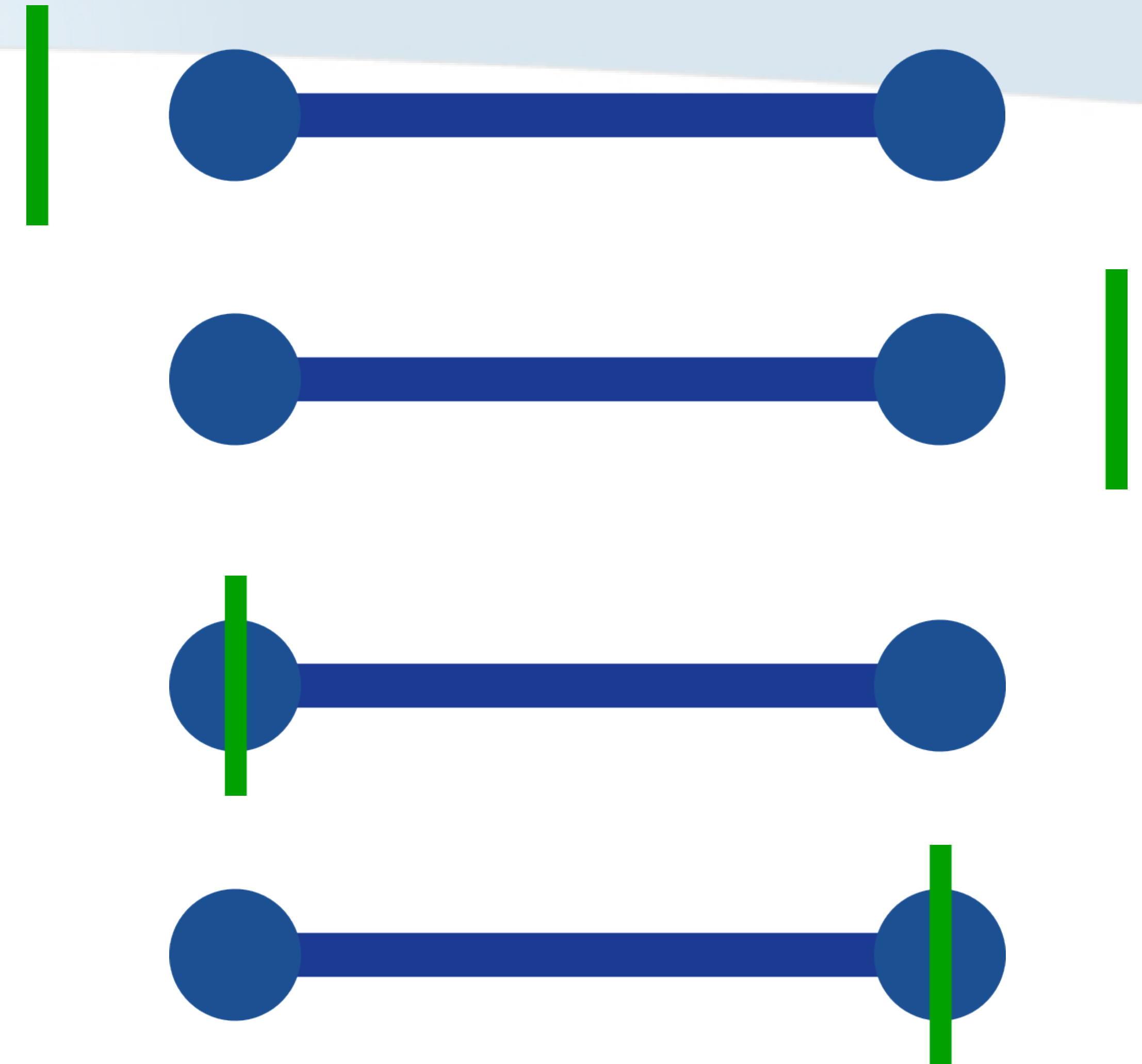
Level set in a 1-simplex

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 - 0-manifold
 - If intersection, **3 cases only**



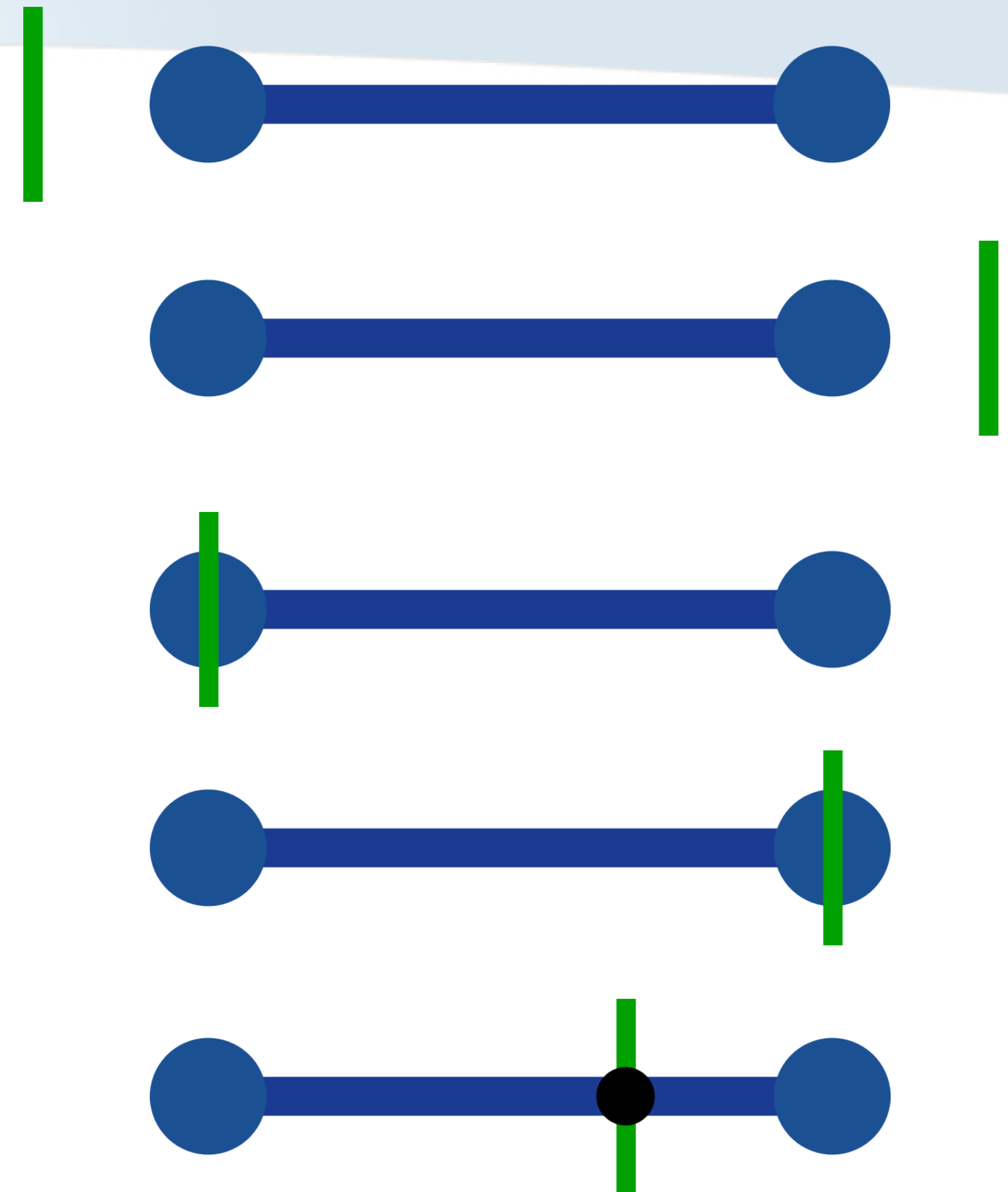
Level set in a 1-simplex

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 - 0-manifold
 - If intersection, **3 cases only**



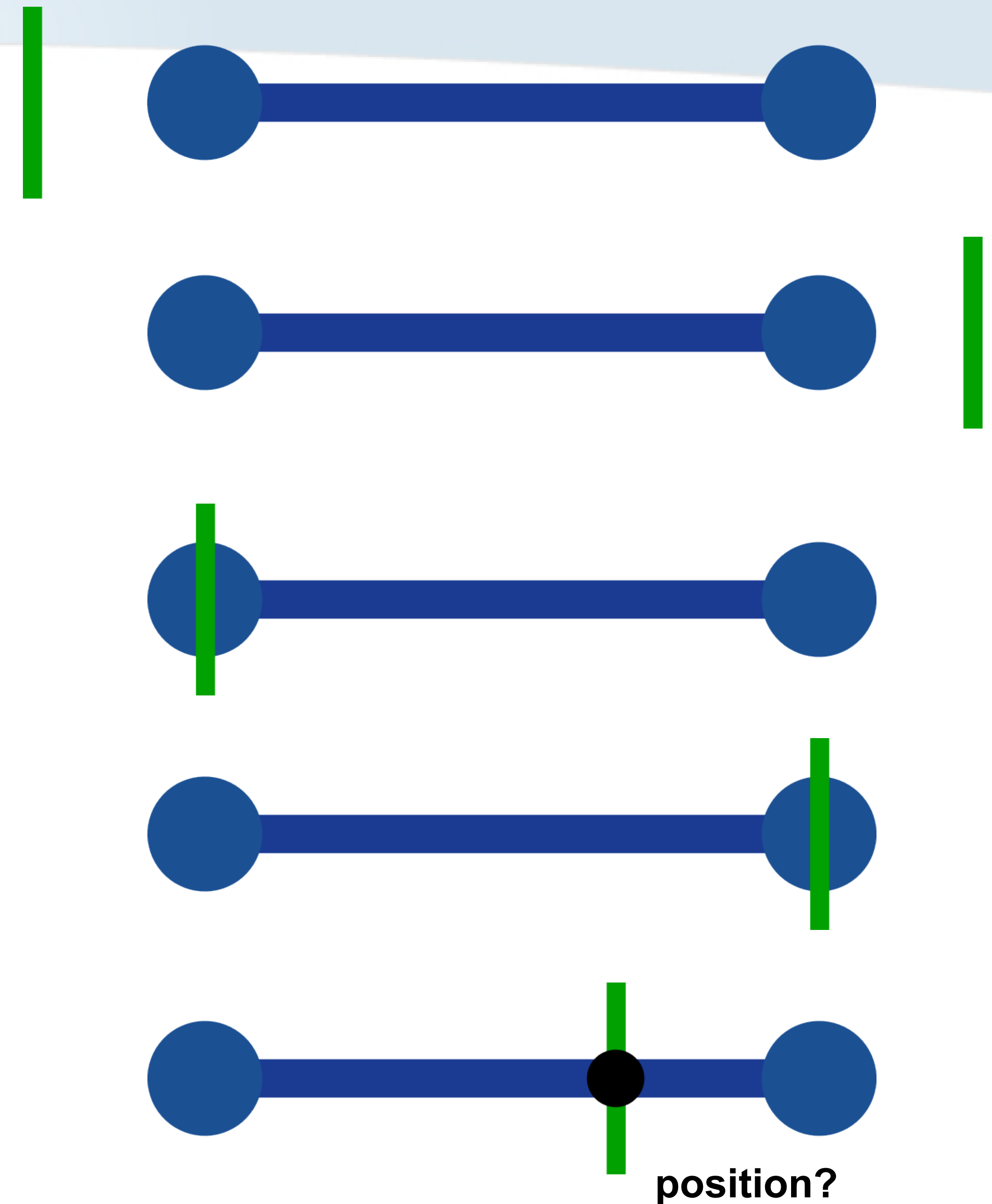
Level set in a 1-simplex

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 - 0-manifold
 - If intersection, **3 cases only**



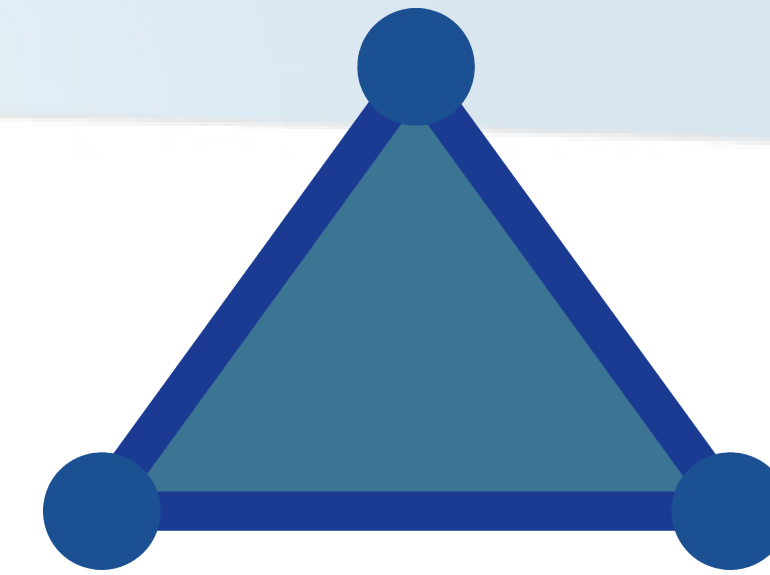
Level set in a 1-simplex

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 - 0-manifold
 - If intersection, **3 cases only**



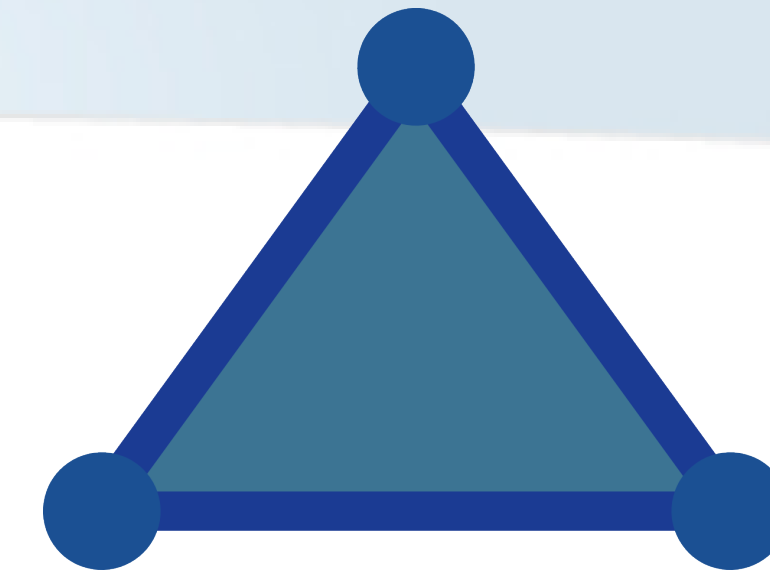
Level set in a 2-simplex

- Let \mathcal{D} be a single triangle
 - $f(v_0), f(v_1), f(v_2)$

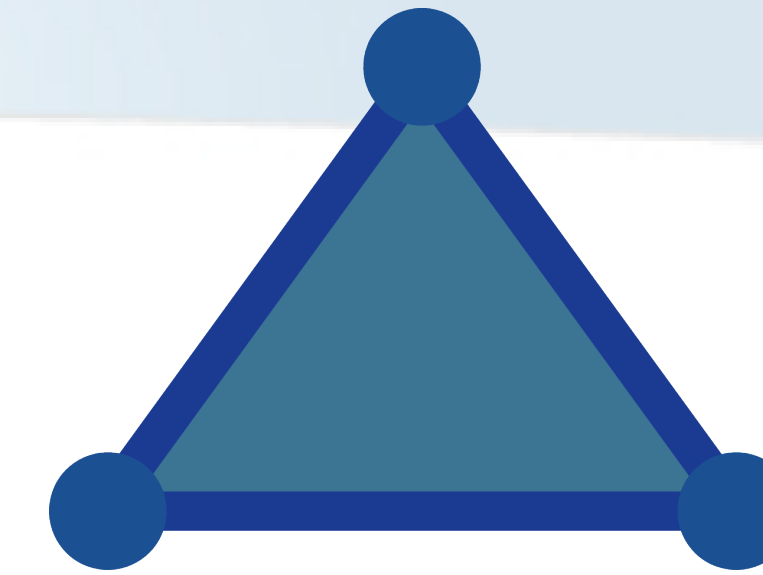


Level set in a 2-simplex

- Let \mathcal{D} be a single triangle
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- Let i be an isovalue
 - $f^{-1}(i) = \{p \in \mathcal{D} / f(p) = i\}$

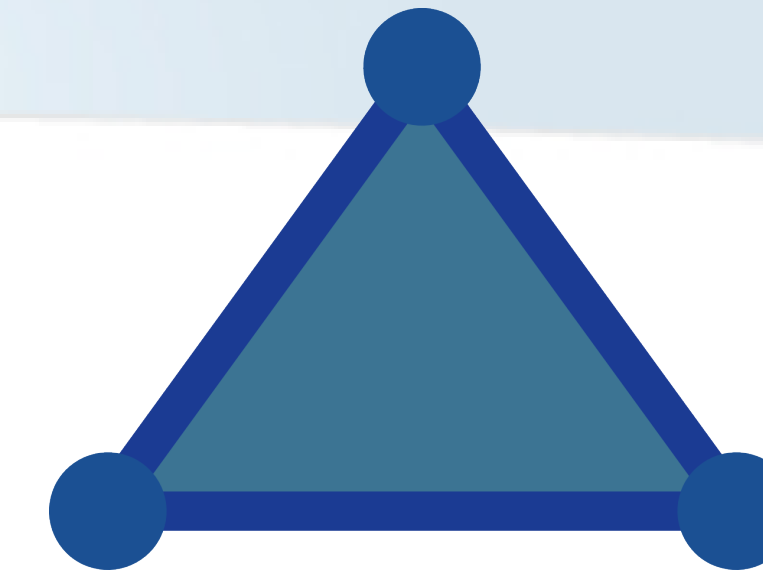


Level set in a 2-simplex



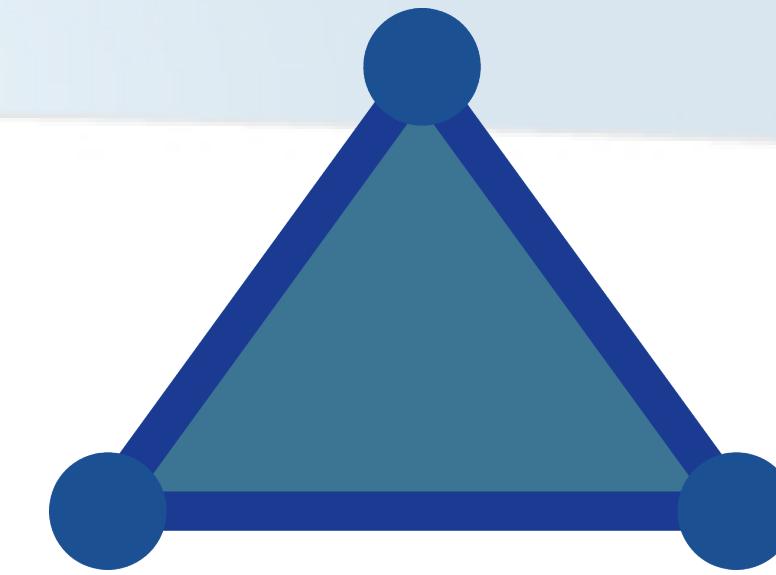
- Let \mathcal{D} be a single triangle
 - $f(v_0), f(v_1), f(v_2)$
- Let i be an isovalue
 - $f^{-1}(i) = \{p \in \mathcal{D} \mid f(p) = i\}$
 - **No critical point inside the triangle!**

Level set in a 2-simplex



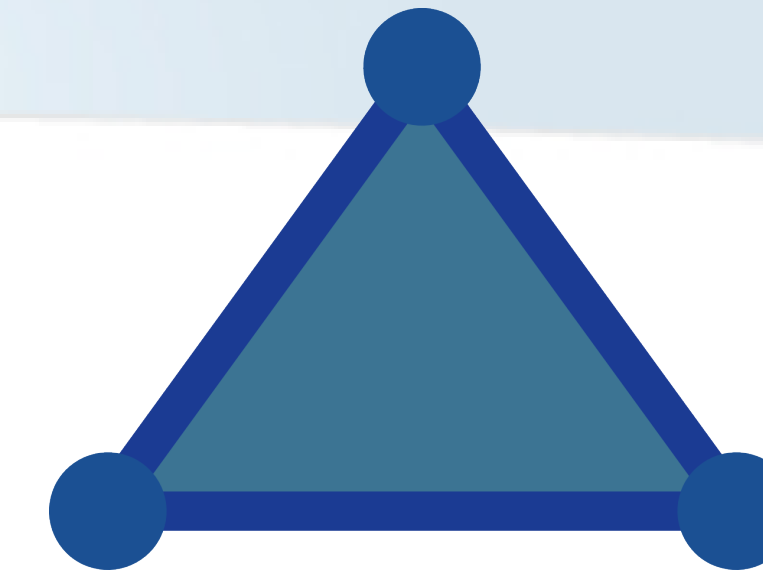
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 - $f^{-1}(i) = \{p \in \mathcal{D} \mid f(p) = i\}$
 - **No critical point inside the triangle!**
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Level set in a 2-simplex



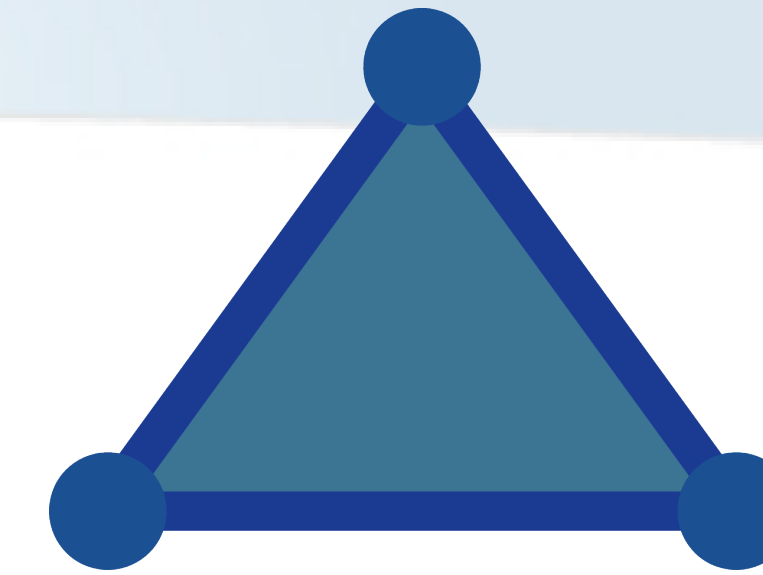
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 - **No critical point inside the triangle!**
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 - Can be computed by only looking at the boundary

Level set in a 2-simplex



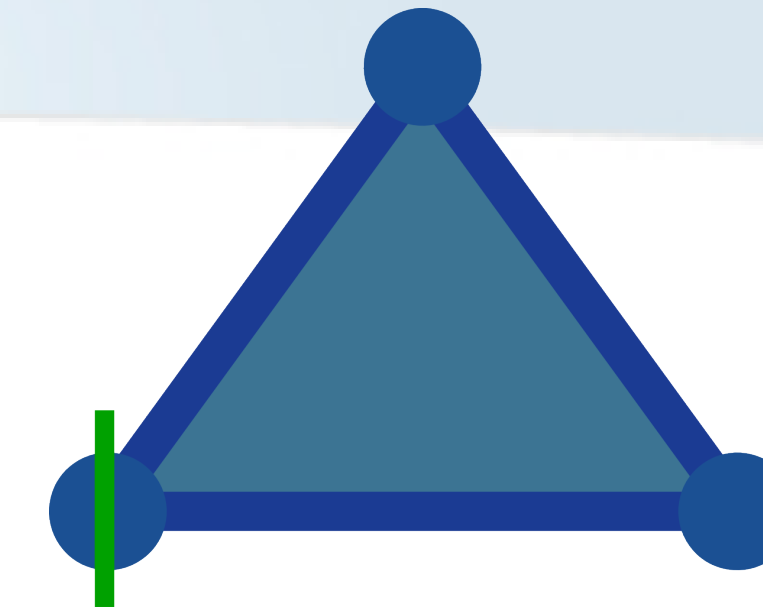
- Let \mathcal{D} be a single triangle
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 - Level sets on edges: boundary of the level set

Level set in a 2-simplex



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 - If edge-intersections, **9 cases only**

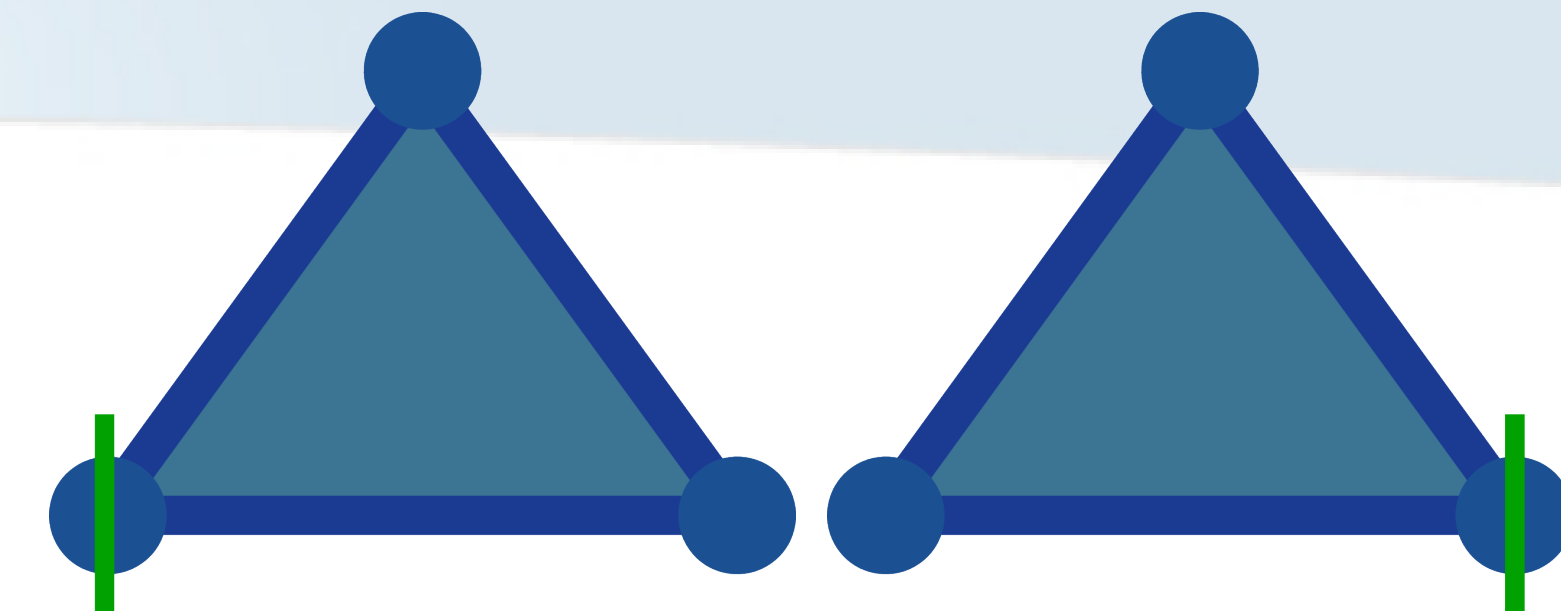
Level set in a 2-simplex



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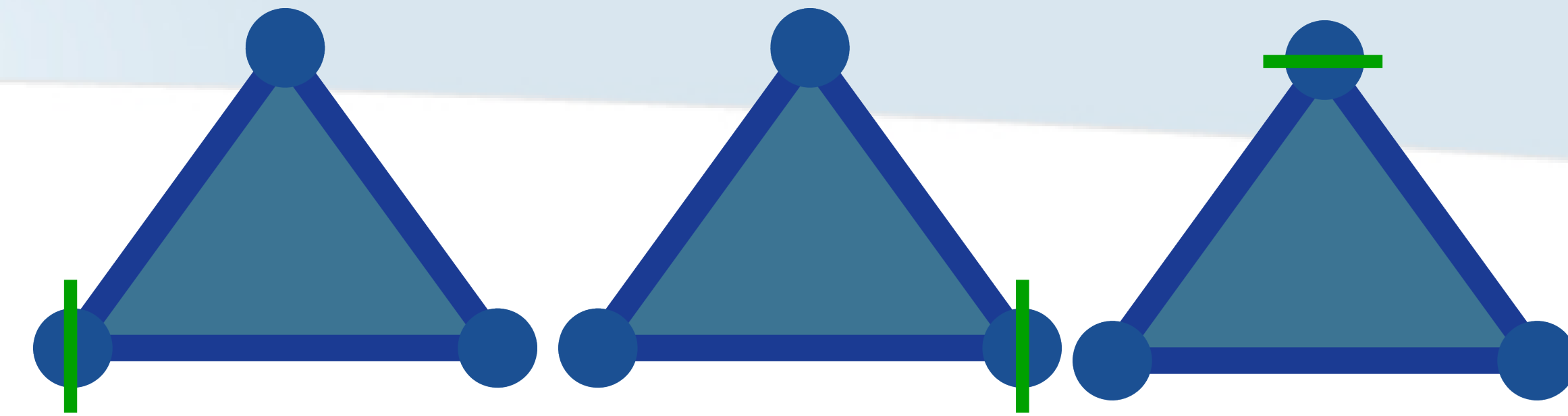
Level set in a 2-simplex

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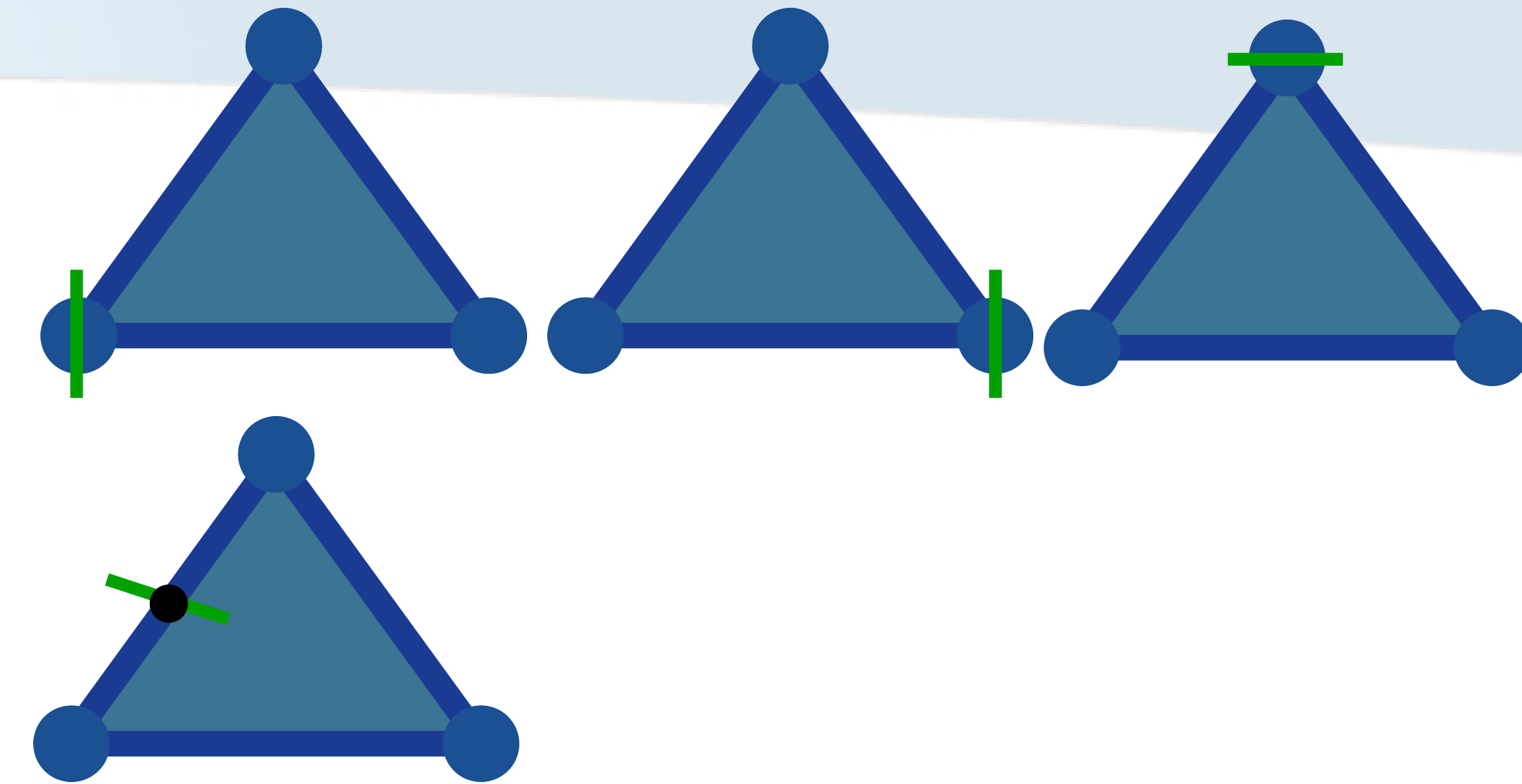
Level set in a 2-simplex

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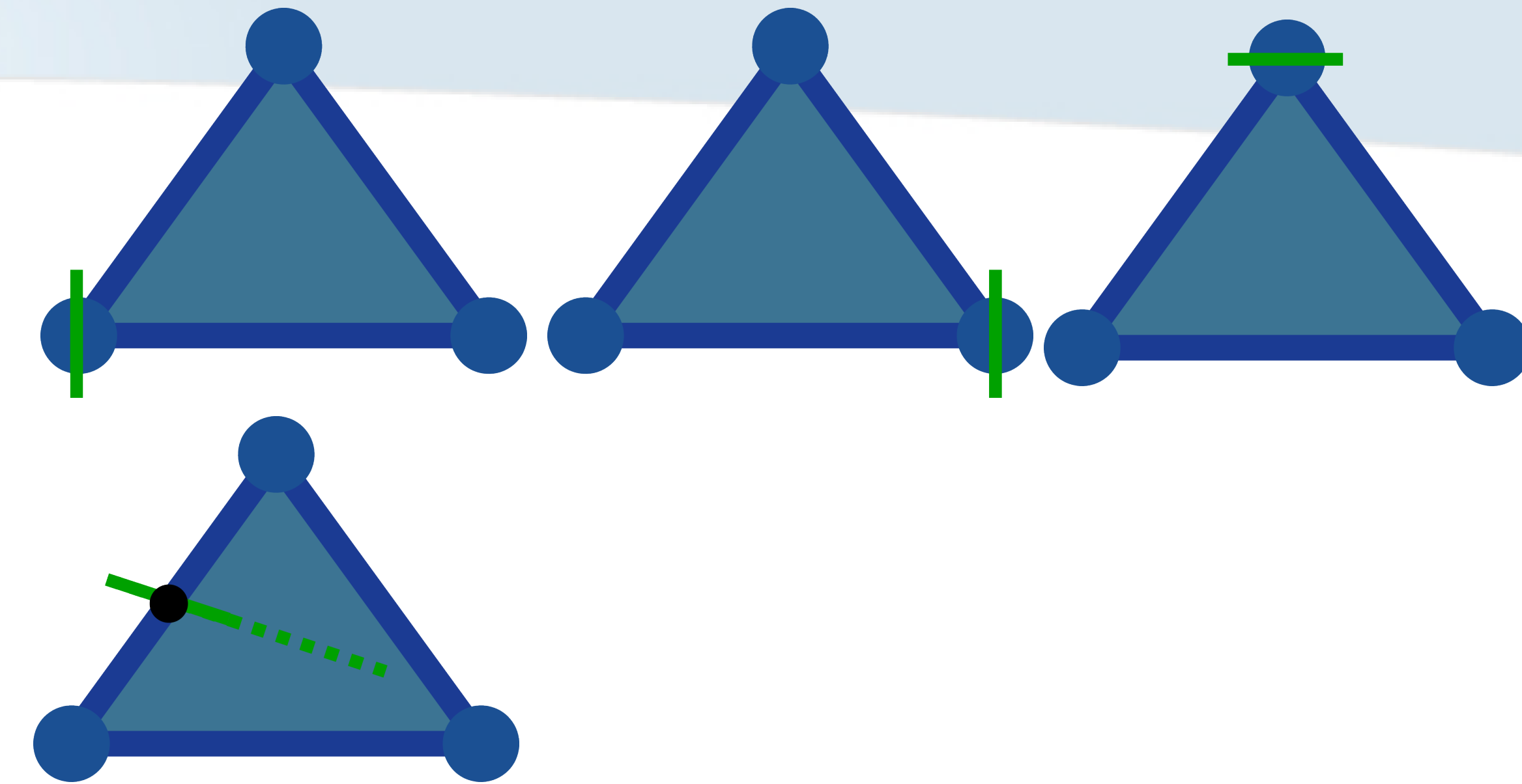
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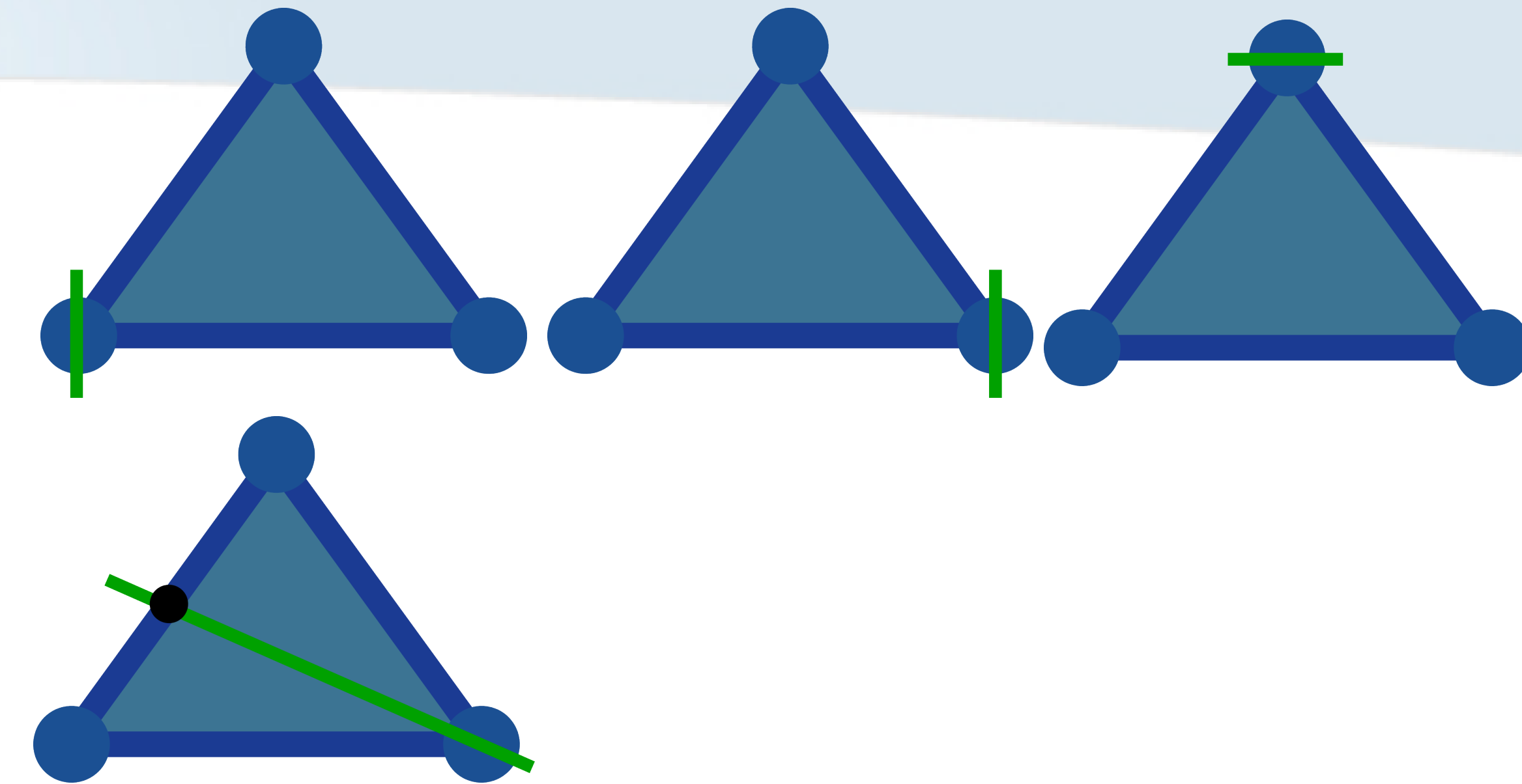
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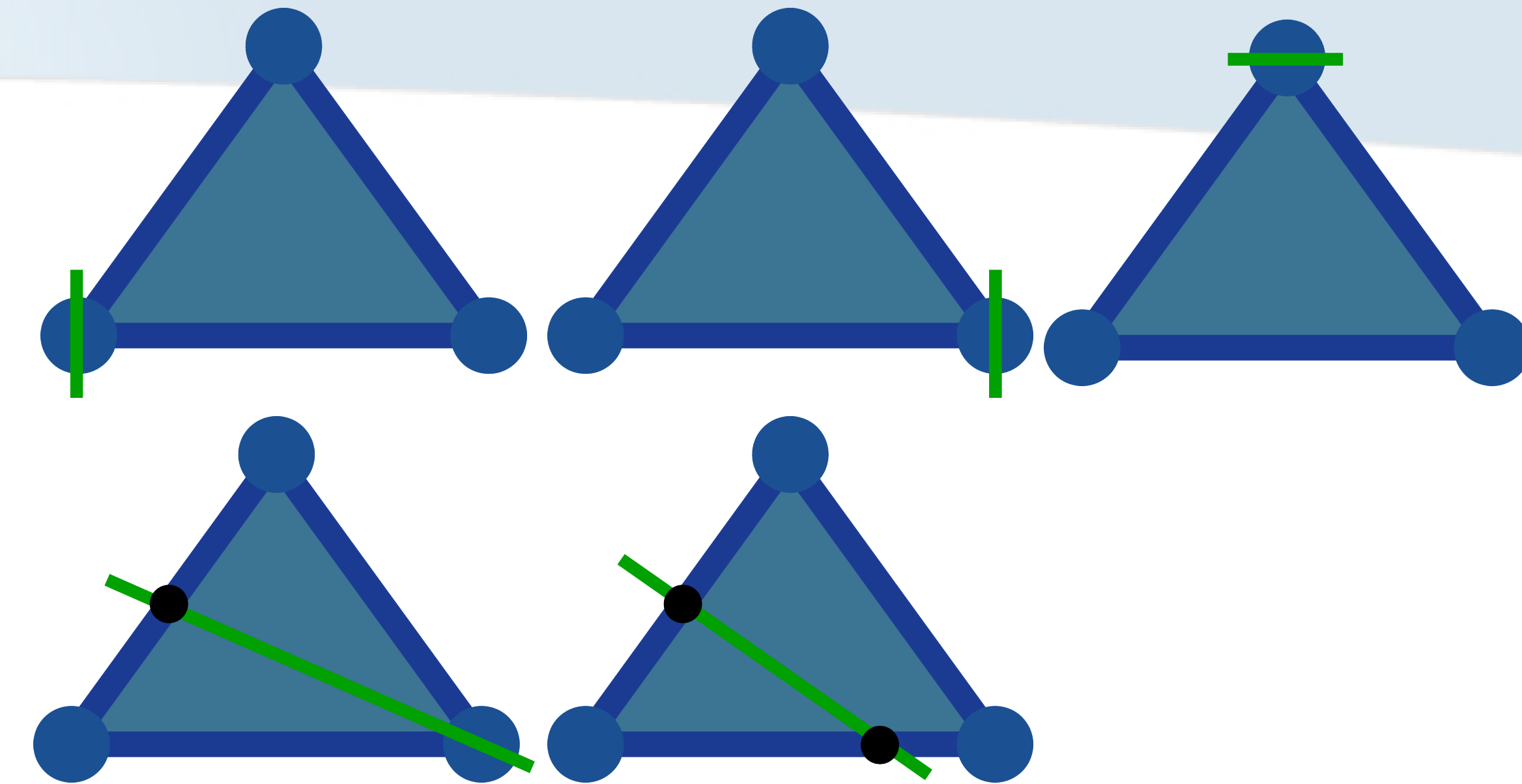
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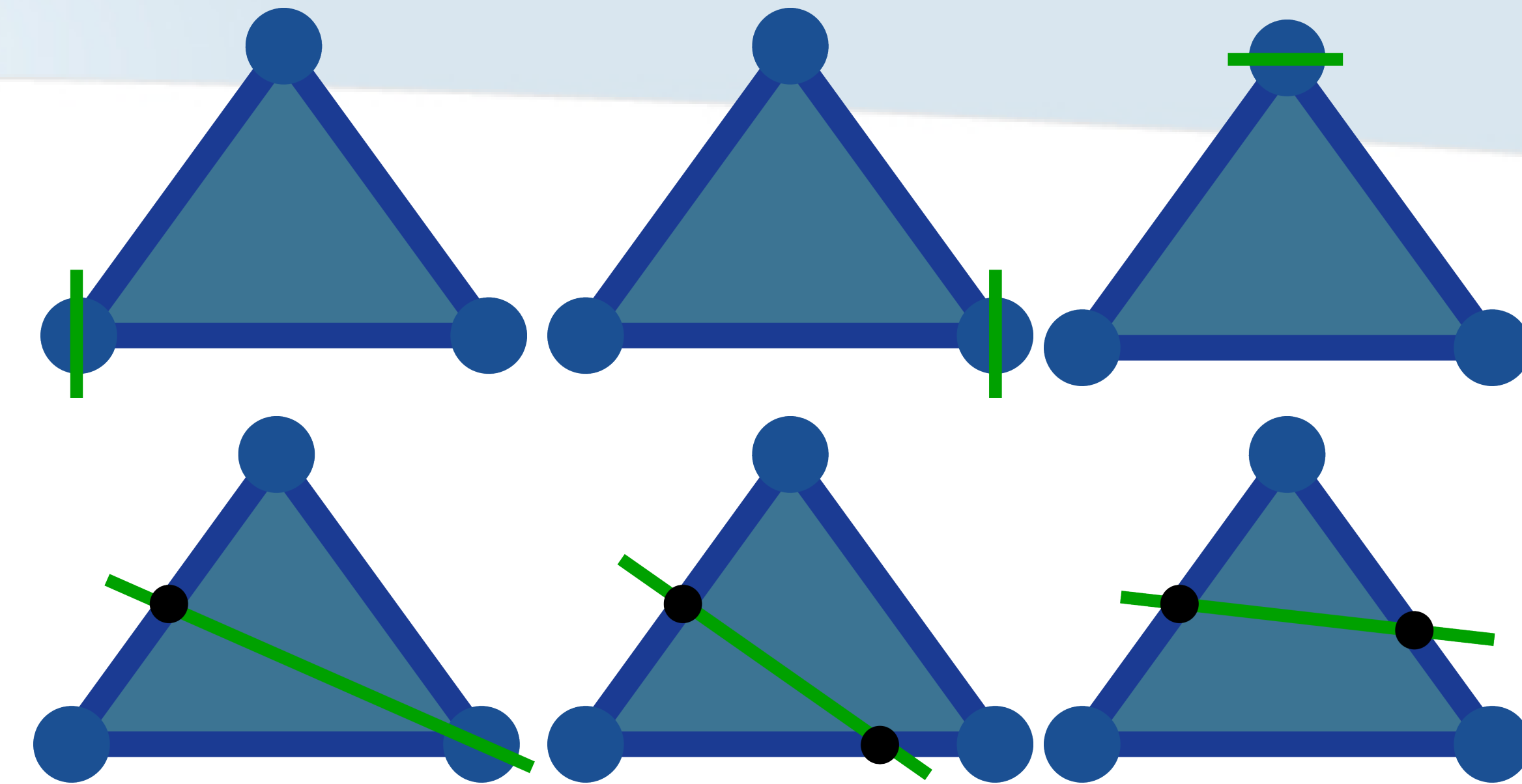
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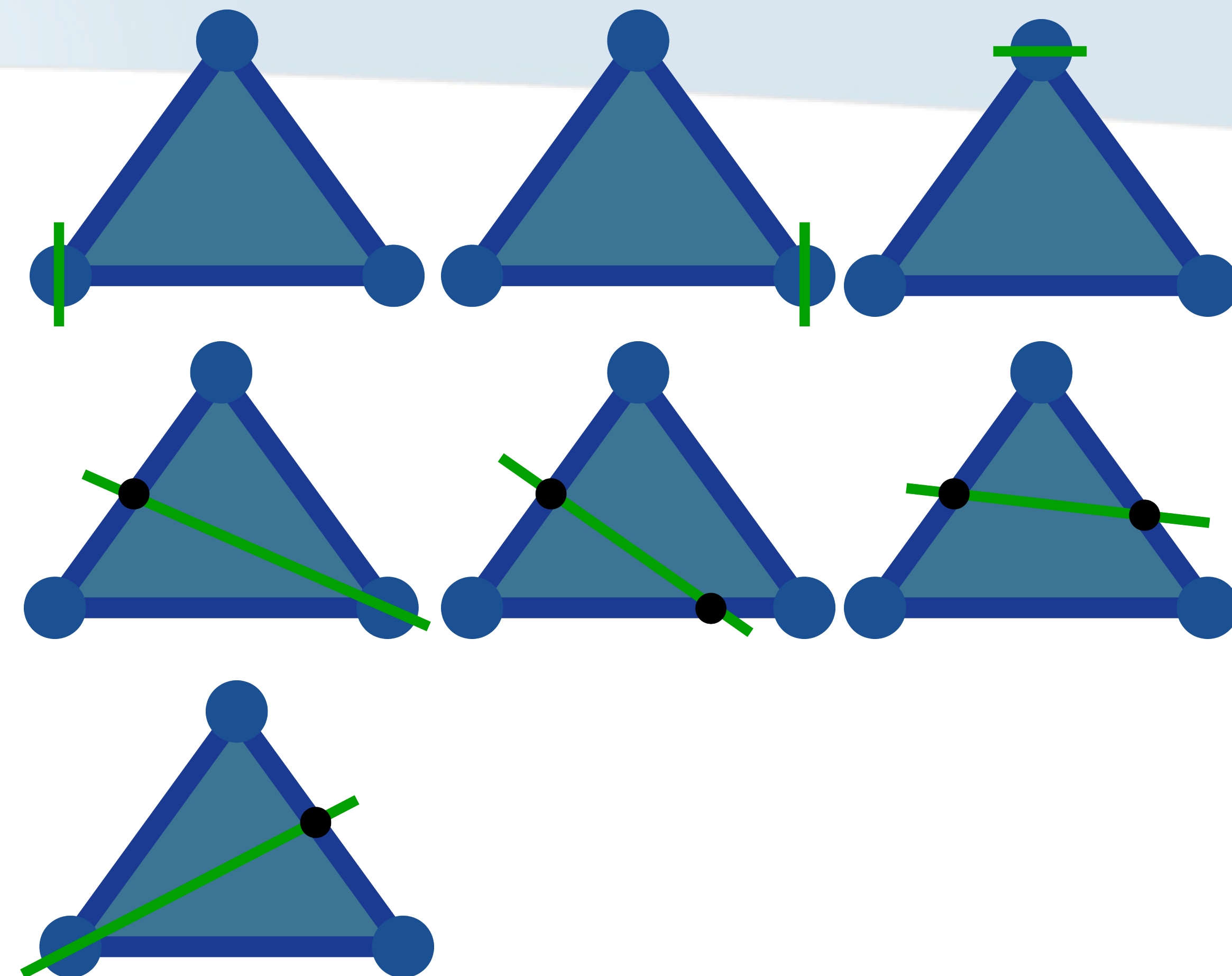
Level set in a 2-simplex

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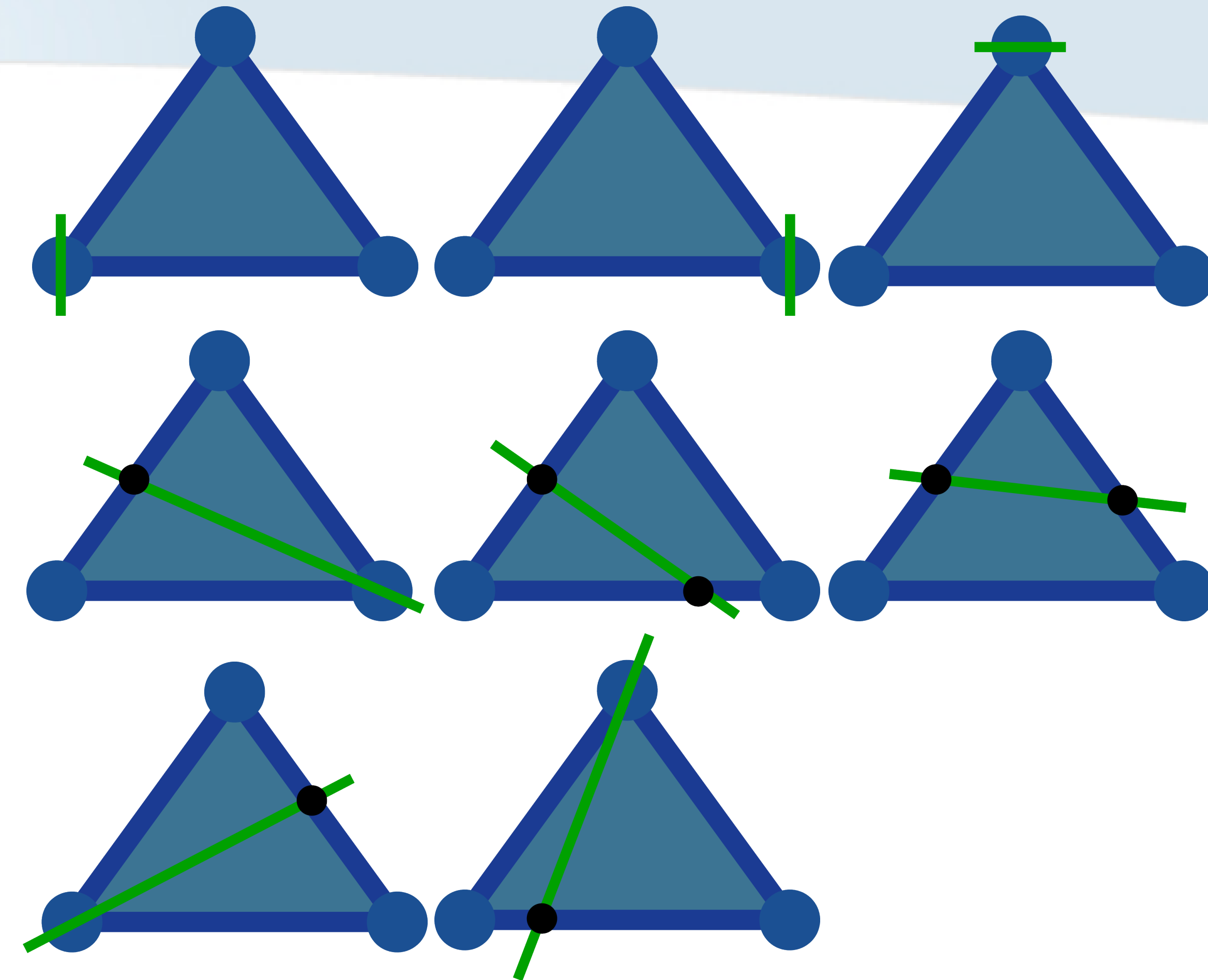
Level set in a 2-simplex

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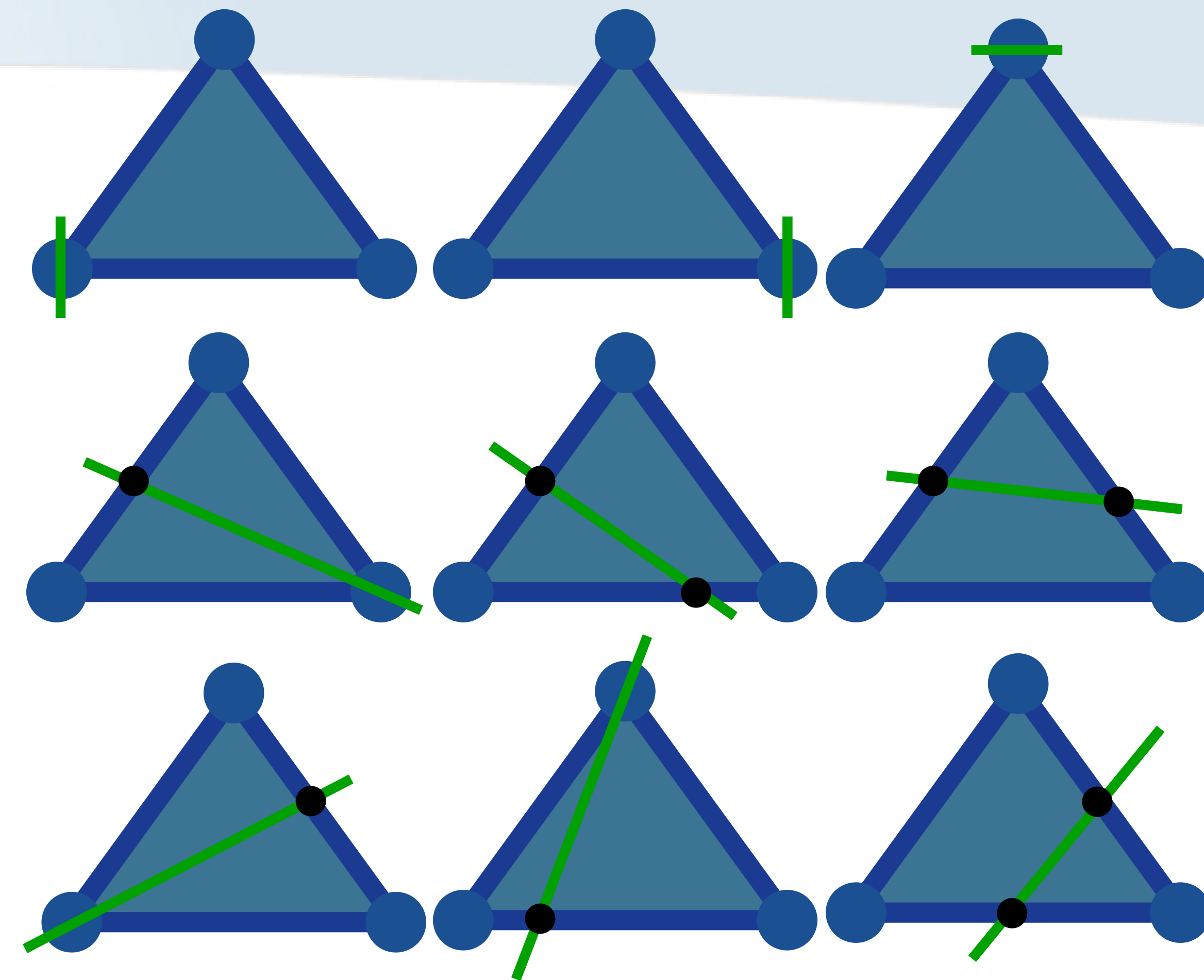
Level set in a 2-simplex

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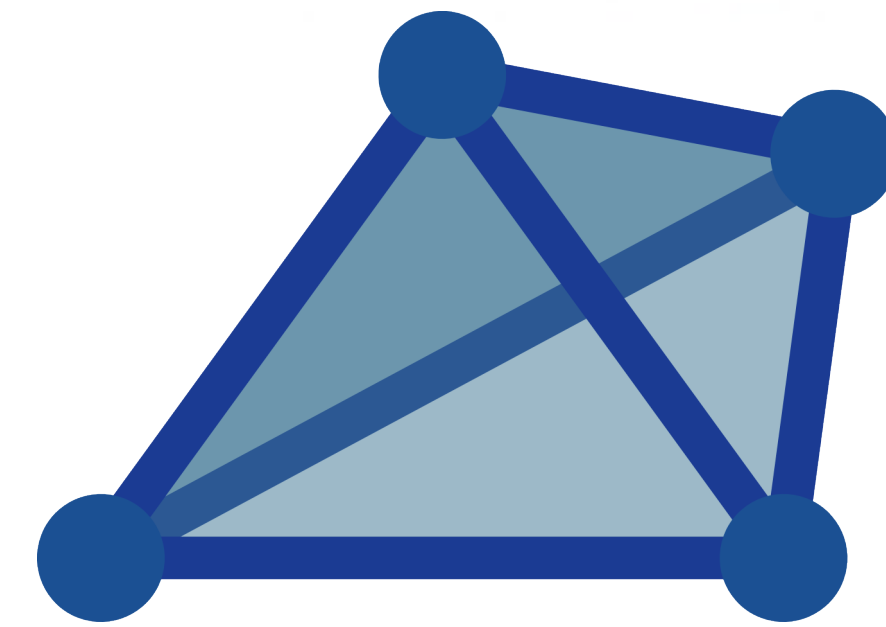
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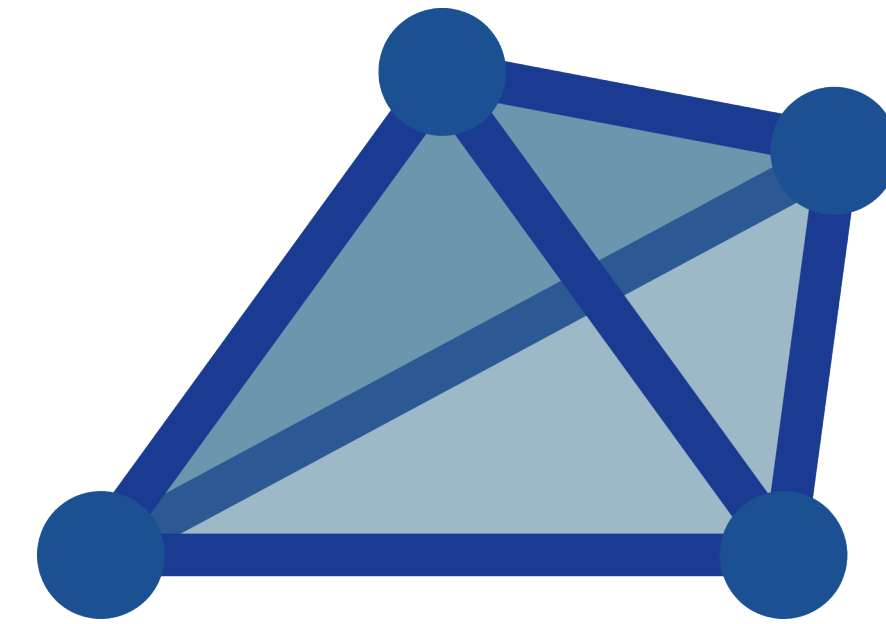
Level set in a 3-simplex

- Let \mathcal{D} be a single tetrahedron
 - $f(v_0), f(v_1), f(v_2), f(v_3)$



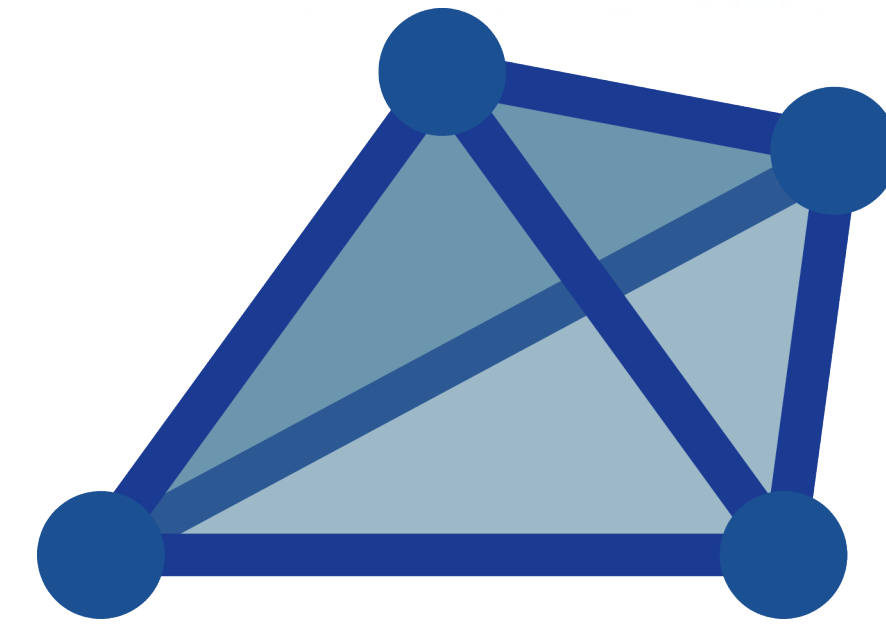
Level set in a 3-simplex

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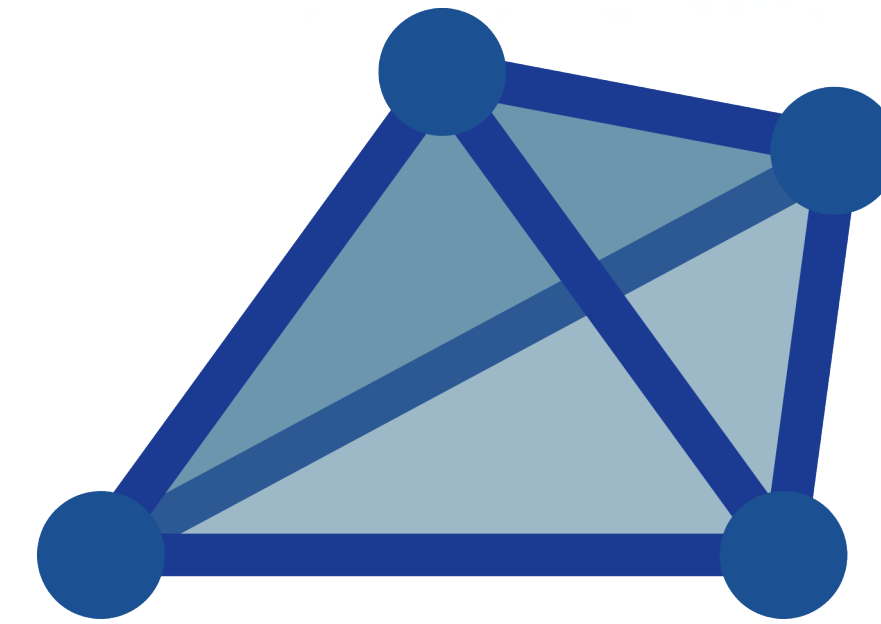
Level set in a 3-simplex

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 - **No critical point inside the tet!**

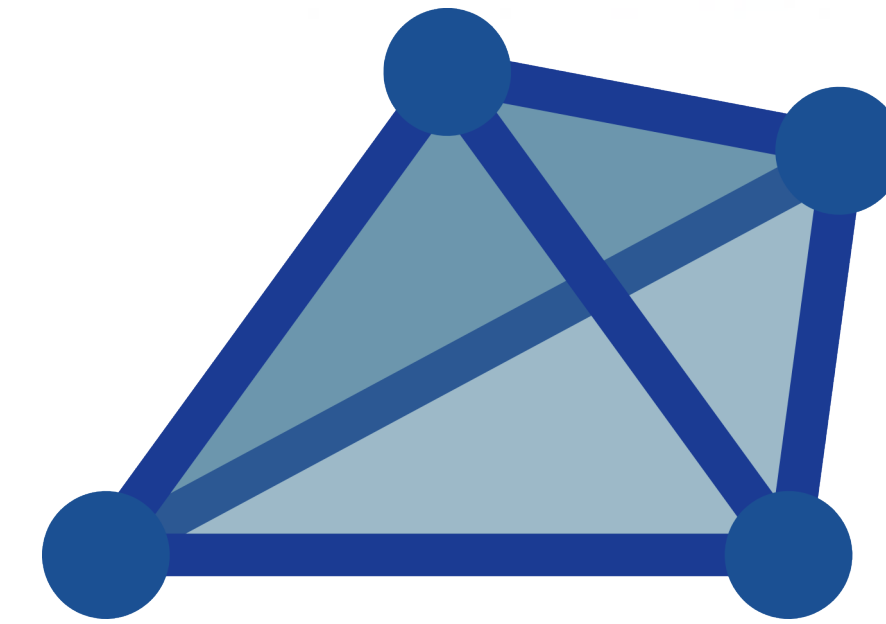


Level set in a 3-simplex

- Let \mathcal{D} be a single tetrahedron
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- Let i be an isovalue
 - $f^{-1}(i) = \{p \in \mathcal{D} \mid f(p) = i\}$
 - **No critical point inside the tet!**
 - Simply connected, open, 2-manifold

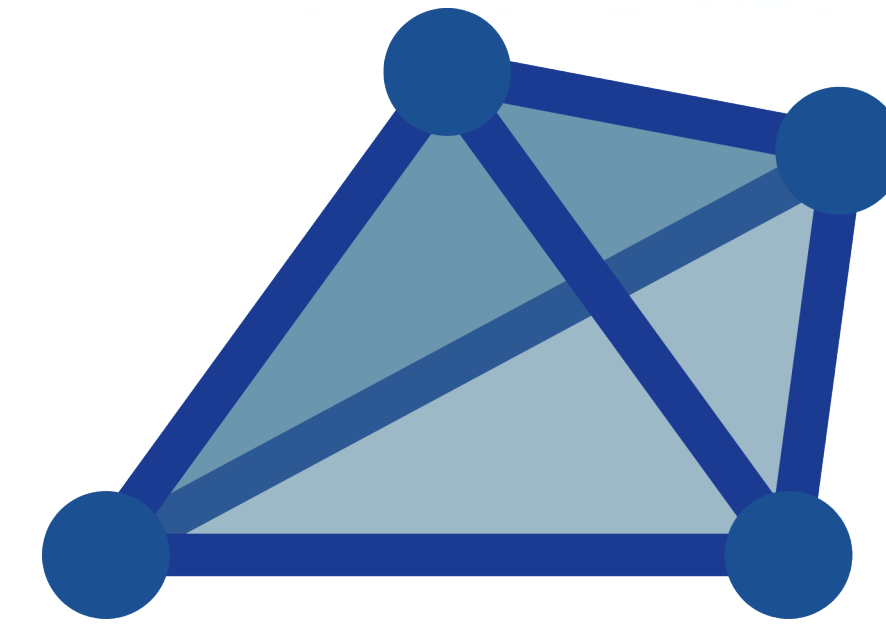


Level set in a 3-simplex



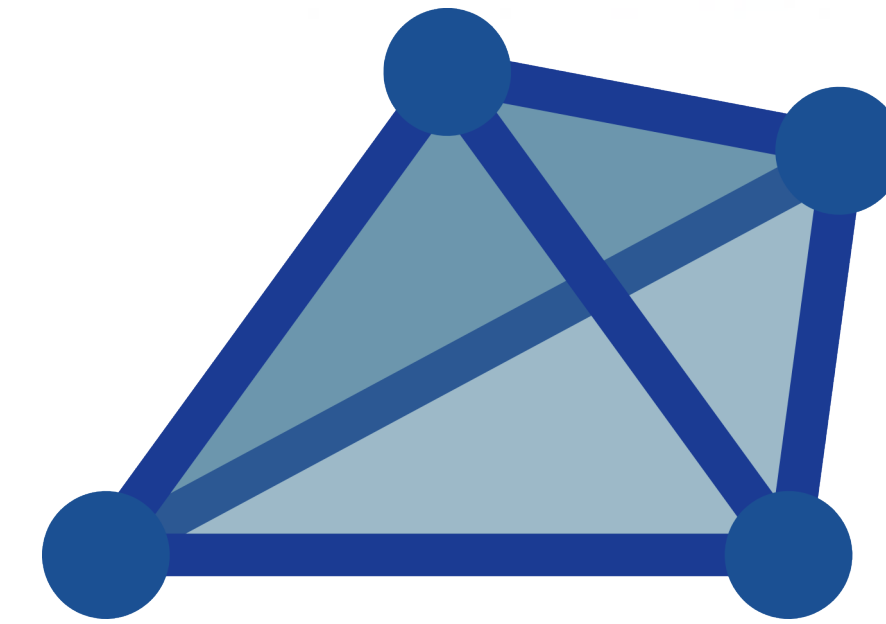
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 - $f^{-1}(i) = \{p \in \mathcal{D} \mid f(p) = i\}$
 - **No critical point inside the tet!**
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 - Can be computed by only looking at the boundary

Level set in a 3-simplex



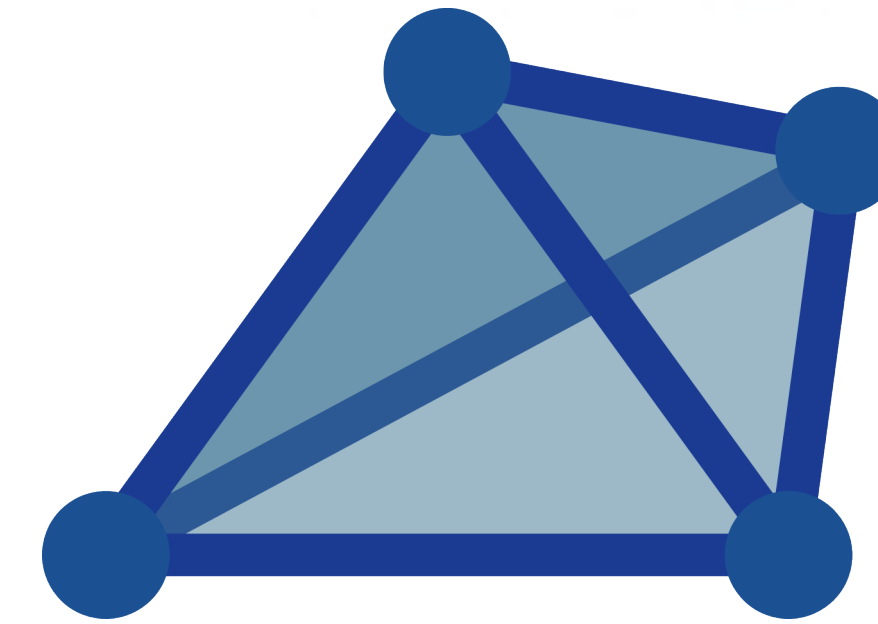
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- Let i be an isovalue
 - $f^{-1}(i) = \{p \in \mathcal{D} \mid f(p) = i\}$
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 - Level sets on triangles: boundary of the level set

Level set in a 3-simplex



- Let \mathcal{D} be a single tetrahedron
 - $f(v_0), f(v_1), f(v_2), f(v_3)$
- Let i be an isovalue
 - $f^{-1}(i) = \{p \in \mathcal{D} \mid f(p) = i\}$
 - **No critical point inside the tet!**
 - Simply connected, open, 2-manifold
 - Can be computed by only looking at the boundary
 - Level sets on triangles: boundary of the level set
- Many cases

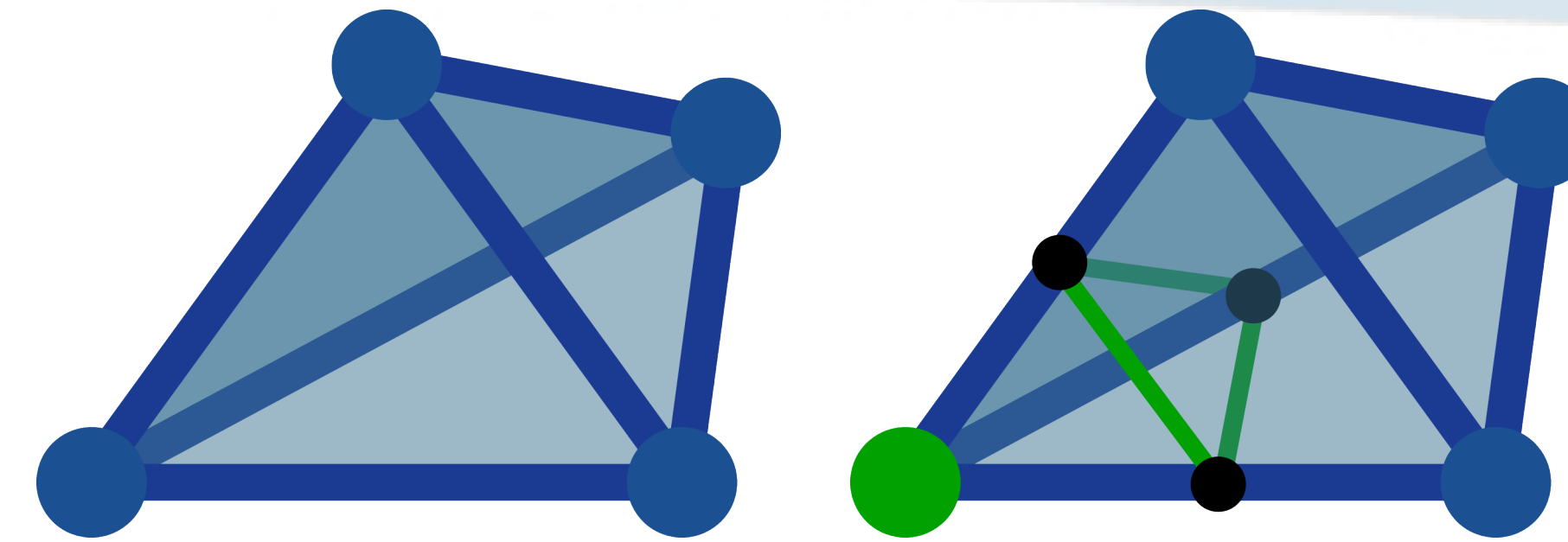
Level set in a 3-simplex



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- Let i be an isovalue
 - $f^{-1}(i) = \{p \in \mathcal{D} \mid f(p) = i\}$
 - **No critical point inside the tet!**
 - Simply connected, open, 2-manifold
 - Can be computed by only looking at the boundary
 - Level sets on triangles: boundary of the level set
- Many cases, in terms of function value: only 5

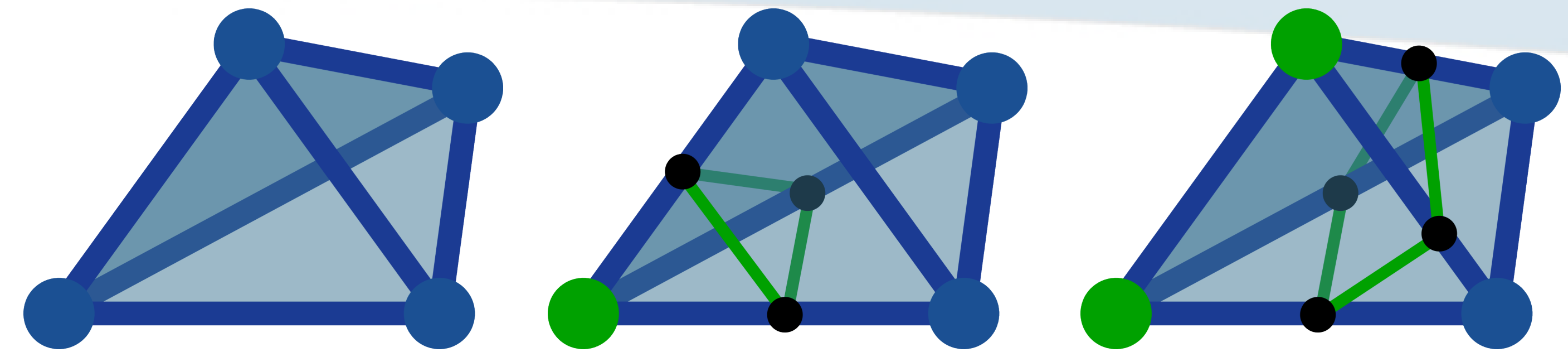
Level set in a 3-simplex

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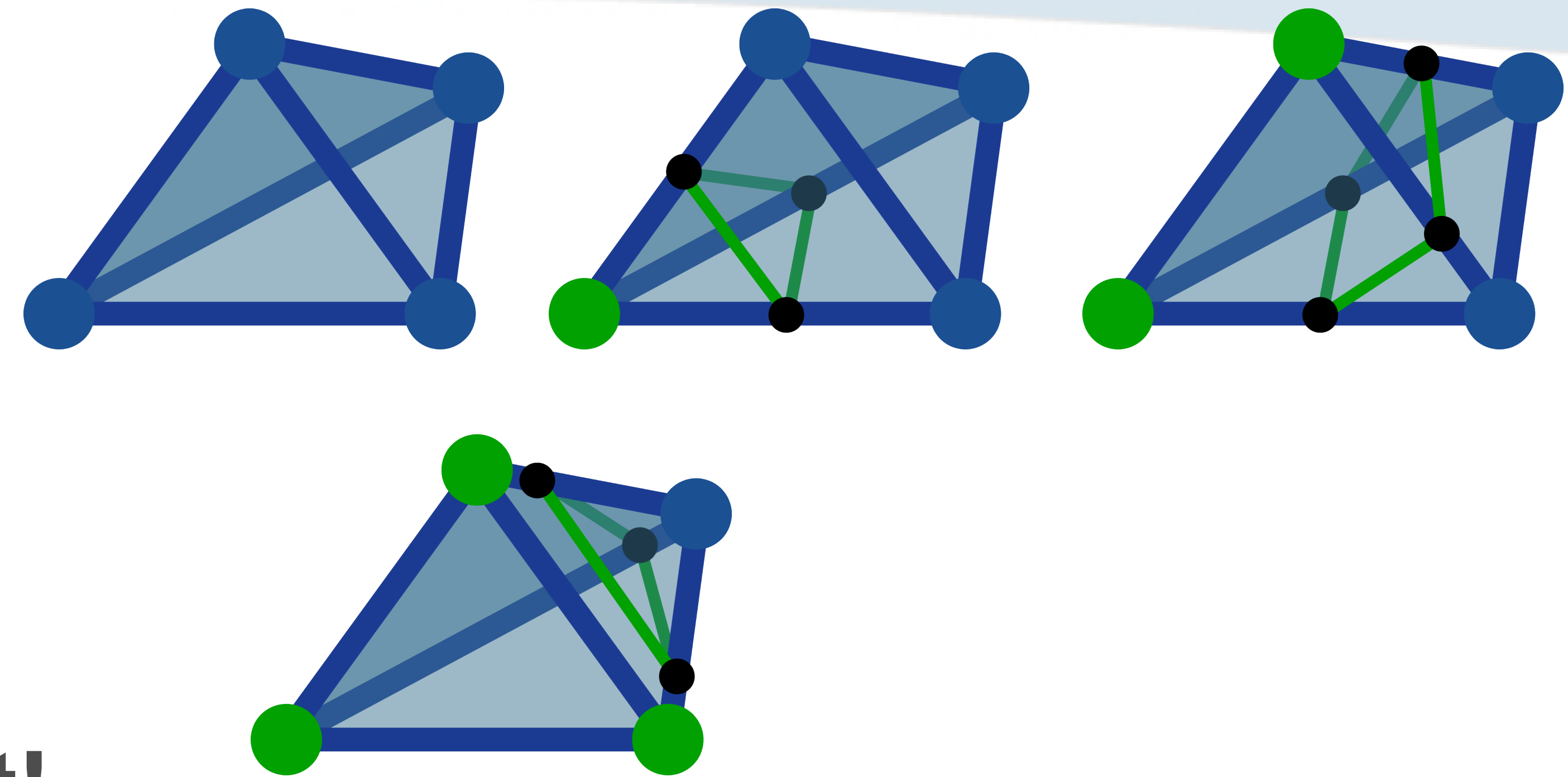
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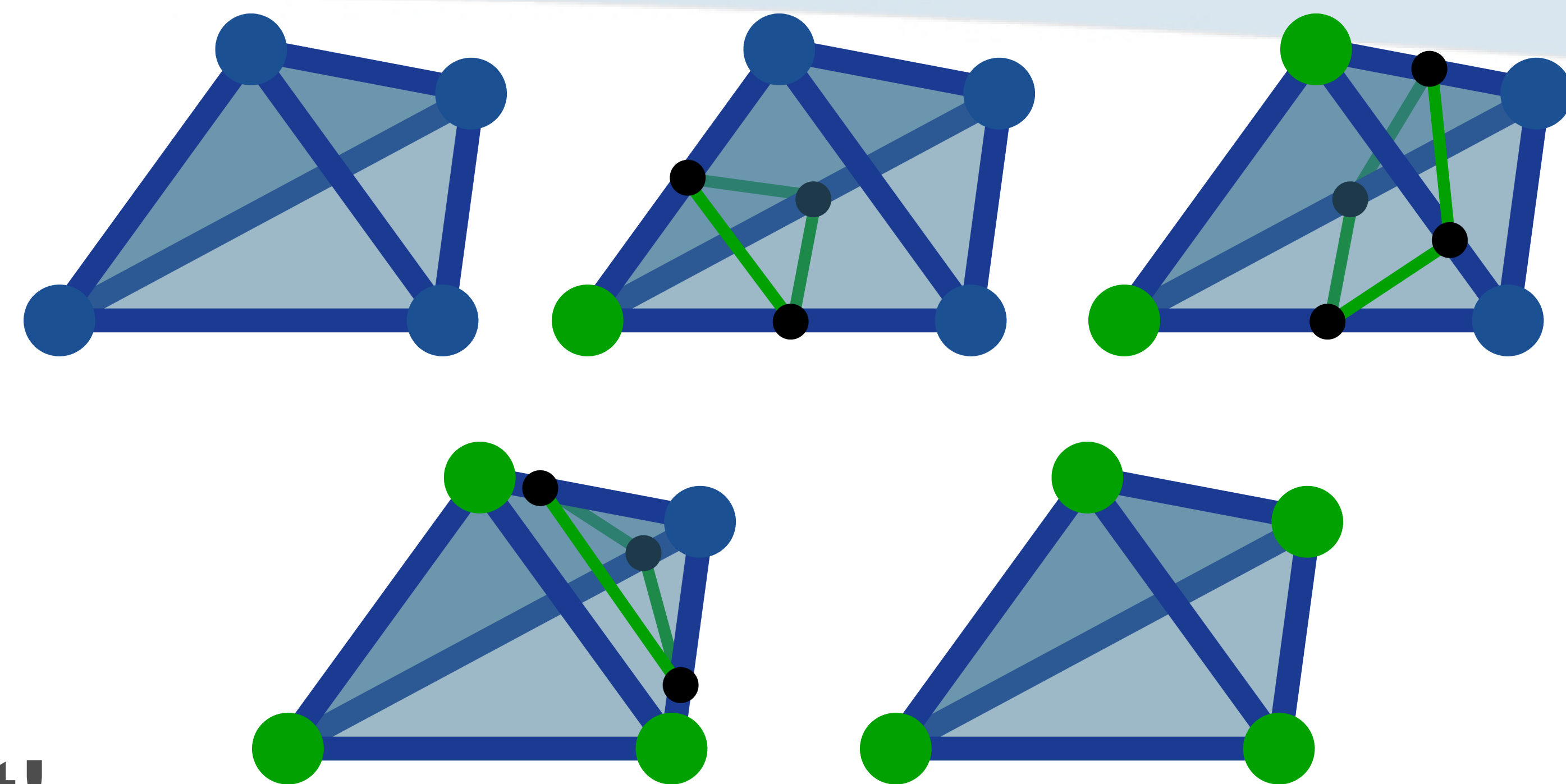
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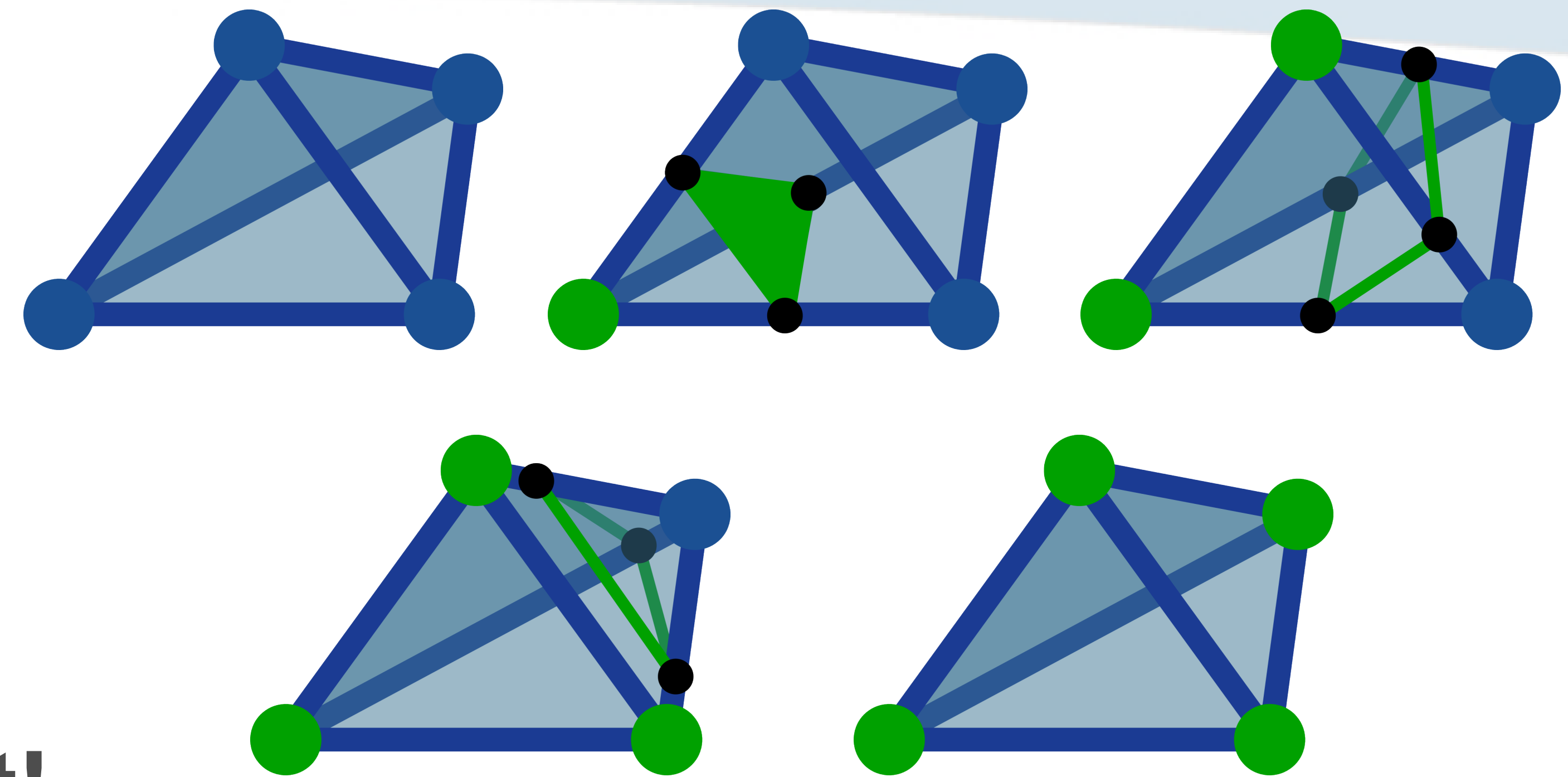
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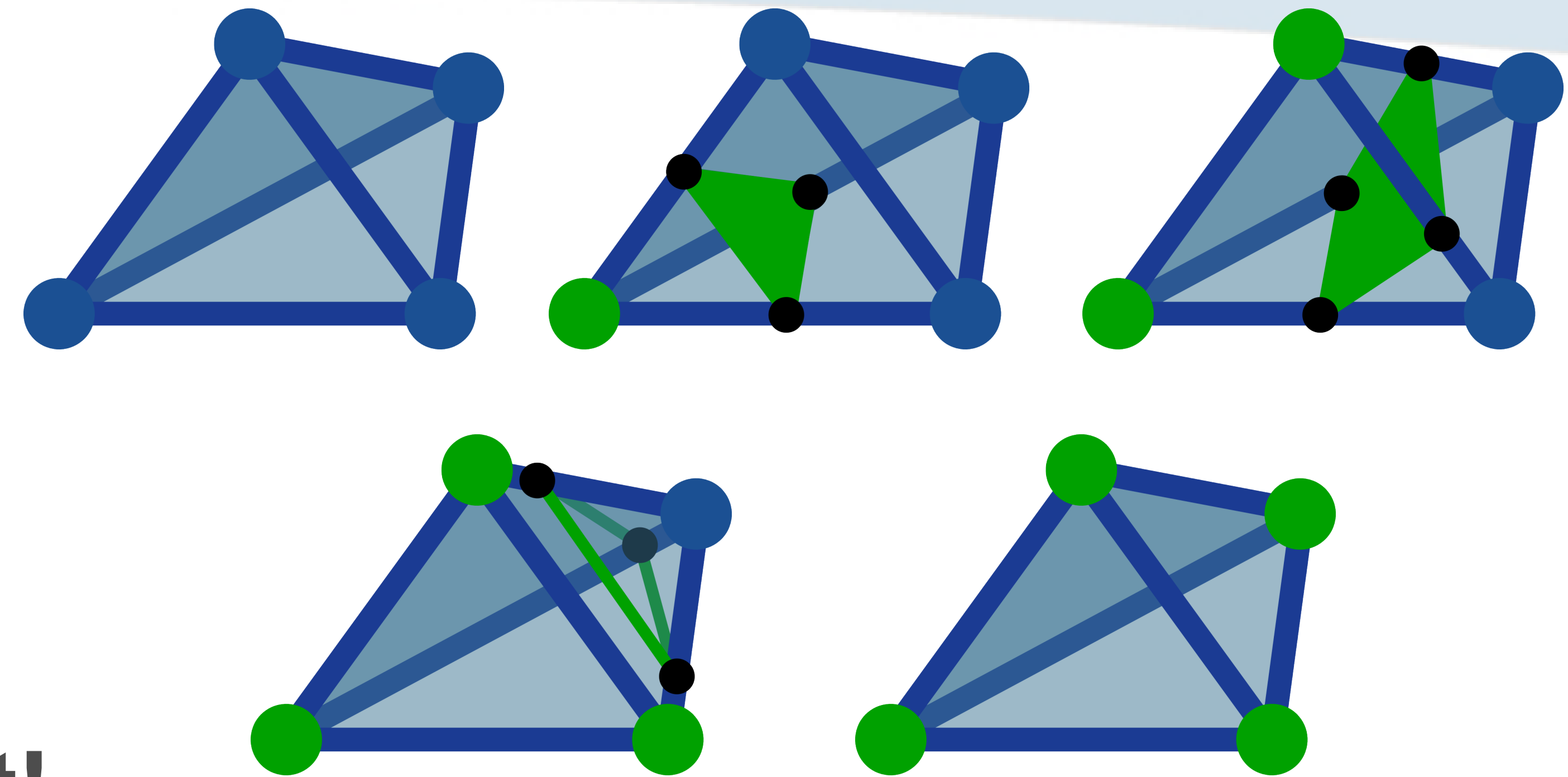
Level set in a 3-simplex

- Let \mathcal{D} be a single tetrahedron
 - $f(v_0), f(v_1), f(v_2), f(v_3)$
- Let i be an isovalue
 - $f^{-1}(i) = \{p \in \mathcal{D} \mid f(p) = i\}$
 - **No critical point inside the tet!**
 - Simply connected, open, 2-manifold
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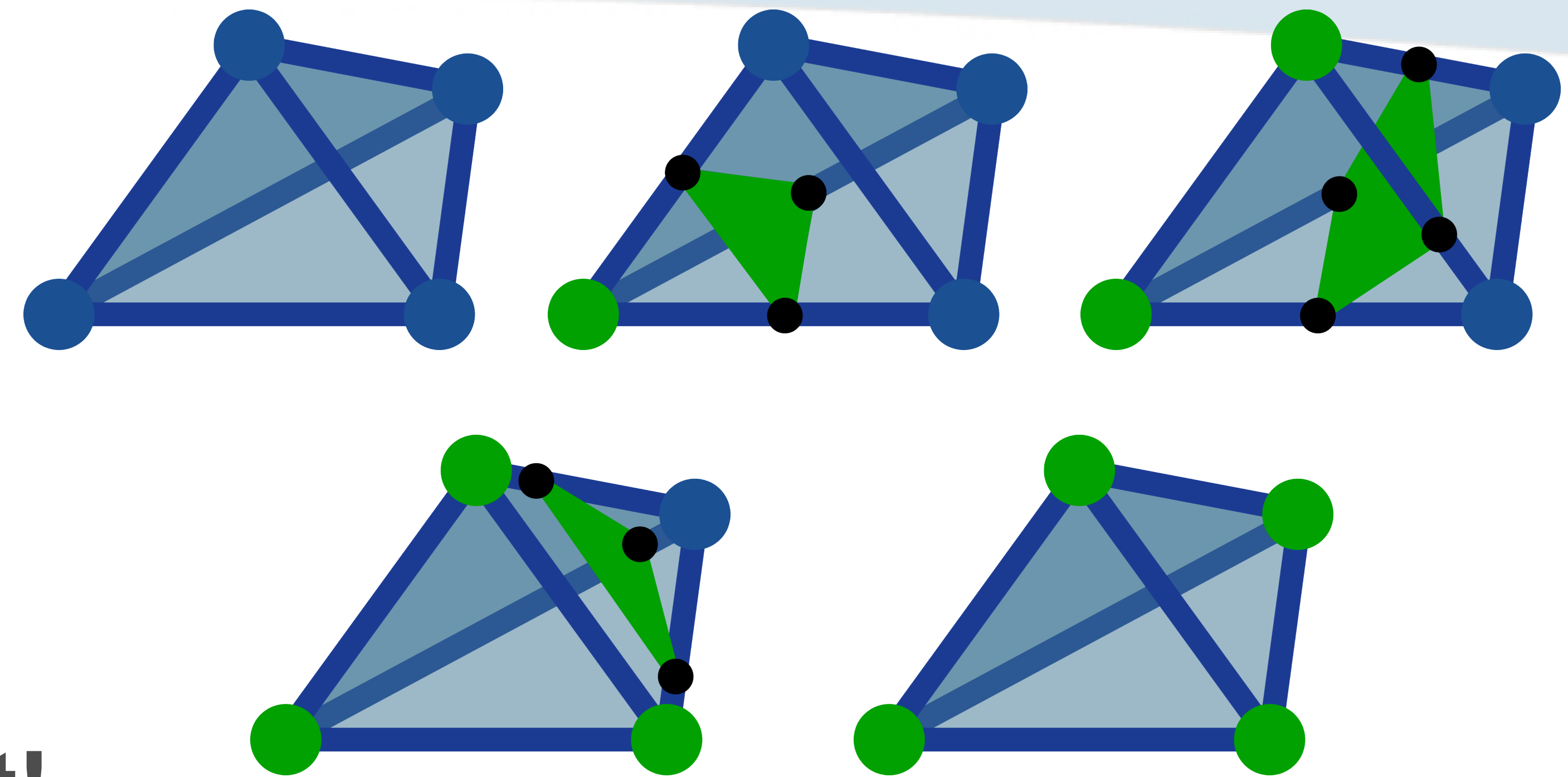
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Level set in a d-simplex

- Let \mathcal{D} be a single d-simplex
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Level set in a d-simplex

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 - **No critical point inside the simplex!**
 - Simply connected, open, (d-1)-manifold

Level set in a d-simplex

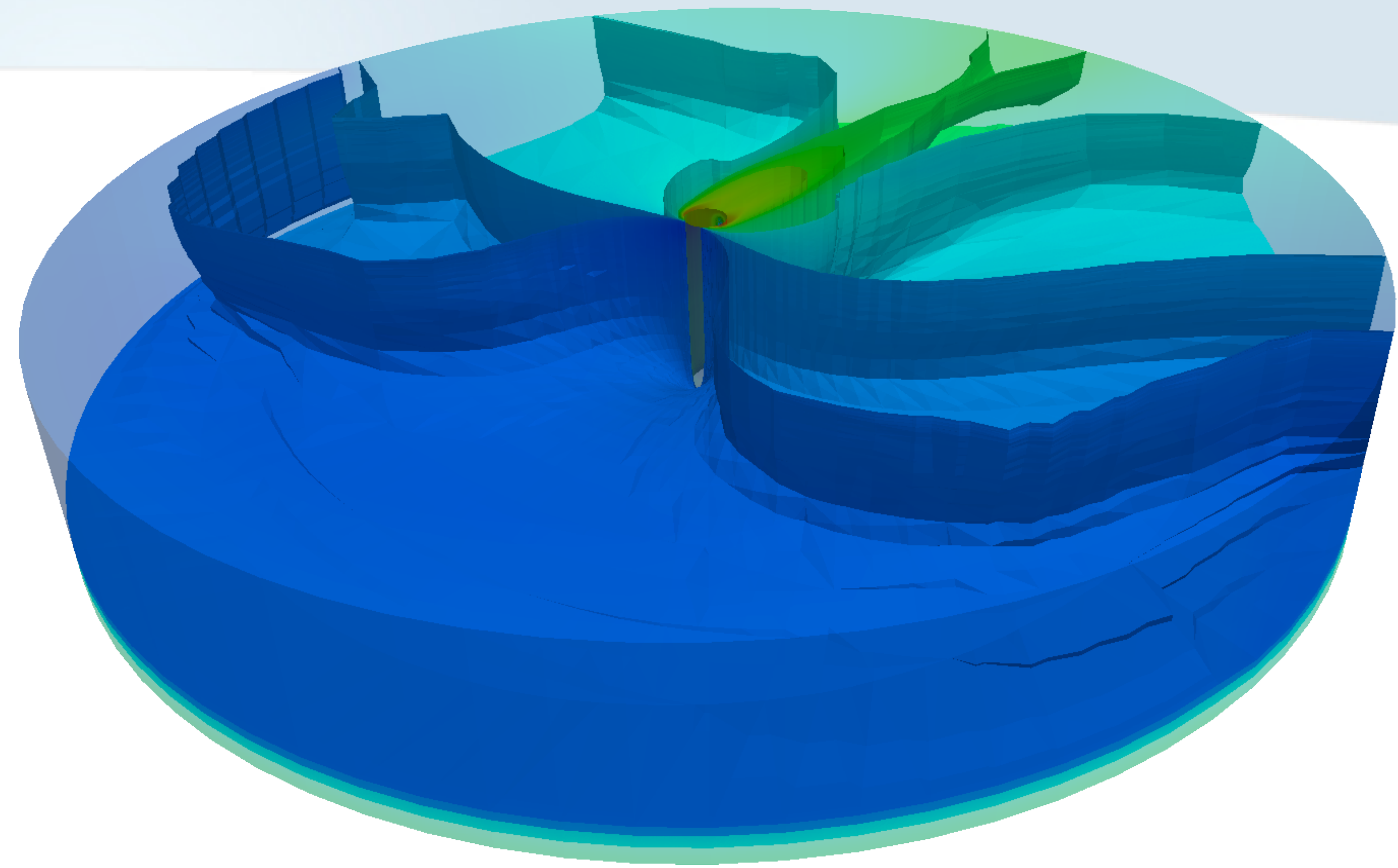
- Let \mathcal{D} be a single d-simplex
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 - Level sets on (d-1)-faces: boundary of the level set

Level set in a d-simplex

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 - $f(v_0), f(v_1), \dots, f(v_d)$
- Let i be an isovalue
 - $f^{-1}(i) = \{p \in \mathcal{D} \mid f(p) = i\}$
 - **No critical point inside the simplex!**
 - Simply connected, open, (d-1)-manifold
 - Can be computed by only looking at the boundary
 - Level sets on (d-1)-faces: boundary of the level set
 - Recursive process

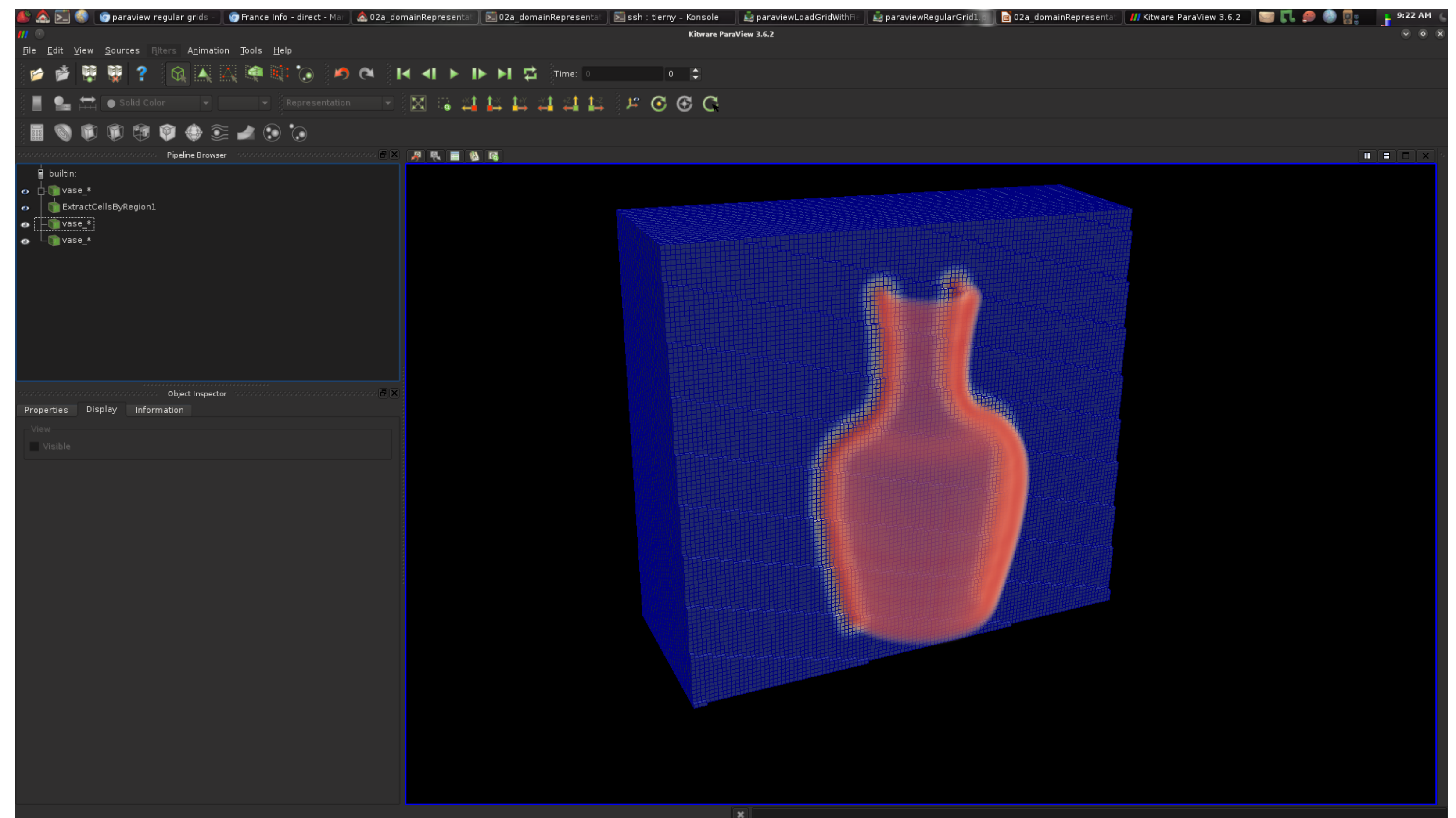
Level set extraction

- Now we know
 - How to compute a level set
 - In arbitrary dimension
 - But in only one d-simplex :(
- General algorithm
 - Flip through the list of d-simplex
 - Apply the algorithm on a per d-simplex basis
 - “*Marching Tetrahedra*”



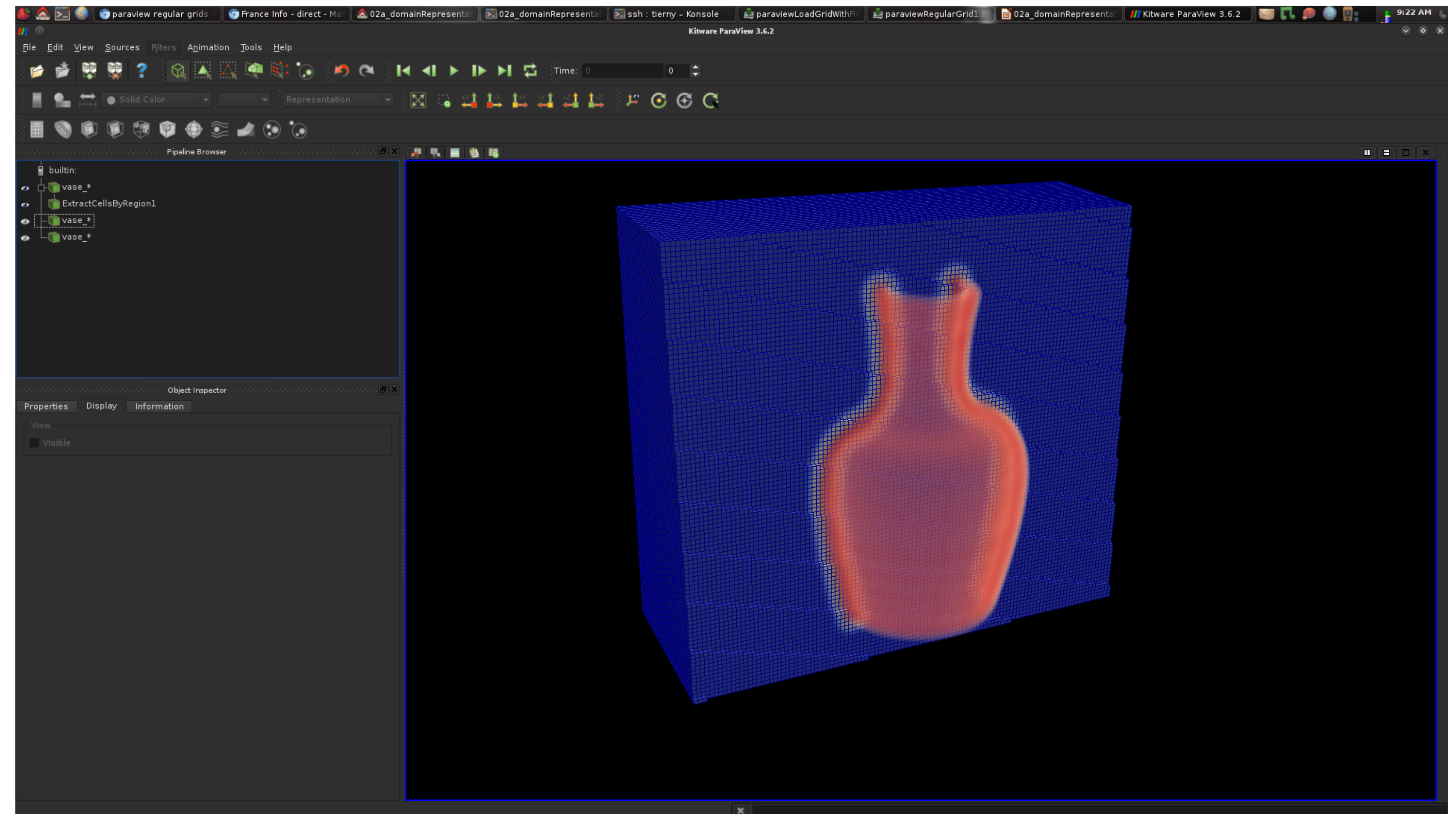
Level sets on regular grids

- What about regular grids?



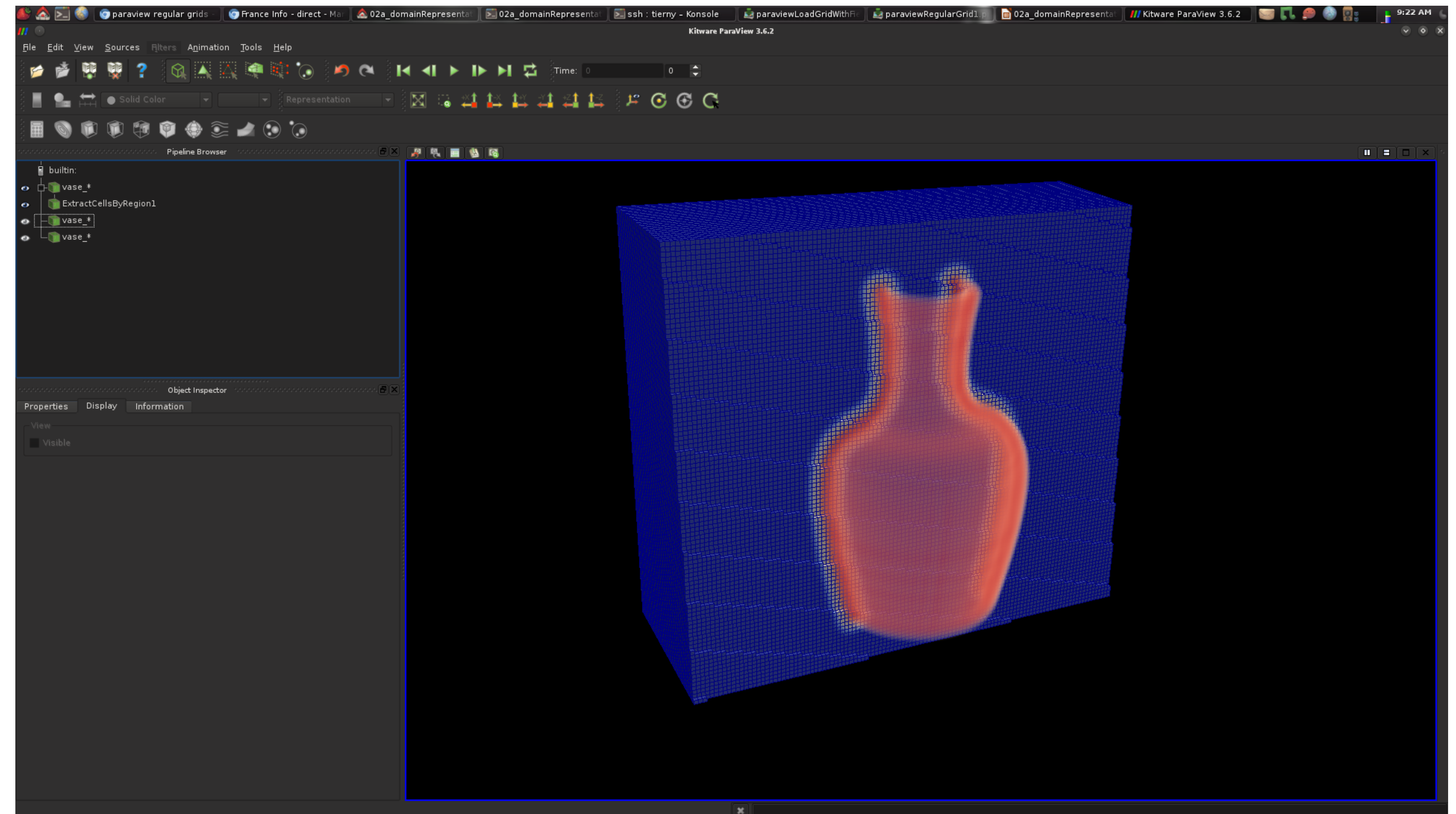
Level sets on regular grids

- What about regular grids?
 - In principle
 - Same rationale



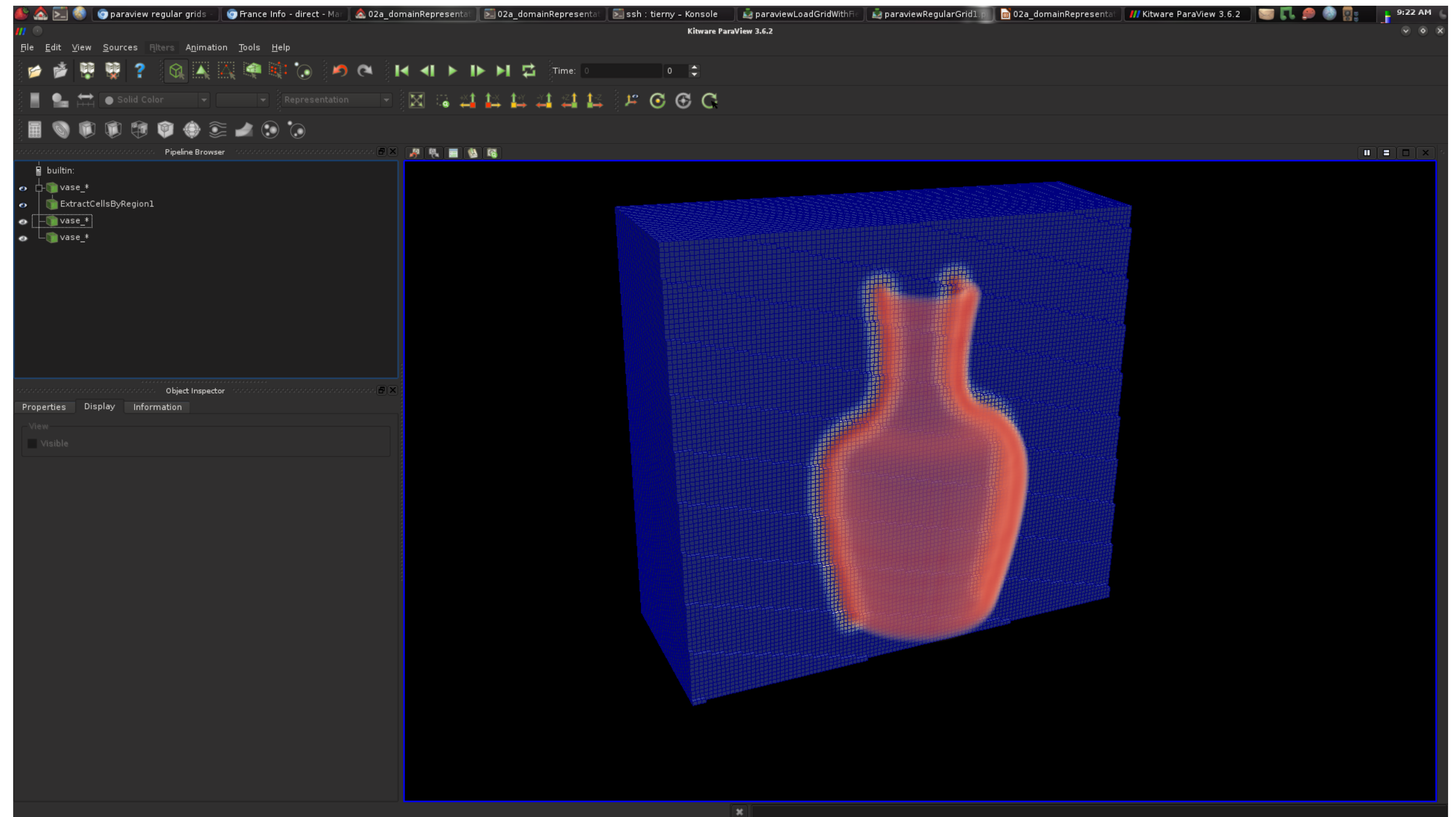
Level sets on regular grids

- What about regular grids?
 - In principle
 - Same rationale
- 2D regular grids:
 - Marching squares



Level sets on regular grids

- What about regular grids?
 - In principle
 - Same rationale
- 2D regular grids:
 - Marching squares
- 3D regular grids:
 - Marching cubes



Marching squares

- Let \mathcal{D} be a 2-regular grid

Marching squares

- Let \mathcal{D} be a 2-regular grid
 - With bilinear interpolant

Marching squares

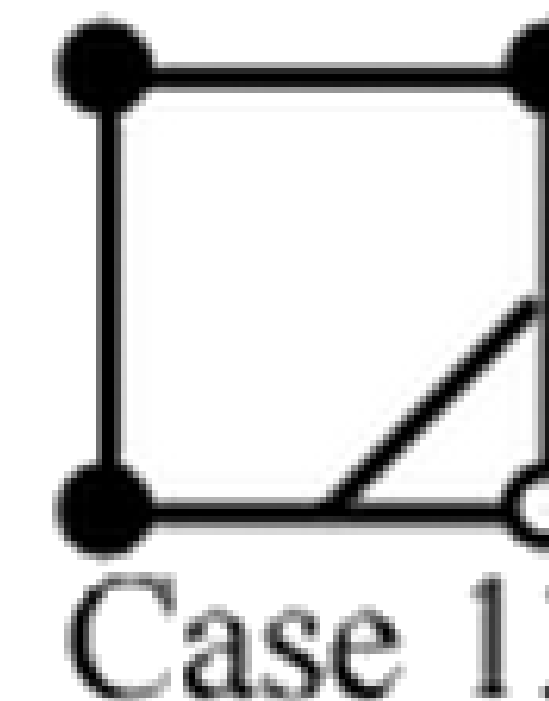
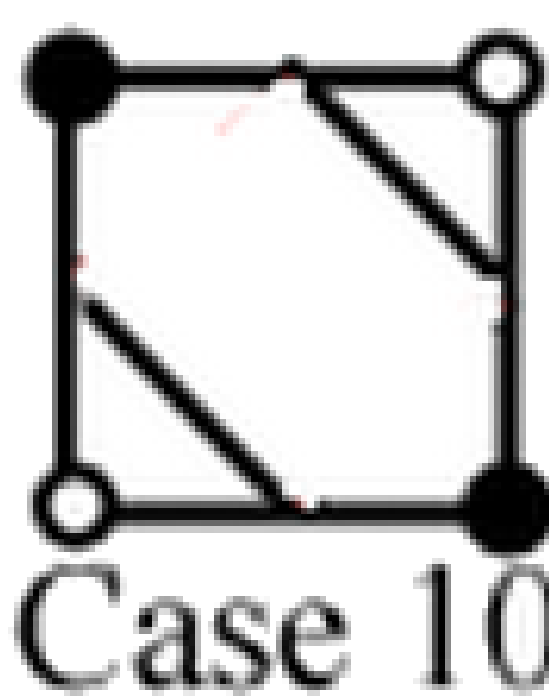
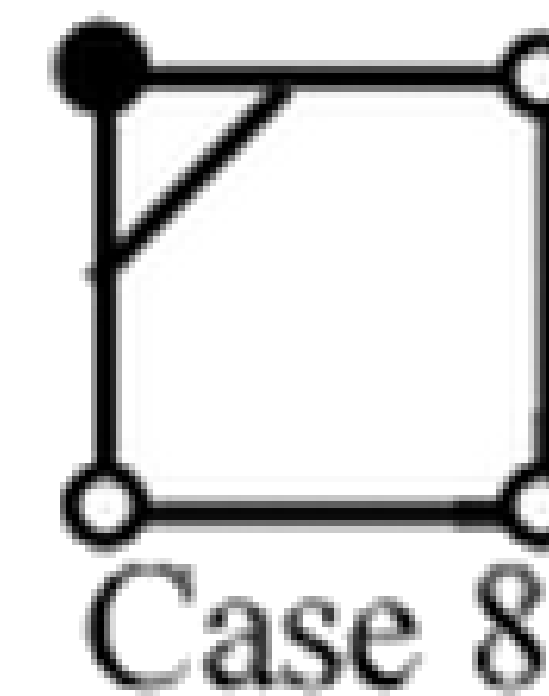
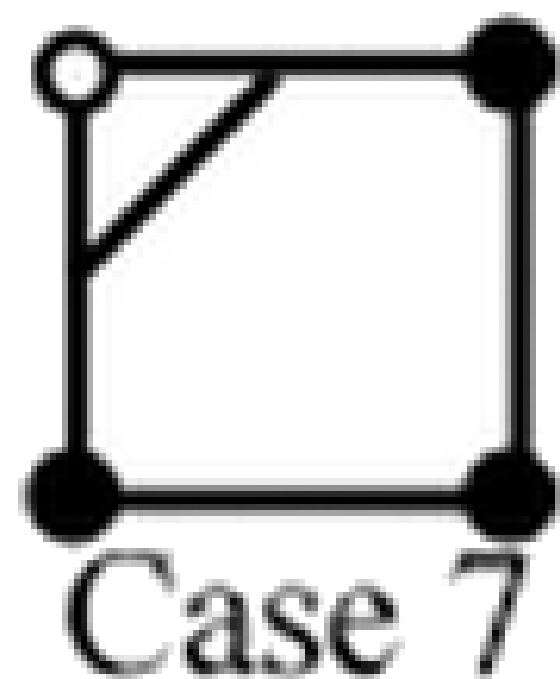
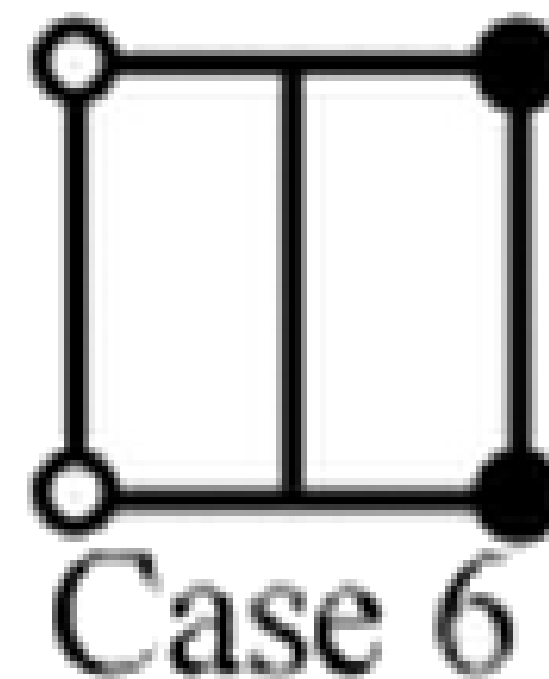
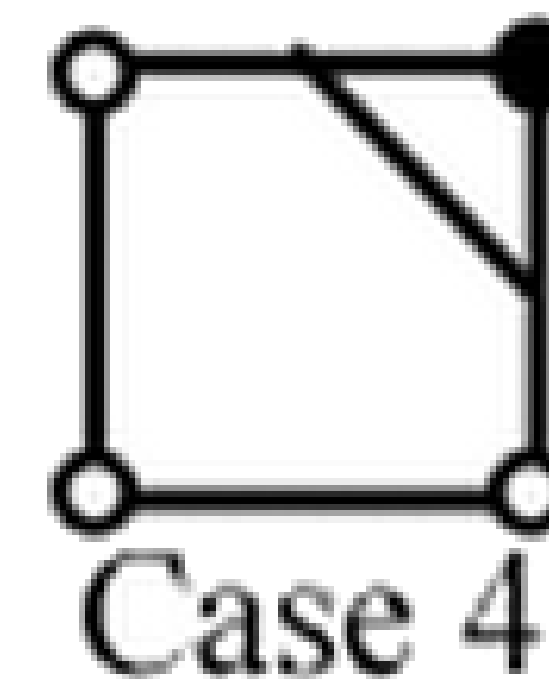
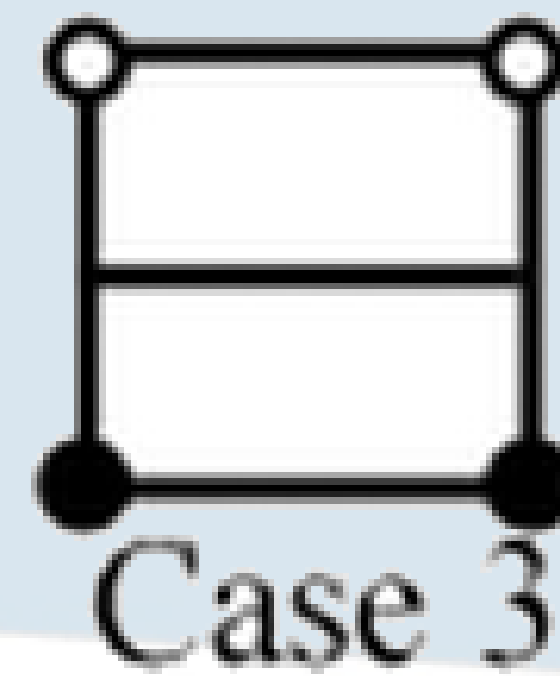
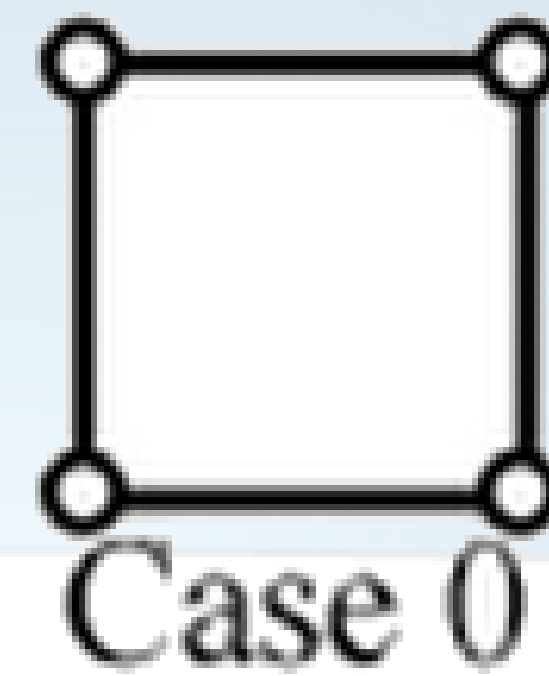
- Let \mathcal{D} be a 2-regular grid
 - With bilinear interpolant
- Level set extraction
 - Loop over the unit cells

Marching squares

- Let \mathcal{D} be a 2-regular grid
 - With bilinear interpolant
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 - Loop over the unit cells
 - Cases on a 2D unit cell

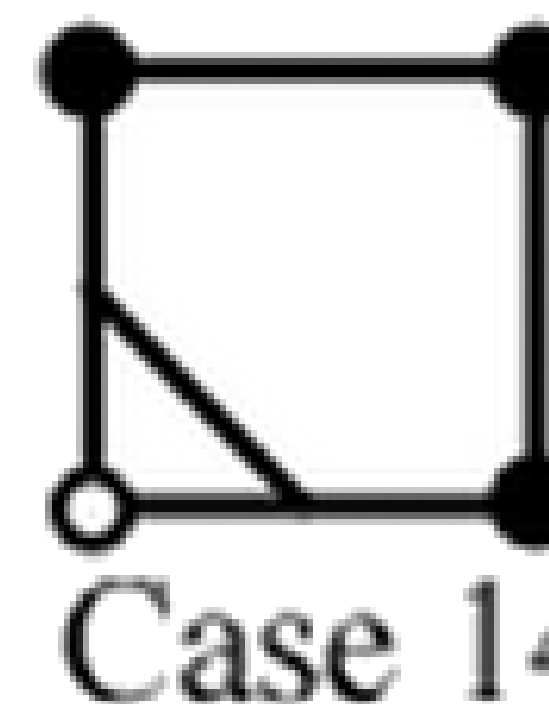
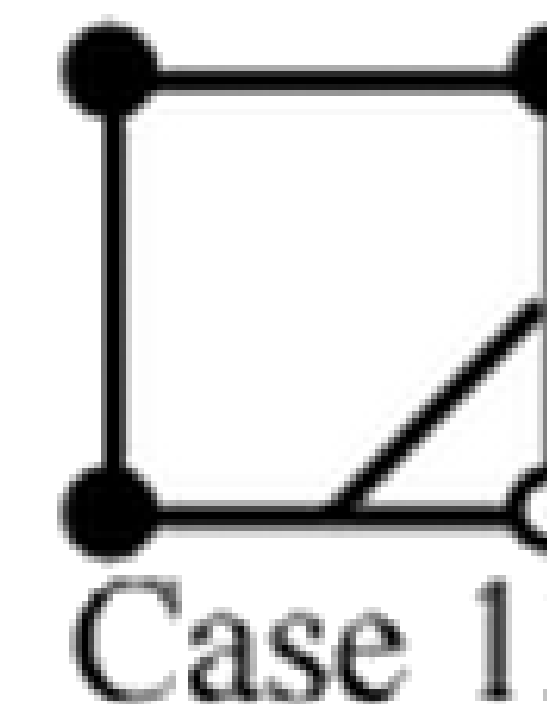
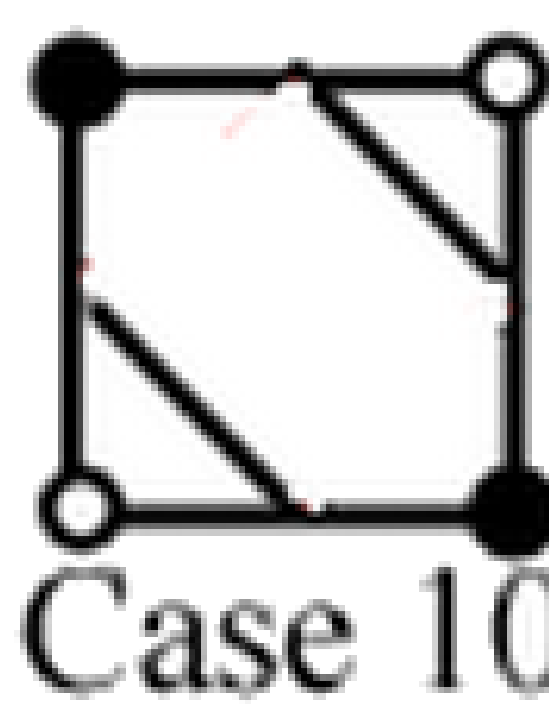
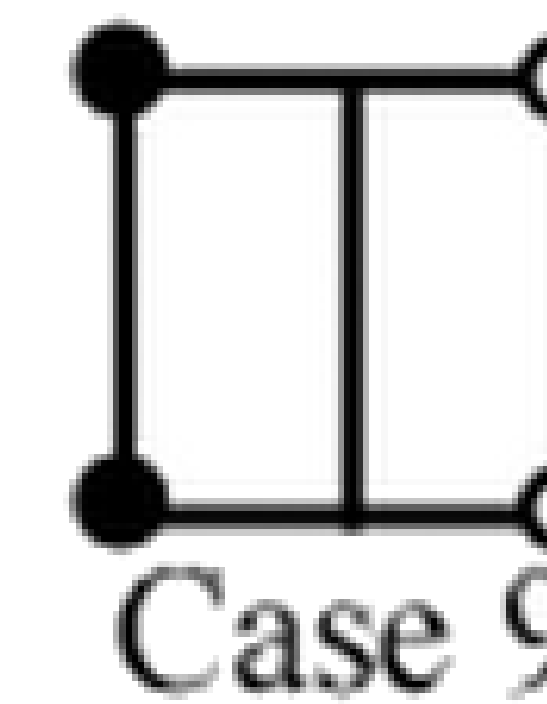
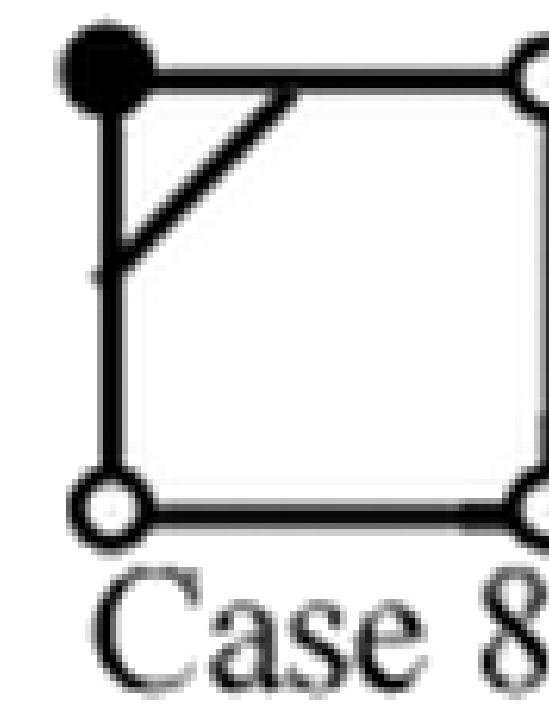
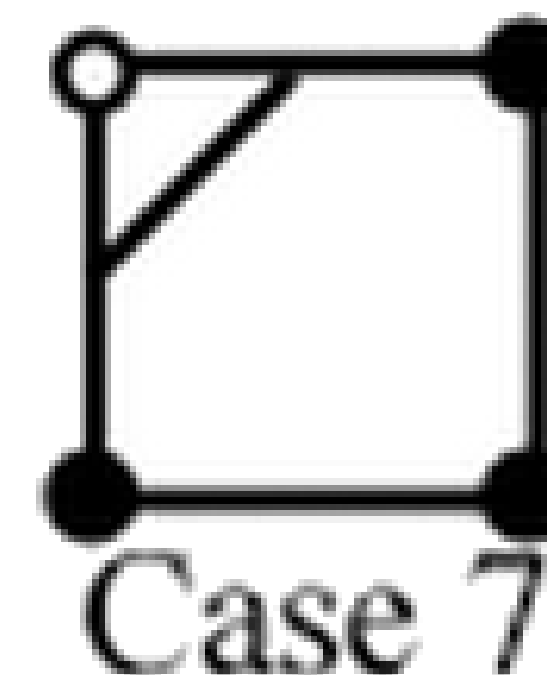
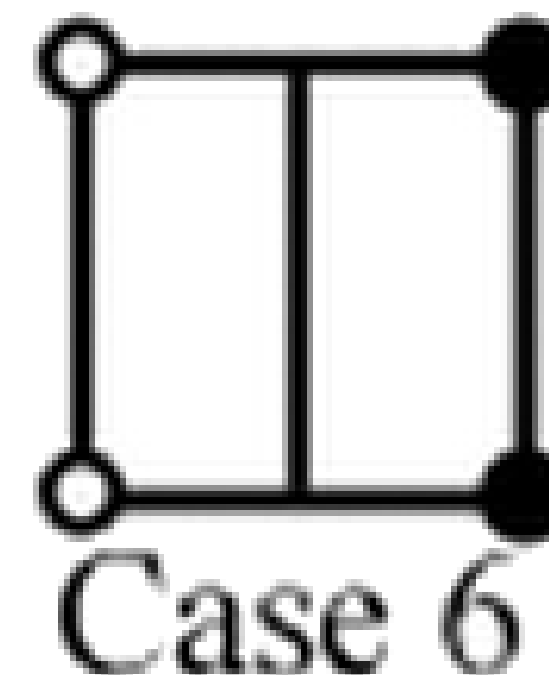
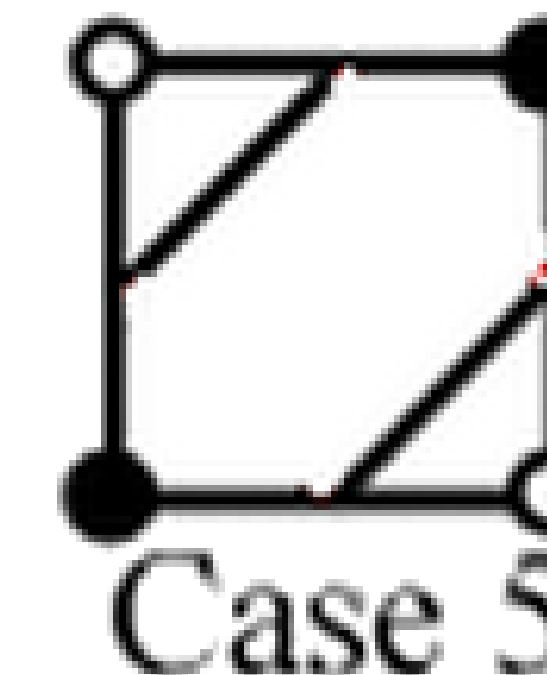
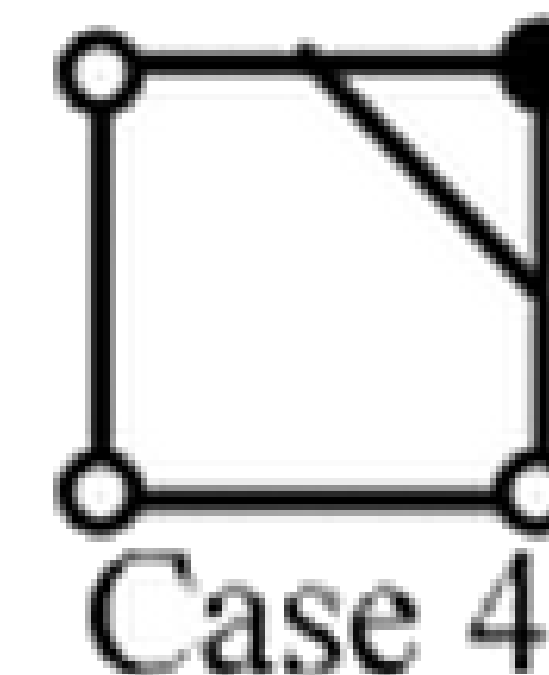
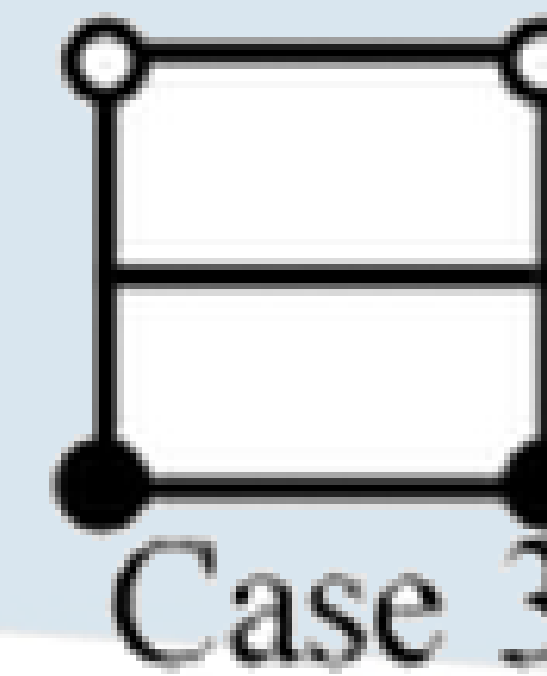
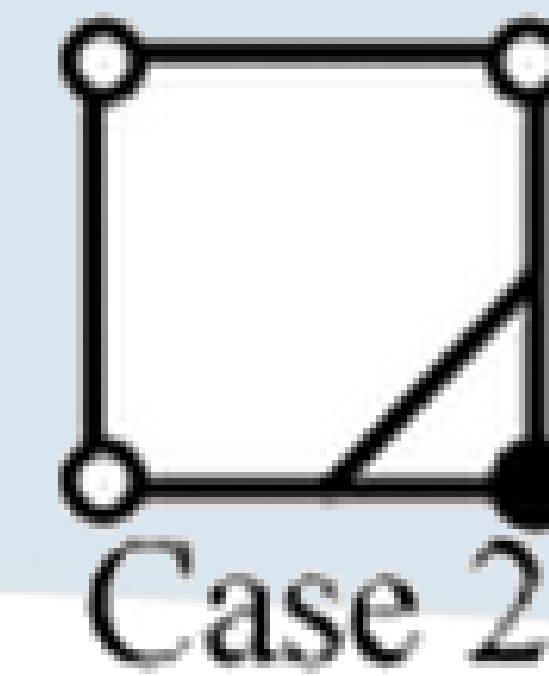
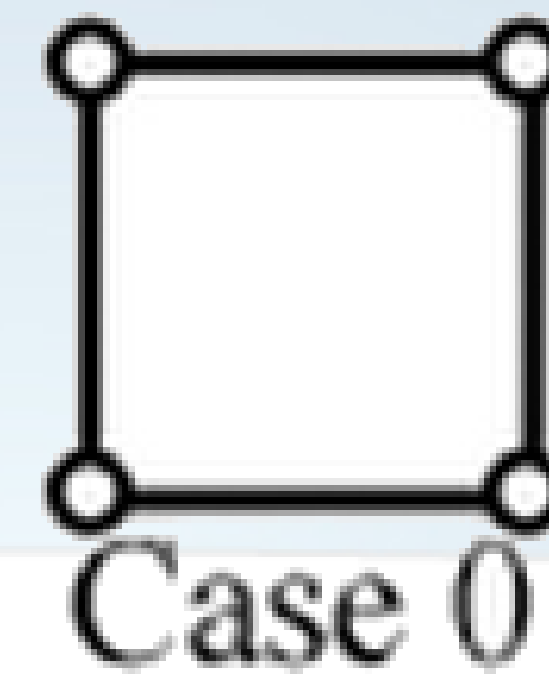
Marching squares

- Let \mathcal{D} be a 2-regular grid
 - With bilinear interpolant
- Level set extraction
 - Loop over the unit cells
 - Cases on a 2D unit cell



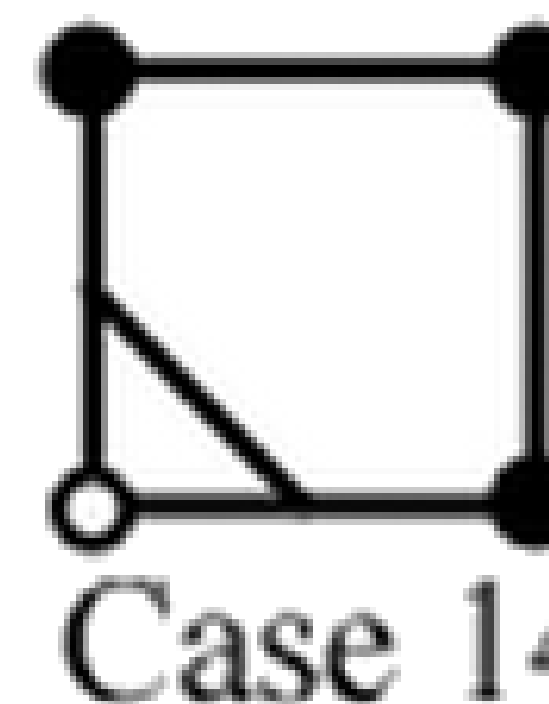
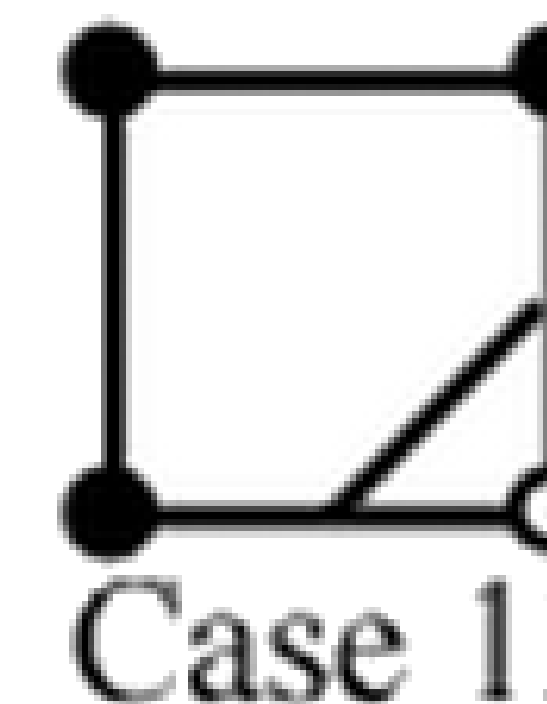
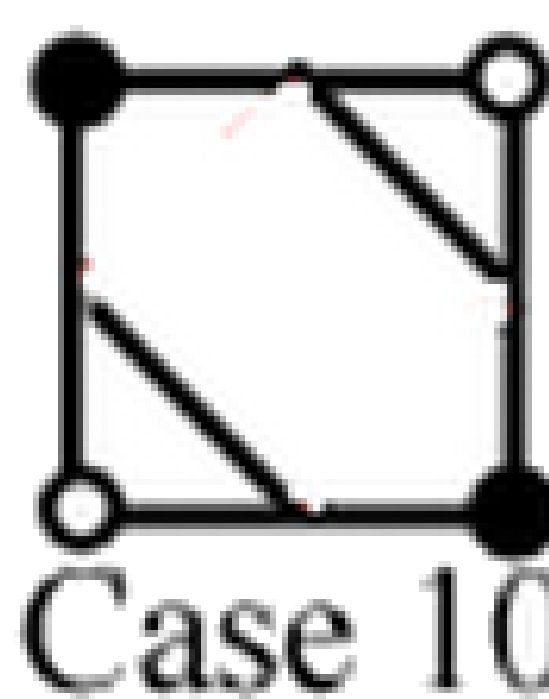
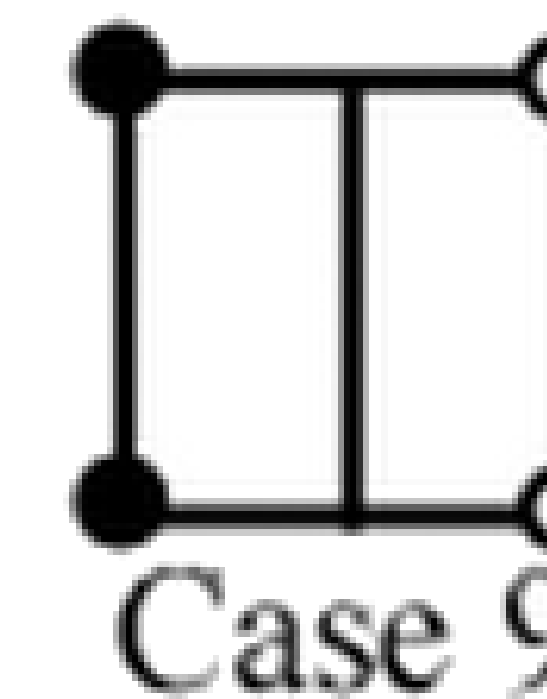
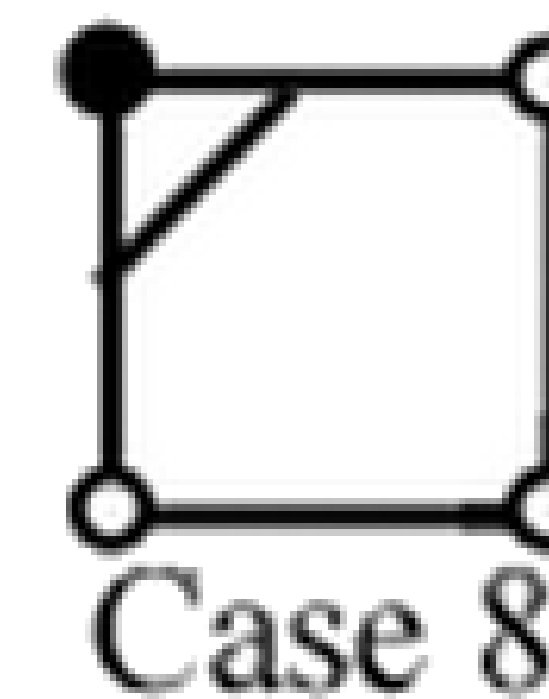
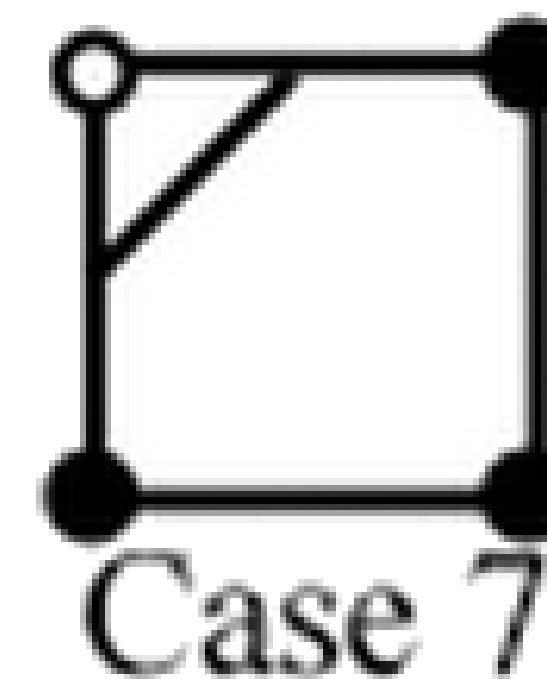
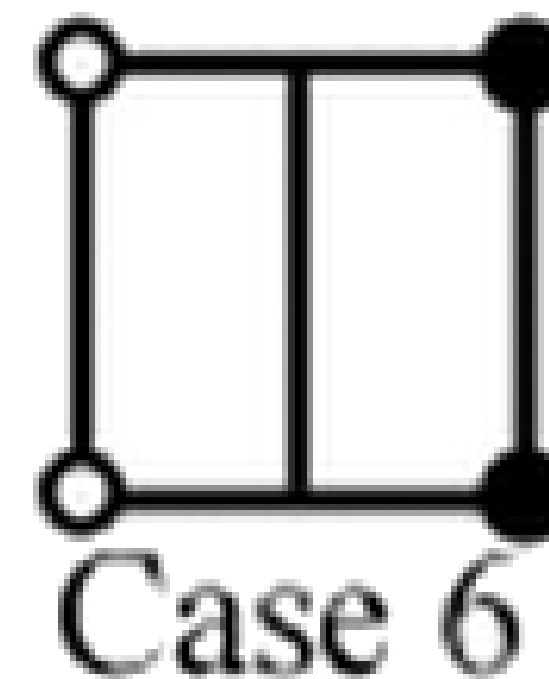
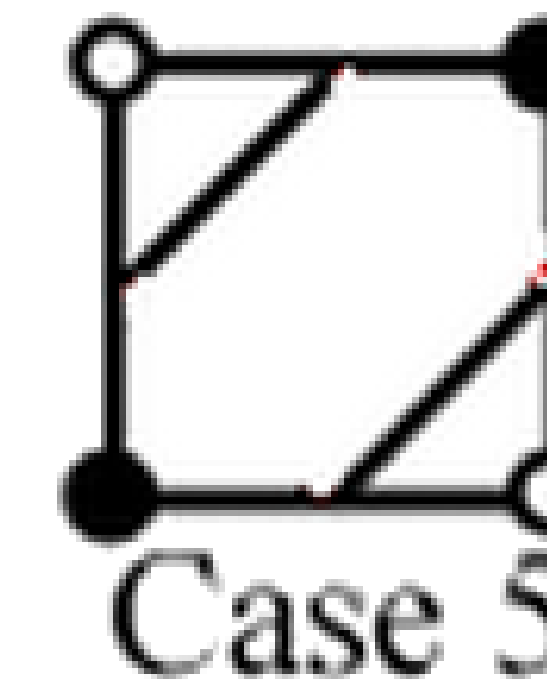
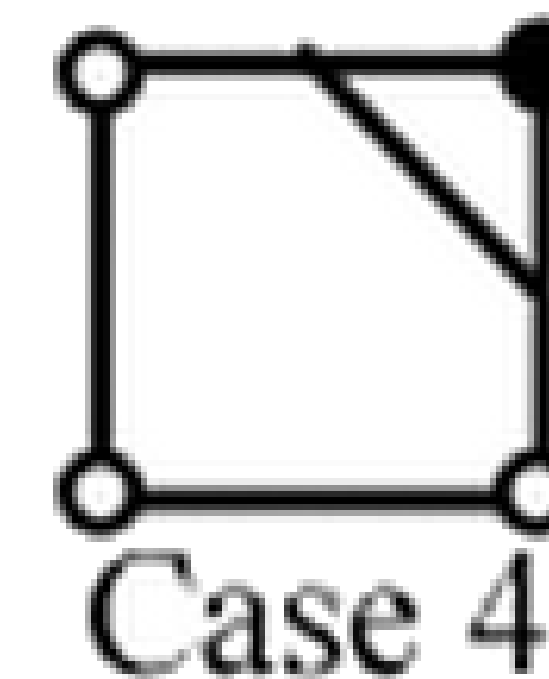
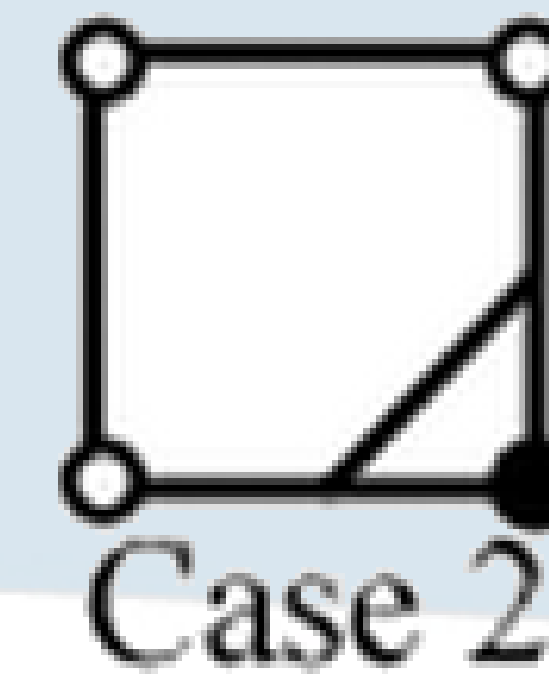
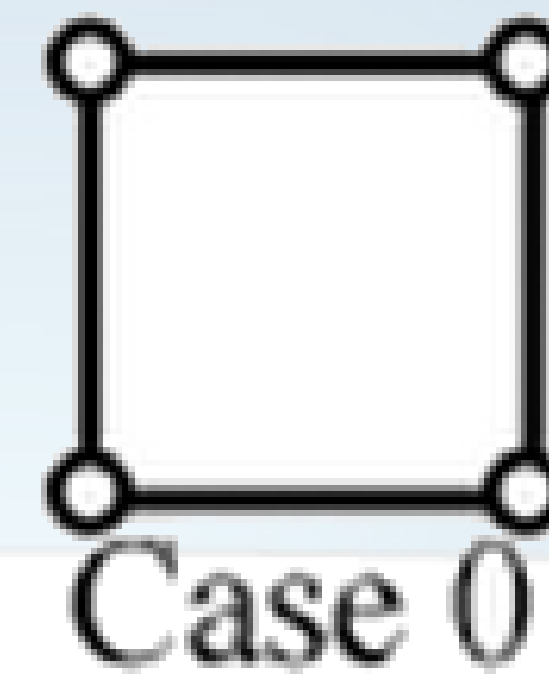
Marching squares

- Let \mathcal{D} be a 2-regular grid
 - With bilinear interpolant
- Level set extraction
 - Loop over the unit cells
 - Cases on a 2D unit cell
 - Much more than in a triangle

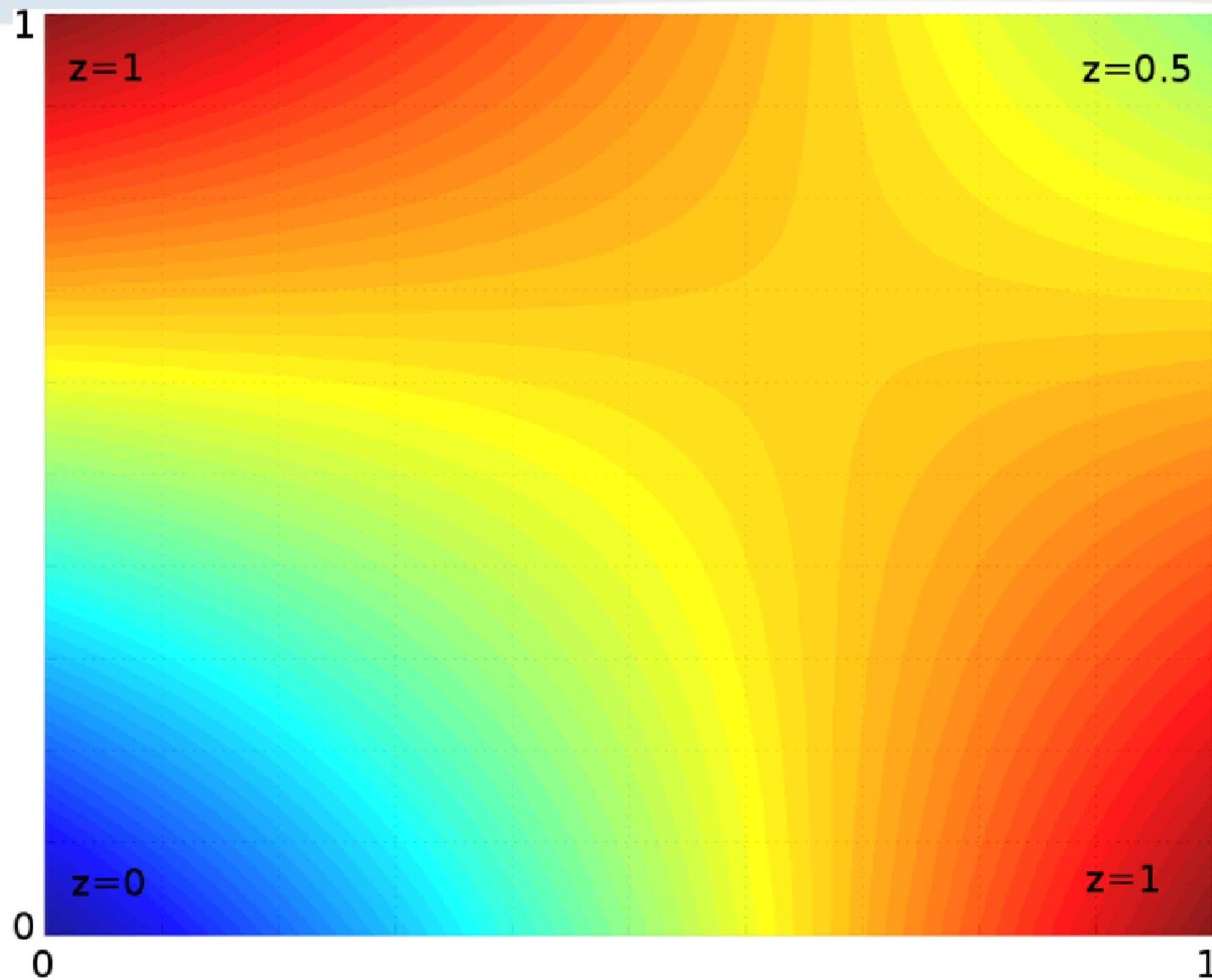


Marching squares

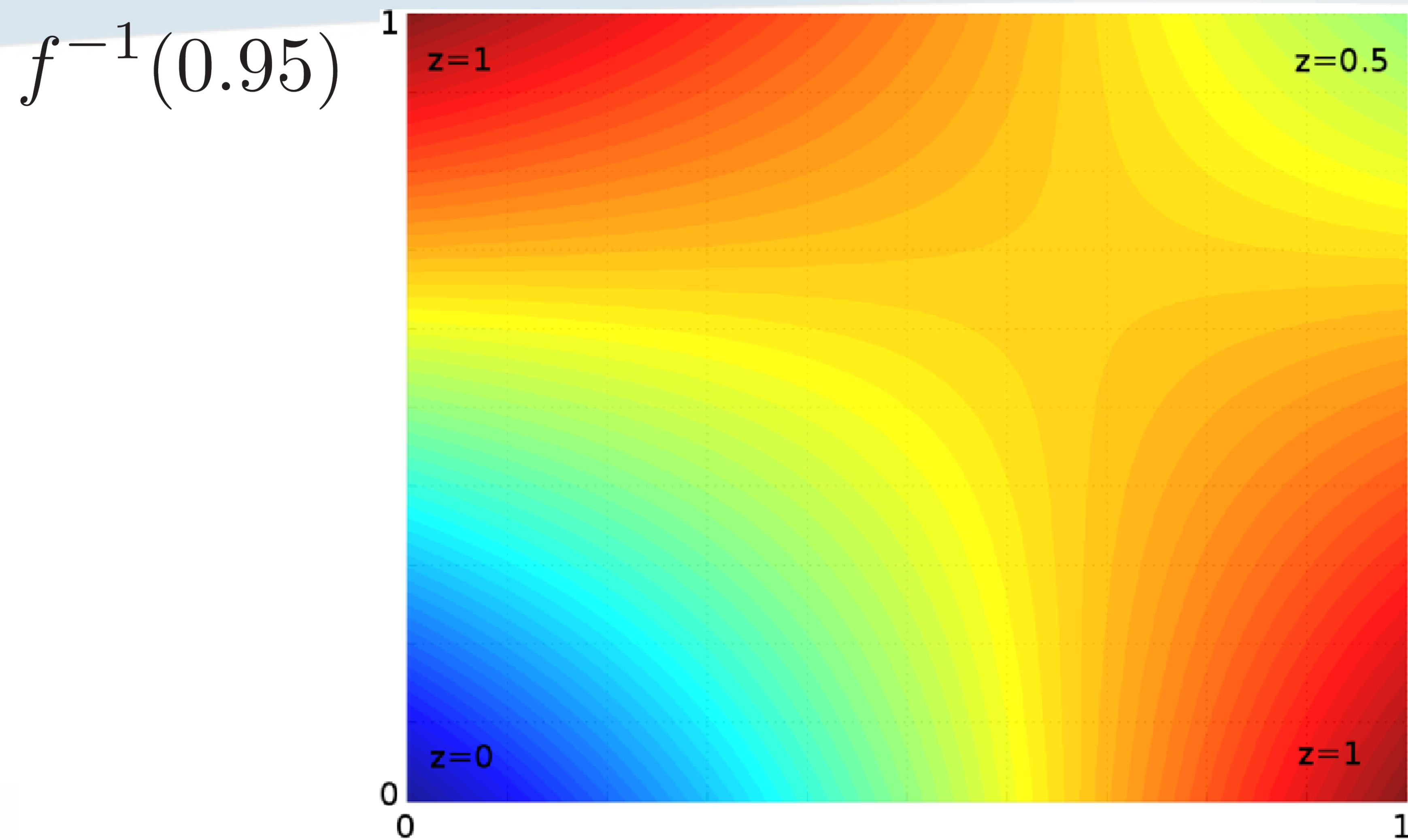
- Let \mathcal{D} be a 2-regular grid
 - With bilinear interpolant
- Level set extraction
 - Loop over the unit cells
 - Cases on a 2D unit cell
 - Much more than in a triangle
 - More than in a tet!



Issues of marching squares

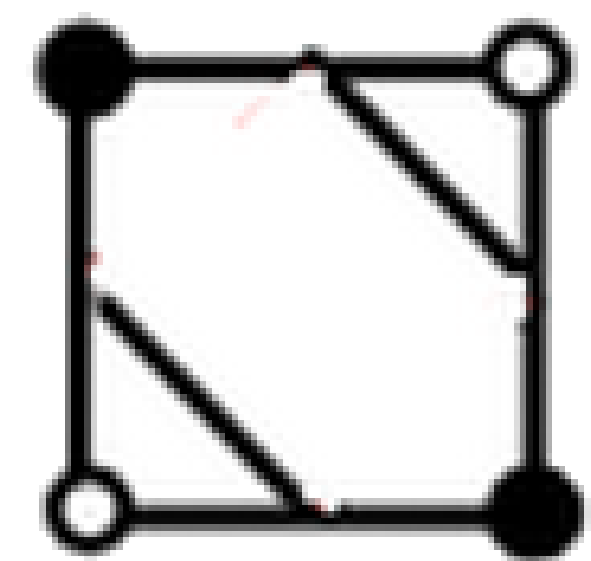


Issues of marching squares

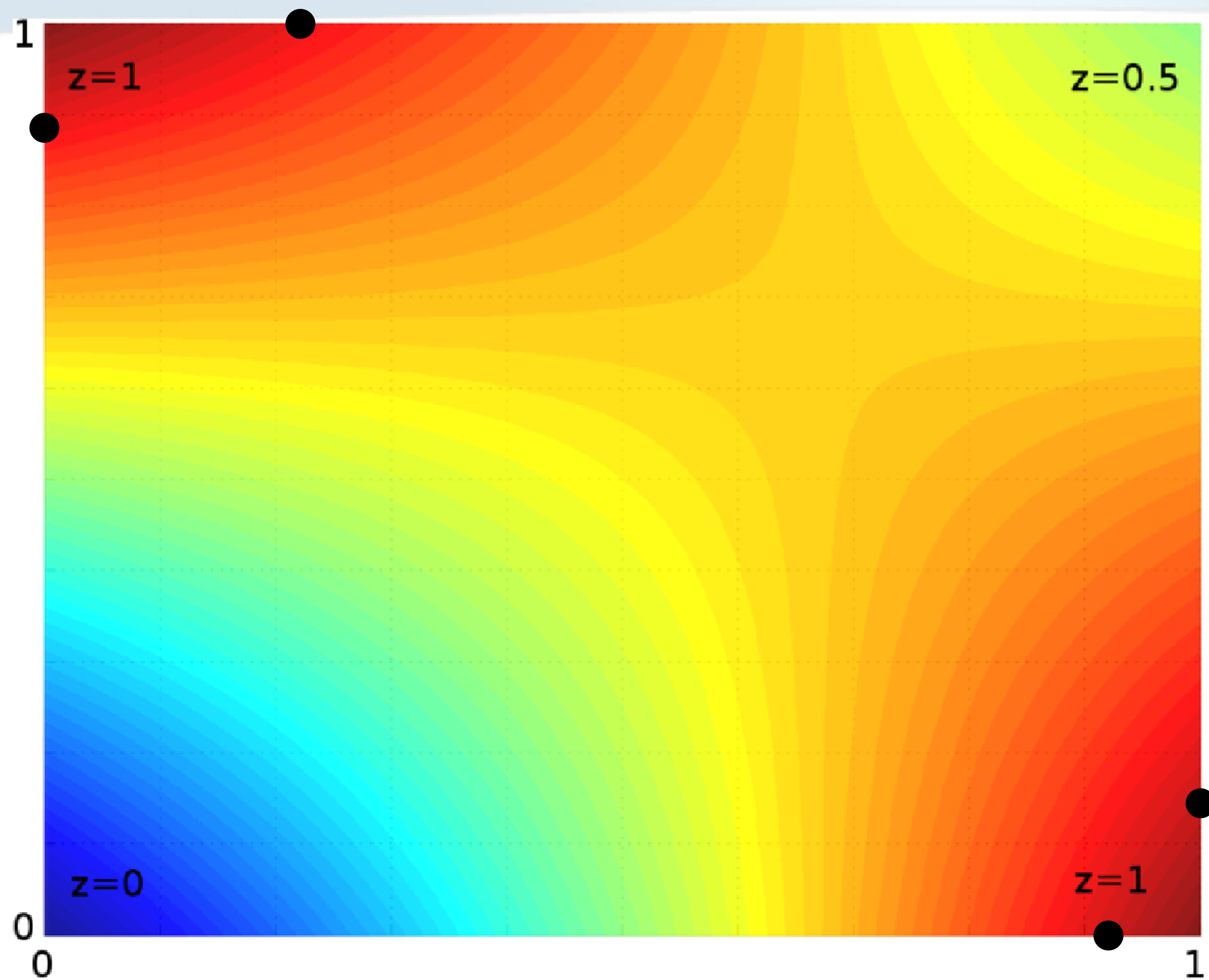


Issues of marching squares

$$f^{-1}(0.95)$$

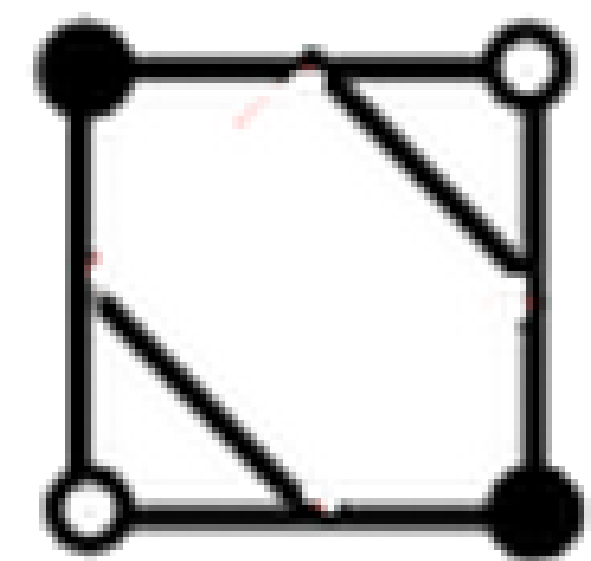


Case 10

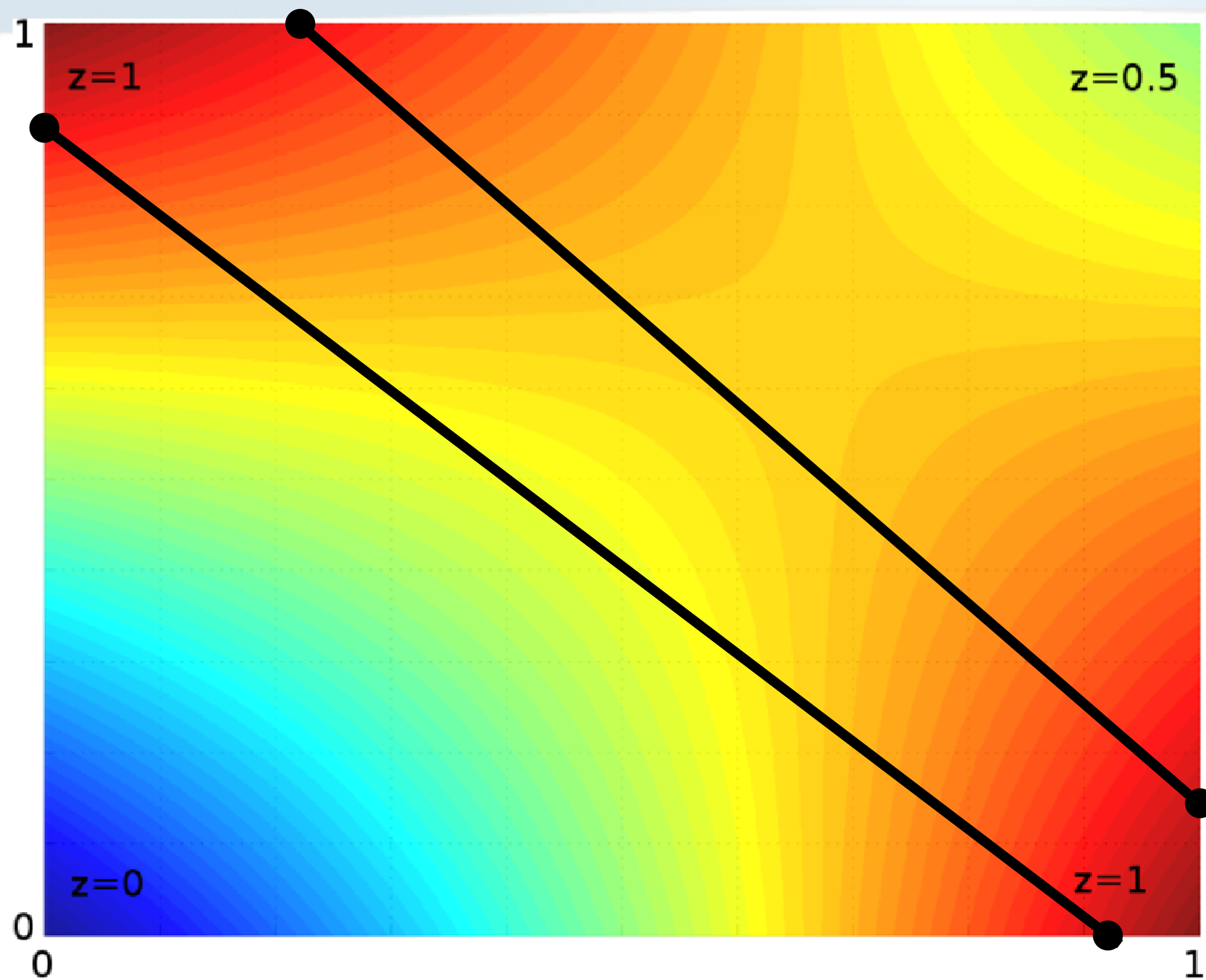


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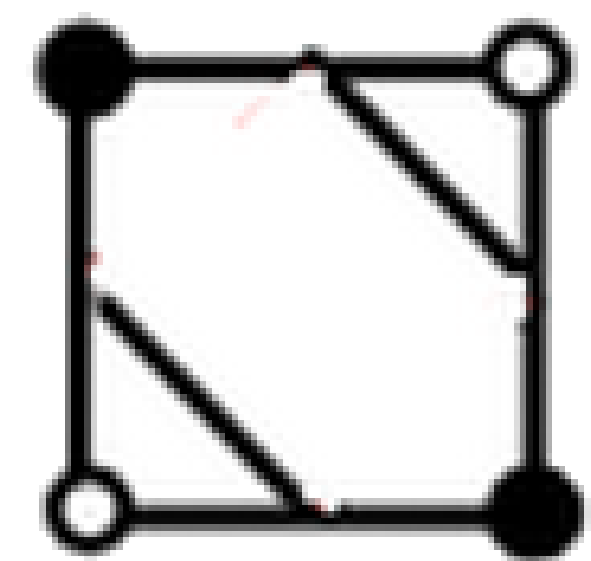


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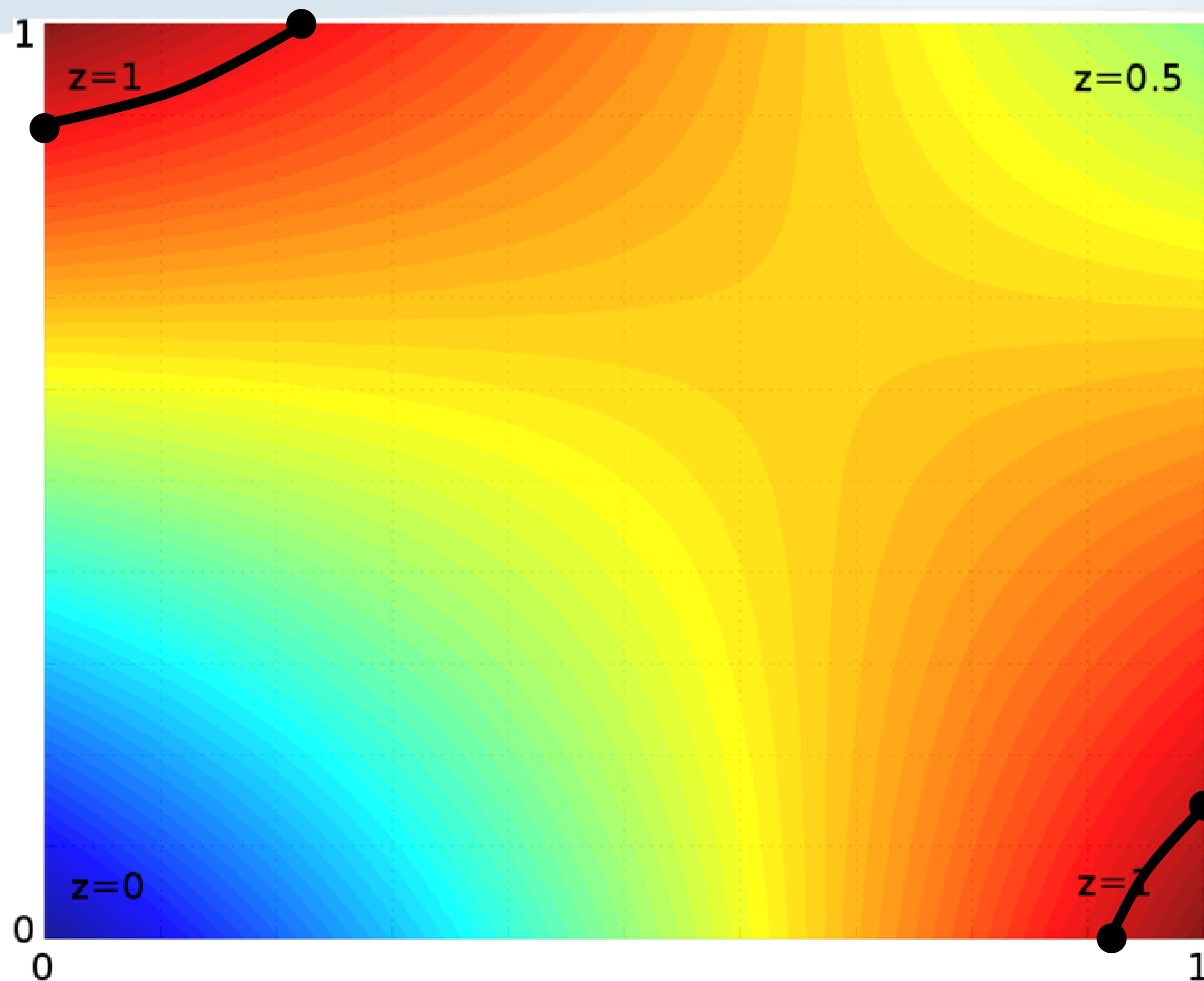


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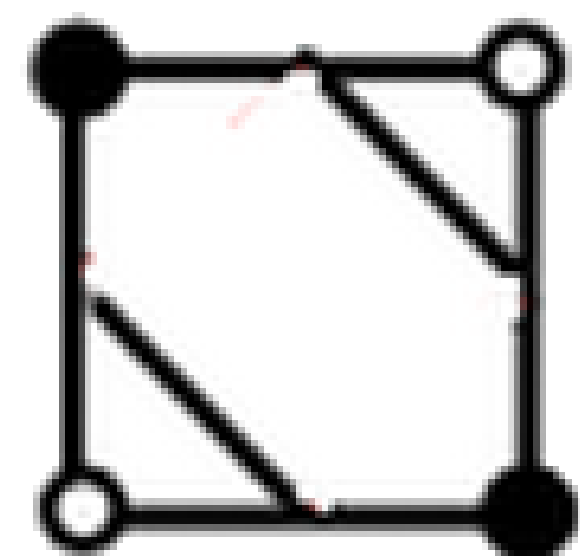


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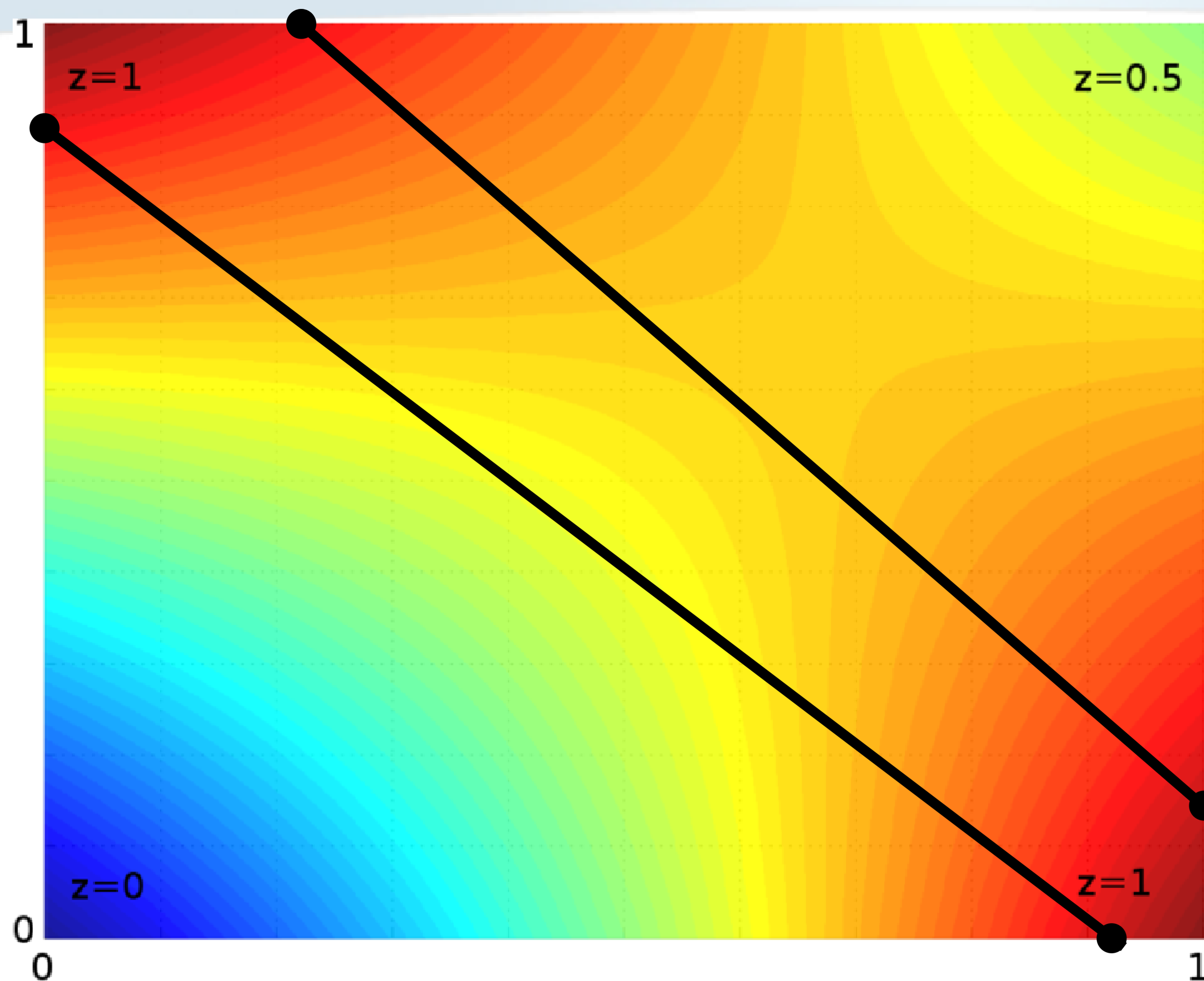


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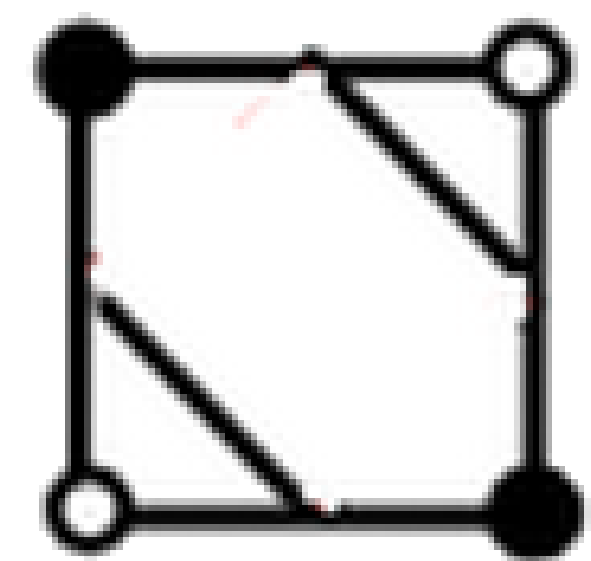


Case 10

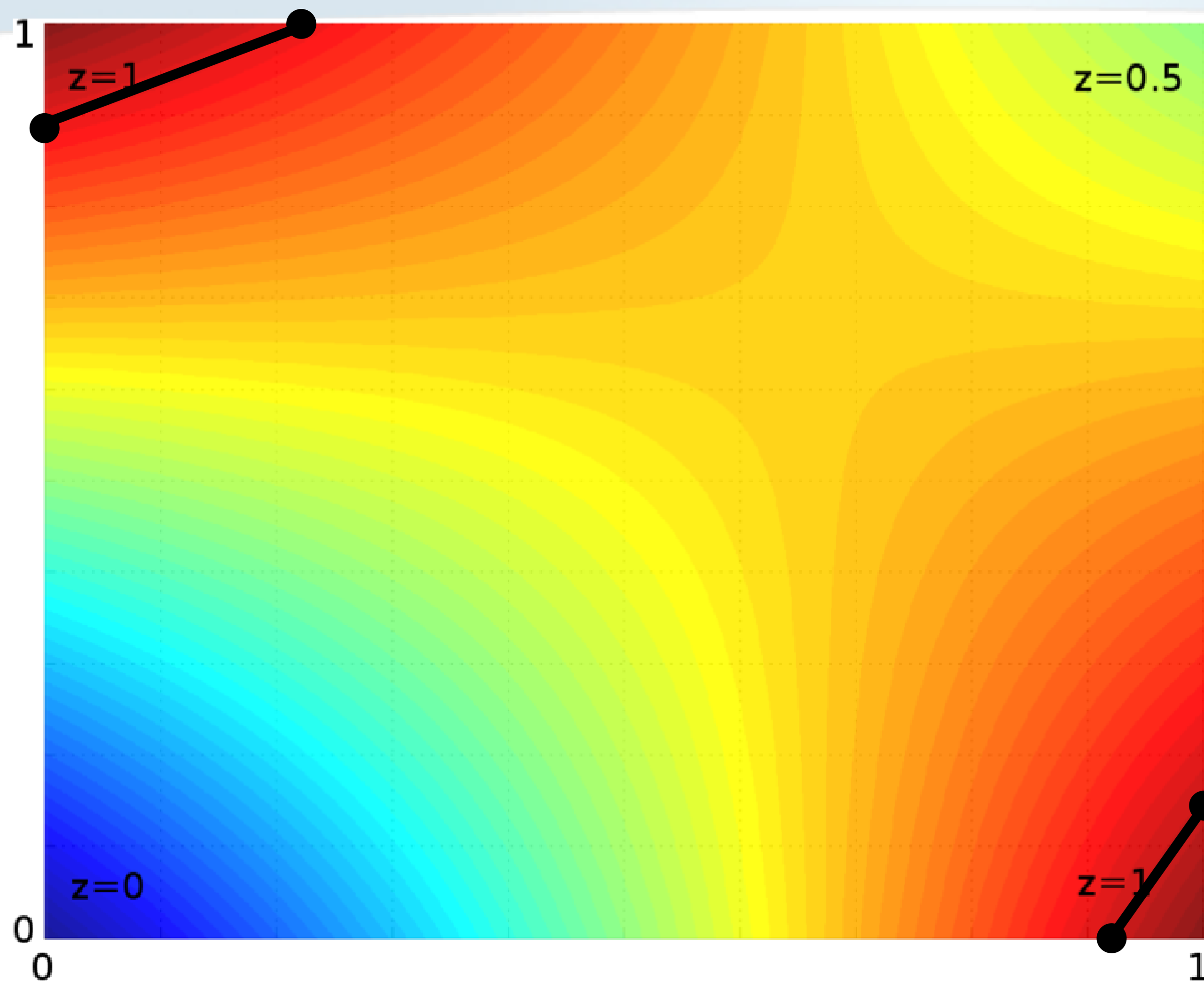


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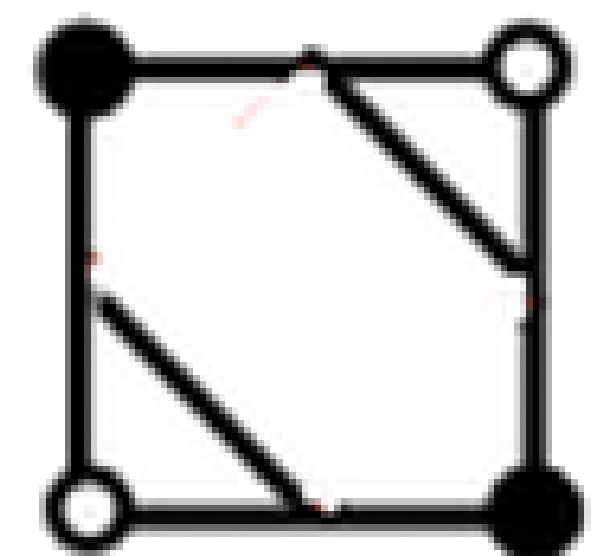


Case 10

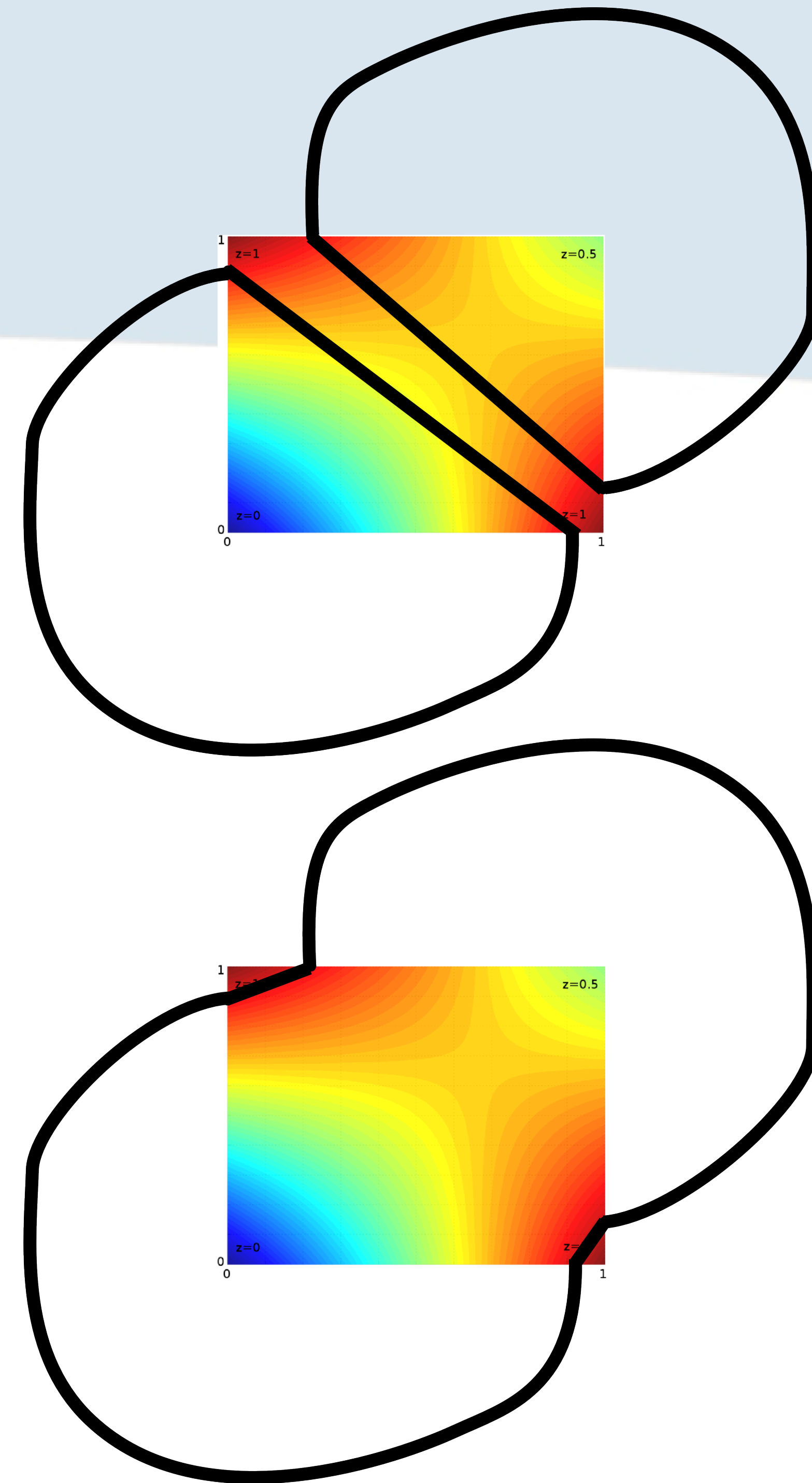
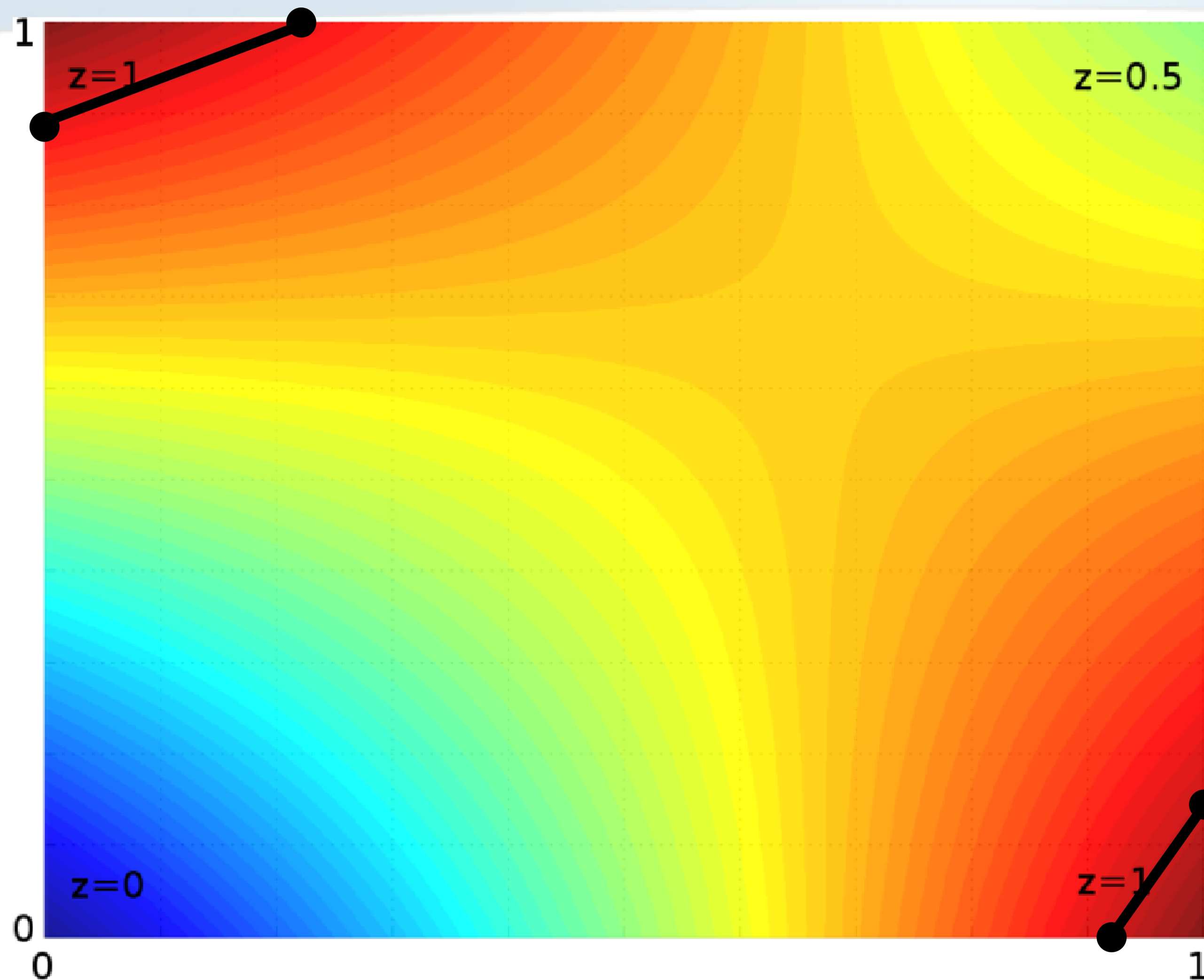


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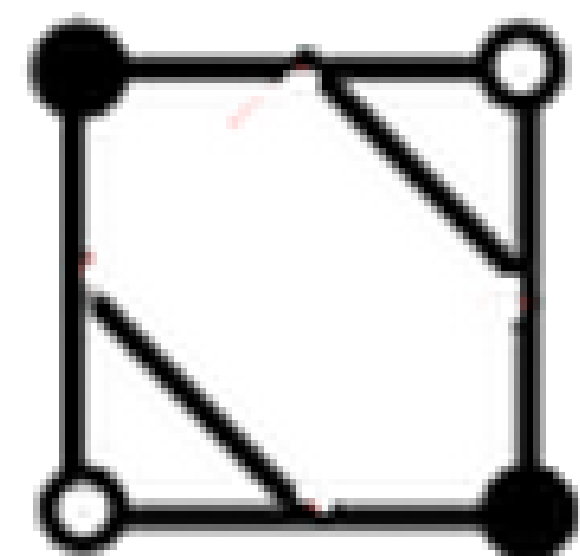


Case 10

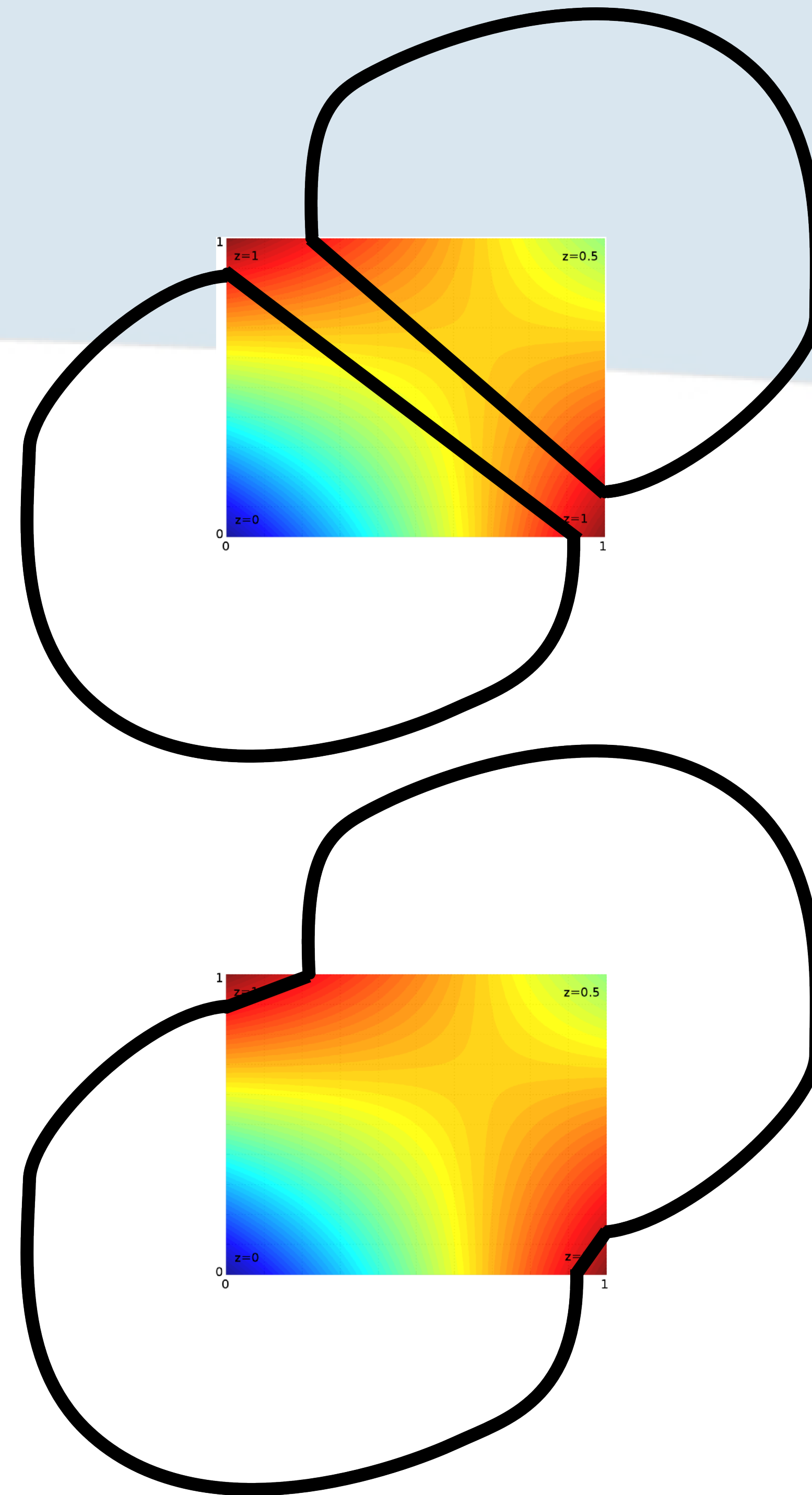
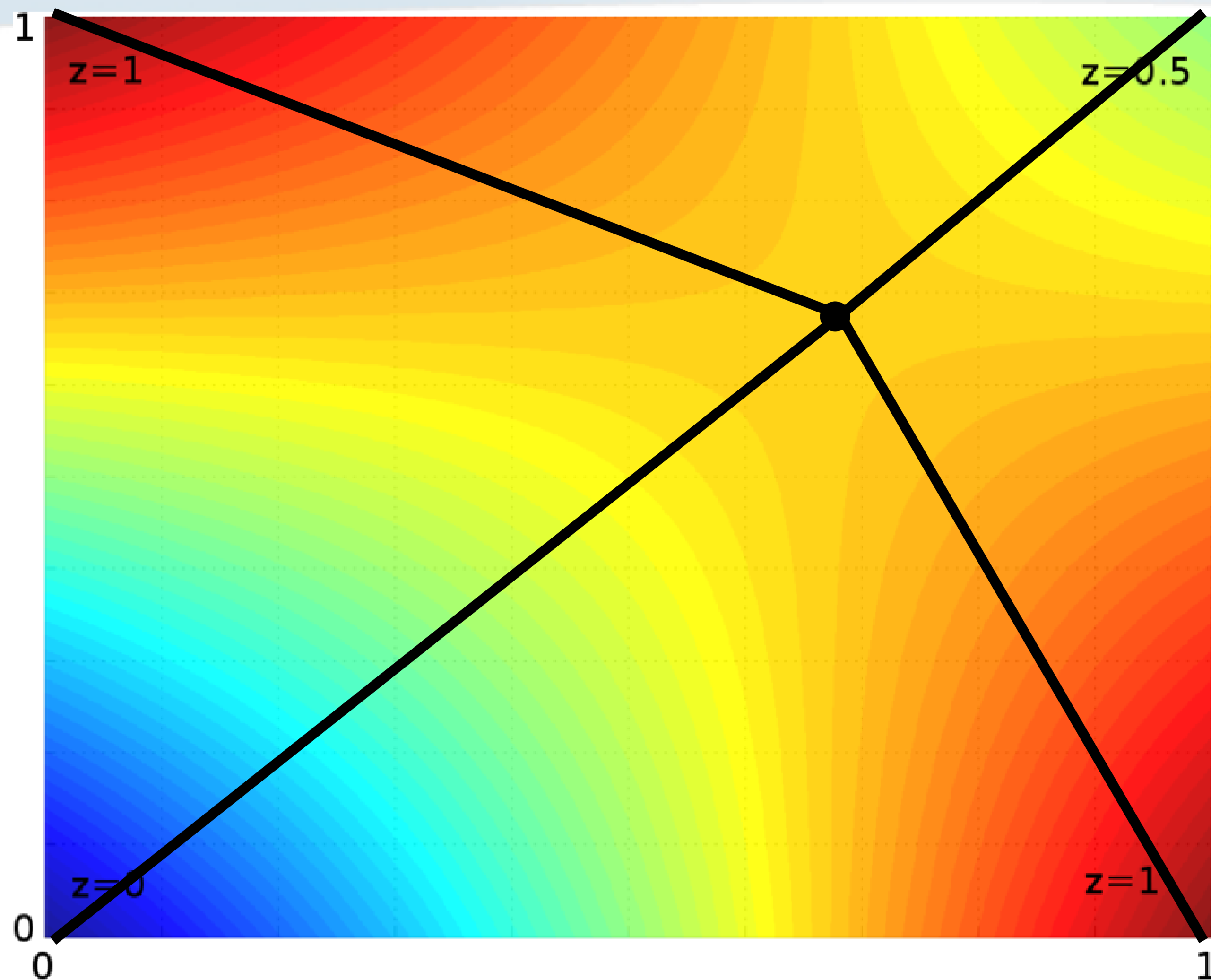


Issues of marching squares

$$f^{-1}(0.95)$$

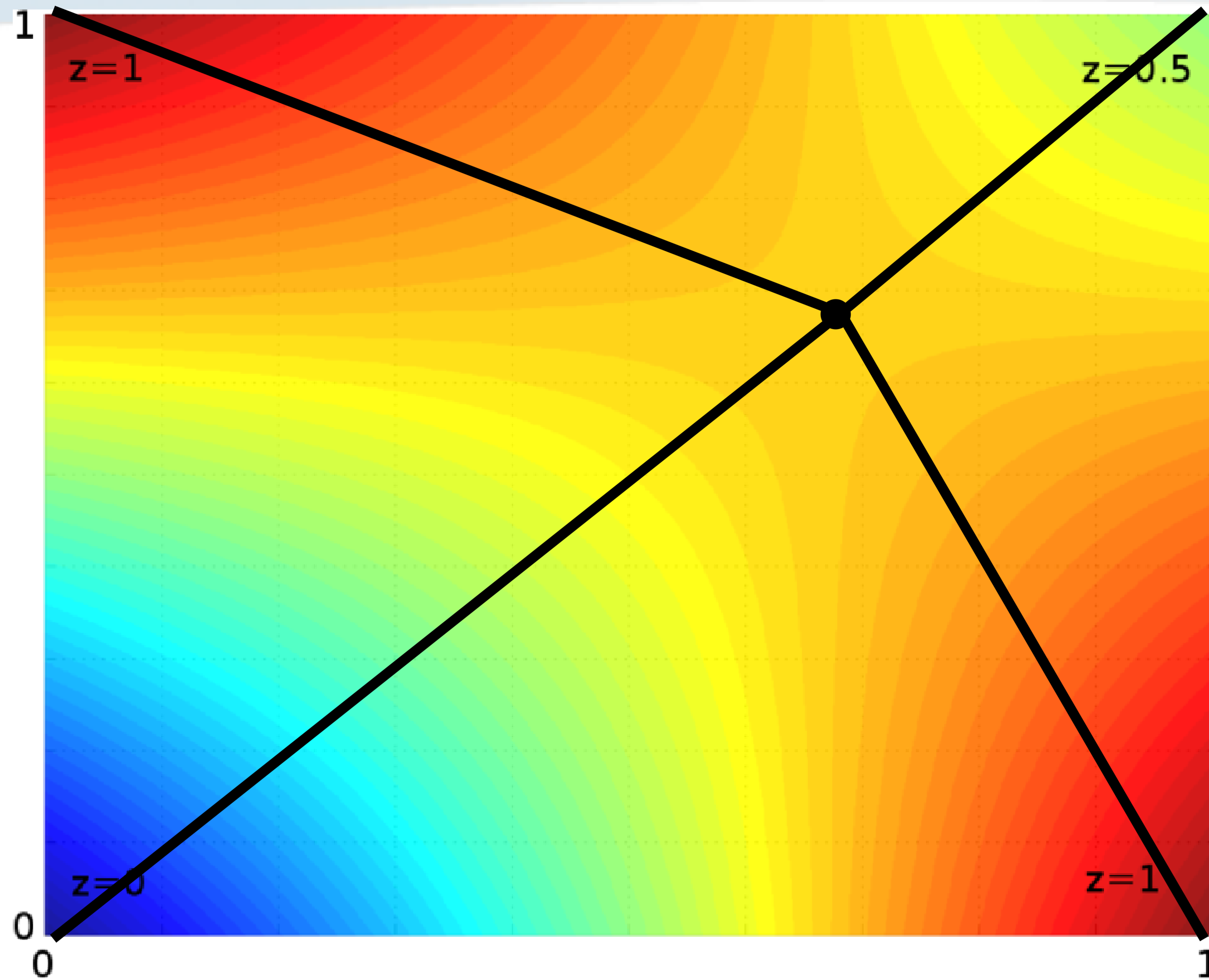
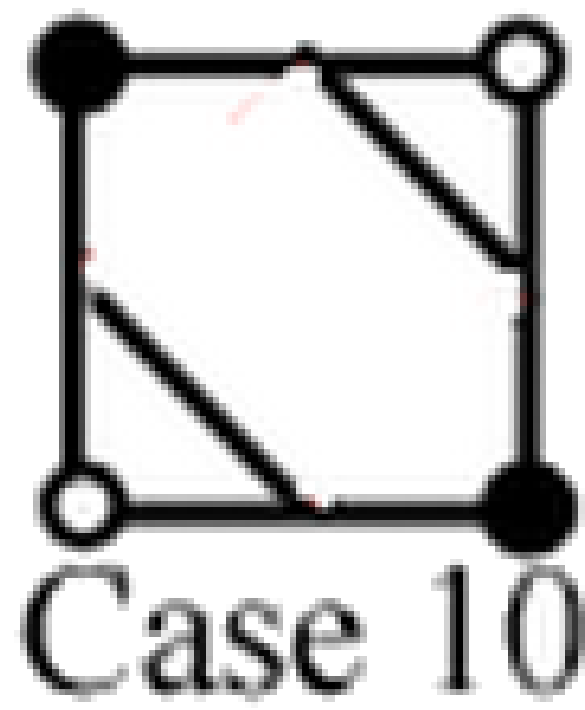


Case 10

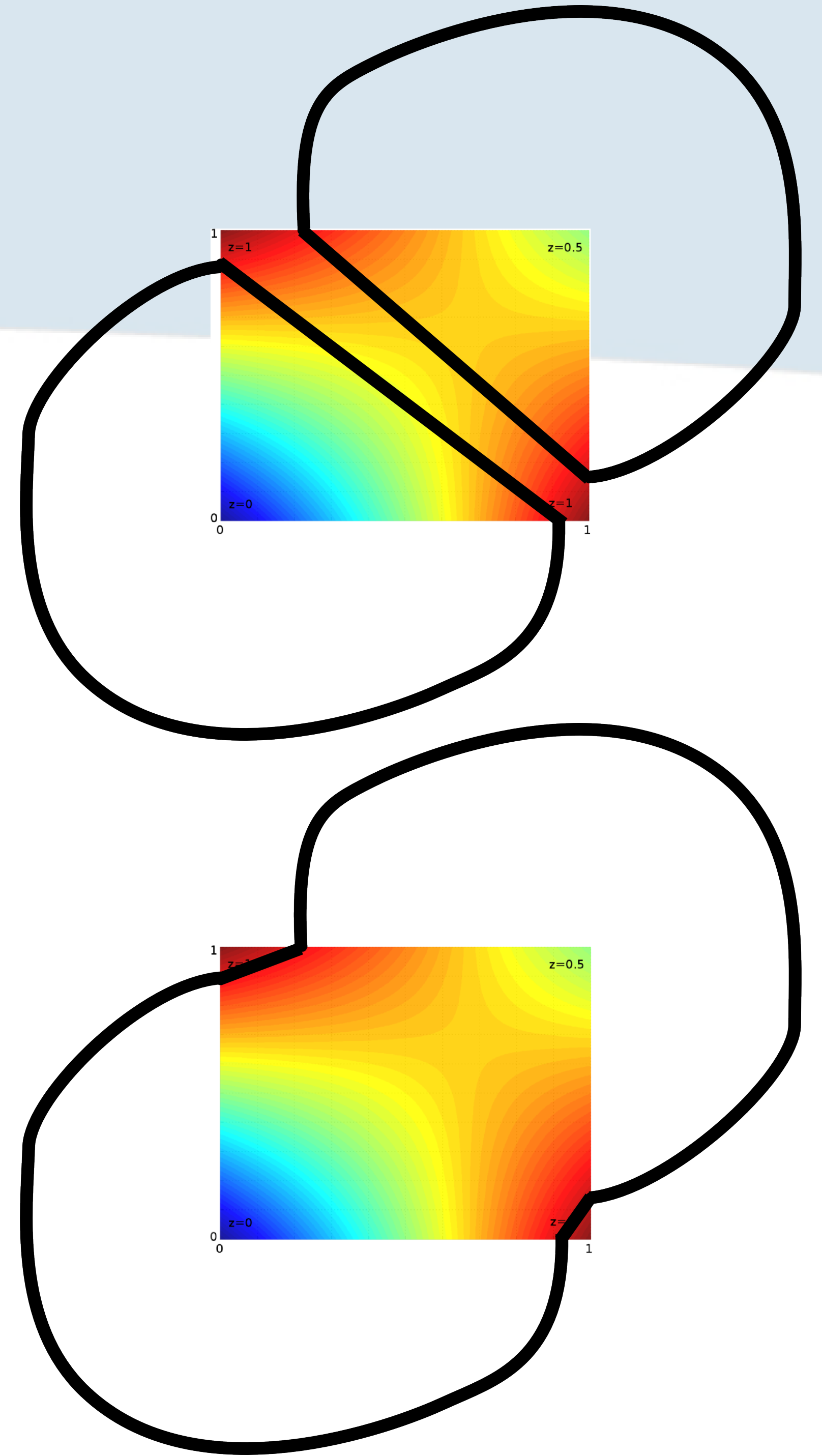


Issues of marching squares

$$f^{-1}(0.95)$$

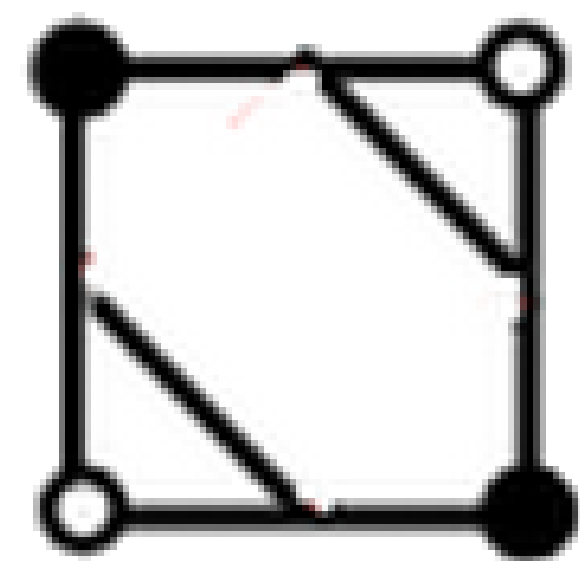


- Geometrically inaccurate (lines)

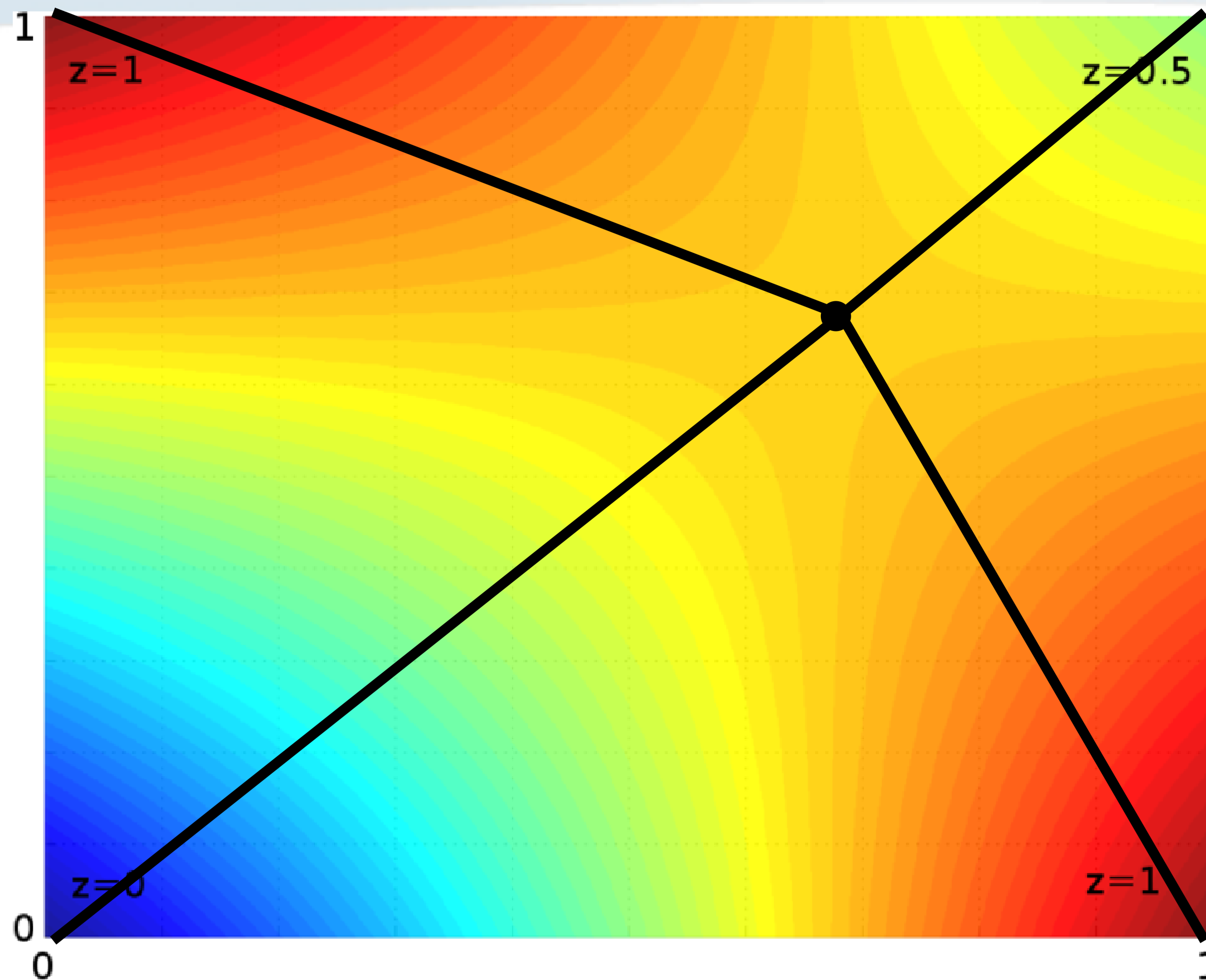


Issues of marching squares

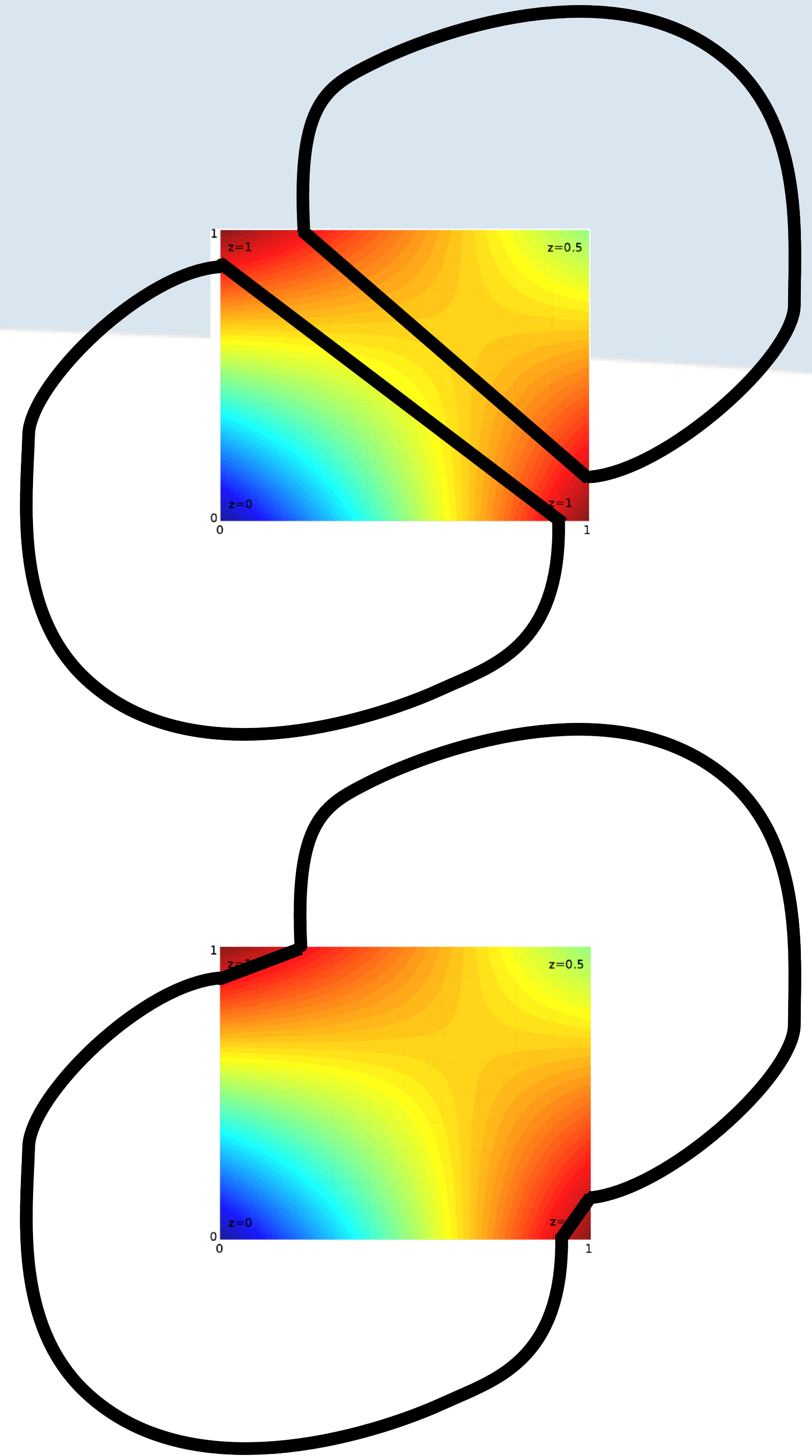
$$f^{-1}(0.95)$$



Case 10

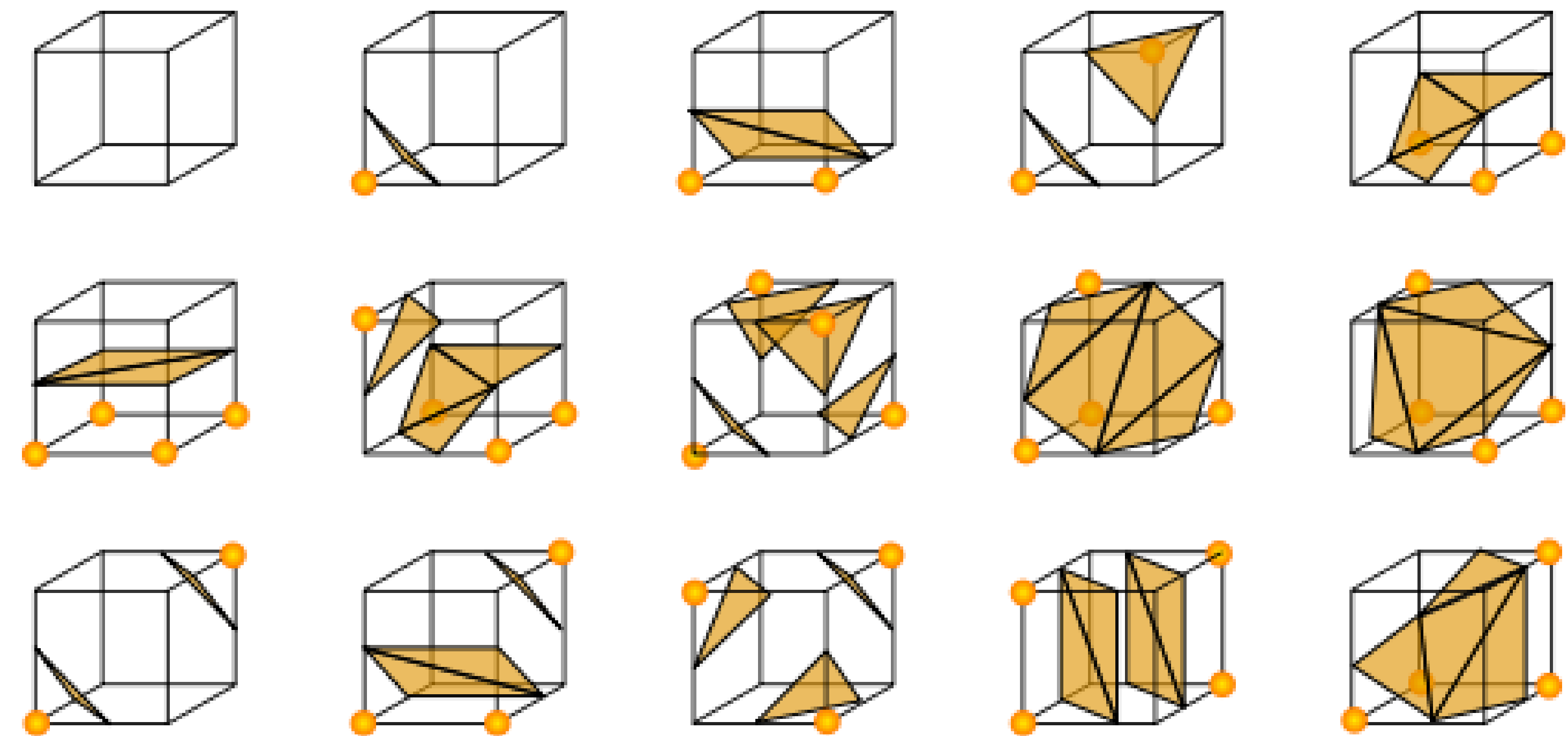


- Geometrically inaccurate (lines)
- Topologically inconsistent (**numerical** estimation of the saddle)



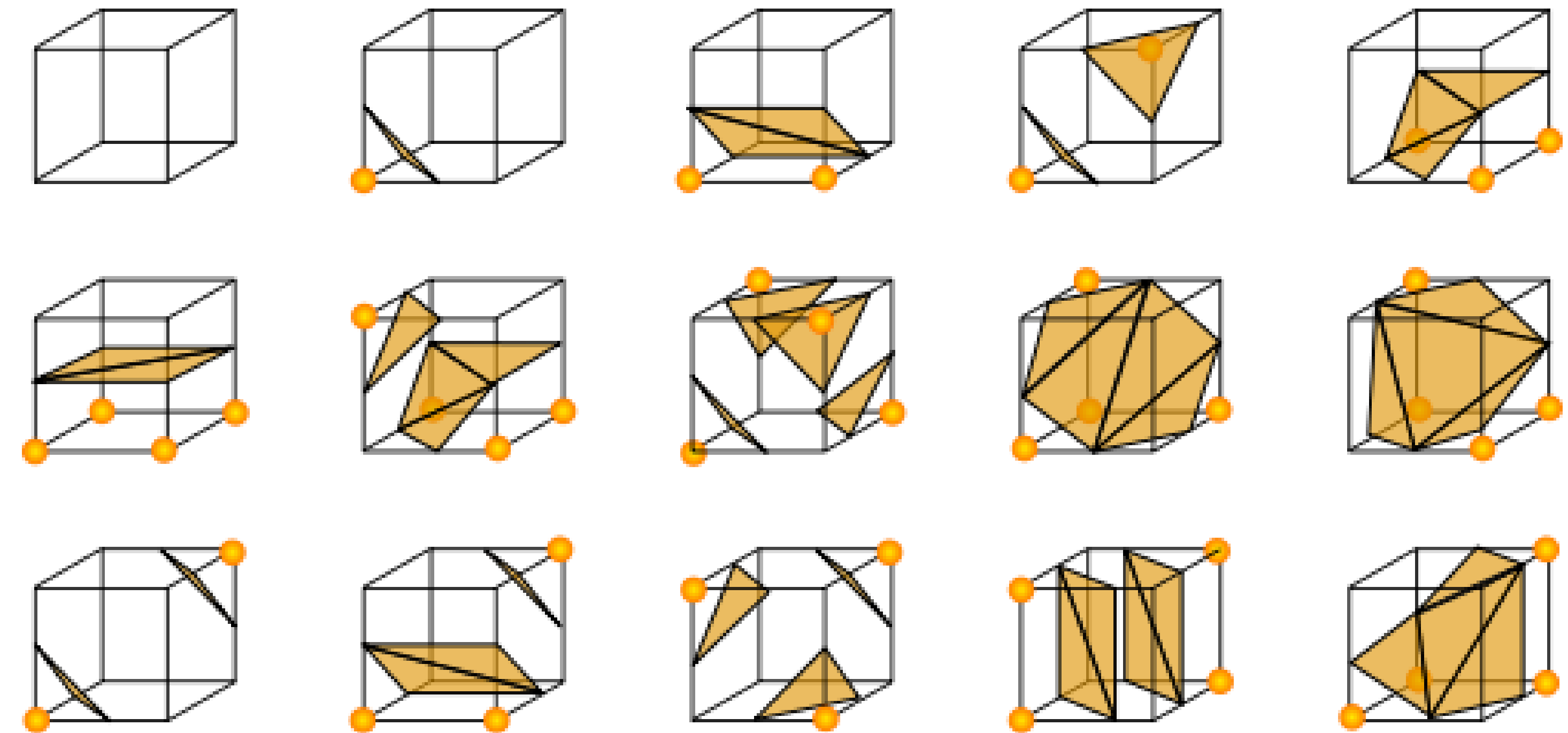
Marching cubes

- Let \mathcal{D} be a 3-regular grid
- With trilinear interpolant



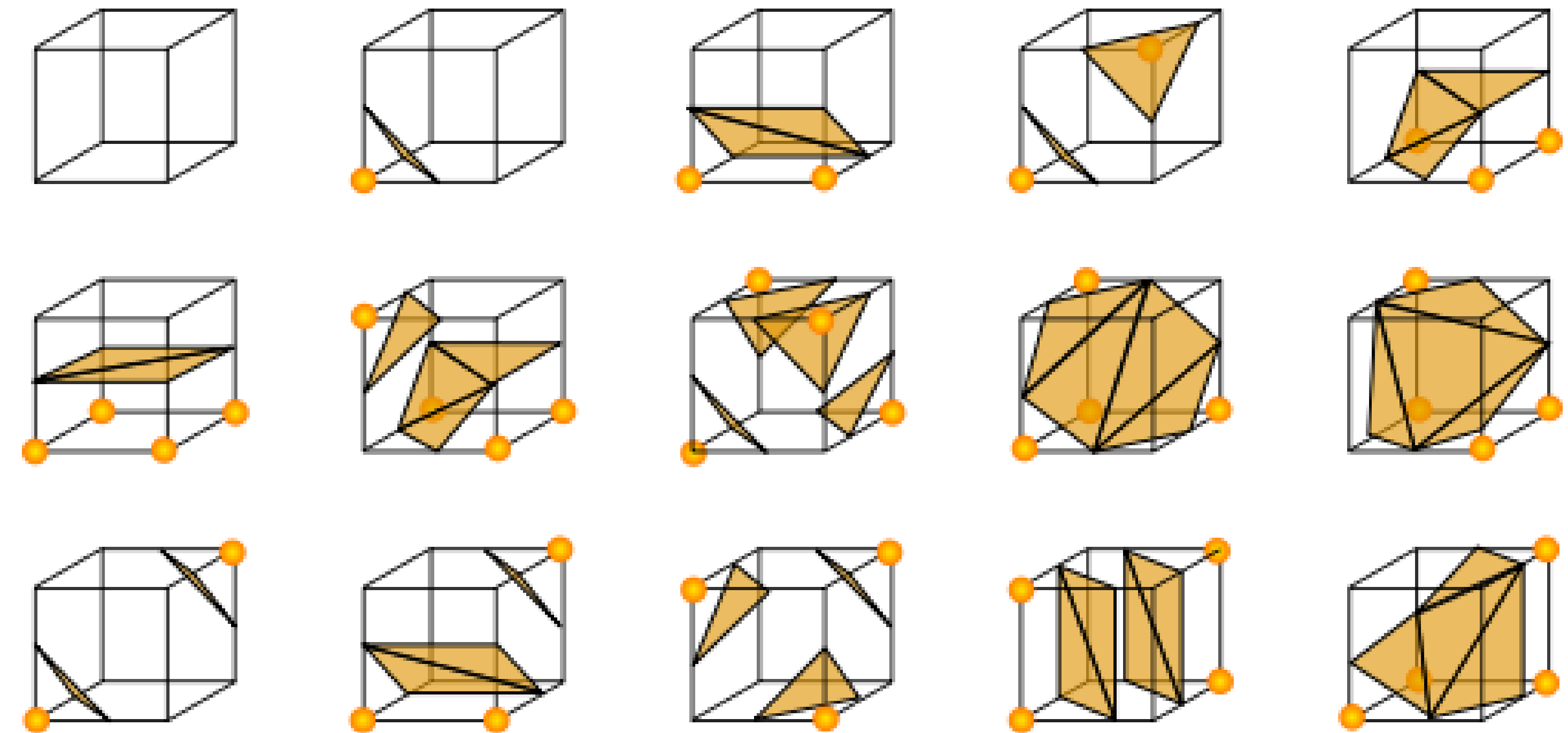
Marching cubes

- Let \mathcal{D} be a 3-regular grid
 - With trilinear interpolant
- Level set extraction
 - Loop over the unit cells



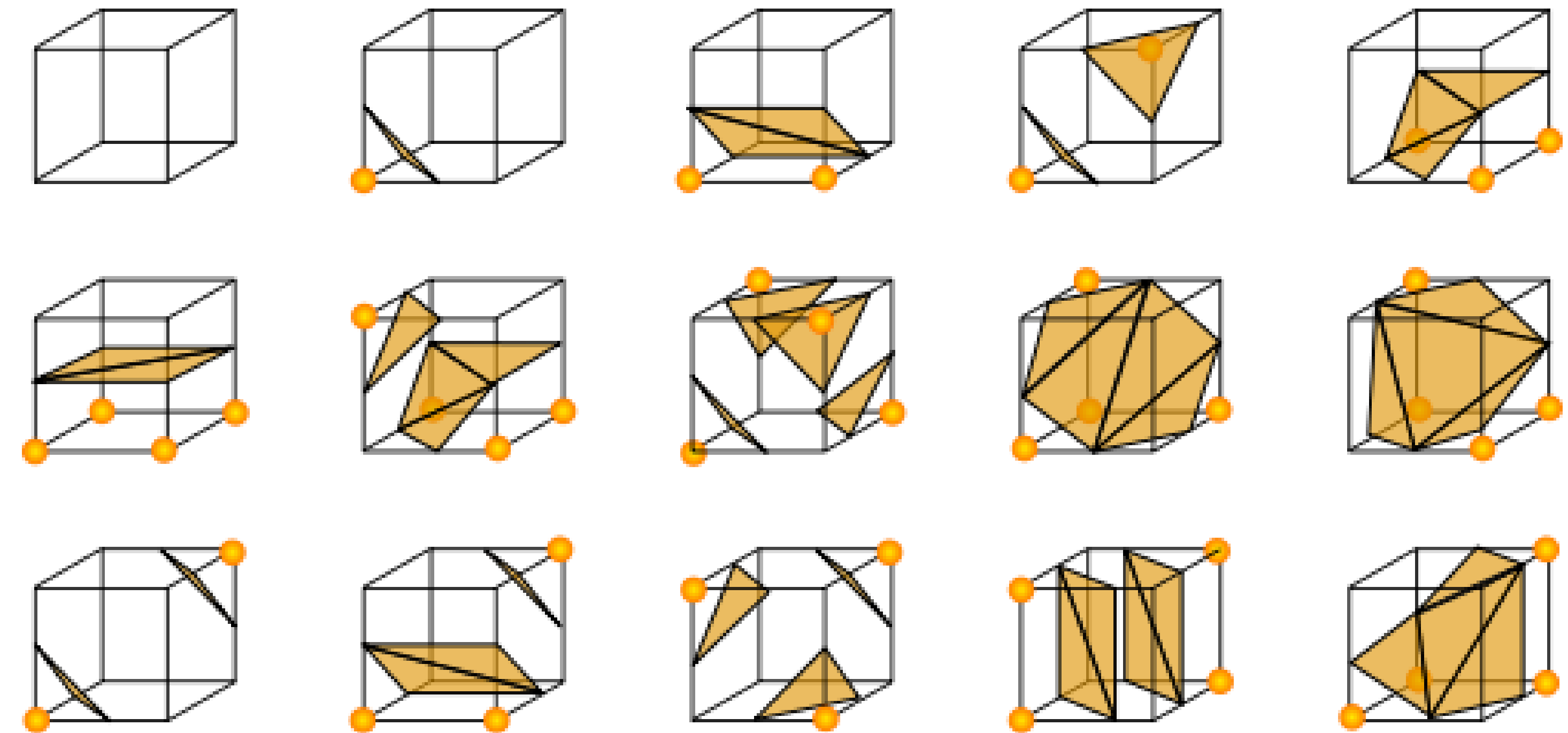
Marching cubes

- Let \mathcal{D} be a 3-regular grid
 - With trilinear interpolant
- Level set extraction
 - Loop over the unit cells
 - Cases on a 3D unit cell



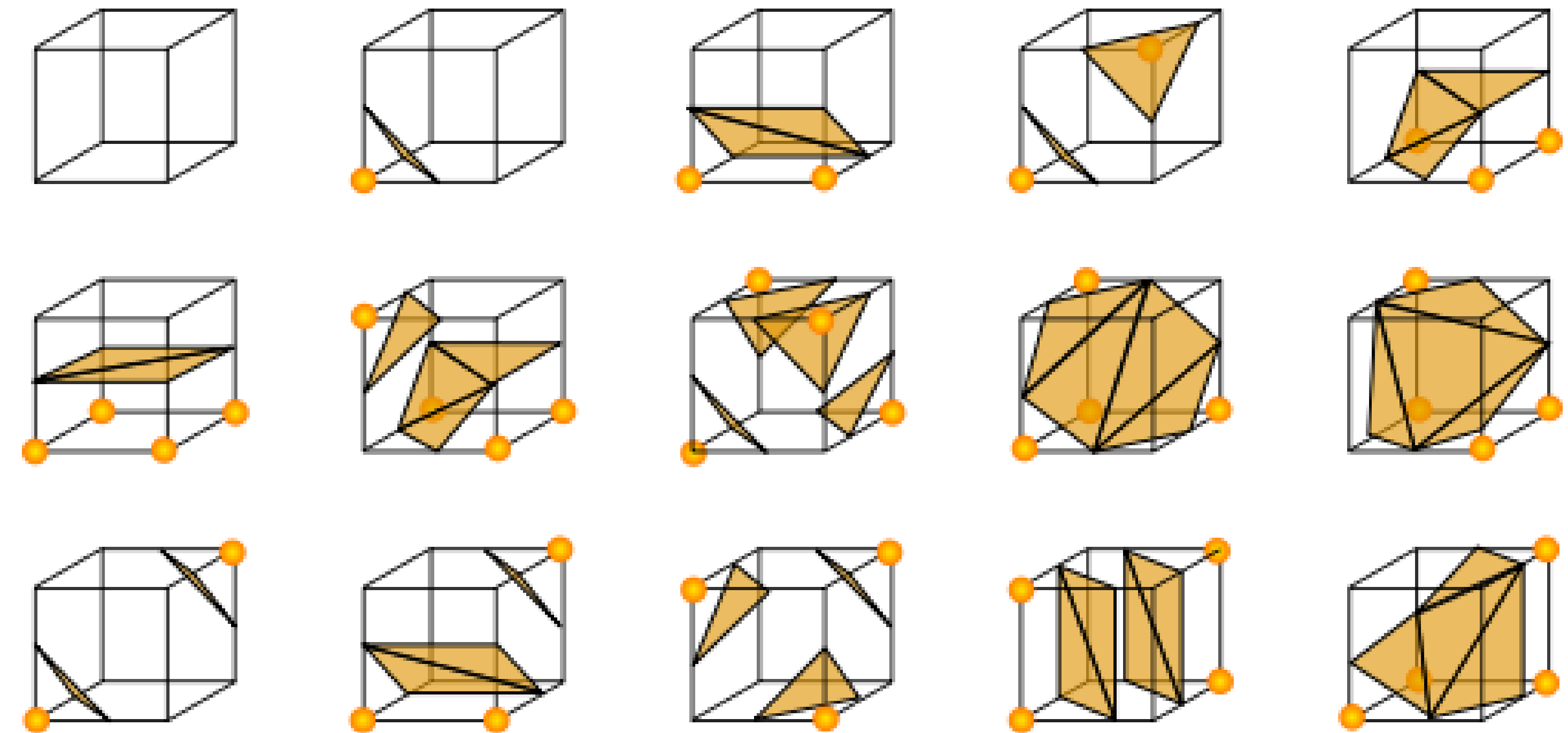
Marching cubes

- Let \mathcal{D} be a 3-regular grid
 - With trilinear interpolant
- Level set extraction
 - Loop over the unit cells
 - Cases on a 3D unit cell
 - 256 cases



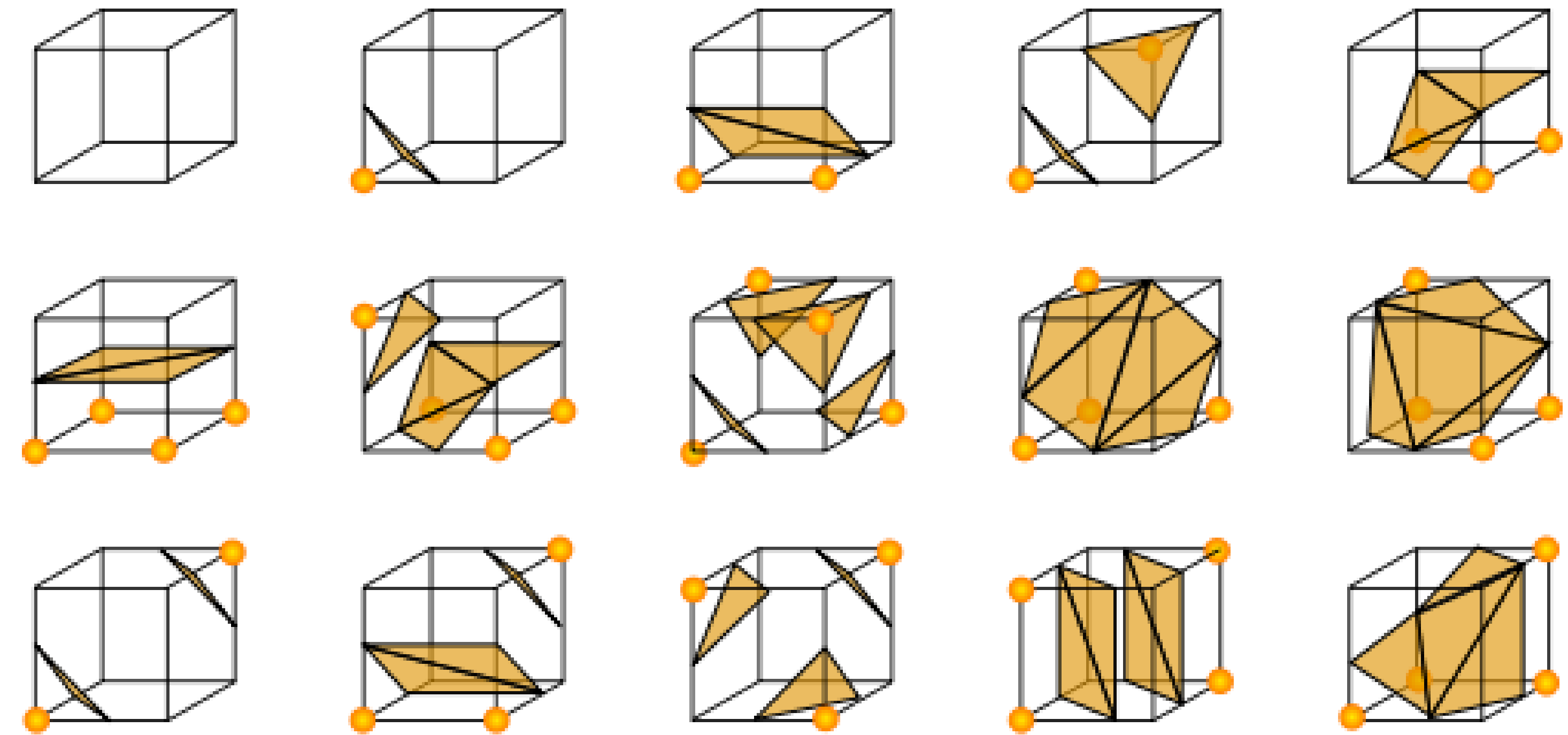
Issues of marching cubes

- Same as before



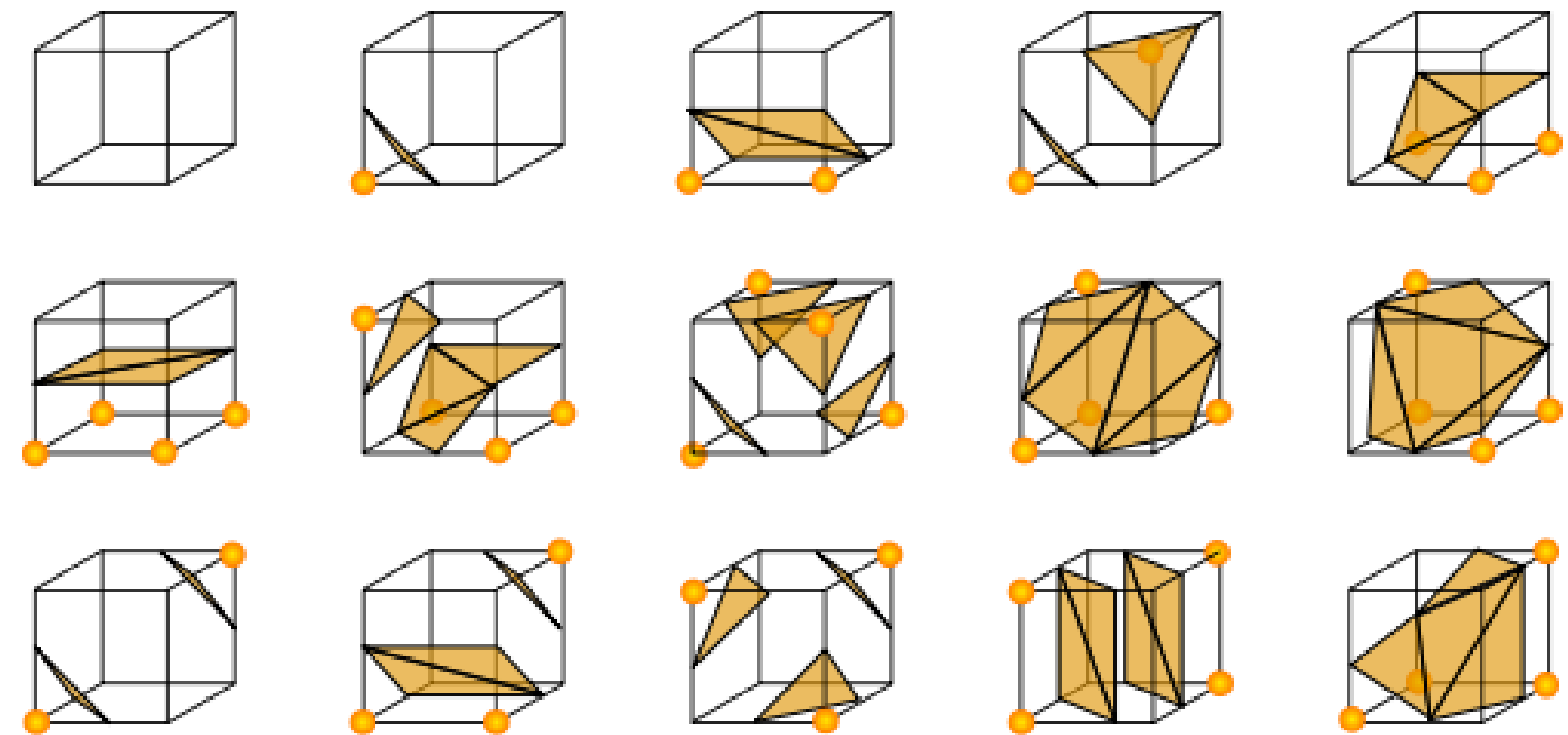
Issues of marching cubes

- Same as before
 - But worse!



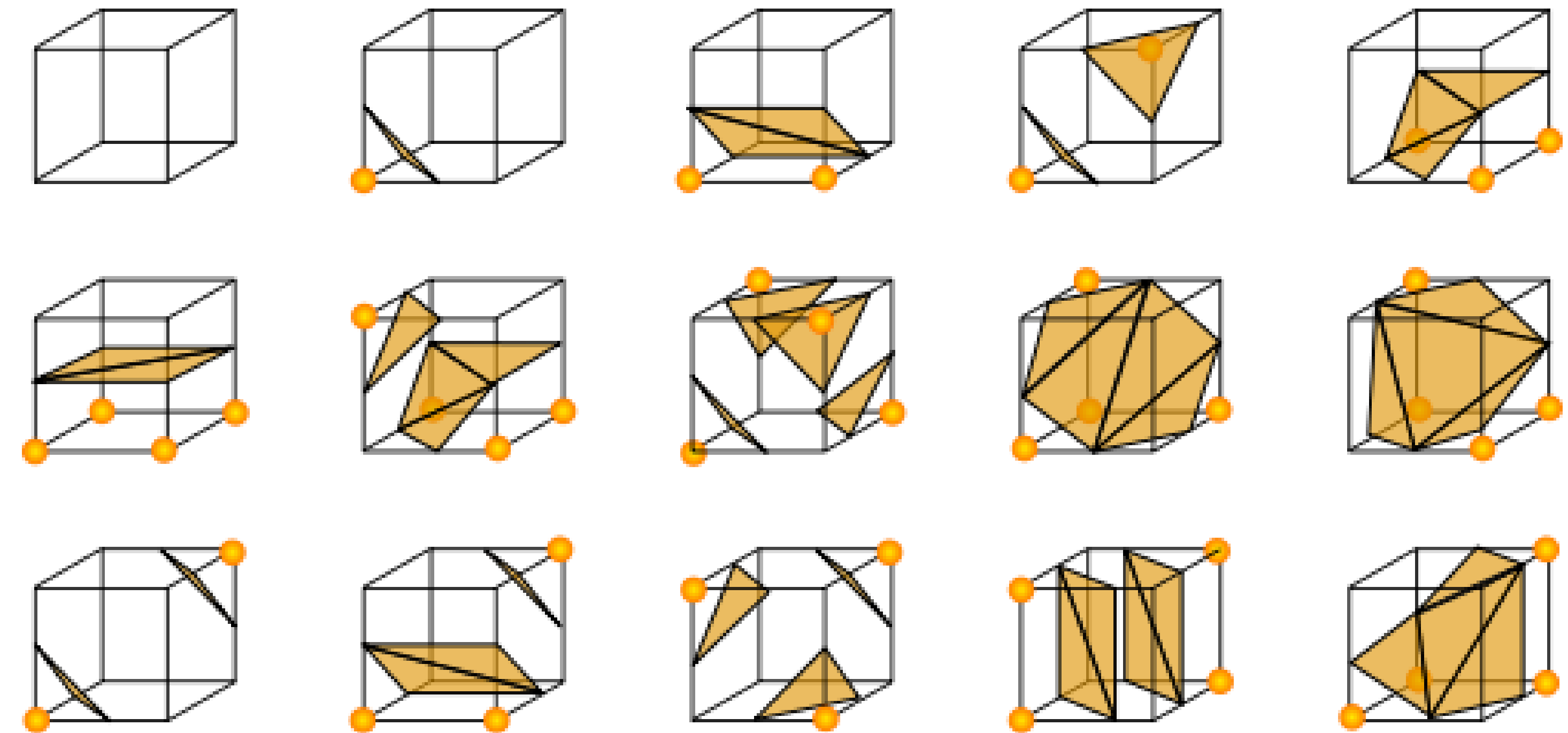
Issues of marching cubes

- Same as before
 - But worse!
- Lorensen and Cline 1987



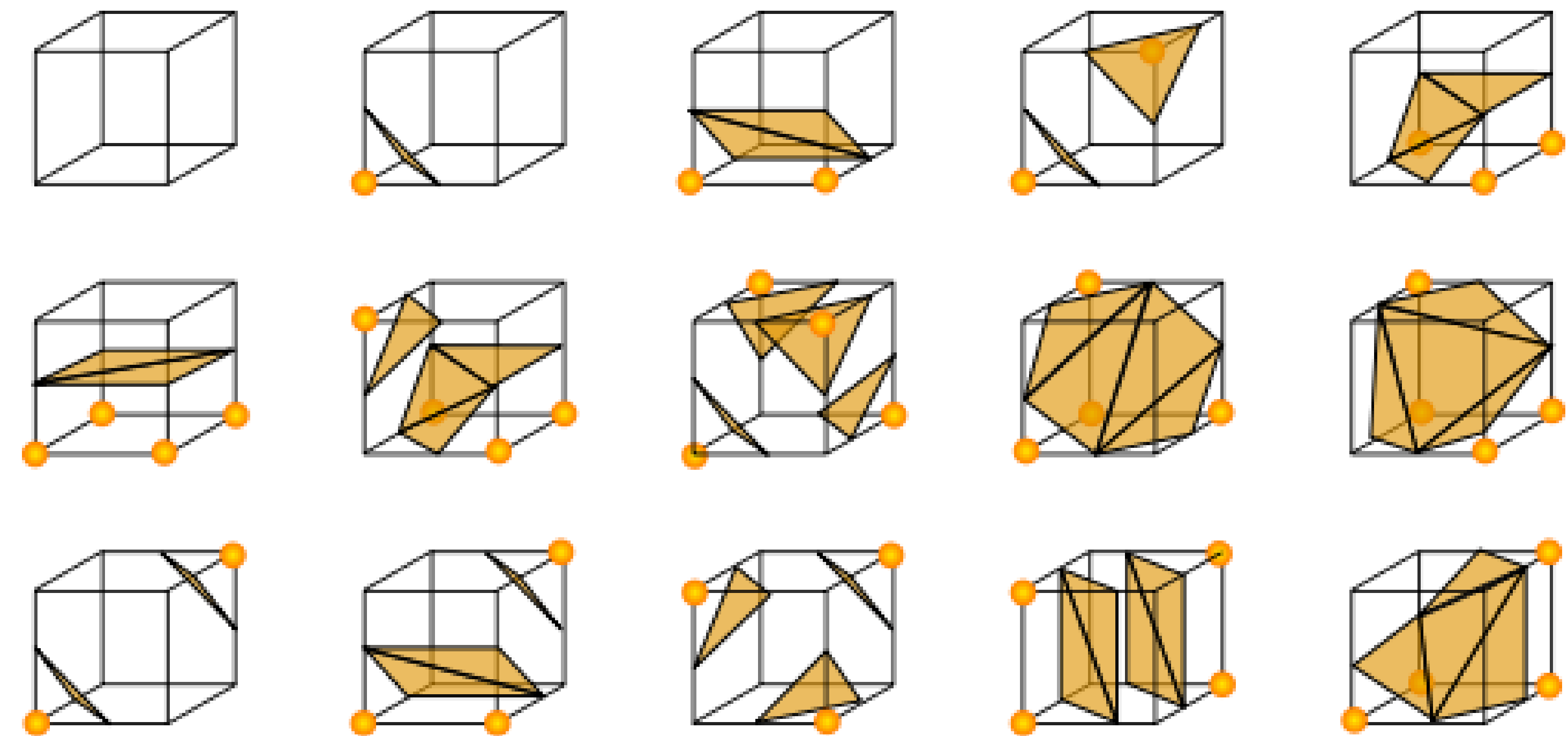
Issues of marching cubes

- Same as before
 - But worse!
- Lorensen and Cline 1987
 - 16 cases (symmetries)



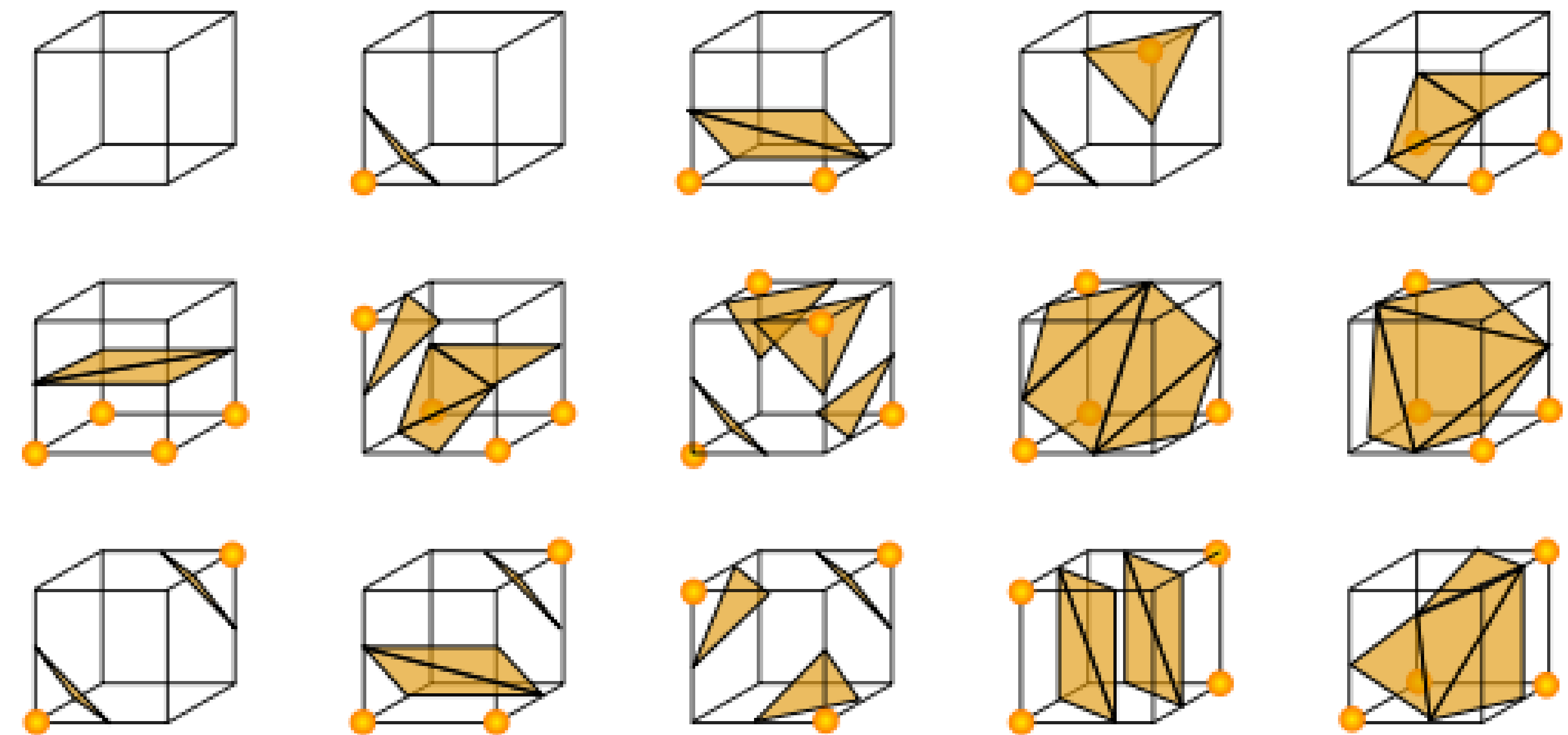
Issues of marching cubes

- Same as before
 - But worse!
- Lorensen and Cline 1987
 - 16 cases (symmetries)
 - Possible cracks



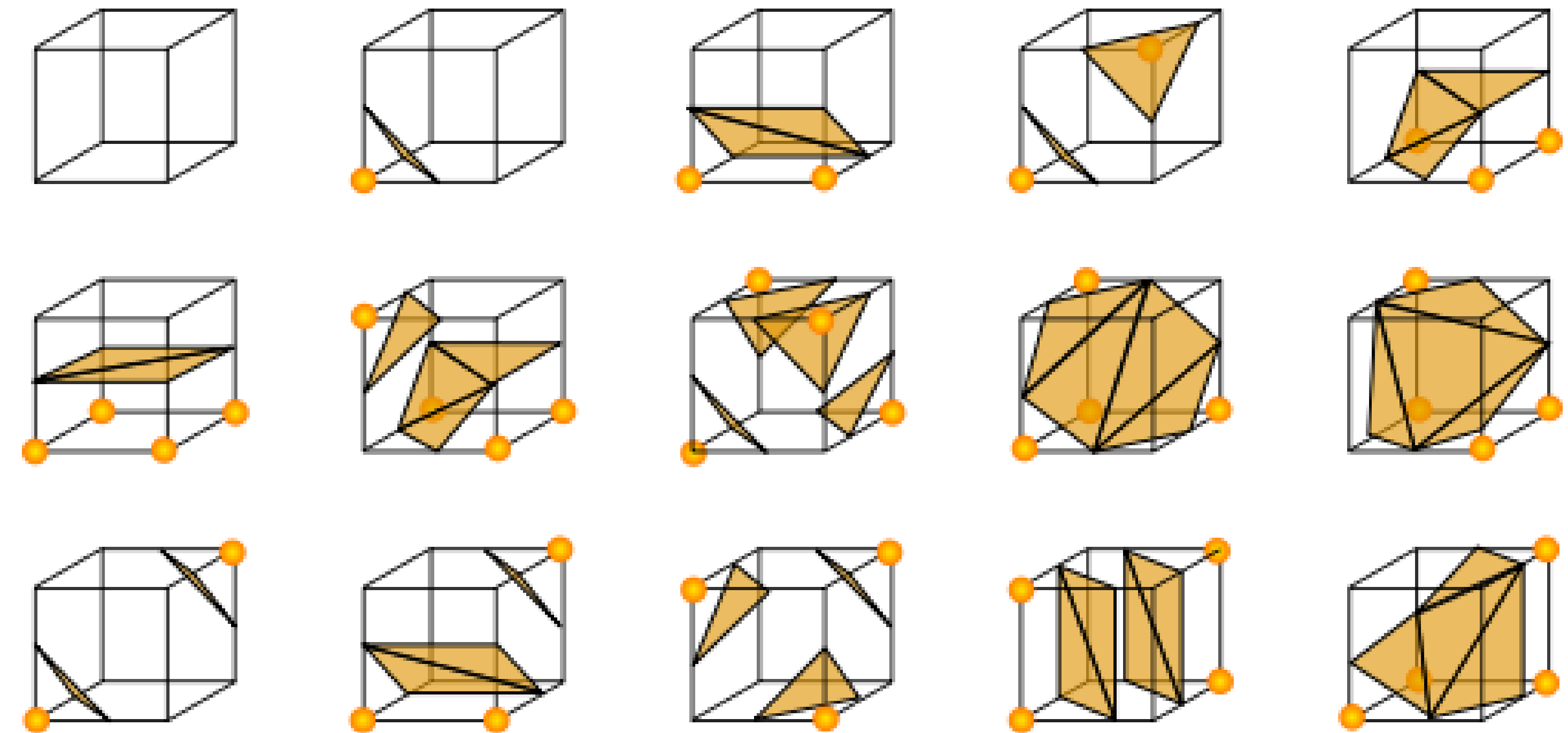
Issues of marching cubes

- Same as before
 - But worse!
- Lorensen and Cline 1987
 - 16 cases (symmetries)
 - Possible cracks
 - Improvement 28 cases



Issues of marching cubes

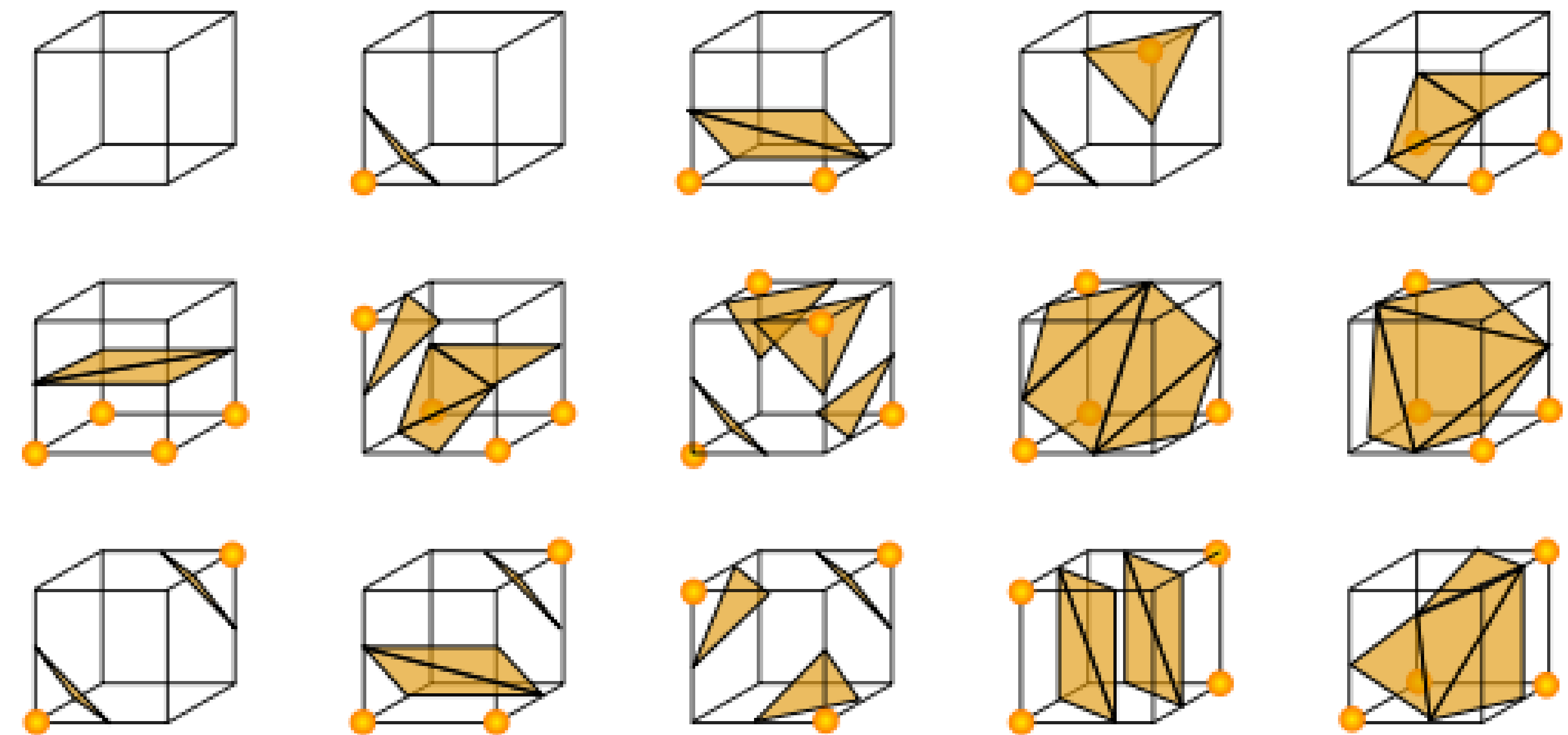
- Same as before
 - But worse!
- Lorensen and Cline 1987
 - 16 cases (symmetries)
 - Possible cracks
 - Improvement 28 cases
- Saddle curve (components and genus):



[Wikipedia]

Issues of marching cubes

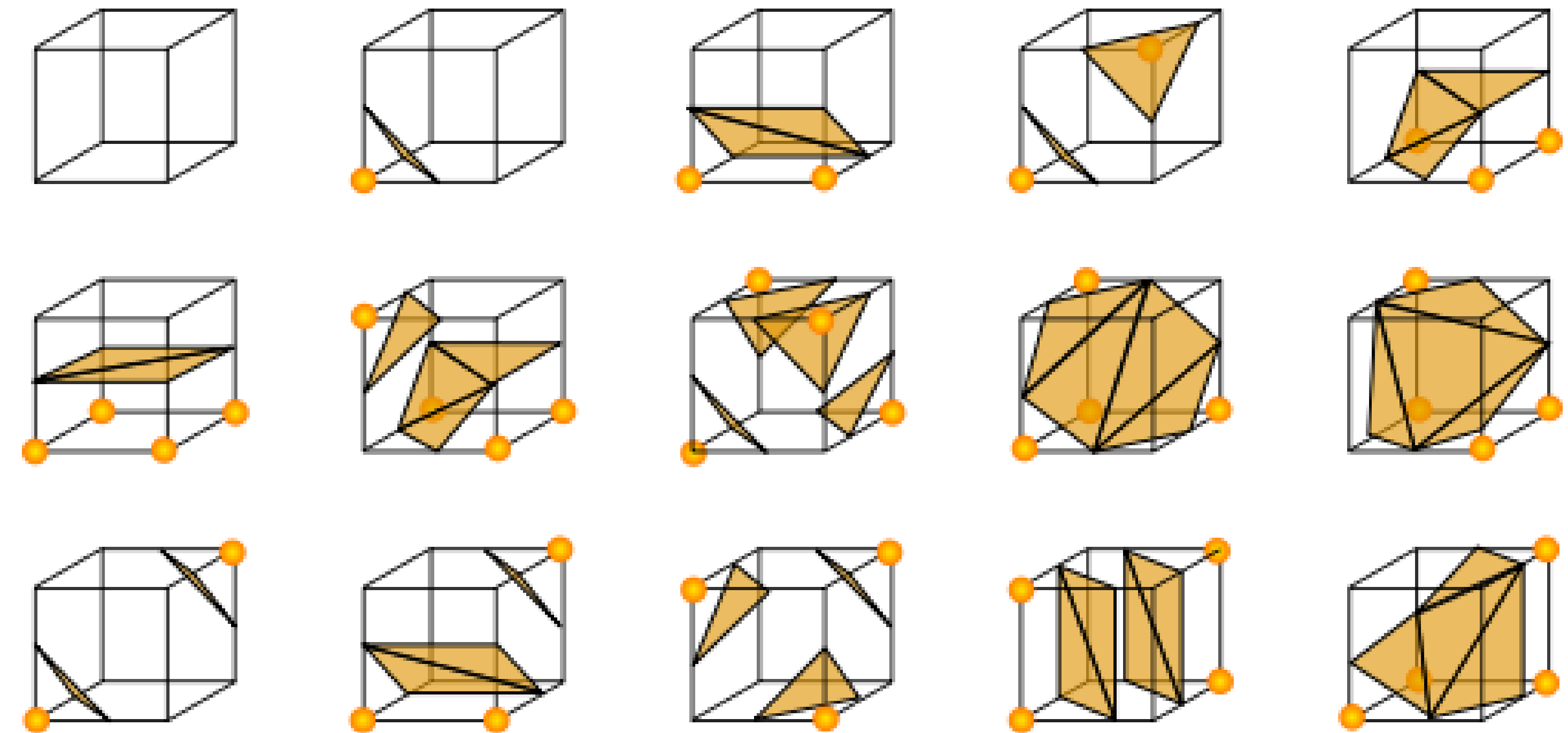
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[Wikipedia]

Issues of marching cubes

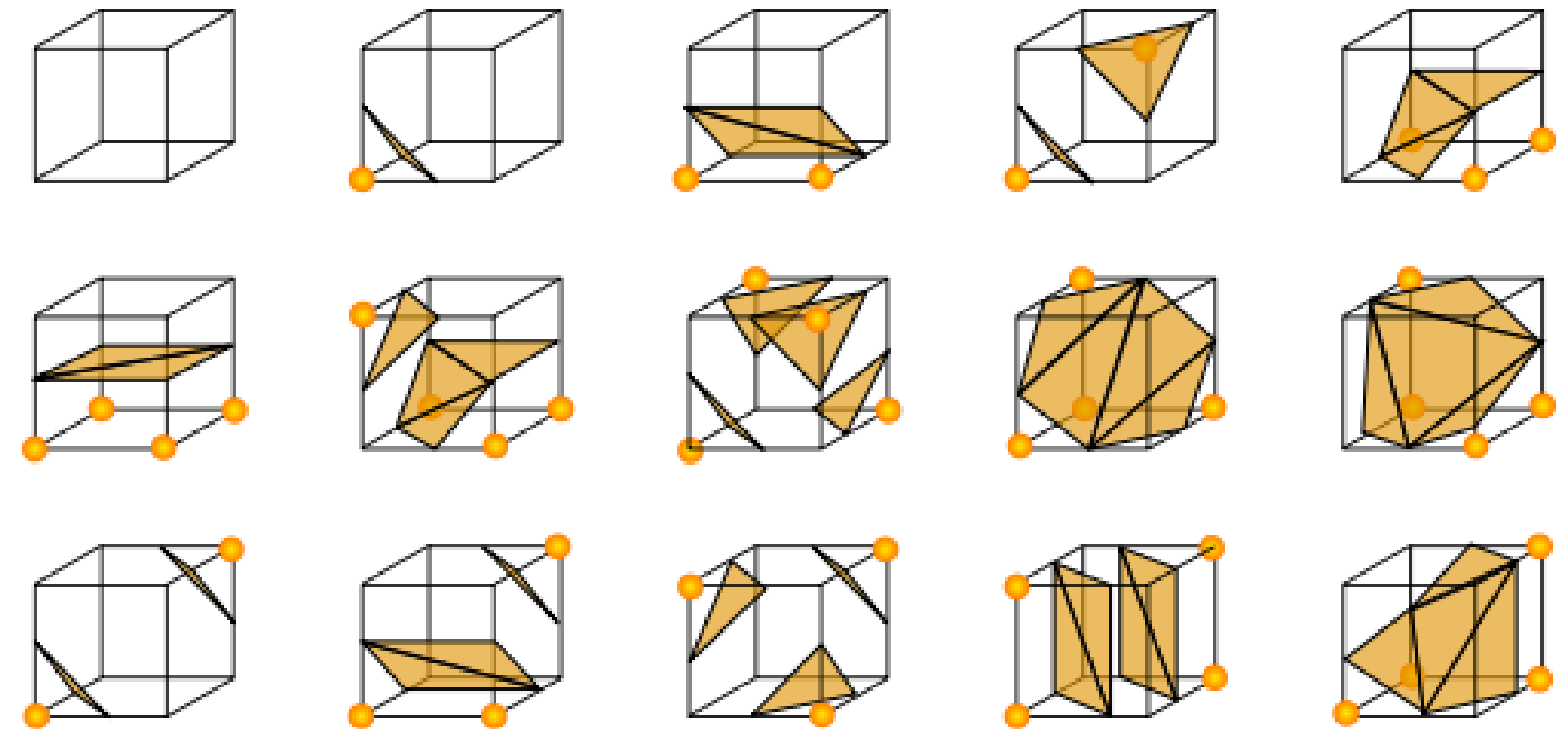
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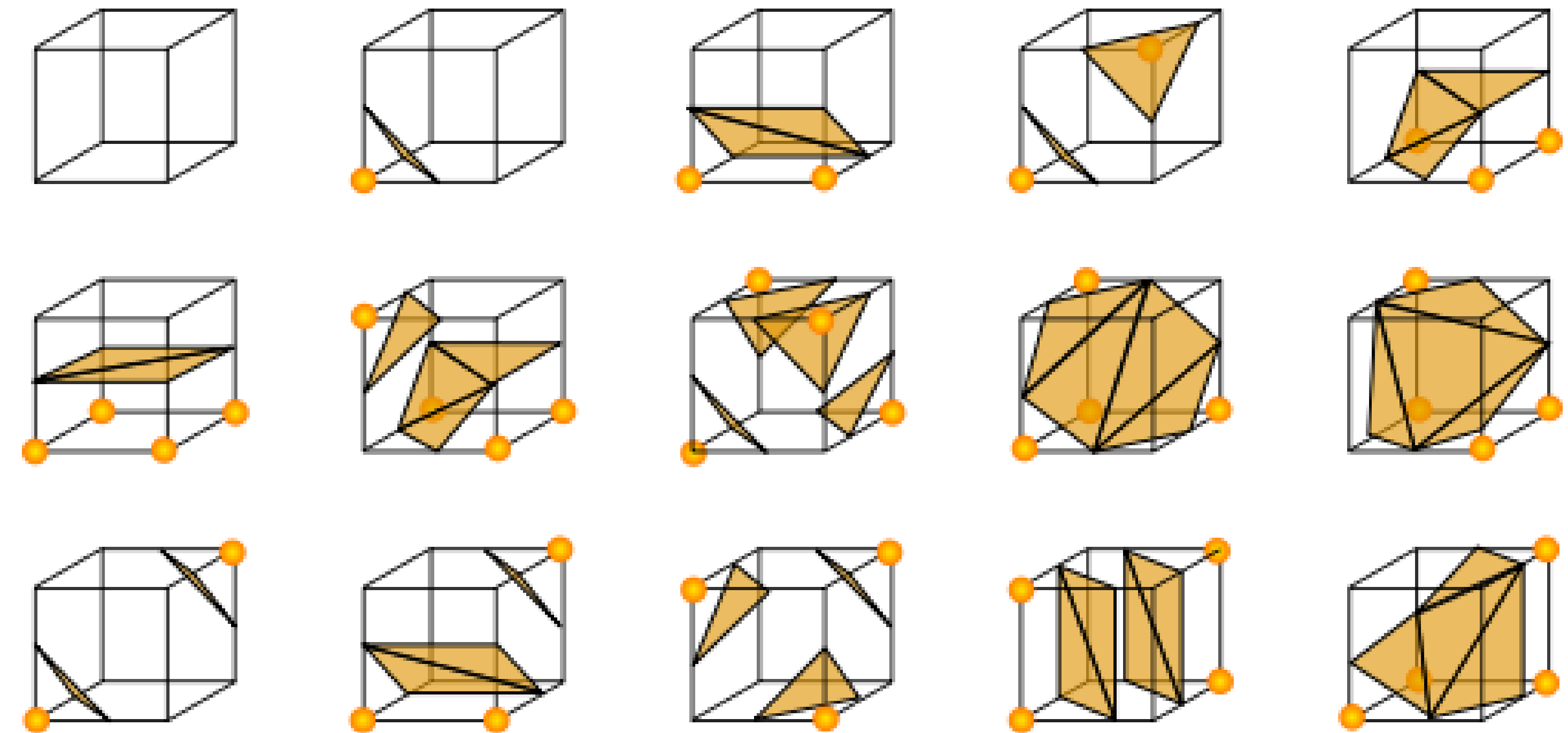
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[Wikipedia]

Issues of marching cubes

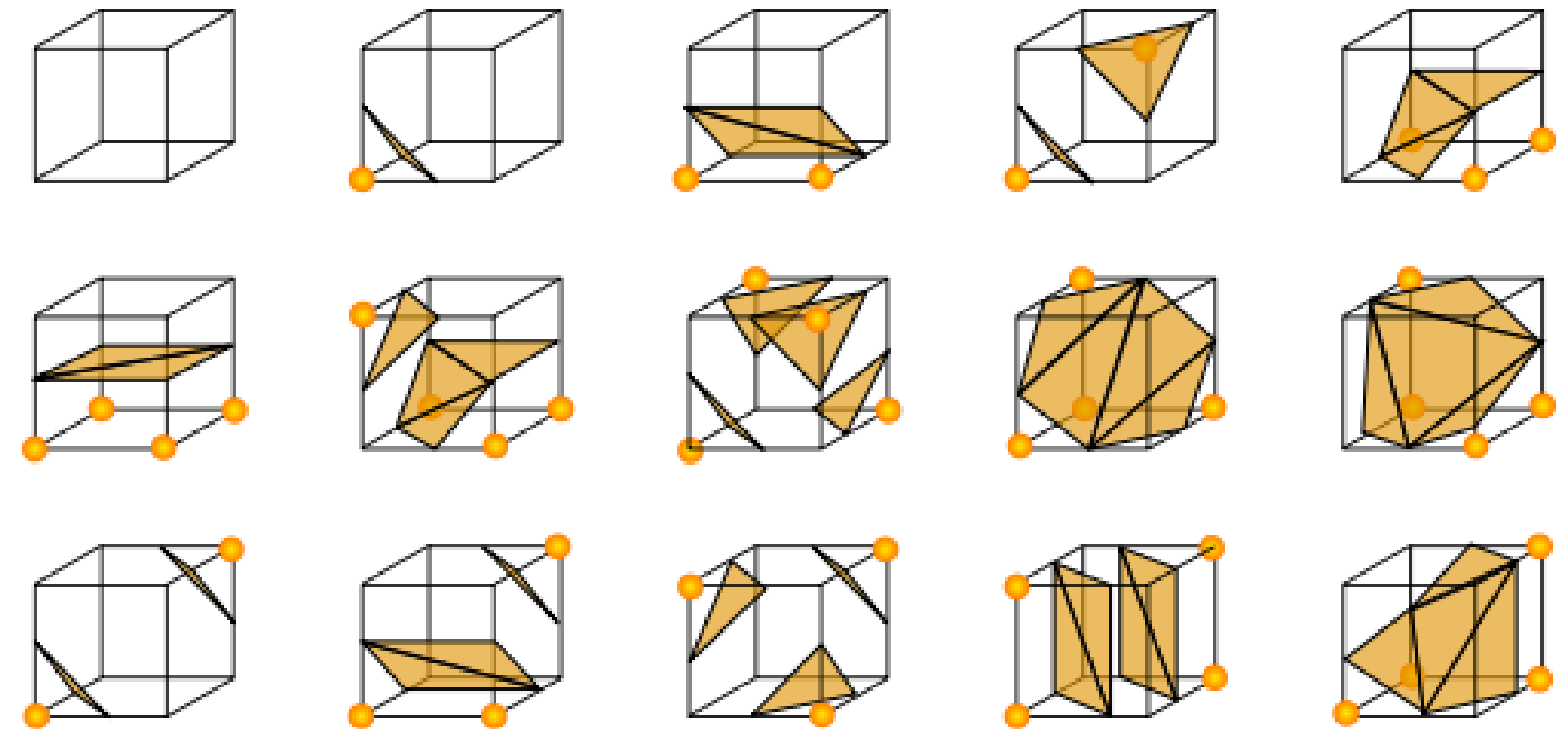
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[Wikipedia]

Issues of marching cubes

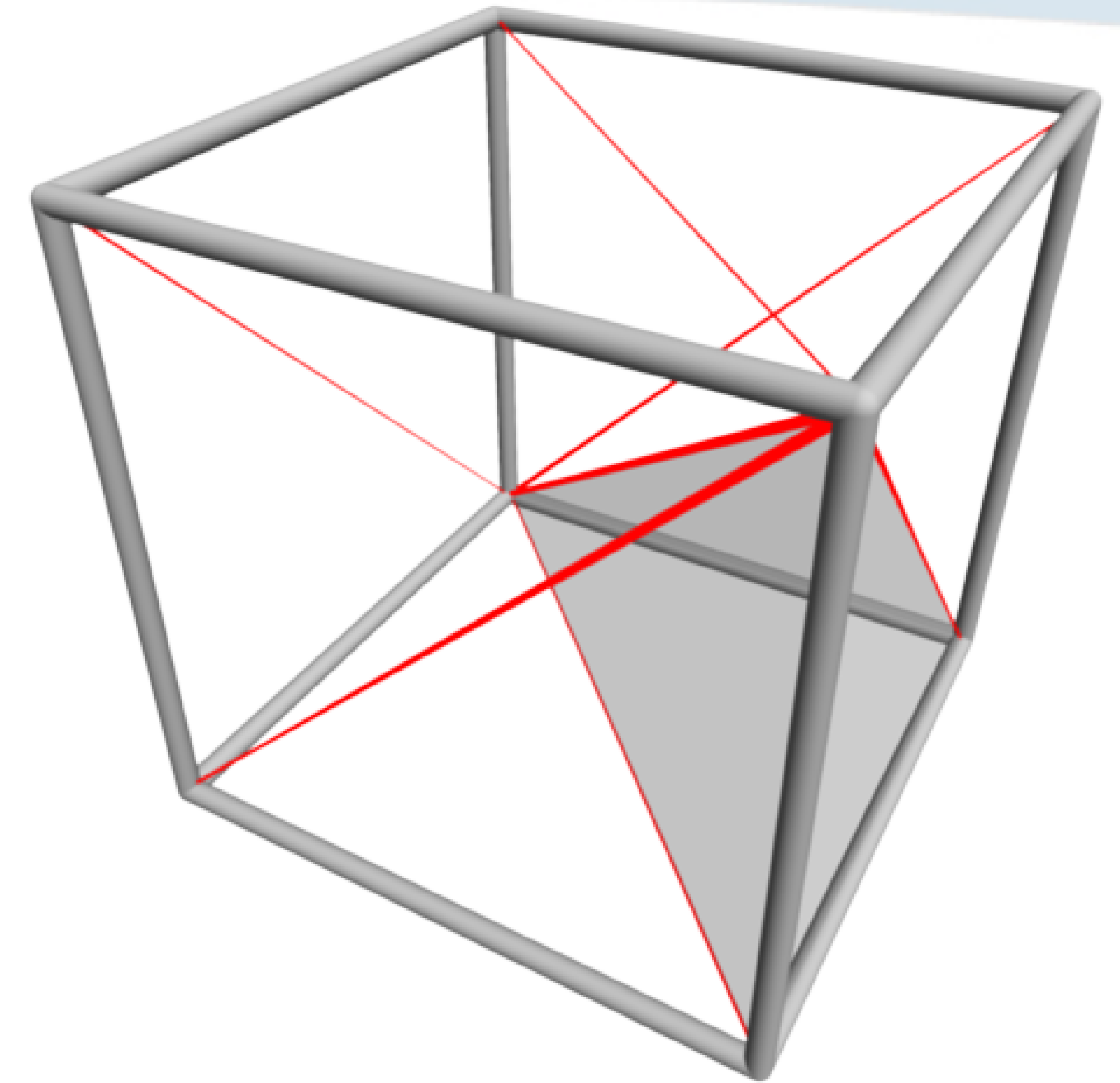
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[Wikipedia]

Issues of marching cubes

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[Wikipedia]

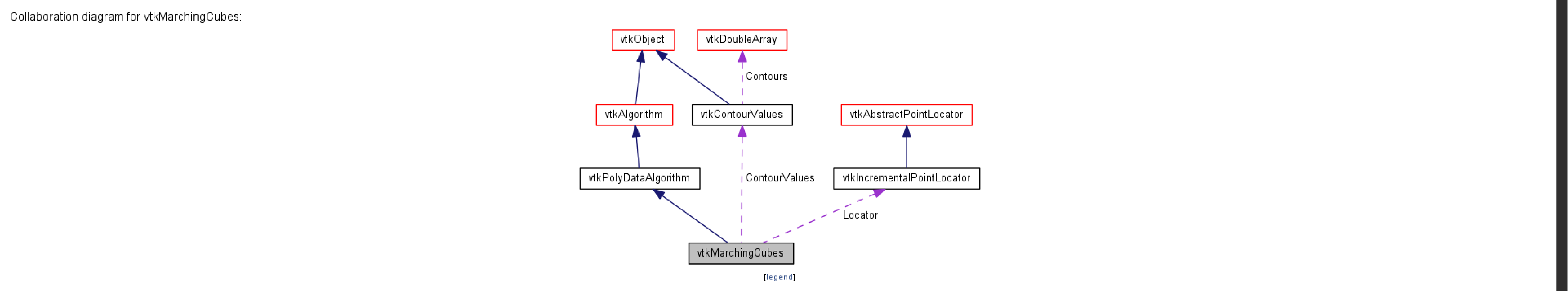
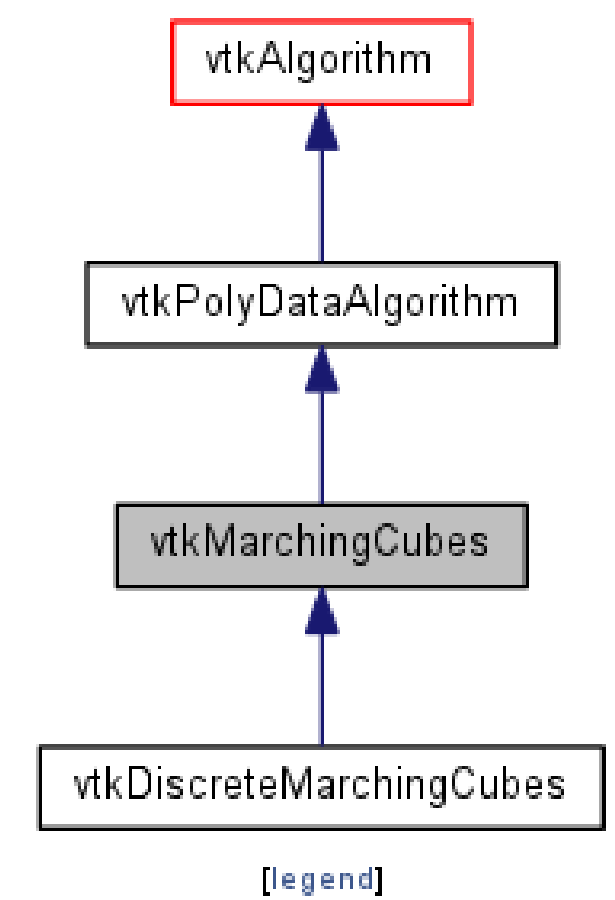
Public Types | Public Member Functions | Static Public Member Functions | Protected Member Functions | Protected Attributes | List of all members

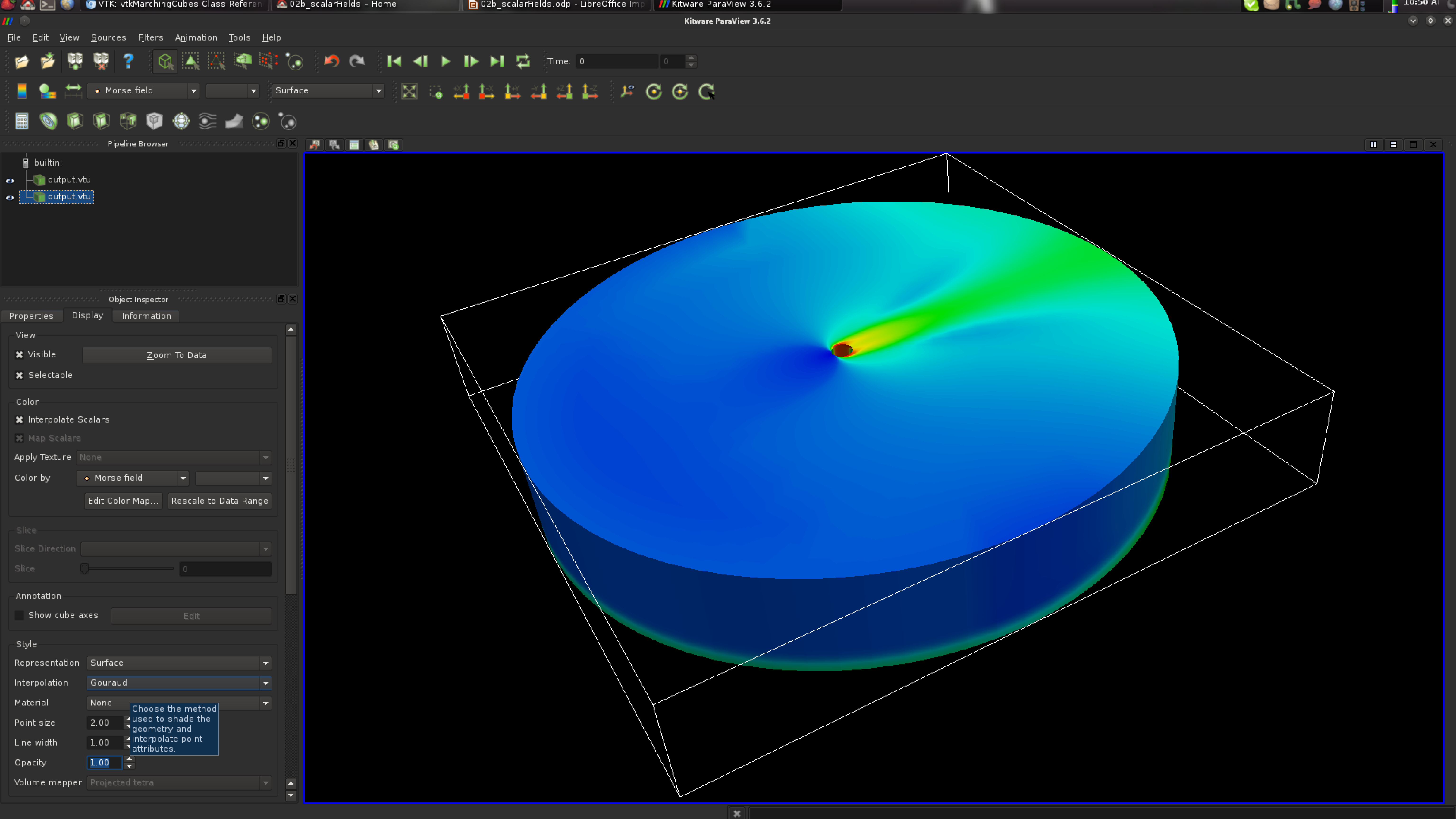
vtkMarchingCubes Class Reference

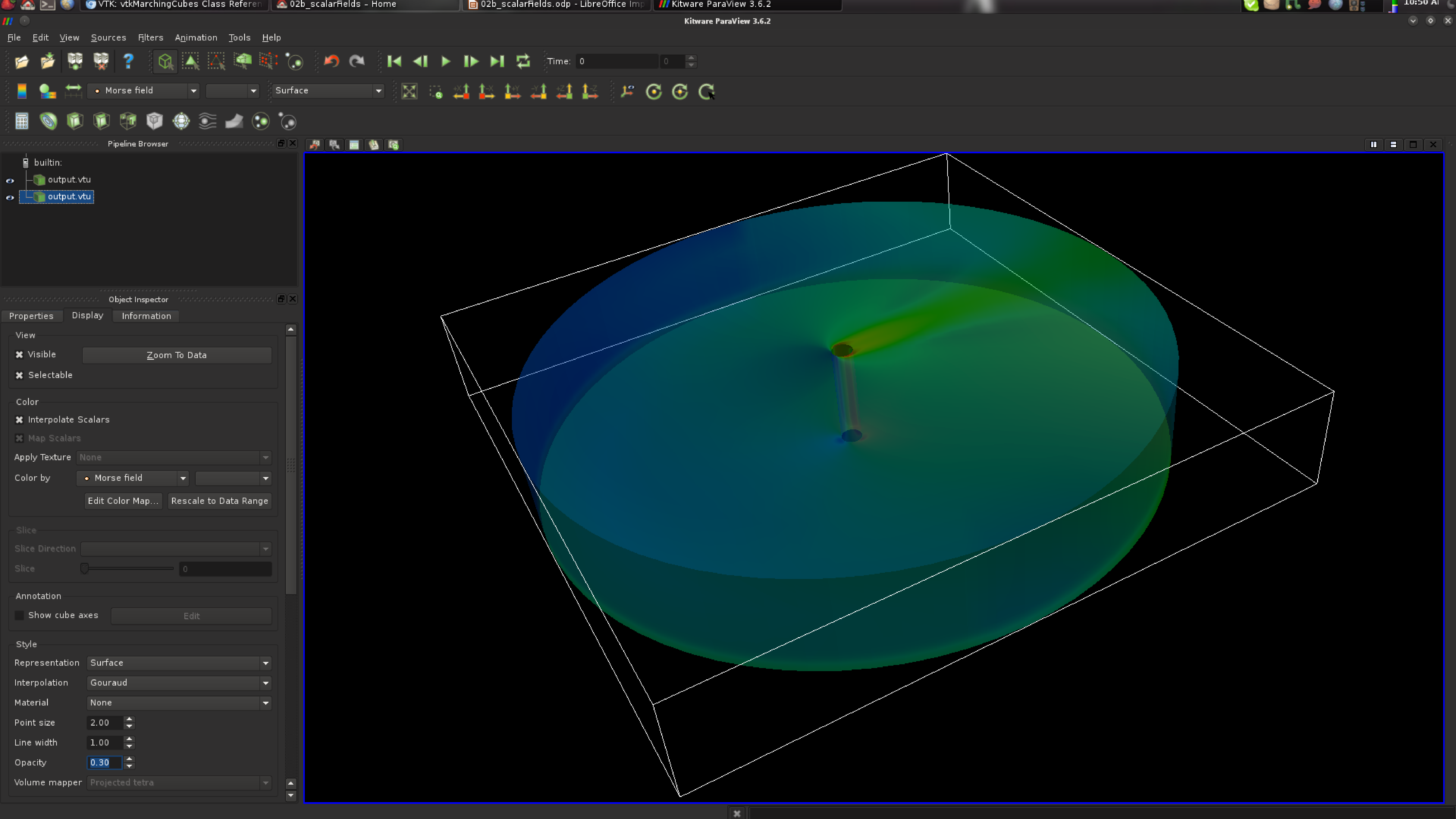
generate isosurface(s) from volume [More...](#)

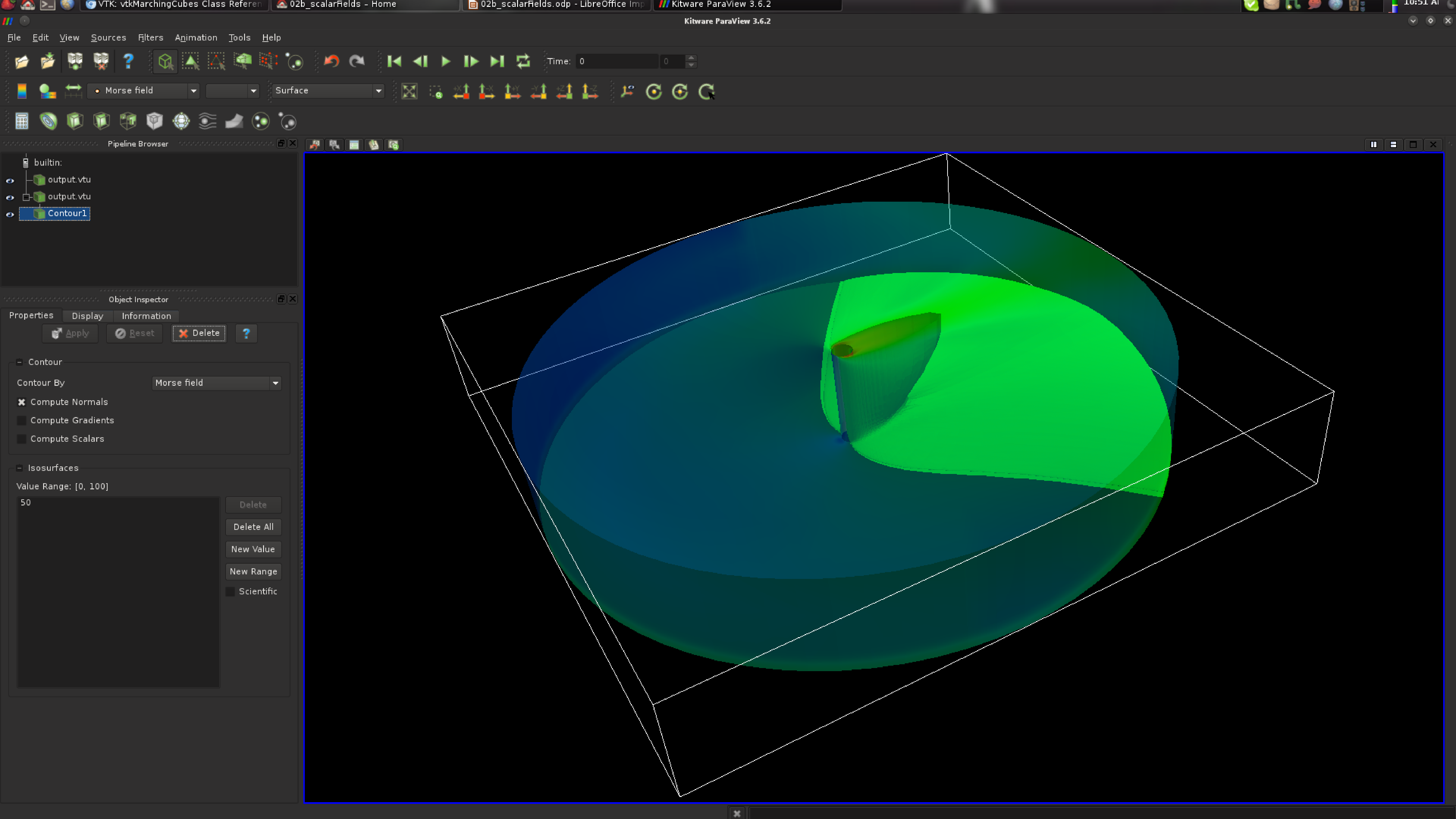
```
#include <vtkMarchingCubes.h>
```

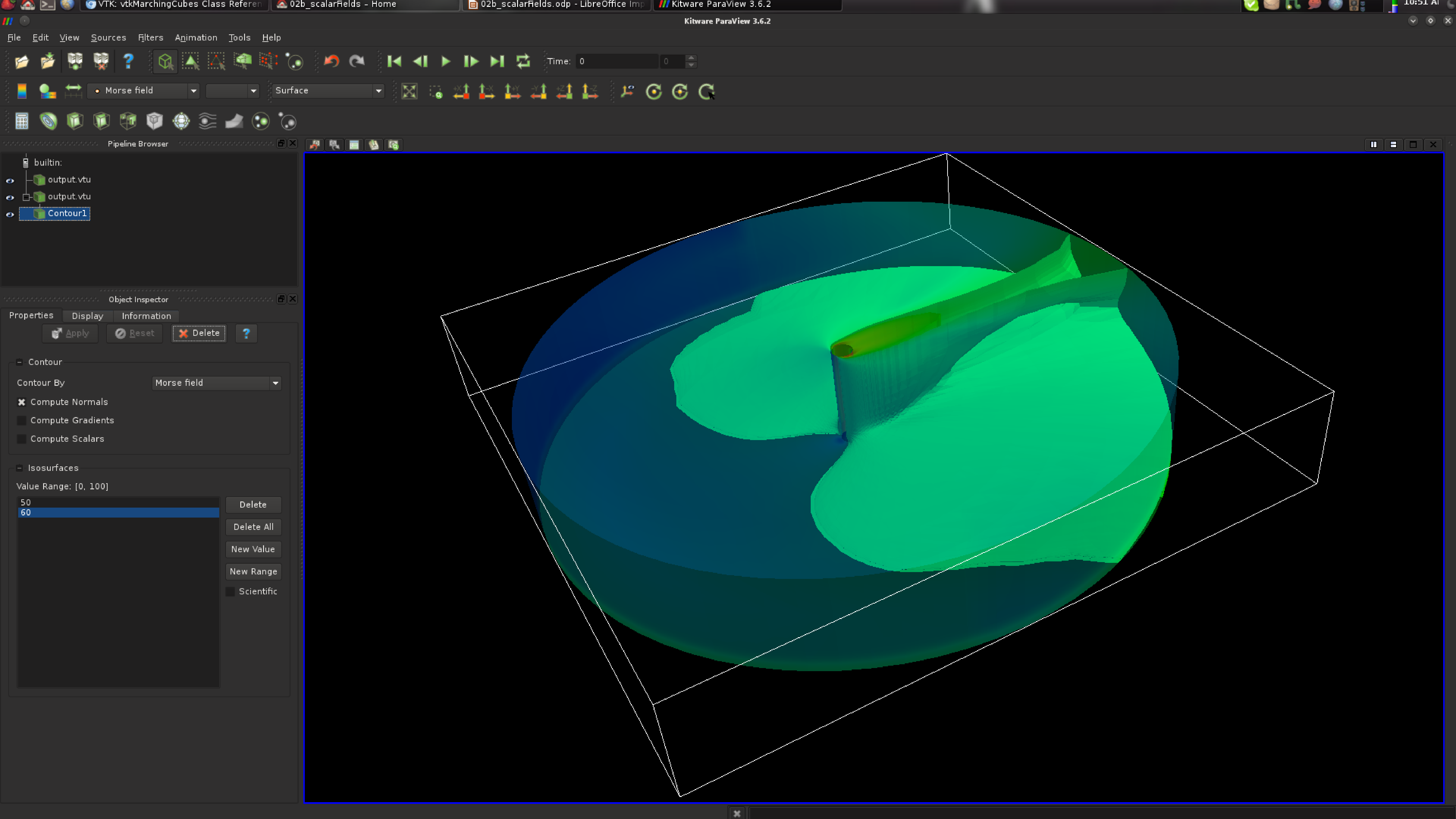
Inheritance diagram for vtkMarchingCubes:

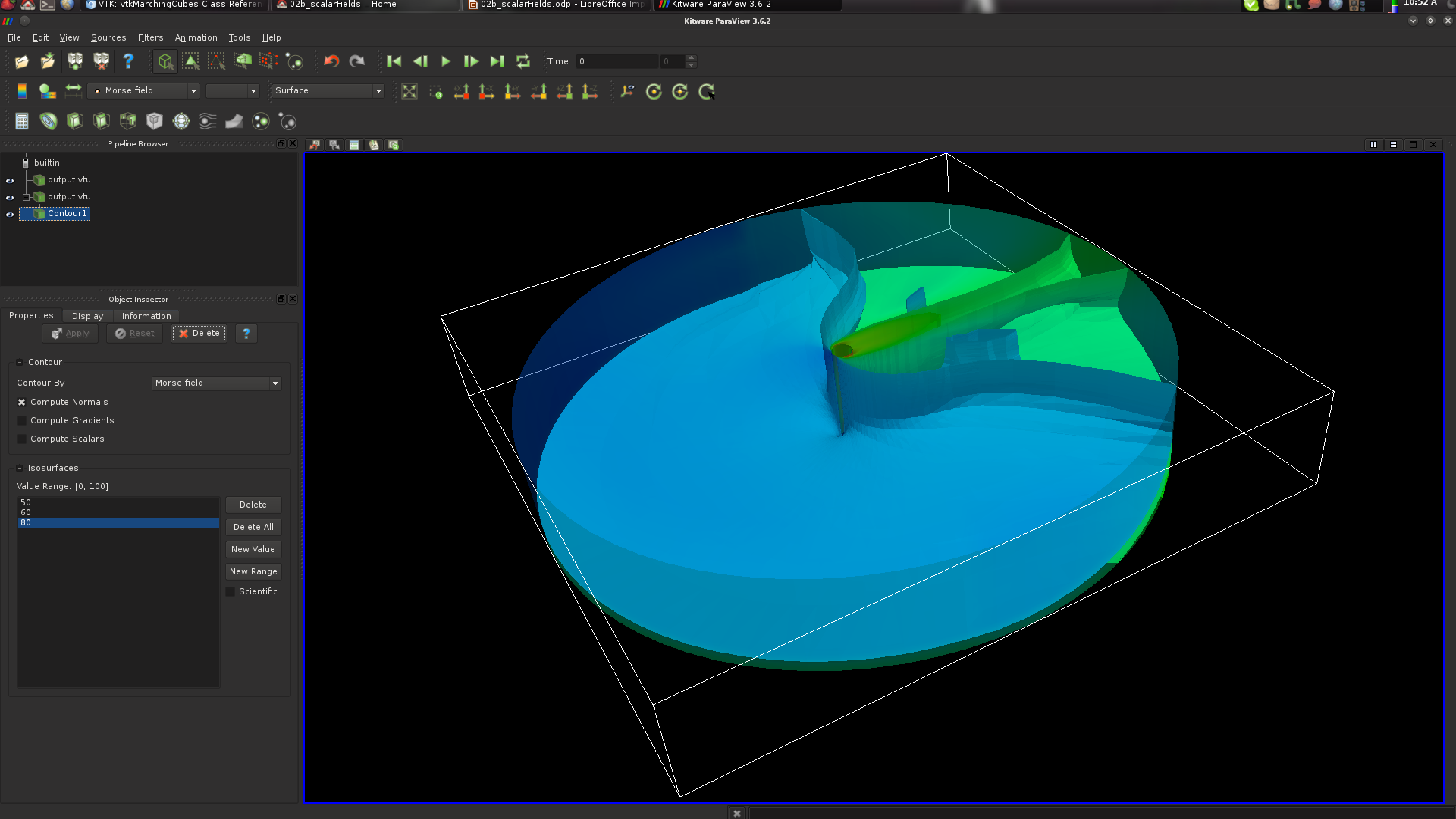


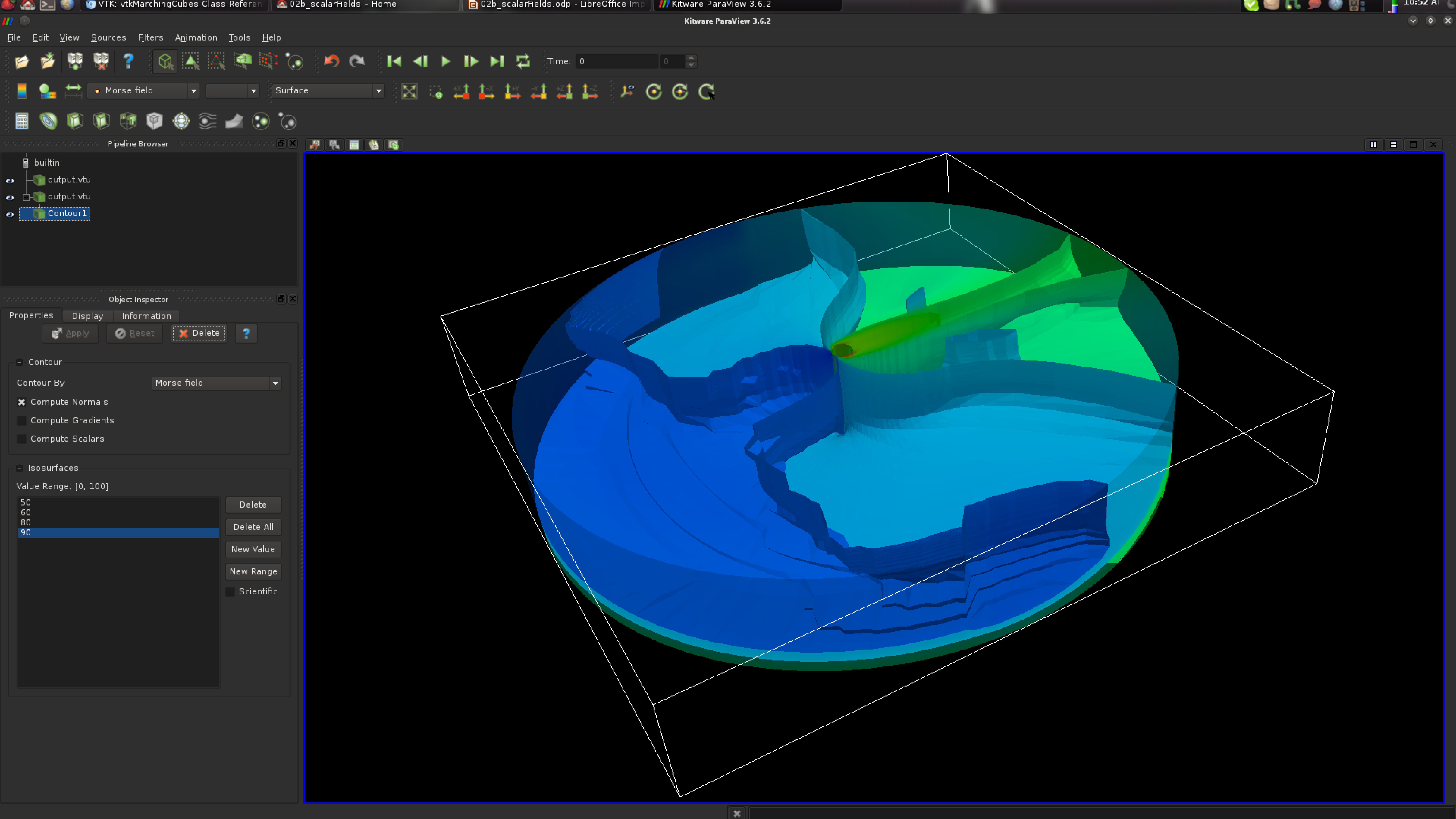






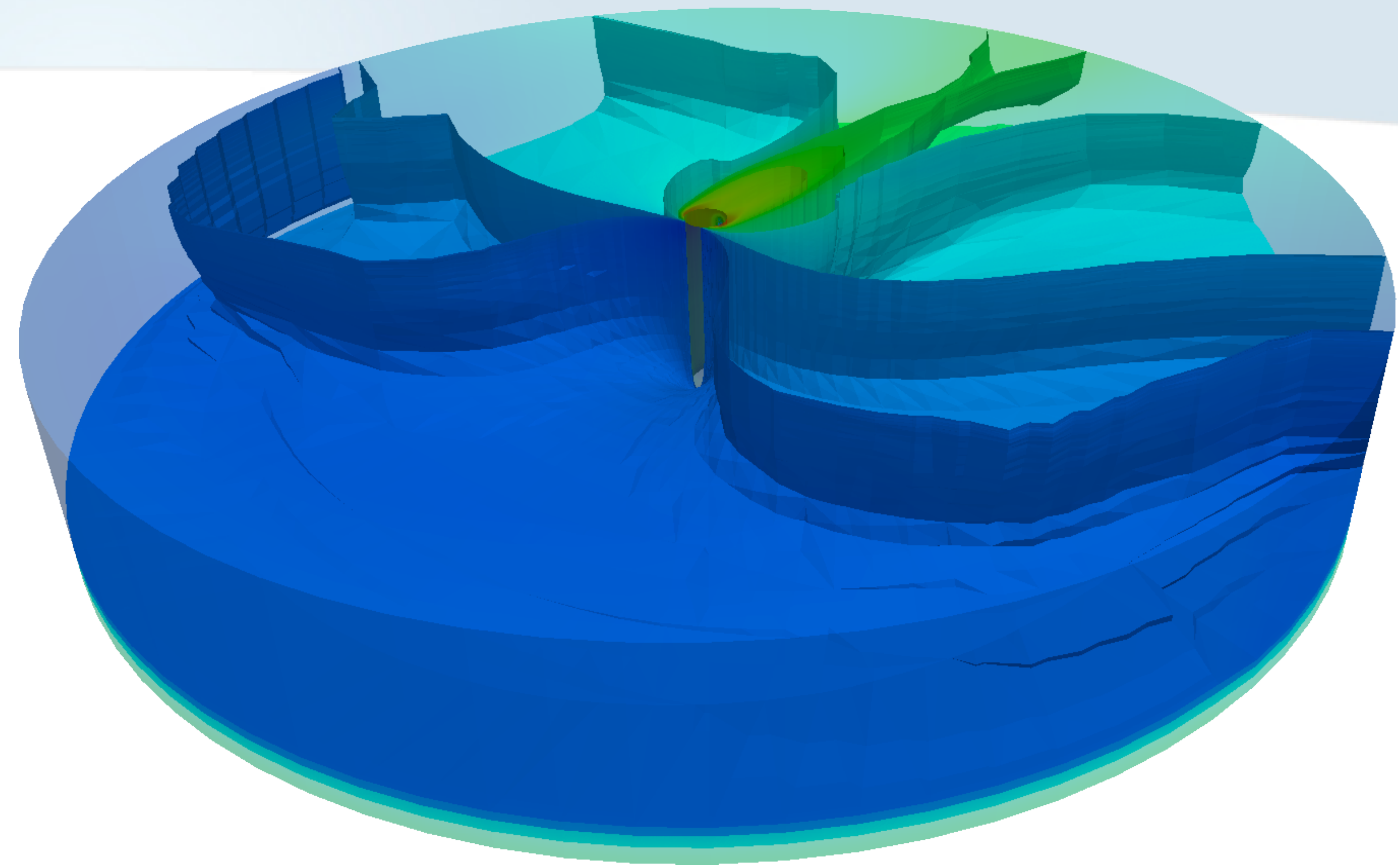






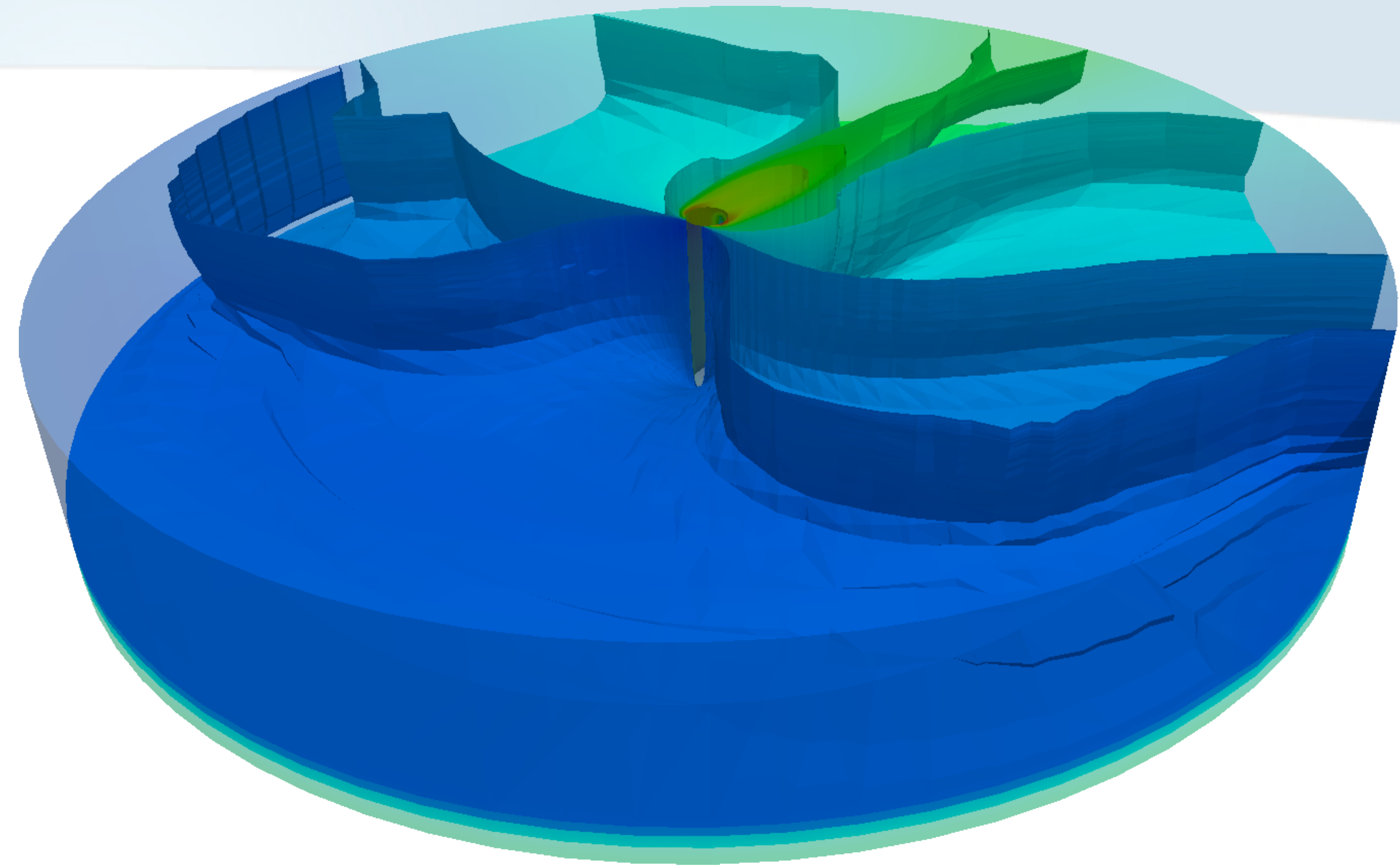
Fast level set extraction

- Marching xxxxxx
 - Visit all the unit cells
 - Per-cell extraction



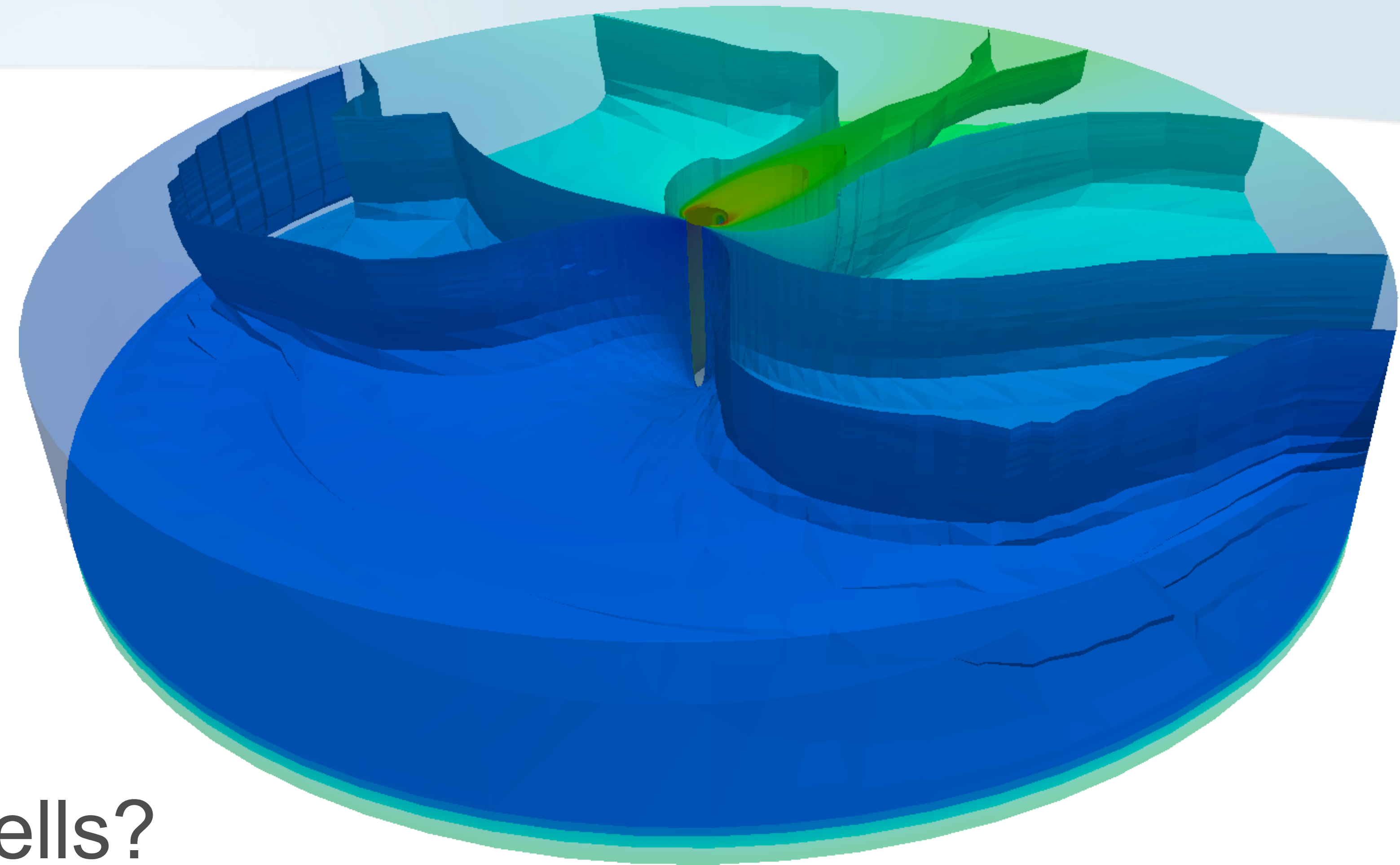
Fast level set extraction

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- Speeding up extraction



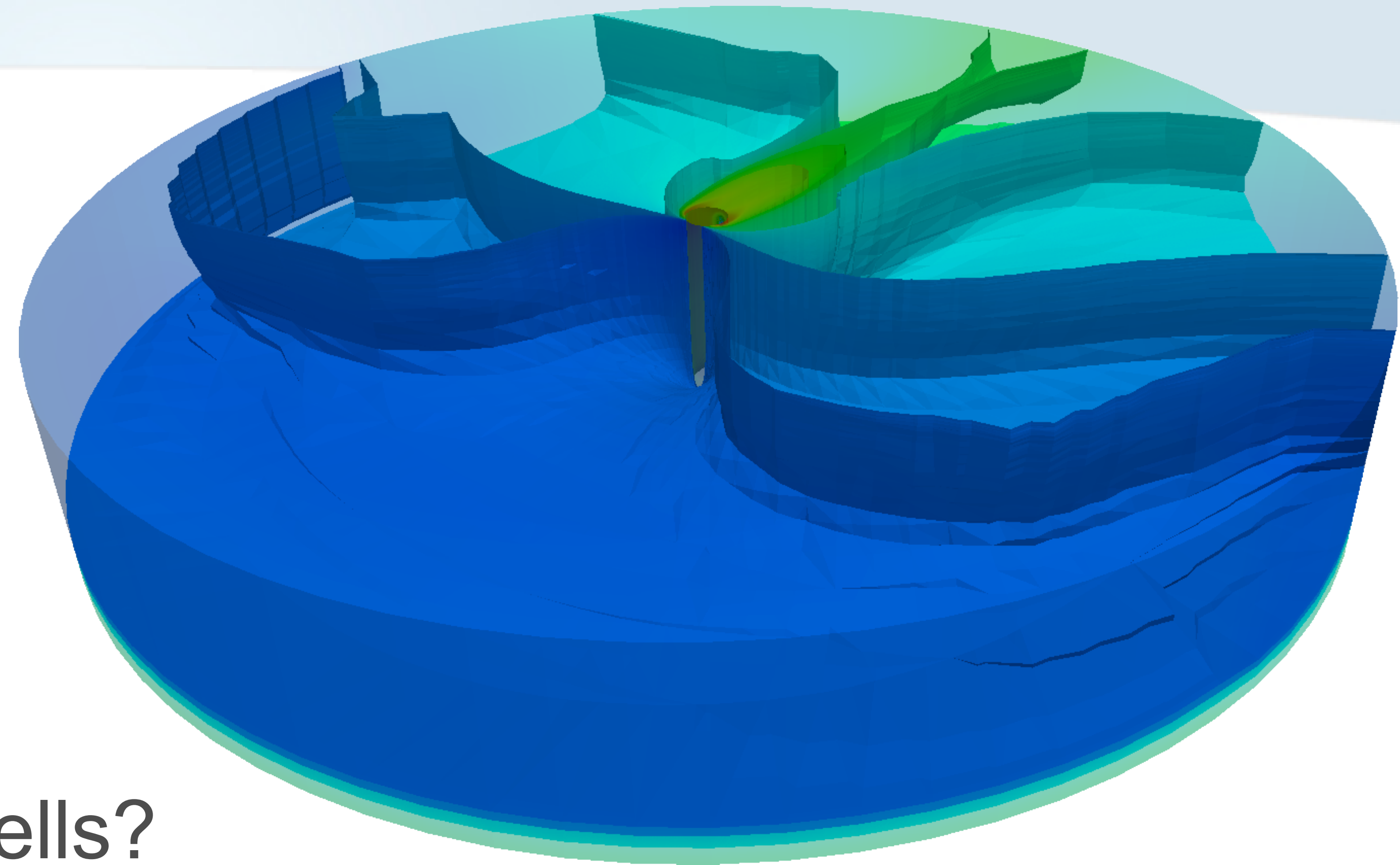
Fast level set extraction

- Marching xxxxxx
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 - Do we need to visit **ALL** the cells?

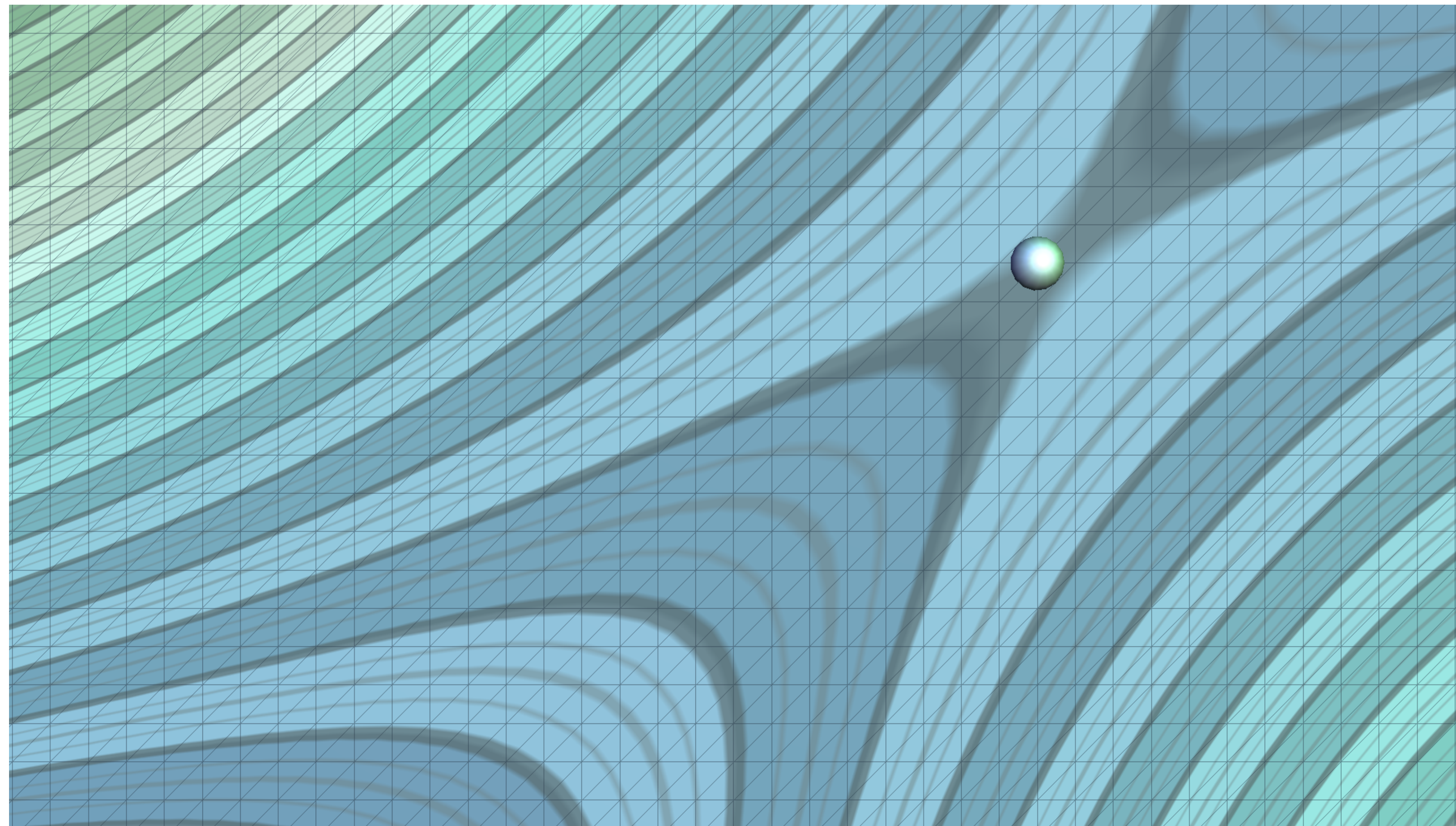
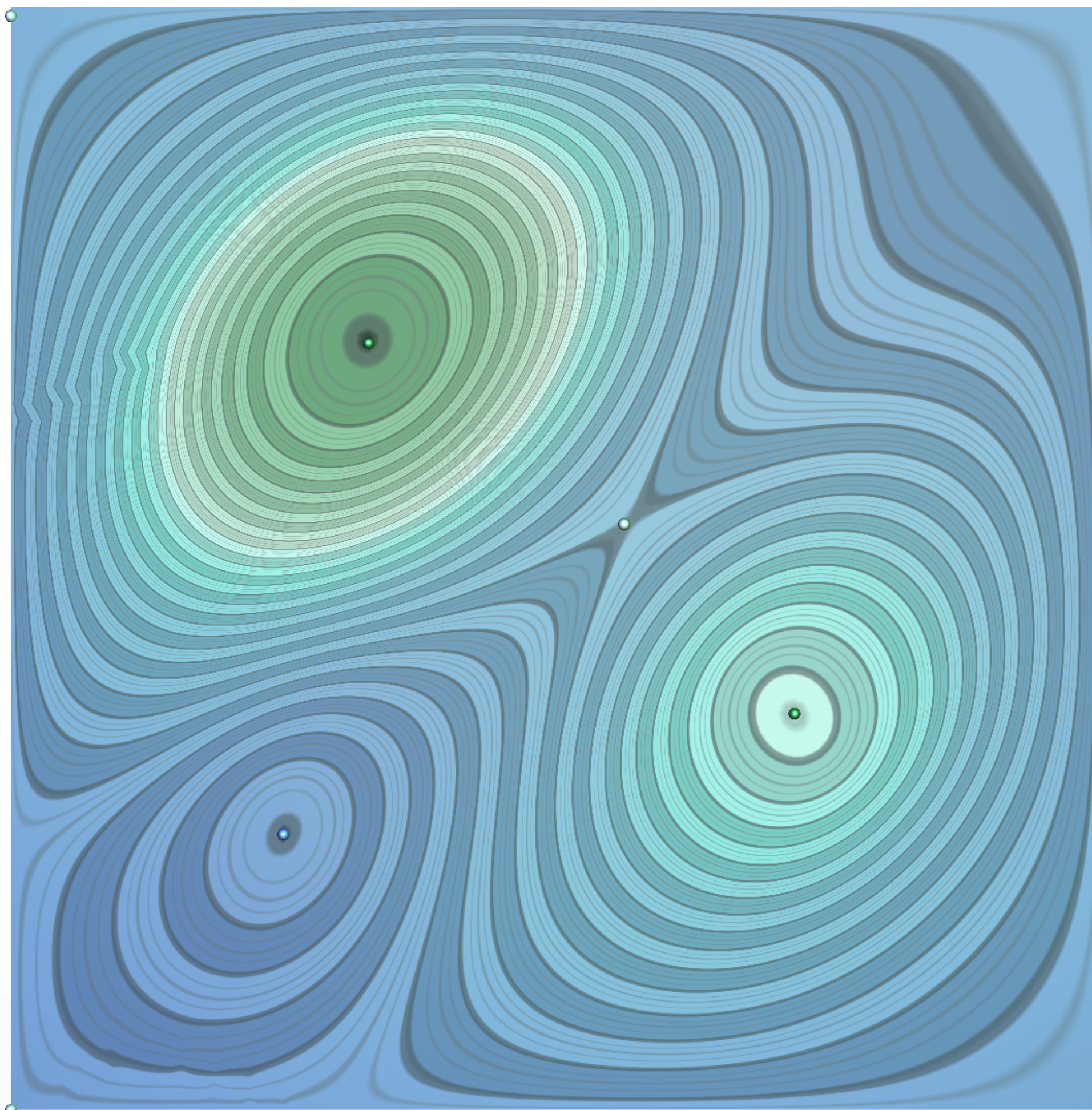


Fast level set extraction

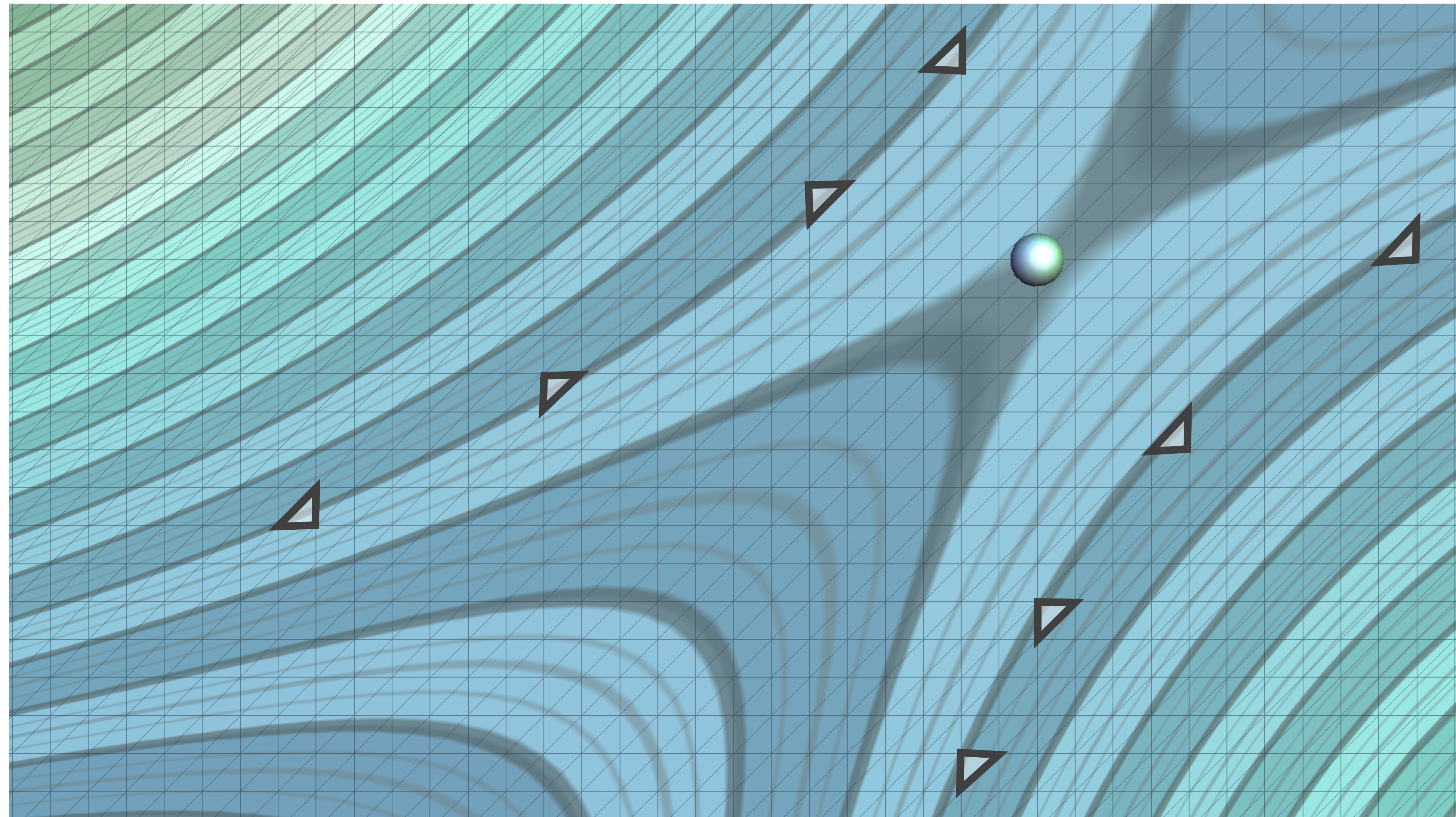
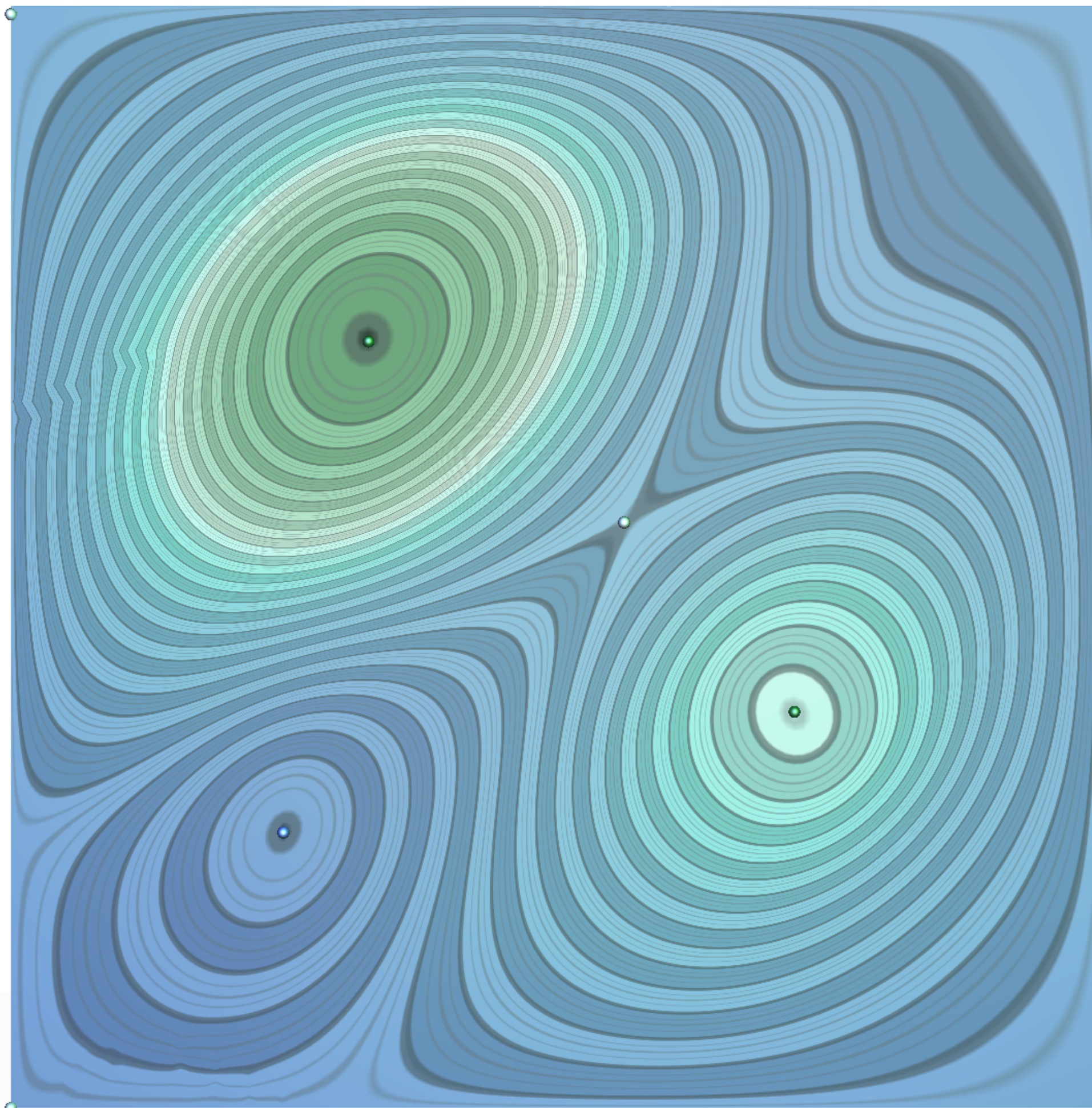
- Marching xxxxxx
 - Visit all the unit cells
 - Per-cell extraction
- Speeding up extraction
 - Do we need to visit **ALL** the cells?
 - Can't we just visit only the cells that are needed?



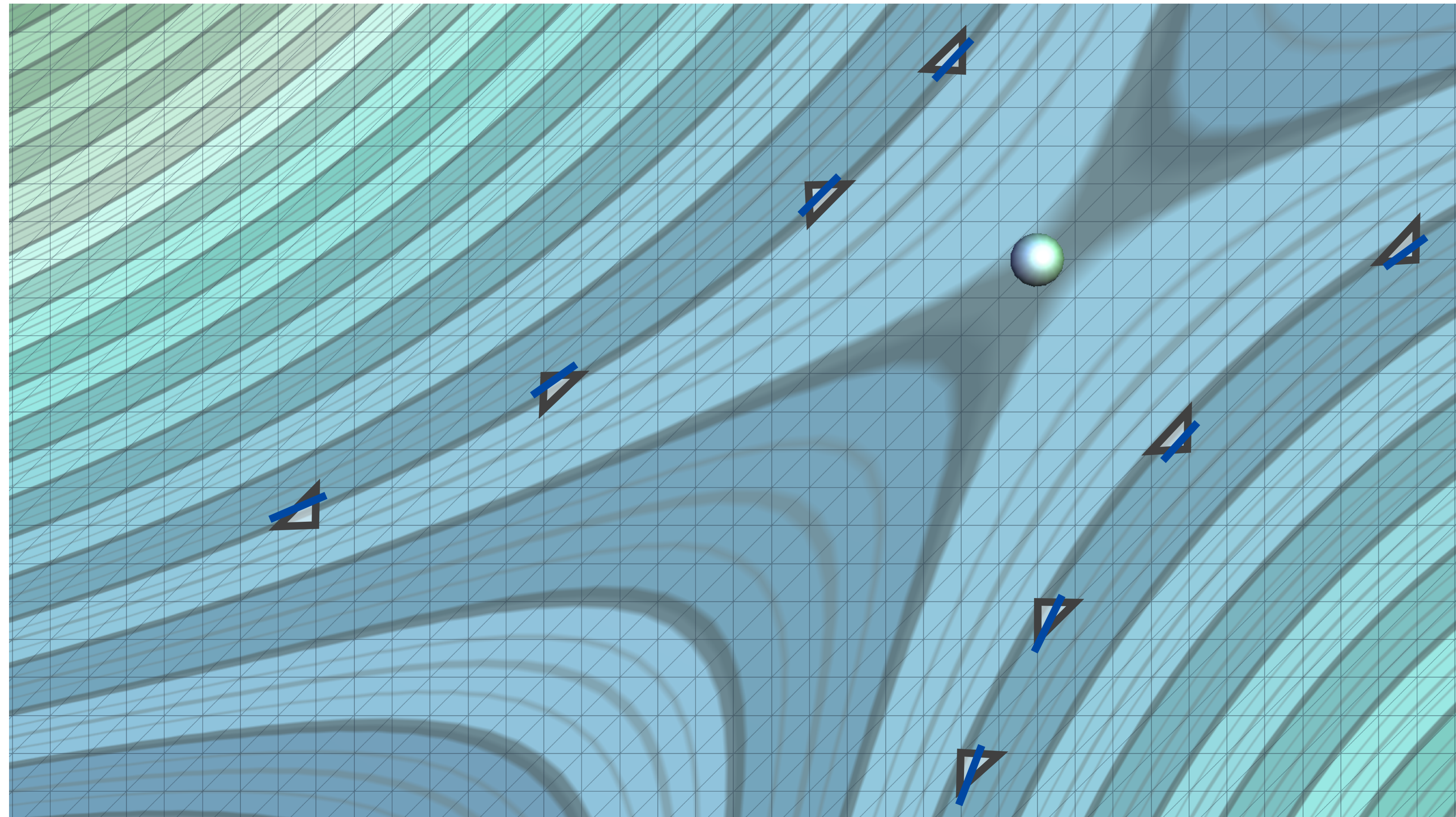
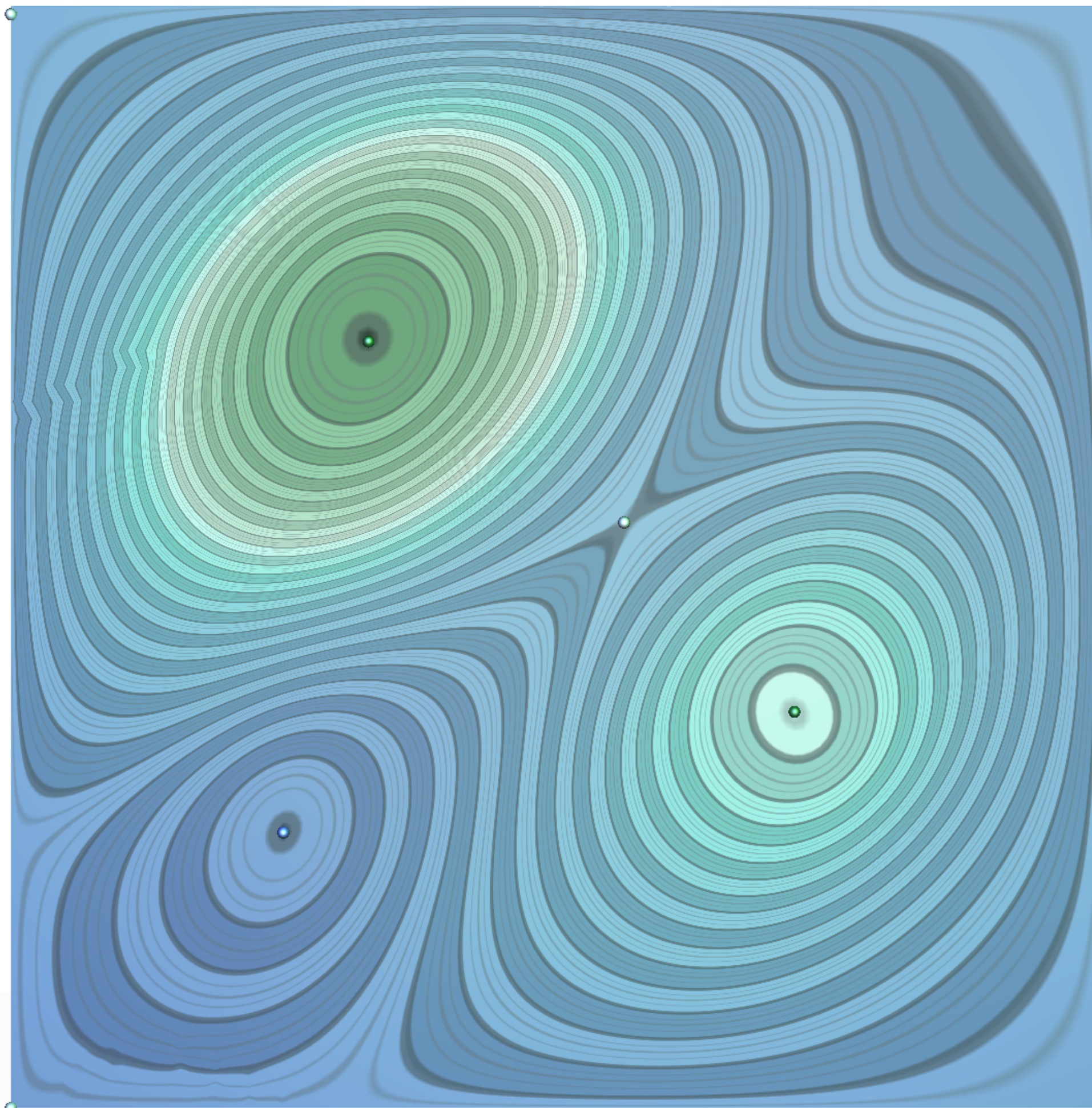
Seeds for level set extraction



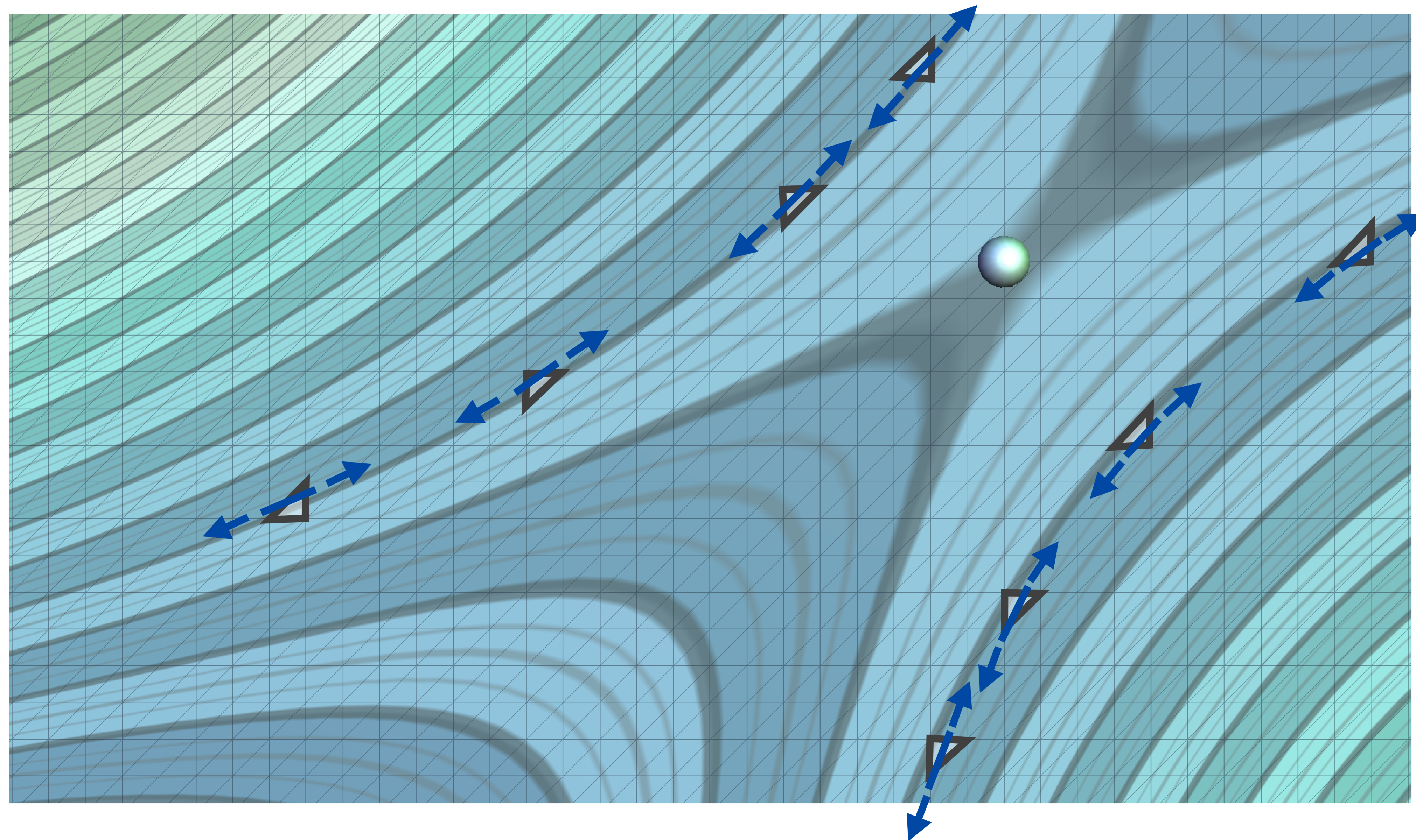
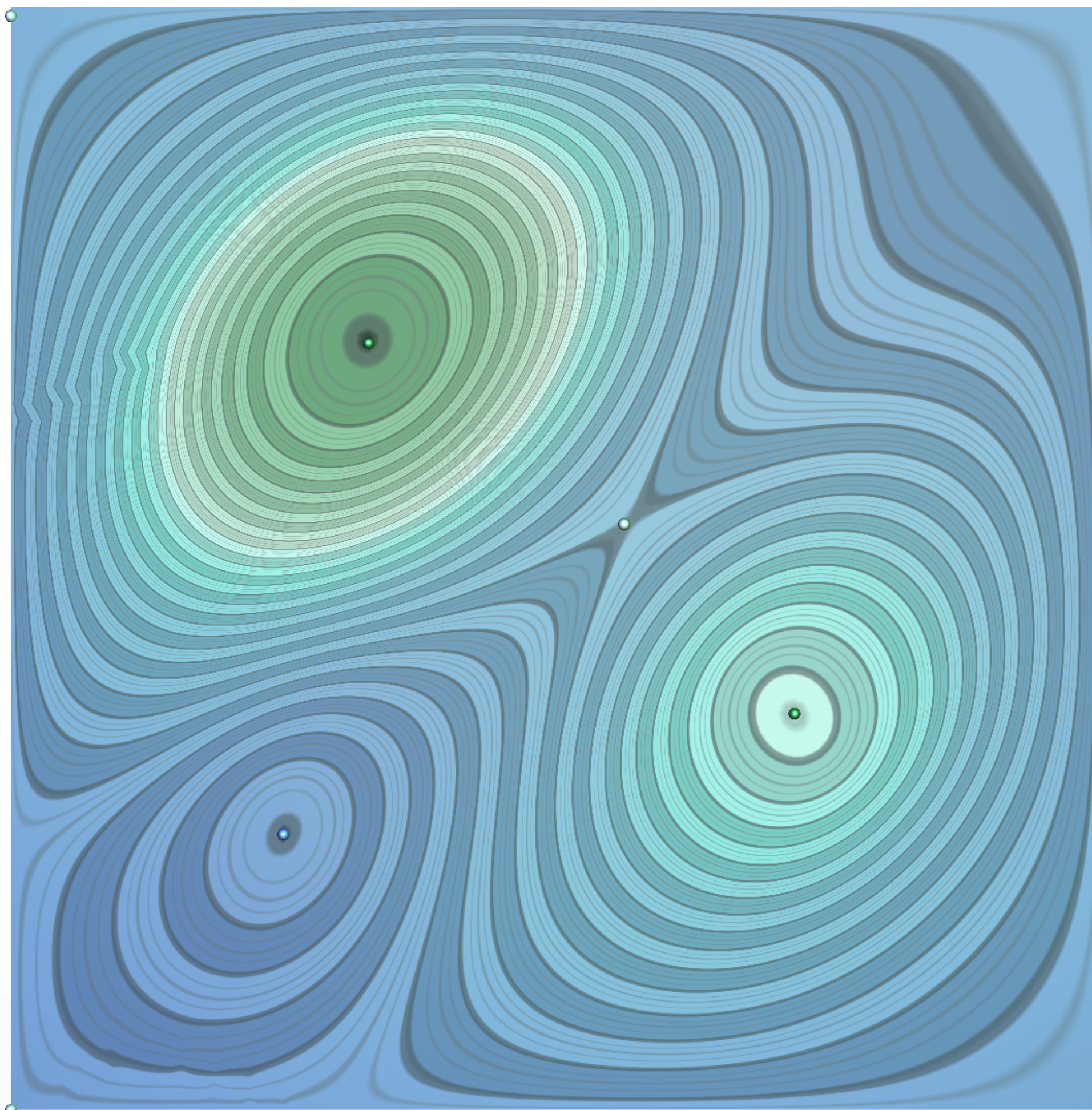
Seeds for level set extraction



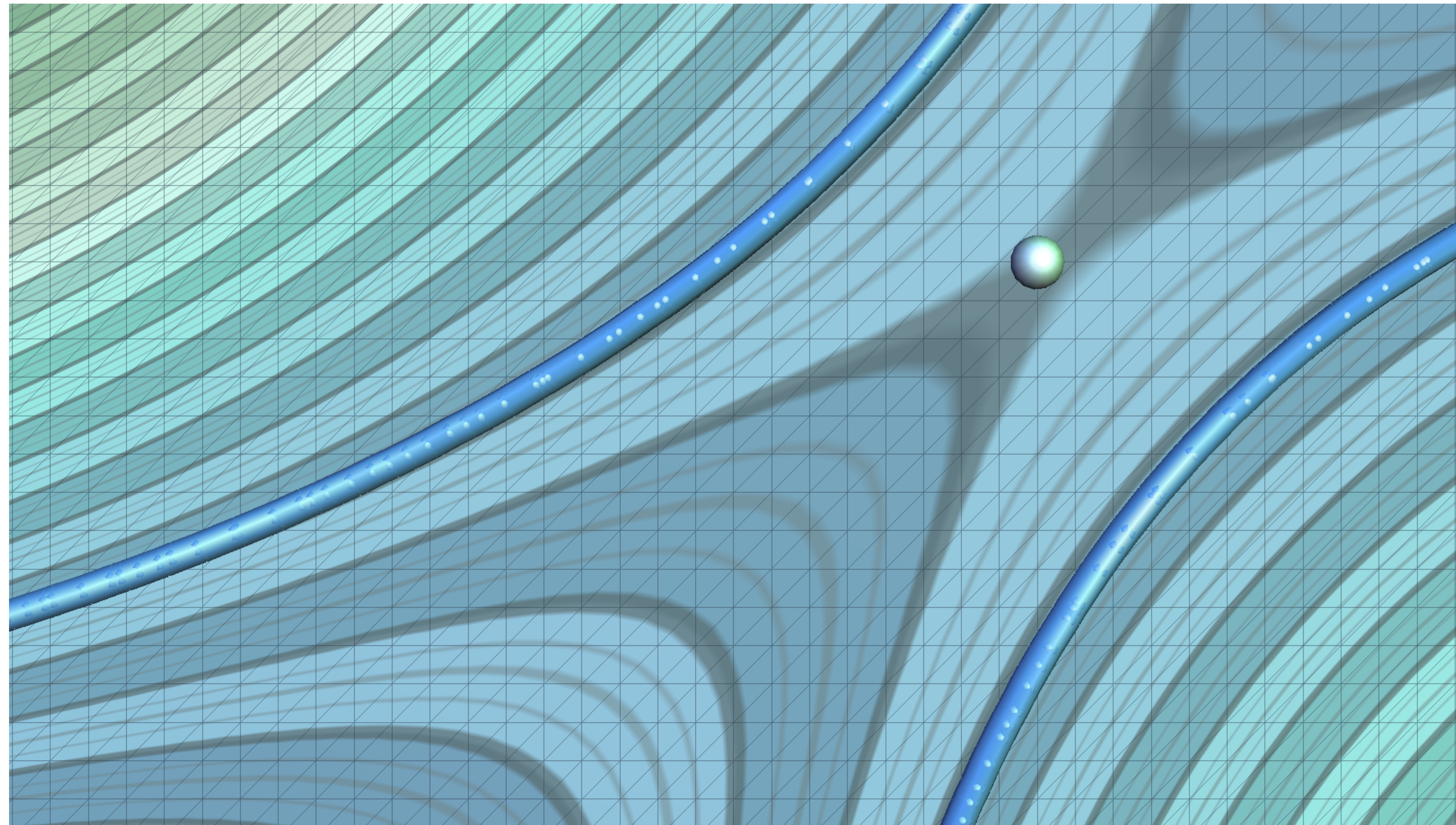
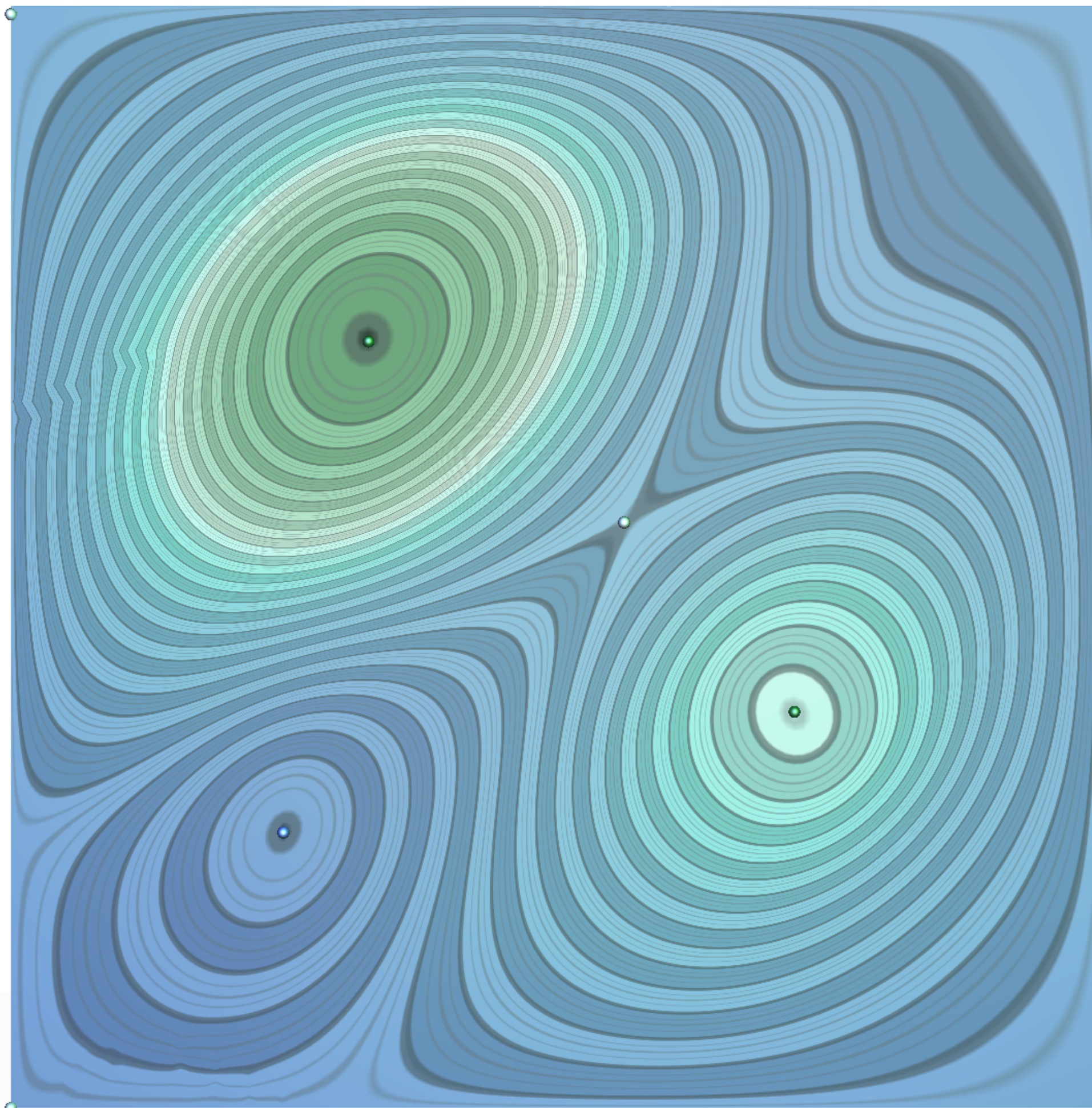
Seeds for level set extraction



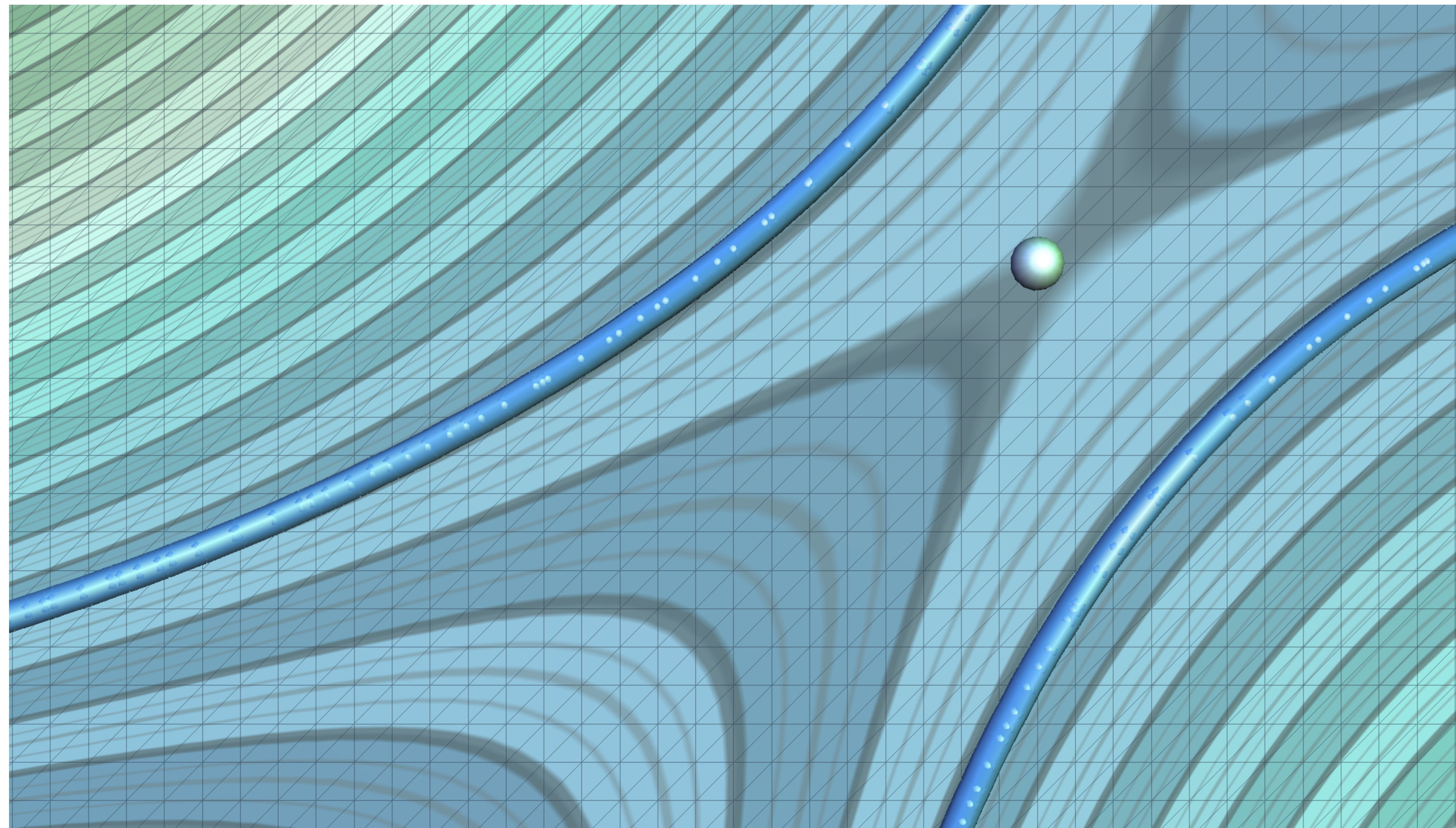
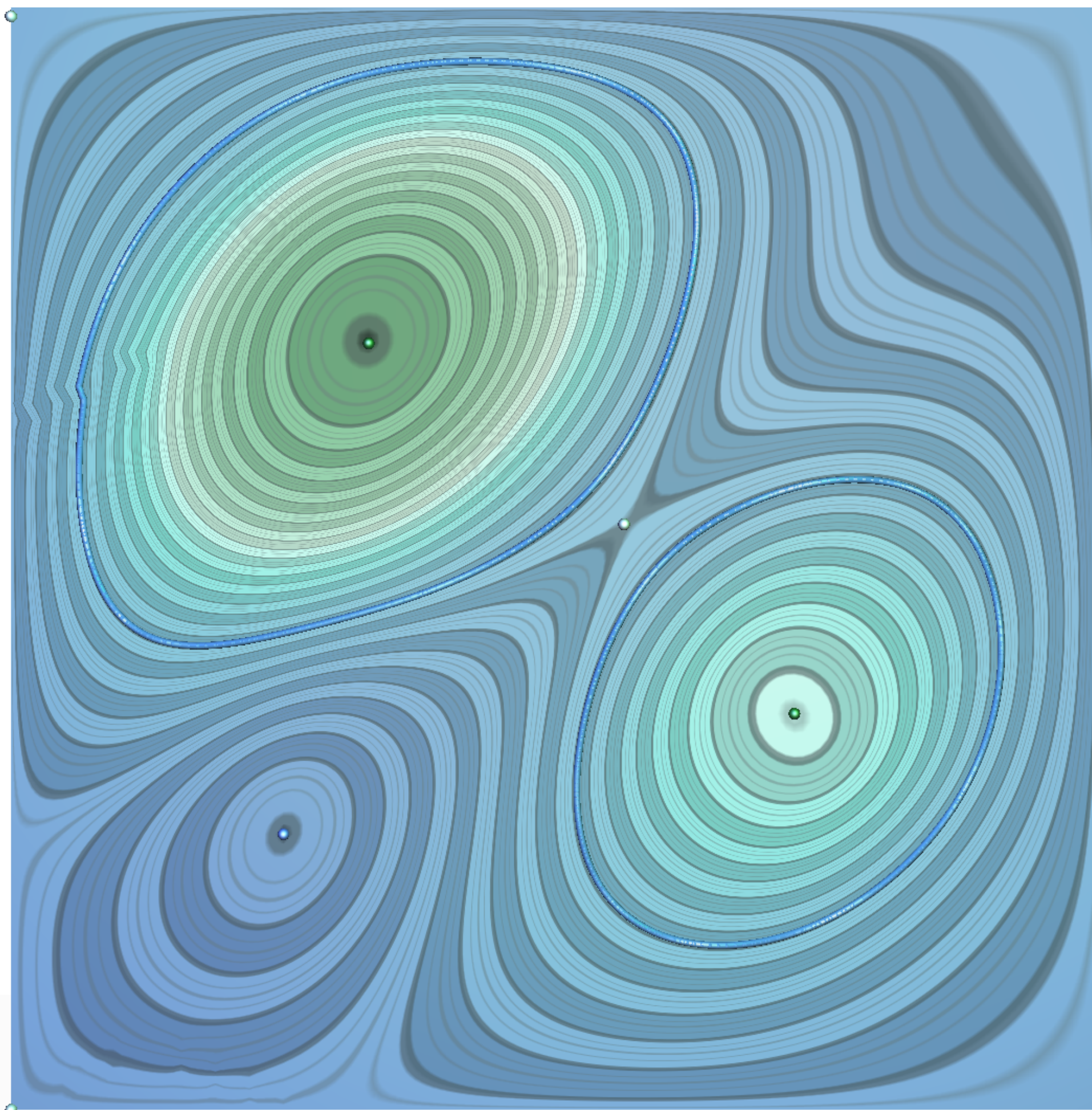
Seeds for level set extraction



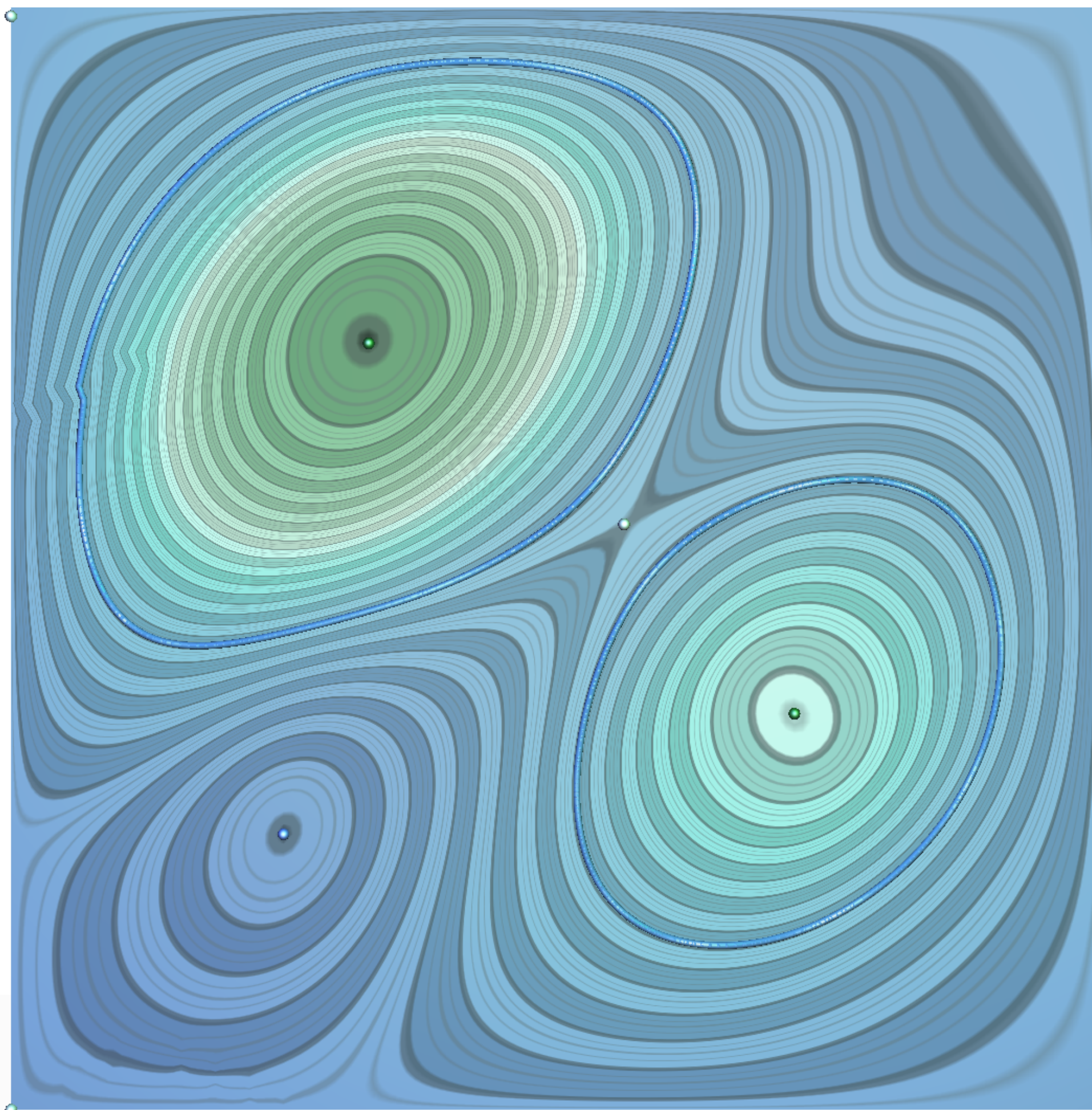
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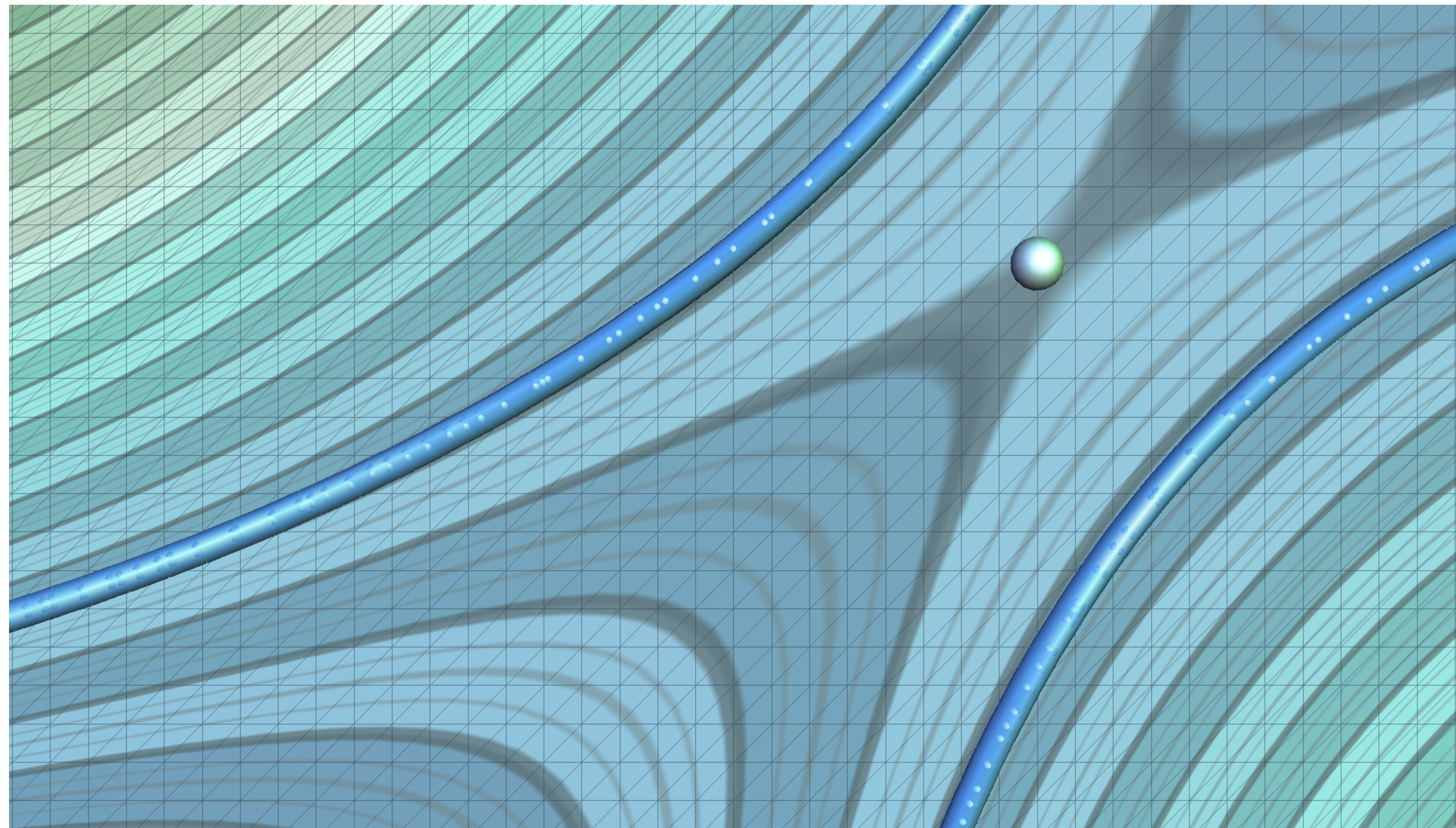
Seeds for level set extraction



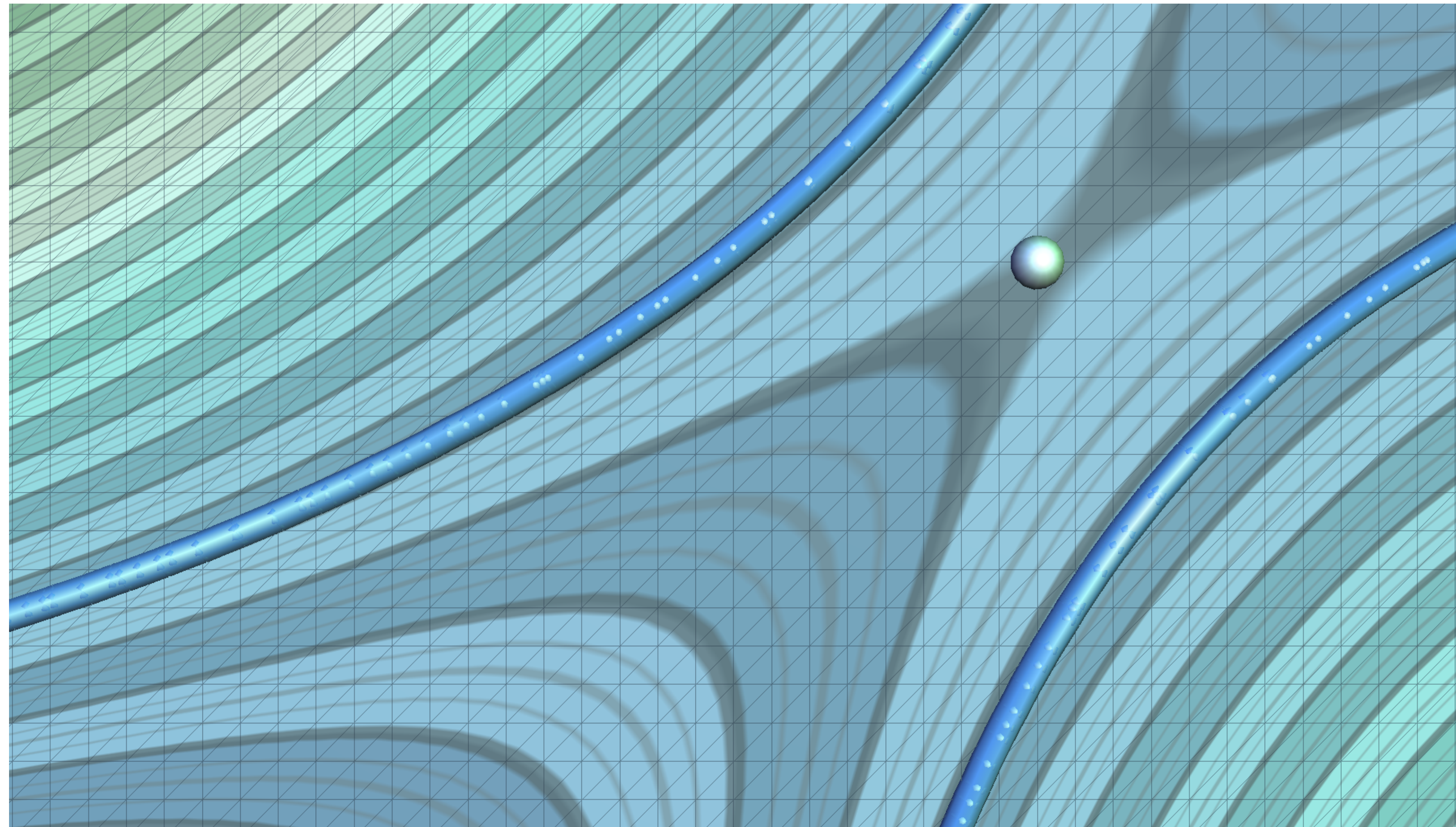
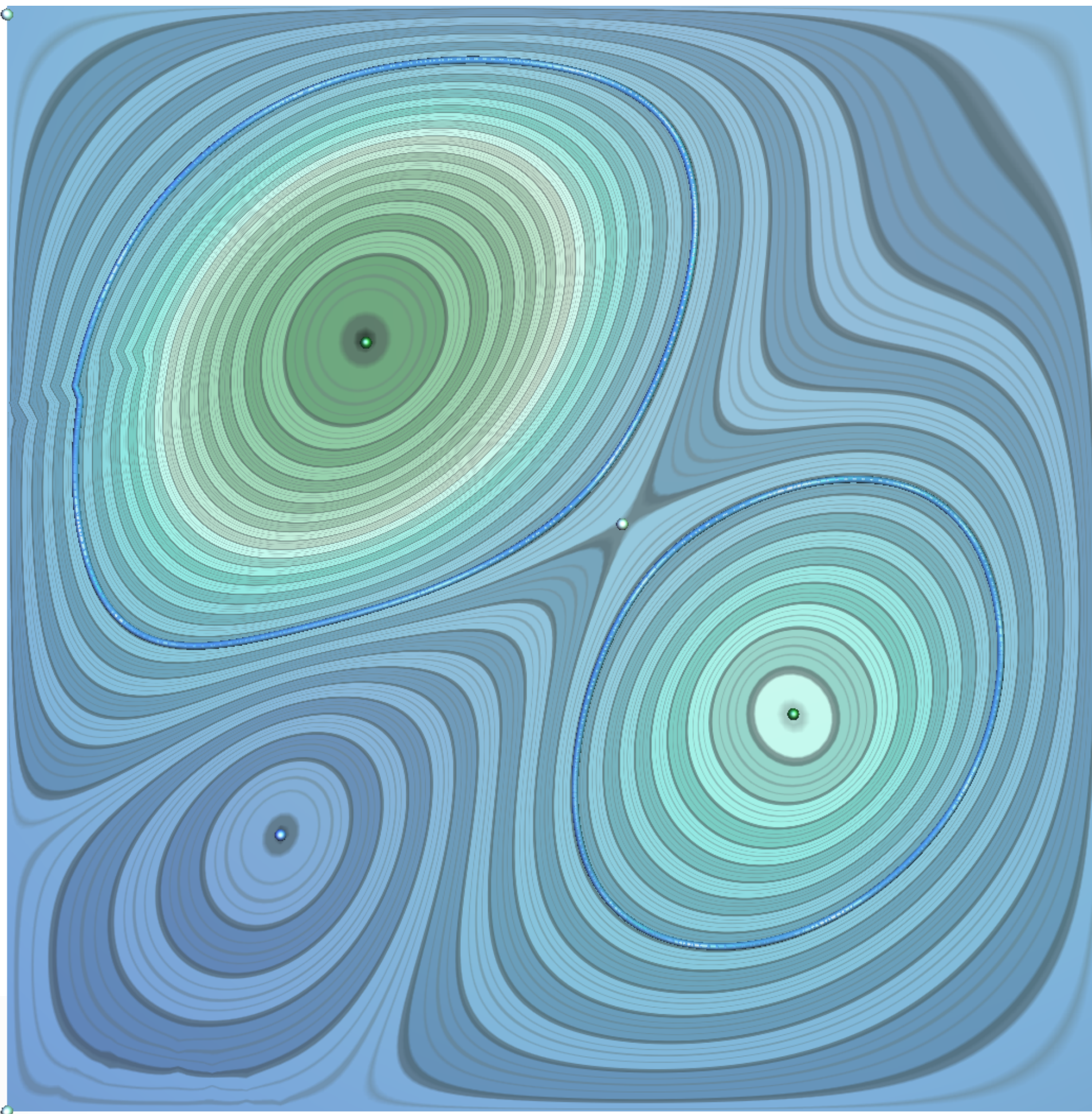
Seeds for level set extraction



Minimal number of seeds?



Seeds for level set extraction



Minimal number of seeds?

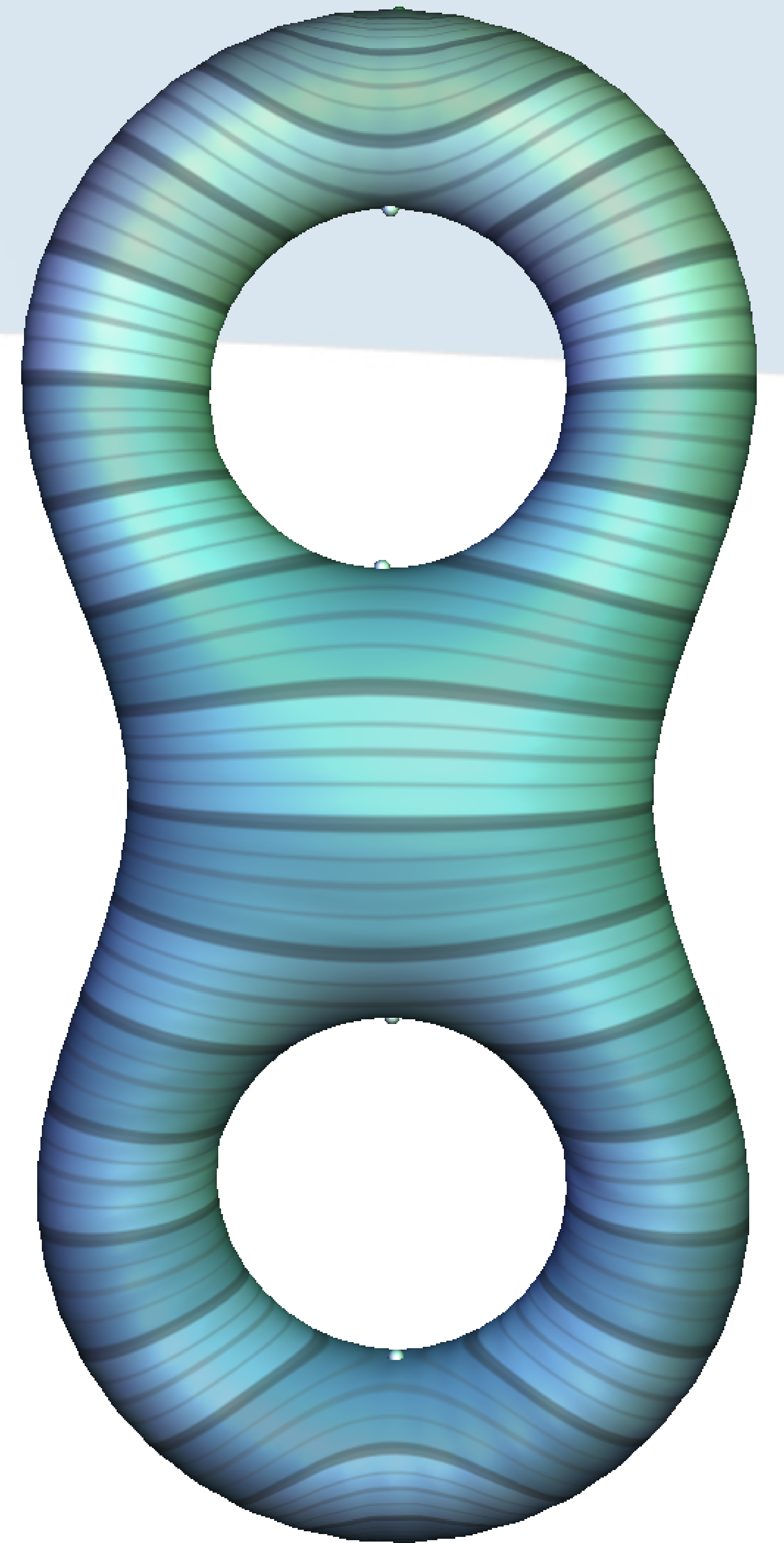
- One per connected component of $f^{-1}(i)$

Indexing contours

- Notion of Reeb graph

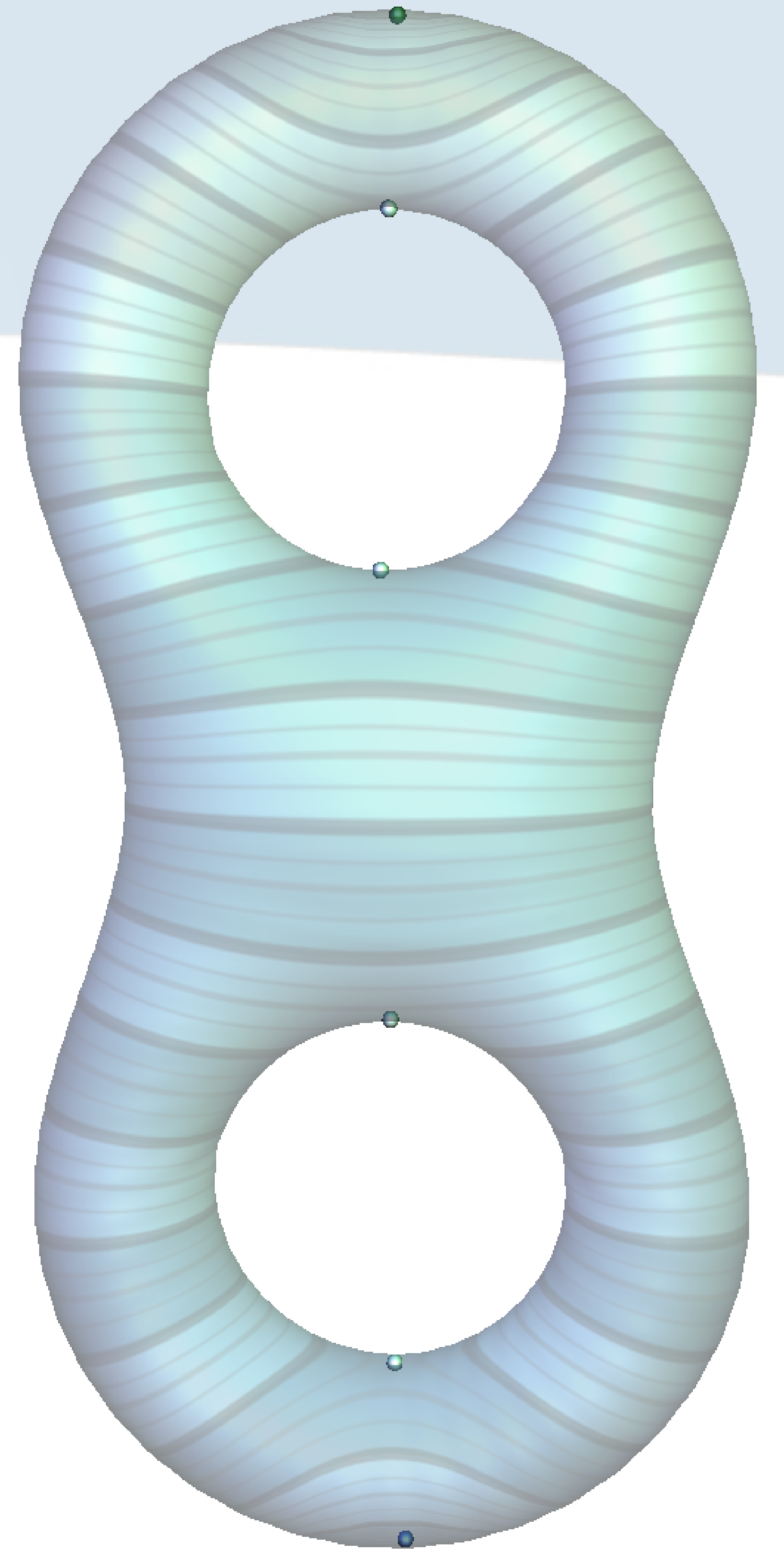
Indexing contours

- Notion of Reeb graph
 - $f : \mathcal{M} \rightarrow \mathbb{R}$
 - *Morse* function



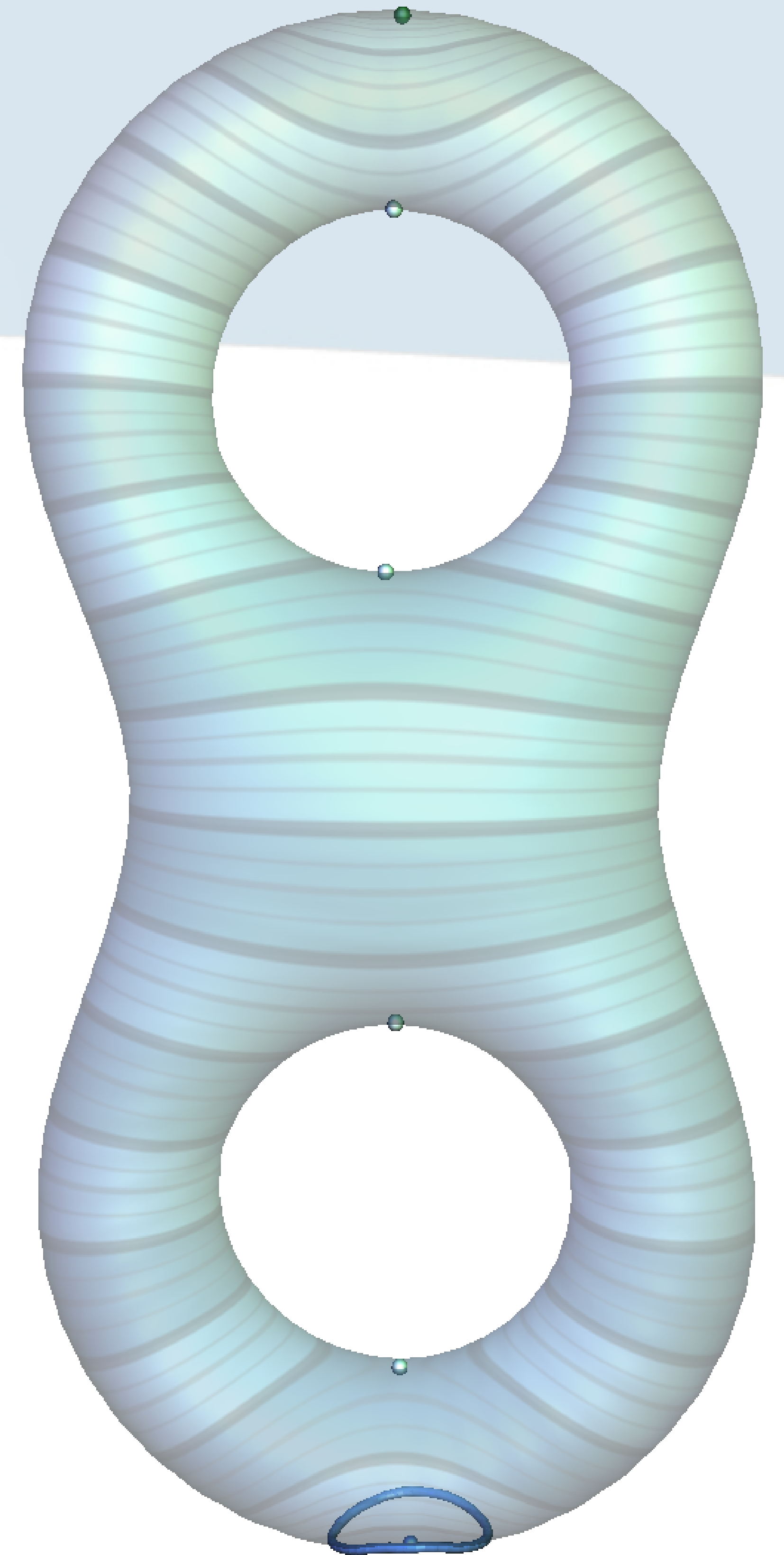
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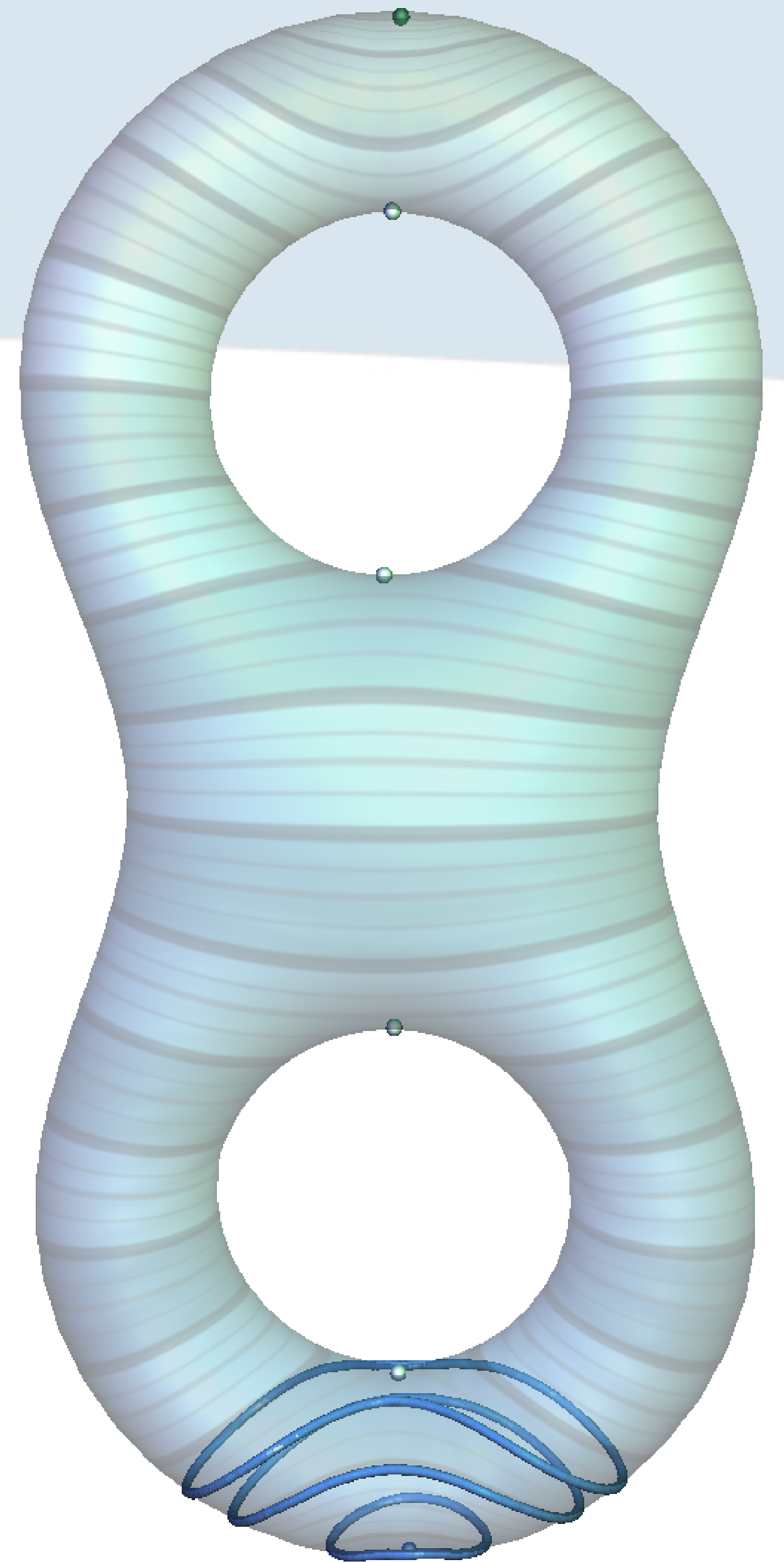
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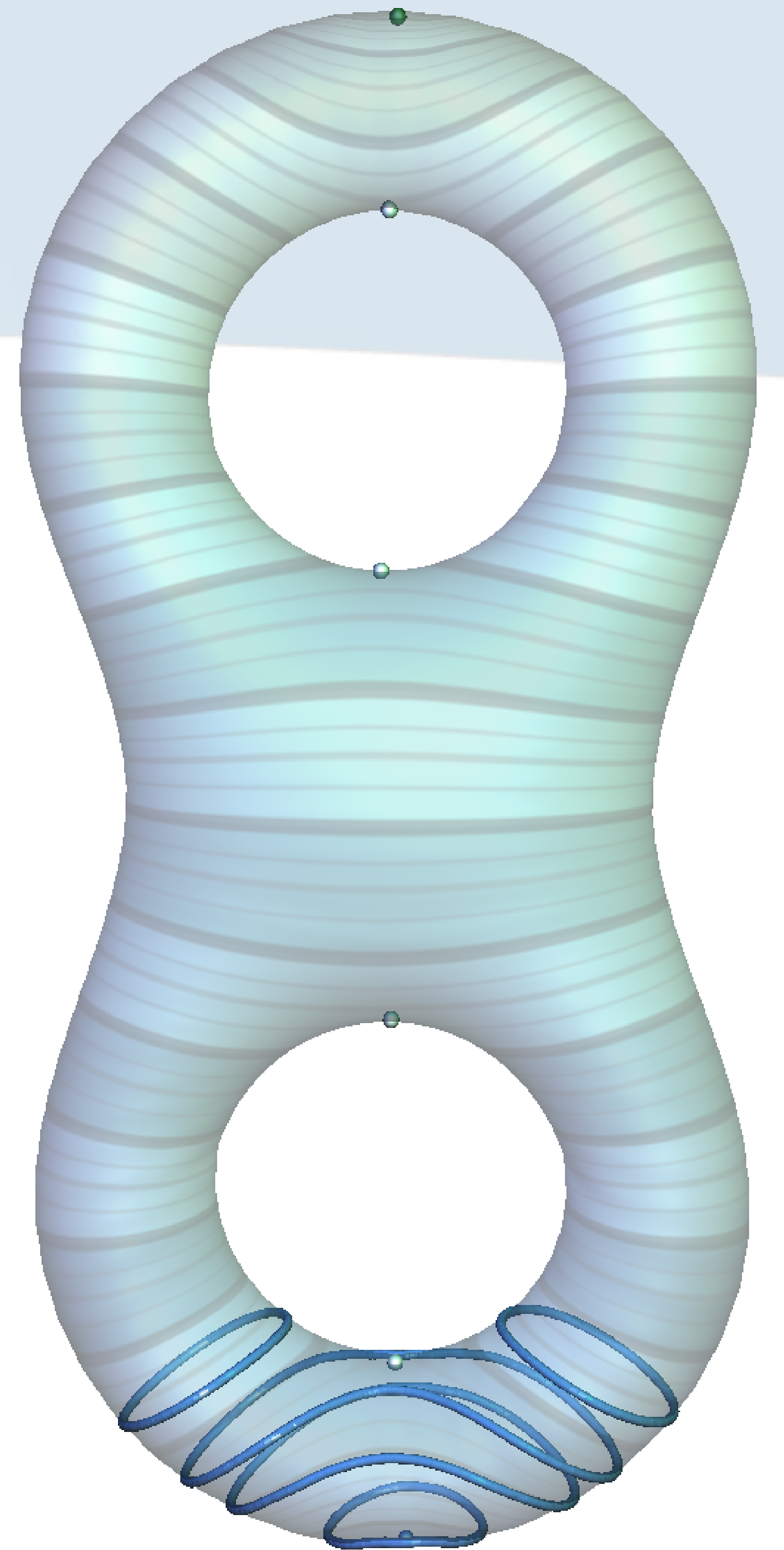
Indexing contours

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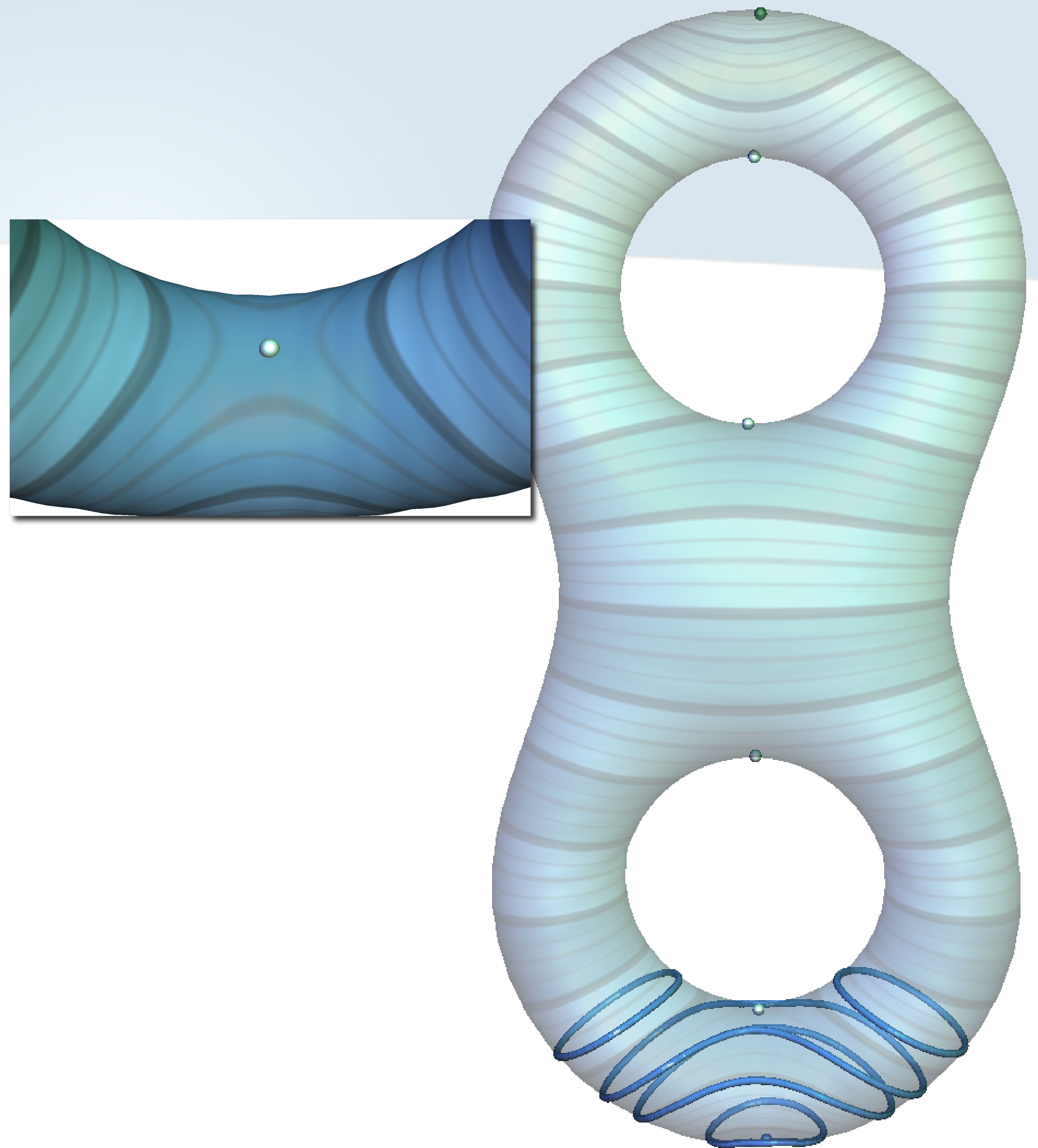
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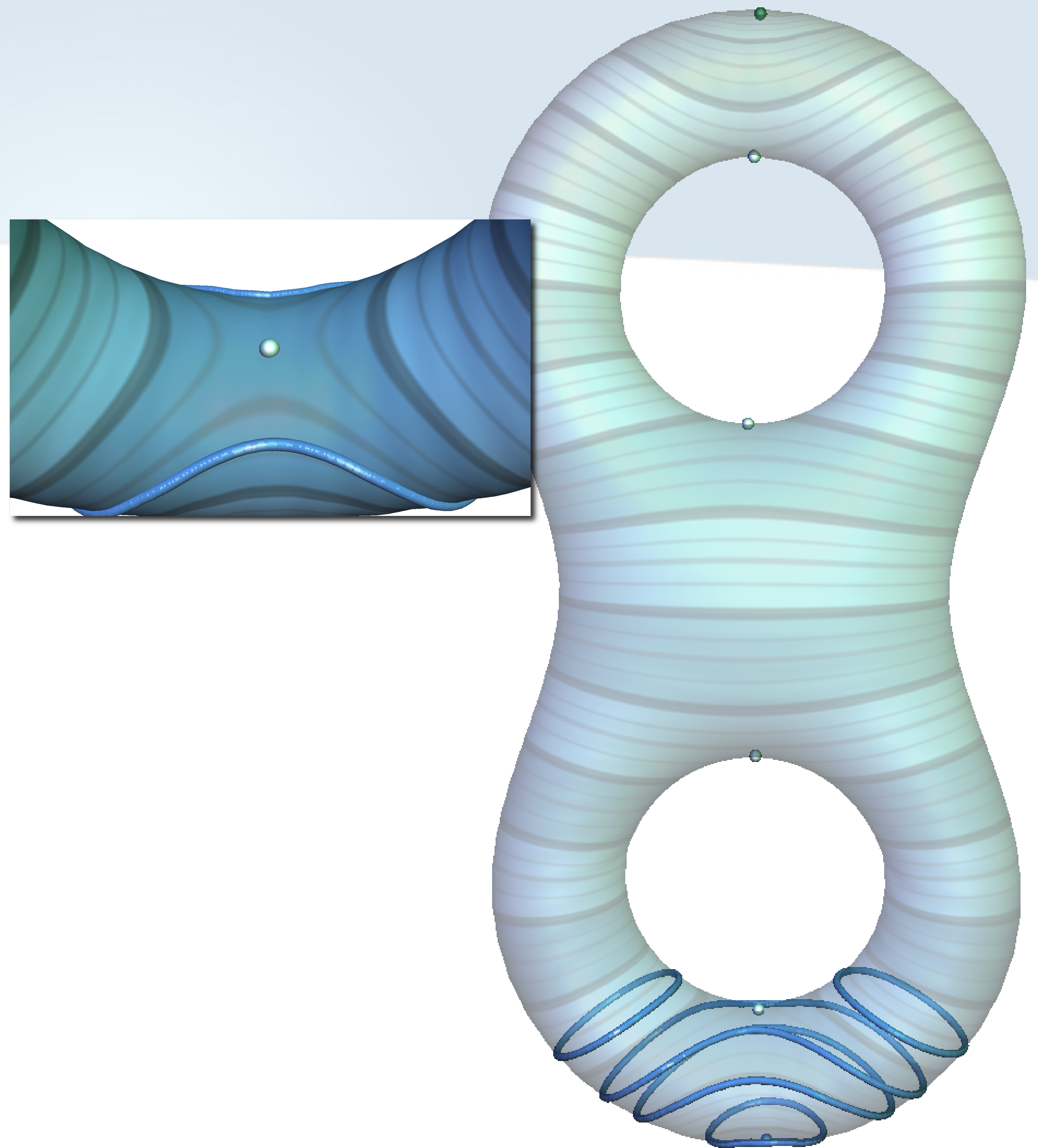
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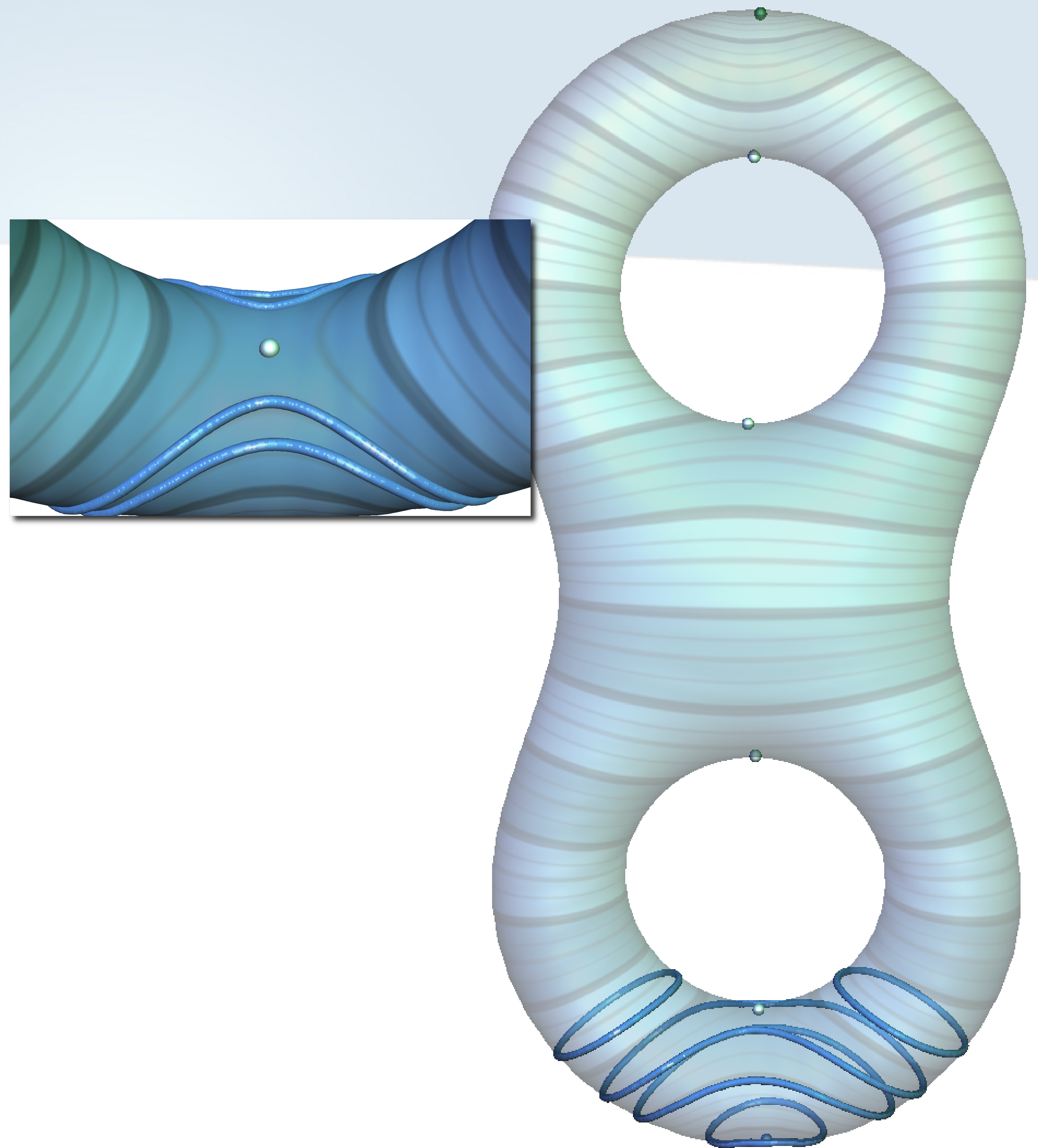
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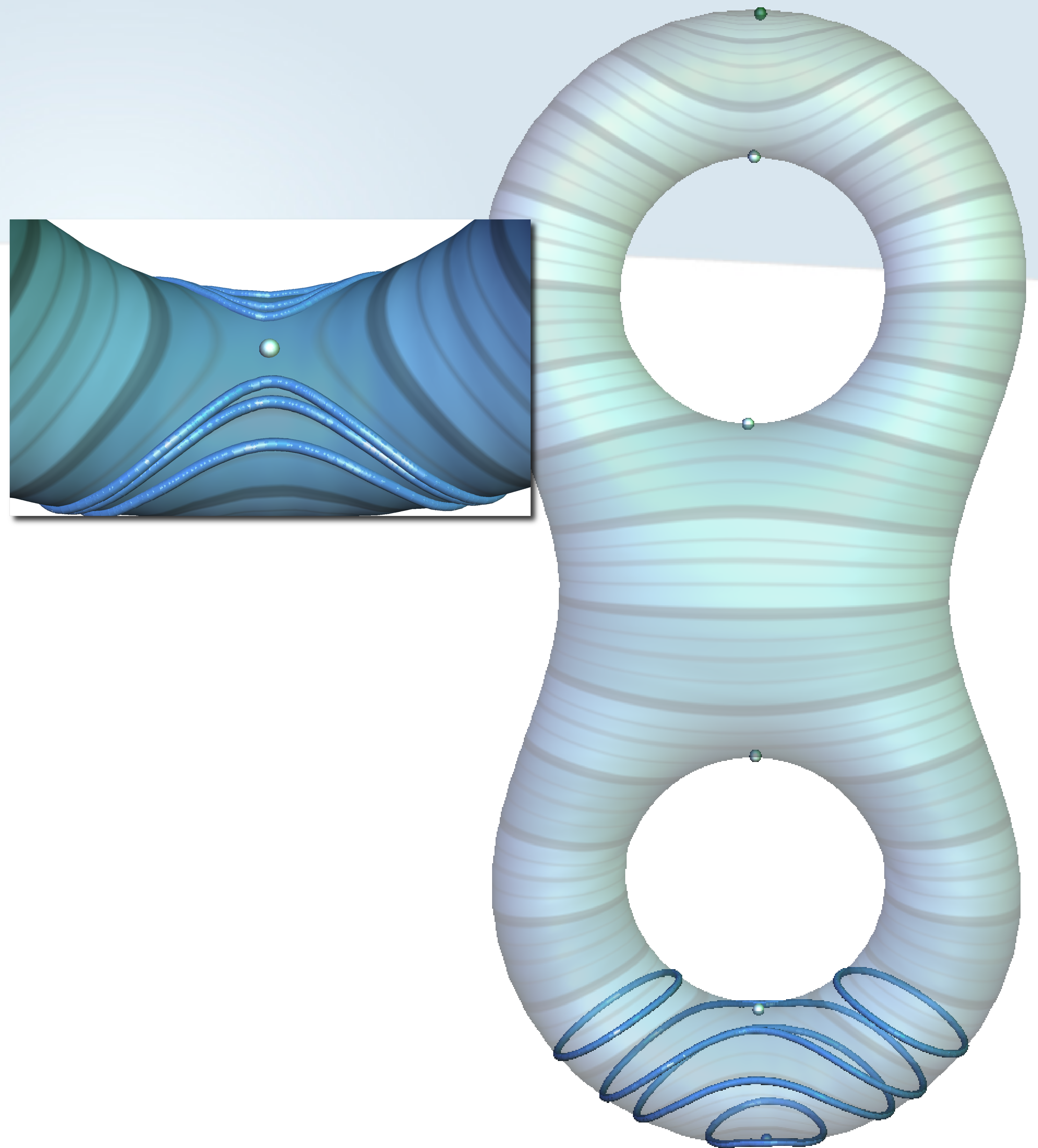
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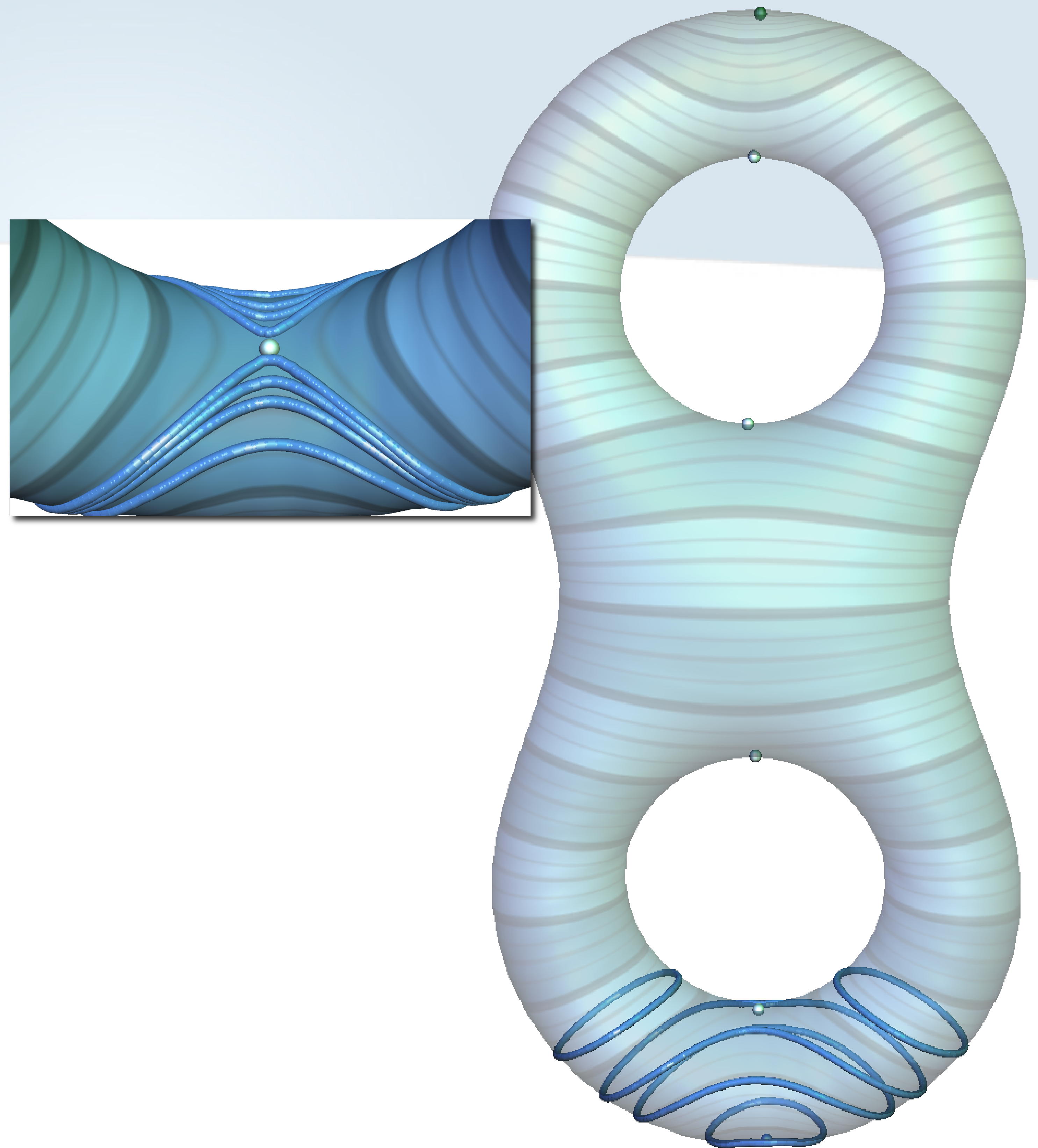
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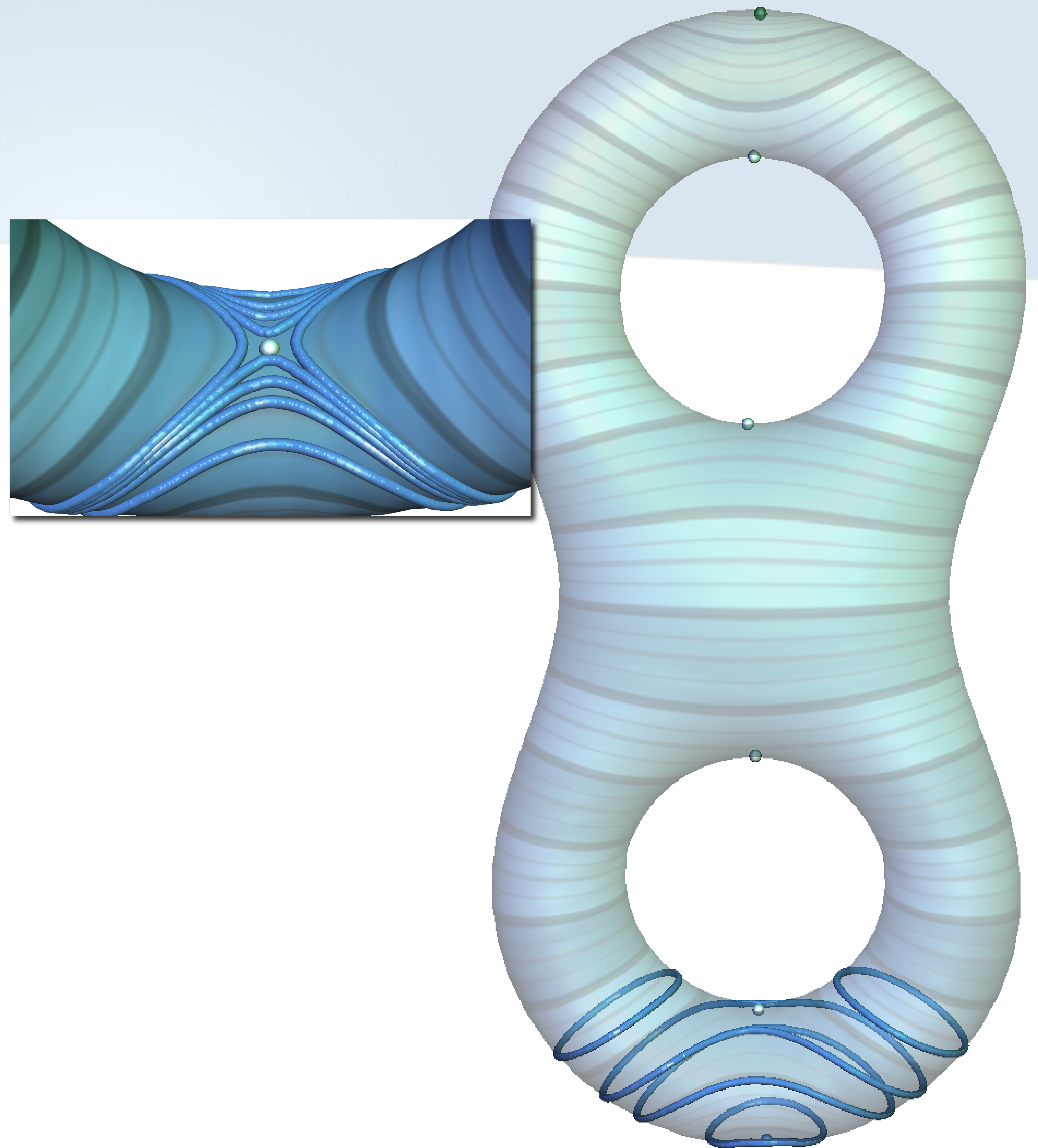
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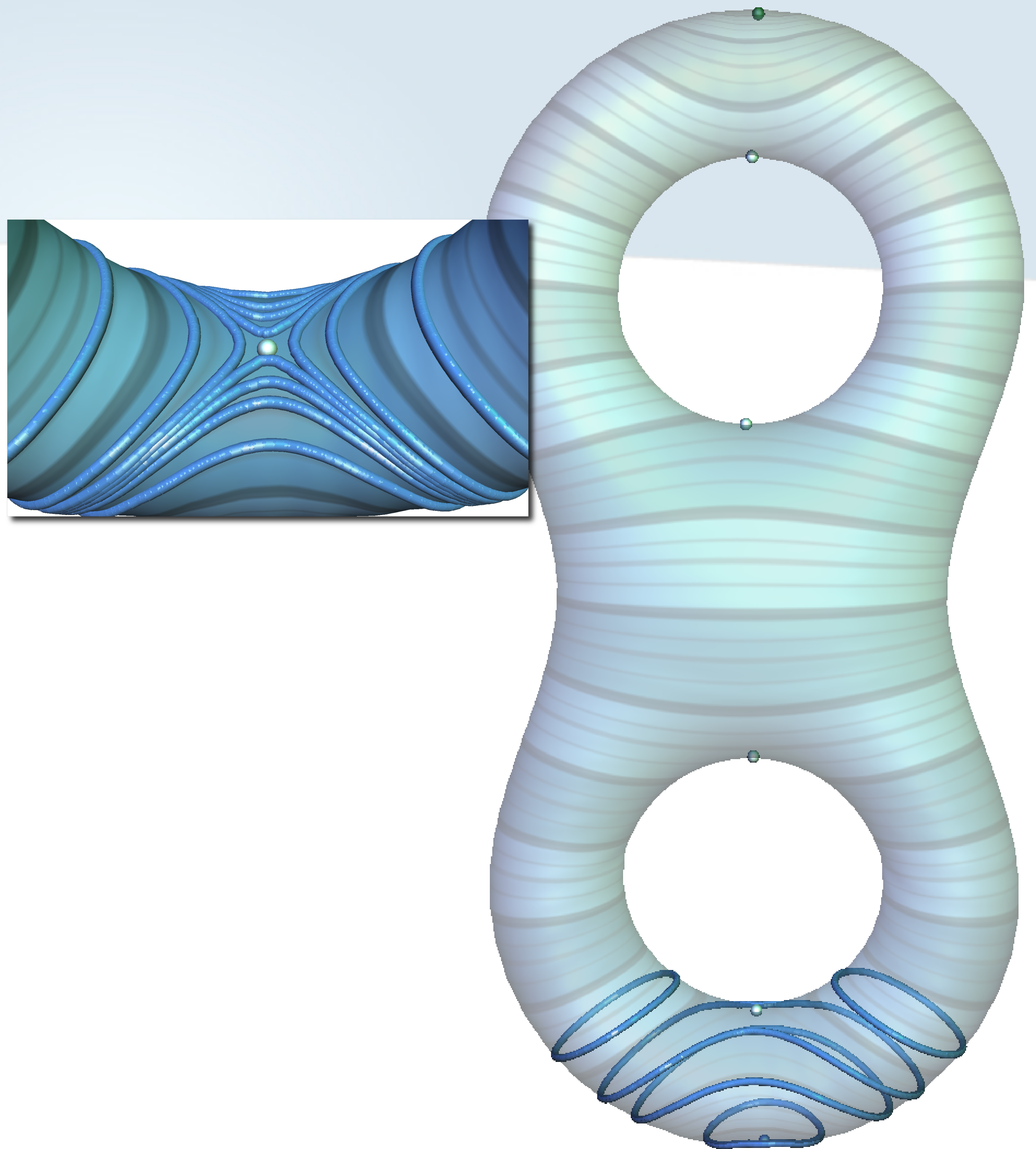
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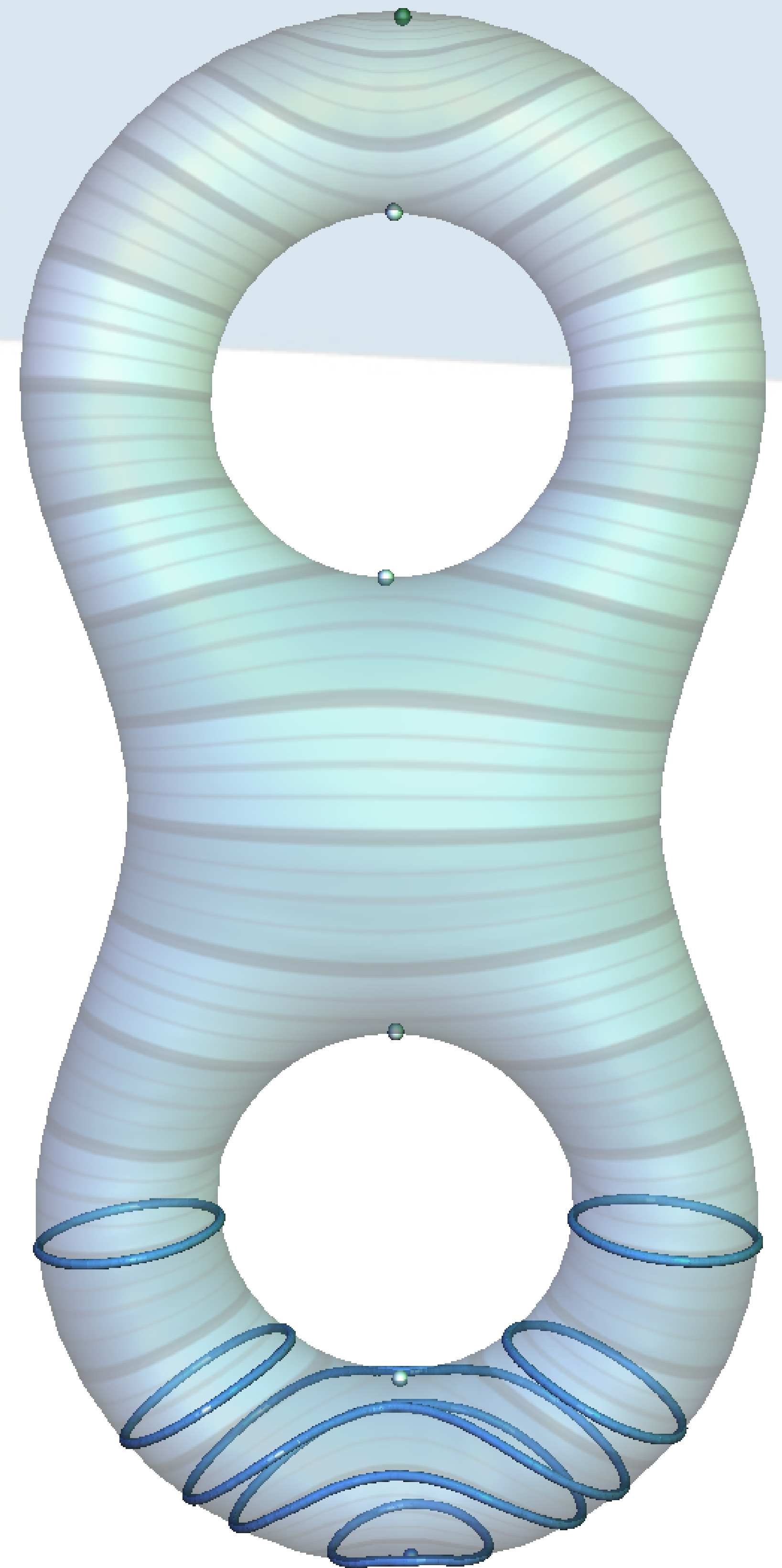
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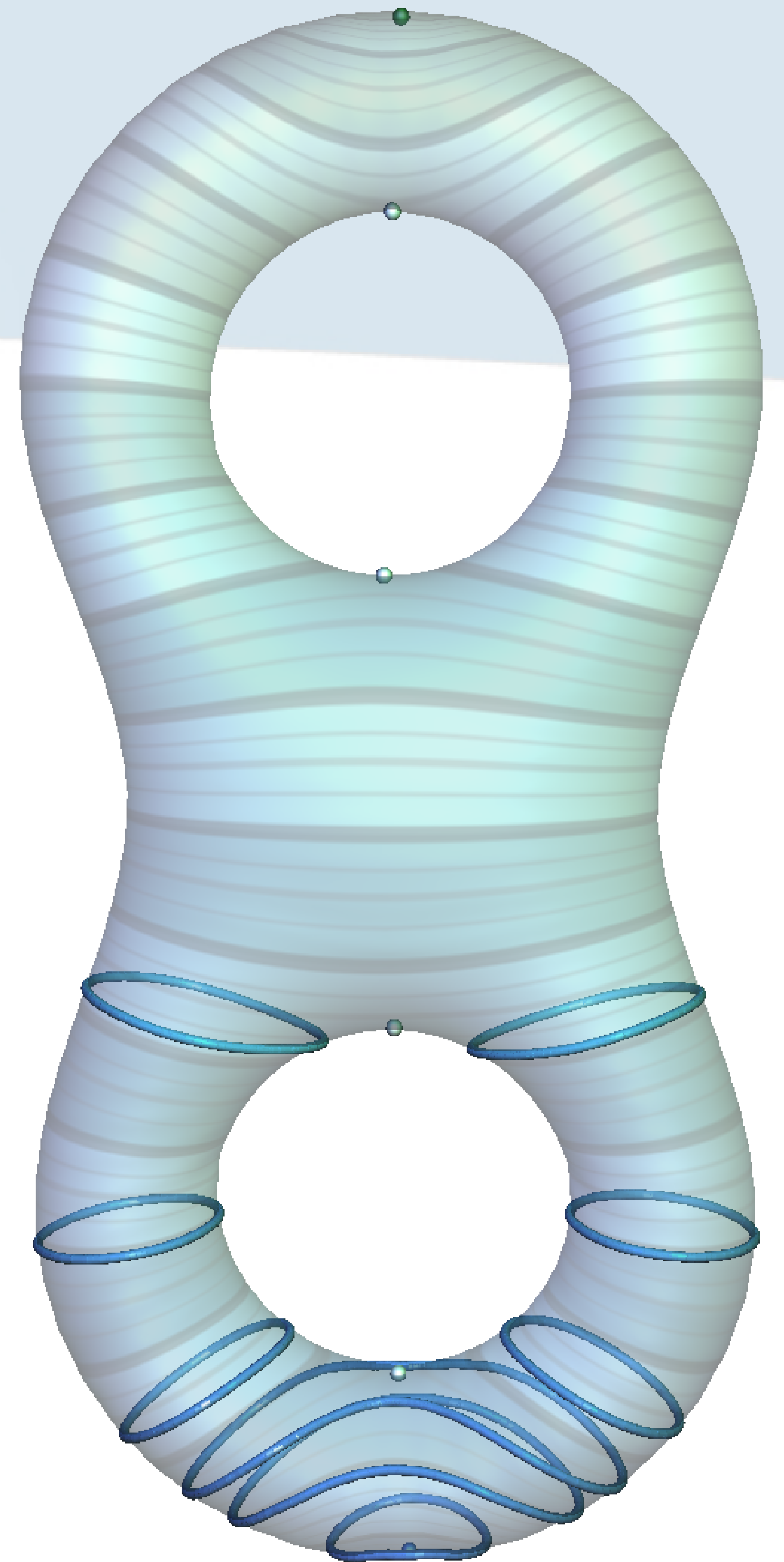
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Indexing contours

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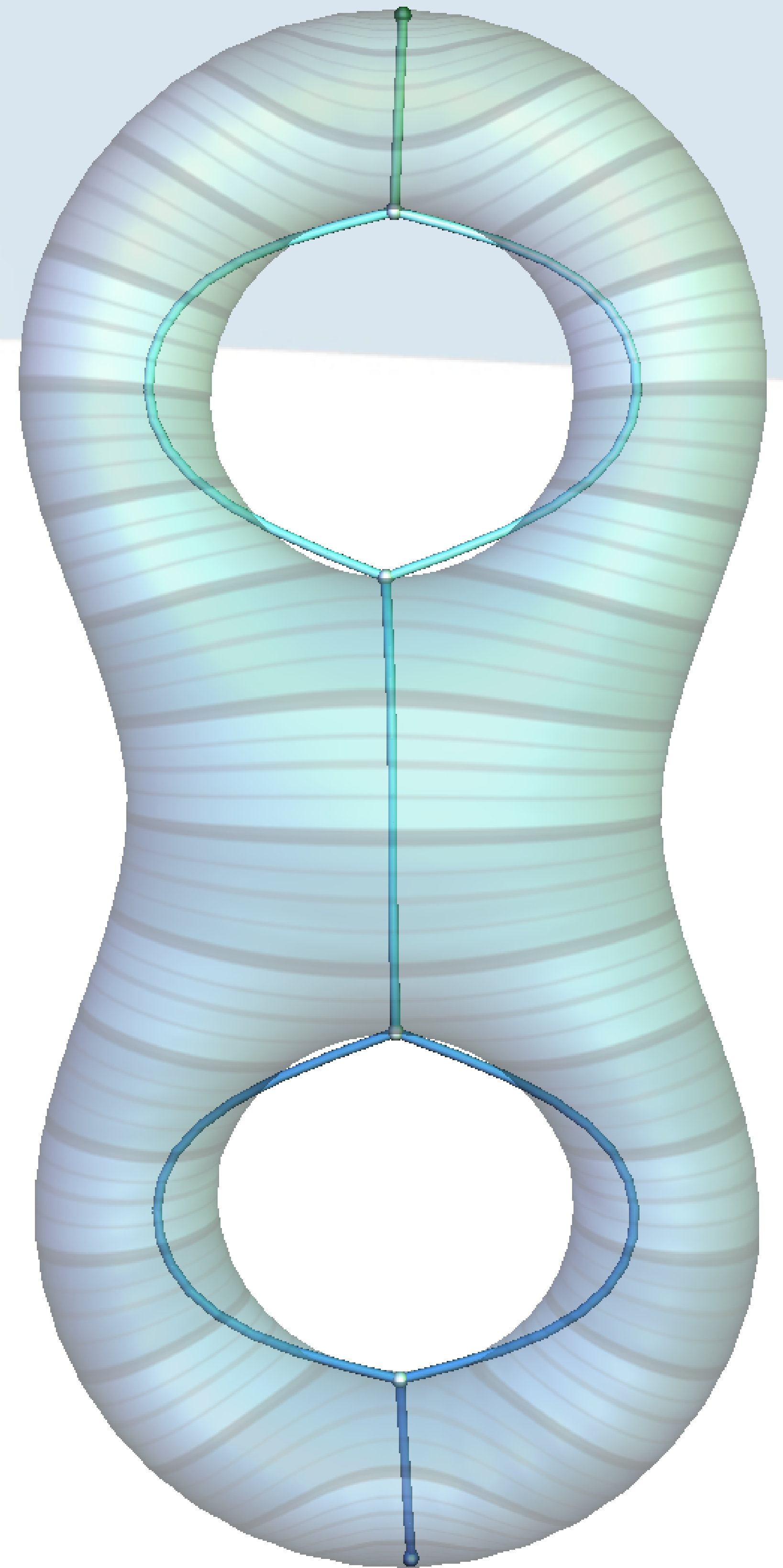
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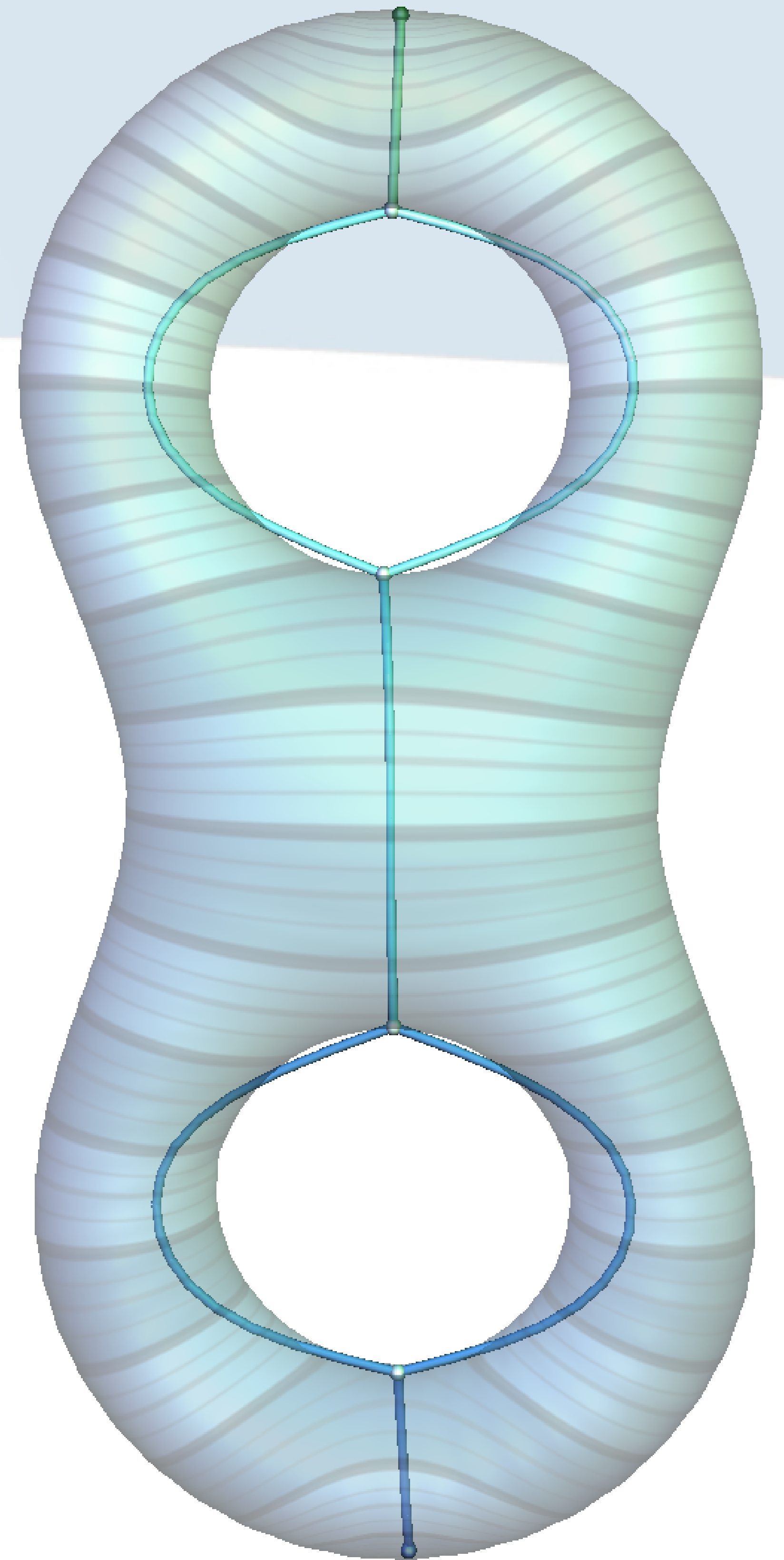
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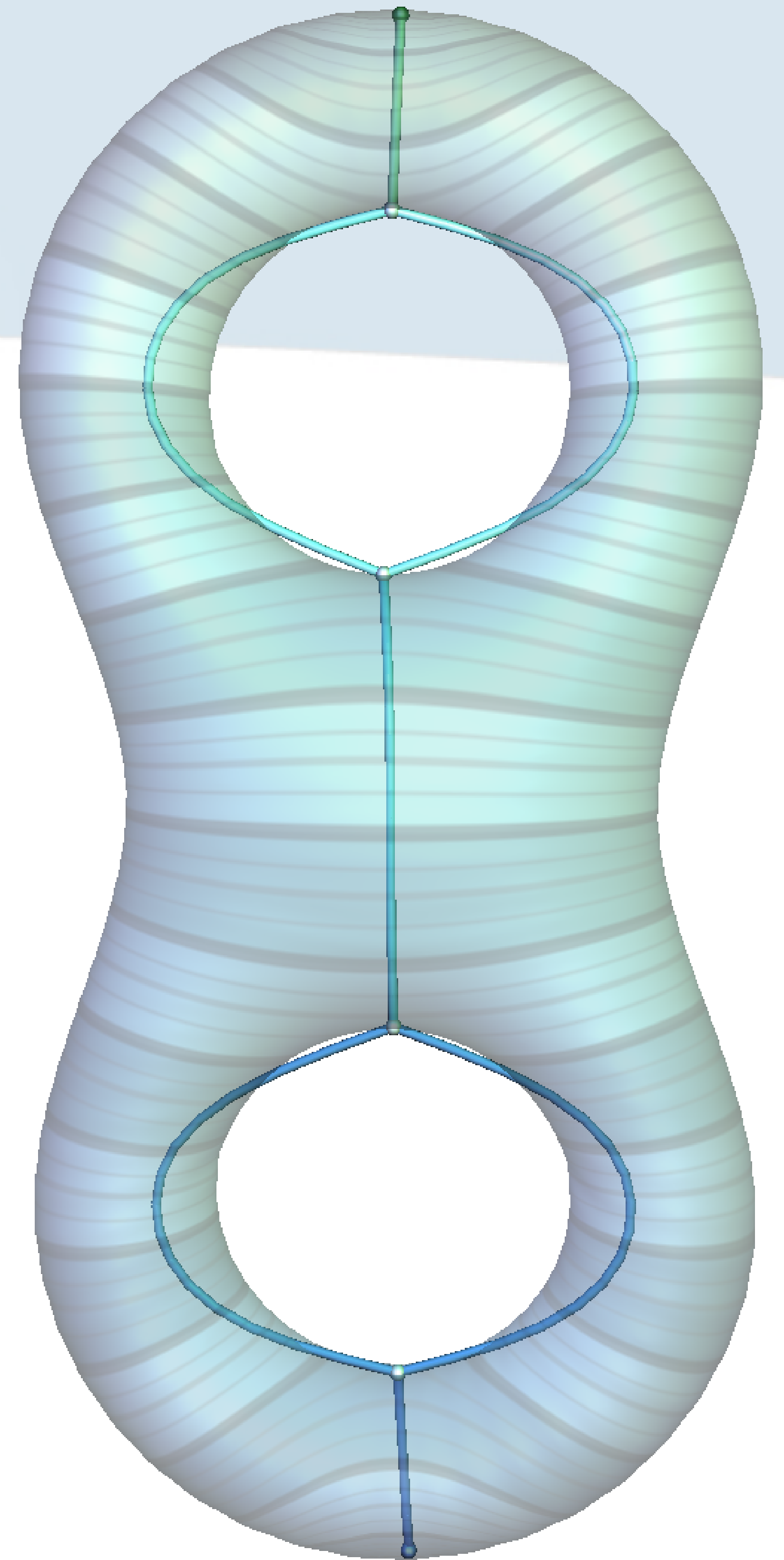
Indexing contours

- Notion of Reeb graph
 - $f : \mathcal{M} \rightarrow \mathbb{R}$
 - *Morse* function
- Contour retraction
 - Continuous map that retracts each contour to a single point



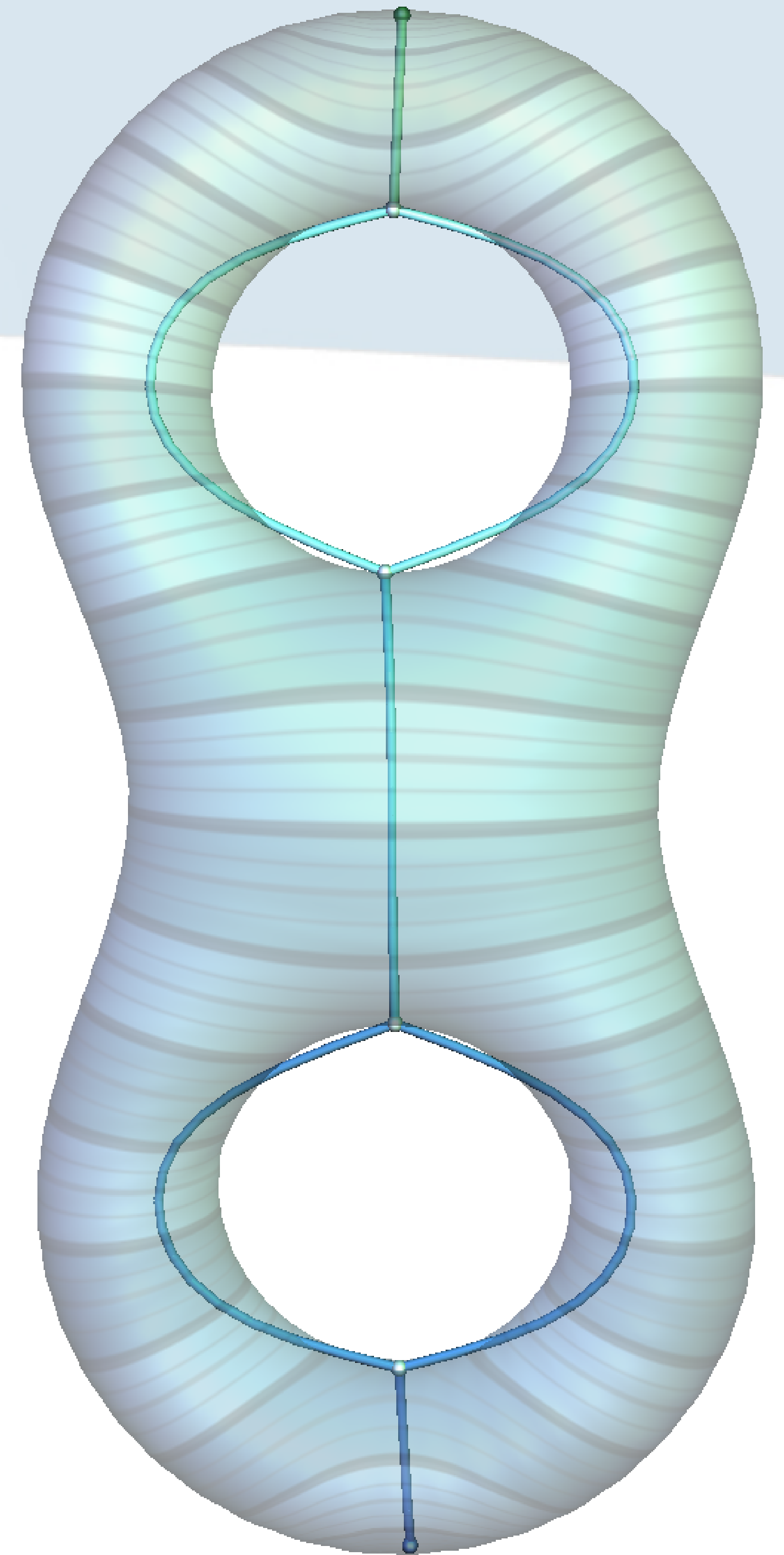
Indexing contours

- Notion of Reeb graph
 - $f : \mathcal{M} \rightarrow \mathbb{R}$
 - *Morse* function
- Contour retraction
 - Continuous map that retracts each contour to a single point
- Reeb graph $\mathcal{R}(f)$
 - Contour retraction of \mathcal{M} under f



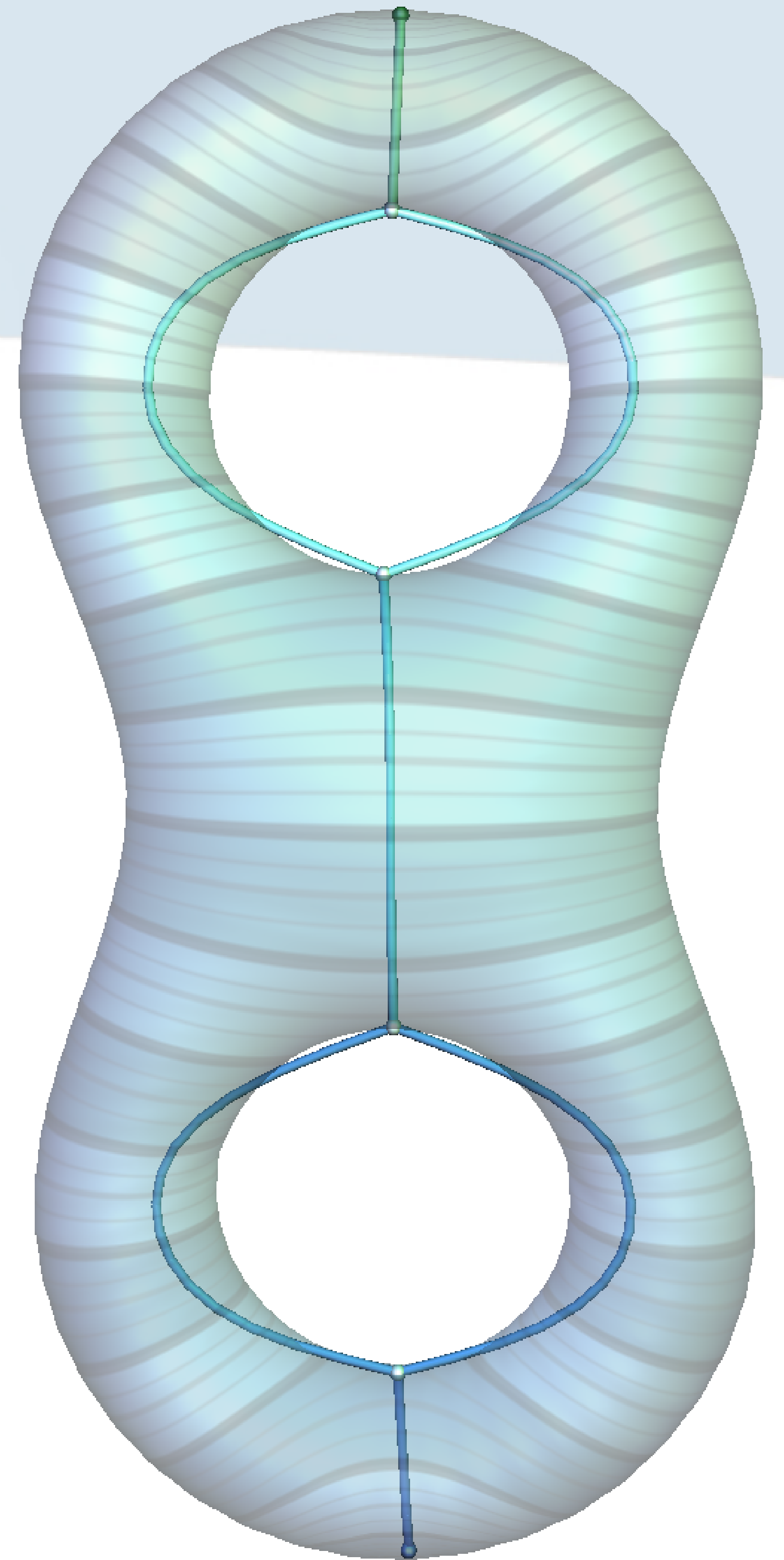
Indexing contours

- Reeb graph properties
 - Continuous 1-dimensional simplicial complex



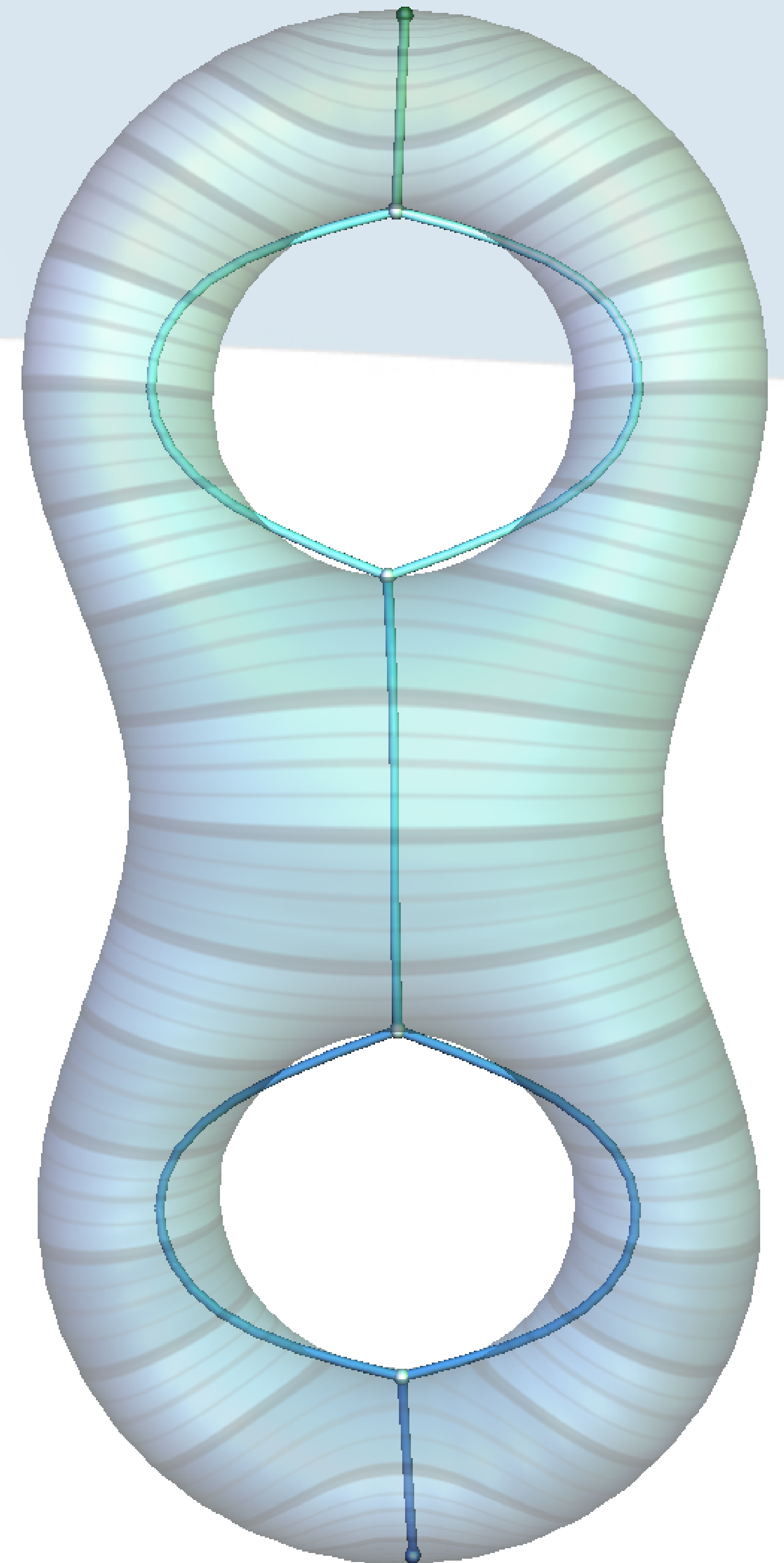
Indexing contours

- Reeb graph properties
 - Continuous 1-dimensional simplicial complex
 - Extrema: valence 1



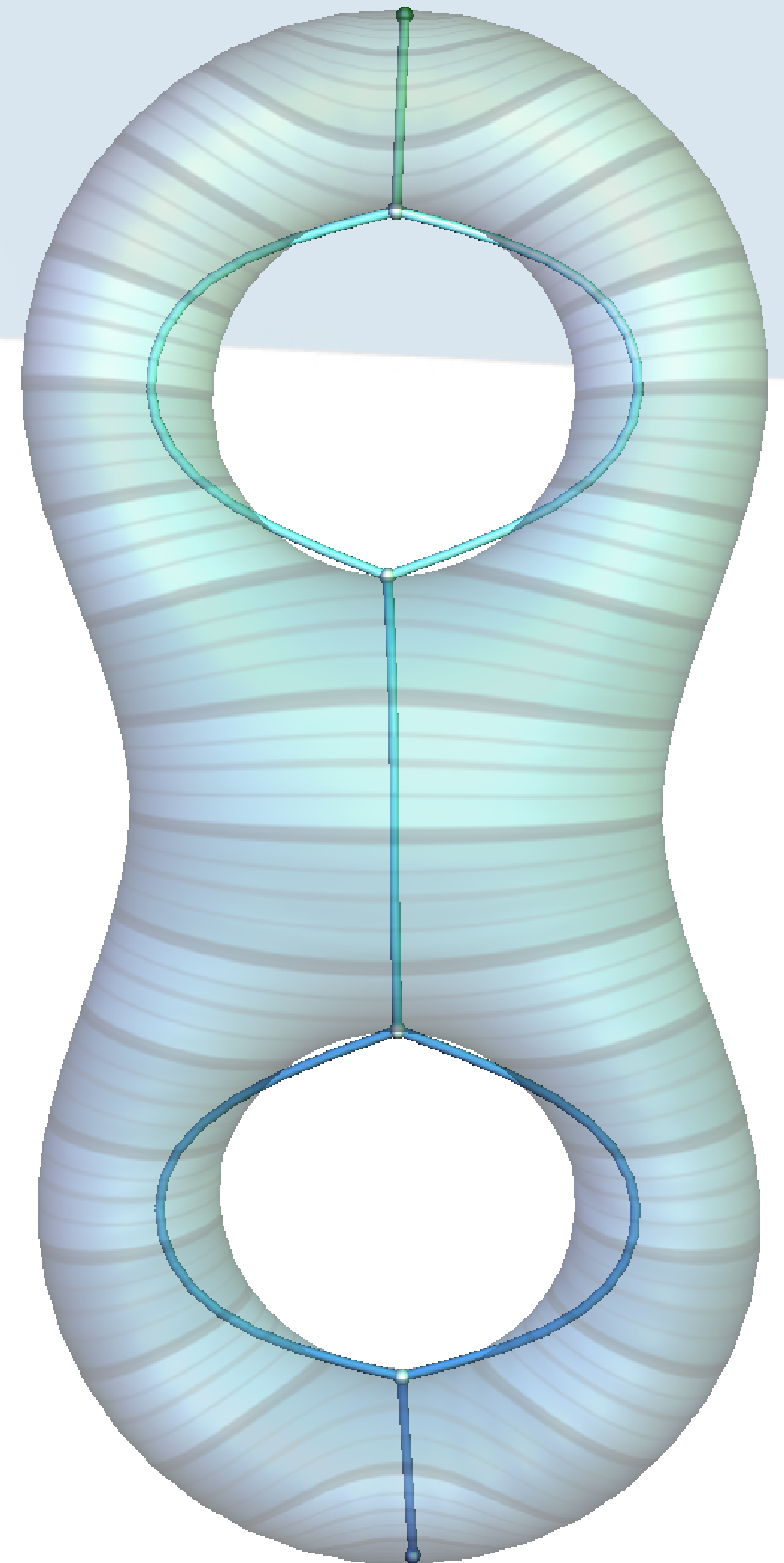
Indexing contours

- Reeb graph properties
 - Continuous 1-dimensional simplicial complex
 - Extrema: valence 1
 - Saddles in 2D: valence 3 or 4 (boundary)
 - Saddles in nD: valence 2 or 3



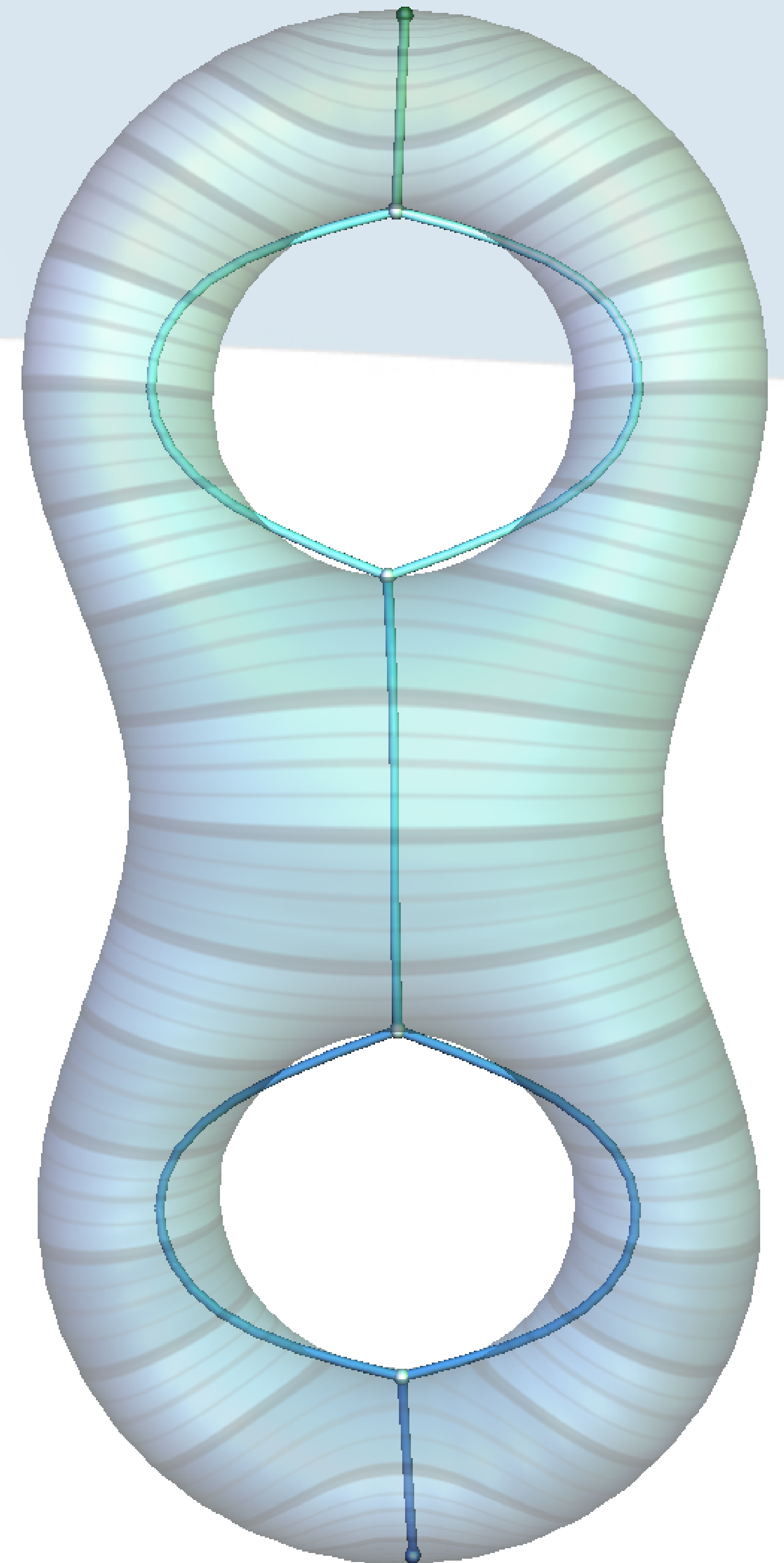
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- In practice:
 - Arcs: collection of vertices



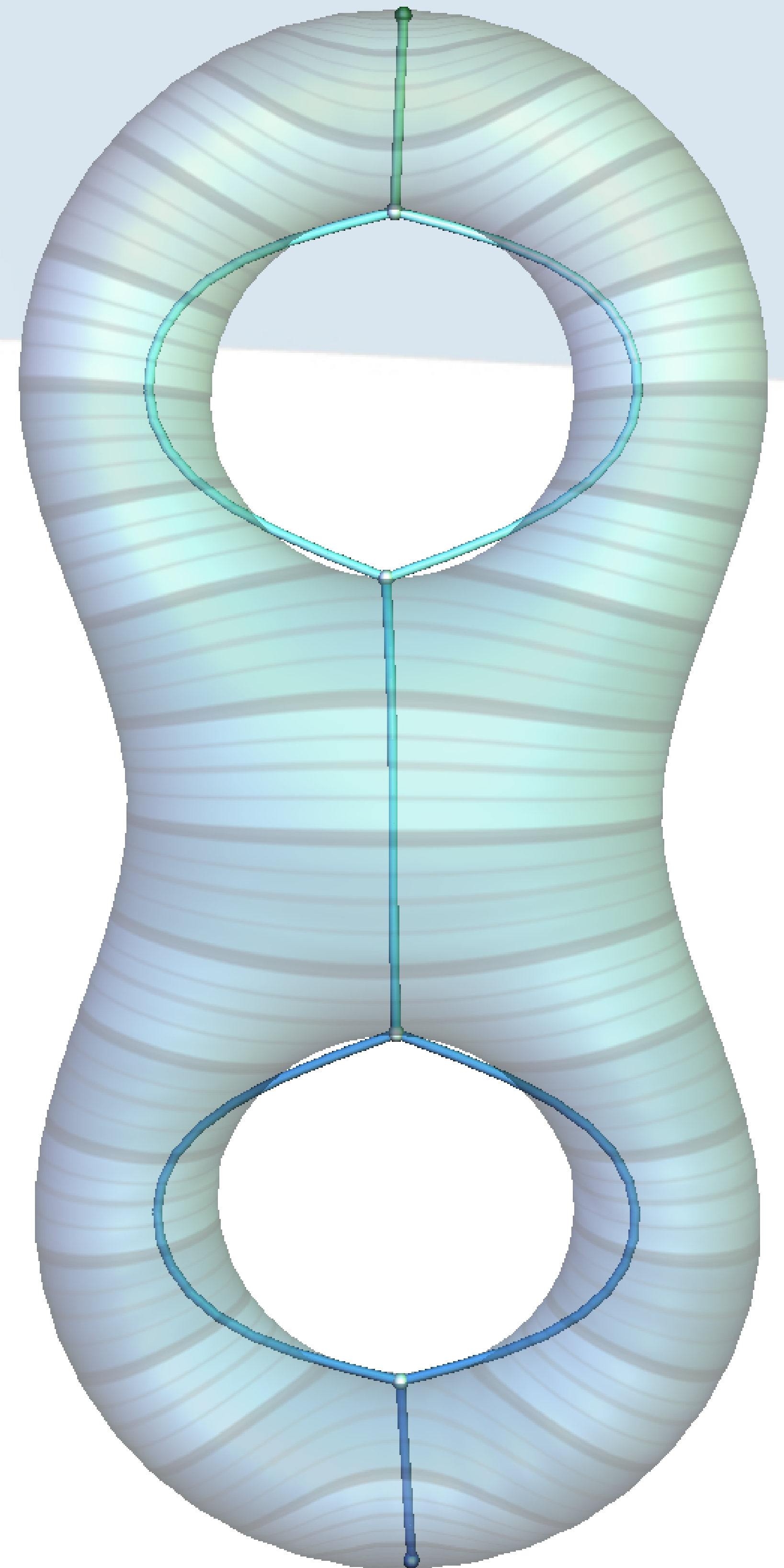
Indexing contours

- Reeb graph properties
 - Continuous 1-dimensional simplicial complex
 - Extrema: valence 1
 - Saddles in 2D: valence 3 or 4 (boundary)
 - Saddles in nD: valence 2 or 3
- In practice:
 - Arcs: collection of vertices
 - Simply connected domains: Carr00



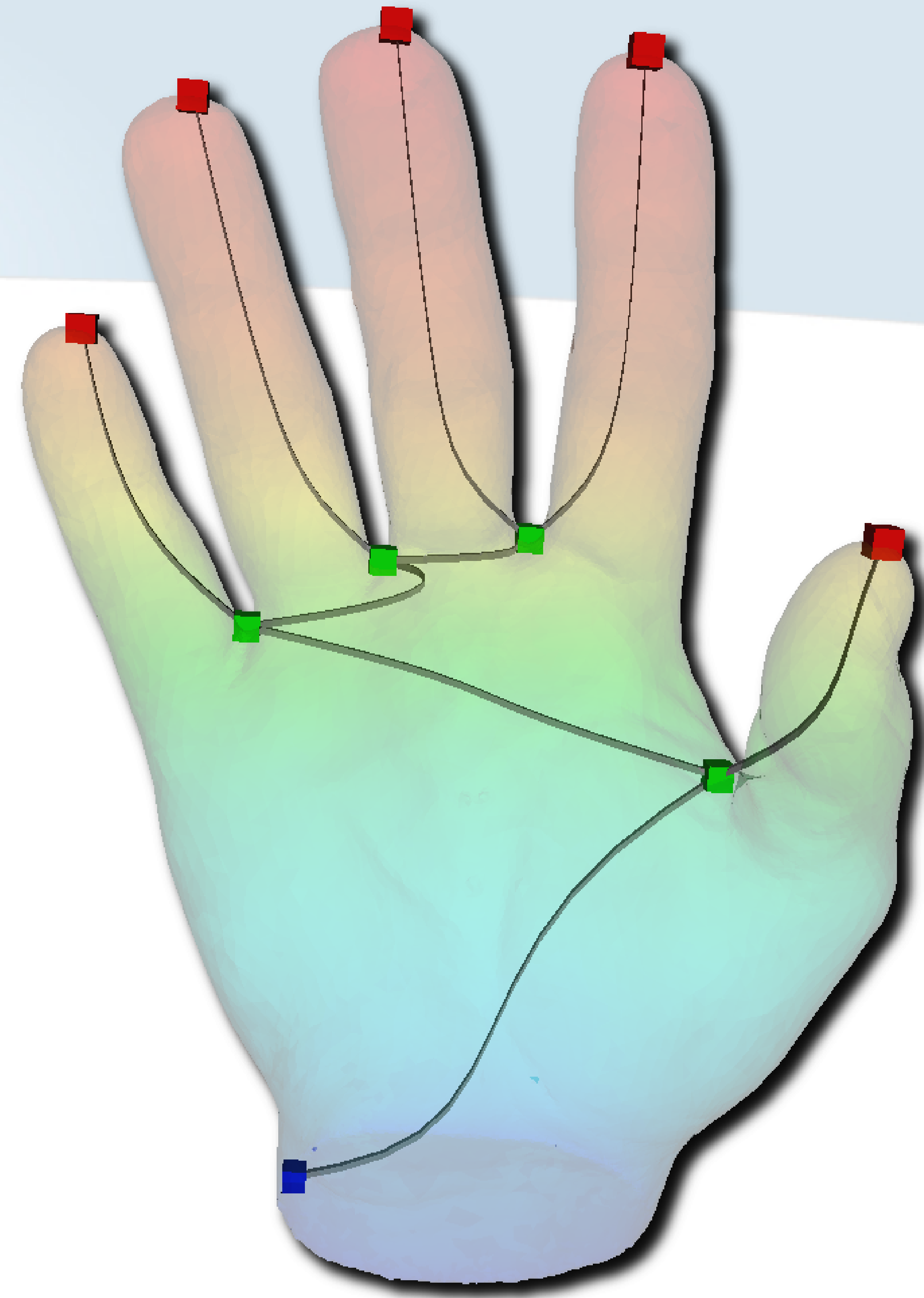
Indexing contours

- Reeb graph properties
 - Continuous 1-dimensional simplicial complex
 - Extrema: valence 1
 - Saddles in 2D: valence 3 or 4 (boundary)
 - Saddles in nD: valence 2 or 3
- In practice:
 - Arcs: collection of vertices
 - Simply connected domains: Carr00
 - Otherwise: Pascucci07, Tierny09, Parsa12



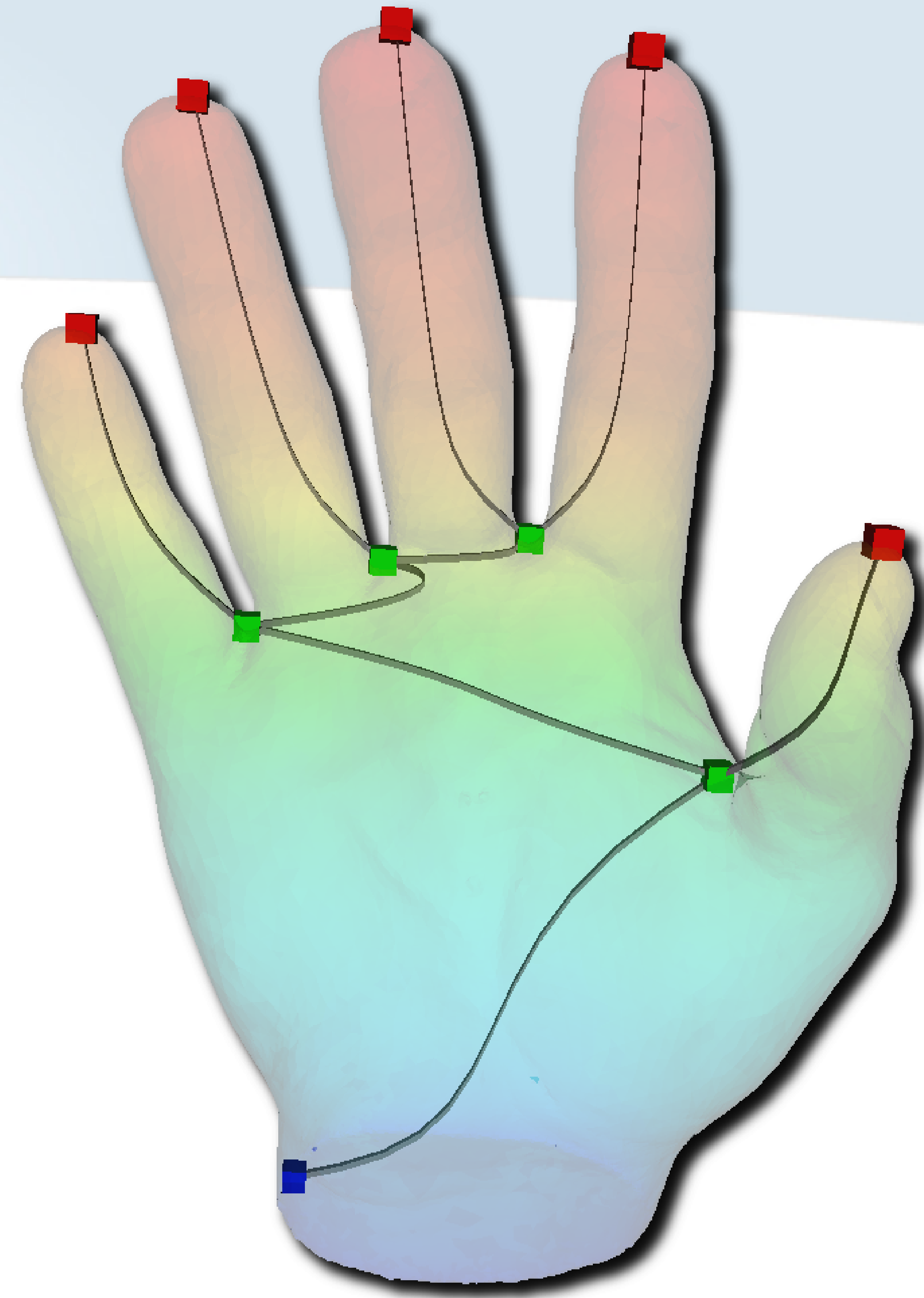
Online contour query

- Reeb graph computation
 - Once for all, matters of seconds



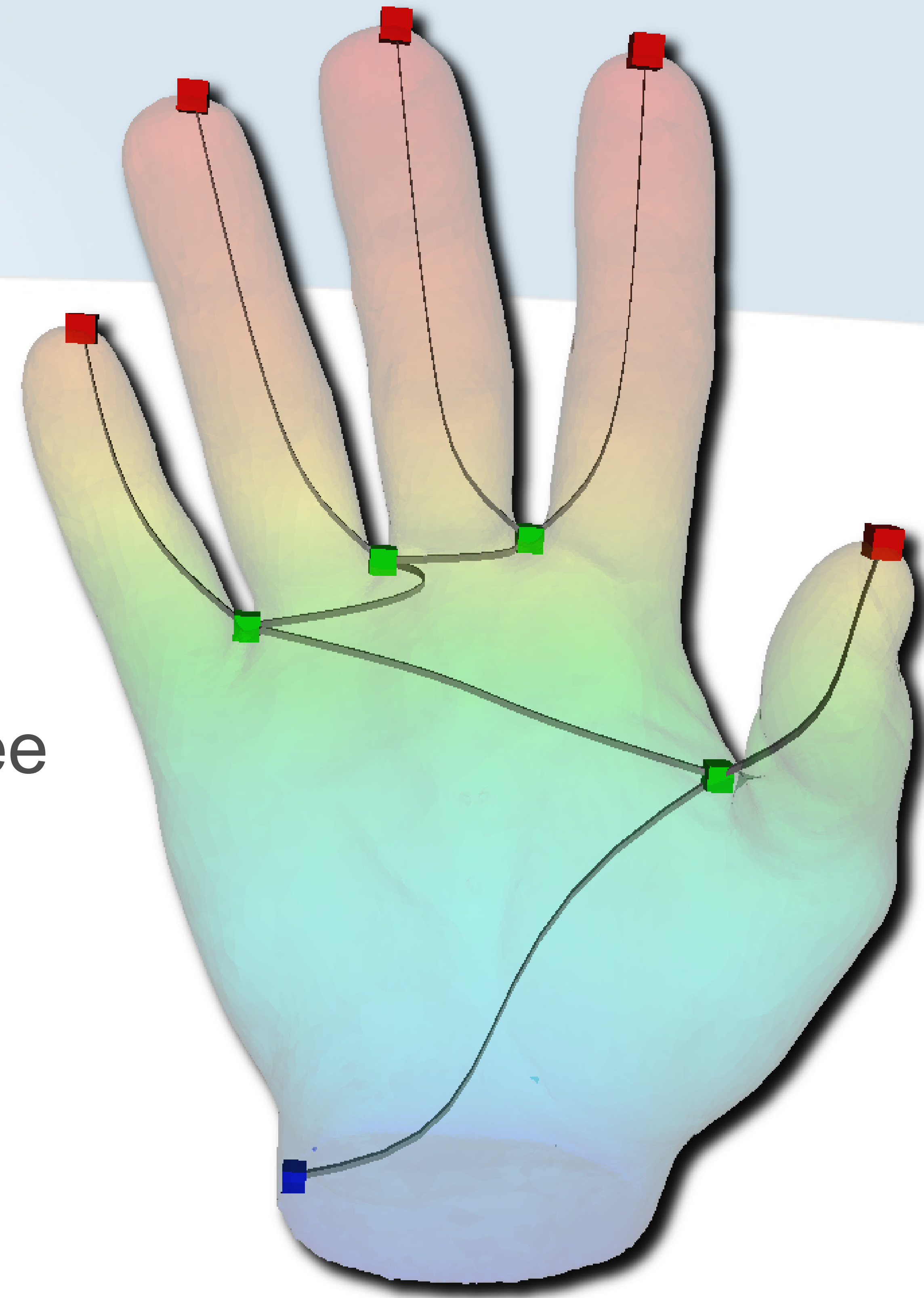
Online contour query

- Reeb graph computation
 - Once for all, matters of seconds
 - Store the arcs in balanced interval tree



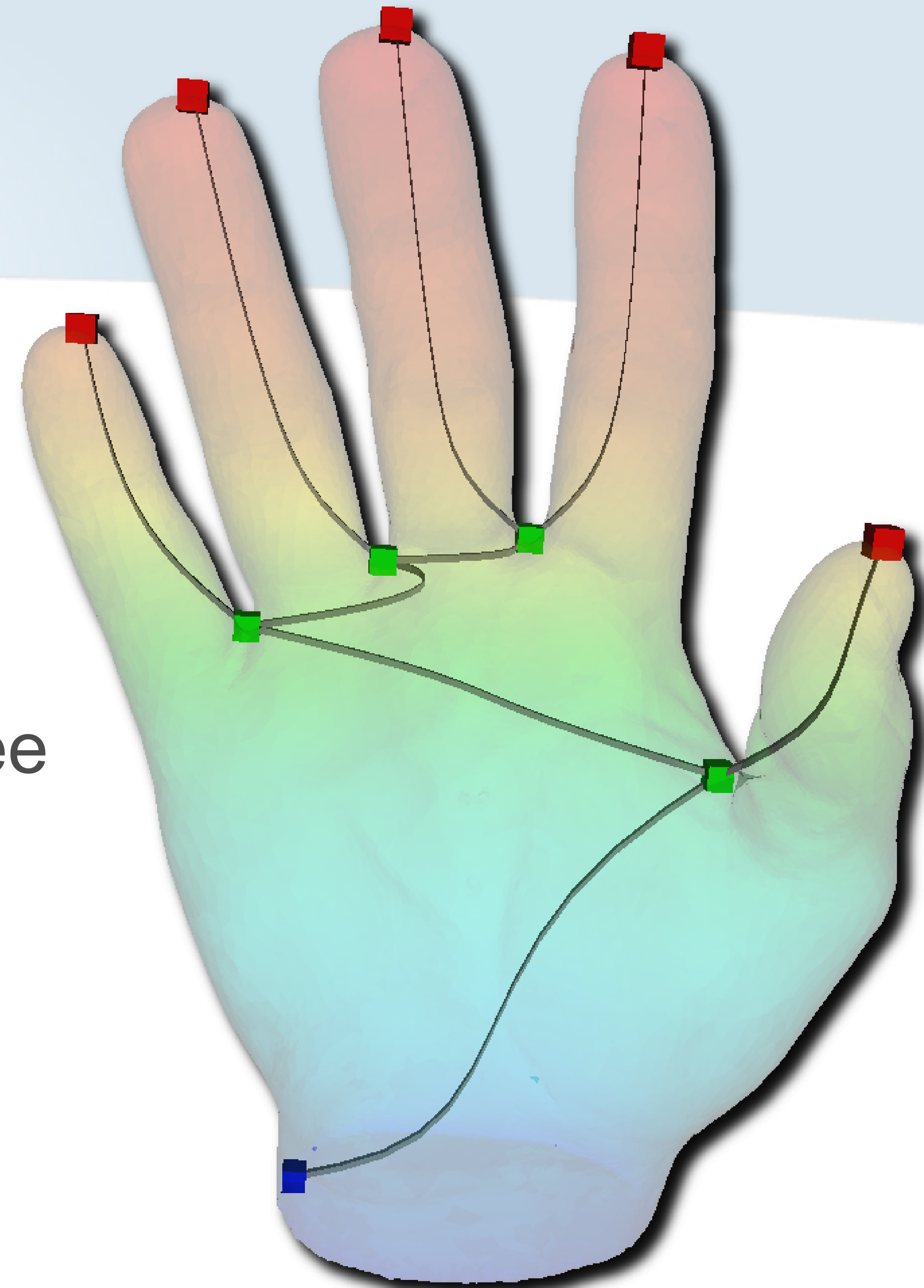
Online contour query

- Reeb graph computation
 - Once for all, matters of seconds
 - Store the arcs in balanced interval tree
 - For each arc, balanced binary search tree



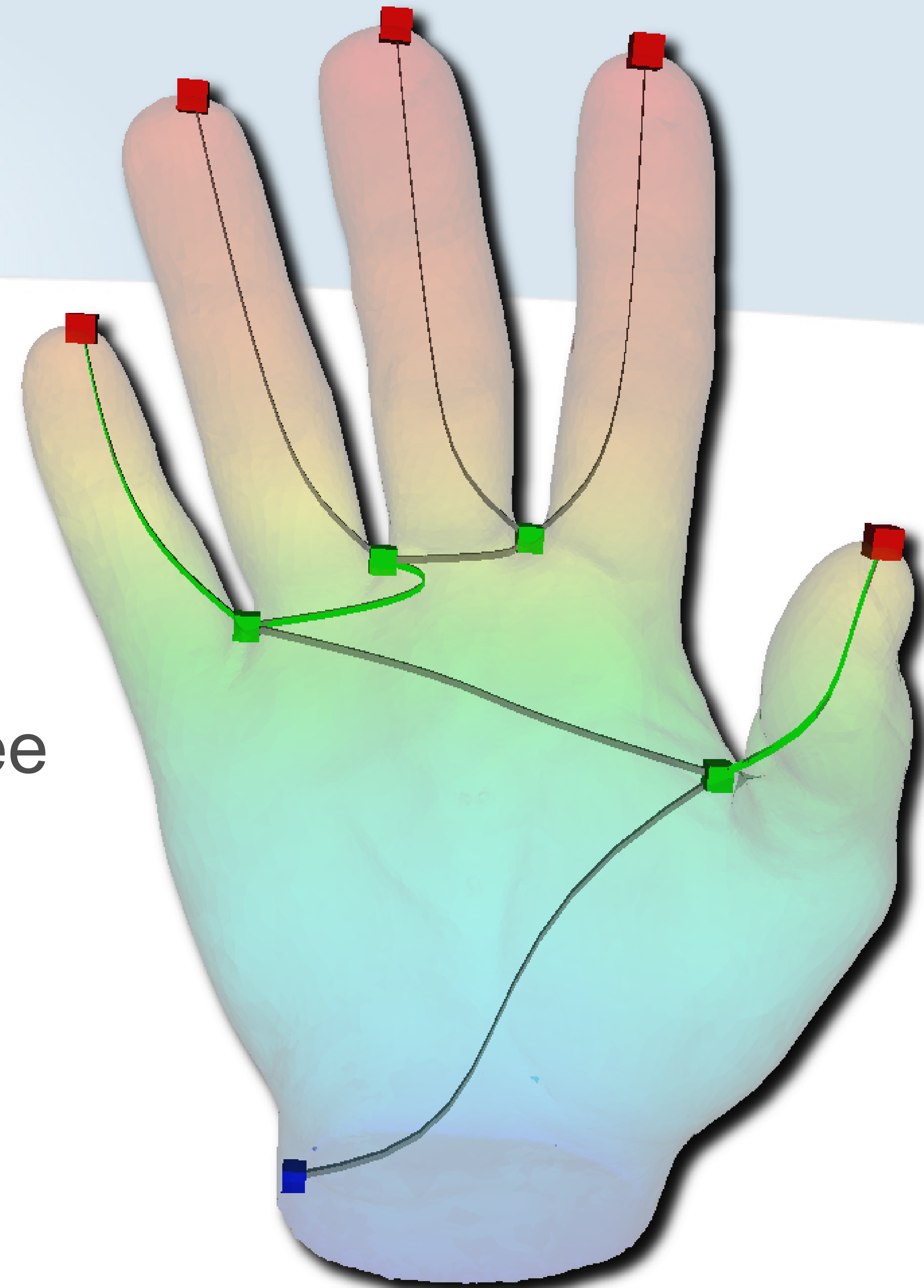
Online contour query

- Reeb graph computation
 - Once for all, matters of seconds
 - Store the arcs in balanced interval tree
 - For each arc, balanced binary search tree
- Isovalue query:



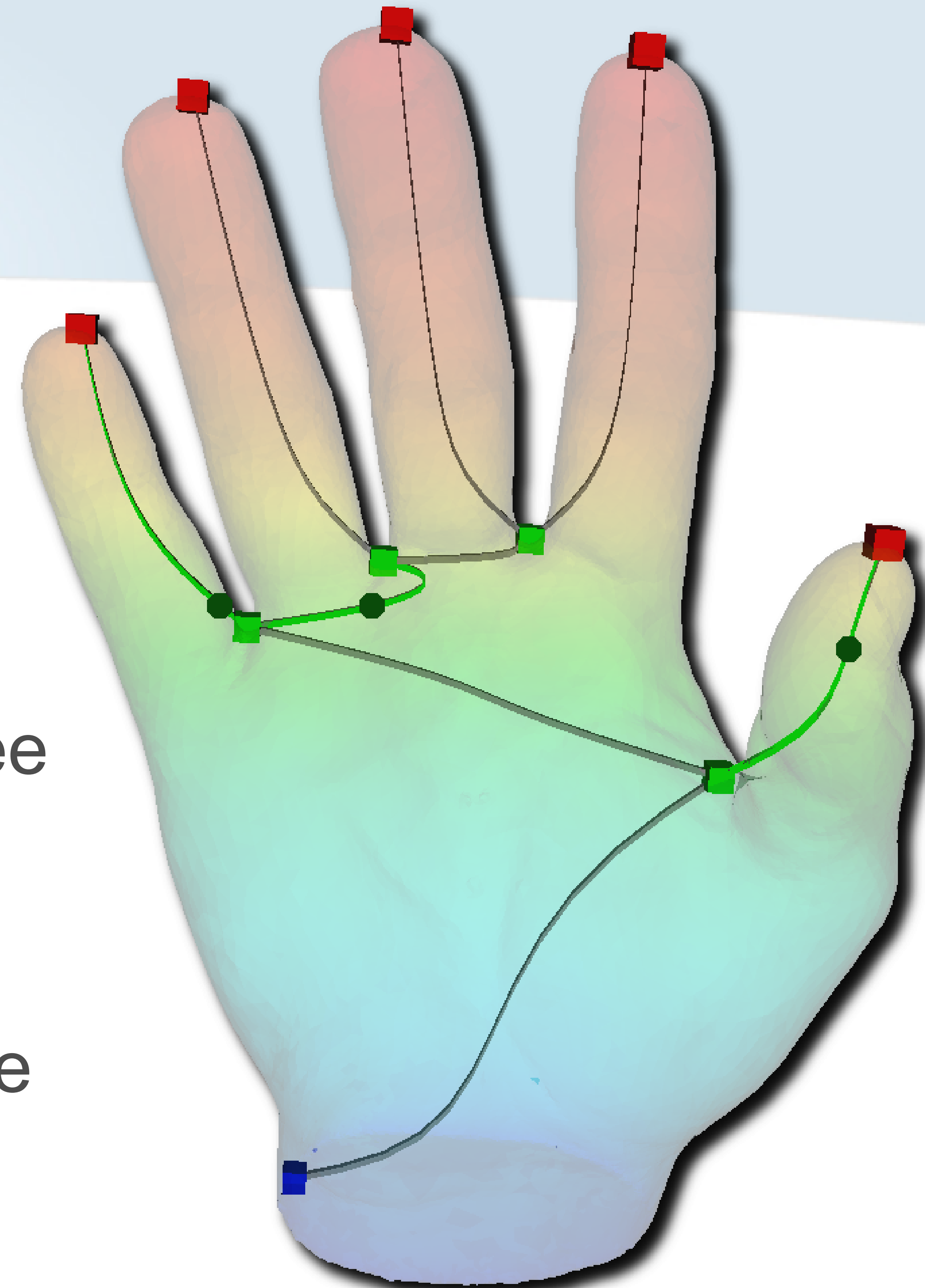
Online contour query

- Reeb graph computation
 - Once for all, matters of seconds
 - Store the arcs in balanced interval tree
 - For each arc, balanced binary search tree
- Isovalue query:
 - Find the arcs crossing the isovalue



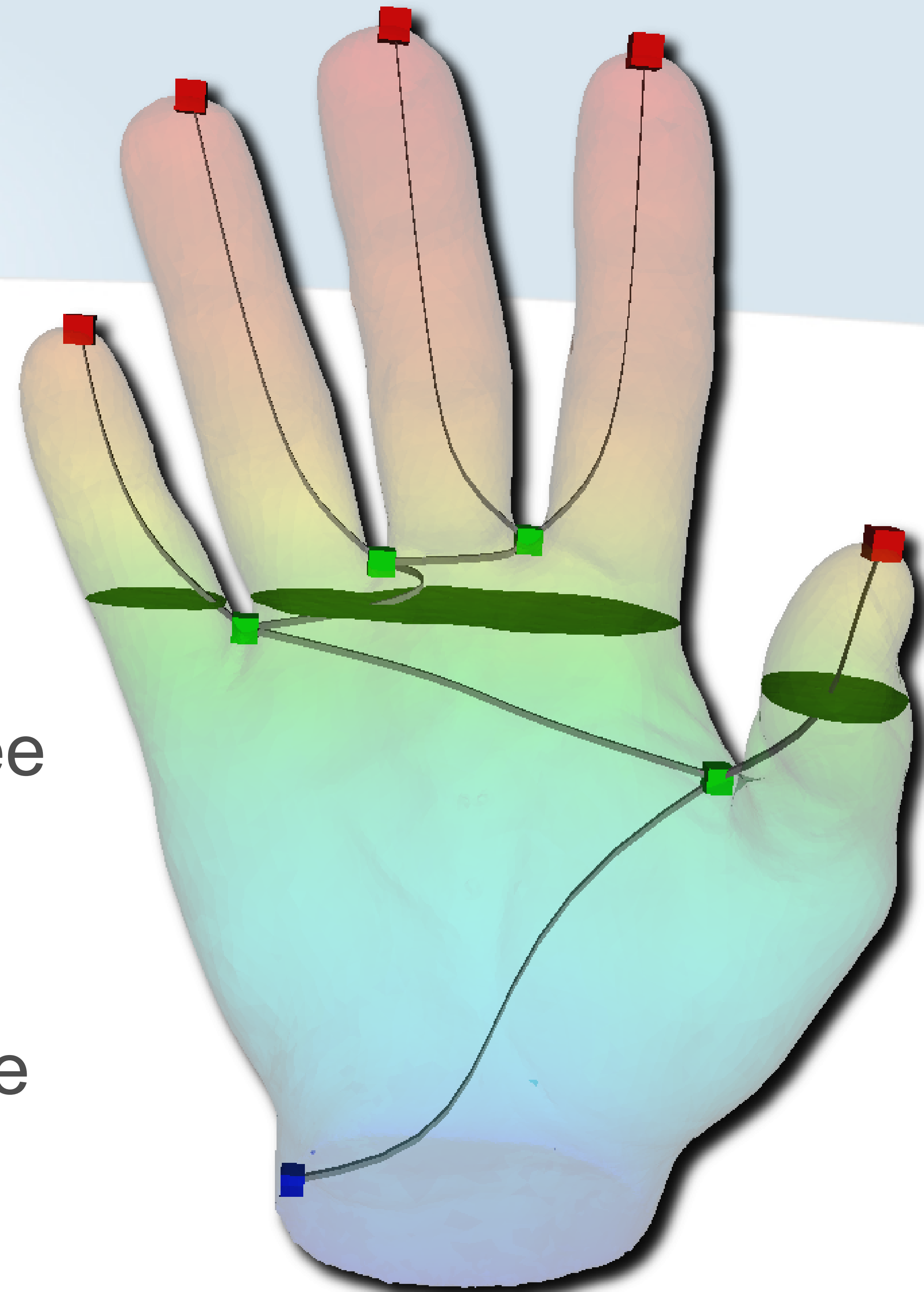
Online contour query

- Reeb graph computation
 - Once for all, matters of seconds
 - Store the arcs in balanced interval tree
 - For each arc, balanced binary search tree
- Isovalue query:
 - Find the arcs crossing the isovalue
 - Find the vertex right below the isovalue



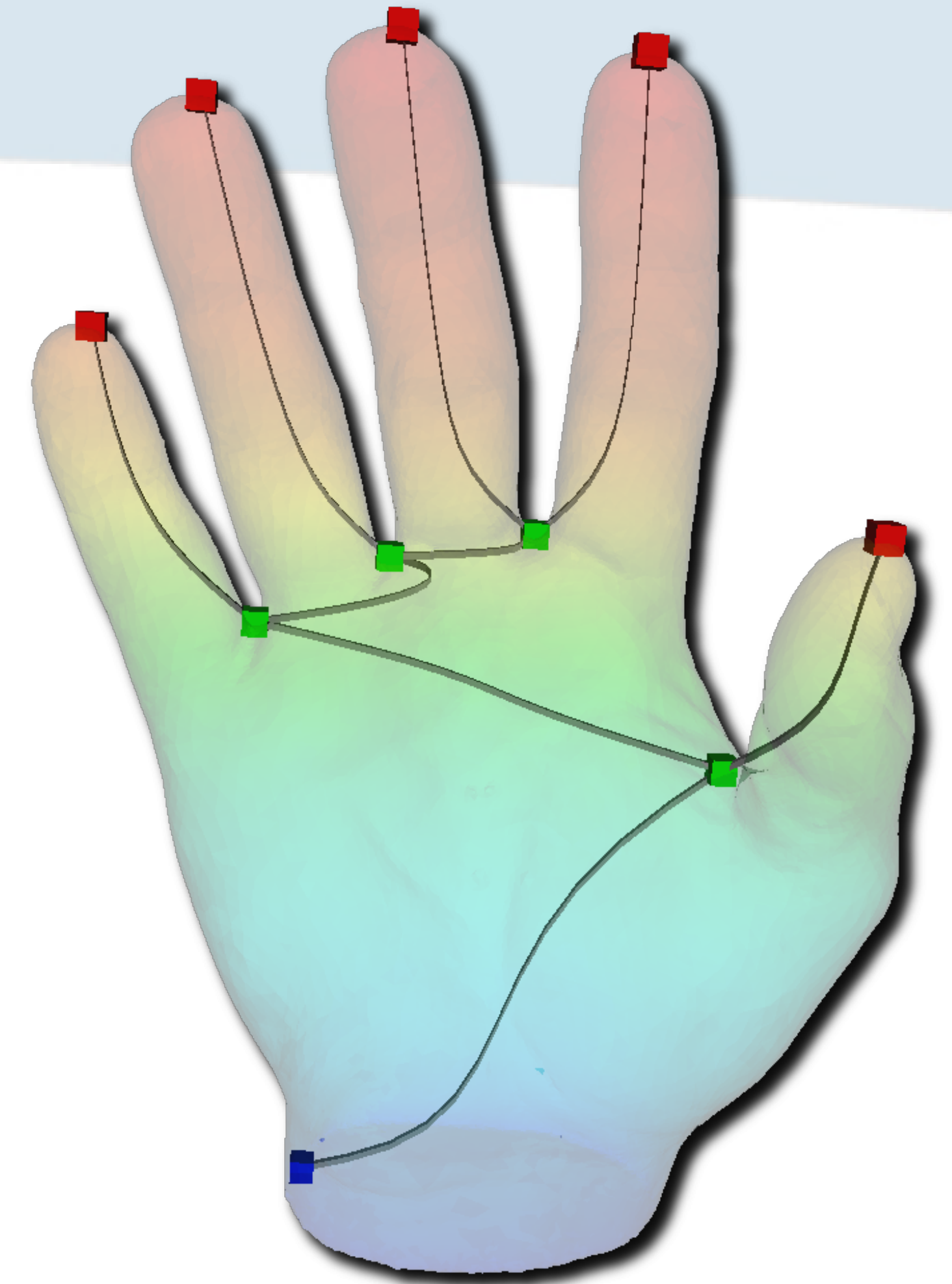
Online contour query

- Reeb graph computation
 - Once for all, matters of seconds
 - Store the arcs in balanced interval tree
 - For each arc, balanced binary search tree
- Isovalue query:
 - Find the arcs crossing the isovalue
 - Find the vertex right below the isovalue
 - Return its d-simplices



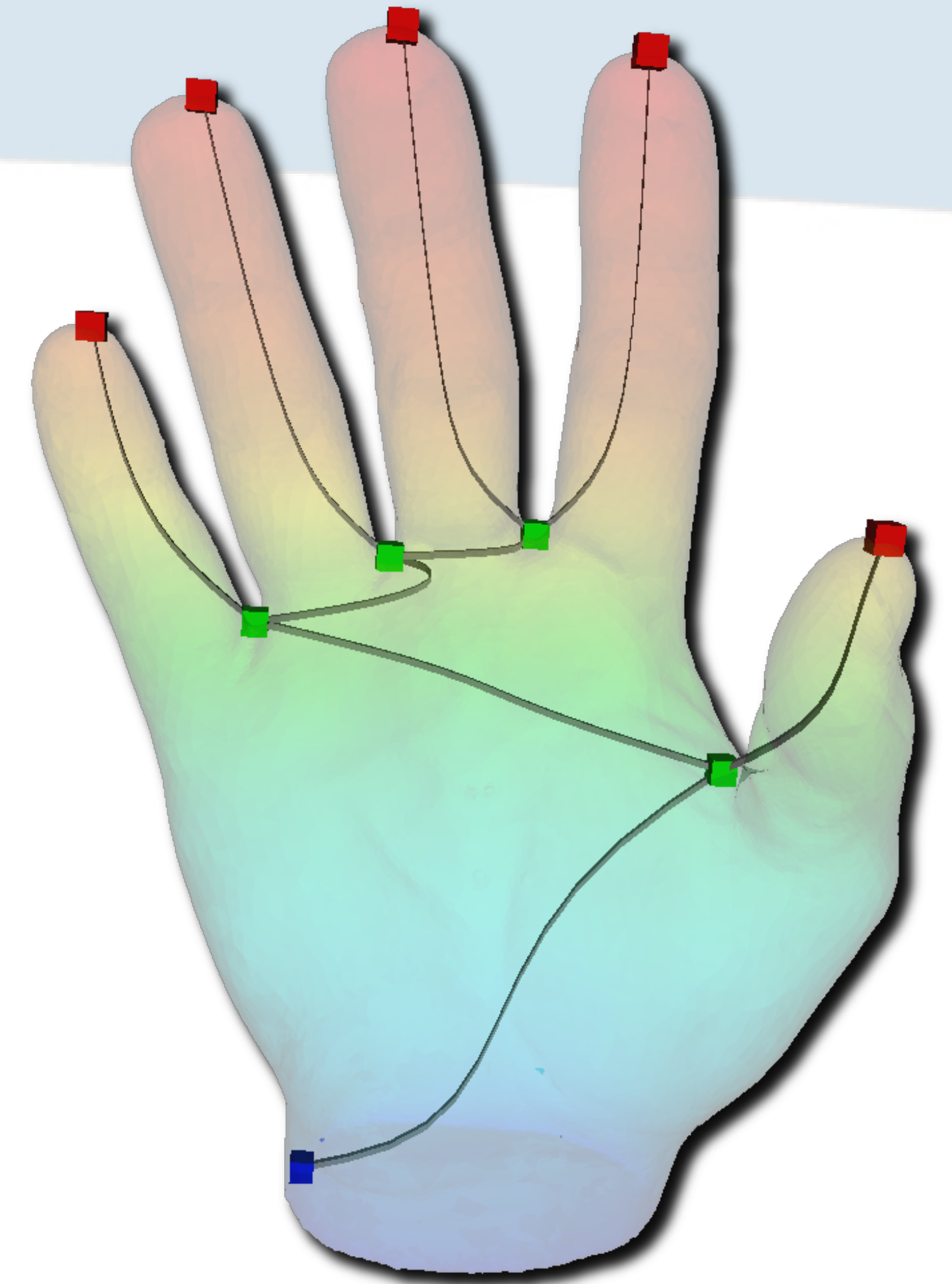
Query with topological simplification

- Reeb graph simplification



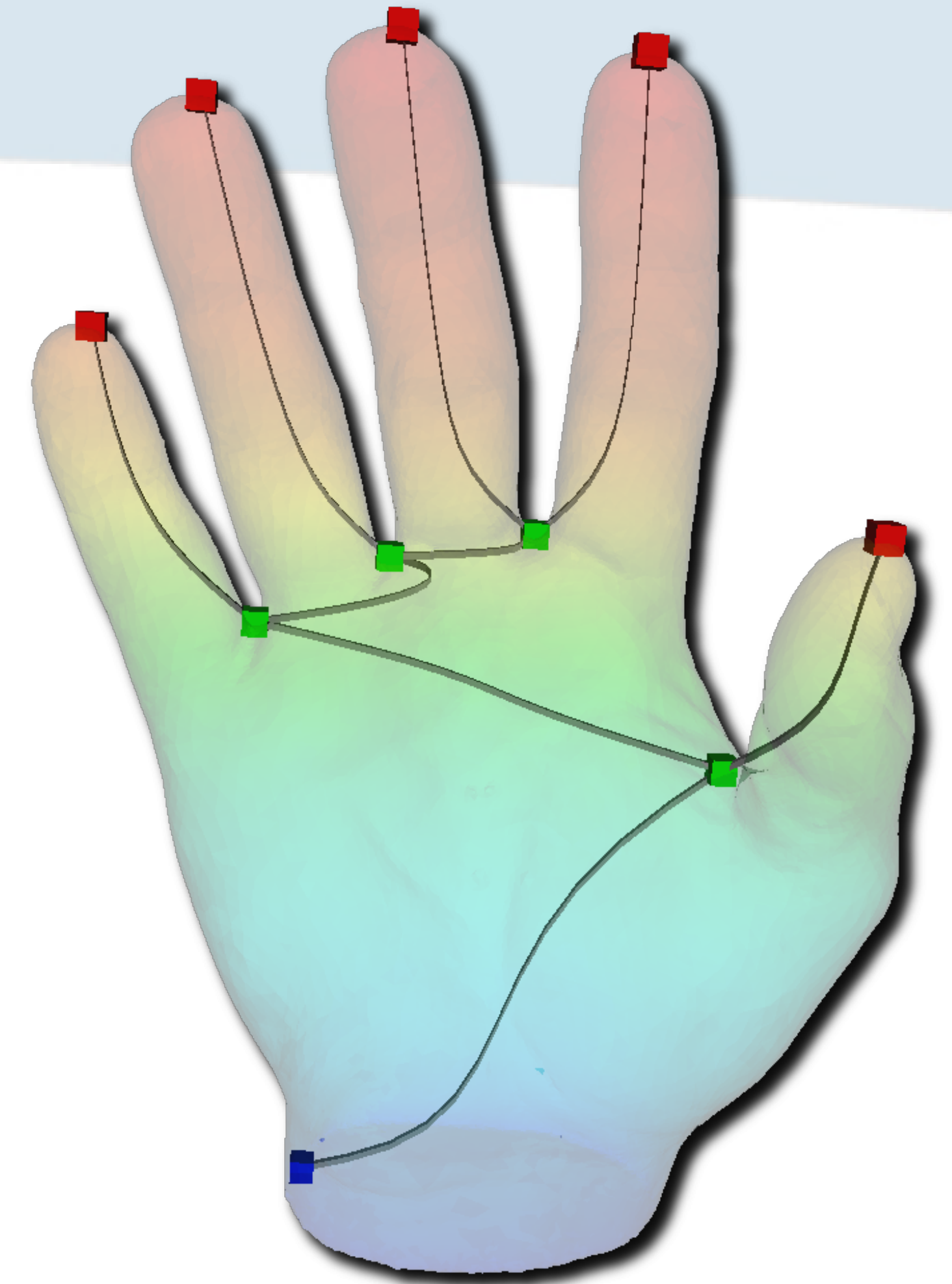
Query with topological simplification

- Reeb graph simplification
 - Persistent homology



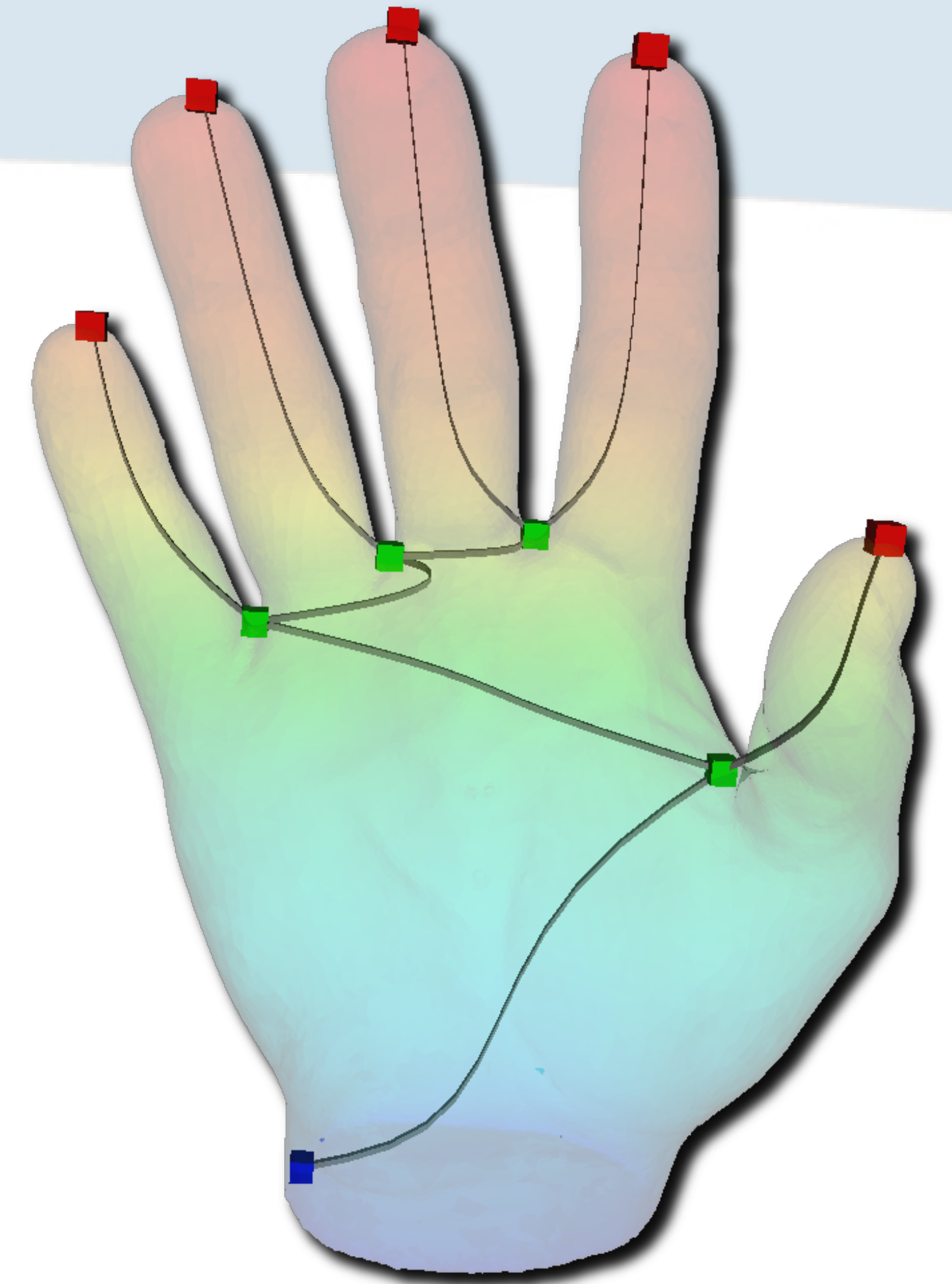
Query with topological simplification

- Reeb graph simplification
 - Persistent homology
 - Given a criterion and a threshold



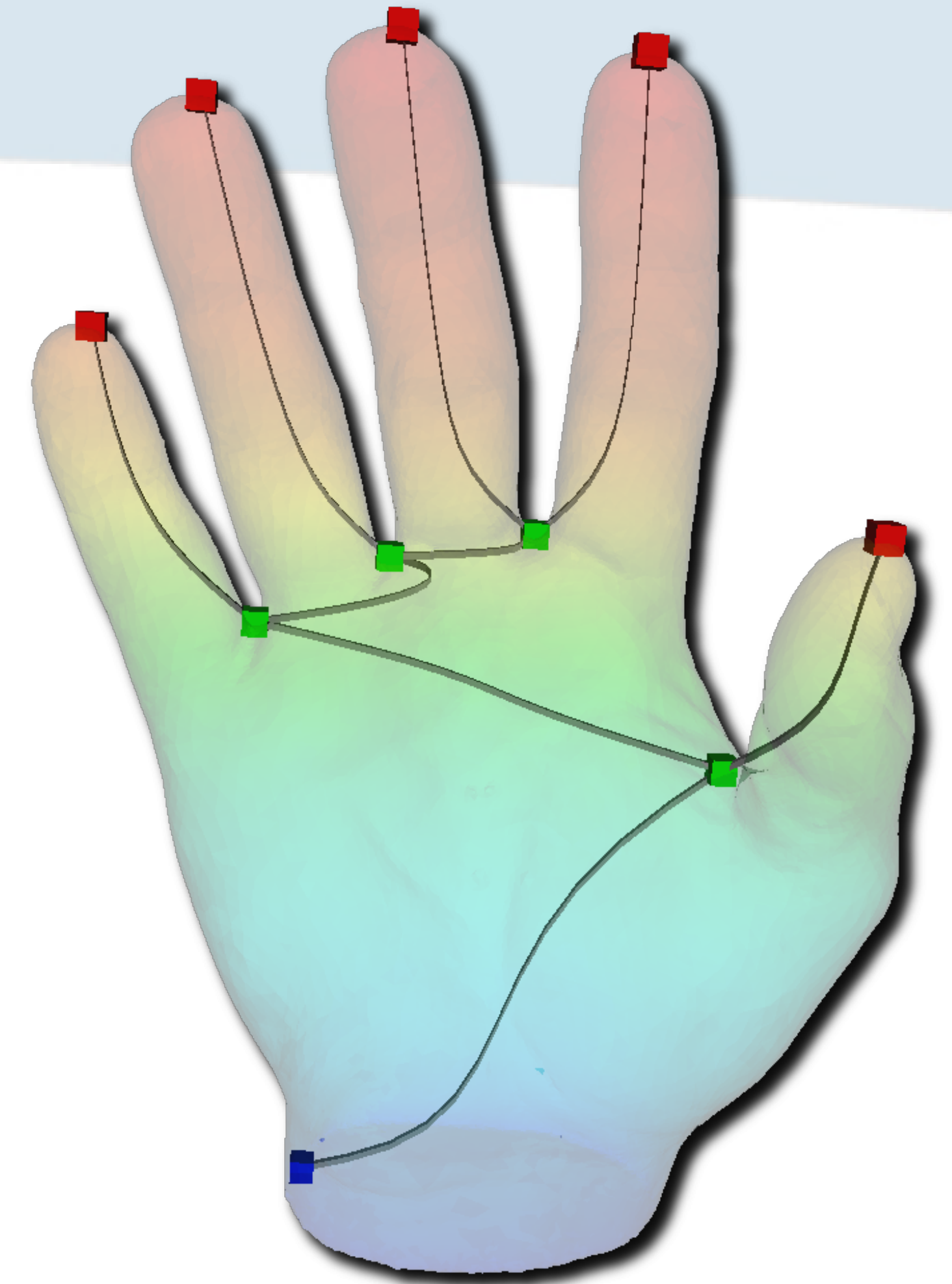
Query with topological simplification

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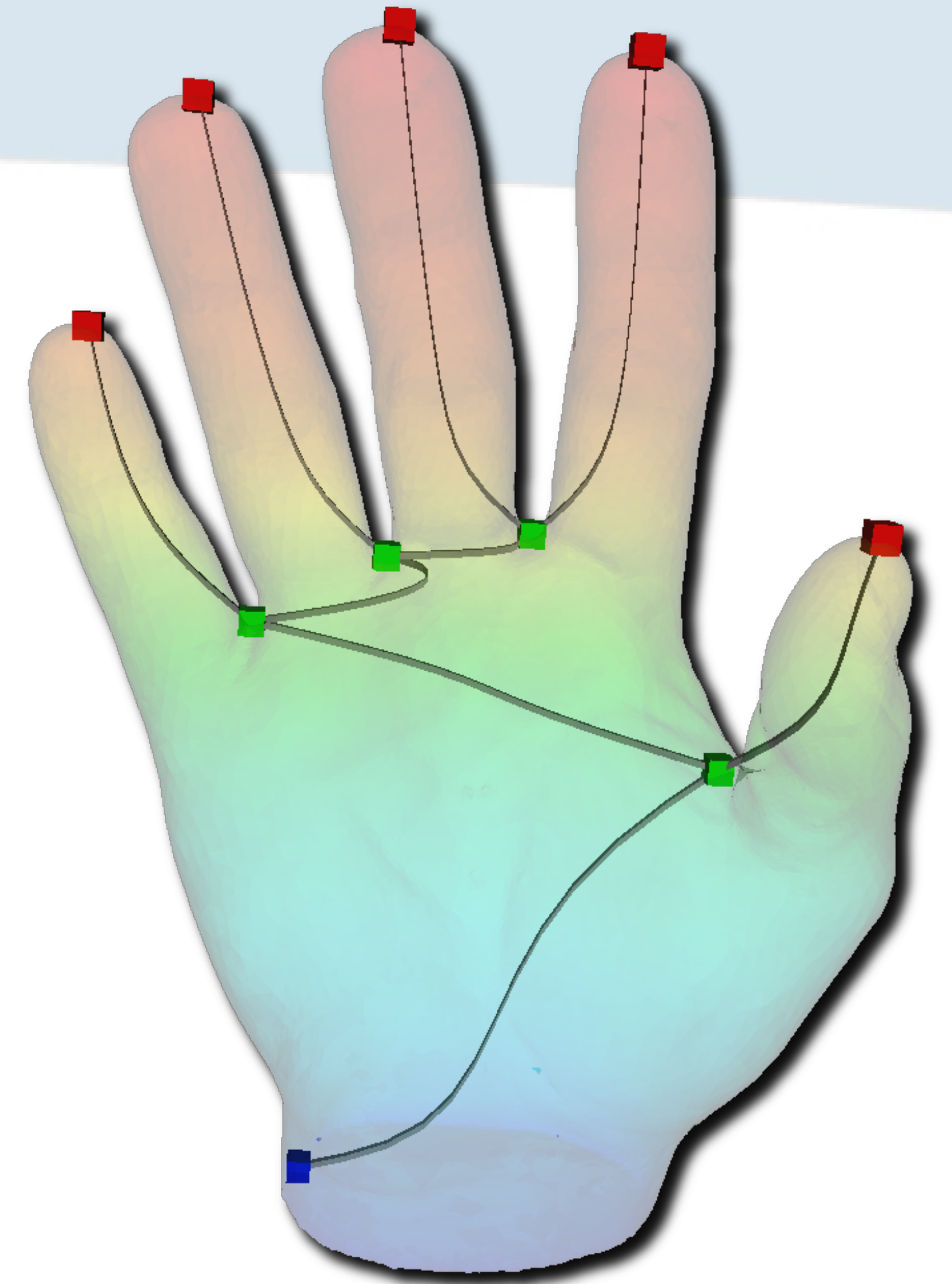
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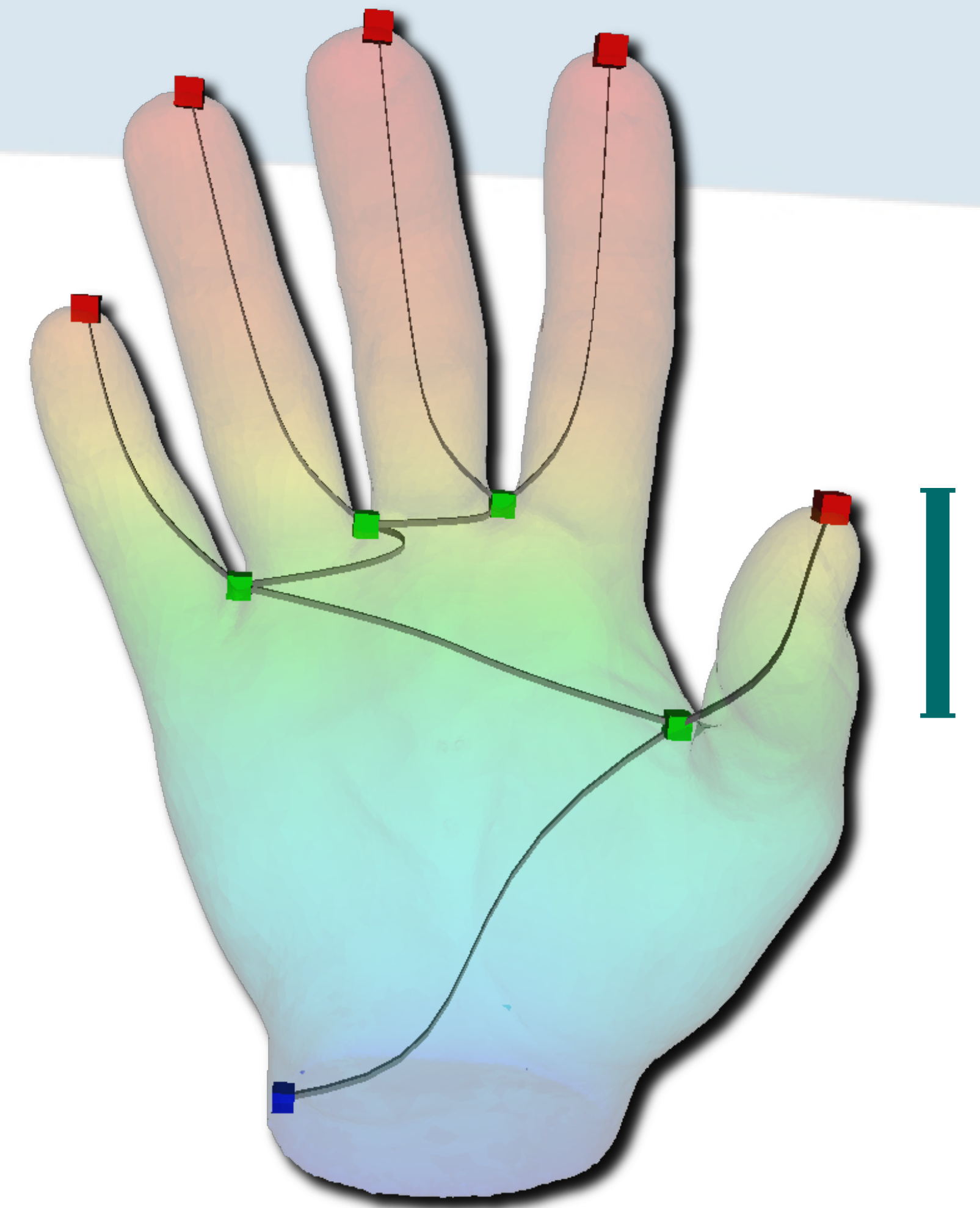
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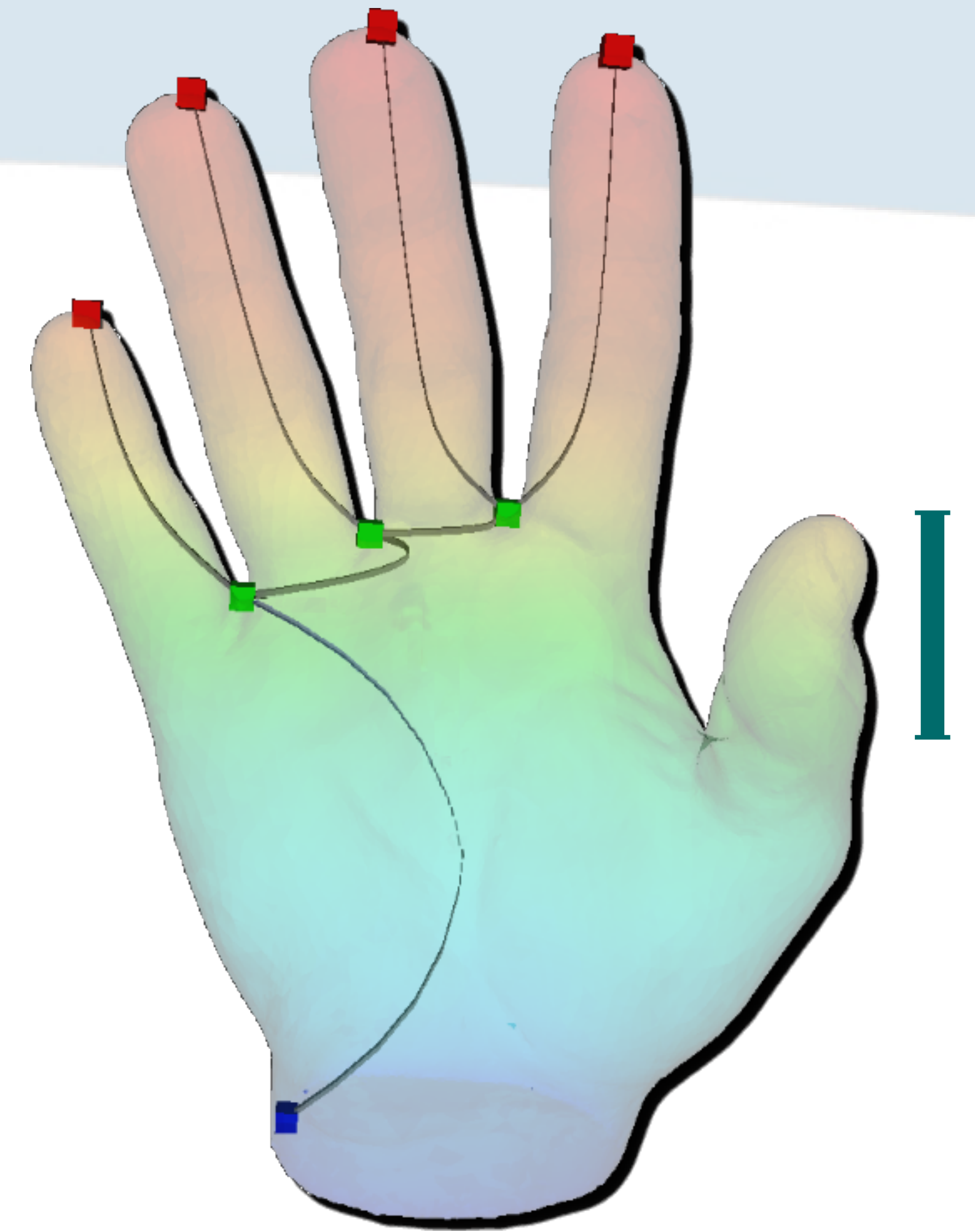
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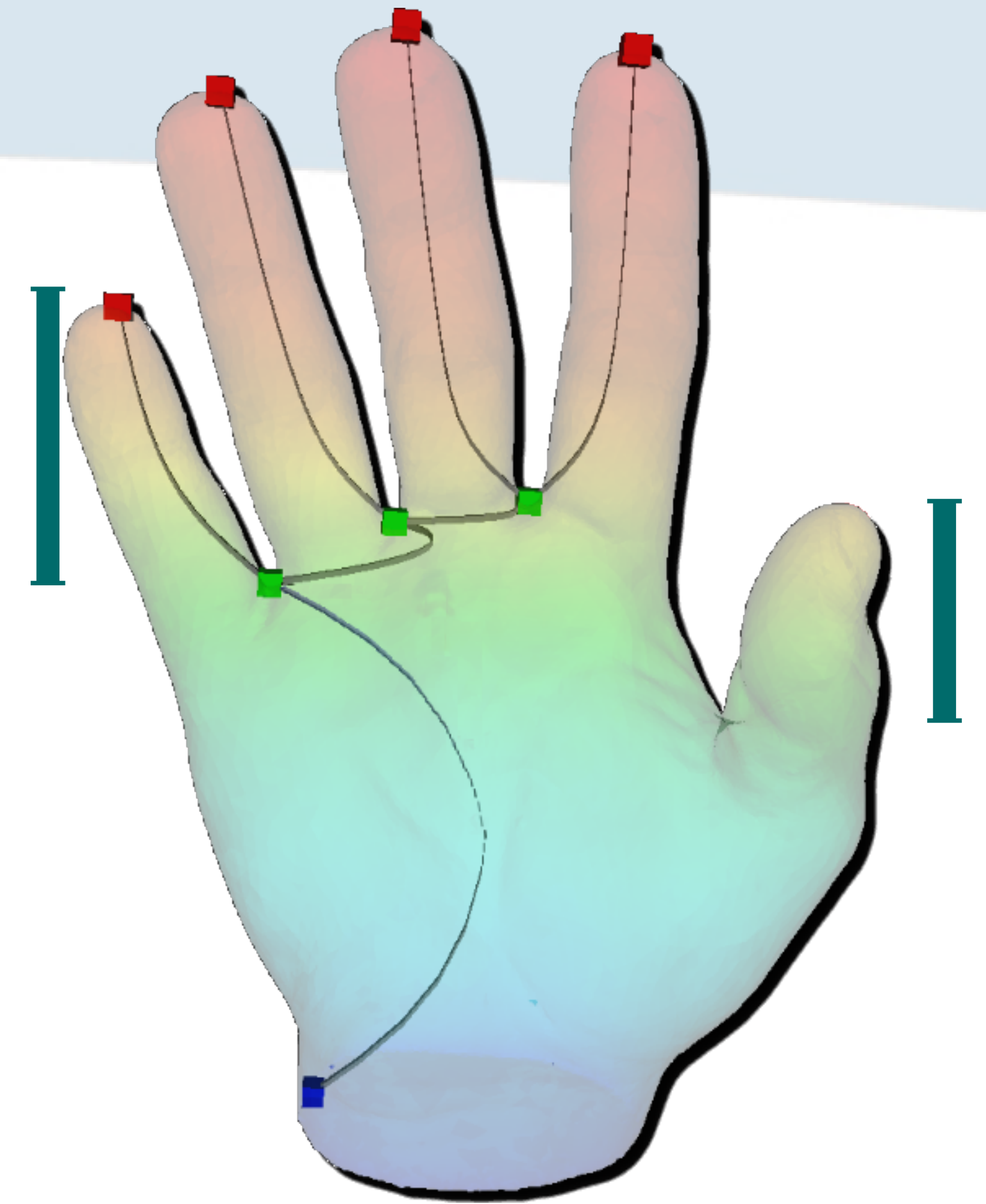
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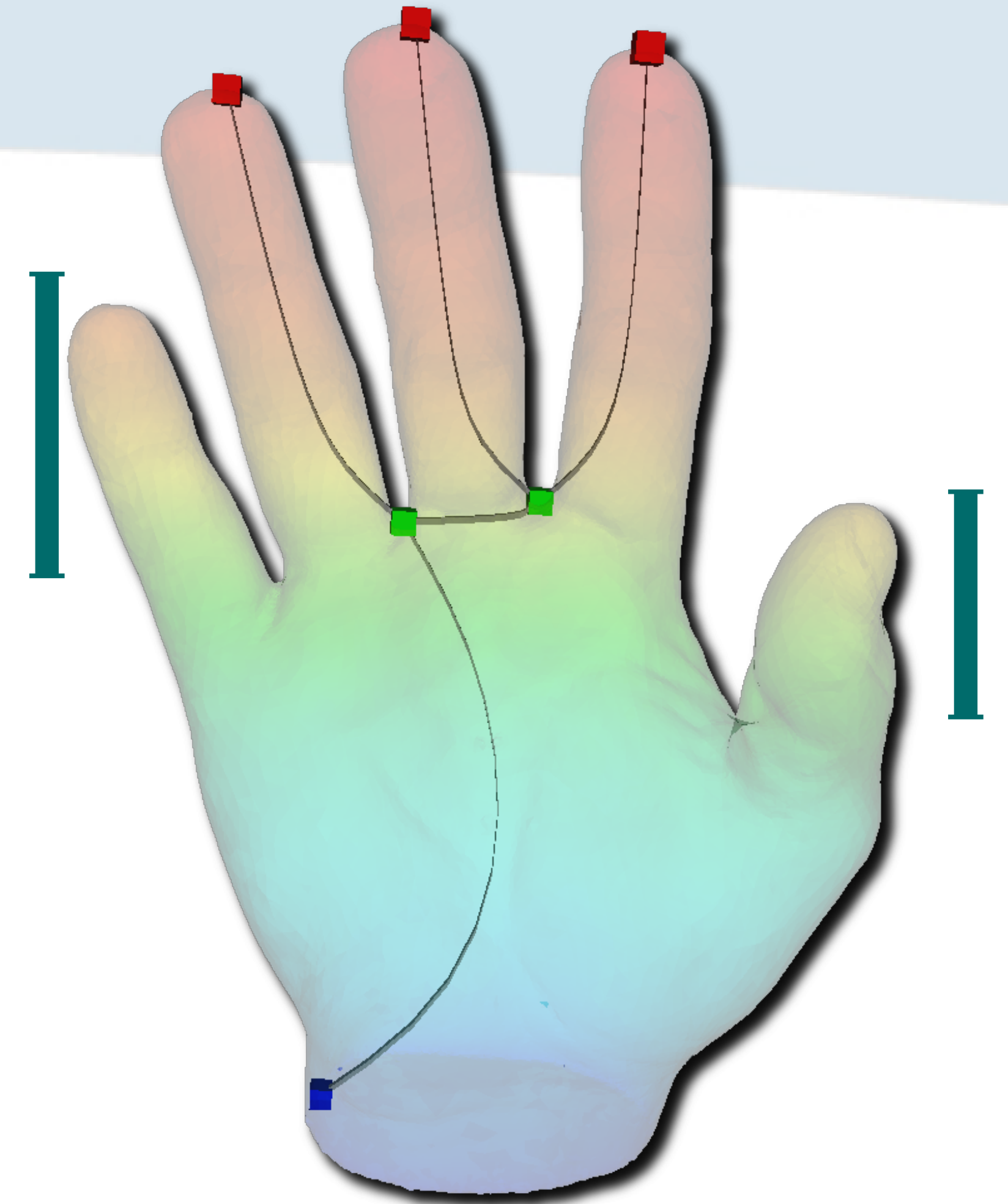
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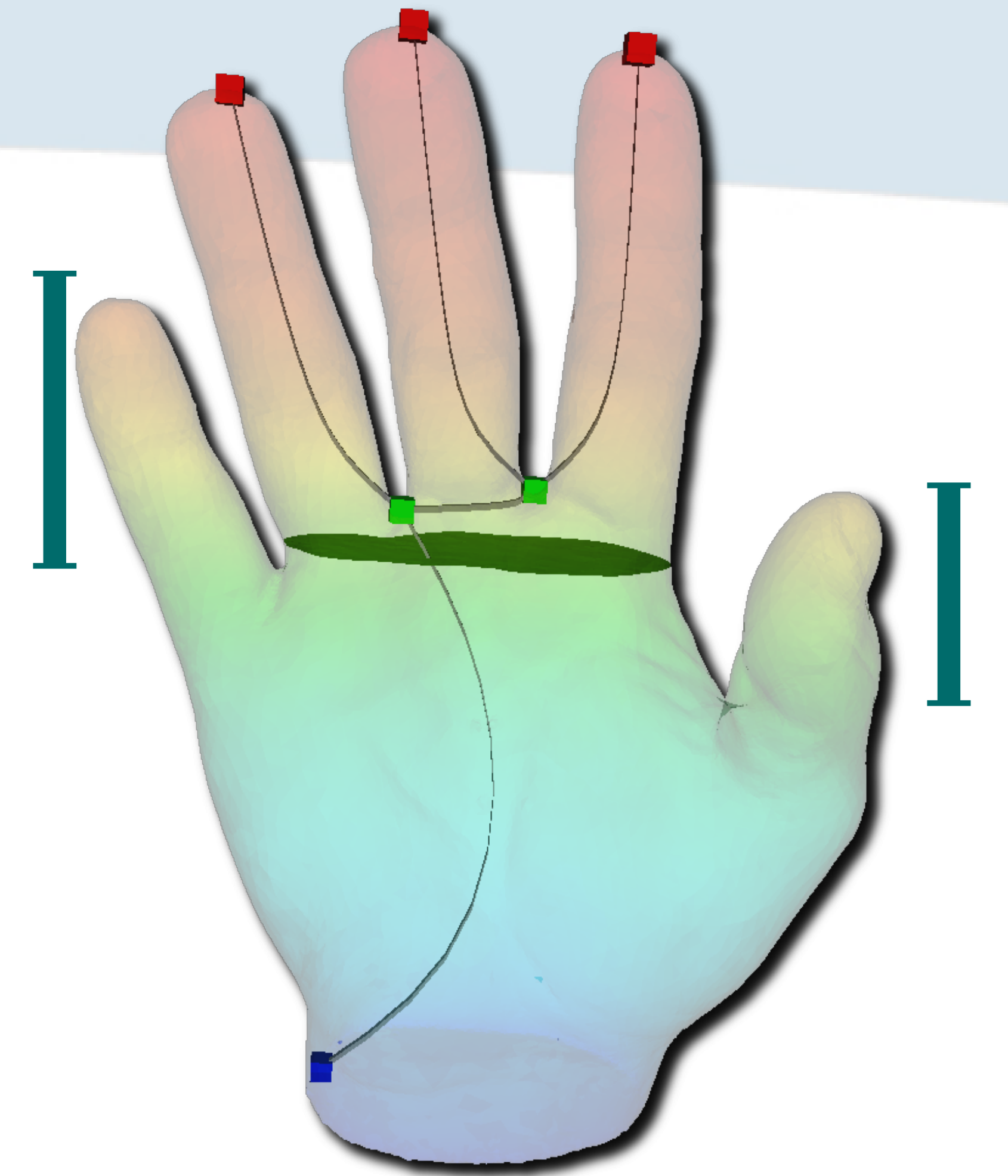
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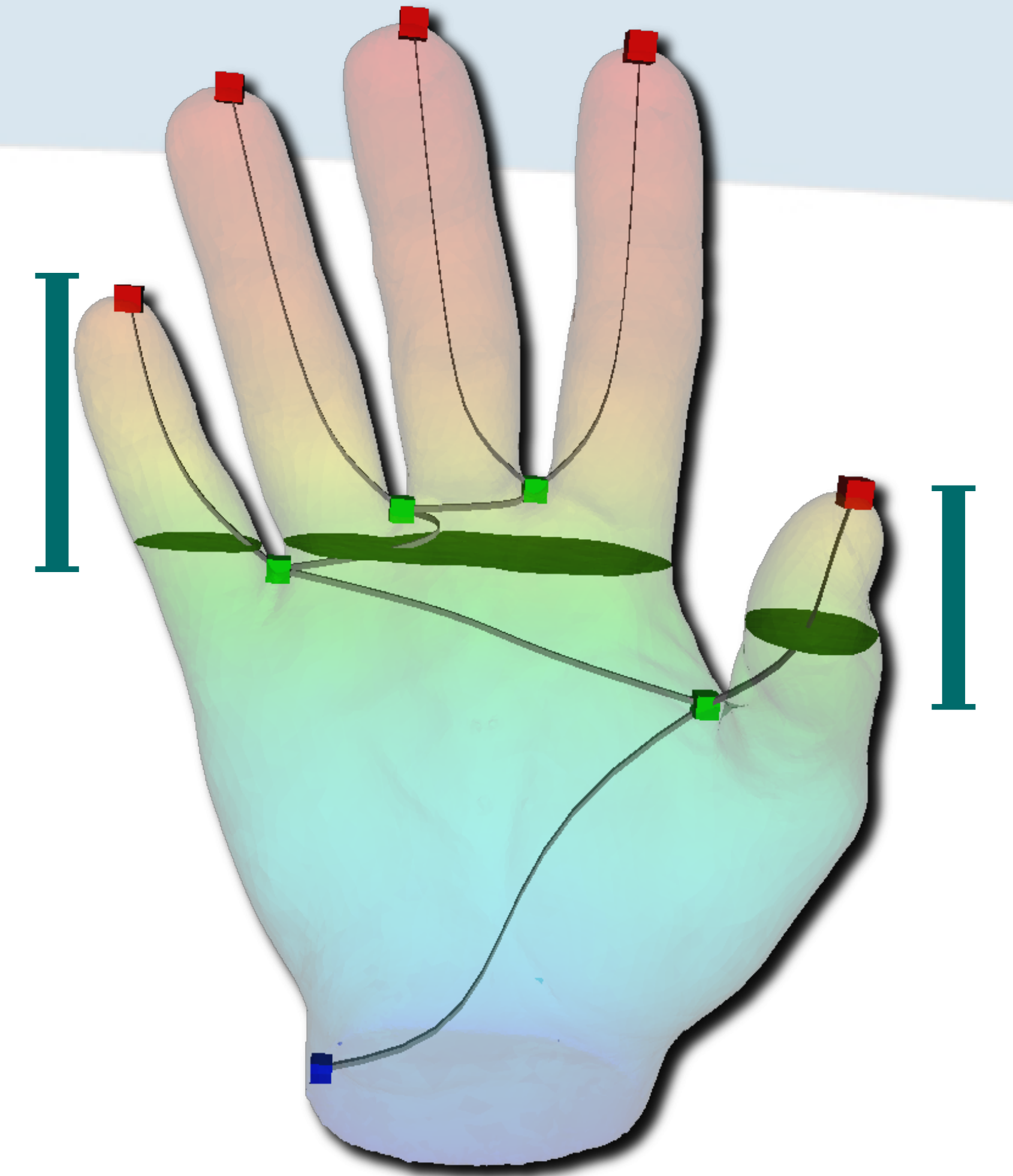
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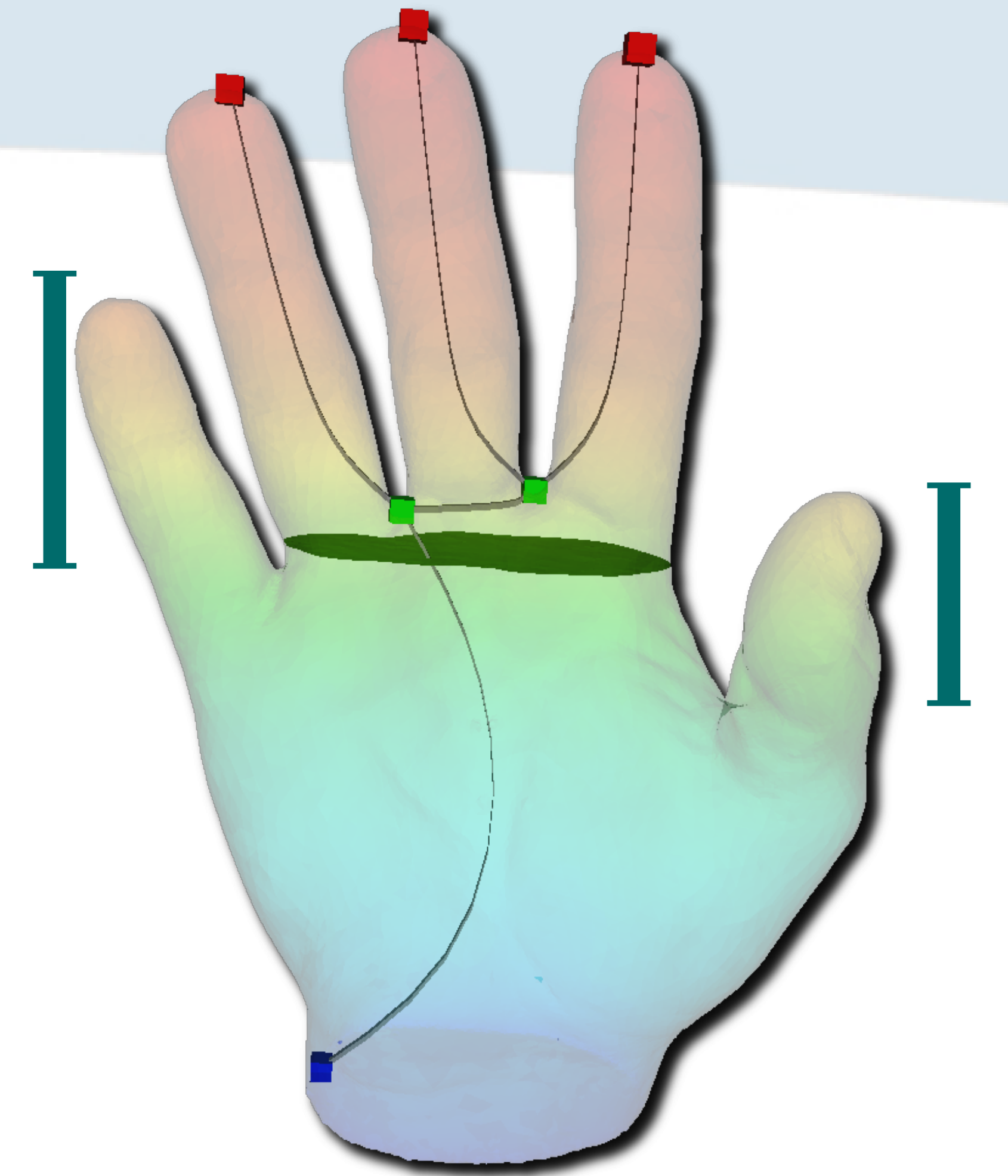
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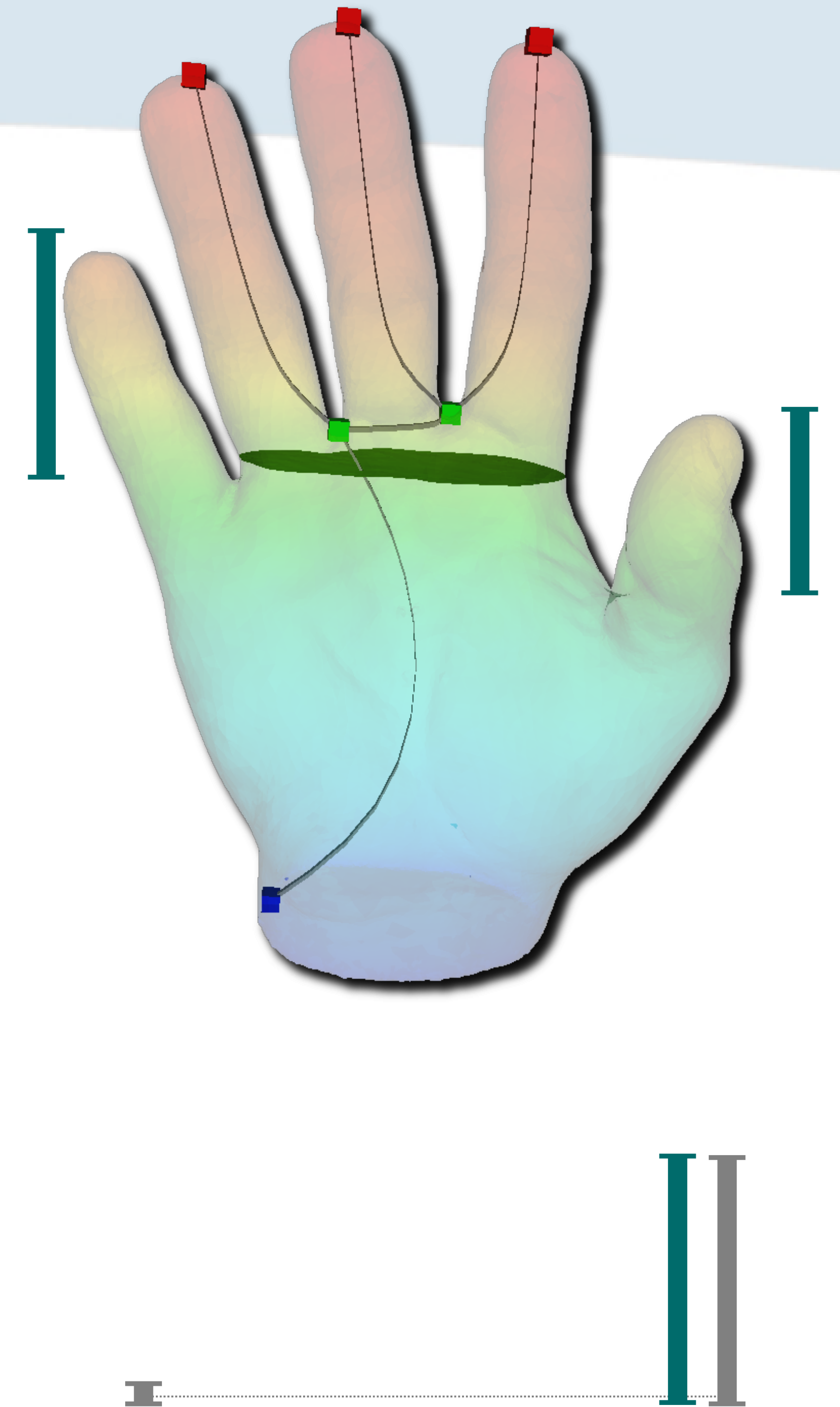
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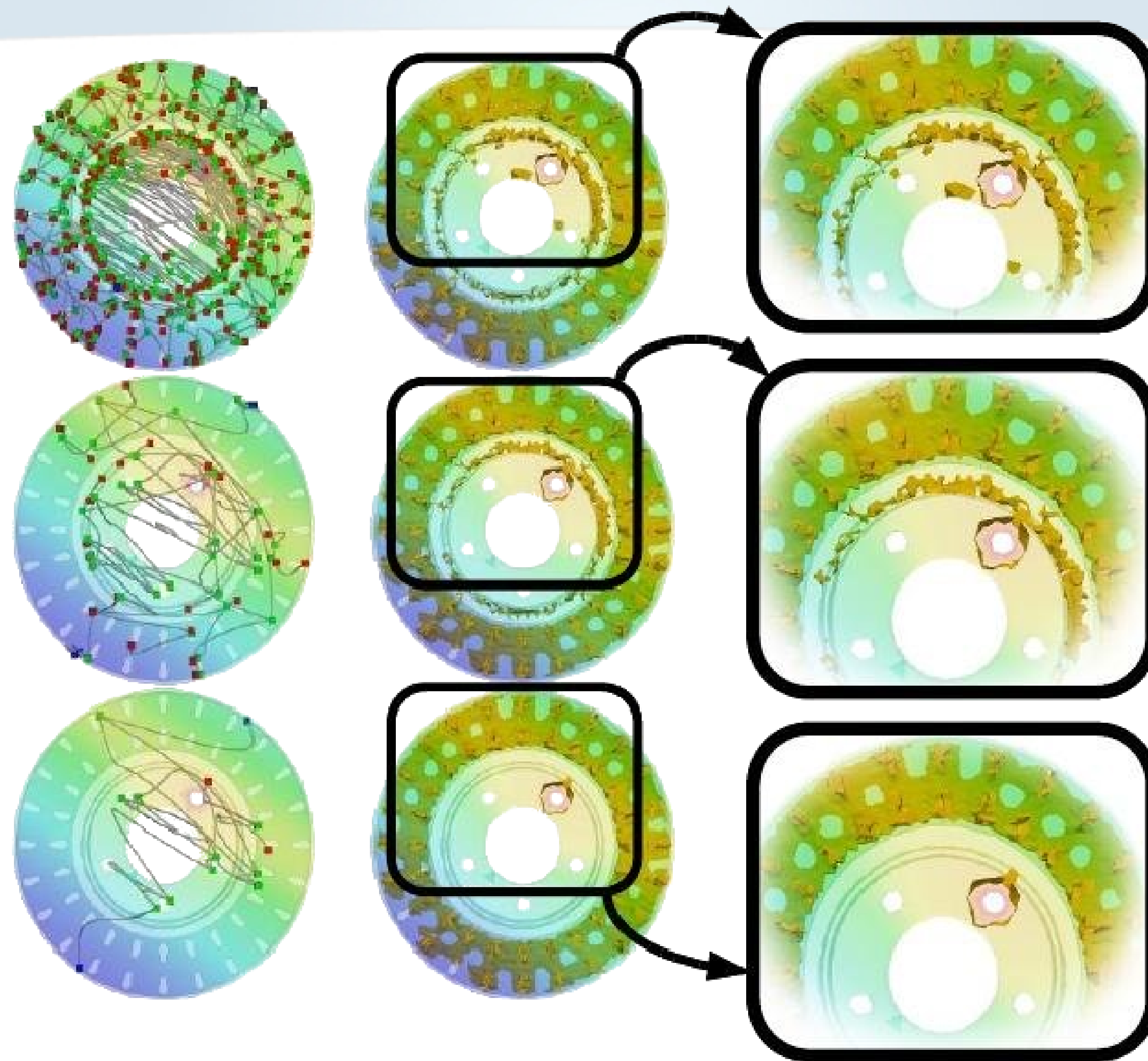


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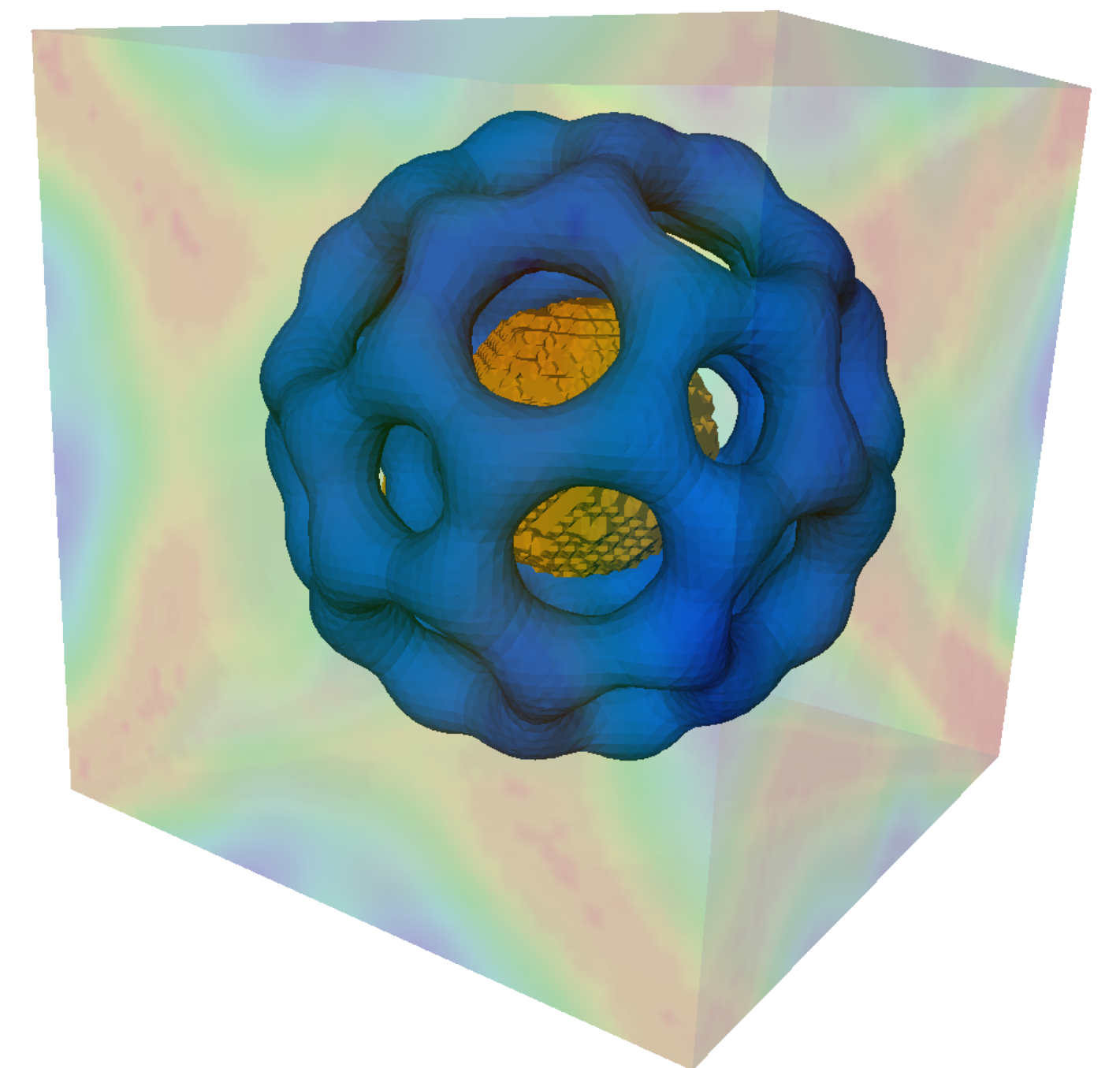
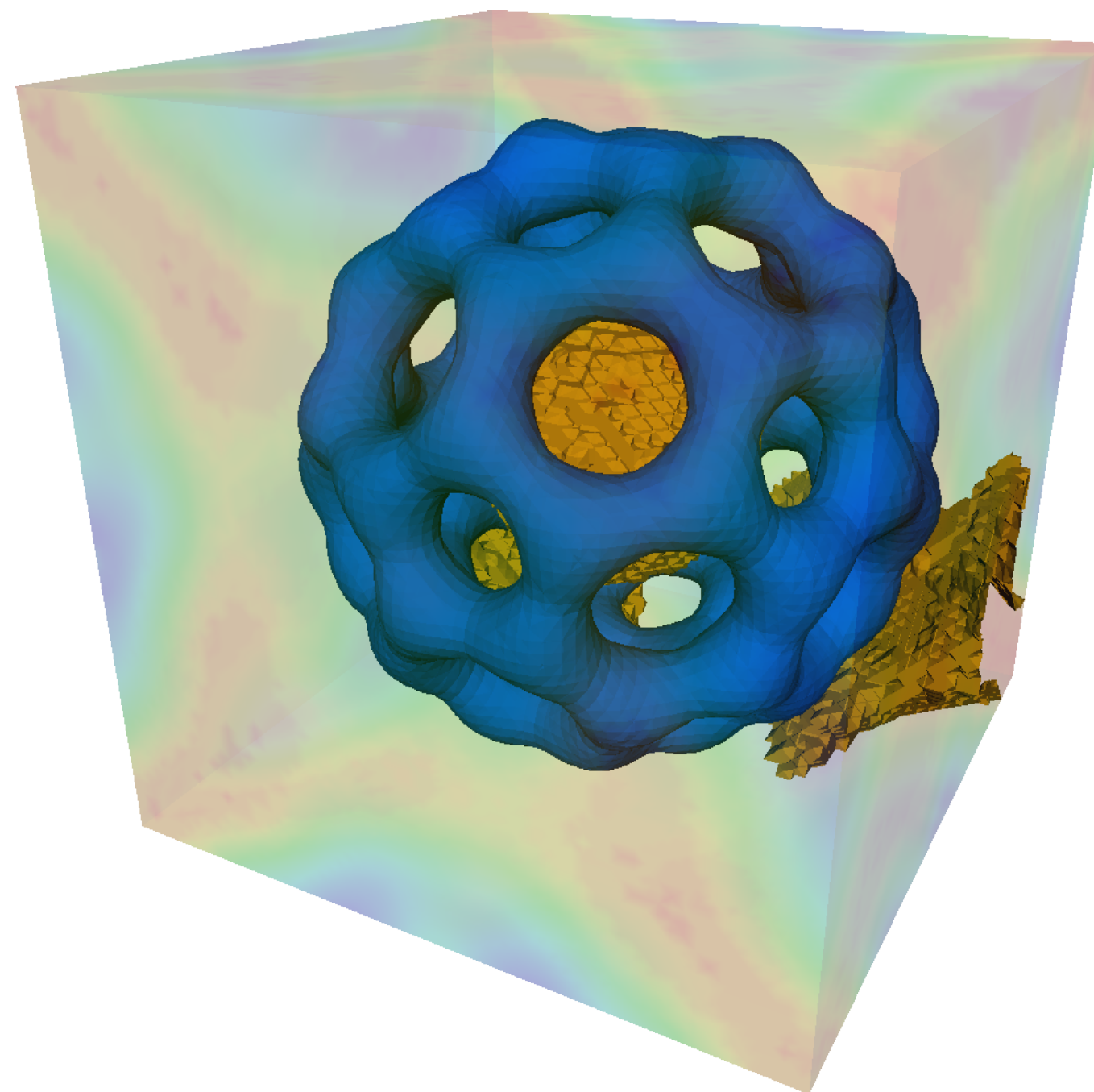
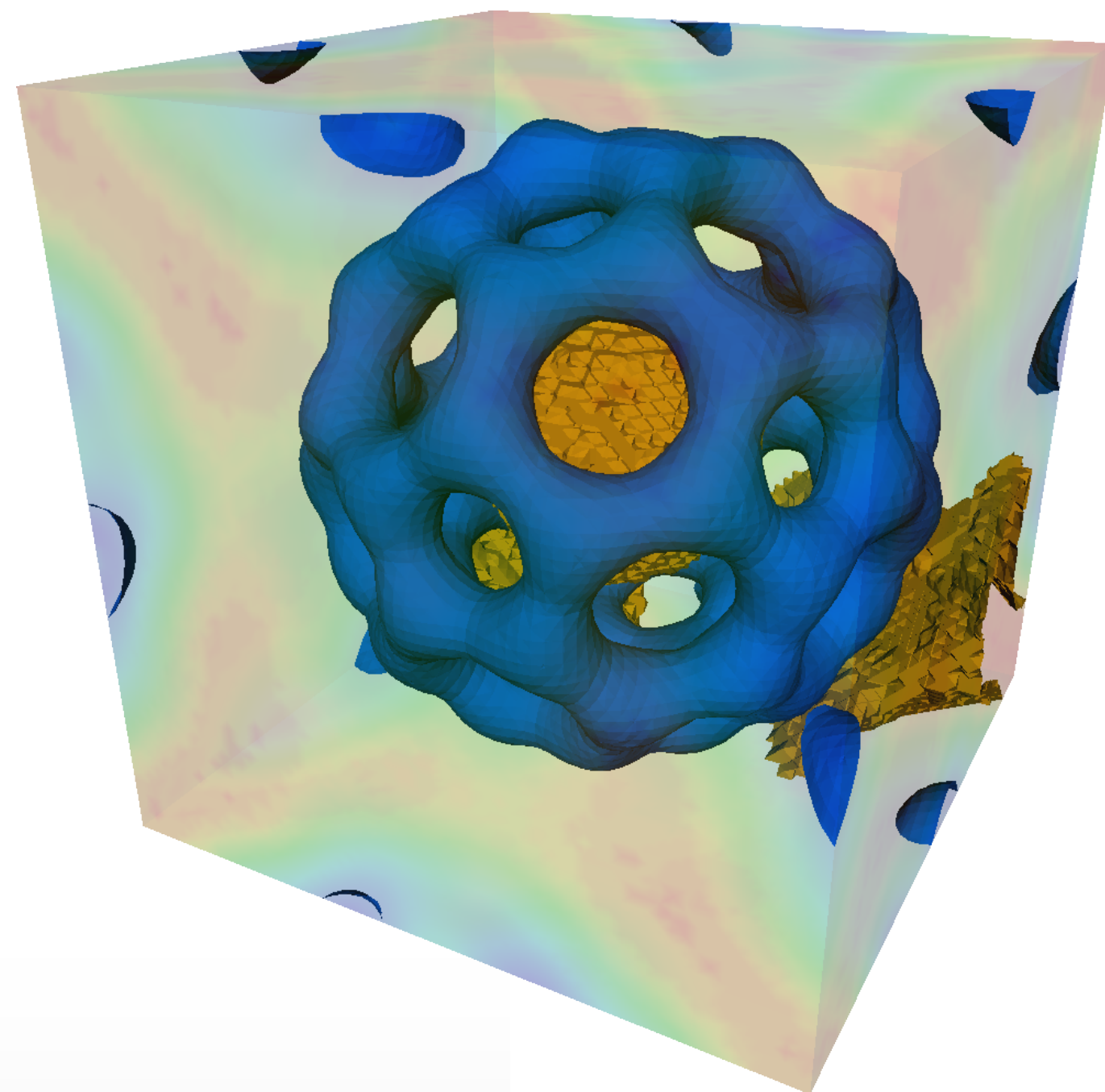
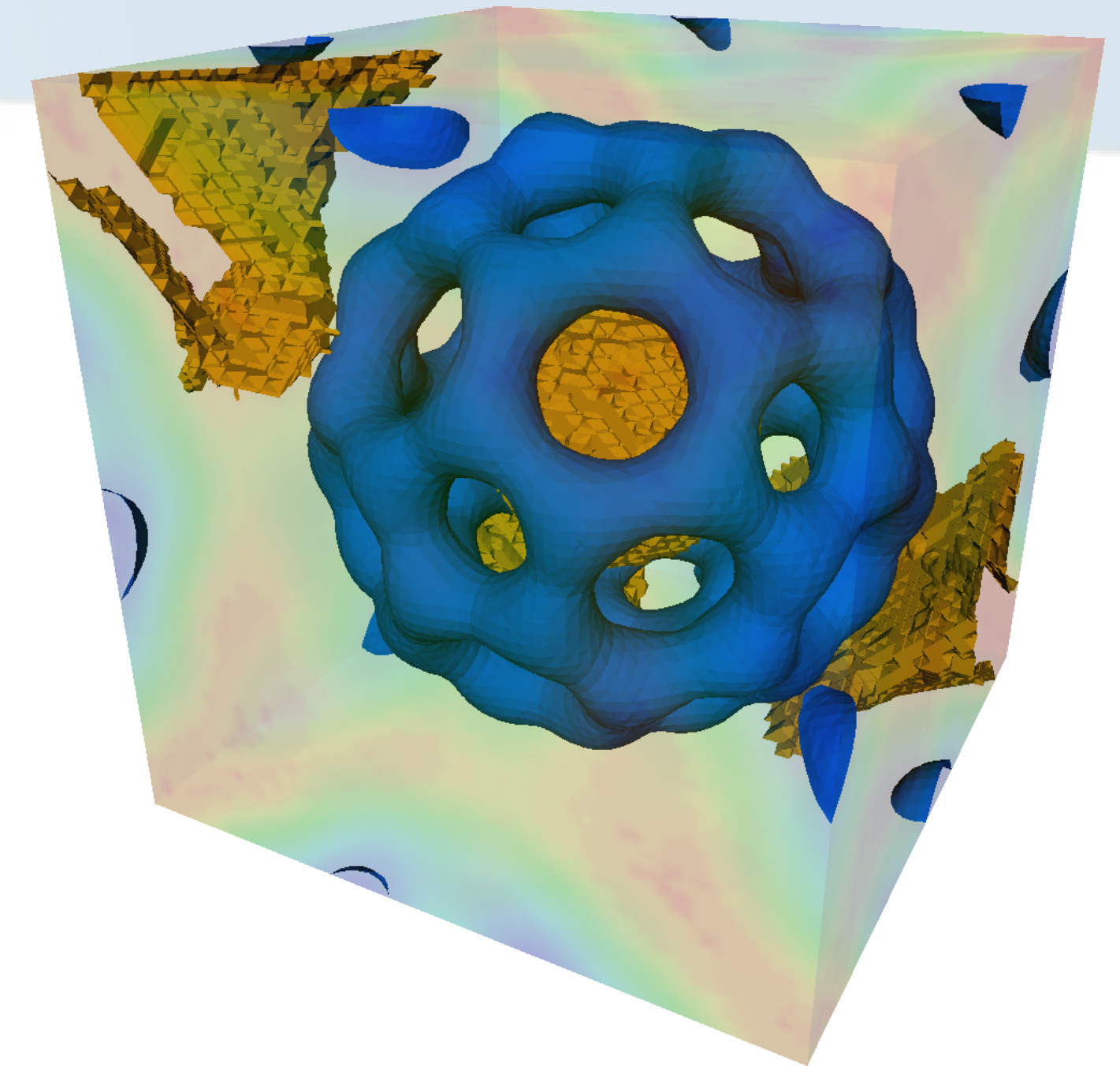
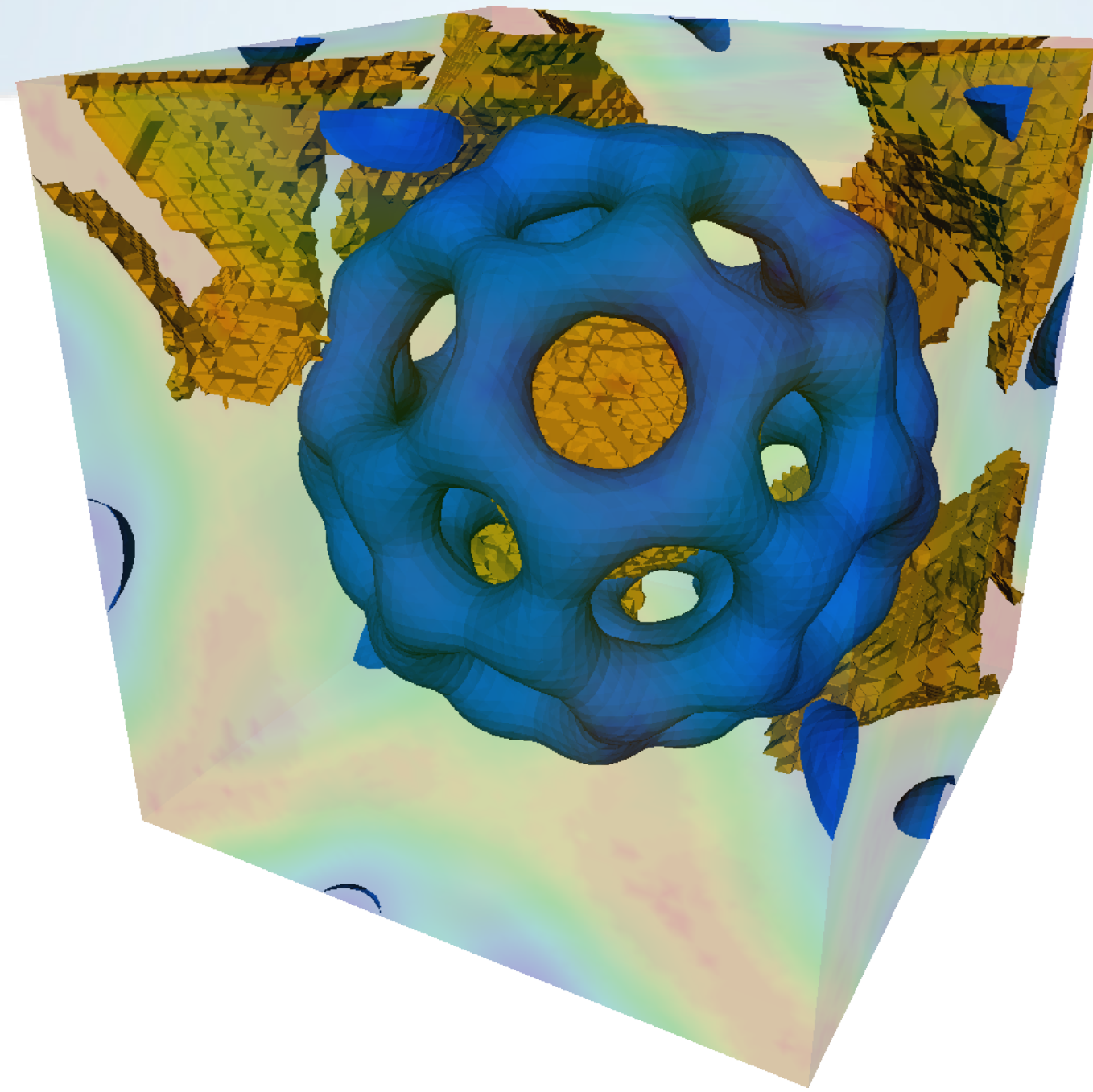
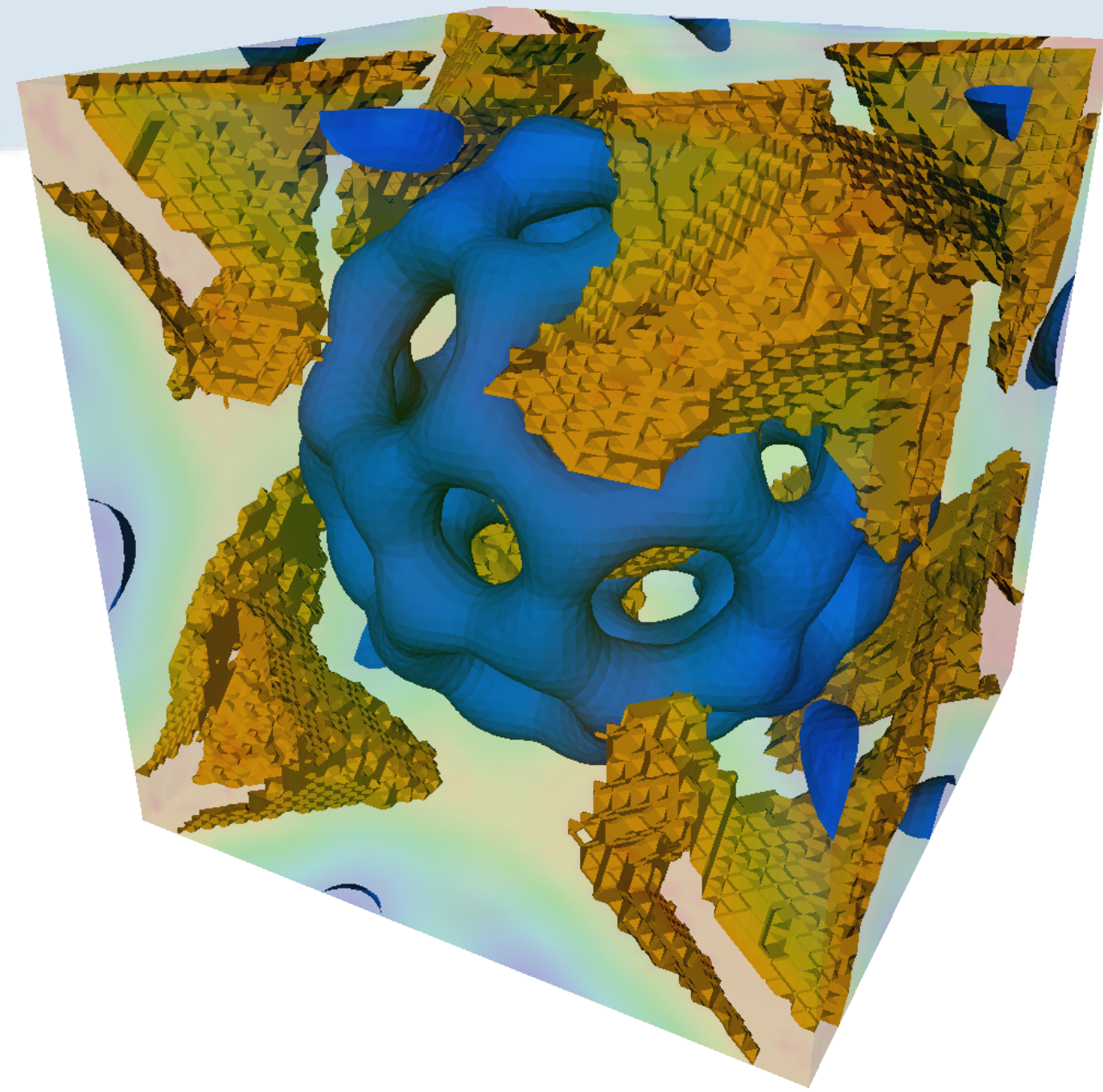
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- Criterion examples:
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 - Volume/Area of the arc
 - ...



Query with topological simplification



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